(1) TallyGenicom

## 9050 Laser Printer Service Manual

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## Chapter 1 Introduction

This manual is a standard service manual containing information required for maintenance of this laser printer (standard specifications).
This manual is intended for use by OEMs when they provide maintenance services for this laser printer or when they prepare maintenance data. It is prohibited to use this manual for other purposes.
This document is protected by copyright. It is illegal to photocopy or duplicate any part of this document in any form without previous permission in writing.
Additional information about this printer, such as specifications, can be found in other supplied documents.

## Conventions

The term "MSI" should be translated to "MPF" (Multi Purpose Feeder) in any text or illustration.
Tray numbering for all text and illustrations should be read in the in the following manner:

| Printed <br> Tray \# | TG Tray \# |
| :--- | :--- |
| 1 | 2 |
| 2 | 3 |
| 3 | 4 |
| 4 | 5 |
| 5 | 1 (MSI/MPF) |
| 6 | 6 (HCF) |
| MSI/MPF | 1 |
| HCF | 6 |

Maintenance operations requiring special cautions or additional information to descriptions of this manual are presented as "Warning", "Caution", or "Note", according to their nature.


If instructions are not observed, death or serious injury may be caused.


If instructions are not observed, injuries of workers or physical damages to assets (including this laser printer) may result.

NOTE Particularly important essentials for procedures, steps, rules, and other conditions.
Reference Incidental information to descriptions.

## Safety

To prevent possible accidents during maintenance operation, you should strictly observe the "Warning" and "Caution" information in this manual.
Performing dangerous operations and procedures out of range of this manual should be avoided.

Occasionally procedures not covered by this manual may be required in actual operation, which

## Laser Beams

This laser printer has a switch (INTERLOCK S/W 5V) which removes power to the laser beam output circuit, preventing operation of the laser beam output unit (ROS ASSY-12). The switch automatically removes power when the CRU is removed.
Do not turn the switch ON except for normal operation to prevent laser emissions during maintenance.
-If your eyes are exposed to laser beams, you may lose your eyesight.

- Never open any cover if warning label for laser beams is attached there.
-Before disassembling and reassembling this laser printer, be sure to turn it OFF. -When servicing this laser printer while it is running, be sure to follow the procedures specified in this manual.
- You should understand the laser beam is capable of causing injury to the human body, including anyone in the general area.


## NOTE Laser beams have the following characteristics:

-Frequencies are smaller in width than other beams (sun and electric bulbs) and phases are uniform so that high monochromatic and convergence performance can be obtained and thin beams of light can reach places at a long distance.
-Due to the high convergence, beams are concentrated in high density and high temperature, which is dangerous to human body.

Reference: Laser beams of this laser printer are invisible rays which you cannot see.


# Chapter 2 Principles of Operation 

## Engine

## Summary of Print Process

Electrophotography is used in the FIO printer to print image on paper using a video signal sent from the PWBA ESS to the PWBA MCU F. The electrophotography is composed of the following 7 steps.

1. Charging

Negative charges are uniformly distributed over the drum surface by the Bias Charge Roll.
2. Exposure

The laser scanner scans the drum surface with a laser beam modulated with the signal from the PWBA ESS (controller), to create an invisible electrostatic latent image on the drum surface.
3. Development

During development, toner particles are attracted to the electrostatic latent image on the drum surface, forming a visible toner image.
4. Transfer

The toner image is transferred from the drum surface to the paper.
5. Detack

Electric charges on the paper are partially neutralized. As a result, the paper is stripped off the drum surface.
6. Fusing

The toner image is permanently fixed to the paper by heat and pressure.
7. Cleaning

The remaining toner is removed from the drum surface.

- Summary of print process


By rotating the drum, the drum surface undergoes various steps including charging, exposure, development, transfer, detack, and cleaning. A toner image is created on the drum surface and transferred to the paper. The paper is subject to the transfer, detack, and fusing steps by the paper transport mechanism. When the paper is positioned relative to the image, the toner image is transferred to the paper from the drum surface, and then fused.
Main components directly associated with the print process and paper transport are illustrated in the following figures.

- Components associated with print process

- Components associated with paper transportation


In the exposure step, the negatively charged drum surface is scanned by a laser beam. The laser diode of the ROS (Raster Output Scanner) passes through a rotating polygon mirror (6 facets) and lens scanning the drum from one end to the other.
The radiation of the laser beam varies according to a video signal from the PWBA ESS.
The laser beam shot at the drum excites electrons directed to the photo conductor. As a result, electron-hole pairs are induced in the photoconductive layer. Since electrons are moved toward the body inside the drum by the electric field, the electron-hole pairs move to the surface of the photoconductive layer. Negative charges in the portion decrease, thus creating an invisible electrostatic latent image there.
Toner particles are adsorbed onto this electrostatic latent image in the next step. Thus, the image is developed. The toner particles adsorbed to the drum are attracted to positive charges supplied by the BTR, and are transferred to the paper. The drum is sent for detack and cleaning steps.

- Electrostatic latent image formed on drum


In the cleaning step, the remaining toner is removed from the drum surface. The drum surface is prepared for the next cycle.
The toner is scraped off the drum surface by a cleaning blade.
NOTE The toner scraped off in the cleaning step is collected in a recovery toner compartment partitioned from unused toner. The transfer rate is normally more than $90 \%$, but varies depending on the image coverage range and environmental conditions such as temperature and humidity. The used toner cannot be reused.

NOTE When the printing step is started, the whole drum surface is scanned with a laser beam. If charges generated in the previous step remain on the drum surface, they are completely removed. At the beginning and end of the continuous printing step, a negative high voltage is applied to the BTR. If toner particles adhere to the BTR in the previous printing step, the toner particles are returned to the drum surface. In this way, the surface of the BTR is cleaned.

## Driving Force Transmission Path

## Main Motor

The rotating force of the MAIN MOTOR is transmitted through the GEAR and the PULLEY 25T to components that need mechanical driving force as shown in the following flow.


The driving force transmitted to the GEAR drives the ROLLER ASSY-TA, ROLLER ASSY-FEED, ROLLER ASSY REGI, FUSER ASSY, and ROLL ASSY OCT through the clutch and gears.
The driving force transmitted to the PULLEY 25T drives the EXIT1 (ROLL ASSY-OCT) through the gears.
The driving force transmitted to the FUSER ASSY drives the Heat Roll.

## Drum Motor

The rotating force of the DRUM MOTOR is transmitted through the gears to components that need mechanical driving force as shown in the following flow.


The driving force transmitted to the CRU drives the DRUM. The driving force is then transmitted to the BTR by direct contact with the DRUM.

## Paper Transport

## Paper Transport Path

Paper is supplied from the MPF, Tray1 or Tray2, and is transported to the printer along the paper transport path shown below.


## Layout of Paper Transport Path

The following is a cross section of the FIO laser printer, showing main components directly associated with the paper path and transport.

- Main components associated with transport of paper



## Functions of Main Components

This chapter describes the functions of the main components of the FIO laser printer.
4.1 Paper Cassette
4.2 Paper Feeder
4.3 MPF
4.4 Xero
4.5 Fuser
4.6 Drive
4.7 Electrical Components and Rollers

## Paper Cassette

It is necessary to adjust the FRONT SIDE GUIDE ASSY, REAR SIDE GUIDE and END GUIDE of the Paper Cassette to match the paper size.
FRONT SIDE GUIDE ASSY and REAR SIDE GUIDE
The FRONT SIDE GUIDE ASSY can be adjusted to different paper sizes by moving it to the front or rear. These guides come into contact with the front and rear edges of the paper and hold it in position.
The REAR SIDE GUIDE moves together with the FRONT SIDE GUIDE ASSY.
END GUIDE
The Paper Cassette is so designed that it can adapt to the paper length in the paper feed direction by moving the END GUIDE to the left or right.

The force pushing up the BOTTOM PLATE is transmitted by the driving force of the MOTOR on the FEEDER ASSEMBLY to the LIFT UP SHAFT through the GEAR (13T/60T) and SECTOR GEAR (60T). The BOTTOM PLATE is pushed up by the rotation of the LIFT UP SHAFT, which causes the supplied paper to get in contact with the ROLLER ASSY (NUDGER).

- Paper Cassette


Detection of paper size
The paper size to which the cassette is set is transmitted to the switches S/W1 to S/W5 on the SWITCH ASSY P S by moving these guides. The paper size is detected by the ON/OFF information of these switches.
Paper sizes that can be automatically detected are as 5.1 Paper Size Control

## Paper Feeder

Since the Tray1 and Tray2 are functionally equivalent in terms of the SWITCH ASSY P S, NO PAPER SENSOR, LEVEL SENSOR and PRE FEED SENSOR, only the components of one tray are described here.
The Paper Feeder is a mechanical unit for supplying paper from the Paper Cassette to the printer. The driving force from the TRAY $1 / 2$ FEED LIFT UP MOTOR on the FEEDER ASSY is transmitted to the three ROLLER ASSY to feed paper.

When the ROLLER ASSY (NUDGER) picks up some sheets of paper and the remaining paper decreases, the ACTUATOR of the LEVEL SENSOR lowers accordingly. When the LEVEL SENSOR detects the lowering, the TRAY $1 / 2$ FEED LIFT UP MOTOR is activated to lift the LIFT UP SHAFT and the BOTTOM PLATE is also lifted accordingly. Thus, the remaining paper is ready to be fed out.

## TRAY 1/2 FEED LIFT UP MOTOR

This motor is activated to feed paper and to lift the BOTTOM PLATE. When feeding paper, it rotates forward to drive the ROLLER ASSY (NUDGER). When lifting the BOTTOM PLATE, it rotates reversely to drive the tray module gears to lift the LIFT UP SHAFT.

## SWITCH ASSY P S

This SWITCH ASSY P S switches for setting the size of paper supplied from each Paper Cassette. A signal indicating the set size is transmitted as a voltage to the PWBA MCU F. NO PAPER SENSOR If paper runs out in a Paper Cassette, the ACTUATOR lowers and the flag of the ACTUATOR that has stayed in the NO PAPER SENSOR sensing area leaves there. Thus, the light
of the sensor is transmitted. When the sensing area is blocked (paper is present), the signal becomes OFF.

LEVEL SENSOR
This sensor detects, by the ACTUATOR position, whether paper in the Paper Cassette is lifted. When the flag of the ACTUATOR leaves the LEVEL SENSOR sensing area, the sensor detects that the paper has been lifted.

## PRE FEED SENSOR

This sensor detects a paper jam in the Paper Cassette by the paper position and sensor ON/ OFF time.
The sensor ON/OFF states can be monitored by paper passing through the PRE FEED SENSOR sensing area.


## MPF

The MPF is a mechanical unit to feed manually supplied paper to the printer. The driving force from the MAIN MOTOR of the MAIN ASSY 242 is transmitted to the ROLLER ASSY-FEED to feed paper.
ROLLER ASSY-FEED
The ROLLER ASSY-FEED feeds paper set on the MPF.
ROLLER ASSY-DRIVE

The ROLLER ASSY-DRIVE feeds paper into the printer. SOLENOID PICK UP

The SOLENOID PICK UP transmits the driving force from the MAIN MOTOR to the ROLLER ASSY-FEED.

## SENSOR-PHOTO IN

The SENSOR-PHOTO IN detects whether paper is present on the MPF.

## SENSOR ASSY-MPF

The SENSOR ASSY-MPF detects the width (length in the main scanning direction) of paper on the MPF.


Detecting paper size
The size of paper on the MPF is transmitted to the SENSOR ASSY-MPF by moving the MPF paper guide, and is determined by the PWBA MCU F.
Paper sizes that can be automatically detected are as follows:

| Paper size | Width (mm) | Feed length (mm) |
| :---: | :---: | :---: |
| Side-Guide Stopper <br> (min.) | 84 | - |
| Paper detection area <br> (min.) | 88.2 | - |
| $3.5 " \times 8.5 " S E F$ | 88.9 | 215.9 |
| Post Card SEF | 101.6 | 152.4 |
| 5.5" x 8.5" SEF | 139.7 | 215.9 |
| Postcard LEF | 148 | 100 |
| A6 LEF | 148 | 105 |
| A5 SEF | 148 | 210 |
| Post Card LEF | 152.4 | 101.6 |
| B6 LEF | 182 | 128.5 |
| B5 SEF | 182 | 257 |
| Monarch LEF | 190.5 | 98.4 |
| A5 LEF | 210 | 148 |
| A4 SEF | 210 | 297 |
| 5.5" x 8.5" LEF | 215.9 | 139.7 |
| $5.5 " \times 11 "$ SEF (Letter) | 215.9 | 279.4 |


| $5.5 " \times 13 "$ SEF (Legal) | 215.9 | 330.2 |
| :---: | :---: | :---: |
| $5.5 " \times 14 "$ SEF (Legal) | 215.9 | 355.6 |
| DL LEF | 220 | 110 |
| C5 LEF | 229 | 162 |
| C4 SEF | 229 | 324 |
| Rectangular LEF | 235 | 120 |
| Com10 LEF | 241.3 | 104.8 |
| B5 LEF | 257 | 182 |
| B4 SEF | 257 | 364 |
| Executive LEF | 266.7 | 184.2 |
| $16 K ~ L E F ~ T F X(P R C) ~$ | $267(270)$ | $194(195)$ |
| 8K SEF TFX(PRC) | $267(270)$ | $389(390)$ |
| $8.5 " \times 11 "$ SEF (Letter) | 279.4 | 215.9 |
| $11 " \times 17 "$ LEF | 279.4 | 431.8 |
| A4 LEF | 297 | 210 |
| A3 SEF | 297 | 420 |
| Stopper (max.) | 303 | - |

## Xero

CRU
The CRU is made up of the following main six components.

- Drum

The Drum is composed of a photoconductive surface layer (an insulator in the dark but becomes conductor when receiving light) and a conductive inner layer (aluminum cylinder).
The Drum retains electric charges on the surface in the dark, and becomes conductive when exposed to light.

- BCR

The BCR (Bias Charge Roll) uniformly distributes negative charges on the Drum surface.

- Auger

The Auger is a spiral mixer to stir toner supplied from the Toner Cartridge and carriers in the Drum Cartridge.

- Magnet Roll

The Magnet Roll retains developer in a thin layer on its surface, and feeds toner to the gap between the Drum and the Magnet Roll.

- Finger

The Finger is a mechanism to prevent paper from being caught.

- Cleaning Blade

The Cleaning Blade scrapes toner remaining after the transfer step off the drum surface.

## HSG ASSY-BTR

The BTR of the HSG ASSY-BTR is driven by direct contact with the Drum of the CRU.
The BTR applies positive charges to the rear surface of the paper when the paper passes between the BTR and Drum. The negatively charged toner image is attracted by positive charges on the rear surface of the paper. Thus, the toner image is transferred from the drum surface to the paper surface.


## ROS ASSY

The ROS ASSY-12 scans the drum surface with a laser beam. It consists of four main components: LD (Laser Diode) PWB, ROS MOTOR, POLYGON MIRROR, and SOS PWB.

## (1) LD PWB

The LD PWB generates a laser beam with the two LDs of LD1 and LD2. The beam is turned ON or OFF according to a print data signal.

## (2) ROS MOTOR / POLYGON MIRROR

The Polygon Mirror is mounted to the shaft of the ROS Motor, and is rotated at a high speed by the ROS Motor. The mirror rotation shifts the incidence and reflection angles of a laser beam to scan the laser beam in the drum axial direction. The laser beam reached the Polygon Mirror passes through the Lens L1, Lens L2 and Window, and then arrives at the drum surface.

## (3) SOS PWB

When a laser beam hits the SOS Sensor on the SOS PWB, the beam is converted to an electrical signal (SOS signal), and detects the initial position where a scan starts on each line.
When a laser beam is scanned across the drum surface from one end to the other while turning ON and OFF the beam, one line of latent image is created. If the scanning by the laser beam is repeated while rotating the drum, a two-dimensional image is created. The resolution in the scanning direction (from right to left) is determined by the rotational speed of the ROS Motor, depending on how quickly the laser is adjusted. The resolution in the process direction (from top to bottom) is determined by the rotational speed of the ROS Motor. (The higher the scanning speed becomes, the earlier scanning of the next row can be started.)


Fuser
Heat Roll
The Heat Roll is a hollow metal tube with its surface coated. This tube is heated by the inner Heater Rod. The heat is applied to the paper passing between the Heat Roll and Pressure Roll, fusing and fixing the toner on the paper.
Pressure Roll
The Pressure Roll is a metal shaft coated with sponge rubber. Pressure is applied to the paper between the Pressure Roll and Heat Roll, pressing the melted toner against the paper.
Heater Rod
The Heater Rod of the lamp comprises a quartz glass tube containing a heater coil. A terminal is mounted to the end of the Heater Rod via a harness. Three Heater Rods are provided: the Main Heater Rod to heat entire Heat Roll, and the Sub Heater Rods 1 and 2 to heat the central portion of the Heat Roll.

## Thermostat

If the Heat Roll temperature exceeds the preset temperature, the Thermostat cuts off the circuits of the Main Heater Rod and Sub Heater Rods 1 and 2.

## Center Thermistor

The Center Thermistor monitors the surface temperature of the paper-feed portion of the Heat Roll to control ON/OFF of the Main Heater Rod and Sub Heater Rods 1 and 2.
Rear Thermistor
The Rear Thermistor monitors the surface temperature at rear side of the Heat Roll to switch the heater rod to use.
Pressure Roll Thermistor
The Pressure Roll Thermistor monitors the temperature of the Pressure Roll to control the idling time for fuser warm-up before printing.
Fuser Exit Sensor
The Fuser Exit Sensor detects the arrival of paper at the detection point in the exit area of the Fuser, and also detects the ejection of paper from this point.


## Exit

The Exit1 is a component to eject printed paper from the printer to the Face Down Tray. With the optional Exit2 installed, it is also possible to eject paper to the Exit2 Face Down Tray by changing the orientation of the Gate-Exit 1 on the Exit1.
MOTOR ASSY 242
The MOTOR ASSY 242 drives the ROLL ASSY OCT that feeds paper to each tray. With the optional Duplex installed, this motor also has a function to reversely feed paper to the Duplex.
ROLL ASSY OCT
The ROLL ASSY OCT feeds printed paper from the Fuser to the Face Down Trays. SENSOR-PHOTO IN

The SENSOR-PHOTO IN detects Exit1 Face Down Tray full by moving the ACTUATOR up and down.

GATE-EXIT 1
The GATE-EXIT 1 switches the paper transport path. When the GATE-EXIT 1 is lifted, paper is fed to the Exit1 Face Down Tray. When it is lowered, paper is fed to the Exit2 Face Down Tray.


## Drive

MAIN ASSY 242
The MAIN ASSY 242, comprising the Main Motor, Fuser Motor and gears, transmits driving force to the components of the printer.
Main Motor
The Main Motor is a DC brushless motor to drive the ROLL ASSY OCT, FUSER ASSY, ROLL ASSY REGI, and ROLLER ASSY-TA.
Drum Motor
The Drum Motor is a DC brushless motor to drive the CRU Drum, Mag Roll and HSG ASSYBTR.


## Electrical Components and Controller

## SWITCH-POWER

Turning ON/OFF the SWITCH-POWER supplies/cuts off the main power of the printer.

## OUTLET MN

The OUTLET MN supplies the power to the Finisher directly from the main POWER UNIT. SWITCH (24V Interlock Switch)

The SWITCH ( 24 V Interlock Switch) is a safety switch to cut off a 24 VDC power supply from the POWER UNIT to the PSHV-Y2, PWBA MCU F and to the MOTOR ASSY 242, while the COVER ASSY FRONT and the COVER ASSY-LH are open.
SWITCH ASSY XERO INTLK (5V Interlock Switch)
The SWITCH ASSY XERO INTLK (5V Interlock Switch) is a safety switch to cut off a 5 VDC power supply from the POWER UNIT to the LD PWB of the ROS ASSY-12 while the CRU is removed.

SWITCH-I/L,CAB
The SWITCH-I/L,CAB detects open/close of the COVER ASSY LH LOW C.
FAN FUSER
The FAN FUSER discharges air from the printer to prevent excessive temperature increase. POWER UNIT

The POWER UNIT generates low voltages ( 5 V and 3.3 V for logic circuits, 5 V for Laser Diodes, and 24 V for motors/clutches) from AC power. It also contains the Fuser Relay to feed/cut off AC power to the Heater Rod of the FUSER ASSY. PSHV-Y2

The PSHV-Y2 generates AC power and a high DC voltage, and feeds them to the charging (BCR), development (Magnet Roll), transfer (BTR), and peeling (Detack Saw) units. PWBA MCU F

The PWBA MCU F controls printing operation based on the communication with the Print Controller and on sensor/switch information. It also controls optional module boards.

The PWBA ESS connected to the PWBA MCU F controls the entire system. ROLLER ASSY-TA

The ROLLER ASSY-TA feeds paper from the Tray2 or an optional tray to the CRU or Fuser. ROLLER ASSY REGI

The ROLLER ASSY REGI feeds paper from the Tray2, optional tray or MPF to the CRU or Fuser.


## Control

## Paper Size Control

## Paper Cassette Feeding

The following table gives the states (ON/OFF) of the switches on the Switch ASSY P S, corresponding to the paper sizes of the Paper Cassette.

NOTE The switches on the Switch ASSY P S are denoted by "S/W2", "S/W4", "S/W3", "S/W5", and "S/W1" respectively from the left side.

| Paper Size | ANALOG SWITCH |  |  |  | DIGITAL SWITCH |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | S/W1 | S/W2 | S/W3 | S/W4 | S/W5 |
| No Cassette | OFF | OFF | OFF | OFF | OFF |
| 5.5 " $\times 8.5$ "SEF/A5 SEF | OFF | OFF | ON | OFF | OFF |
| B5 SEF | OFF | OFF | ON | ON | ON |
| 8.5 " $\times 13$ "SEF | OFF | ON | OFF | ON | OFF |
| 8.5" x 14"SEF | OFF | ON | OFF | ON | ON |
| A4 SEF | OFF | ON | ON | OFF | OFF |
| 8.5 " $\times 11$ "SEF | OFF | ON | ON | OFF | ON |
| A4 LEF | ON | OFF | ON | OFF | OFF |


| A3 SEF | ON | OFF | ON | ON | OFF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| B5 LEF/Executive LEF | ON | ON | OFF | OFF | ON |
| 8K SEF(TFX/GCO) | ON | ON | OFF | ON | OFF |
| B4 SEF | ON | ON | OFF | ON | ON |
| $8.5^{\prime \prime} \times 11 " L E F ~$ | ON | ON | ON | OFF | OFF |
| $16 K ~ L E F(T F X / G C O) ~$ | ON | ON | ON | OFF | ON |
| $11 " \times 17 " L E F ~$ | ON | ON | ON | ON | ON |

## ROS Control

## Rotation of ROS Motor

The ON/OFF control of the ROS Motor is performed according to the mode of operation as shown below.

| Operation mode | ROS Motor ON/OFF |
| :--- | :--- |
| Standby mode | Always OFF |
| Print mode | Turns ON upon receiving the signal from the <br> controller, and turns OFF after a preset time has <br> passed from the end of printing. Also turns OFF <br> if a print command is not received within 30 sec- <br> onds from the reception of the signal. |
| Sleep mode | Always OFF |

## Determination of ROS Ready

The ROS goes into ready state after the specified period passes since the reception of the ROS MPA start signal and the SOS cycle exceeds the reference value.

## ROS Reference Value

| ROS reference value | Description |
| :---: | :--- |
| Ready reference value | SOS signal interval (equivalent to 98\% or more of the rated rpm of <br> the ROS Motor) |
| Fail reference value | SOS signal interval (less than 98\% of the rated rpm of the ROS <br> Motor) |

## Fuser Control

## Fuser Control Method

The ON/OFF control of the Main/Sub Heater Rods is performed based on the Fuser control temperature. The Fuser transits between the five states (Warm UP, Ready, Standby, Print, and Low Power) depending on the Heat Roll surface temperature or printer conditions.
The Fuser temperature control starts when the Fuser Ready in the POWER UNIT is turned ON after a preset time period has passed from power ON. If a failure occurs, the Heater Rods are turned OFF, then the Fuser Ready is turned OFF, and then the Fuser temperature control is stopped.

## Main/Sub Heater Rods ON/OFF Control

The Center and Rear Thermistors detect the Heat Roll surface temperature (Fuser temperature) to regulate the temperature at the target control temperature by turning ON or OFF the Main/Sub Heater Rods.
Fuser Warm-up

The Fuser warm-up starts at the time of power ON, interlock open/close, jam reset, or return from the Low Power mode, and ends when the Ready temperature is attained, when a failure occurs, or when executing Diagnosis.
Schematic Diagram of Safety System


## 1000 Sheet Feeder

## Driving Force Transmission Path

## Main Motor

The rotating force of the MAIN MOTOR is transmitted through the gears to components that need mechanical driving force as shown in the following flow.


## Paper Transport

Paper Transport Path

Paper is supplied from the Tray3 or Tray4, and is transported to the printer along the paper transport path shown below.


## Layout of Paper Transport Path

The following is a cross section of the FIO laser printer and the optional 2 TRAY MODULE, showing main components directly associated with the paper path and transport.

- Main components associated with the paper transport



## Paper Transport

## Paper Transport Path

Paper is supplied from the Tray3 or Tray4, and is transported to the printer along the paper transport path shown below.


## Layout of Paper Transport Path

The following is a cross section of the FIO laser printer and the optional 2 TRAY MODULE, showing main components directly associated with the paper path and transport.

- Main components associated with the paper transport



## Functions of Main Components

When the optional 2 TRAY MODULE is installed under the printer, additional trays are available. The following chapters outline the functions of the main components of the 2 TRAY MODULE.
10.1 Paper Cassette
10.2 Paper Feeder
10.3 Main Components

## Paper Cassette

It is necessary to adjust the FRONT SIDE GUIDE ASSY, REAR SIDE GUIDE and END GUIDE on the Paper Cassette to match the paper size.

FRONT SIDE GUIDE ASSY and REAR SIDE GUIDE
The FRONT SIDE GUIDE ASSY can be adjusted to different paper sizes by moving it to the front or rear. These guides come into contact with the front and rear edges of the paper and hold it in position.
The REAR SIDE GUIDE moves together with the FRONT SIDE GUIDE ASSY.

## END GUIDE

The Paper Cassette is so designed that it can adapt to the paper length in the paper feed direction by moving the END GUIDE to the left or right.

## BOTTOM PLATE

The force pushing up the BOTTOM PLATE is transmitted by the driving force of the MOTOR on the FEEDER ASSEMBLY to the LIFT UP SHAFT through the GEAR (13T/60T) and SECTOR GEAR (60T). The BOTTOM PLATE is pushed up by turning the LIFT UP SHAFT, which causes the supplied paper to get in contact with the ROLLER ASSY (NUDGER).

- Paper Cassette


Detection of paper size
The paper size to which the cassette is set is transmitted to the switches S/W1 to S/W5 on the TRAY 3/4 PAPER SIZE SWITCH by moving these guides. The paper size is detected by the ON/OFF information of these switches.

Paper sizes that can be automatically detected are as 4.1 Paper Size Control:

## Paper Feeder

Since the Tray3 and Tray4 are functionally equivalent in terms of the TRAY 3/4 PAPER SIZE SWITCH, NO PAPER SENSOR, LEVEL SENSOR and PRE FEED SENSOR, only the components of one tray are described here.

The Paper Feeder is a mechanical unit for supplying paper from the Paper Cassette to the printer. The driving force from the TRAY $1 / 2$ FEED LIFT UP MOTOR on the FEEDER ASSY is transmitted to the three ROLLER ASSYs to feed paper.

When the ROLLER ASSY (NUDGER) picks up some sheets of paper and the remaining paper decreases, the ACTUATOR (SUPPORT ASSEMBLY) of the LEVEL SENSOR lowers accordingly. When the LEVEL SENSOR detects the lowering, the TRAY $1 / 2$ FEED LIFT UP MOTOR is activated to turn the LIFT UP SHAFT and the BOTTOM PLATE is also lifted accordingly. Thus, the remaining paper is ready to be fed out.

TRAY 1/2 FEED LIFT UP MOTOR
This motor is activated to feed paper and to lift the BOTTOM PLATE. When feeding paper, it rotates forward to drive the ROLLER ASSY (NUDGER). When lifting the BOTTOM PLATE, it rotates reversely to drive the tray module gears to turn the LIFT UP SHAFT.

This TRAY 3/4 PAPER SIZE SWITCH switches for setting the size of paper supplied from each Paper Cassette. A signal indicating the set size is transmitted as a voltage to the PWBA MCU F.

## NO PAPER SENSOR

If paper runs out in the Paper Cassette, the ACTUATOR lowers and the flag of the ACTUATOR that has stayed in the NO PAPER SENSOR sensing area leaves there. Thus, the light of the sensor is transmitted. When the sensing area is blocked (paper is present), the signal becomes OFF.

## LEVEL SENSOR

This sensor detects, by the ACTUATOR position, whether paper in the Paper Cassette is lifted. When the flag of the ACTUATOR leaves the LEVEL SENSOR sensing area, the sensor detects that the paper has been lifted.

## PRE FEED SENSOR

This sensor detects a paper jam in the Paper Cassette by the paper position and sensor ON/ OFF time.
The sensor ON/OFF states can be monitored by paper passing through the PRE FEED SENSOR sensing area.


## Main Components

## LEFT COVER INTERLOCK SWITCH

The LEFT COVER INTERLOCK SWITCH detects open/close of the LEFT COVER ASSEMBLY.

TRAY 3 FEED OUT SENSOR
The TRAY 3 FEED OUT SENSOR detects paper fed from the Tray 3 or Tray 4.

## TRAY 4 FEED OUT SENSOR

The TRAY 4 FEED OUT SENSOR detects paper fed from the Tray 4.

## TAKEAWAY ROLL ASSEMBLY

The TAKEAWAY ROLL ASSEMBLY feeds paper from the Tray 3 or Tray 4 to the printer.

## TRAY MODULE PWB

The TRAY MODULE PWB that contains a CPU controls paper feed in the 2 TRAY MODULE upon receiving a command from the PWBA MCU F and sensor/switch information.


## Control

## Paper Size Control

## Paper Cassette Feeding

The following table gives ON/OFF states of the switches on the TRAY 3/4 PAPER SIZE SWITCH, corresponding to the paper sizes on the Paper Cassette.


NOTEThe switches on the TRAY 3/4 PAPER SIZE SWITCH are denoted by "S/W2", "S/W4", "S/W3", "S/W5", and "S/W1" respectively from the left side.

| Paper Size | ANALOG SWITCH |  |  |  | DIGITAL <br> SWITCH |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | S/W1 | S/W2 | S/W3 | S/W4 | S/W5 |
| No Cassette | OFF | OFF | OFF | OFF | OFF |
| 5.5" x 8.5"SEF/A5 SEF | OFF | OFF | ON | OFF | OFF |
| B5 SEF | OFF | OFF | ON | ON | ON |
| 8.5" x 13"SEF | OFF | ON | OFF | ON | OFF |
| 8.5 " $\times 14$ "SEF | OFF | ON | OFF | ON | ON |
| A4 SEF | OFF | ON | ON | OFF | OFF |
| 8.5" x 11"SEF | OFF | ON | ON | OFF | ON |


| A4 LEF | ON | OFF | ON | OFF | OFF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A3 SEF | ON | OFF | ON | ON | OFF |
| B5 LEF/Executive LEF | ON | ON | OFF | OFF | ON |
| 8K SEF(TFX/GCO) | ON | ON | OFF | ON | OFF |
| B4 SEF | ON | ON | OFF | ON | ON |
| 8.5" $\times 11 " L E F ~$ | ON | ON | ON | OFF | OFF |
| $16 K ~ L E F(T F X / G C O) ~$ | ON | ON | ON | OFF | ON |
| $11 " \times 17 " L E F ~$ | ON | ON | ON | ON | ON |

## Exit 2

## Driving Force Transmission Path

## Motor Assy Exit 2

The rotating force of the MOTOR ASSY EXIT2 is transmitted through the gears to components that need mechanical driving force as shown in the following flow.


The transmitted driving force drives the ROLL ASSY-FU, ROLL ASSY-INV and ROLL ASSY OCT through the gears.

## Motor Assy-offset

The rotating force of the MOTOR ASSY-OFFSET is transmitted to component that need mechanical actions as shown in the following flow. The ROLL ASSY OCT goes to the OFFSET position by lateral movement not by rotary motion.


## Paper Transport

## Paper Transport Path

With the optional EXIT2 installed, paper is supplied from the MPF, Tray1 or Tray2, and is transported to the printer along the paper transport path shown below.


## Layout of Paper Transport Path

The following figure illustrates the main components directly associated with the paper path and transport with the optional EXIT2 installed.

- Main components associated with transport of paper



## Functions of Main Components

When the optional EXIT2 is installed on the top of the printer, offset transfer of paper is available with the FIO laser printer.
This chapter outlines the functions of the main components of the EXIT2.

## MOTOR ASSY EXIT 2

The MOTOR ASSY EXIT 2 is a stepping motor to drive the ROLL ASSY-FU, ROLL ASSYINV and ROLL ASSY OCT. Forward rotation of this motor drives these rollers to feed paper to the Exit2 Face Down Tray. Reverse rotation of this motor drives the ROL ASSY-INV to feed paper to the optional DUPLEX.

## MOTOR ASSY-OFFSET

The MOTOR ASSY-OFFSET is a stepping motor to move the ROLL ASSY OCT frontward or rearward. Forward rotation of this motor moves the ROLL ASSY OCT to the front side. Reverse rotation of this motor moves it to the rear side.

## SOLENOID ASSY FU

The SOLENOID ASSY FU is a solenoid to activate the GATE-EXIT, 2 for switching the paper transport path. By lifting the iron core of the SOLENOID ASSY FU, the GATE-EXIT, 2 is raised to eject paper to the Exit2 Face Down Tray.

The PWBA EXIT that contains a CPU controls paper feed in the EXIT2 upon receiving a command from the PWBA MCU F and sensor/switch information.

SWITCH-I/L,CAB
The SWITCH-I/L,CAB detects open/close of the CHUTE LH HIGH.

## SENSOR-PHOTO IN

The SENSOR-PHOTO IN detects whether paper is remaining in the EXIT2.

## SENSOR

The SENSOR also detects whether paper is remaining in the EXIT2.

## OCT POSITION SENSOR

The OCT POSITION SENSOR detects the ROLL ASSY OCT position.

ROLL ASSY-INV / ROLL ASSY OCT
The ROLL ASSY-INV and ROLL ASSY OCT are rollers to eject paper to the Exit2 Face Down Tray or to feed paper to the optional DUPLEX.


## HCF

## Overview

The HCF, a paper feeder connected to the Printer, has a function to feed up to 2,000 sheets of paper. The following outlines the operation of the HCF.
Configuration
The HCF is composed of the following three blocks.

- Tray Block: Contains paper.
- Feeder Block: Feeds paper from the Tray to the Transport Block.
- Transport Block: Transfers paper from the Feeder Block to the Printer.



## Main Functions

In addition to the paper feed feature, the HCF has functions to:

- M/C status monitoring
- Paper size detection
- No-paper detection
- Tray lifting
- Remaining paper volume detection
- Paper jam detection

See the items below for details of each function.

## Paper Capacity

Paper volume loaded in the Tray: 2,000 sheets maximum ( 20 lb 4024 DP )
Paper height: 220 mm maximum

## Paper Size

The HCF accepts the following paper sizes.

- A4 LEF
- B5 LEF
- Letter (8.5" x 11") LEF
- $7.25^{\prime \prime}$ x $10.5^{\prime \prime}$ LEF


## Feedable Paper Weight

56-216 gsm

## Paper Feeding

## Outline

The HCF feeds paper from the Tray to the IOT through the Feeder Block and the Transport Block.

This block comprises Roll Assy Nudger (called "Nudger Roll" hereafter) to feed paper from the Tray, Roll Assy Feed ("Feed Roll" hereafter) and Roll Assy Retard ("Retard Roll" hereinafter) to feed paper from the Nudger Roll to the Transport Block.
These rollers are driven by the Feed Motor (stepping motor) on the Feeder Assy HCF at prescribed timings.
The paper fed by the Feed Roll and Retard Roll passes through the Pre Feed Sensor installed in the following stage.

The Pre Feed Sensor detects the presence of paper fed from the Tray.
The Pre Feed Sensor controls the Feed Motor speed, and ON/OFF operation of the Nudger Solenoid.

Transport Block
This block transfers paper fed from the Feeder Block to the IOT with the Roller Assy TA ("Take Away Roll" hereinafter) and with the roller installed inside the Cover Assy Top.

The Take Away Roll is driven by the Motor Assy (stepping motor) ("T/A Motor" hereinafter) installed on the rear side.

The paper fed with the Take Away Roll passes through the Feed Out Sensor installed in the following stage.
The Feed Out Sensor detects the presence of paper fed from the Tray, and controls the Feed Motor stop and the T/A Motor speed. It also detects paper jams to identify paper jam zone.


## Feeder Block Operation

Upon receiving the feed start signal from the controller, the HCF activates the Nudger Solenoid after a preset time has passed to press the Nudger Roll against the paper in the Tray.
Further, after a preset time has passed after receiving the feed start signal, the HCF rotates forward the Feed Motor to feed paper from the Tray to the Feed Roll side with the Nudger Roll.
When the end of paper reaches the Pre Feed Sensor (reflective photo-sensor) and the Sensor turns ON, the Nudger Solenoid is deactivated so that the Nudger Roll separates from the paper in the Tray
The Nudger Solenoid keeps activated at high-voltage for a specified time from its actuation. After that, it still keeps activated at low-voltage until it is deactivated. If the HCF receives the feed start signal for the next paper while the solenoid is activated at low-voltage, it maintains the actuation state at the low-voltage, while pressing the Nudger Roll against the paper in the Tray.
When the paper is transferred to the IOT and the Feed Out Sensor turns ON, the Nudger Solenoid is re-activated for a preset time.

Feed Motor start/stop timing and revs are controlled based on the Feed Motor Start signal and the Pre Feed Sensor ON timing.
Thus, paper is fed from the Tray to the Transport Block.


## Transport Block Operation

Upon receiving the feed start signal from the controller, the HCF activates the T/A Motor at a high speed after a preset time has passed. This rotating power of the T/A Motor is transmitted to the Take Away Roll, and the paper from the Feeder Block is transferred to the IOT.

When the Feed Out Sensor (photo-sensor) is turned ON (light receiving) by the paper fed with the Take Away Roll, the T/A motor speed decreases after a preset time has passed.
When the Regi Sensor in the IOT is turned ON by the paper fed from the HCF, the T/A Motor starts stopping by the trigger of the sensor ON.
When the next feed start signal is received before the T/A Motor is turned OFF, however, the T/A motor continues to rotate.

Thus, paper is transferred from the Transport Block to the IOT.


Feeder Block Sensor/Motor Functions
Functions of the sensors and motors of the Feeder Block are outlined below.
(1) Feed Motor

The Feed Motor is a stepping motor that rotates forward the Nudger Roll and Feed Roll to feed paper from the Tray to the Transport Block. The motor also lifts the Tray by reverse rotation. (For details, see Sections 5 and 7.)
(2) Nudger Solenoid

The Nudger Solenoid raises or lowers the Nudger Roll. The solenoid keeps activated from the beginning of paper feed until the Pre Feed Sensor turns ON.
The solenoid is activated when the Tray is inserted and when the power is turned ON to check the presence of paper in the Tray. (For details, see Section 6.)
(3) Pre Feed Sensor

The Pre Feed Sensor detects whether paper has been fed from the Tray, and controls the Feed Motor speed. The sensor also becomes a trigger to deactivate the Nudger Solenoid. The sensor turns ON upon detecting paper, and determines that paper is present.
(4) T/A Motor

The T/A Motor is a stepping motor that rotates the Take Away Roll to feed paper to the IOT.

## (5) Feed Out Sensor

The Feed Out Sensor detects whether paper has been fed from the Tray, and becomes a trigger to stop the Feed Motor and also to control the T/A Motor speed.
The sensor turns ON (light receiving) upon detecting paper, and determines that paper is present.


## M/C Status Monitoring

This function includes detection of static paper jams, interlocking, and insertion of the Tray.

## Static Paper Jam Detection

Checks the states of all relevant sensors on the paper path to detect paper jams. When paper is present on the sensor, it is treated as a static jam. This detection of paper jam is carried out during the startup procedure and at every Jam/Fail detection. The states of all relevant sensors are checked during the startup procedure. In addition, the sensor states are always checked at every constant time for the Jam/Fail detection, in order to monitor the variation in sensor levels.

## Interlock Detection

Checks the "Open" state of the Transport Cover Interlock Switch and the Home Position Switch. This checking is constantly carried out while the power is ON.
When "Open" of the Transport Cover Interlock Switch is detected, printing operation is inhibited, and the 24 V supply to the Feed Motor and the T/A Motor is shut off. When "Open" of the Home Position Switch is detected, transfer of paper from the HCF is inhibited.


## Tray Insertion Detection

The Tray In Sensor checks whether the Tray is properly set. This checking is constantly carried out while the power is ON. Printing operation is inhibited if the Tray In Sensor OFF (Tray is not present) is detected before starting printing.


Functions of sensors used for M/C status monitoring The following outlines the functions of the sensors used for monitoring M/C status.
(1) Transport Cover Interlock Switch (Safety interlock)

Detects open/close of the Transport Cover. The ON state of this switch indicates that the Transport Cover is closed.
(2) Home Position Switch

Detects the coupling of the HCF with the IOT. The OFF state of this switch indicates that the HCF is separated from the IOT. In this case, transfer of paper is inhibited.
(3) Tray In Sensor

Detects insertion of the Tray into the HCF. This sensor turns ON when the Tray is properly inserted. While it is OFF, paper feeding from the Tray is inhibited.

## Paper Size Detection

Paper size is automatically detected by loading paper in the Tray and by the GUIDE ASSY SIDE $R$ that is attached to the Tray and aligned with the side of paper. The position of the GUIDE ASSY SIDE R is detected by the HCF Size Sensor R and the HCF Size Sensor L.

NOTE Detectable paper size and sensor level pattern are as follows:

| Table 1: Paper Size | Table 2: HCF Size <br> Sensor R | Table 3: HCF Size <br> Sensor L |
| :--- | :--- | :--- |
| B5L | OFF | OFF |
| $7.25^{\prime \prime} \times 10.5^{\prime \prime} \mathrm{L}$ | ON | OFF |
| $8.5^{\prime \prime} \times 11^{\prime \prime} \mathrm{L}$ | OFF | ON |
| A4L |  |  |

(Note: B5L and 7.25 " $\times 10.5^{\prime \prime} \mathrm{L}$ can be switched by the NVM.)


Detection of paper size is carried out during the startup procedure, and when a specified time has passed from the Tray In Sensor level change "OFF to ON" with the Tray inserted. Paper size is also detected at every constant time. When the same size has been detected a specified times consecutively, the size of paper loaded in the Tray is determined.
If a sensor level pattern does not match any of those in the above table, paper size cannot be determined. In this case, though the Tray is lifted, print start by feeding paper from the Tray is inhibited.

Function of the sensor used for paper size detection
The following outlines the function of the sensor used for detecting paper size.
(1) Size Sensors

There are two Size Sensors: HCF Size Sensor R and HCF Size Sensor L.
By moving the GUIDE ASSY SIDE R to turn ON/OFF these sensors, and by using the resulting sensor level patterns, paper size can be determined.

## Tray Lifting

Tray lift operation starts automatically when the Tray is inserted with paper loaded.
The paper is lifted and stops at the feeding position. At the same time, detection of no paper and remaining paper volume becomes available.

The Tray lifting operation when the power is turned ON or when the Tray is inserted is carried out in the following procedure.

- Activate the Nudger Solenoid.
- Check the Level Sensor status a specified time has passed after the Nudger Solenoid is activated.
- When the sensor is OFF, rotate reversely the Feed Motor to lift the Tray.

When the sensor is turned ON by the lift operation, stop the Feed Motor after a specified time has passed to stop lifting the Tray.
If the sensor is ON at power ON, the Tray is regarded to be already at the feeding position. Therefore, the Tray is no longer lifted.

While paper is being transferred to the IOT, the Tray lifting is carried out in the following procedure.

- If Level Sensor OFF is detected when the Nudger Solenoid is deactivated during paper feeding, quick lifting of the Tray is carried out.
In this case, rotate reversely the Feed Motor a specified time has passed after completion of the paper transfer to the IOT, and then stop the motor after a specified time has passed. The quick lifting is carried out while the motor is rotating reversely. The Nudger Solenoid is deactivated during the quick lifting. At this time, the Nudger Roll is off the paper, and therefore no paper is fed.

The tray lift operation is not carried out when a paper jam occurs in the HCF or when the Transport Cover Interlock Switch or the Home Position Switch detects Interlock Open.

Lowering the Tray is carried out when the Tray is removed. No motor is used during the lowering operation. The Tray descends only by the paper weight and the PLATE ASSY BOTTOM.


## No-Paper Detection

This function checks whether paper is loaded or not in the Tray.
When paper is present, the actuator in the middle of the HCF is raised by the lifting of paper and leaves the sensing area of the No Paper Sensor (photo-sensor), which makes the sensor lightreceivable. Thus, presence of paper is detected.
On the other hand, if paper end occurs when the Tray is at the feeding position, the actuator comes inside the sensing area of the No Paper Sensor, which blocks the light transmission of the sensor. Thus, "No-Paper" is detected.
If the Tray is not lifted, the actuator remains in the sensing area of the sensor, while blocking the light transmission of the sensor. In this case, "No-Paper" is determined regardless of the presence of paper in the Tray.


Detection of "No-Paper" is carried out at every constant period after the lifting operation is completed.
When "No-Paper" is detected, paper transfer from the HCF is inhibited.
If "No-Paper" is detected during printing, print operation of the next paper is stopped. However, when the printer is operating in the ATS Mode and there is paper of the same size in another Tray, paper is automatically fed out of the Tray.

Function of sensor used for No-Paper detection
The following outlines the function of the sensor used for detecting No-Paper.
(1) No Paper Sensor

Detects whether paper is present or not in the Tray.
When this sensor is OFF (light receiving) while the Tray is at the feeding position, the presence of paper is detected.

## Remaining Paper Volume Detection

This function determines the paper volume remaining in the Tray by using the Feed Motor rotation time and the Level Sensor ON timing during the Tray lifting time. Thus, the printer notifies operators of remaining paper volume as $25 \%, 50 \%, 75 \%$, FULL, or 0 (zero).

If the remaining paper volume becomes zero before "No-Paper" is detected, the indication remains at (25\%).
When the No Paper Sensor detects "No-Paper", the indication becomes (0) (zero).

When a fault occurs, determination of remaining paper volume is carried out as shown below.

- When the Interlock becomes open during lifting operation

Remaining paper volume is determined based on the total of the time until Interlock open + the time from the Feed Motor forward/reverse rotation until the Level Sensor ON.

- When the power is turned OFF and ON during lifting operation

Remaining paper volume is determined by the lifting time after power ON. (In this case, be careful that the actual volume of the remaining paper in the Tray may differ from the indication.)

- When the power is turned OFF and ON while the Tray is at the feeding position

If the Level Sensor is ON when the power is turned ON, the remaining paper volume before the previous power OFF is regarded as the remaining paper volume at that time.
If the sensor is OFF when the power is turned ON, the HCF regards that the Tray has been removed, and determines the remaining paper volume based on the time from the Feed Motor forward/reverse rotation until the Level Sensor ON.
Function of sensor used for remaining paper volume detection
The following outlines the function of the sensor used for detecting the volume of remaining paper
(1) Tray Level Sensor

Detects the paper feeding position (paper height) in the Tray to control the paper position. While this sensor is OFF, lifting the Tray is continued until the sensor turns ON.


## Tandem Tray

## Driving Force Transmission Path

## Main Motor

The rotating force of the MAIN MOTOR is transmitted through the gears to components that need mechanical driving force as shown in the following flow.


The driving force transmitted to the GEAR drives the TAKEAWAY ROLL ASSEMBLY through the clutch and gears.

## Paper Transport

## Paper Transport Path

Paper is supplied from the Tray3 or Tray4, and is transported to the printer along the paper transport path shown below.


## Layout of Paper Transport Path

The following is a cross section of the FIO laser printer and the optional TANDEM TRAY MODULE, showing main components directly associated with the paper path and transport.

- Main components associated with the paper transport



## Functions of Main Components

When the optional TANDEM TRAY MODULE is installed under the printer, additional trays are available.
The following chapters outline the functions of the main components of the TANDEM TRAY MODULE.
24.1 Paper Cassette
24.2 Paper Feeder
24.3 Main Components

## Paper Cassette

It is necessary to adjust the FRONT SIDE GUIDE and REAR SIDE GUIDE on the Paper Cassette to match the paper size.

## FRONT SIDE GUIDE / REAR SIDE GUIDE

The FRONT SIDE GUIDE can be adjusted to different paper sizes by moving it to the front or rear. These guides come into contact with the front and rear edges of the paper and hold it in position.
The REAR SIDE GUIDE moves together with the FRONT SIDE GUIDE.

## BOTTOM PLATE

Regarding the Tray3, the force pushing up the BOTTOM PLATE is transmitted by the driving force of the MOTOR on the FEEDER ASSEMBLY to the LIFT SHAFT ASSEMBLY through
the GEAR ASSEMBLY (Tray 3). The BOTTOM PLATE is pushed up via the TRAY CABLE, F/R CABLE and F/L CABLE by the rotation of the LIFT SHAFT ASSEMBLY, which causes the supplied paper to get in contact with the ROLLER ASSY (NUDGER).
Regarding the Tray4, the force pushing up the BOTTOM PLATE is transmitted to the LIFT SHAFT ASSEMBLY through the GEAR ASSEMBLY (Tray 4). The BOTTOM PLATE is pushed up via the FRONT TRAY CABLE and REAR TRAY CABLE by the rotation of the LIFT SHAFT ASSEMBLY, which causes the supplied paper to get in contact with the ROLLER ASSY (NUDGER).

- Tray3 Paper Cassette

- Tray4 Paper Cassette


Detection of paper size
The paper size to which the cassette is set is transmitted to the switches S/W1 and S/W3 on the TRAY $3 / 4$ PAPER SIZE SWITCH by moving these guides. The paper size is detected by the ON/OFF information of these switches.
Paper sizes that can be automatically detected are as 4.1 Paper Size Control:

## Paper Feeder

Since the Tray3 and Tray4 are functionally equivalent in terms of the TRAY 3/4 PAPER SIZE SWITCH, NO PAPER SENSOR, LEVEL SENSOR and PRE FEED SENSOR, only the components of one tray are described here.

The Paper Feeder is a mechanical unit for supplying paper from the Paper Cassette to the printer. The driving force from the TRAY $1 / 2$ FEED LIFT UP MOTOR on the FEEDER ASSY is transmitted to the three ROLLER ASSYs to feed paper.

When the ROLLER ASSY (NUDGER) picks up some sheets of paper and the remaining paper decreases, the ACTUATOR (SUPPORT ASSEMBLY) of the NO PAPER SENSOR lowers accordingly.

## TRAY 1/2 FEED LIFT UP MOTOR

This motor is activated to feed paper and to lift the BOTTOM PLATE. When feeding paper, it rotates forward to drive the ROLLER ASSY (NUDGER).

TRAY 3/4 PAPER SIZE SWITCH
This TRAY 3/4 PAPER SIZE SWITCH switches for setting the size of paper supplied from each Paper Cassette. A signal indicating the set size is transmitted as a voltage to the PWBA MCU F.

NO PAPER SENSOR
If paper runs out in the Paper Cassette, the ACTUATOR (SUPPORT ASSEMBLY) lowers and the flag of the ACTUATOR (SUPPORT ASSEMBLY) that has stayed in the NO PAPER SENSOR sensing area leaves there. Thus, the light of the sensor is transmitted. When the sensing area is blocked (paper is present), the signal becomes OFF.

## LEVEL SENSOR

This sensor detects, by the ACTUATOR position, whether paper in the Paper Cassette is lifted. When the flag of the ACTUATOR leaves the LEVEL SENSOR sensing area, the sensor detects that the paper has been lifted.

## PRE FEED SENSOR

This sensor detects a paper jam in the Paper Cassette by the paper position and sensor ON/ OFF time.

The sensor ON/OFF states can be monitored by paper passing through the PRE FEED SENSOR sensing area.


## Main Components

## LEFT COVER INTERLOCK SWITCH

The LEFT COVER INTERLOCK SWITCH detects open/close of the LEFT COVER ASSEMBLY.

The TRAY 3 FEED OUT SENSOR detects paper fed from the Tray 3 or Tray 4.

TRAY 4 FEED OUT SENSOR
The TRAY 4 FEED OUT SENSOR detects paper fed from the Tray 4.

TAKEAWAY ROLL ASSEMBLY
The TAKEAWAY ROLL ASSEMBLY feeds paper from the Tray 3 or Tray 4 to the printer.

## TRAY MODULE PWB

The TRAY MODULE PWB that contains a CPU controls paper feed in the TANDEM TRAY MODULE upon receiving a command from the PWBA MCU F and sensor/switch information.

LEFT COVER INTERLOCK SWITCH


## Paper Size Control

## Paper Cassette Feeding

The following table gives ON/OFF states of the switches on the TRAY 3/4 PAPER SIZE SWITCH, corresponding to the paper sizes of the Paper Cassette.

NOTE The switches on the TRAY 3/4 PAPER SIZE SWITCH are denoted by "S/W1" and "S/W3" respectively from the left side.

| Paper Size | ANALOG SWITCH |  |
| :---: | :---: | :---: |
|  | S/W1 | S/W3 |
| No Cassette | OFF | OFF |
| B5L/7.25" $\times 10.5 " \mathrm{~L}$ | OFF | ON |
| $8.5^{\prime \prime} \times 11 " \mathrm{~L}$ | ON | OFF |


| A 4 L | ON | ON |
| :---: | :---: | :---: |

## Duplex

## Driving Force Transmission Path

## MOTOR ASSY DUP

The rotating force of the MOTOR ASSY DUP is transmitted through the gears to components that need mechanical driving force as shown in the following flow.


The transmitted driving force drives the ROLLER DUP A3L (UPPER), ROLLER ASSY DUP and ROLLER DUP A3L (LOWER) through the gears.

## Paper Transport

## Paper Transport Path

With the optional DUPLEX installed, paper is supplied from the MPF, Tray1 or Tray2, and is transported to the printer along the paper transport path shown below.


## Layout of Paper Transport Path

The following figure illustrates the main components directly associated with the paper path and transport with the optional DUPLEX installed.

- Main components associated with transport of paper



## Functions of Main Components

When the optional DUPLEX is installed to the left of the printer, duplex (double-sided) printing is available with the FIO laser printer.
The following outlines the functions of the main components of the DUPLEX.

## SWITCH-I/L,CAB

The SWITCH-I/L,CAB detects open/close of the COVER DUP.

## SENSOR-PHOTO IN

The SENSOR-PHOTO IN detects whether paper is remaining in the Duplex.

ROLLER DUP A3L (UPPER/LOWER) / ROLL ASSY DUP
The ROLLER DUP A3L (UPPER), ROLLER DUP A3L (LOWER) and ROLL ASSY DUP refeed the paper printed on the front side, through the Duplex to the printer to print on the rear side.

## PWBA DUPLEX

The PWBA DUPLEX that contains a CPU controls paper feed in the Duplex upon receiving a command from the PWBA MCU F and sensor/switch information.

The MOTOR ASSY DUP transmits driving force to the ROLLER DUP A3L (UPPER), ROLL ASSY DUP and ROLLER DUP A3L (LOWER) that feed paper.


## Finisher

## Overview

The Finisher performs post-processing, such as stapling, punching, and stacking paper transferred from the IOT, and ejects paper to the Top Tray or the Stacker Tray.

The following outlines the operation of the Finisher.

## Configuration

The Finisher is composed of the following five blocks:

- Horizontal-Transport Block to feed paper from the IOT to the Finisher (called "H-TRA" hereafter)
- Puncher Block to punch paper
- Compile Tray Block to align paper
- Stapler Block to staple a set of paper at specified positions
- Stacker Tray Block to stack paper



## Paper Size and Weight

The following shows paper sizes and weight that the Finisher can handle, as well as applicable functions for each paper size.
The IOT and the Finisher handle different paper sizes and weights. For this reason, if the IOT has printed paper that the Finisher cannot handle, the Exit Gate in the IOT is switched to eject the paper from Exit 2 onto the H -TRA.

Paper Size/Orientation and Applicable Functions

| Paper size | Inches | $\begin{aligned} & \text { SEF/ } \\ & \text { LEF } \end{aligned}$ | mm (Finished Size) | Top <br> Tray | Stacker |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | Stack | Stack | Offset Stack | Punch (*1) | Staple |
| B5 |  | SEF | $182 \times 257$ | Yes | No | No | No | No |
|  |  | LEF |  | Yes | Yes | Yes | Yes 2 | Yes |
| Executive | $7.25 \times 10.5$ | SEF | $184.2 \times 270$ | Yes | No | No | No | No |
|  |  | LEF |  | Yes | Yes | Yes | $\begin{gathered} \text { Yes } \\ 2,3,4 \end{gathered}$ | No |
| Letter | $8.5 \times 11$ | SEF | $215.9 \times 279.4$ | Yes | Yes | Yes | Yes 2 | Yes |
|  |  | LEF |  | Yes | Yes | Yes | $\begin{gathered} \text { Yes } \\ 2,3,4 \end{gathered}$ | Yes |
| A4 |  | SEF | $210 \times 297$ | Yes | Yes | Yes | Yes 2 | Yes |
|  |  | LEF |  | Yes | Yes | Yes | $\begin{aligned} & \text { Yes } \\ & 2,3,4 \end{aligned}$ | Yes |
| XXX | $8,5 \times 13$ | SEF |  | Yes | Yes | Yes | Yes 2 | Yes |
| Legal | $8.5 \times 14$ | SEF |  | Yes | Yes | Yes | Yes 2 | Yes |
| B4 |  | SEF | $257 \times 364$ | Yes | Yes | Yes | Yes 2 | Yes |


| A3 |  | SEF | $297 \times 420$ | Yes | Yes | Yes | Yes |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Ledger | $11 \times 17$ | SEF |  | Yes | Yes | Yes | Yes |  |
| Custom size | Same width <br> with <br> standard <br> size |  |  | Yes | Yes | Yes | Yes | Yes |
| Custom size | Besides <br> above |  |  | Yes | Yes (*2) | Yes (*2) | No | No |

Note:
*1: Numbers $(2,3,4)$ mean 2 holes, 3 holes, and 4 holes, respectively.
*2: Applicable within the following range:
Paper width: 203.2-297 mm
Paper length: 182-431.8 mm

Paper Wight

- For punching: 52-176 gsm
- For stapling:52-226 gsm (*1)
- For ejecting in the Stacker Tray:52-226 gsm
- For ejecting in the Top Tray:52-226 gsm
(*1: The amount of paper capable of being stapled will be less than 50 if paper weight is greater than 90 gsm .)


## Functions and Applicable Trays

| Processing | Destination of paper |
| :---: | :---: |
| No post-processing | Top Tray or Stacker Tray |
| Punching | Top Tray or Stacker Tray |
| Stapling | Stacker Tray |
| Punching \& Stapling | Stacker Tray |

## Paper Transfer

This section describes transfer of paper from the IOT to a specified tray.
The following figures illustrate layouts (side view viewing from the front side) of sensors, rollers, and main blocks, as well as a layout (rear view) of the main components.

< Finisher >




## H-TRA

When the Finisher is designated by the command of IOT, the Exit Gate in the IOT opens and paper is fed from Exit 1 on the H-TRA.
The H-X'port Motor is activated by the trigger of IOT's Regi Clutch ON to drive the feed belts in the H-TRA. The motor power is transmitted to the two belts between Shaft Assembly (Right) and Shaft Assembly (Left).
The paper fed to the H-TRA is securely held between the belts and the Pinch Rolls, and fed to the Finisher.


## From H-TRA to Puncher

The paper fed from the H-TRA is fed into the Finisher by the Roll Assy Ent located on the X'port section of the Finisher that is driven by the Finisher Transport Motor.
Paper route inside the Finisher is determined by the Transfer Gate.
The Transfer Gate is switched by the Transport Gate Solenoid ON/OFF controlled by the IOT.

The paper is further fed in the Finisher by the Roll Assy-Transfers or the Buffer Roll that are driven by the Regi Motor, and passes through the Puncher.
The X'port Entrance Sensor becomes "LOW" upon detecting paper. After a certain time has passed from the level transition to "H", the Regi Motor that drives the Roll Assy-Transfers or the Buffer Roll, starts reverse rotation.
The paper is returned to the Puncher by the Roll Assy-Transfers or the Buffer Roll, and is stopped with its end gently pressed against the Guide Assy.

The stopper in the Guide Assy lies to let paper pass through when feeding paper to the exit (while the Regi Motor is rotating forward), but rises when paper is returned (while the Regi Motor is rotating reversely) to stop the paper.
Thus, punch hole positions in the paper feed direction are determined. (For determining punch hole positions in the paper width direction, see Section 3.)


## From Puncher to Compile Tray

The paper is transferred to the Compile Tray by the Buffer Roll (driven by the Regi Motor) and by the Roll Assy-Exit Low (driven by the Exit Motor).
When the first paper reaches the Compile Tray, the Eject Clamp Motor is activated to lower the Eject Clamp so that the Eject Clamp and the Shaft Assy-Eject Roll can clamp the paper.
Thus, the paper transferred from the Puncher is held by the Shaft Assy-Eject Roll and the Eject Clamp driven by the Eject Motor, and is fed to the exit.
When the paper rear end passes through the Compile Exit Sensor, the Eject Motor starts reverse rotation to return the paper to the Compile Tray.

When the following paper reaches the Compile Tray, the Eject Clamp is raised and the paper that has passed through the Roll Assy-Exit Low falls on the Compile Tray.
At this time, the Main Paddle is rotated by the Shaft Assy-Paddle (driven by the Finisher Transport Motor) to feed the paper so that the paper rear end butts against the rear wall of the Compile Tray.
The Sub Paddle Solenoid of the Chute Assy Eject is activated to lower the Sub Paddle (driven by the Finisher Transport Motor) so that the paper can be fed to the Compile Tray.


When printing multiple sets, while stapling the first set on the Compile Tray or ejecting it to the Stacker Tray, the first paper of the second set shall not be fed to the Compile Tray.
To this end, when the first paper of the second set reaches the Finisher, the Buffer Gate Solenoid is activated by the IOT command and by the X'port Entrance Sensor to switch the Buffer Gate. Thus, the paper route is switched in the Buffer Roll's circumferential direction. (This operation is called "Buffer Path" hereafter.)
The first paper of the second set is aligned with the second paper, and then they are fed together to the Compile Tray.

Even for one sheet of paper, the Buffer Path operation is executed in the same way. The paper is stacked temporarily on the Compile Tray, and then ejected in the Stacker Tray.
After Buffer Path is executed for the first paper, if the second paper of a different size comes, the first paper is fed to the Compile Tray, but the second one is fed to the Compile Tray without Buffer Path. At this time, a certain delay time is provided to avoid the second paper from colliding with the first one.


## From Compile Tray to Stacker Tray

Stapled paper on the Compile Tray (stapling mode) or aligned paper (non-stapling mode) are held between the Eject Clamp (lowered by the Eject Clamp Motor) and the Shaft Assy-Eject Roll. The Shaft Assy-Eject Roll is driven by the Eject Motor to transferred paper to the Stacker Tray. After paper is transferred to the Stacker Tray, it is held by the Paddle-Set Clamp attached to the Shaft Assy-Eject Roll.

## From Puncher to Top Tray

The paper to be ejected to the Top Tray is switched the paper path by the Transfer Gate located behind the Puncher, and fed in the Roll Assy-Transfer direction.
The Transfer Gate is switched by the Transport Gate Solenoid. While the solenoid is activated, paper is fed in the Roll Assy-Transfer direction.
The two Roll Assy-Transfers driven by the Regi Motor feed paper to the Roll Assy-Exit Top at the top of the Finisher.
The Roll Assy-Exit Top driven by the Exit Motor to eject the paper to the Top Tray.
The Roll Assy-Exit Top decelerates after a pre-specified period of time from the following trigger events.

1. Models without puncher: ENT SNR transition to "Low".
2. Models with puncher: Restart of the Roll Assy-Exit Top after punching



## Functions of Sensors along the Paper Path

H-TRA

1. H-X'port Entrance Sensor

A photo-interrupter to detect whether paper is fed from the IOT to the H-TRA
It turns " H " (+5 V) (light receiving) when paper enters the H-TRA.
2. H-X'port Exit Sensor

A photo-interrupter to detect whether paper passes through the H-TRA It turns " H " ( +5 V ) (light receiving) when paper reaches this sensor, and turns "L" ( 0 V ) when paper exits from the H-TRA.
3. H-X'port Interlock Sensor

A photo-interrupter to detect open/close of the Cover Assy Top of the H-TRA It turns "H" (+5 V) (light receiving) when the Cover Assy Top opens.


Finisher

1. X'port Entrance Sensor

A reflective photo-sensor to detect whether paper is fed from the H -TRA to the Finisher turns " H " ( +5 V ) while paper is present within the sensing area.
When the level turns " H " due to the first paper of the second set during multi-set printing, activates the Buffer Gate Solenoid to switch the Buffer Gate so that the paper goes in the Buffer Roll's circumferential direction.
2. Gate Sensor

A reflective photo-sensor to detect the front end of paper it turns " L " ( 0 V ) when the front end reaches the sensing area.
3. Compile Exit Sensor

A photo-interrupter to detect whether paper passes through the Compile Exit Sensor it turns "H" (+5 V) (light receiving) when the actuator is driven out of the sensing area by the paper.
When the level tunes "H", activates the Front Tamper Motor and the Rear Tamper Motor on the Compile Tray.
This sensor is also used to control ON/OFF of the Eject Motor.
4. Compile Tray No Paper Sensor

A photo-interrupter to detect whether paper is present or not on the Compile Tray.
While paper is present, the actuator is outside the sensing area, and the sensor turns at " H " (+5 V) (light receiving).
5. Buffer Path Sensor

A photo-interrupter to detect whether paper is fed toward the Buffer Roll
While paper is present, the actuator is outside the sensing area, and the sensor turns at " H " (+5 V) (light receiving).
6. Top Tray Exit Sensor

A photo-interrupter to detect whether paper is fed to the Roll Assy-Exit Top at the exit side of the Top Tray
When the paper is fed, the actuator leaves from the sensing area, and the sensor tunes " H " (+5 V).
7. Top Tray Full Sensor

A reflective photo-sensor to detect the stack volume of paper in the Top Tray


## Puncher

This section describes the paper punching operation of the Puncher.

Four types of Puncher are provided: 2/3-hole type, 2/4-hole type, 2-hole type and 3-hole type. (For overseas specifications, 2/3-hole type, 2/4-hole type and 3-hole type are provided.) The following explains the 2/3-hole type (2-hole/3-hole auto-switching).
Every type has the same construction, except for the Punch Hole Select Sensor that is provided for the 2-hole type and 3-hole type only. But the sensor is not working currently.

## Adjusting Punching Positions

The punching positions from the paper edge in the direction of feed are determined by gently pressing the paper against the Guide Assy (see Section 2.2).

While the punching positions from the paper edge in the direction of paper width are determined by the following method.

- Activate the Puncher Move Motor and move the Puncher to the front side until the Puncher Move Home Sensor turns " L ".
- Rotate reversely the motor and move the Puncher to the rear side until the sensor turns"H" to determine the home position.
- The Puncher Move Motor is run to move the puncher to the front until the Side Regi Sensor1 or 2 detects the paper edge, and then the puncher is further moved to the front according to the pulse-number determined by the paper size.(The Puncher Move Motor stops at this position.)



## Punching

After punching positions are determined, activate the Puncher Motor to move the Cam Plate. With the movement of the Cam Plate, the pins descend along the guide holes to punch the paper.

This operation is performed for each sheet of paper.
The Cam Plate can lower the pins even while it is moving to the front or rear side.
The Puncher Motor is rotated forward or reversely for each sheet of paper, which is triggered by the Puncher Front Sensor ON/OFF.


## Detecting Punch Dust Full

Punch dust is stored in the Punch Dust Box.
A sensor is provided to detect punch dust full.
When punch dust full is detected, it is notified to the operator only once.
Even if punch dust is not removed, the finisher can still punch paper. However it can spread punch dust inside the machine.

## Detecting Punch Dust Box

The Punch Box Set Sensor detects whether the Punch Dust Box is properly set.
When the sensor does not detect that the box is properly set for four seconds, the punch dust box count is reset. This time period can be changed by rewriting the non-volatile memory.

## Functions of Puncher Sensors/Motors

## 1. Side Regi Sensor 1

A reflective photo-sensor to detect the side edge of large paper
Paper side edge is detected by ON/OFF of this sensor while shifting the Puncher (containing this sensor) in the direction of paper width. The sensor remains at "H" (+5 v) while paper is present, and turns " $L$ " when paper side edge is detected.
2. Side Regi Sensor 2

A reflective photo-sensor to detect the side edge of small paper. This sensor has the same function as the Side Regi Sensor 1.
3. Puncher Move Home Sensor

A photo-interrupter to detect the home position of the moving Puncher. It turns "H" (+5 v) (light blocking) when the home position is detected.
4. Puncher Home Sensor

A photo-interrupter to detect the home position of the Cam Plate that lowers the punching pins. It turns "H" (+5 V) when the home position is detected.
5. Punch Hole Select Sensor

A photo-interrupter to detect the rear position of the Cam Plate. It turns "H" (+5 V) when the rear position is detected. This sensor also detects the Cam position to switch punch holes (2-hole/3-hole).
6. Puncher Front Sensor

A photo-interrupter to detect the front position of the Cam Plate. It turns " H " (+5 V) when the front position is detected. This sensor is used to determine to which side (front or rear) the Cam Plate should be moved.
7. Puncher Motor Sensor

A photo-interrupter to detect pulse generated by the actuator attached to the Puncher Motor. It counts Puncher Motor revolutions, and becomes a trigger to stop the motor (by shutting off the current).
8. Puncher Move Motor

A stepping motor to move the Puncher in the paper width direction
9. Puncher Motor

A DC motor to move the Cam Plate that lowers the punching pins. Forward rotation of the motor moves the Cam Plate to the front side, and reverse rotation moves it to the rear side.
10. Punch Box Set Sensor

A photo-interrupter to detect whether the Dust Box is properly set. When the Punch Dust Box is properly set, the actuator of the box blocks the light transmission of the sensor, which turns the sensor to " H " (+5 V).
11. Punch Full Sensor

A photo-interrupter to detect the Punch Dust Box is filled with punch dust.


## Compile Tray

This section describes the operation of the Compile Tray that aligns the paper edge transferred from the Puncher.

## Outline of Operation

When paper is fed onto the Compile Tray, tamping operation is performed to align the paper edge in the paper width direction.
When ejecting stapled sets of paper to the Stacker Tray, if they are stacked in the Stacker Tray with the same staple position, the height of the stapled portion will increase. This will cause improper compiling of paper due to butting of the following paper. To prevent such improper compiling, offsetting is required by shifting the staple position between sets of paper.


## Capacity of Compile Tray

Paper volume that can be stacked on the Compile Tray is limited as shown in the table below. The number of sheets depends on whether paper is stapled or not, as well as on paper size.

If the number of sheets of one set to be stapled exceeds the limit, the exceeding sheets are not stacked on the Compile Tray, and are forcibly ejected to the Stacker Tray without being stapled. This forcible ejection is performed to prevent damage to the Staple Assembly.

When feeding large paper in the non-staple mode, there may be a misalignment depending on paper characteristics. For this reason, the default paper capacity is set to a smaller value.

Compile Tray Paper Capacity
$\left.\begin{array}{|c|c|c|c|}\hline \text { Condition } & \text { Min. } & \text { Default } & \text { Max. } \\ \hline \text { Staple mode } & 2 & 50 & 75 \\ \hline \text { For small paper (less than 216 mm in the feed direction) } \\ \text { in non-staple mode }\end{array}\right) 10 \quad 50 \quad 100$

## Compile Tray Operation with Multiple Paper Sizes

When two or more paper sizes are used and their widths are same (example: A4L and A3S), all the sheets are compiled and stapled as a set on the Compile Tray, and then ejected to the Stacker Tray.
While if two or more paper sizes with different paper width are used, stapling paper on the Compile Tray is stopped when a different size is detected. Such different-size sheets of paper are forcibly ejected to the Stacker Tray.

## Tamping

When paper is fed from the Puncher to the Compile Tray, tamping operation is performed to align the paper in the paper width direction on the Compile Tray.
Tamping is an operation to align paper to the specified position on the Compile Tray using the Front Tamper or Rear Tamper by moving them to the end of paper by the respective motors. Tamping is executed each time when a sheet of paper reaches the Compile Tray. Additional tamping is executed after tamping the last sheet.
There are three types of tamping.

- Front Tamping

Tampering by the Rear Tamper with the Front Tamper fixed at the home position

- Rear Tamping

Tampering by the Front Tamper with the Rear Tamper fixed at the home position

- Center Tamping

Tampering by the Front and Rear Tampers to align paper to the almost center

## Front Tamping

Front Tamping is used in the following cases.

- In the non-staple mode
- When executing front stapling (corner)

The tamper positions during Front Tamping are shown below:


1. Front Tamper home position (Front Tamper Home Sensor position)
2. Front Tamper size position
3. Front Tamper offset position
4. Rear Tamper home position (Rear Tamper Home Sensor position)
5. Rear Tamper standby position
6. Rear Tamper tamping position
7. Rear Tamper offset position

## Rear Tamping

Rear Tamping is used in the following cases.

- When executing rear stapling (corner)
- When executing dual stapling
- The tamper positions during Rear Tamping are shown below:


1. Front Tamper home position (Front Tamper Home Sensor position)
2. Front Tamper tamping position
3. Front Tamper offset position
4. Rear Tamper home position (Rear Tamper Home Sensor position)
5. Rear Tamper size position
6. Rear Tamper offset position

## Center Tamping

Center Tamping is used in the following case.

- When executing rear stapling (straight)

The tamper positions during Center Tamping are shown below:
Front Tamper Home Sensor


1. Front Tamper home position (Front Tamper Home Sensor position)
2. Front Tamper standby position
3. Front Tamper tamping position
4. Front Tamper offset position
5. Rear Tamper home position (Rear Tamper Home Sensor position)
6. Rear Tamper standby position
7. Rear Tamper size position
8. Rear Tamper offset position

## Determining Tamper Home Position

When the Compile Exit Sensor turns "H" (+5 V) (light receiving), the Front and Rear Tamper Motors on the Compile Tray are activated, and the Front and Rear Tampers start moving. The Front Tamper home position is determined when the Front Tamper enters the Front Tamper Home Sensor sensing area.
In the same way, the Rear Tamper home position is determined when the Rear Tamper enters the Rear Tamper Home Sensor sensing area.

## Tamping

Tamping is executed after a preset time has passed after the Compile Tray No Paper Sensor turns "H" (+5 V) when paper is detected on the Compile Tray.

## Offsetting

Offsetting is an operation to shift the position of paper to be ejected to the Stacker Tray so that boundaries between paper units (sets of paper, job unit, etc.) can be easily recognized.
Offsetting is executed for staple positions.

## During Front Stapling (Corner)

Shifts stapled sheets using the Front Tamper by 20 mm to the rear side before ejecting them to the Stacker Tray.

## During Rear Stapling (Corner/Straight)

For paper with a width of 216 mm or more [Rear Staple (Corner)]:
Shifts stapled sheets using the Rear Tamper by 20 mm to the front side before ejecting them to the Stacker Tray.

For paper with a width of less than 216 mm [Rear Staple (Straight)]:
Shifts stapled sheets using the Front Tamper by 9 mm to the rear side before ejecting them to the Stacker Tray.

During Dual Stapling
Shifts stapled sheets using the Front Tamper by 9 mm to the rear side before ejecting them to the Stacker Tray.
Offsetting is not executed ( 0 mm ) for small paper.

## Functions of Compile Tray Sensors/Motors

1. Compile Tray No Paper Sensor

A photo-interrupter to detect whether paper is present or not on the Compile Tray. When paper is detected, the actuator leaves the sensing area, which turns the sensor to "H" (+5 V) (light receiving).
2. Front Tamper Home Sensor

A photo-interrupter to detect the Front Tamper home position. When the Front Tamper comes to the home position, it enters the sensor's sensing area, which turns the sensor to "H" (+5 V) (light blocking).
3. Rear Tamper Home Sensor

A photo-interrupter to detect the Rear Tamper home position. When the Rear Tamper comes to the home position, it enters the sensor's sensing area, which turns the sensor to " H " (+5 V) (light blocking).
4. Front Tamper Motor

A stepping motor to move the Front Tamper for tamping. Clockwise rotation of this motor moves the Front Tamper to the rear side. Counterclockwise rotation of this motor moves the tamper to the front side.
5. Rear Tamper Motor

A stepping motor to move the Rear Tamper for tamping. Clockwise rotation of this motor moves the Rear Tamper to the front side. Counterclockwise rotation of this motor moves the tamper to the rear side


## Stapler

This section describes the operation of the Stapler.

## Stapling Operation

Sheets of paper fed from the Puncher are tamped on the Compile Tray, and then stapled at specified positions by the command of IOT.

## Staple Positions

There are the following four stapling modes.

## Front Staple (Corner) [Front Corner]

The Stapler staples a set of paper obliquely (45 degrees) after the Rear Tamper aligns the paper to the front side.


## Dual Staple [Dual]

The Stapler staples a set of paper at fixed positions (front/ rear sides) in parallel with the paper edge, after the Front Tamper aligns the paper to the specified position for each paper size.
Rear Staple (Straight) [Rear Straight]
This type of stapling is applied for paper with a width of less than 216 mm .
The Stapler staples a set of paper in parallel with the paper edge after the Front Tamper aligns the paper to the rear side.
Rear Staple (Corner) [Rear Corner]
This type of stapling is applied for paper with a width of 216 mm or more.

The Stapler moves to the rear corner and staples a set of paper obliquely ( 45 degrees) after the Front Tamper aligns the paper to the rear side.

## Paper Sizes That Allow Stapling

Paper size that allows stapling depends on stapling positions.
The following table shows paper sizes and the applicability of stapling for each staple position.

|  | Front <br> Corner | Rear <br> Corner | Rear <br> Straight | Dual |
| :---: | :---: | :---: | :---: | :---: |
| A3SEF | Yes | Yes | No | Yes |
| A4LEF | Yes | Yes | No | Yes |


| $11 \times 17$ SEF | Yes | Yes | No | Yes |
| :---: | :---: | :---: | :---: | :---: |
| $8.5 \times 11$ LEF | Yes | Yes | No | Yes |
| 8KSEF(GCO), 16KLEF(GCO) | Yes | Yes | No | Yes |
| B4SEF, B5LEF | Yes | Yes | No | Yes |
| $8 \times 10 L E F$ | Yes | Yes | No | Yes |
| $8.5 \times 14$ SEF $/ 8.5 \times 13 S E F / 8.5 \times 11 S E F$ | Yes | No | Yes | Yes |
| A4SEF | Yes | No | Yes | Yes |
| $8 \times 10$ SEF | Yes | No | Yes | Yes |

Yes: Applicable
No: Not applicable

### 0.1 Stapling One Sheet

Upon receiving the stapling command from the IOT with one sheet remaining on the Compile Tray, the Finisher ejects the paper to the Stacker Tray without stapling it.

### 0.2 Stapling Multi-Size Paper

When sheets with different sizes and same width (example: A4L and A3S) are present on the Compile Tray, all the sheets are stapled, and then ejected to the Stacker Tray.

While if sheets with different widths are present on the Compile Tray, stapling is stopped when a different width is detected. Such different-width sheets are forcibly ejected to the Stacker Tray.

### 0.3 Paper Limits for Stapling

The number of sheets to be stapled is limited to prevent damage to the Stapler.

- If the number of sheets of one set to be stapled exceeds the limit of the Compile Tray, the exceeding sheets are not stacked on the Compile Tray, and are forcibly ejected to the Stacker Tray without being stapled.
- After the forcible ejection of paper, if the number of following sheets of one set to be stapled exceeds the limit of the Compile Tray, the exceeding sheets are also ejected forcibly to the Stacker Tray without being stapled.
- After that, even if the number of following sheets of one set to be stapled falls within the limit, the sheets are also ejected forcibly to the Stacker Tray without being stapled.


Upper limit of Compile Tray paper capacity when stapling: default: 50 (variable (10 to 100) by the non-volatile memory),

### 0.4 Stapler Operation

The Stapler stays at the front home position, that is, at the Front Staple (Corner) position when the power is turned ON.
The Stapler starts stapling when a set of sheets to be stapled is stacked on the Compile Tray.
The Stapler does not move during stapling in the Front Staple mode.
In any mode other than the Front Staple mode, the Stapler moves to the specified position, and then perform stapling


## Stapler Head

Stapling operation is executed by closing the Stapler Head.
The Stapler Head, containing the Staple Motor, the Staple Home Sensor, the Self Priming Sensor, and the Low Staple Sensor, is activated by the Staple Motor.
Forward (clockwise) rotation of the motor drives the Stapler to staple a set of sheets, and returns the stapling unit to the home position.
If stapling fails, the motor rotates reversely (counterclockwise) to return the Stapler Head to the home position.
When staples become low, the Low Staple Sensor detects it and stapling stops automatically displaying an alarm message. The message is also displayed when the Staple Cartridge is not installed.


## Functions of Stapler Sensors/Motors

1. Stapler Move Home Position Sensor

A photo-interrupter to detect the Stapler home position, Rear Staple (Corner) position, and Rear Staple (Straight) position. It turns "H" (+5 V) (light blocking) when the Stapler comes at the specified position.
2. Stapler Move Motor

A DC motor to move the Stapler Head. Clockwise rotation of this motor moves the Stapler Head to the rear side, while counterclockwise rotation moves the Stapler Head to the front side.
3. Low Staple Sensor (in the Stapler Head). A photo-interrupter to detect near end of staples It turns "H" (+5 V) when staples become 20 staple left.
4. Self Priming Sensor (in the Stapler Head)

A photo-interrupter to detect that staples are at the Stapler Head end, and also to detect failure in stapling. " L " $(0 \mathrm{~V})$ (light blocking) when stapling is ready.
5. Staple Home Sensor (in the Stapler Head)

A photo-interrupter to detect the Stapler Head home position, and also to detect failure in stapling. This sensor also functions as a trigger to stop the Staple Motor. It turns "L" ( 0 V ) (light blocking) while the Stapler Head stays at the home position.
6. Staple Motor (in the Stapler Head)

A DC motor to activate the Stapler Head for stapling. Clockwise rotation of this motor enables stapling, while counterclockwise rotation returns the Stapler Head.


## Operation

The Top Tray contains the Top Tray Full Sensor to detect the paper stack volume in the Top Tray. Once the sensor detects "full stack" (500 sheets) of the Top Tray, ejection of paper to the Top Tray is inhibited until "full stack" is reset.

## Functions of Top Tray Sensors

1. Top Tray Exit Sensor

A photo-interrupter to detect that paper has come to the Roll Assy-Exit Top at the exit of the Top Tray. When paper reaches the Roll Assy-Exit Top, the actuator leaves the sensing area, which turns the sensor to "H" (+5 V).
2. Top Tray Full Sensor

A reflective photo-sensor to detect the paper stack volume in the Top Tray. It turns"H" (+5 V) when it detects "full stack".

## Stacker Tray

The Stacker Tray goes up and down to an appropriate position according to the volume of paper fed from the Compile Tray so as to properly stack paper to "full stack".

## Operation

The Stacker Tray moves to an appropriate position according to the volume of paper fed from the Compile Tray. The Stacker Height Sensor 1 and the Stacker Height Sensor 2 detect the height of paper in the Stacker Tray, and the Stacker Encode Sensor determines the volume of paper in the tray.
When paper or the Stacker Tray comes between the light emitter and the photo-receiver of the Stacker Height Sensor 1 and Stacker Height Sensor 2, the emitted light is blocked and the sen-
sors turn "H". The height of paper or the Stacker Tray is detected based on the levels of these sensors.

(Driven by Regi Motor)
This sensor information is used to control the Elevator Motor. The motor is activated to move the Stacker Tray while the Stacker Height Sensor 1 turns into the light blocking state to the light receiving state.


The Stacker No Paper Sensor is turned ON or OFF by the Actuator attached to the Carriage Assy R on the rear side of the Finisher. In case the Stacker Tray abnormally goes up above the Stacker No Paper Sensor, the Upper Limit Sensor is installed above the Stacker No Paper Sensor for the protection against the abnormal operation.

If an operator removes paper from the Stacker Tray during printing, it is detected by the Stacker Height Sensor 2, and the ejection of paper to the Stacker Tray is inhibited. Then the Elevator Motor is activated to move the Stacker Tray to the Stacker Height Sensor 1 sensing area. Thus, the ejection of paper to the Stacker Tray is restored.
If an operator removes paper from the Stacker Tray while printing is stopped, it is detected by the Stacker Height Sensor 2. After three seconds have passed, the Elevator Motor is activated to move the Stacker Tray to the Stacker Height Sensor 1 sensing area. Thus, the ejection of paper to the Stacker Tray is restored.

The Stacker Tray lowers according to the volume of paper it contains. If any obstacle under the tray hinders the tray from lowering, "Stacker Lower safety Warning" is detected and the Stacker Tray is stopped.


## Full Stack Detection

"Full stack" is detected when paper in the Stacker Tray becomes full to prevent paper jam or falling of paper to the floor. The Stacker Tray can stack up to approx. 3000 sheets.
The paper volume in the Stacker Tray is detected at every 10\% (approx. 300 sheets) and notified to the Controller.

Furthermore, the Stacker Tray can stack up to 200 sets (default) of stapled paper. (This value can be changed by the non-volatile memory between 10 and 200.)
The Stacker Tray can continue to stack paper until paper volume reaches either of the limits above.

In the "mix stacking" mode, all the sizes are allowed until paper volume of approx. 300 sheets in the Stacker Tray is detected.
The "mix stacking" means one of the following cases:

- A larger (any side of paper) sheet of paper is stacked on a smaller sheet

Example: A4LEF ( $297 \times 210$ ) paper is stacked on A4SEF ( $210 \times 297$ ) paper.
Note:
When B5LEF ( $257 \times 182$ ) paper is stacked on A4LEF (297x210) paper, this is not "mix stacking".

- A sheet of paper of less than 11 inches is stacked in the Stacker Tray with the Staple Mode changed.

- An operator put a sheet (or sheets) when no paper is remaining in the Stacker Tray. The size and condition of paper stacked in the tray are not identified.)
- Paper was present in the Stacker Tray when power was turned ON.

The size and condition of paper stacked in the tray are not identified.)

- The Finisher entered the Sleep Mode with "mix stacking" and then has exited the Sleep Mode.
- The post-processing mode has changed.


## Functions of Stacker Tray Sensors/Motors

## 1. Stacker Height Sensor 1

A pair of light emitter and photo-receiver to detect the height of paper in the Stacker Tray. This sensor is used to control the Elevator Motor. When blocked by paper or the tray, this sensor turns " H " deciding that the Stacker Tray is above the reference level. To the contrary, when receiving light, this sensor turns "L" deciding that the Stacker Tray is below the reference level. The" $H$ " to " $L$ " turning point of the sensor is defined as the reference level.
2. Stacker Height Sensor 2

A pair of light emitter and photo-receiver to detect the height of paper in the Stacker Tray (same function as Stacker Height Sensor 1). This sensor is also used to control the Elevator Motor. When blocked by paper or the tray, this sensor turns "H" deciding that the Stacker Tray is above the reference level. To the contrary, when receiving light, this sensor turns "L" deciding that the Stacker Tray is below the reference level.
3. Stacker No Paper Sensor

A photo-interrupter to detect that the Stacker Tray is at the highest position, and also to detect "no paper". When the Actuator attached to the Carriage Assy R enters the sensing area, the emitted light is blocked, which turns the sensor to " H " ( +5 V ).
4. Upper Limit Sensor

A photo-interrupter to detect the Stacker Tray's abnormal elevation above the top position (Stacker No Paper Sensor position). When the Actuator attached to the Carriage Assy R enters the sensing area, the emitted light is blocked, which turns the sensor to "H" (+5 V).
5. Stack Encode Sensor

A photo-interrupter to count pulse of the Encoder attached to the Shaft-Elev. The paper volume in the Stacker Tray is detected based on this count.
6. Elevator Motor

A DC motor to elevate or lower the Stacker Tray. Clockwise rotation elevates the tray, and counterclockwise rotation lowers the tray.
7. Eject Motor

A DC motor to eject stapled or non-stapled paper to the Stacker Tray. Clockwise rotation ejects paper to the Stacker Tray, and counterclockwise rotation reverses the Eject Roll to feed the paper from the Puncher to the Compile Tray.
8. Eject Clamp Motor

A DC motor to elevate or lower the Eject Clamp when feeding paper from the Puncher to the Compile Tray or from the Compile Tray to the Stacker Tray
9. Set Clamp Home Sensor

A photo-interrupter to detect the Set Clamp home position. This sensor functions as a trigger to control ON/OFF of the Set Clamp Clutch.
10. Set Clamp Clutch

When this clutch is activated, it transmits the Eject Motor rotating power to the Shaft AssyEject Roll.


## Power Supply and Interlock

The Finisher is equipped with the following interlock switches.

- Finisher Front Door Switch:

Turns OFF when the Cover Assy Front opens, shutting off the Interlock, +24 VDC line in the Finisher.

- Eject Cover Switch:

Turns OFF when the COVER EJECT on the right side opens, shutting off the Interlock, +24 VDC line in the Finisher.


## Chapter 3 Installation

## Engine

## Installation

## Installation Location

- Get the necessary space for operation of this laser printer.
- Install where the temperature and the humidity meet the following environment:
- During operation: 5 to 35 degrees C / 15 to $85 \%$ RH ( $70 \%$ RH at 35 degrees C, $85 \%$ RH at 32 degrees C).
- No condensation
- Not in operation:-20 to 40 degrees C / 5 to $85 \%$ RH (A place with no condensation)
- Install in a flat place with the angle of gradient of 5 degree or less.
- Install in a place with the illumination of 3000 Lux or less. (Avoid direct sunlight.)
- Avoid a place near a water system, a humidifier or fire, a dusty place, or a place which gets direct air from air conditioning.
- Avoid any location where volatile or flammable gas is generated.
- Avoid an ill-ventilated place.
- Avoid an unstable and non-durable place.


## Unpacking

## Unpacking Laser Printer

Unpack the carton and confirm that the laser printer and the attachments are undamaged.

1) Printer
2) Paper Cassette
3) $C R U$
4) TONER CARTRIDGE
5) Power Cable
6) User Guide





## Installation Procedures

## Installing Laser Printer

1. Unpack the laser printer, and place it in the installation location after removing packing materials as shown in figures A through $E$.
2. Peel off packing tapes applied to the laser printer as shown in figures $F$ through $G$.
3. Remove the packing materials from inside of the printer. $(H, J)$
4. Open the COVER ASSY FRONT, and install the TONER CARTRIDGE (K).
5. Unpack the Toner Cartridge, then be sure to shake it seven to eight times holding both sides (L,M).
6. Unpack the CRU (N).
7. Open the COVER ASSY-LH and install the CRU (O,P).
8. Pull off the seal from the CRU (Q).

NOTE When removing the seal, draw it out straight and horizontally. After the removal, be careful not to shake or give a shock to the CRU.
9. Close the COVER ASSY-LH and COVER ASSY FRONT. (R,S)
10. Draw out the paper cassette and load paper in the cassette ( $\mathrm{T}, \mathrm{U}, \mathrm{V}$ ).
11. Push the paper tray into the laser printer (W).
12. If using only the base unit execute the remaining steps; else, install additional items.
13. Connect the power cord $(X)$.
14. Turn on the power switch of the laser printer $(\mathrm{Y})$.
15. Try some test prints with each of the paper-feed trays to confirm that there is no problem.

## 1000 Sheet Feeder



## Installation

## Unpacking

Unpack the carton, and confirm that all components are accounted for and without any damage.

1) 2 TRAY MODULE unit
2) SCREW ( 2 pcs ) to install the 2 TRAY MODULE

## Installation Procedures

For details, refer to the Instruction Manual supplied with the main unit.

1. Unpack the optional 2 TRAY MODULE, remove packing materials, and check the attached articles.
2. Remove the Tray1 and Tray2 from the printer.
3. Place the printer on the 2 TRAY MODULE so that the three Adjust Pins on top of the two TRAY MODULE is inserted into the holes of the printer.
4. Remove the COVER-CAP MCU on the rear of the printer. Place finger on top edge of option cover cap MCU and push down to release the cover.

5. Connect the harness connector of the cable to the connector on the rear panel of the printer, and then attach the COVER-CAP MCU.

6. Remove Trays 1 and 2.

To remove the trays pull tray 1 out until you hit the stops, then place your hands on the left and right side edges o fthe paper tray. Lift up and pull back towards you with your left hand to release the left side of the tray. Lift up and pull back towards you to release the right side of the tray. Repeat to remove the other tray.
7. Fasten the optional 2 TRAY MODULE to the printer with two Screws.
8. Install the Tray1 and Tray2.
9. Turn ON the power switch of the printer. Note that trays are now displayed in the Operator panel.

## Duplex



## Installation

## Unpacking

Unpack the carton, and confirm that the number of the Option DUPLEX and the attachments, and their appearances have no problem.

1) DUPLEX unit




## Installation Procedures

1) Unpack the optional DUPLEX, remove packing materials, and check the attached articles.
2) Insert the hooks at the lower part of the DUPLEX into the holes on the left side of the printer.
3) Open the COVER DUP and turn the two LOCK DUPs on the DUPLEX to secure the DUPLEX.
4) Remove the COVER-CAP MCU from the rear of the printer.
5) Connect the HARN ASSY DUP A to the connector on the rear panel of the printer, and then attach the COVER-CAP MCU.

6) Turn ON the power switch of the printer.
7) Try some test duplex-printings to confirm that there is no problem.

## Exit 2



## Installation

## Unpacking

Unpack the carton and confirm that the number of the Option EXIT2 and the attachments are undamaged.

1) EXIT2 unit


## Installation Procedures

NOTE The optional EXIT2 can be installed only when the printer is installed with the optional DUPLEX.

1) Unpack the optional EXIT2, remove packing materials, and check the attached articles.
2) Remove the COVER-TOP, EXIT 1 from the printer.
3) Install the EXIT2 on the printer while lifting up the two hooks on the bottom of the EXIT2.

4) Connect the power cord of the printer.
5) Turn ON the power switch of the printer.
6) Try some test duplex-printings to eject the them onto the EXIT2, and confirm that there is no problem.

## High Capacity Feeder (HCF)



## Installation

## Unpacking

Unpack the carton, and confirm that the number of the Option HCF and the attachments, and their appearances have no problem.

1) Option HCF main unit
2) JOINT BRACKET
3) Screws (2 pieces) (For fixing the JOINT BRACKET to the Tandem Tray Module or 2 Tray Module under the printer)



## Installation procedures

1) Unpack the Option HCF, remove packing materials, and confirm the attachments.
2) Install the JOINT BRACKET to the Tandem Tray or 2 Tray Module installed under the laser printer as shown in the figure using the two SCREWs.
3) Move the HCF toward the laser printer so that the projections of the JOINT BRACKET put into the holes of the BRACKET on the HCF to engage them.
4) Remove the HCF Sliding fixing Screw as shown below.

NOTE After removing the Sliding fixing Screw slides the HCF once, and make sure that the HCF is engaged with the printer surely.
5) Connect the connection cable of the HCF to the laser printer.

NOTE When connecting, be sure not to twist and pinch the cable.
6) After installing the equipment, turn on the power switch of the laser printer.
7) Try running some test prints with the newly installed paper-feed tray to confirm that there is no problem.


## Tandem Tray



## Installation

## Unpacking

Unpack the carton, and confirm that the number of the Option TANDEM TRAY MODULE and the attachments, and their appearances have no problem.

1) TANDEM TRAY MODULE unit
2) SCREW (2 pcs) to install the TANDEM TRAY MODULE

## Installation Procedures

1. Unpack the optional TANDEM TRAY MODULE, remove packing materials, and check the attached articles.
2. See " 1000 Sheet Feeder" on page 6 for installtions instructions. The Tandem feeder is installed in a simialr manner.


## Finisher



Horizontal Transport


Finisher

## Installation

## Unpacking

## Unpacking Option Horizontal-Transport

Unpack the carton, and confirm that the number of the Option Horizontal-Transport and the attachments, and their appearances have no problem.

1) Option Horizontal-Transport main unit
2) Screws (2 pieces) (For Horizontal-Transport securing)

## Unpacking Option Finisher

Unpack the carton, and confirm that the number of the Option Finisher and the attachments, and their appearances have no problem.

1) Option Finisher main unit
2) PLATE ASSY DOCKING IOT (1 piece)
3) Screws (2 pieces) (For PLATE ASSY DOCKING IOT securing)


NOTE *There is a box of parts inside the finisher cabinet that must be removed before proceeding to the next step.


## Installation Procedures

## Installing Option Horizontal-Transport

For details, refer to the Instruction Manual supplied with the main unit or Chapter3 RRP25.1 H-TRANSPORT ASSEMBLY.

1) Unpack the Horizontal-Transport, remove packing materials, and confirm the attachments.
2) Remove the ACTUATOR (PL6.2.27) and WEIGHT ASSY-PAPER (PL6.2.28) for full stack sensor on the Exit 1 of the laser printer.
3) Place the Horizontal-Transport on top of the laser printer.
4) Fix the Horizontal-Transport to the laser printer surely using the two SCREWs.

5) After installing the Finisher, connect the connection cable of the Horizontal-Transport to the Finisher.
6) After completing the installation, turn on the power of the laser printer.
7) Try running some test prints with the newly installed equipment to confirm that there is no problem.

## Installing Option Finisher

For details, refer to the Instruction Manual supplied with the main unit or Chapter3 RRP25.2 STAPLE FINISHER.

1) Unpack the Finisher, remove packing materials, and confirm the attachments.
2) Install the PLATE ASSY DOCKING IOT (supplied accessory of the Finisher) to the laser printer as shown in the figure, and fix the PLATE ASSY DOCKING IOT to laser printer surely using two SCREWs.


PLATE ASSY DOCKING IOT
3) Open the COVER ASSY FRONT of the Finisher.
4) Release the BINDING BANDs securing the puncher and stapler with the frame of the Finisher.

5) While pulling the PLATE DOCKING inside the Finisher, move the Finisher toward the laser printer so that the projections of the PLATE ASSY DOCKING IOT put into the holes on the PLATE ASSY DOCKING of the finisher.

6) Release the hand from the PLATE DOCKING to engage the PLATE ASSY DOCKING IOT and PLATE DOCKING.
7) Close the FRONT ASSY COVER of the Finisher.
8) Connect the connection cable of the Horizontal-Transport to the Finisher.
9) Connect the power cord and connection cable to the laser printer.
10) After completing the installation, turn on the power of the laser printer.
11) Try running some test prints with the newly installed equipment to confirm that there is no problem.

## Chapter 4 Wiring

## General Wiring Diagram

The following describes the legend of the general wiring diagram shown on the next page.

| Symbols | Description |
| :---: | :---: |
|  | Denotes a connection between parts with harnesses and wires. |
| XX | A frame not having parts name inside denotes the connector (P/J). Numeric value inside implies the connector number. |
|  | A frame of broken line denotes the connector ( $\mathrm{P} / \mathrm{J}$ ) written in several places separately. <br> Numeric value inside implies the connector number. |
| PWBA ABC PL X.Y.Z | A frame having parts name inside denotes the parts. PL X.Y.Z implies the item "Z" of plate (PL) "X.Y" in Chapter 5. Parts List. |
|  | A frame of dotted line denotes the section in "2. Wiring Diagram between Parts", and numeric value implies the section number. |



## Wiring Diagram between Parts

## Configuration

The wiring diagram is separated into 11 sections to show detailed connection between parts.
1 Power supply

- Connection between POWER UNIT and PWBA ESS
- Connection between POWER UNIT and PWB A EXIT
- Connection between POWER UNIT and PWB A MCU F
- Connection between POWER UNIT and CHOKE COIL
- Connection between POWER UNIT and OUTLET MN
- Connection between POWER UNIT and SWITCH-POWER
- Connection between POWER UNIT and BRACKER GFI INL
- Connection between PWB A MCU F and SWITCH (LH Cover)
- Connection between PWB A MCU F and SWITCH (Front Cover)
- Connection between PWB A MCU F and SWITCH ASSY XERO INTLK

2 Fuser

- Connection between PWB A MCU F and POWER UNIT
- Connection between PWB A MCU F and FUSER ASSY
- Connection between PWB A MCU F and SENSOR PHOTO (Fuser Exit Sensor)
- Connection between POWER UNIT and FUSER ASSY

3 Paper feed

- Connection between PWB A MCU F and CLUTCH ASY REGI H
- Connection between PWB A MCU F and SNR ASSY REGI
- Connection between PWB A MCU F and SWITCH-I/L,CAB
- Connection between PWB A MCU F and SENSOR (Takeaway Sensor)
- Connection between PWB A MCU F and CLUTCH ASSY T/A

4 Xero / Deve

- Connection between PWB A MCU F and PSHV-Y2
- Connection between PWB A MCU F and CRU (ATC Sensor)
- Connection between PWB A MCU F and SENSOR HUM\&TE
- Connection between PWB A MCU F and MOTOR ASSY-DISP 30K

5 Drive / CRUM

- Connection between PWB A MCU F and MOTOR ASSY 242
- Connection between PWB A MCU F and PWBA CRUM CP1 (Xero CRU)
- Connection between PWB A MCU F and PWBA CRUM CP1 (Toner CRU)
- Connection between PWB A MCU F and CRU FAN
- Connection between MOTOR ASSY 242 and FAN FUSER

6 Tray1

- Connection between PWB A MCU F and TRAY1 FEED LIFT UP MOTOR
- Connection between PWB A MCU F and SENSOR (Tray1 Level Sensor)
- Connection between PWB A MCU F and SENSOR (Tray1 No Paper Sensor)
- Connection between PWB A MCU F and SENSOR (Tray1 Pre Feed Sensor)
- Connection between PWB A MCU F and SWITCH ASSY P S (Tray1 Size Sensor)

Tray2

- Connection between PWB A MCU F and TRAY2 FEED LIFT UP MOTOR
- Connection between PWB A MCU F and SENSOR (Tray2 Level Sensor)
- Connection between PWB A MCU F and SENSOR (Tray2 No Paper Sensor)
- Connection between PWB A MCU F and SENSOR (Tray2 Pre Feed Sensor)
- Connection between PWB A MCU F and SWITCH ASSY P S (Tray2 Size Sensor)

8 MPF

- Connection between PWB A MCU F and SENSOR ASSY-MPF
- Connection between PWB A MCU F and SOLENOID PICK UP
- Connection between PWB A MCU F and SENSOR-PHOTO IN (MPF No Paper Sensor)

9 ROS

- Connection between PWBA ESS and ROS ASSY-12
- Connection between PWB A MCU F and ROS ASSY-12

10 EXIT

- Connection between PWB A EXIT and SENSOR-PHOTO IN (OCT Home Sensor)
- Connection between PWB A EXIT and SENSOR-PHOTO IN (Full Stack Sensor)
- Connection between PWB A EXIT and MOTOR ASSY-OFFSET
- Connection between PWB A EXIT and PWB A MCU F

11 Controller

- Connection between PWB A EXIT and PWBA ESS


## Notes on Using the Wiring Diagram between Parts

The following describes the legend of the wiring diagrams between parts shown on the following pages.
NOTE The description of general symbols is omitted.

| Symbols | Description |
| :--- | :--- |
|  | Denotes a plug. |
| P/JXx | Denotes Pin yy and Jack yy of the connector Pxx and Jxx. |
| YY |  |


| Symbols |  |
| :--- | :--- |



| Signal line name | Description |
| :---: | :--- |
| MAIN POWER ON | ON/OFF control signal of Power Supply in POWER UNIT |

- Short protection (over-current protection) \& Over-voltage protection of POWER UNIT
- Each output has the short protection and over-voltage protection functions as shown on the table below:

|  | Output Status |  |  |
| :--- | :---: | :---: | :---: |
|  | 3.3 VDC | 5 VDC | 24 VDC |
| Over-current value | $9-14 \mathrm{~A}$ | $7-11 \mathrm{~A}$ | $14-19 \mathrm{~A}$ |
| 3.3 V short | Cut off | Cut off | Cut off |
| 5V short | Normal output | Cut off | Cut off |
| 24 V short | Normal output | Cut off | Cut off |
| Over-voltage value | $4-5 \mathrm{~V}$ | $6-8 \mathrm{~V}$ | $26.7-32 \mathrm{~V}$ |
| 3.3 V | Cut off | Cut off | Cut off |
| 5 V | Cut off | Cut off | Cut off |
| 24 V | Normal output | Cut off | Cut off |

In the case of short protection (over-current protection) cut off:
After the clearance of the shortage, power off, allow 10 sec . and power on; the output is restored.
In the case of over-voltage protection Cut off:
After the overvoltage protection functions, power off, allow 10 sec . and power on; the output is restored.

## 2 Fuser



| Signal line name | Description |
| :--- | :--- |
| MAIN HEATER ON(H)+5VDC | ON/OFF control signal of Main Heater in FUSER ASSY |
| SUB HEATER1 ON(H)+5VDC | ON/OFF control signal of Sub Heater1 in FUSER ASSY |
| SUB HEATER2 ON(H)+5VDC | ON/OFF control signal of Sub Heater2 in FUSER ASSY |
| RELAY ON(L)+24VDC | ON/OFF control signal of Fuser Relay in FUSER ASSY |
| ZERO CROSS | ZERO CROSS signal |
| CENTER STS SIGNAL | Heart Roll surface temperature data (analog value) mea- <br> sured by Center STS in FUSER ASSY |
| 2ND STS SIGNAL | Heart Roll surface temperature data (analog value) mea- <br> sured by 2nd STS in FUSER ASSY |
| REAR STS SIGNAL | Heart Roll surface temperature data (analog value) mea- <br> sured by Rear STS in FUSER ASSY |
| FUSER EXIT PAPER SENSED(L)+5VDC | Paper detection signal in fuser by Fuser Exit Sensor in <br> FUSER ASSY |

3 Paper Feed


| Signal line name | Description |
| :--- | :--- |
| REGI CLUTCH ON(L)+24VDC | CLUTCH ASY REGI H(Regi Clutch) ON/OFF control <br> signal |
| REGI SENSOR PAPER SENSED(L)+5VDC, | Paper detection signal by SNR ASSY REGI in Regis- <br> tration |
| L/H LOWER COVER OPEN(H)+5VDC | L/H LOWER COVER open/close detection signal by <br> SWITCH-I/L,CAB |
| TAKEAWAY SENSOR SENSED(L)+5VDC | Paper detection signal by SNR TAKEAWAY in trans- <br> port section |
| TAKEAWAY CLUTCH ON(L)+24VDC | CLUTCH ASSY T/A ON/OFF control signal |

## 4 Xero / Deve



| Signal line name | Description |
| :--- | :--- |
| DTS ON | ON/OFF control signal of DTS output |
| BTR MONITOR | Voltage monitor signal of BTR output (analog value) |
| BTR SEL | Polarity switching signal of BTR output |
| BTR REMOTE | Current control signal of BTR DC output (analog value) |
| BCR AC CLOCK | Clock signal od BCR AC output |
| BCR AC ON | ON/OFF control signal of BCR AC output |
| BCR DC REMOTE | ON/OFF control signal of BCR DC output (analog value) |
| DEVE BIAS DC REMOTE | DEVE BIAS DC voltage output signal |
| DEVE BIAS DC ON | ON/OFF control signal of DEVE BIAS DC output |
| ATC SENSOR SIGNAL | Toner concentration in the developing unit detection signal <br> (analog value) measured by ATC Sensor in CRU |
| HUMIDITY SIGNAL | Humidity detection signal (analog value) measured by SEN- <br> SOR HUM\&TE in the machine |
| TEMP SIGNAL | Temperature detection signal (analog value) measured by <br> SENSOR HUM\&TE in the machine |
| DISPENSE MOTOR ON(L) +24VDC | MOTOR ASSY-DISP 30K ON/OFF control signal |

## 5 Drive / CRUM



| Signal line name | Description |
| :--- | :--- |
| FUSER FAN ON | High Speed / Low Speed switching signal of FAN FUSER |
| FUSER FAN FAIL(H)+5VDC | Fail detection signal of FAN FUSER |
| M/C CLOCK | Clock signal from Main Motor in MOTOR ASSY 242 |
| MAIN MOTOR REF CLOCK | Reference Clock signal to Main Motor in MOTOR ASSY 242 |
| MAIN MOTOR ON(L)+5VDC | ON/OFF control signal of Main Motor in MOTOR ASSY 242 |
| DRUM MOTOR FAIL(H)+5VDC | Fail detection signal of Drum Motor in MOTOR ASSY 242 |
| DRUM MOTOR REF CLOCK | Reference clock signal to Drum Motor in MOTOR ASSY 242 |
| DRUM MOTOR ON(L)+5VDC | ON/OFF control signal of Drum Motor in MOTOR ASSY 242 |
| DRUM MOTOR CW/CCW | Rotation direction switching signal of Drum Motor in MOTOR <br> ASSY 242 |
| TX DATA, MUTE, CDET | Read/Write control signal of PWBA CRUM CP1 |
| CRU FAN ON(H)+24VDC | ON/OFF control signal of CRU FAN |
| CRU FAN FAIL(H)+5VDC | Fail detection signal of CRU FAN |

## 6 Tray1



| Signal line name | Description |
| :--- | :--- |
| FMOT1 A, FMOT1 B, FMOT1 /A, FMOT1 /B | TRAY1 FEED LIFT UP MOTOR exciting signal |
| TRAY1 LEVEL UP(H)+5VDC | Rise (paper feed possible level) detection signal of <br> plate in Tray1 by SENSOR (Tray1 Level Sensor) |
| TRAY1 PAPER SENSED(L)+5VDC | Paper detection signal in Tray1 of SENSOR (Tray1 <br> No Paper Sensor) |
| TRAY1 PRE FEED SENSED(L)+5VDC | Feed paper detection signal from Tray1 by SENSOR <br> (Tray1 Pre Feed Sensor) |
| TRAY1 SIZE SWITCH SIGNAL | Paper size detection signal (analog value) of <br> SWITCH ASSY P S (Tray1 Size Sensor) |
| TRAY1 SIZE SWITCH S5 ON(L)+5VDC | S5 in SWITCH ASSY P S (Tray1 Size Sensor) ON/ <br> OFF detection signal |

- Paper size detection
- The ON/OFF pattern of each switch (S1-S5) of SWITCH ASSY P S and the relation of paper size and the output voltage of TRAY1 SIZE SWITCH SIGNAL are as follows.

| Paper Size | S1 | S2 | S3 | S4 | S5 | Output Voltage(V) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| No Tray | OFF | OFF | OFF | OFF | OFF | 4.66A\}0.05 |
| 5.5 "Å~8.5" SEFIA5 SEF | OFF | OFF | ON | OFF | OFF | 4.01Å\}0.05 |
| B5 SEF | OFF | OFF | ON | ON | ON | 3.69£\}0.05 |
| 8.5 "A~13" SEF | OFF | ON | OFF | ON | OFF | $3.07 \AA$ ¢ 0.05 |
| 8.5"A~~14"SEF | OFF | ON | OFF | ON | ON |  |
| A4 SEF | OFF | ON | ON | OFF | OFF | 2.75Å\}0.05 |
| 8.5"Å~11"SEF | OFF | ON | ON | OFF | ON |  |
| A4 LEF | ON | OFF | ON | OFF | OFF | 1.52A\}0.05 |
| A3 SEF | ON | OFF | ON | ON | OFF | $1.21 \AA$ \}0.05 |
| B5 LEF/ Executive LEF | ON | ON | OFF | OFF | ON | 0.91£\}0.05 |
| 8K SEF (TFX/GCO) | ON | ON | OFF | ON | OFF | $0.60 \AA$ \}0.05 |
| B4 SEF | ON | ON | OFF | ON | ON |  |
| 8.5"Å~11"LEF | ON | ON | ON | OFF | OFF | 0.30Å\}0.05 |
| 16K LEF(TFX/GCO) | ON | ON | ON | OFF | ON |  |
| 11"Å~17"LEF | ON | ON | ON | ON | ON | 0.00 ¢ 00.05 |

7 Tray2


| Signal line name | Description |
| :--- | :--- |
| FMOT2 A, FMOT2 B, FMOT2 /A, FMOT2 /B | TRAY2 FEED LIFT UP MOTOR exciting signal |
| TRAY2 LEVEL UP(H)+5VDC | Rise (paper feed possible level) detection signal of <br> plate in Tray2 by SENSOR (Tray2 Level Sensor). |
| TRAY2 PAPER SENSED(L)+5VDC | Paper detection signal in Tray2 of SENSOR (Tray2 <br> No Paper Sensor) |
| TRAY2 PRE FEED SENSED(L)+5VDC | Feed paper detection signal from Tray2 by SENSOR <br> (Tray2 Pre Feed Sensor) |
| TRAY2 SIZE SWITCH SIGNAL | Paper size detection signal (analog value) of <br> SWITCH ASSY P S (Tray2 Size Sensor) |
| TRAY2 SIZE SWITCH S5 ON(L)+5VDC | S5 in SWITCH ASSY P S (Tray2 Size Sensor) ON/ <br> OFF detection signal |

- Paper size detection
- The ON/OFF pattern of each switch (S1-S5) of SWITCH ASSY P S and the relation of paper size and the output voltage of TRAY2 SIZE SWITCH SIGNAL are as follows.

| Paper Size | S1 | S2 | S3 | S4 | S5 | Output Voltage(V) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| No Tray | OFF | OFF | OFF | OFF | OFF | 4.66A\}0.05 |
| 5.5"Å~8.5"SEF/A5 SEF | OFF | OFF | ON | OFF | OFF | 4.01A\}0.05 |
| B5 SEF | OFF | OFF | ON | ON | ON | 3.69A\}0.05 |
| 8.5"A~13"SEF | OFF | ON | OFF | ON | OFF | 3.07Å\}0.05 |
| 8.5"A~14"SEF | OFF | ON | OFF | ON | ON |  |
| A4 SEF | OFF | ON | ON | OFF | OFF | $2.75 \AA\} 0.05$ |
| 8.5"A~11"SEF | OFF | ON | ON | OFF | ON |  |
| A4 LEF | ON | OFF | ON | OFF | OFF | $1.52 A\} 0.05$ |
| A3 SEF | ON | OFF | ON | ON | OFF | 1.21A\}0.05 |
| B5 LEF/ Executive LEF | ON | ON | OFF | OFF | ON | 0.91乏\}0.05 |
| 8K SEF (TFX/GCO) | ON | ON | OFF | ON | OFF | $0.60 \AA\}$ \} 0.05 |
| B4 SEF | ON | ON | OFF | ON | ON |  |
| 8.5"A~11"LEF | ON | ON | ON | OFF | OFF | $0.30 \AA\} 0.05$ |
| 16K LEF(TFX/GCO) | ON | ON | ON | OFF | ON |  |
| 11"Å~17"LEF | ON | ON | ON | ON | ON | 0.00A\}0.05 |

8 MPF


| Signal line name | Description |
| :--- | :--- |
| MPF SIZE SENSOR SIGNAL | MPF Paper size detection signal (analog value) in the main <br> scan direction of SENSOR ASSY-MPF |
| PICK UP SOLENOID ON(L)+24VDC | SOLENOID PICK UP ON/OFF control signal |
| MPF PAPER SENSED(L)+5VDC | Paper detection signal in MPF by SENSOR-PHOTO IN (MPF <br> No Paper Sensor) |

- MPF Paper size detection in the main scan direction

The paper guide of MPF is interlocked with, variable resistance of SENSOR ASSY-MPF changes, and the output voltage of MPF SIZE SENSOR SIGNAL changes.
The relation between the output voltage of MPF SIZE SENSOR SIGNAL and paper size is shown below.

| Paper size | Feed length (mm) | Output Voltage(V) |
| :---: | :---: | :---: |
| Guide stopper (MIN) | 84 | 4.72 |
| Paper detection range (MIN) | 88.2 | 4.72 |
| 3.5"A~8.5"SEF | 88.9 | 4.71 |
| Post Card SEF | 101.6 | 4.48 |
| 5.5"Å~8.5"SEF | 139.7 | 3.79 |
| Japanese Post card LEF | 148 | 3.64 |
| A6 LEF | 148 | 3.64 |
| A5 SEF | 148 | 3.64 |
| Post Card LEF | 152.4 | 3.56 |
| B6LEF | 182 | 3.03 |
| B5SEF | 182 | 3.03 |
| Monarch LEF | 190.5 | 2.87 |
| A5 LEF | 210 | 2.52 |
| A4 SEF | 210 | 2.52 |
| 5.5"Å~8.5"LEF | 215.9 | 2.41 |
| 5.5"A~ 11 "SEF(Letter) | 215.9 | 2.41 |
| 5.5"A~13"SEF(Legal) | 215.9 | 2.41 |
| 5.5"A~14"SEF(Legal) | 215.9 | 2.41 |
| DL LEF | 220 | 2.34 |
| C5 LEF | 229 | 2.18 |
| C4 SEF | 229 | 2.18 |
| Vertical (Long size) No. 3 LEF | 235 | 2.07 |
| Com10LEF | 241.3 | 1.95 |
| B5 LEF | 257 | 1.67 |
| B4 SEF | 257 | 1.67 |
| Executive LEF | 266.7 | 1.50 |
| 16K LEF (TFX) | 267(270) | 1.49(1.44) |
| 8K SEF (TFX) | 267(270) | 1.49(1.44) |
| 8.5"A~11"SEF (Letter) | 279.4 | 1.27 |
| 11 ${ }^{\text {A }}$ ~17"LEF | 279.4 | 1.27 |
| A4 LEF | 297 | 0.95 |
| A3 SEF | 297 | 0.95 |
| Guide stopper (MAX) | 303 | 0.84 |

## 9 ROS



| Signal line name | Description |
| :--- | :--- |
| /XDATA1, XDATA1, /XDATA2, XDATA2 | Pixel data signals to make LD (Laser Diodes) in ROS <br> ASSY-12 emit the light |
| ROS VALID | Compulsive putting-out-lights signal of LD in ROS ASSY- <br> 12 |
| LD+5VDC | Power supply voltage for LD in ROS ASSY-12 |
| SOS SIGNAL | Scanning start reference signal based on the input of laser <br> beam to the SOS Sensor in ROS ASSY-12 |
| POWER CONTROL1 ON(L)+5VDC | ON/OFF control signal of LD Power in ROS ASSY-12 |
| ROS VREF OUT SIGNAL | Voltages for adjusting light quantity of LD in ROS ASSY-12 |
| ROS MONITOR | Light quantity monitor signal for LD in ROS ASSY-12 |
| POWER CONTROL2 ON(L)+5VDC | ON/OFF control signal of LD Power in ROS ASSY-12 |
| LD ENABLE ON(L)+5VDC | Enable signal of LD in ROS ASSY-12 |
| ROS MOTOR ON(L)+5VDC | ON/OFF control signal of ROS Motor in ROS ASSY-12 |
| ROS MOTOR CLOCK | Clock signal of ROS Motor in ROS ASSY-12 |

## 10 Exit



| Signal line name | Description |
| :--- | :--- |
| OCT HOME SENSED(L)+5VDC | OCT home position detection signal by SENSOR- <br> PHOTO IN (OCT Home Sensor) |
| FULL STACK SENSED(L)+5VDC | Stacker tray paper full detection signal by SENSOR- <br> PHOTO IN (Full Stack Sensor) |
| OFFSET MOTOR A, OFFSET MOTOR B, <br> OFFSET MOTOR /A, OFFSET MOTOR /B | MOTOR ASSY-OFFSET exciting signal |
| ENGINE TO EXIT | Communication signal of PWB A MCU F (Engine) <br> and PWB A EXIT (Exit) (Engine->Exit) |
| EXIT TO ENGINE | Communication signal of PWB A EXIT (Exit) and <br> PWB A MCU F (Engine) (Exit->Engine) |
| FUSER EXIT PAPER SENSED(H)+5VDC | Paper detection signal in fuser by Fuser Exit Sensor <br> in FUSER ASSY (Engine->Exit) |
| REGI CLUTCH ON(L)+5VDC | CLUTCH ASY REGI H(Regi Clutch) ON/OFF control <br> signal (Engine->Exit) |
| EXIT GATE SOLENOID ON(H)+5VDC | SOLENOID ASSY (Exit Gate Solenoid) ON/OFF con- <br> trol signal (Engine->Exit) |

## 11 Controller



| Signal line name | Description |
| :---: | :---: |
| COMMAND (ESS TO ENGINE) | Communication signal of PWBA ESS (ESS) and PWB A MCU F (Engine) |
| STATUS (ENGINE TO ESS) |  |
| STATUS READY |  |
| COMMAND READY |  |
| SCLOCK |  |
| FWE |  |
| TOP |  |
| BD |  |
| START |  |
| PRED |  |
| ENGINE READY |  |
| ESS READY |  |
| READY |  |

## 1000 Sheet Feeder

## General Wiring Diagram



## Wiring Diagram between Parts

## Configuration

The wiring diagram is separated into 3 sections to show detailed connection between parts.

1 Drive

- Connection between TRAY MODULE PWB and CLUTCH (Takeaway Clutch)
- Connection between TRAY MODULE PWB and MAIN MOTOR
- Connection between TRAY MODULE PWB and LEFT COVER INTERLOCK SWITCH

2 Tray3

- Connection between TRAY MODULE PWB and TRAY3 FEED LIFT UP MOTOR
- Connection between TRAY MODULE PWB and SENSOR (Tray3 Level Sensor)
- Connection between TRAY MODULE PWB and SENSOR (Tray3 No Paper Sensor)
- Connection between TRAY MODULE PWB and SENSOR (Tray3 Pre Feed Sensor)
- Connection between TRAY MODULE PWB and TRAY3 PAPER SIZE SWITCH
- Connection between TRAY MODULE PWB and TRAY3 FEED OUT SENSOR

3 Tray4

- Connection between TRAY MODULE PWB and TRAY4 FEED LIFT UP MOTOR
- Connection between TRAY MODULE PWB and SENSOR (Tray4 Level Sensor)
- Connection between TRAY MODULE PWB and SENSOR (Tray4 No Paper Sensor)
- Connection between TRAY MODULE PWB and SENSOR (Tray4 Pre Feed Sensor)
- Connection between TRAY MODULE PWB and TRAY4 PAPER SIZE SWITCH
- Connection between TRAY MODULE PWB and TRAY4 FEED OUT SENSOR


## Notes on Using the Wiring Diagram between Parts

The following describes the legend of the wiring diagrams between parts shown on the following pages.
Note that the description of general symbols is omitted.

| Symbols | Description |
| :--- | :--- |
|  | Denotes a plug. |


| Symbols | Description |
| :---: | :---: |
| Control | Denotes the control and its outline in PWB. |
| DEVE_A | Denotes a connection between parts with harnesses or wires, attached with signal name/contents. |
| $\xrightarrow{\text { REGI CLUTCH ON(L)+24VDC }}$ | Denotes the function, and logic value of the signal to operate the function (Low: L, High: H). <br> The given voltage is for signal in high status. <br> The arrow indicates the direction of signal. |
| $\stackrel{\text { EXIT PAPER SENSED }(\mathrm{L})+3.3 \mathrm{VDC}}{ }$ | Denotes the function, and logic value of the signal when the func tion operated (Low: L, High: H). <br> The given voltage is for signal in high status. <br> The arrow indicates the direction of signal. |
| $T$ | Denotes a connection between wires. |
| I/L +24VDC | Denotes DC voltage when the interlock switch in HNB MCU WITH CPU turns on |
| $\begin{gathered} \text { +5VDC } \\ \text { +3.3VDC } \end{gathered}$ | Denotes DC voltage. |
| SG | Denotes signal ground. |
| AG | Denotes analog ground. |
| RTN | Denotes the return. |

1 Drive


| Signal line name | Description |
| :--- | :--- |
| TAKEAWAY CLUTCH ON(L)+24VDC | TAKEAWAY CLUTCH ON/OFF control signal |
| TAKEAWAY MOTOR ON(L)+5VDC | TAKEAWAY MOTOR ON/OFF control signal |
| TAKEAWAY MOTOR CLOCK | Clock signal to TAKEAWAY MOTOR |
| M/C CLOCK | Clock signal from TAKEAWAY MOTOR |
| LEFT COVER OPEN(H)+5VDC | LEFT COVER open/close detection signal by LEFT <br> COVER INTERLOCK SWITCH |
| ENGINE TO 2TM | Communication signal of PWB A MCU F (Engine) <br> and TRAY MODULE PWB (2TM) (Engine->2TM) |
| 2TM TO ENGINE | Communication signal of TRAY MODULE PWB <br> (2TM) and PWB A MCU F (Engine) (2TM->Engine) |
| TRAY3 FEED/LIFT MOTOR ON(H)+5VDC | TRAY3 FEED LIFT UP MOTOR ON/OFF control <br> signal (Engine->2TM) |
| TRAY4 FEED/LIFT MOTOR ON(H)+5VDC | TRAY4 FEED LIFT UP MOTOR ON/OFF control <br> signal (Engine->2TM) |
| FEED READY | Feed ready signal from 2TM (2TM->Engine) |
| TRAY3 FEED OUT PAPER SENSED(L)+5VDC | Paper detection signal by TRAY3 FEED OUT SEN- <br> SOR in transport section (2TM->Engine) |
| TRAY4 FEED OUT PAPER SENSED(L)+5VDC | Paper detection signal by TRAY4 FEED OUT SEN- <br> SOR in transport section (2TM->Engine) |
| FEED STOP | Feed stop signal to 2TM (Engine->2TM) |

2 Tray3


| Signal line name | Description |
| :--- | :--- |
| FMOT3 A, FMOT3 B, FMOT3 /A, FMOT3 /B | TRAY3 FEED LIFT UP MOTOR exciting signal |
| TRAY3 LEVEL UP(H)+5VDC | Rise (paper feed possible level) detection signal of <br> plate in Tray3 by SENSOR (Tray3 Level Sensor) |
| TRAY3 PAPER SENSED(L)+5VDC | Paper detection signal in Tray3 of SENSOR (Tray3 <br> No Paper Sensor) |
| TRAY3 PRE FEED SENSED(L)+5VDC | Feed paper detection signal from Tray3 by SENSOR <br> (Tray3 Pre Feed Sensor) |
| TRAY3 SIZE SWITCH SIGNAL | Paper size detection signal (analog value) of TRAY3 <br> PAPER SIZE SWITCH |
| TRAY3 SIZE SWITCH S5 ON(L)+5VDC | S5 in TRAY3 PAPER SIZE SWITCH ON/OFF detec- <br> tion signal |
| TRAY3 FEED OUT PAPER SENSED(L)+5VDC | Paper detection signal by TRAY3 FEED OUT SEN- <br> SOR in transport section |

Paper size detection

- The ON/OFF pattern of each switch (S1-S5) of TRAY3 PAPER SIZE SWITCH and the relation of paper size and the output voltage of TRAY3 SIZE SWITCH SIGNAL are as follows.

| Paper Size | S1 | S2 | S3 | S4 | S5 | Output <br> Voltage(V) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| No Tray | OFF | OFF | OFF | OFF | OFF | 3.06A\}0.05 |
| 5.5"A 8.5 " SEF/A5 SEF | OFF | OFF | ON | OFF | OFF | 2.65A\}0.05 |
| B5 SEF | OFF | OFF | ON | ON | ON | 2.45A\}0.05 |
| 8.5" $\AA \sim 13$ "SEF | OFF | ON | OFF | ON | OFF | 2.05A\}\}0.05 |
| 8.5"A~14"SEF | OFF | ON | OFF | ON | ON |  |
| A4 SEF | OFF | ON | ON | OFF | OFF | 1.85A\}0.05 |
| 8.5"A~11"SEF | OFF | ON | ON | OFF | ON |  |
| A4 LEF | ON | OFF | ON | OFF | OFF | 1.07A\}0.05 |
| A3 SEF | ON | OFF | ON | ON | OFF | 0.87A\}0.05 |
| B5 LEF/ Executive LEF | ON | ON | OFF | OFF | ON | 0.68A\}0.05 |
| 8K SEF (TFX/GCO) | ON | ON | OFF | ON | OFF | $0.49 \AA\} 0.05$ |
| B4 SEF | ON | ON | OFF | ON | ON |  |
| 8.5"A~11"LEF | ON | ON | ON | OFF | OFF | $0.29 \AA\} 0.05$ |
| 16K LEF(TFX/GCO) | ON | ON | ON | OFF | ON |  |
| 11"Å~17"LEF | ON | ON | ON | ON | ON | 0.10 $\} 0.05$ |

## 3 Tray4



| Signal line name | Description |
| :--- | :--- |
| FMOT4 A, FMOT4 B, FMOT4 /A, FMOT4 /B | TRAY4 FEED LIFT UP MOTOR exciting signal |
| TRAY4 LEVEL UP(H)+5VDC | Rise (paper feed possible level) detection signal of <br> plate in Tray4 by SENSOR (Tray4 Level Sensor) |
| TRAY4 PAPER SENSED(L)+5VDC | Paper detection signal in Tray4 of SENSOR (Tray4 <br> No Paper Sensor) |
| TRAY4 PRE FEED SENSED(L)+5VDC | Feed paper detection signal from Tray4 by SENSOR <br> (Tray4 Pre Feed Sensor) |
| TRAY4 SIZE SWITCH SIGNAL | Paper size detection signal (analog value) of TRAY4 <br> PAPER SIZE SWITCH |
| TRAY4 SIZE SWITCH S5 ON(L)+5VDC | S5 in TRAY4 PAPER SIZE SWITCH ON/OFF detec- <br> tion signal |
| TRAY4 FEED OUT PAPER SENSED(L)+5VDC | Paper detection signal by TRAY4 FEED OUT SEN- <br> SOR in transport section |

Paper size detection
The ON/OFF pattern of each switch (S1-S5) of TRAY4 PAPER SIZE SWITCH and the relation of paper size and the output voltage of TRAY4 SIZE SWITCH SIGNAL are as follows.

| Paper Size | S1 | S2 | S3 | S4 | S5 | Output Voltage(V) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| No Tray | OFF | OFF | OFF | OFF | OFF | 3.06A\}0.05 |
| 5.5"Å~8.5"SEF/A5 SEF | OFF | OFF | ON | OFF | OFF | $2.65 \AA\} 0.05$ |
| B5 SEF | OFF | OFF | ON | ON | ON | 2.45A\}0.05 |
| 8.5"Å~13"SEF | OFF | ON | OFF | ON | OFF | $2.05 \AA$ ¢0.05 |
| 8.5"Å~14"SEF | OFF | ON | OFF | ON | ON |  |
| A4 SEF | OFF | ON | ON | OFF | OFF | $1.85 A ̊\} 0.05$ |
| 8.5"Å~11"SEF | OFF | ON | ON | OFF | ON |  |
| A4 LEF | ON | OFF | ON | OFF | OFF | 1.07Ȧ\}0.05 |
| A3 SEF | ON | OFF | ON | ON | OFF | 0.87Å\}0.05 |
| B5 LEF/ Executive LEF | ON | ON | OFF | OFF | ON | 0.68 Å\}0.05 |
| 8K SEF (TFX/GCO) | ON | ON | OFF | ON | OFF | $0.49 A ̊\} 0.05$ |
| B4 SEF | ON | ON | OFF | ON | ON |  |
| 8.5"Å~11"LEF | ON | ON | ON | OFF | OFF | 0.29Å\}0.05 |
| 16K LEF(TFX/GCO) | ON | ON | ON | OFF | ON |  |
| 11"Å~17"LEF | ON | ON | ON | ON | ON | 0.10Å\}0.05 |

## Duplex

## General Wiring Diagram

The following describes the legend of the general wiring diagram shown on the next page.

| Symbols | Description |
| :---: | :---: |
|  | Denotes a connection between parts with harnesses and wires. |


| Symbols | Description |
| :---: | :---: |
| XX | A frame not having parts name inside denotes the connector ( $\mathrm{P} / \mathrm{J}$ ). Numeric value inside implies the connector number. |
| ${ }_{-}^{-x} \bar{x}{ }^{\urcorner}$ | A frame of broken line denotes the connector ( $\mathrm{P} / \mathrm{J}$ ) written in several places separately. <br> Numeric value inside implies the connector number. |
| $\begin{aligned} & \text { PWBA ABC } \\ & \text { PL X.Y.Z } \end{aligned}$ | A frame having parts name inside denotes the parts. PL X.Y.Z implies the item "Z" of plate (PL) "X.Y" in Chapter 5. Parts List. |
| 1 | A frame of dotted line denotes the section in " 2 . Wiring Diagram between Parts", and numeric value implies the section number. |



## Wiring Diagram between Parts

## Configuration

The wiring diagram is separated into 1 sections to show detailed connection between parts.

- 1 Duplex
- Connection between PWBA DUPLEX and SENSOR-PHOTO IN (Duplex Sensor)
- Connection between PWBA DUPLEX and SWITCH-I/L,CAB (Duplex Open Switch)
- Connection between PWBA DUPLEX and MOTOR ASSY DUP
- Connection between PWBA DUPLEX and PWB A MCU F


## Notes on Using the Wiring Diagram between Parts

The following describes the legend of the wiring diagrams between parts shown on the following pages.

Note that the description of general symbols is omitted.

| Symbols | Description |
| :---: | :---: |
|  | Denotes a plug. |
|  | Denotes a jack. |
| $\begin{gathered} \mathrm{P} / \mathrm{Jxx} \\ \square \mathrm{Yy} \nearrow \end{gathered}$ | Denotes Pin yy and Jack yy of the connector Pxx and Jxx. |
| $\begin{aligned} & \text { PWBA ABC } \\ & \text { PL X.Y.Z } \end{aligned}$ | Denotes the parts. <br> PL X.Y.Z implies the item "Z" of plate (PL) "X.Y" in Chapter 5. Parts List. |


| Symbols | Description |
| :---: | :---: |
| 1 Heater 1 | Denotes functional parts attached with functional parts name. |
| Control | Denotes the control and its outline in PWB. |
| DEVE A | Denotes a connection between parts with harnesses or wires, attached with signal name/contents. |
| $\xrightarrow{\text { REGI CLUTCH ON(L)+24VDC }}$ | Denotes the function, and logic value of the signal to operate the function (Low: L, High: H). <br> The given voltage is for signal in high status. <br> The arrow indicates the direction of signal. |
| $\stackrel{\text { EXIT PAPER SENSED }(\mathrm{L})+3.3 \mathrm{VDC}}{ }$ | Denotes the function, and logic value of the signal when the function operated (Low: L, High: H). <br> The given voltage is for signal in high status. <br> The arrow indicates the direction of signal. |
| $T$ | Denotes a connection between wires. |
| I/L +24VDC | Denotes DC voltage when the interlock switch in HNB MCU WITH CPU turns on |
| $\begin{gathered} \text { +5VDC } \\ \text { +3.3VDC } \end{gathered}$ | Denotes DC voltage. |
| SG | Denotes signal ground. |
| AG | Denotes analog ground. |
| RTN | Denotes the return. |

## 1 Duplex



| Signal line name | Description |
| :--- | :--- |
| DUPLEX SENSOR PAPER SENSED(L)+5VDC | Paper detection signal by SENSOR-PHOTO IN <br> (Duplex Sensor) in duplex |
| DUPLEX OPEN(H)+5VDC | DUPLEX COVER open/close detection signal by <br> SWITCH-I/L,CAB (Duplex Open Switch) |
| DUPLEX MOTOR A, DUPLEX MOTOR B, <br> DUPLEX MOTOR /A, DUPLEX MOTOR /B, | MOTOR ASSY DUP exciting signal |
| ENGINE TO DUPLEX | Communication signal of PWB A MCU F (Engine) <br> and PWBA DUPLEX (Duplex) (Engine->Duplex) |
| DUPLEX TO ENGINE | Communication signal of PWBA DUPLEX (Duplex) <br> and PWB A MCU F (Engine) (Duplex->Engine) |
| REGI SENSOR PAPER SENSED(H)+5VDC | Paper detection signal by SNR ASSY REGI in Reg- <br> istration (Engine->Duplex) |
| REGI CLUTCH ON(L)+5VDC | CLUTCH ASY REGI H(Regi Clutch) ON/OFF con- <br> trol signal (Engine->Duplex) |

## Exit

## General Wiring Diagram

The following describes the legend of the general wiring diagram shown on the next page.

| Symbols | Description |
| :---: | :---: |
|  | Denotes a connection between parts with harnesses and wires. |
| XX | A frame not having parts name inside denotes the connector ( $\mathrm{P} / \mathrm{J}$ ). Numeric value inside implies the connector number. |
|  | A frame of broken line denotes the connector ( $\mathrm{P} / \mathrm{J}$ ) written in several places separately. <br> Numeric value inside implies the connector number. |
| $\begin{aligned} & \text { PWBA ABC } \\ & \text { PL X.Y.Z } \end{aligned}$ | A frame having parts name inside denotes the parts. PL X.Y.Z implies the item "Z" of plate (PL) "X.Y" in Chapter 5. Parts List. |
|  | A frame of dotted line denotes the section in " 2 . Wiring Diagram between Parts", and numeric value implies the section number. |



## Wiring Diagram between Parts

## Configuration

The wiring diagram is separated into 2 sections to show detailed connection between parts.

- 1 Motor / Solenoid
- Connection between PWB A EXIT and MOTOR ASSY-OFFSET
- Connection between PWB A EXIT and MOTOR ASSY EXIT 2
- Connection between PWB A EXIT and SOLENOID ASSY (Exit Gate Solenoid)
- Connection between PWB A EXIT and SOLENOID ASSY FU (Face Up Gate Solenoid)
- 2 Sensor / Fan
- Connection between PWB A EXIT and SENSOR-PHOTO IN (OCT Home2 Sensor)
- Connection between PWB A EXIT and SENSOR-PHOTO IN (Exit2 Sensor)
- Connection between PWB A EXIT and SENSOR-PHOTO IN (Full Stack2 Sensor)
- Connection between PWB A EXIT and SWITCH-I/L,CAB (Face Up Detect Switch)
- Connection between PWB A EXIT and SWITCH-I/L,CAB (Exit2 Interlock)
- Connection between PWB A EXIT and EXIT FAN


## Notes on Using the Wiring Diagram between Parts

The following describes the legend of the wiring diagrams between parts shown on the following pages.
Note that the description of general symbols is omitted.

| Symbols | Description |
| :--- | :--- |


| Symbols | Description |
| :---: | :---: |
| $\xrightarrow{\text { REGI CLUTCH ON(L)+24VDC }}$ | Denotes the function, and logic value of the signal to operate the function (Low: L, High: H). <br> The given voltage is for signal in high status. <br> The arrow indicates the direction of signal. |
| EXIT PAPER SENSED(L)+3.3VDC | Denotes the function, and logic value of the signal when the function operated (Low: L, High: H). <br> The given voltage is for signal in high status. <br> The arrow indicates the direction of signal. |
|  | Denotes a connection between wires. |
| I/L +24VDC | Denotes DC voltage when the interlock switch in HNB MCU WITH CPU turns on |
| $\begin{gathered} \text { +5VDC } \\ +3.3 V D C \end{gathered}$ | Denotes DC voltage. |
| SG | Denotes signal ground. |
| AG | Denotes analog ground. |
| RTN | Denotes the return. |

## 1 Motor / Solenoid



| Signal line name | Description |
| :--- | :--- |
| OFFSET MOTOR2 A, OFFSET MOTOR2 B, <br> OFFSET MOTOR2 IA, OFFSET MOTOR2 /B | MOTOR ASSY-OFFSET exciting signal |
| EXIT MOTOR A, EXIT MOTOR B, <br> EXIT MOTOR /A, EXIT MOTOR /B, | MOTOR ASSY EXIT 2 exciting signal |
| EXIT GATE SOLENOID ON(L)+24VDC | SOLENOID ASSY (Exit Gate Solenoid) ON/OFF con- <br> trol signal |
| FUT GATE SOLENOID ON(L)+24VDC | SOLENOID ASSY FU (Face Up Gate Solenoid) ON/ <br> OFF control signal |

2 Sensor / Fan


| Signal line name | Description |
| :--- | :--- |
| OCT2 HOME SENSED(L)+5VDC | OCT2 home position detection signal by SENSOR- <br> PHOTO IN (OCT2 Home Sensor) |
| EXIT2 PAPER SENSED(L)+5VDC | Paper detection signal by SENSOR-PHOTO IN (Exit2 <br> Sensor) in Exit2 transport section |
| FULL STACK2 SENSED(L)+5VDC | Stacker tray paper full detection signal by SENSOR- <br> PHOTO IN (Full Stack2 Sensor) |
| EXIT2 DETECTED(L)+5VDC | Exit2 set detection signal |
| FACE UP TRAY DETECTED(L)+5VDC | Face Up Tray wearing detection signal by SWITCH-I/ <br> L,CAB (Face Up Detect Switch) |
| EXIT2 INTERLOCK OPEN(H)+5VDC | Exit2 Cover Open/close detection signal by SWITCH- <br> I/L,CAB (Exit2 Interlock) |
| EXIT FAN ON(H) +5VDC | EXIT FAN ON/OFF control signal |

## Finisher

## General Wiring Diagram

The following describes the legend of the general wiring diagram shown on the next page.

| Symbols | Description |
| :---: | :---: |
|  | Denotes a connection between parts with harnesses and wires. |
| $x X$ | A frame not having parts name inside denotes the connector ( $\mathrm{P} / \mathrm{J}$ ). Numeric value inside implies the connector number. |
|  | A frame of broken line denotes the connector (P/J) written in several places separately. <br> Numeric value inside implies the connector number. |
| PWBA ABC PL X.Y.Z | A frame having parts name inside denotes the parts. PL X.Y.Z implies the item "Z" of plate (PL) "X.Y" in Chapter 5. Parts List. |
|  | A frame of dotted line denotes the section in "2. Wiring Diagram between Parts", and numeric value implies the section number. |



Configuration
The wiring diagram is separated into 10 sections to show detailed connection between parts.

- 1 Power Supply
- Connection between PWB MAIN-C and PWB A MCU F
- Connection between PWB MAIN-C and LVPS-C
- Connection between PWB MAIN-C and PWB T-TRA
- Connection between PWB MAIN-C and INTERLOCK SWITCH (Front Door Switch)
- Connection between PWB MAIN-C and SENSOR ASSY (Eject Switch)
- 2 H -Transport
- Connection between PWB T-TRA and H-TRANSPORT MOTOR
- Connection between PWB T-TRA and H-TRANSPORT ENTRANCE SENSOR
- Connection between PWB T-TRA and H-TRANSPORT EXIT SENSOR
- Connection between PWB T-TRA and H-TRANSPORT INTERLOCK SENSOR
- Connection between PWB T-TRA and SENSOR (Punch Full Sensor)
- 3 Sensor (Paper feed section)
- Connection between PWB MAIN-C and SENSOR ASSY (Buffer Path Sensor)
- Connection between PWB MAIN-C and SENSOR (Top Tray Full Sensor)
- Connection between PWB MAIN-C and SENSOR (Top Tray Exit Sensor)
- Connection between PWB MAIN-C and SENSOR (Compile Exit Sensor)
- Connection between PWB MAIN-C and SENSOR (XÕ Port Entrance Sensor)
- Connection between PWB MAIN-C and SENSOR (Gate Sensor)
- 4 Sensor (Exit section)
- Connection between PWB MAIN-C and SENSOR (Upper Limit Sensor)
- Connection between PWB MAIN-C and SENSOR (Stacker No Paper Sensor)
- Connection between PWB MAIN-C and SENSOR (Stacker Encode Sensor)
- Connection between PWB MAIN-C and SENSOR (Set Clamp Home Sensor)
- Connection between PWB MAIN-C and SENSOR (Eject Clamp Sensor)
- Connection between PWB MAIN-C and COVER ASSY SENSOR (Stacker Height Sensor1)
- Connection between PWB MAIN-C and COVER ASSY SENSOR (Stacker Height Sensor2)


## - 5 Motor

- Connection between PWB MAIN-C and MOTOR ASSY (Exit Motor)
- Connection between PWB MAIN-C and MOTOR ASSY (Regi Motor)
- Connection between PWB MAIN-C and BRACKET ASSY-EJECT
- Connection between PWB MAIN-C and MOTOR ASSY (Transport Motor)
- 6 Motor / Clutch / Solenoid
- Connection between PWB MAIN-C and MOTOR ASSY-DC (Eject Clamp Motor)
- Connection between PWB MAIN-C and CLUTCH Z34 (Set Clamp Clutch)
- Connection between PWB MAIN-C and SOLENOID ASSY (Sub Paddle Solenoid)
- Connection between PWB MAIN-C and BRACKET ASSY SOL (Transport Gate Solenoid)
- Connection between PWB MAIN-C and BRACKET ASSY SOL (Buffer Gate Solenoid)
- Connection between PWB MAIN-C and MOTOR ASSY-DC (Elevator Motor)
- 7 Tamper
- Connection between PWB MAIN-C and MOTOR ASSY (Rear Tamper Motor)
- Connection between PWB MAIN-C and MOTOR ASSY2 (Front Tamper Motor)
- Connection between PWB MAIN-C and SENSOR (Rear Tamper Home Sensor)
- Connection between PWB MAIN-C and SENSOR (Front Tamper Home Sensor)
- Connection between PWB MAIN-C and SENSOR (Compiler Tray No Paper Sensor)
- 8 Stapler
- Connection between PWB MAIN-C and SENSOR (Stapler Move Home Position Sensor)
- Connection between PWB MAIN-C and STAPLER ASSY
- Connection between PWB MAIN-C and CARRIAGE ASSY LOWER, STAPLER (Stapler Move Motor)
- 9 Puncher1
- Connection between PWB MAIN-C and SENSOR (Punch Box Set Sensor)
- Connection between PWB MAIN-C and SENSOR (Punch Move Home Sensor)
- Connection between PWB MAIN-C and SENSOR (Side Regi Sensor1)
- Connection between PWB MAIN-C and SENSOR (Side Regi Sensor2)
- Connection between PWB MAIN-C and SENSOR (Puncher Motor Sensor)
- 10 Puncher2
- Connection between PWB MAIN-C and BRACKET ASSY-MOTOR,PUNCH
- Connection between PWB MAIN-C and MOTOR ASSY (Puncher Motor)
- Connection between PWB MAIN-C and SENSOR (Punch Hole Select Sensor)
- Connection between PWB MAIN-C and SENSOR (Punch Front Sensor)
- Connection between PWB MAIN-C and SENSOR (Punch Home Sensor)


## Notes on Using the Wiring Diagram between Parts

The following describes the legend of the wiring diagrams between parts shown on the following pages.
Note that the description of general symbols is omitted.

| Symbols |  |
| :--- | :--- |
|  | Denotes a plug. |
| $\square$ | Denotes a jack. |
| $\square$ |  |


| Symbols | Description |
| :---: | :---: |
|  | Denotes Pin yy and Jack yy of the connector Pxx and Jxx. |
| $\begin{array}{\|l} \hline \text { PWBA ABC } \\ \text { PL X.Y.Z } \end{array}$ | Denotes the parts. <br> PL X.Y.Z implies the item "Z" of plate (PL) "X.Y" in Chapter 5. Parts List. |
| Heater | Denotes functional parts attached with functional parts name. |
| Control | Denotes the control and its outline in PWB. |
| DEVE_A | Denotes a connection between parts with harnesses or wires, attached with signal name/contents. |
| $\xrightarrow{\text { REGI CLUTCH ON(L)+24VDC }}$ | Denotes the function, and logic value of the signal to operate the function (Low: L, High: H). <br> The given voltage is for signal in high status. <br> The arrow indicates the direction of signal. |
| EXIT PAPER SENSED(L)+3.3VDC | Denotes the function, and logic value of the signal when the function operated (Low: L, High: H). <br> The given voltage is for signal in high status. <br> The arrow indicates the direction of signal. |
| \| | Denotes a connection between wires. |
| I/L +24VDC | Denotes DC voltage when the interlock switch in HNB MCU WITH CPU turns on |
| $\begin{gathered} +5 \mathrm{VDC} \\ +3.3 \mathrm{VDC} \end{gathered}$ | Denotes DC voltage. |
| SG | Denotes signal ground. |
| AG | Denotes analog ground. |


| Symbols | Description |
| :---: | :--- |
| RTN | Denotes the return. |

## 1 Power Supply



| Signal line name | Description |
| :---: | :---: |
| LVPS SQ | ON/OFF control signal of LVPS-C (Finisher) from PWB A MCU F (Engine) |
| FUSER EXIT (FUSER EXIT PAPER SENSED(H)+5VDC) | Paper detection signal in fuser by Fuser Exit Sensor in FUSER ASSY (Engine->Finisher) |
| REGI CLUTCH ON (REGI CLUTCH ON(L)+5VDC) | CLUTCH ASY REGI H(Regi Clutch) ON/OFF control signal (Engine->Finisher) |
| ENGINE TO FIN | Communication signal of PWB A MCU F (Engine) and PWB MAIN-C (Finisher) (Engine->Finisher) |
| FIN TO ENGINE | Communication signal of PWB MAIN-C (Finisher) and PWB A MCU F (Engine) (Finisher->Engine) |
| FRONT SW | FINISHER FRONT DOOR open/close detection signal |
| EJECT COVER | FINISHER EJECT COVER open/close detection signal |
| IF MOT CURRENT | Not used |
| IF MOT PHASE | Not used |
| HT/IF MOT CLK | H-TRANSPORT MOTOR clock signal |
| MOT RESET | H-TRANSPORT MOTOR reset signal |
| IF MOT ENB | Current setting value switching signal of H-TRANSPORT MOTOR |
| IF ENT SNR | Not used |
| IF EXIT SNR | Not used |
| DEC HOME SNR | Not used |
| DEC CLUTCH DRV | Not used |
| DOCKING SNR | Not used |
| IOT FULL SNR | Not used |
| HTRA ENT SNR | Paper detection signal by H-TRANSPORT ENTRANCE SENSOR in H-Transport |
| HTRA EXIT SNR | Paper detection signal by H-TRANSPORT EXIT SENSOR in H-Transport |
| HTRA I/L SNR | H-TRANSPORT COVER open/close detection signal by H-TRANSPORT INTERLOCK SENSOR |
| PUNCH FULL SNR | Punch waste full detection signal of Punch dust box |
| HTRA MOT ENABLE | H-TRANSPORT MOTOR ON/OFF control signal |
| IF MOT BRAKE | Not used |
| GATE SOL PUSH | Not used |
| GATE SOL PULL | Not used |
| RS232C SELECT | Communication selection signal of Engine and PC (Download Mode change) |
| FIN TO H-TRA | Communication signal of PWB MAIN-C (Finisher) and PWB H-TRA(H-Transport) (Finisher->H-Transport) |
| H-TRA TO FIN | Communication signal of PWB H-TRA(H-Transport) and PWB MAIN-C (Finisher) (H-Transport->Finisher) |

## 2 H-Transport



| Signal line name | Description |
| :--- | :--- |
| H-TRANSPORT MOTOR A, H-TRANSPORT MOTOR B, <br> H-TRANSPORT MOTOR /A, H-TRANSPORT MOTOR /B | H-TRANSPORT MOTOR exciting signal |
| ENTRANCE SENSOR PAPER SENSED(L)+5VDC | Paper detection signal by H-TRANSPORT <br> ENTRANCE SENSOR in H-Transport |
| EXIT SENSOR PAPER SENSED(L)+5VDC | Paper detection signal by H-TRANSPORT <br> EXIT SENSOR in H-Transport |
| H-TRANSPORT COVER CLOSED(L)+5VDC | H-TRANSPORT COVER open/close <br> detection signal by H-TRANSPORT <br> INTERLOCK SENSOR |
| PUNCH FULL(L)+5VDC | Punch waste full detection signal of Punch <br> dust box by PUNCH FULL SENSOR |

3 Sensor (Paper feed section)


| Signal line name | Description |
| :--- | :--- |
| BUFFER PATH PAPER SENSED(L)+5VDC | Paper detection signal by SENSOR ASSY (Buffer Path <br> Sensor) in Buffer Path |
| TOP TRAY FULL SENSED(L)+5VDC | Top Tray paper full detection signal by SENSOR (Top <br> Tray Full Sensor) |
| TOP TRAY EXIT PAPER SENSED(L)+5VDC | Discharge paper detection signal to Top Tray by SEN- <br> SOR (Top Tray Exit Sensor) |
| COMPILE EXIT PAPER SENSED(L)+5VDC | Transport paper detection signal to Compile Tray by <br> SENSOR (Compile Exit Sensor) |
| XPORT PAPER SENSED(L)+5VDC | Paper detection signal by SENSOR (X'Port Entrance <br> Sensor) in transport section AB |
| GATE SENSOR PAPER SENSED(H) +5VDC | Paper detection signal by SENSOR (Gate Sensor) in <br> gate |

## 4 Sensor (Exit section)



| Signal line name | Description |
| :--- | :--- |
| UPPER LIMIT SENSED(L)+5VDC | Maximum detection signal at the time of Stack <br> Tray rise by SENSOR (Upper Limit Sensor) |
| STACKER PAPER SENSED(L)+5VDC | Paper detection signal in Stack Tray by SEN- <br> SOR (Stacker No Paper Sensor) |
| STACKER ENCODE SENSOR SENSED(L)+5VDC | Encoder pulse count detection signal by SEN- <br> SOR (Stacker Encode Sensor) <br> (The quantity of the paper discharged by the <br> pulse count on Stack Tray is detected) |
| SET CLAMP HOME SENSED(L)+5VDC | Set Clamp home position detection signal by <br> SENSOR (Set Clamp Home Sensor) |
| EJECT CLAMP UP(L)+5VDC | Eject Clamp up/down detection signal by SEN- <br> SOR (Eject Clamp Sensor) |
| STACKER HEIGHT SENSOR1 CLOCK | Abnormal conditions signal for driving the infra- <br> red rays Light Emitting Diode of STACKER <br> HEIGHT SENSOR1 |
| STACKER HEIGHT SENSOR2 CLOCK | Abnormal conditions signal for driving the infra- <br> red rays Light Emitting Diode of STACKER <br> HEIGHT SENSOR2 |
| STACKER HEIGHT SENSOR1 SENSED(L)+5VDC | Height detection signal of Stack Tray by COVER <br> ASSY SENSOR (Stacker Height Sensor1) |
| STACKER HEIGHT SENSOR2 SENSED(L)+5VDC | Height detection signal of Stack Tray by COVER <br> ASSY SENSOR (Stacker Height Sensor2) |

## 5 Motor



| Signal line name | Description |
| :--- | :--- |
| EXIT MOTOR A, EXIT MOTOR /A, EXIT MOTOR B, <br> EXIT MOTOR /B | MOTOR ASSY (Exit Motor) exciting signal |
| REGI MOTOR A, REGI MOTOR /A, REGI MOTOR B, <br> REGI MOTOR/B | MOTOR ASSY (Regi Motor) exciting signal |
| EJECT MOTOR A, EJECT MOTOR /A, EJECT <br> MOTOR B, EJECT MOTOR /B | BRACKET ASSY-EJECT exciting signal |
| TRANSPOER MOTOR A, TRANSPOER MOTOR /A, <br> TRANSPOER MOTOR B, TRANSPOER MOTOR /B | MOTOR ASSY (Transport Motor) exciting sig- <br> nal |

## 6 Motor / Clutch / Solenoid



| Signal line name | Description |
| :--- | :--- |
| EJECT CLAMP MOTOR CCW ON(H)+24VDC | CCW direction rotation ON/OFF control signal of <br> MOTOR ASSY-DC (Eject Clamp Motor) <br> (Eject Clamp UP/DOWN) |
| EJECT CLAMP MOTOR CW ON(H)+24VDC | CW direction rotation ON/OFF control signal of <br> MOTOR ASSY-DC (Eject Clamp Motor) <br> (Reverse) |
| SET CLAMP CLUTCH ON(L)+24VDC | CLUTCH Z34(Set Clamp Clutch) ON/OFF control <br> signal |
| SUB PADDLE SOLENOID ON(L)+24VDC | SOLENOID ASSY (Sub Paddle Solenoid) ON/ <br> OFF control signal |
| TRANSPORT GATE SOLENOID PUSH(L)+24VDC | BRACKET ASSY SOL (Transport Gate Solenoid) <br> Push signal (Stacker side) |
| TRANSPORT GATE SOLENOID PULL(L)+24VDC | BRACKET ASSY SOL (Transport Gate Solenoid) <br> Pull signal (SCT side) |
| BUFFER GATE SOLENOID PUSH(L)+24VDC | BRACKET ASSY SOL (Buffer Gate Solenoid) <br> Push signal (Stacker side) |
| BUFFER GATE SOLENOID PULL(L)+24VDC | BRACKET ASSY SOL (Buffer Gate Solenoid) ÇA <br> Pull signal (Buffer side) |
| ELEVATOR MOTOR DOWN(H)+24VDC | Stack Tray downward direction ON/OFF control <br> signal of MOTOR ASSY-DC (Elevator Motor) |
| ELEVATOR MOTOR UP(H)+24VDC | Stack Tray rise direction ON/OFF control signal of <br> MOTOR ASSY-DC (Elevator Motor) |

## 7 Tamper



| Signal line name | Description |
| :---: | :---: |
| REAR TAMPER MOTOR A, REAR TAMPER MOTOR /A, REAR TAMPER MOTOR B, REAR TAMPER MOTOR /B | MOTOR ASSY (Rear Tamper Motor) exciting signal |
| FRONT TAMPER MOTOR A, FRONT TAMPER MOTOR IA, FRONT TAMPER MOTOR B, FRONT TAMPER MOTOR /B | MOTOR ASSY (Front Tamper Motor) exciting signal |
| REAR TAMPER HOME SENSED(L)+5VDC | Rear Tamper home position detection signal by SEN- SOR (Rear Tamper Home Sensor) |
| FRONT TAMPER HOME SENSED(L)+5VDC | Front Tamper home position detection signal by SENSOR (Front Tamper Home Sensor) |
| COMPILER TRAY PAPER SENSED(L)+5VDC | Paper detection signal in Compiler Tray by SENSOR (Compiler Tray No Paper Sensor) |



| Signal line name | Description |
| :--- | :--- |
| STAPLER HOME POSITION SENSED(L)+5VDC | Stapler home position detection signal by SENSOR <br> (Stapler Move Home Position Sensor) |
| LOW STAPLE SENSED(L)+5VDC | Detection signal of the needle of Stapler by Low <br> Staple Sensor in STAPLER ASSY. |
| STAPLE READY SENSED(L)+5VDC | Detection signal of the Ready state of Stapler by <br> Staple Ready Sensor in STAPLER ASSY |
| STAPLE HEAD HOME SENSED(L)+5VDC | Stapler Head home position detection signal by Sta- <br> ple Home Sensor in STAPLER ASSY |
| STAPLE MOTOR +, STAPLE MOTOR - <br> STAPLE MOVE MOTOR A, <br> STAPLE MOVE MOTOR /A, <br> STAPLE MOVE MOTOR B, <br> STAPLE MOVE MOTOR /B | Cxciting signal of Staple Motor in STAPLER ASSY |

## 9 Puncher1



| Signal line name | Description |
| :--- | :--- |
| PUNCH BOX SET(L)+5VDC | Punch Box wearing direction signal by SENSOR <br> (Punch Box Set Sensor) |
| PUNCHER HOME SENSED(L)+5VDC | Puncher home position detection signal by SEN- <br> SOR (Puncher Move Home Sensor) |
| SIDE REGI SENSOR2 SENSED(L)+5VDC | Paper detection signal by SENSOR (Side Regi <br> Sensor2) |
| SIDE REGI SENSOR1 SENSED(L)+5VDC | Paper detection signal by SENSOR (Side Regi <br> Sensor1) |
| PUNCHER MOTOR SENSOR SENSED(L)+5VDC | Number-of-rotations detection signal of Puncher <br> Motor by SENSOR (Puncher Motor Sensor) |

## 10 Puncher2



| Signal line name | Description |
| :--- | :--- |
| PUNCH MOVE MOTOR A, <br> PUNCH MOVE MOTOR /A, <br> PUNCH MOVE MOTOR B, <br> PUNCH MOVE MOTOR /B | BRACKET ASSY-MOTOR,PUNCH exciting signal |
| PUNCHER MOTOR CCW ON(H)+24VDC | CCW direction rotation ON/OFF control signal of <br> MOTOR ASSY (Puncher Motor) <br> (It moves to the Puncher Rear side) |
| PUNCHER MOTOR CW ON(H)+24VDC | CW direction rotation ON/OFF control signal of <br> MOTOR ASSY (Puncher Motor) <br> (It moves to the Puncher Front side) |
| PUNCH HOLE SEL SENSOR SENSED(L)+5VDC | 2 holes / 3 hole change detection signal by SEN- <br> SOR (Punch Hole Select Sensor). |
| PUNCHER FRONT SENSOR SENSED(L)+5VDC | Puncher ÇA Cam Plate of Puncher Front Position <br> of SENSOR (Puncher Front Sensor) |
| PUNCHER HOME SENSOR SENSED(L)+5VDC | Cam Plate of Puncher home position detection <br> signal by SENSOR (Puncher Home Sensor) |

## General Wiring Diagram

The following describes the legend of the general wiring diagram shown on the next page.

| Symbols | Description |
| :---: | :---: |
|  | Denotes a connection between parts with harnesses and wires. |
| XX | A frame not having parts name inside denotes the connector ( $\mathrm{P} / \mathrm{J}$ ). Numeric value inside implies the connector number. |
| $\stackrel{\ulcorner }{\llcorner } \bar{x} \bar{X} \neg$ | A frame of broken line denotes the connector (P/J) written in several places separately. <br> Numeric value inside implies the connector number. |
| $\begin{aligned} & \text { PWBA ABC } \\ & \text { PL X.Y.Z } \end{aligned}$ | A frame having parts name inside denotes the parts. PL X.Y.Z implies the item "Z" of plate (PL) "X.Y" in Chapter 5. Parts List. |
|  | A frame of dotted line denotes the section in "2. Wiring Diagram between Parts", and numeric value implies the section number. |



## Wiring Diagram between Parts

## Configuration

The wiring diagram is separated into 3 sections to show detailed connection between parts.

- 1 Switch
- Connection between PWB ASSY and PWB A MCU F
- Connection between PWB ASSY and SW IL ASSY DOCKING
- Connection between PWB ASSY and SWITCH (Top Interlock Switch)
- 2 Sensor
- Connection between PWB ASSY and SENSOR (HCF Size Sensor L)
- Connection between PWB ASSY and SENSOR (HCF Size Sensor R)
- Connection between PWB ASSY and SENSOR (HCF Tray Set Sensor)
- Connection between PWB ASSY and SENSOR ASSY TA (HCF Feed Out Sensor)
- 3 Sensor/Motor/Solenoid
- Connection between PWB ASSY and MOTOR ASSY HCF (HCF Feed Motor)
- Connection between PWB ASSY and MOTOR ASSY HCF (HCF T/A Motor)
- Connection between PWB ASSY and SOLENOID ASSY (HCF Nudger Solenoid)
- Connection between PWB ASSY and SENSOR-PHOTO IN (HCF Level Sensor)
- Connection between PWB ASSY and SENSOR ASSY (HCF Pre Feed Sensor)
- Connection between PWB ASSY and SENSOR-PHOTO IN (HCF No Paper Sensor)

Notes on Using the Wiring Diagram between Parts
The following describes the legend of the wiring diagrams between parts shown on the following pages.
Note that the description of general symbols is omitted.

| Symbols | Description |
| :---: | :---: |
| E | Denotes a plug. |
| $\bigcirc$ | Denotes a jack. |
|  | Denotes Pin yy and Jack yy of the connector Pxx and Jxx. |
| PWBA ABC <br> PL X.Y.Z | Denotes the parts. <br> PL X.Y.Z implies the item "Z" of plate (PL) "X.Y" in Chapter 5. Parts List. |
| Heater | Denotes functional parts attached with functional parts name. |
| Control | Denotes the control and its outline in PWB. |
| DEVE A | Denotes a connection between parts with harnesses or wires, attached with signal name/contents. |
| $\xrightarrow{\text { REGI CLUTCH ON(L)+24VDC }}$ | Denotes the function, and logic value of the signal to operate the function (Low: L, High: H). <br> The given voltage is for signal in high status. <br> The arrow indicates the direction of signal. |
| EXIT PAPER SENSED(L)+3.3VDC | Denotes the function, and logic value of the signal when the function operated (Low: L, High: H). <br> The given voltage is for signal in high status. <br> The arrow indicates the direction of signal. |


| Symbols | Description |
| :---: | :--- |
| I/L +24 VDC | Denotes a connection between wires. <br> CPU turns on |
|  | Denotes DC voltage. |
|  | Denotes signal ground. |
| AG | Denotes analog ground. |
| RTN |  |

1 Switch


| Signal line name | Description |
| :--- | :--- |
| DOCKING SWITCH CLOSE(L)+5VDC | wearing detection signal of HCF and Engine by SW IL <br> ASSY DOCKING AAi Low AF wearing Åj |
| ENGINE TO HCF | Communication signal of PWB ASSY(HCF) and PWB <br> A MCU F (Engine) (Engine->HCF) |
| HCF TO ENGINE | Communication signal of PWB ASSY(HCF) and PWB <br> A MCU F (Engine) (HCF->Engine) |
| HCF FEED OUT PAPER SENSED(H)+5VDC | Paper detection signal by HCF Feed Out Sensor in <br> transport section (HCF->Engine) |
| HCF PAPER SENSED(L)+5VDC | Paper detection signal in HCF Tray of HCF No Paper <br> Sensor (HCF->Engine) |
| FEED STOP | Feed Stop signal to HCF (Engine->HCF) |
| SYS RESET | System Reset signal to HCF (Engine->HCF) |

2 Sensor


| Signal line name | Description |
| :--- | :--- |
| HCF SIZE SENSOR L SENSED(L)+5VDC | HCF Size Sensor L ON/OFF detection signal |
| HCF SIZE SENSOR R SENSED(L)+5VDC | HCF Size Sensor R ON/OFF detection signal |
| HCF TRAY SET(L)+5VDC | HCF Tray set signal by HCF Tray Set Sensor |
| HCF FEED OUT PAPER SENSED(H)+5VDC | Paper detection signal by HCF Feed Out Sensor in <br> transport section |

- Paper size detection
- The ON/OFF pattern of HCF SIZE SENSOR L and HCF SIZE SENSOR R and the relation of paper size are as follows.

| Paper Size | SENSOR L | SENSOR R |
| :--- | :---: | :---: |
| B5 LEF /7.25"A~10.5" LEF | OFF | OFF |
| $8.5^{\prime \prime A \sim 11 " ~ L E F ~}$ | ON | OFF |
| A4 LEF | OFF | ON |

## 3 Sensor/Motor/Solenoid



| Signal line name | Description |
| :--- | :--- |
| HCF FEED MOTOR A, HCF FEED MOTOR NA, <br> HCF FEED MOTOR B, HCF FEED MOTOR NB, | HCF Feed Motor exciting signal |
| HCF T/A MOTOR A, HCF T/A MOTOR NA, |  |
| HCF T/A MOTOR B, HCF T/A MOTOR NB, |  | HCF T/A Motor exciting signal $\quad$| HCF NUDGER SOLENOID(L)+24VDC | HCF Nudger Solenoid ON/OFF control signal |
| :--- | :--- |
| HCF LIFT UP(H)+5VDC | Rise (paper feed possible level) detection signal of <br> plate in HCF by HCF Level Sensor |
| HCF FEED PAPER SENSED(L)+5VDC | Feed paper detection signal from HCF by HCF Pre <br> Feed Sensor |
| HCF TRAY NO PAPER SENSED(H)+5VDC | Paper detection signal in HCF Tray by HCF No <br> Paper Sensor (High: No paper) |

## Tandem Tray

## General Wiring Diagram

The following describes the legend of the general wiring diagram shown on the next page.

| Symbols | Description |
| :---: | :---: |
|  | Denotes a connection between parts with harnesses and wires. |
| XX | A frame not having parts name inside denotes the connector ( $\mathrm{P} / \mathrm{J}$ ). Numeric value inside implies the connector number. |
| $\stackrel{\ulcorner-X \bar{X}}{\llcorner } \stackrel{ }{\square}$ | A frame of broken line denotes the connector (P/J) written in several places separately. <br> Numeric value inside implies the connector number. |
| PWBA ABC <br> PL X.Y.Z | A frame having parts name inside denotes the parts. PL X.Y.Z implies the item "Z" of plate (PL) "X.Y" in Chapter 5. Parts List. |
|  | A frame of dotted line denotes the section in " 2 . Wiring Diagram between Parts", and numeric value implies the section number. |



## Wiring Diagram between Parts

## Configuration

The wiring diagram is separated into 3 sections to show detailed connection between parts.

- 1 Drive
- Connection between TRAY MODULE PWB and CLUTCH (Takeaway Clutch)
- Connection between TRAY MODULE PWB and MAIN MOTOR
- Connection between TRAY MODULE PWB and LEFT COVER INTERLOCK SWITCH
- Connection between TRAY MODULE PWB and PWB A MCU F
- 2 Tray3
- Connection between TRAY MODULE PWB and TRAY3 FEED LIFT UP MOTOR
- Connection between TRAY MODULE PWB and SENSOR (Tray3 Level Sensor)
- Connection between TRAY MODULE PWB and SENSOR (Tray3 No Paper Sensor)
- Connection between TRAY MODULE PWB and SENSOR (Tray3 Pre Feed Sensor)
- Connection between TRAY MODULE PWB and TRAY3 PAPER SIZE SWITCH
- Connection between TRAY MODULE PWB and TRAY3 FEED OUT SENSOR
- 3 Tray 4
- Connection between TRAY MODULE PWB and TRAY4 FEED LIFT UP MOTOR
- Connection between TRAY MODULE PWB and SENSOR (Tray4 Level Sensor)
- Connection between TRAY MODULE PWB and SENSOR (Tray4 No Paper Sensor)
- Connection between TRAY MODULE PWB and SENSOR (Tray4 Pre Feed Sensor)
- Connection between TRAY MODULE PWB and TRAY4 PAPER SIZE SWITCH
- Connection between TRAY MODULE PWB and TRAY4 FEED OUT SENSOR


## Notes on Using the Wiring Diagram between Parts

The following describes the legend of the wiring diagrams between parts shown on the following pages.
Note that the description of general symbols is omitted.

| Symbols | Description |
| :--- | :--- |


| Symbols | Description |
| :---: | :---: |
| $\xrightarrow{\text { DEVE_A }}$ | Denotes a connection between parts with harnesses or wires, attached with signal name/contents. |
| $\xrightarrow{\text { REGI CLUTCH ON(L)+24VDC }}$ | Denotes the function, and logic value of the signal to operate the function (Low: L, High: H). <br> The given voltage is for signal in high status. <br> The arrow indicates the direction of signal. |
| EXIT PAPER SENSED(L)+3.3VDC | Denotes the function, and logic value of the signal when the function operated (Low: L, High: H). <br> The given voltage is for signal in high status. <br> The arrow indicates the direction of signal. |
|  | Denotes a connection between wires. |
| I/L +24VDC | Denotes DC voltage when the interlock switch in HNB MCU WITH CPU turns on |
| $\begin{gathered} +5 \mathrm{VDC} \\ +3.3 \mathrm{VDC} \end{gathered}$ | Denotes DC voltage. |
| SG | Denotes signal ground. |
| AG | Denotes analog ground. |
| RTN | Denotes the return. |

## 1 Drive



| Signal line name | Description |
| :--- | :--- |
| TAKEAWAY CLUTCH ON(L)+24VDC | TAKEAWAY CLUTCH ON/OFF control signal |
| TAKEAWAY MOTOR ON(L)+5VDC | TAKEAWAY MOTOR ON/OFF control signal |
| TAKEAWAY MOTOR CLOCK | Clock signal to TAKEAWAY MOTOR |
| M/C CLOCK | Clock signal from TAKEAWAY MOTOR |
| LEFT COVER OPEN(H)+5VDC | LEFT COVER open/close detection signal by LEFT <br> COVER INTERLOCK SWITCH |
| ENGINE TO TTM | Communication signal of PWB A MCU F (Engine) <br> and TRAY MODULE PWB (TTM) (Engine->TTM) |
| TTM TO ENGINE | Communication signal of TRAY MODULE PWB <br> (TTM) and PWB A MCU F (Engine) (TTM->Engine) |
| TRAY3 FEED/LIFT MOTOR ON(H)+5VDC | TRAY3 FEED LIFT UP MOTOR ON/OFF control <br> signal (Engine->TTM) |
| TRAY4 FEED/LIFT MOTOR ON(H)+5VDC | TRAY4 FEED LIFT UP MOTOR ON/OFF control <br> signal (Engine->TTM) |
| FEED READY | Feed ready signal from TTM (TTM->Engine) |
| TRAY3 FEED OUT PAPER SENSED(L)+5VDC | Paper detection signal by TRAY3 FEED OUT SEN- <br> SOR in transport section (TTM->Engine) |
| TRAY4 FEED OUT PAPER SENSED(L)+5VDC | Paper detection signal by TRAY4 FEED OUT SEN- <br> SOR in transport section (TTM->Engine) |
| FEED STOP | Feed stop signal to TTM (Engine->TTM) |

2 Tray3


| Signal line name | Description |
| :--- | :--- |
| FMOT3 A, FMOT3 B, FMOT3 /A, FMOT3 /B | TRAY3 FEED LIFT UP MOTOR exciting signal |
| TRAY3 LEVEL UP(H)+5VDC | Rise (paper feed possible level) detection signal of <br> plate in Tray3 by SENSOR (Tray3 Level Sensor) |
| TRAY3 PAPER SENSED(L)+5VDC | Paper detection signal in Tray3 of SENSOR (Tray3 <br> No Paper Sensor) |
| TRAY3 PRE FEED SENSED(L)+5VDC | Feed paper detection signal from Tray3 by SENSOR <br> (Tray3 Pre Feed Sensor) |
| TRAY3 SIZE SWITCH SIGNAL | Paper size detection signal (analog value) of TRAY3 <br> PAPER SIZE SWITCH |
| TRAY3 FEED OUT PAPER SENSED(L)+5VDC | Paper detection signal by TRAY3 FEED OUT SEN- <br> SOR in transport section |

Paper size detection

- The ON/OFF pattern of each switch (S1, S2) of TRAY3 PAPER SIZE SWITCH and the relation of paper size and the output voltage of TRAY3 SIZE SWITCH SIGNAL are as follows.

| Paper Size | S1 | S2 | Output <br> Voltage(V) |
| :--- | :---: | :---: | :---: |
| No Tray | OFF | OFF | $3.06 \AA\} 0.03$ |
| B5 LEF / 7.25" $\AA \sim 10.5^{\prime \prime}$ LEF | OFF | ON | $2.61 \AA\} 0.03$ |
| $8.5^{\prime \prime} \AA \sim 11^{\prime \prime}$ LEF | ON | OFF | $1.41 \AA\} 0.03$ |
| A4 LEF | ON | ON | $1.00 \AA\} 0.03$ |

3 Tray4


| Signal line name | Description |
| :--- | :--- |
| FMOT4 A, FMOT4 B, FMOT4 /A, FMOT4 /B | TRAY4 FEED LIFT UP MOTOR exciting signal |
| TRAY4 LEVEL UP(H)+5VDC | Rise (paper feed possible level) detection signal of <br> plate in Tray4 by SENSOR (Tray4 Level Sensor) |
| TRAY4 PAPER SENSED(L)+5VDC | Paper detection signal in Tray4 of SENSOR (Tray4 <br> No Paper Sensor) |
| TRAY4 PRE FEED SENSED(L)+5VDC | Feed paper detection signal from Tray4 by SENSOR <br> (Tray4 Pre Feed Sensor) |
| TRAY4 SIZE SWITCH SIGNAL | Paper size detection signal (analog value) of TRAY4 <br> PAPER SIZE SWITCH |
| TRAY4 FEED OUT PAPER SENSED(L)+5VDC | Paper detection signal by TRAY4 FEED OUT SEN- <br> SOR in transport section |

Paper size detection

- The ON/OFF pattern of each switch (S1, S2) of TRAY4 PAPER SIZE SWITCH and the relation of paper size and the output voltage of TRAY4 SIZE SWITCH SIGNAL are as follows.

| Paper Size | S1 | S2 | Output <br> Voltage(V) |
| :--- | :---: | :---: | :---: |
| No Tray | OFF | OFF | $3.06 \AA\} 0.03$ |
| B5 LEF $/ 7.25^{\prime \prime} \AA \sim 10.5^{\prime \prime}$ LEF | OFF | ON | $2.61 \AA\} 000$ |
| $8.5^{\prime \prime} \AA \sim 11^{\prime \prime}$ LEF | ON | OFF | $1.41 \AA\} 0.03$ |
| A4 LEF | ON | ON | $1.00 \AA\} 0.03$ |

## Chapter 5 Plug/Jack

## Engine

## Connector [P (plug) / J (jack)]

## List of P/J

| P/J | Coordinat es | Remarks |
| :---: | :---: | :---: |
| 1 | D-204 | Connects Power Unit and Main Switch Harness Assembly |
| 2 | D-243 | Connects Power Unit and Finisher Outlet |
| 3 | D-245 | Connects Power Unit and Heater Harness Assembly |
| 6 | E-245 | Connects Power Unit and Fuser AC Harness Assembly |
| 7 | E-245 | Not Connects |
| 11 | D-245 | Connects Power Unit and GFI |
| 12 | D-245 | Connects Power Unit and GFI |
| 20 | J-141 | Connects Main Lamp and Fuser Harness Assembly |
| 21 | J-141 | Connects Sub Lamp 1 and Fuser Harness Assembly |
| 22 | J-141 | Connects Sub Lamp 2 and Fuser Harness Assembly |
| 50 | F-229 | Connects GFI and Power Unit |
| 56 | B-238 | Connects Main Switch and Main Switch Harness Assembly |
| 57 | B-239 | Connects Main Switch and Main Switch Harness Assembly |
| 68 | B-239 | Connects Main Switch and Main Switch Harness Assembly |
| 69 | B-239 | Connects Main Switch and Main Switch Harness Assembly |
| 72 | F-230 | Connects GFI and Frame (Earth) |
| 73 | G-230 | Connects Finisher Outlet and Power Unit |
| 74 | G-230 | Connects Finisher Outlet and Power Unit |
| 75 | G-230 | Connects Finisher Outlet and Frame (Earth) |
| 100 | G-180 | Connects Tray 1 Level Sensor and Tray 1 Feeder Harness Assembly |
| 101 | G-180 | Connects Tray 1 No Paper Sensor and Tray 1 Feeder Harness Assembly |
| 102 | G-180 | Connects Tray 2 Level Sensor and Tray 2 Feeder Harness Assembly |
| 103 | G-180 | Connects Tray 2 No Paper Sensor and Tray 2 Feeder Harness Assembly |
| 104 | F-167 | Connects REGI Sensor and REGI Harness Assembly |
| 105 | F-186 | Connects Take Away Sensor and Take Away Sensor Harness Assembly |
| 106 | D-183 | Connects LHL Switch and PH Harness Assembly |
| 107 | D-153 | Connects MPF Size Sensor and MPF Sensor Harness Assembly |
| 108 | G-152 | Connects MPF No Paper Sensor and MPF Harness Assembly |
| 109 | D-200 | Connects Tray 1 Size Sensor and Size Harness Assembly |
| 110 | D-201 | Connects Tray 2 Size Sensor and Size Harness Assembly |
| 117 | B-134 | Connects OCT Home 1 Sensor and OCT Harness Assembly |
| 118 | B-134 | Connects Full Stack Sensor and OCT Harness Assembly |
| 120 | H-196 | Connects LH Cover Interlock Switch and PWBA MCU |
| 121 | C-244 | Connects Front Cover Interlock Switch and INTLK Harness Assembly |
| 125 | C-106 | Connects Fuser Exit Sensor and PH Harness Assembly |
| 126 | D-122 | Connects XERO CRU and Crum Harness Assembly |
| 127 | F-108 | Connects Toner CRU and Crum Harness Assembly |
| 130 | E-124 | Connects ROS (Scanner) and ROS Harness Assembly |
| 131 | B-139 | Connects Center STS and FUSER Outlet |
| 132 | B-139 | Connects 2nd STS and FUSER Outlet |
| 133 | B-139 | Connects Rear STS and FUSER Outlet |


| P/J | Coordinat es | Remarks |
| :---: | :---: | :---: |
| 133 | H-181 | Connects Tray 1 Pre Feed Sensor and Tray 1 Feeder Harness Assembly |
| 134 | H-181 | Connects Tray 2 Pre Feed Sensor and Tray 2 Feeder Harness Assembly |
| 140 | F-123 | Connects ROS and ROS Harness Assembly |
| 150 | G-166 | Connects Hum \& Temp Sensor and REGI Harness Assembly |
| 160 | F-123 | Connects ROS and ROS Harness Assembly |
| 170 | F-123 | Connects ROS and ROS Harness Assembly |
| 201 | E-180 | Connects Tray 1 Feed Liftup Motor and Tray 1 Feeder Harness Assembly |
| 202 | E-180 | Connects Tray 2 Feed Liftup Motor and Tray 2 Feeder Harness Assembly |
| 204 | H-199 | Connects Takeaway Clutch and PH Harness Assembly |
| 205 | D-151 | Connects MPF Feed Solenoid and MPF Harness Assembly |
| 206 | G-196 | Connects No. 1 OCT MOT and EXIT Harness Assembly |
| 214 | G-198 | Connects Drive Assembly and Drive Harness Assembly |
| 215 | E-166 | Connects REGI Clutch and REGI Harness Assembly |
| 216 | H-106 | Connects Dispense MOT and LV PWR Harness Assembly |
| 221 | E-107 | Connects PWBA MCU and CRU Fan |
| 311 | B-242 | Connects Console Panel and Console Panel Harness Assembly |
| 400 | C-214 | Connects PWBA MCU and LV PWR Harness Assembly |
| 401 | C-214 | Connects PWBA MCU and LV PWR Harness Assembly |
| 402 | D-212 | Connects PWBA MCU and ESS Harness Assembly |
| 403 | F-211 | Connects PWBA MCU and REGI Harness Assembly |
| 404 | E-212 | Connects PWBA MCU and XERO Harness Assembly |
| 405 | G-212 | Connects PWBA MCU and INTLK Harness Assembly |
| 406 | D-212 | Connects PWBA MCU and ROS Harness Assembly |
| 407 | C-212 | Connects PWBA MCU and ROS Harness Assembly |
| 408 | G-211 | Connects PWBA MCU and Drive Harness Assembly |
| 409 | G-213 | Connects PWBA MCU and Feeder Harness Assembly |
| 410 | G-212 | Connects PWBA MCU and PH Harness Assembly |
| 411 | G-214 | Connects PWBA MCU and MPF Harness Assembly |
| 412 | C-213 | Connects PWBA MCU and Size Harness Assembly |
| 413 | D-214 | Connects PWBA MCU and Tray Module Harness Assembly |
| 414 | F-214 | Connects PWBA MCU and HCF Harness Assembly |
| 415 | F-214 | Connects PWBA MCU and HCF Harness Assembly |
| 416 | D-214 | Connects PWBA MCU and Output Unit |
| 417 | E-214 | Connects PWBA MCU and DUP Harness Assembly |
| 419 | D-212 | Connects PWBA MCU and Crum Harness Assembly |
| 420 | C-212 | Connects PWBA MCU and LV PWR Harness Assembly |
| 421 | C-213 | Connects PWBA MCU and LV PWR Harness Assembly |
| 430 | H-120 | Connects PWBA EXIT and LV PWR Harness Assembly |
| 431 | H-120 | Connects PWBA EXIT and LV PWR Harness Assembly |
| 432 | H-120 | Connects PWBA EXIT and EXIT Harness Assembly |
| 433 | I-120 | Connects PWBA EXIT and EXIT Harness Assembly |
| 434 | I-120 | Connects PWBA EXIT and EXIT Harness Assembly |
| 500 | C-110 | Connects HVPS and REGI Harness Assembly |
| 521 | I-246 | Connects Power Unit and LV PWR Harness Assembly |
| 525 | I-247 | Connects Power Unit and LV PWR Harness Assembly |
| 526 | I-245 | Connects Power Unit and LV PWR Harness Assembly |
| 600 | A-139 | Connects FUSER and FUSER AC Harness Assembly |
| 600 | H-196 | Connects FUSER Assembly and Fuser Harness Assembly |


| P/J | Coordinat <br> es | Remarks |
| :---: | :---: | :--- |
| 601 | C-183 | Connects Tray 1 Feeder Harness Assembly and Feeder Harness Assembly |
| 602 | C-184 | Connects Tray 2 Feeder Harness Assembly and Feeder Harness Assembly |
| 605 | I-199 | Connects MPF Assembly and MPF Harness Assembly |
| 606 | G-195 | Connects EXIT 2 Harness Assembly and EXIT Harness Assembly |
| 607 | G-199 | Connects Fuser Harness Assembly and PH Harness Assembly |
| 608 | C-184 | Connects Take Away Sensor Harness Assembly and PH Harness Assembly |
| 609 | D-151 | Connects MPF Sensor Harness Assembly and MPF Harness Assembly |
| 610 | B-109 | Connects ATC Sensor and REGI Harness Assembly |
| 613 | G-196 | Connects OCT Harness Assembly and EXIT Harness Assembly |
| 620 | F-122 | Connects ROS and ROS Harness Assembly |
| 800 | H-200 | Connects HCF and HCF Harness Assembly |

P/J layout diagram











## 1000 Sheet Feeder

List of PIJ

| P/J | Coordinat <br> es | Remarks |
| :---: | :---: | :--- |
| 101A | C-304 | Connects Level Sensor 4 and Tray 4 Harness Assembly |
| 101B | C-304 | Connects Level Sensor 3 and Tray 3 Harness Assembly |
| 102A | D-305 | Connects No Paper Sensor 4 and Tray 4 Harness Assembly |
| $102 B$ | D-305 | Connects No Paper Sensor 3 and Tray 3 Harness Assembly |
| $103 A$ | D-306 | Connects Pre Feed Sensor 4 and Tray 4 Harness Assembly |
| $103 B$ | D-306 | Connects Pre Feed Sensor 3 and Tray 3 Harness Assembly |
| 202A | B-304 | Connects FMOT 4 and Tray 4 Harness Assembly |
| $202 B$ | B-304 | Connects FMOT 3 and Tray 3 Harness Assembly |
| 541 | F-323 | Connects PWBA ABC TM and Tray Module Harness Assembly |
| 548 | E-323 | Connects PWBA ABC TM and Size Switch Harness Assembly |
| $549 A$ | F-324 | Connects PWBA ABC TM and Feeder Harness Assembly |
| $549 B$ | F-324 | Connects PWBA ABC TM and Feeder Harness Assembly |
| 552 | F-323 | Connects PWBA ABC TM and T/A Harness Assembly |
| 554 | F-323 | Connects PWBA ABC TM and Interlock Switch Harness Assembly |
| $661 A$ | D-309 | Connects Tray 4 Harness Assembly and Feeder Harness Assembly |
| $661 B$ | D-308 | Connects Tray 3 Harness Assembly and Feeder Harness Assembly |
| 812 | D-308 | Connects Interlock Switch and Interlock Switch Harness Assembly |
| 820 | G-307 | Connects Size Switch 3 and Size Switch Harness Assembly |
| 821 | E-308 | Connects F-Out Sensor 3 and F-Out Sensor 3 Harness Assembly |
| 822 | I-322 | Connects T/A Clutch and T/A Harness Assembly |
| 824 | G-308 | Connects Size Switch 4 and Size Switch Harness Assembly |
| 825 | E-309 | Connects F-Out Sensor 4 and F-Out Sensor 4 Harness Assembly |
| 826 | G-324 | Connects T/A Motor and T/A Harness Assembly |
| 841 | I-320 | Connects F-Out Sensor 3 Harness Assembly and Size Switch Harness Assem- <br> bly |
| 842 | D-308 | Connects F-Out Sensor 4 Harness Assembly and Size Switch Harness Assem- <br> bly |

P/J layout diagram



## Duplex

## List of P/J

| P/J | Coordinat <br> es | Remarks |
| :---: | :---: | :--- |
| 123 | D-606 | Connects DUP Sensor and DUP Sensor Harness Assembly |
| 124 | B-606 | Connects DUP Open Switch and Sensor Harness Assembly |
| 212 | C-608 | Connects DUP Motor and DUP Motor Harness Assembly |
| 540 | H-608 | Connects PWBA DUP and DUP Harness Assembly |
| 541 | H-609 | Connects PWBA DUP and DUP Sensor Harness Assembly |
| 542 | H-609 | Connects PWBA DUP and DUP Motor Harness Assembly |



## Exit 2

Connector [P (plug) / J (jack)]
List of PIJ

| P/J | Coordinat <br> es | Remarks |
| :---: | :---: | :--- |
| 111 | D-707 | Connects OCT Home 2 Sensor and Exit 2 Harness Assembly |
| 112 | F-708 | Connects Exit 2 Sensor and Exit 2 Harness Assembly |
| 113 | F-707 | Connects Full Stack Sensor and Exit 2 Harness Assembly |
| 115 | B-706 | Not Used |
| 116 | C-706 | Connects Interlock Switch and Exit 2 Harness Assembly |
| 207 | C-707 | Connects No.2 OCT Motor and Exit 2 Harness Assembly |
| 208 | B-707 | Connects Exit Drive Motor and Exit 2 Harness Assembly |
| 209 | D-708 | Connects Exit Gate Solenoid and Exit 2 Harness Assembly |
| 210 | C-708 | Connects Fut Gate Solenoid and Exit 2 Harness Assembly |



Finisher

| P/J | Coordinat es | Remarks |
| :---: | :---: | :---: |
| 2 | E-903 | Connects LVPS and AC Inlet Harness Assembly |
| 502 | B-902 | Connects LVPS and LVPS Harness Assembly |
| 505 | B-902 | Connects LVPS and LVPS Harness Assembly |
| 8300 | G-894 | Connects PWBA Main-C and I/F Harness Assembly |
| 8301 | G-894 | Not Connects |
| 8302 | E-895 | Connects PWBA Main-C and Main Sensor Harness Assembly |
| 8304 | E-892 | Connects PWBA Main-C and Main Drive Harness Assembly |
| 8305 | E-894 | Connects PWBA Main-C and Elevator Motor |
| 8306 | G-892 | Connects PWBA Main-C and Punch Drive Harness Assembly |
| 8307 | G-893 | Connects PWBA Main-C and Punch Sensor Harness Assembly |
| 8308 | F-892 | Connects PWBA Main-C and Staple Harness Assembly |
| 8309 | E-894 | Connects PWBA Main-C and Compiler Harness Assembly |
| 8310 | G-895 | Connects PWBA Main-C and Htra Harness Assembly |
| 8311 | E-896 | Not Connects |
| 8313 | F-896 | Not Connects |
| 8314 | F-896 | Connects PWBA Main-C and Interlock Harness Assembly |
| 8315 | E-896 | Connects PWBA Main-C and LVPS Harness Assembly |
| 8316 | G-896 | Not Connects |
| 8317 | E-896 | Not Connects |
| 8319 | E-883 | Connects X'port Ent Sensor and Harness Assembly |
| 8320 | F-853 | Connects Compile Exit Sensor and Comp Sensor Harness Assembly |
| 8321 | F-881 | Connects Top Tray Exit Sensor and Top Tray Exit Sensor Harness Assembly |
| 8322 | F-881 | Connects Top Tray Full Sensor and Top Tray Full Sensor Harness Assembly |
| 8324 | E-852 | Connects Eject Clamp Home Sensor and Main Sensor Harness Assembly |
| 8325 | E-868 | Connects Set Clamp Home Sensor and Main Sensor Harness Assembly |
| 8326 | E-821 | Connects Stacker No Paper Sensor and Main Sensor Harness Assembly |
| 8327 | E-821 | Connects Upper Limit Sensor and Main Sensor Harness Assembly |
| 8328 | D-821 | Connects Stack Encoder Sensor and Main Sensor Harness Assembly |
| 8330 | J-821 | Connects Stack Height Sensor 2 and Main Sensor Harness Assembly |
| 8331 | E-819 | Connects Stack Height Sensor 1 and Main Sensor Harness Assembly |
| 8334 | C-880 | Connects Exit Motor and Main Drive Harness Assembly |
| 8335 | D-881 | Connects Regi Motor and Main Drive Harness Assembly |
| 8336 | D-866 | Connects Eject Motor and Main Drive Harness Assembly |
| 8338 | E-868 | Connects Set Clamp Clutch and Main Drive Harness Assembly |
| 8339 | C-851 | Connects Eject Clamp Motor and Main Drive Harness Assembly |
| 8340 | H-852 | Connects Sub Paddle Solenoid and Main Drive Harness Assembly |
| 8341 | C-853 | Connects Transport Gate Solenoid and Main Drive Harness Assembly |
| 8342 | B-884 | Connects Fin Transport Motor and Main Drive Harness Assembly |
| 8344 | E-835 | Connects Puncher Move Motor and Punch Drive Harness Assembly |
| 8345 | C-837 | Connects Puncher Motor and Punch Unit Harness Assembly |
| 8346 | C-836 | Connects Punch Hole Select Sensor and Punch Unit Harness Assembly |
| 8347 | C-836 | Connects Puncher Front Sensor and Punch Unit Harness Assembly |
| 8348 | C-836 | Connects Puncher Home Sensor and Punch Unit Harness Assembly |
| 8349 | C-837 | Connects Puncher Motor Sensor and Punch Unit Harness Assembly |
| 8350 | G-837 | Connects Side Regi Sensor 1 and Punch Unit Harness Assembly |
| 8351 | G-837 | Connects Side Regi Sensor 2 and Punch Unit Harness Assembly |
| 8352 | C-836 | Connects Puncher Move Home Sensor and Punch Sensor Harness Assembly |


| P/J | Coordinat <br> es | Remarks |
| :--- | :---: | :--- |
| 8353 | C-838 | Connects Punch Box Set Sensor and Punch Box Set Sensor Harness Assembly |
| 8354 | E-826 | Connects Stapler Move Position Sensor and Staple Harness Assembly |
| 8356 | F-826 | Connects Stapler Unit and Staple Harness Assembly |
| 8357 | F-826 | Connects Stapler Unit and Staple Harness Assembly |
| 8358 | F-826 | Connects Stapler Move Motor and Staple Harness Assembly |
| 8359 | G-869 | Connects Compile Tray No Paper and Compiler Harness Assembly |
| 8360 | I-869 | Connects Front Tamper Home Sensor and Compiler Harness Assembly |
| 8361 | E-868 | Connects Rear Tamper Home Sensor and Compiler Harness Assembly |
| 8362 | F-868 | Connects Rear Tamper Motor and Compiler Harness Assembly |
| 8363 | G-869 | Connects Front Tamper Motor and Compiler Harness Assembly |
| 8364 | H-852 | Connects Eject Cover Switch and Interlock Harness Assembly |
| 8365 | F-822 | Connects Finisher Front Door Switch and Interlock Harness Assembly |
| 8371 | I-898 | Connects PWBA Htra and Htra Harness Assembly |
| 8372 | I-898 | Connects PWBA Htra and H-X'port 1 Harness Assembly |
| 8373 | I-898 | Not Connects |
| 8376 | E-895 | Connects PWBA Main-C and Gate Sensor 1 Harness Assembly |
| 8379 | I-807 | Connects H-X'Port Ent Sensor and H-X'Port Harness Assembly |
| 8380 | C-807 | Connects H-X'Port Motor and H-X'Port Harness Assembly |
| 8381 | J-809 | Connects H-X'Port Exit Sensor and H-X'Port Harness Assembly |
| 8382 | G-810 | Connects H-X'Port Interlock Sensor and H-X'Port Harness Assembly |
| 8389 | F-892 | Not Connects |
| 8392 | F-882 | Connects Buffer Path Sensor and Buffer Path Sensor Harness Assembly |
| 8394 | B-853 | Connects Buffer Gate Solenoid and Main Drive Harness Assembly |
| 8394 | J-898 | Connects PWBA Htra and Htra Assembly |
| 8432 | E-882 | Connects Gate Sensor and Gate Sensor Harness Assembly |
| 8452 | C-839 | Connects Punch Full Sensor and Punch Full Sensor Harness Assembly |
| 8500 | I-898 | Connects PWBA Htra and Punch Full Sensor Harness Assembly |

## P/J layout diagram









## HCF

| P/J | Coordinat es | Remarks |
| :---: | :---: | :---: |
| 1 | G-523 | Connects PWBA HCF and Sensor Harness Assembly |
| 2 | G-523 | Connects PWBA HCF and HCF Feeder 1 Harness Assembly |
| 3 | G-524 | Connects PWBA HCF and HCF Harness Assembly |
| 4 | G-524 | Connects PWBA HCF and HCF Harness Assembly |
| 5 | F-524 | Connects PWBA HCF and Interlock Switch Harness Assembly |
| 6 | F-524 | Connects PWBA HCF and HCF Feeder 1 Harness Assembly |
| 8 | G-523 | Connects PWBA HCF and Side Out Switch Harness Assembly |
| 51 | F-521 | Connects Size A Sensor and Sensor Harness Assembly |
| 52 | G-521 | Connects Size B Sensor and Sensor Harness Assembly |
| 53 | F-525 | Connects Tray In Sensor and Sensor Harness Assembly |
| 54 | E-505 | Connects Feed Out Sensor Harness Assembly and Sensor Harness Assembly |
| 56 | C-506 | Connects HCF Feeder Harness Assembly and HCF Feeder 1 Harness Assembly |
| 57 | E-524 | Connects T/A Motor and HCF Feeder 1 Harness Assembly |
| 58 | D-506 | Connects Feed Motor and HCF Feeder Harness Assembly |
| 59 | D-506 | Connects NUG Solenoid and HCF Feeder Harness Assembly |
| 60 | G-506 | Connects No Paper Sensor and HCF Feeder Harness Assembly |
| 61 | H-506 | Connects PF Sensor and HCF Feeder Harness Assembly |
| 62 | H-506 | Connects Level Sensor and HCF Feeder Harness Assembly |
| 67 | H-506 | Connects Feed Out Sensor and Feed Out Sensor Harness Assembly |
| FS001 | E-505 | Connects Trans Interlock Switch and Interlock Switch Harness Assembly |
| FS002 | E-505 | Connects Trans Interlock Switch and Interlock Switch Harness Assembly |
| FS003 | E-507 | Connects HCF Side Out Switch and Side Out Switch Harness Assembly |
| FS004 | E-507 | Connects HCF Side Out Switch and Side Out Switch Harness Assembly |

## PL 0.5 P/J layout diagram




## Tandem Tray

## Connector [P (plug) / J (jack)]

## List of PIJ

| P/J | Coordinat <br> es | Remarks |
| :---: | :---: | :--- |
| 101A | C-404 | Connects Level Sensor 4 and Tray 4 Harness Assembly |
| 101B | C-404 | Connects Level Sensor 3 and Tray 3 Harness Assembly |
| 102A | D-405 | Connects No Paper Sensor 4 and Tray 4 Harness Assembly |


| P/J | Coordinat <br> es | Remarks |
| :---: | :---: | :--- |
| 102B | D-405 | Connects No Paper Sensor 3 and Tray 3 Harness Assembly |
| 103A | D-406 | Connects Pre Feed Sensor 4 and Tray 4 Harness Assembly |
| 103B | D-406 | Connects Pre Feed Sensor 3 and Tray 3 Harness Assembly |
| 202A | A-404 | Connects FMOT 4 and Tray 4 Harness Assembly |
| 202B | A-404 | Connects FMOT 3 and Tray 3 Harness Assembly |
| 541 | E-423 | Connects PWBA ABC TM and Tray Module Harness Assembly |
| 548 | D-423 | Connects PWBA ABC TM and Size Switch Harness Assembly |
| 549A | E-424 | Connects PWBA ABC TM and Feeder Harness Assembly |
| $549 B$ | E-424 | Connects PWBA ABC TM and Feeder Harness Assembly |
| 552 | E-423 | Connects PWBA ABC TM and T/A Harness Assembly |
| 554 | E-423 | Connects PWBA ABC TM and Interlock Switch Harness Assembly |
| 661 A | H-412 | Connects Tray 4 Harness Assembly and Feeder Harness Assembly |
| $661 B$ | B-409 | Connects Tray 3 Harness Assembly and Feeder Harness Assembly |
| 812 | B-408 | Connects Interlock Switch and Interlock Switch Harness Assembly |
| 820 | E-409 | Connects Size Switch 3 and Size Switch Harness Assembly |
| 821 | B-408 | Connects F-Out Sensor 3 and F-Out Sensor 3 Harness Assembly |
| 822 | I-423 | Connects T/A Clutch and T/A Harness Assembly |
| 824 | E-408 | Connects Size Switch 4 and Size Switch Harness Assembly |
| 825 | F-421 | Connects F-Out Sensor 4 and F-Out Sensor 4 Harness Assembly |
| 826 | G-423 | Connects T/A Motor and T/A Harness Assembly |
| 841 | I-420 | Connects F-Out Sensor 3 Harness Assembly and Size Switch Harness Assem- <br> bly |
| 842 | H-422 | Connects F-Out Sensor 4 Harness Assembly and Size Switch Harness Assem- <br> bly |

PIJ layout diagram

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## Chapter 6 Removal / Replacement Procedures

Parts removal and replacement procedures are described in thin this chapter.
NOTE Parts are controlled as spare parts. When servicing parts for which there are no procedures, observe their condition in the parts lists.
NOTE Though the optional parts are assumed to be removed, they may not be removed if not required for the purpose of service.

## Before starting service work

- Turn the power OFF and remove the power cord from the electric outlet.
- When performing service operation for parts around the Fuser Assembly, start the service after the Fuser Assembly and parts around it have cooled down.
- To prevent damage, do not use force to remove or install parts.
- Since a wide variety of screws are used, be careful not to mistake their positions, to prevent crushing of the screw holes or other troubles.
- Wear a antistatic wrist band to remove static electricity from the human body.


## Confirmation after service

Be sure to run the machine in all modes of operation to ensure that the machine is completely operational.

## Description of procedures

- "RRP X.Y "AAAAA" at the top of procedures represent the procedure number and the part name.
- "(PL X.Y.Z)" following the part name in procedures represent that the parts are those of the plate (PL) "X.Y", item "Z" in Chapter 5, Parts List.
- In the procedures, directions are represented as follows.
- Front: Front when you are facing the front of this machine.
- Rear: Inner direction when you are facing the front of this machine.
- Left: Left hand when you are facing the front of this machine.
- Right: Right hand when you are facing the front of this machine


Figure 1 Machine IOT Directions


Figure 21000 Sheet Feeder Directions


Figure 3 Duplex Unit Directions


Figure 4 Exit 2 Directions


Figure 5 Finisher Horizontal Transport Directions


Figure 6 Finisher Unit Directions


Figure 7 High Capacity Feeder Directions


Figure 8 Tandem Tray Directions

- The screws in procedures are expressed with their replacing position, color, characteristics and nominal length, etc.
- "RRP X.Y" in the midst or at the end of sentences in the procedures indicate that work procedures related with the "RRP X.Y" are described.
- "Figure $X$ " at the end of the sentences of procedures indicate that illustrations instructive for the "RRP X.Y" are included.
- The screws in the illustrations should be removed using a plus (+) screwdriver unless otherwise specified.
- A black arrow in the illustrations indicate movement in the arrow mark direction.
- Numbered black arrows indicate movement in the order of the numbers.
- White arrows (FRONT) in the illustrations indicate the front direction.
- For the positions of the connectors (P/J), refer to Chapter 7, Electric wiring.


## RRP 1 IOT Covers

## RRP 1.1 Fuser Cover (FR, PR)

## Removal

1. Open the Front Cover Assembly (PL 1.1.9).
2. Remove the screw (Del Tite, M3x8mm) securing the Fuser Cover (FR, PR) to the machine.
3. Remove the Fuser Cover (FR, PR).


Figure 1 Front and Fuser Cover

## Replacement

1. Install the Fuser Cover (FR, PR) to the machine using the screw (Del Tite, M3x8mm).
2. Close the Front Cover Assembly (PL 1.1.9).

## RRP 1.2 Top Rear Cover (PR)

## Removal

1. Remove the ESS Cap Cover (PR) (PL 1.2.4).
2. Remove the two screws (Del Tite, M3x8mm) securing the Upper Rear Cover (PL 1.2.5) to the machine.
3. Open the Upper Rear Cover.
4. Remove the screw (Del Tite, M3x8mm) securing the Top Cover (RR, PR) to the machine.
5. Remove the Top Cover (RR, PR) by moving it in the direction of the arrow.


Figure 1 Top Cover

## Replacement

1. Install the Top Cover (RR, PR) to the machine using the screw (Del Tite, M3x8mm).
2. Close the Upper Rear Cover (PL 1.2.5).
3. Install the Upper Rear Cover to the machine using the two screws (Del Tite, M3x8mm)
4. Install the ESS Cap Cover (PR) (PL 1.2.4).

## RRP 1.3 Interlock Switch

## Removal

1. Remove the Top Cover Assembly (PR) (PL 1.1.8).
2. Remove the Front Cover Assembly (PL 1.1.9).
3. Remove the Fuser Cover (FR, PR) (PL 1.1.2).
4. Remove the Inner Cover Assembly (MN) (PL 1.1.13).
5. Remove the screw (Del Tite, M3x6mm) securing the Bracket ILSW (PL 1.1.4) to the machine.
6. Disconnect the connector (P/J140) of the Interlock Harness Assembly (A) (PL 8.2.10) from the switch.
7. Remove the Switch together with the Bracket ILSW.
8. Release the hooks on the switch by pressing the hooks on the Switch.
9. Remove the Switch.


Figure 1 Interlock Switch

## Replacement

1. Install the Switch to the Bracket ILSW (PL 1.1.4) while pressing the hook on the switch.
2. Connect connector (P/J140) of the Interlock Harness Assembly (A) (PL 8.2.10) to the SWITCH.
3. Install the Bracket ILSW to the machine using the screw (Del Tite, M3x6mm).
4. Install the Inner Cover Assembly (MN) (PL 1.1.13).
5. Install the Fuser Cover (FR, PR) (PL 1.1.2).
6. Install the Front Cover Assembly (PL 1.1.9).
7. Install the Top Cover Assembly (PR) (PL 1.1.8).

## RRP 1.4 Console Panel

## Removal

1. Remove the Top Cover Assembly (PR) (PL 1.1.8).
2. Place the Top Cover Assembly (PR) up side down, and remove the Console Panel by releasing the six hooks securing the Console Panel to the Top Cover Assembly (PR).
3. Move the Console Panel in the arrow direction to remove.


Figure 1 Console Panel

## Replacement

1. Fit the left side hooks of the Console Panel into the holes on the Top Cover Assembly (PR) (PL 1.1.8).
2. Install the Console Panel to the Top Cover Assembly (PR) using six hooks.
3. Install the Top Cover Assembly (PR) (PL 1.1.8).

## RRP 1.5 Top Cover Assembly (PR)

## Removal

1. Open the Front Cover Assembly (PL 1.1.9).
2. Remove the Fuser Cover (FR, PR) (PL 1.1.2).
3. Remove the two screws (Del Tite, M3x8mm) securing the Top Cover Assembly (PR) to the machine.
4. Remove the Top Cover Assembly (PR) by moving it in the direction of the arrow.
5. Disconnect the connector (P/J301) of the Console Panel Harness Assembly (PL 1.1.7) from the Top Cover Assembly (PR).


Figure 1 Top Cover Assembly

## Replacement

1. Connect the connector (P/J301) of the Console Panel Harness Assembly (PL 1.1.7) to the Top Cover Assembly (PR).
2. Install the Top Cover Assembly (PR) while moving it in the direction of the arrow (to the front).
3. Install the Top Cover Assembly (PR) to the machine using the two screws (Del Tite, M3x8mm).
4. Install the Fuser Cover (FR, PR) (PL 1.1.2).
5. Close the Front Cover Assembly (PL 1.1.9).

## RRP 1.6 Front Cover Assembly

## Removal

1. Open the Front Cover Assembly.
2. Remove the Strip (PL 1.1.12) securing the Front Cover Assembly to the Inner Cover Assembly (MN) (PL 1.1.13) by releasing the hook.
3. With the Front Cover Assembly open, slide the Front Cover Assembly in the direction of the arrow A to release the lower right holder from the boss on the right of the printer.
4. While the lower right holder of the Front Cover Assembly is released, place the cover slightly obliquely to the printer and slide it in the direction of the arrow B to release the lower left holder from the boss on the left of the printer.
5. Remove the Front Cover Assembly.


Figure 1 Front Cover Assembly

## Replacement

1. Place the Front Cover Assembly to parallel to the printer, and fit the lower left holder onto the boss on the left of the printer.
2. While placing the Front Cover Assembly to parallel to the printer, slide it in the direction of the arrow A so that the boss on the lower left of the Front Cover Assembly fit the holder on the printer first, and slide the Front Cover Assembly in the direction of arrow B so that the boss on the lower right fits in the holder on the printer.
3. Install the Strip (PL 1.1.12) to the Inner Cover Assembly (MN) (PL 1.1.13) with the hook.
4. Close the Front Cover Assembly.

## RRP 1.7 Front Cover

## Removal

1. Remove the Front Cover Assembly (PL 1.1.9).
2. Remove the screw (Silver, M3x8mm) securing the Strip (PL 1.1.12) to the Front Cover (PL 1.1.11), remove the Strip.
3. Release the two hooks on the Front Cover securing the Magnet Catch 30 (PL 1.1.10) to the Front Cover, remove the Magnet Catch 30.


Figure 1 Front Cover

## Replacement

1. Install the Magnet Catch 30 (PL 1.1.10) to the Front Cover (PL 1.1.11), and secure with two hooks.
2. Install the Strip to the Front Cover using the screw (Silver, M3x8mm).

NOTE The Strip has two holes, be sure to use bottom hole when tightening.
3. Install the Front Cover Assembly (PL 1.1.9).

## RRP 1.8 Inner Cover Assembly (MN)

## Removal

1. Remove the Top Cover Assembly (PR) (PL 1.1.8).
2. Remove the Front Cover Assembly (PL 1.1.9).
3. Remove the Fuser Cover (FR, PR) (PL 1.1.2).
4. Remove the CRU (PL 5.1.15).
5. Remove the three screws (Del Tite, M3x8mm) securing the Inner Cover Assembly (MN) to the machine.
6. Remove the Inner Cover Assembly (MN).


Figure 1 Inner Cover Assembly

## Replacement

1. Install the Inner Cover Assembly (MN) to the machine using the three screws (Del Tite, $\mathrm{M} 3 \times 8 \mathrm{~mm}$ ).
NOTE When installing, be surer to put the four lower hooks on the Inner Cover Assembly (MN) inside the Bracket on the printer.
2. Install the CRU (PL 5.1.15).
3. Install the Fuser Cover (FR, PR) (PL 1.1.2).
4. Install the Front Cover Assembly (PL 1.1.9).
5. Install the Top Cover Assembly (PR) (PL 1.1.8).

## RRP 1.9 Upper Right Cover

## Removal

1. Remove the two screws (Del Tite, M3x8mm) securing the Upper Right Cover to the machine.
2. Move the upper rib of the Upper Right Cover in the direction of the arrow to release the upper rib.
3. Move the Lower Right Cover (PL 1.2.2) downward to release the lower rib.
4. Remove the Upper Right Cover.


Figure 1 Right Upper Cover

## Replacement

1. Move the upper rib on the Upper Right Cover in the opposite direction of the arrow to engage them to the frame.
2. Install the Upper Right Cover to the machine using the two screws (Del Tite, M3x8mm).

NOTE Be sure to secure the lower rib on the Upper Right Cover to the upper part of the Lower Right Cover (PL 1.2.2).

## RRP 1.10 Lower Right Cover

## Removal

1. Remove the Upper Right Cover (PL 1.2.1).
2. Pull out the Tray 3 and Tray 4.
3. Remove the Lower Right Cover by pulling the center of it upward.


Figure 1 Lower Right Cover

## Replacement

1. Fit the four bosses on the back of the Lower Right Cover into the four holes on the frame, and push the COVER RIGHT downward to install.
2. Install the Tray 3 and Tray 4.
3. Install the Upper Right Cover (PL 1.2.1).

## RRP 1.11 ESS Cap Cover (PR)

## Removal

1. Open the ESS Cap Cover (PR).
2. Remove the lower boss on the ESS Cap Cover (PR) (PL 1.2.4) securing the ESS Cap Cover (PR) to the printer.

NOTE To remove the ESS Cap Cover (PR) easily, push down on the cover of the retainer of the boss.


Figure 1 ESS Cover

## Replacement

1. Put the upper boss on the ESS Cap Cover (PR) into the hole of the printer to fix the ESS Cap Cover (PR).
2. Put the lower boss on the ESS Cap Cover (PR) into the hole of the printer.
3. Close the ESS Cap Cover (PR).

## RRP 1.12 Upper Rear Cover

## Removal

1. Remove the ESS Cover Assembly (PL 8.1.20).
2. Remove the two screws (Del Tite, M3x8mm) securing the Upper Rear Cover to the machine.
3. Remove the Upper Rear Cover by moving it in the direction of the arrow.


Figure 1 Upper Rear Cover

## Replacement

1. Install the Upper Rear Cover to the machine, and attach using two screws (Del Tite, M3x8mm).
2. Install the ESS Cover Assembly (PL 8.1.20).

## RRP 1.13 Lower Rear Cover (PR)

## Removal

1. Remove the ESS Cover Assembly (PL 8.1.20).
2. Remove the Upper Rear Cover (PL 1.2.5).
3. Remove the two screws (Del Tite, M3x8mm) securing the Lower Rear Cover (PR) to the machine.
4. Remove the Lower Rear Cover (PR) by moving it in the direction of the arrow.


Figure 1 Lower Rear Cover

## Replacement

1. Install the Lower Rear Cover (PR) to the machine using two screws (Del Tite, M3x8mm).

NOTE Be sure to attach the lower four hooks on the Lower Rear Cover (PR) to the Bracket on the printer.
2. Install the Upper Rear Cover (PL 1.2.5).
3. Install the ESS Cover Assembly (PL 8.1.20).

## RRP 1.14 MCU Cap Cover

## Removal

1. Remove the MCU Cap Cover (PL 1.2.7) from the Lower Rear Cover (PR) (PL 1.2.6) by presing down on the top edge of the MCU Cap Cover in the direction of the down arrow.


Figure 1 MCU Cap Cover

## Replacement

1. Install the MCU Cap Cover (PL 1.2.7) to the Lower Rear Cover (PR) (PL 1.2.6) by moving the MCU Cap Cover in the opposite direction of the arrow.

## RRP 2 Transportation \& Registration

## RRP 2.1 Switch Assembly PS (Tray 1)

## Removal

1. Remove the ESS Cover Assembly (PL 8.1.20).
2. Remove the Upper Rear Cover (PL 1.2.5).
3. Remove the Lower Rear Cover (PR) (PL 1.2.6).
4. Remove the three screws (Del Tite, M3x6mm) securing the AC Chassis Assembly (XC) (PL 8.1.10) to the machine
5. Remove the two screws (Del Tite, M3x6mm) securing the Switch Bracket (PL 2.1.5) to the machine.
6. Remove the Switch Assembly P S together with the Switch Bracket.
7. Disconnect the connector (P/J109) of the Size Harness Assembly (A) (PL 8.2.3) from the Switch Assembly P S.
8. Remove the screw (Del Tite, M3x6mm) securing the Switch Assembly P S (PL 2.1.4) to the Switch Bracket.
9. Remove the Switch Assembly P S.


Figure 1 Tray 1 P S Switch Assembly

## Replacement

1. Install the Switch Assembly P S (PL 2.1.4) to the Switch Bracket (PL 2.1.5) using the screw (Del Tite, M3x6mm).
2. Connect the connector (P/J109) of the Size Harness Assembly (A) (PL 8.2.3) to the Switch Assembly P S.
3. Install the Switch Assembly P S to the machine together with the Switch Bracket using the two screws (Del Tite, M3x6mm).
4. Install the AC Chassis Assembly (XC) (PL 8.1.10) to the machine using the three screws (Del Tite, M3x6mm).
5. Install the Lower Rear Cover (PR) (PL 1.2.6).
6. Install the Upper Rear Cover (PL 1.2.5).
7. Install the ESS Cover Assembly (PL 8.1.20).

## RRP 2.2 Switch Assembly P S (Tray 2)

## Removal

1. Remove the ESS Cover Assembly (PL 8.1.20).
2. Remove the Upper Rear Cover (PL 1.2.5).
3. Remove the Lower Rear Cover (PR) (PL 1.2.6).
4. Remove the three screws (Del Tite, M3x6mm) securing the AC Chassis Assembly (XC) (PL 8.1.10) to the machine.
5. Remove the two screws (Del Tite, M3x6mm) securing the Switch Bracket (PL 2.1.5) to the machine.
6. Disconnect the connector (P/J110) of the Size Harness Assembly (A) (PL 8.2.3) from the Switch Assembly P S.
7. Remove the Switch Assembly P S together with the Switch Bracket.
8. Remove the screw (Del Tite, M3x6mm) securing the Switch Assembly P S (PL 2.1.4) to the Switch Bracket.
9. Remove the Switch Assembly P S.


Figure 1 Tray 2 P S switch Assembly

## Replacement

1. Install the Switch Assembly P S (PL 2.1.4) to the Switch Bracket (PL 2.1.5) using the screw (Del Tite, M3x6mm).
2. Connect the connector (P/J110) of the Size Harness Assembly (A) (PL 8.2.3) to the Switch Assembly P S.
3. Install the Switch Assembly P S to the machine together with the Switch Bracket using the two screws (Del Tite, M3x6mm).
4. Install the AC Chassis Assembly (XC) (PL 8.1.10) to the machine using the three screws (Del Tite, M3x6mm).
5. Install the Lower Rear Cover (PR) (PL 1.2.6).
6. Install the Upper Rear Cover (PL 1.2.5).
7. Install the ESS Cover Assembly (PL 8.1.20).

## RRP 2.3 Feeder 1 Assembly

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Left Hand Cover Assembly (PL 4.2.8).
4. Remove the TA Bracket Assembly (PL 4.1.1).
5. Pull out Tray 1.


Figure 1 Tray 1
6. Remove the bosses on both ends on the Feeder Chute Assembly (PL 2.1.6), the right one first and remove the Feeder Chute Assembly.


Figure 2 Feeder Chute Assembly
7. Release the Feeder C Harness Assembly (PL 8.2.1) from the two clamps on the machine.
8. Disconnect the connector (P/J601) of the Feeder C Harness Assembly (PL 8.2.1) from the machine.
9. Remove the two screws (Del Tite, M3x8mm) securing the Feeder 1 Assembly to the machine.
10. Remove the Feeder 1 Assembly by moving it in the direction of the arrow.


Figure 3 Feeder Assembly (Feeder 1)

## Replacement

1. Insert the Feeder 1 Assembly from the left side (Rear) and attach it using the two screws (Del Tite, M3x8mm).
NOTE When installing the Feeder 1 Assembly, be sure to fit the two bosses on the machine into the holes on the Feeder 1 Assembly.
2. Connect the connector (P/J601) of the Feeder C Harness Assembly (PL 8.2.1) to the machine.
3. Secure the Feeder C Harness Assembly (PL 8.2.1) to the two clamps on the machine.
4. Fit the bosses on both ends on the Feeder Chute Assembly (PL 2.1.6) into the machine, the left one first, and install the Feeder Chute Assembly.
5. Close the Tray 1.
6. Install the TA Bracket Assembly (PL 4.1.1).
7. Install the Left Hand Cover Assembly (PL 4.2.8).
8. Install the MPF Feeder Assembly (PL 3.1.1).
9. Install the MPF RR Cover (PL 3.1.14).

## RRP 2.4 Feeder 2 Assembly

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Left Hand Cover Assembly (PL 4.2.8).
4. Open the Left Hand Lower C Cover Assembly (PL 4.1.10).
5. Remove the TA Bracket Assembly (PL 4.1.1).
6. Pull out the Tray 2.


Figure 1 Tray 2
7. Release the boss on the both ends of the Feeder Chute Assembly 2 (PL 2.1.9) securing it to the machine, the right one first, and remove the Feeder Chute Assembly 2.


Figure 2 Feeder Chute Assembly
8. Remove the two screws (Del Tite, M3x6mm) securing the TA Chute (PL 4.5.9) to the machine and remove the TA Chute while pulling its center.
9. Remove the TA Roller Assembly (PL 4.1.8).


Figure 3 TA Chute
10. Release the Feeder C Harness Assembly (PL 8.2.1) from the two clamps on the machine.
11. Disconnect the connector (P/J602) of the Feeder C Harness Assembly from the machine.
12. Remove the two screws (Del Tite, M3x8mm) securing the Feeder 2 Assembly to the machine.
13. Remove the Feeder 2 Assembly by moving it in the direction of the arrow.


Figure 4 Feeder Assembly (Feeder 2)

## Replacement

1. Insert the Feeder 2 Assembly from the left side (Rear) and attach it using two screws (Del Tite, M3x8mm).
NOTE When installing the Feeder 2 Assembly, be sure to fit the two bosses on the machine into the holes on the Feeder 2 Assembly.
2. Connect the connector (P/J602) of the Feeder C Harness Assembly (PL 8.2.1) to the machine.
3. Secure the Feeder $C$ Harness Assembly to the two clamps on the machine.
4. Install the TA Roller Assembly (PL 4.1.8) (RRP 4.3).
5. Install the TA Chute (PL 4.5.9) to the machine using the two screws (Del Tite, M $3 \times 6 \mathrm{~mm}$

NOTE When installing the TA Chute, be sure to fit the bosses on the TA Chute into the holes on the machine.
6. Fit the bosses on both ends of the Feeder Chute Assembly 2 (PL 2.1.9) into the machine, the left one first, and install the Feeder Chute Assembly 2.
7. Close the Tray 2.
8. Install the TA Bracket Assembly (PL 4.1.1).
9. Close the Left Hand Lower C Cover Assembly (PL 4.1.10).
10. Install the Left Hand Cover Assembly (PL 4.2.8).
11. Install the MPF Feeder Assembly (PL 3.1.1).
12. Install the MPF RR Cover (PL 3.1.14).

## RRP 2.5 Front Side Guide Assembly

## Removal

1. Remove the Tray Assembly (PL 2.2.1).
2. Remove E-rings on both ends (front/rear) securing the Bottom Plate (PL 2.2.10) to the Tray (PL 2.2.11).
3. Push the guide on the front in the arrow direction shown in the figure by finger to release the boss on the Tray from the Bottom Plate.
4. Remove the Bottom Plate by moving it in the direction of the arrow.


Figure 1 Removing Bottom Plate
5. Remove the two screws (Silver, M3x8mm) each securing one of the Pinion Gears (PL 2.2.15) to the Tray.
6. Remove the Pinion Gears.
7. After sliding the Front Side Guide Assembly inward, remove the Front Side Guide Assembly in the direction of the arrow.


Figure 2 Front Side Guide

## Replacement

1. Fit the bosses on the lower part of the Front Side Guide Assembly to the holes on the Tray (PL 2.2.11).
2. Slide the Front Side Guide Assembly fully outward.
3. Install the two Pinion Gears (PL 2.2.15) to the Tray using one screw (Silver, M3x8mm) each.

NOTE Before installing the Pinion Gears, make sure that the Front Side Guide Assembly and the Rear Side Guide (PL 2.2.9) are placed fully outward. After installing the Pinion Gears, make sure that the Front Side Guide Assembly and the Rear Side Guide slide smoothly.
4. Fit the rear guide hole on the Bottom Plate (PL 2.2.10) to the boss on the Tray.
5. Install the Bottom Plate to the Tray.

NOTE Be sure to fit the front guide hole on the Bottom Plate to the boss on the Tray.
6. Fix the Bottom Plate to the Tray using the two E-rings on front and rear.
7. Insert the Tray Assembly (PL 2.2.1).

## RRP 2.6 Rear Side Guide

## Removal

1. Remove the Tray Assembly (PL 2.2.1).
2. Remove E-rings on both ends (front/rear) securing the Bottom Plate (PL 2.2.10) to the Tray (PL 2.2.11).
3. Push the guide on the front in the direction of the arrow, with your finger as shown in the figure to release the boss on the Tray from the Bottom Plate.
4. Remove the Bottom Plate by moving it in the direction of the arrow.


Figure 1 Removing Bottom Plate
5. Remove the two screws (Silver, M3x8mm) each securing one of the Pinion Gears (PL 2.2.15) to the Tray.
6. Remove the Pinion Gears.
7. After sliding the Rear Side Guide inward, remove the Rear Side Guide in the direction of the arrow.

NOTE Be sure to release the bosses on the Rear Side Guide from the holes on the Side Guide Actuator (PL 2.2.12).


Figure 2 Rear Side Guide

## Replacement

1. Fit the bosses on the lower part of the Rear Side Guide to the holes on the Tray (PL 2.2.11).

NOTE Be sure to fit the bosses on the Rear Side Guide into the holes on the Side Guide Actuator (PL 2.2.12).
2. Slide the Rear Side Guide fully outward.
3. Install the two Pinion Gears (PL 2.2.15) to the Tray using one screw (Silver, M3x8mm) each.

NOTE Before installing the Pinion Gears, make sure that the Rear Side Guide and the Front Side Guide Assembly (PL 2.2.6) are placed fully outward. After installing the Pinion Gears, make sure that the Front Side Guide Assembly and the Rear Side Guide slide smoothly.
4. Fit the rear guide hole on the Bottom Plate (PL 2.2.10) to the boss on the Tray.
5. Install the Bottom Plate to the Tray.

NOTE Be sure to fit the front guide hole on the Bottom Plate to the boss on the Tray.
6. Fix the Bottom Plate to the Tray using the two E-rings on front and rear.
7. Insert the Tray Assembly (PL 2.2.1).

## RRP 2.7 End Guide

## Removal

1. Remove the Tray Assembly (PL 2.2.1).
2. Remove the Front Side Guide Assembly (PL 2.2.6).
3. Remove the Rear Side Guide (PL 2.2.9).
4. Remove the Side Guide Actuator (PL 2.2.12).
5. Remove the two hooks securing the Link(PL 2.2.19) to the Tray (PL 2.2.11).


Figure 1 End Guide
6. Release the boss on the End Guide Actuator (PL 2.2.18) from the hole on the Link by moving the Link in the direction of the arrow (A), with its center slightly lifted.
7. Release the boss on the End Guide from the hole on the Link by moving the Link in the direction of the arrow (B).
8. Sliding the End Guide inward as shown in the figure to remove.


Figure 2 End Guide Link

## Replacement

1. Fit the boss on the lower part of the End Guide to the groove on the Tray (PL 2.2.11).
2. Slide the End Guide to around the center of the groove on the Tray.
3. Put the boss on the End Guide into the hole on the Link (PL 2.2.19).
4. Put the boss on the End Guide Actuator (PL 2.2.18) into the hole on the Link by moving the Link in the direction of the arrow (A).
5. Install the Link to the Tray using the two hooks.
6. Install the Side Guide Actuator (PL 2.2.12) to the Rear Side Guide (PL 2.2.9) using the hook.
7. Install the Rear Side Guide (PL 2.2.9).
8. Install the Front Side Guide Assembly (PL 2.2.6).
9. Insert the Tray Assembly (PL 2.2.1).

## RRP 2.8 60T Sector Gear

## Removal

1. Remove the Tray Assembly (PL 2.2.1).
2. Remove the two screws (Silver, M3x8mm) securing the Bracket (PL 2.2.23) to the Tray (P2.2.11) and remove the Bracket.
3. Remove the 60T Sector Gear.


FI32015A1
Figure 1 Sector Gear

## Replacement

1. Engage the 60T Sector Gear with the Gear (13T/60T) (PL 2.2.21).
2. Fit the D-shaped on the Lift Up Shaft into the hole on the 60T Sector Gear, and install the Bracket (PL 2.2.23) to the Tray using two screws (Silver, M3x8mm).
3. Insert the Tray Assembly (PL 2.2.1).

## RRP 2.9 Tray 1\&2 Feed Lift Up Motor

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Left Hand Cover Assembly (PL 4.2.8).
4. Remove the TA Bracket Assembly (PL 4.1.1).
5. Remove the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
6. Disconnect the connector (Tray 1:P/J201, Tray 2:P/J202) of the Wire Harness (PL 2.3.16) from the Tray 1\&2 Feed Lift Up Motors.
7. Remove the two screws (M3x6mm) securing the Tray 1\&2 Feed Lift Up Motors to the Feeder Assembly (PL 2.3.1).
8. Remove the Tray $1 \& 2$ Feed Lift Up Motors.


Figure 1 Tray $\mathbf{1 / 2}$ Feed Lift Motor

## Replacement

1. Install the Tray $1 \& 2$ Feed Lift Up Motors to the Feeder Assembly (PL 2.3.1) using the two screws (M3x6mm).
2. Connect the connector (Tray 1:P/J201, Tray 2:P/J202) of the Wire Harness (PL 2.3.16) to the Tray 1\&2 Feed Lift Up Motors.
3. Install the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
4. Install the TA Bracket Assembly (PL 4.1.1).
5. Install the Left Hand Cover Assembly (PL 4.2.8).
6. Install the MPF Feeder Assembly (PL 3.1.1).
7. Install the MPF RR Cover (PL 3.1.14).

## RRP 2.10 Spacer

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Left Hand Cover Assembly (PL 4.2.8).
4. Remove the TA Bracket Assembly (PL 4.1.1).
5. Remove the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
6. Release the Wire Harness (PL 2.3.16) from the clamp on the Bracket (PL 2.3.3).
7. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 2.3.34).

## NOTE Note that the Gears attached on the Bracket may be detached.

8. Remove E-rings securing the Spacer, Gear (31T) (PL 2.3.5) and the Spring (PL 2.3.6) to the Bracket.

## NOTE Note that Spring may pop out.

9. Remove the Spacer.


FI32017A1
Figure 1 Spacer

## Replacement

1. Install the Spacer to the Bracket (PL 2.3.3) together with the Gear (31T) (PL 2.3.5) and the Spring (PL 2.3.6), and fix them using E-ring.
2. Install the Bracket to the Lower Frame (PL 2.3.34) using the three screws (Del Tite, M3x6mm).

## NOTE Make sure that the Gears attached on the Bracket are correctly installed.

3. Secure the Wire Harness (PL 2.3.16) to the clamp on the Bracket.
4. Install the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
5. Install the TA Bracket Assembly (PL 4.1.1).
6. Install the Left Hand Cover Assembly (PL 4.2.8).
7. Install the MPF Feeder Assembly (PL 3.1.1).
8. Install the MPF RR Cover (PL 3.1.14).

## RRP 2.11 Gear (31T)

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Left Hand Cover Assembly (PL 4.2.8).
4. Remove the TA Bracket Assembly (PL 4.1.1).
5. Remove the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
6. Release the Wire Harness (PL 2.3.16) from the clamp on the Bracket (PL 2.3.3).
7. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 2.3.34).

## NOTE Note that the Gears attached on the Bracket may be detached.

8. Remove E-rings securing Gear (31T), Spacer (PL 2.3.4) and Spring (PL 2.3.6) to Bracket.

## NOTE Note that Spring can pop out.

9. Remove Gear (31T)


FI32018A1
Figure 1 31T Gear

## Replacement

1. Install Gear (31T) to Bracket (PL 2.3.3), together with Spacer (PL 2.3.4) and Spring (PL 2.3.6), using E-rings.
2. Install Bracket to Lower Frame (PL 2.3.34) using three screws (Del Tite, M3x6mm).

NOTE Make sure that the Gears attached on the Bracket are properly installed.
3. Secure the Wire Harness (PL 2.3.16) to the clamp on the Bracket.
4. Install the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
5. Install the TA Bracket Assembly (PL 4.1.1).
6. Install the Left Hand Cover Assembly (PL 4.2.8).
7. Install the MPF Feeder Assembly (PL 3.1.1).
8. Install the MPF RR Cover (PL 3.1.14).

## RRP 2.12 Oneway Clutch

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Left Hand Cover Assembly (PL 4.2.8).
4. Remove the TA Bracket Assembly (PL 4.1.1).
5. Remove the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
6. Release the Wire Harness (PL 2.3.16) from the clamp on the Bracket (PL 2.3.3).
7. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 2.3.34)

NOTE Note that the Gears attached on the Bracket may be detached.
8. Remove the Oneway Clutch.


FI32019A1
Figure 1 Oneway Clutch

## Replacement

1. Install the Oneway Clutch.
2. Install the Bracket (PL 2.3.3) to the Lower Frame (PL 2.3.34) using the three screws (Del Tite, M3x6mm).
NOTE Make sure that the Gears attached on the Bracket are properly installed.
3. Secure the Wire Harness (PL 2.3.16) to the clamp on the Bracket.
4. Install the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
5. Install the TA Bracket Assembly (PL 4.1.1).
6. Install the Left Hand Cover Assembly (PL 4.2.8).
7. Install the MPF Feeder Assembly (PL 3.1.1).
8. Install the MPF RR Cover (PL 3.1.14).

## RRP 2.13 Oneway Gear

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Left Hand Cover Assembly (PL 4.2.8).
4. Remove the TA Bracket Assembly (PL 4.1.1).
5. Remove the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
6. Remove the Oneway Clutch (PL 2.3.7).
7. Remove the Oneway Gear.


FI32020A1
Figure 1 Oneway Gear

## Replacement

1. Install the Oneway Gear.
2. Install the Oneway Clutch (PL 2.3.7) (RRP 2.12).
3. Install the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
4. Install the TA Bracket Assembly (PL 4.1.1).
5. Install the Left Hand Cover Assembly (PL 4.2.8).
6. Install the MPF Feeder Assembly (PL 3.1.1).
7. Install the MPF RR Cover (PL 3.1.14).

## RRP 2.14 Gear (13T)

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Left Hand Cover Assembly (PL 4.2.8).
4. Remove the TA Bracket Assembly (PL 4.1.1).
5. Remove the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
6. Remove the Oneway Clutch (PL 2.3.7) (RRP 2.12).
7. Remove the Oneway Gear (PL 2.3.8).
8. Remove the Gear (13T).


Fl32021A1
Figure 1 13T Gear

## Replacement

1. Install the Gear (13T).
2. Install the Oneway Gear (PL 2.3.8) (RRP 2.13).
3. Install the Oneway Clutch (PL 2.3.7) (RRP 2.12).
4. Install the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
5. Install the TA Bracket Assembly (PL 4.1.1).
6. Install the Left Hand Cover Assembly (PL 4.2.8).
7. install the MPF Feeder Assembly (PL 3.1.1).
8. Install the MPF RR Cover (PL 3.1.14).

## RRP 2.15 Actuator

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Left Hand Cover Assembly (PL 4.2.8).
4. Remove the TA Bracket Assembly (PL 4.1.1).
5. Remove the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
6. Remove the two bosses on the Actuator securing the Actuator to the Feeder Assembly (PL 2.3.1).
7. Remove the Actuator.


Figure 1 Actuator

## Replacement

1. Install Actuator.

NOTE Fit the bosses on the Actuator into the holes on the Feeder Assembly (PL 2.3.1).
2. Install the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
3. Install the TA Bracket Assembly (PL 4.1.1).
4. Install the Left Hand Cover Assembly (PL 4.2.8).
5. Install the MPF Feeder Assembly (PL 3.1.1).
6. Install the MPF RR Cover (PL 3.1.14).

## RRP 2.16 No Paper Sensor

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Left Hand Cover Assembly (PL 4.2.8).
4. Remove the TA Bracket Assembly (PL 4.1.1).
5. Remove the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
6. Disconnect the connector (Tray 1:P/J101, Tray 2:P/J103) of the Wire Harness from the No Paper Sensor.
7. Release the hooks securing the No Paper Sensor to the Feeder Assembly (PL 2.3.1) as shown in the figure.
8. Remove the No Paper Sensor.


Figure 1 No Paper Sensor

## Replacement

1. Secure the No Paper Sensor to the Feeder Assembly (PL 2.3.1) using the hooks.
2. Connect the connector (Tray 1:P/J101, Tray 2:P/J103) of the Wire Harness to No Paper Sensor.
3. Install the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
4. Install the TA Bracket Assembly (PL 4.1.1).
5. Install the Left Hand Cover Assembly (PL 4.2.8).
6. Install the MPF Feeder Assembly (PL 3.1.1).
7. Install the MPF RR Cover (PL 3.1.14).

## RRP 2.17 Level Sensor

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Left Hand Cover Assembly (PL 4.2.8).
4. Remove the TA Bracket Assembly (PL 4.1.1).
5. Remove the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
6. Remove the Actuator (PL 2.3.13).
7. Disconnect the connector (Tray 1:P/J100, Tray 2:P/J102) of the Wire Harness from the Level Sensor.
8. Release the hooks securing the Level Sensor to the Feeder Assembly (PL 2.3.1) as shown in the figure.
9. Remove the Level Sensor.


Figure 1 Level Sensor

## Replacement

1. Secure the Level Sensor to the Feeder Assembly (PL 2.3.1) using the hooks.
2. Connect the connector (Tray 1:P/J100, Tray 2:P/J102) of the Wire Harness to the Level Sensor.
3. Install the Actuator (PL 2.3.13).
4. Install the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
5. Install the TA Bracket Assembly (PL 4.1.1).
6. Install the Left Hand Cover Assembly (PL 4.2.8).
7. Install the MPF Feeder Assembly (PL 3.1.1).
8. Install the MPF RR Cover (PL 3.1.14).

## RRP 2.18 Pre-Feed Sensor

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Left Hand Cover Assembly (PL 4.2.8).
4. Remove the TA Bracket Assembly (PL 4.1.1).
5. Remove the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
6. Remove the Pre-Feed Sensor from the Front Chute(PL 2.3.12) as shown.
7. Disconnect the connector (Tray 1:P/J133, Tray 2:P/J134) of the Wire Harness from the PreFeed Sensor.


Figure 1 Pre Feed Sensor

## Replacement

1. Connect the connector (Tray 1:P/J133, Tray 2:P/J134) of the Wire Harness to the Pre-Feed Sensor.
2. Install the Pre-Feed Sensor to the Front Chute (PL 2.3.12).
3. Install the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
4. Install the TA Bracket Assembly (PL 4.1.1).
5. Install the Left Hand Cover Assembly (PL 4.2.8).
6. Install the MPF Feeder Assembly (PL 3.1.1).
7. Install the MPF RR Cover (PL 3.1.14).

## RRP 2.19 Gear (28T/21T)

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Left Hand Cover Assembly (PL 4.2.8).
4. Remove the TA Bracket Assembly (PL 4.1.1).
5. Remove the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
6. Release the Wire Harness (PL 2.3.16) from the clamp on the Bracket (PL 2.3.3).
7. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 2.3.34).

NOTE Note that the Gears attached on the Bracket may be detached.
8. Remove the Gear (28T/21T).


Figure 1 Gear Removal

## Replacement

1. Install the Gear (28T/21T).
2. Install the Bracket (PL 2.3.3) to the Lower Frame (PL 2.3.34) using the three screws (Del Tite, M3x6mm).

NOTE Make sure that the Gears attached on the Bracket are properly installed.
3. Secure the Wire Harness (PL 2.3.16) connector to the clamp on the Bracket.
4. Install the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
5. Install the TA Bracket Assembly (PL 4.1.1).
6. Install the Left Hand Cover Assembly (PL 4.2.8).
7. Install the MPF Feeder Assembly (PL 3.1.1).
8. Install the MPF RR Cover (PL 3.1.14).

## RRP 2.20 Gear (29T)

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Left Hand Cover Assembly (PL 4.2.8).
4. Remove the TA Bracket Assembly (PL 4.1.1).
5. Remove the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
6. Release the Wire Harness (PL 2.3.16) from the clamp on the Bracket (PL 2.3.3).
7. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 2.3.34).

## NOTE Note that the Gears attached on the Bracket may be detached.

8. Remove the Gear (29T).


Figure 1 29T Gear

1. Install the Gear (29T).
2. Install the Bracket (PL 2.3.3) to the Lower Frame (PL 2.3.34) using three screws (Del Tite, M3x6mm).

NOTE Make sure that the Gears attached on the Bracket are properly installed.
3. Secure the Wire Harness (PL 2.3.16) to the clamp on the Bracket.
4. Install the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
5. Install the TA Bracket Assembly (PL 4.1.1).
6. Install the Left Hand Cover Assembly (PL 4.2.8).
7. Install the MPF Feeder Assembly (PL 3.1.1).
8. Install the MPF RR Cover (PL 3.1.14).

## RRP 2.21 Feed Roller Assembly

## Removal

1. Pull out the Tray 1 or Tray 2.
2. Move the Front Chute (PL 2.3.12) in the direction of the arrow.
3. Release the hook securing the Feed Roller Assembly to the Shaft (PL 2.3.23) as shown in the figure.
4. Remove the Feed Roller Assembly.

NOTE Note that the Oneway Clutch (PL 2.3.21) and the Oneway Gear (22T) (PL 2.3.22) may be detached.

NOTE When removing, do not hold the rubber roller of the Feed Roller Assembly.


Figure 1 Feed Roller Assembly

## Replacement

1. Install the Feed Roller Assembly to the Shaft (PL 2.3.23), and fix it using hook.

NOTE When installing, do not hold the rubber roller of the Feed Roller Assembly.
2. Move the Front Chute (PL 2.3.12) in the opposite direction of the arrow (to the rear side).
3. Close the Tray 1 or Tray 2.

## RRP 2.22 Oneway Clutch

## Removal

1. Pull out the Tray 1 or Tray 2.
2. Remove the Feed Roller Assembly (PL 2.3.20).
3. Remove the Oneway Clutch.

NOTE Note that Oneway Gear (22T) (PL 2.3.22) may be detached.


Figure 1 Oneway Clutch

## Replacement

1. install the Oneway Clutch.
2. Install the Feed Roller Assembly (PL 2.3.20) (RRP 2.21).
3. Close the Tray 1 or Tray 2.

## RRP 2.23 Oneway Gear (22T)

1. Pull out the Tray 1 or Tray 2.
2. Remove the Feed Roller Assembly (PL 2.3.20) (RRP 2.21).
3. Remove the Oneway Clutch (PL 2.3.21).
4. Remove the Oneway Gear (22T).


Figure 1 Oneway Gear

## Replacement

1. Install the Oneway Gear (22T).
2. Install the Oneway Clutch (PL 2.3.21) (RRP 2.22).
3. Install the Feed Roller Assembly (PL 2.3.20) (RRP 2.21).
4. Close the Tray 1 or Tray 2.

## RRP 2.24 Friction Clutch

## Removal

1. Pull out the Tray 1 or Tray 2.
2. Remove the Retard Roller Assembly (PL 2.3.20).
3. Remove the Spacer (PL 2.3.29).
4. Remove the Friction Clutch.


Figure 1 Friction Clutch

## Replacement

1. Install the Friction Clutch.
2. Install the Spacer (PL 2.3.29) (RRP 2.26).
3. Install the Retard Roller Assembly (PL 2.3.20) (RRP 2.25).
4. Close the Tray 1 or Tray 2.

## RRP 2.25 Retard Roller Assembly

## Removal

1. Pull out the Tray 1 or Tray 2.
2. Move the Front Chute (PL 2.3.12) in the direction of the arrow.
3. Release the hook securing the Retard Roller Assembly to the Retard Shaft (PL 2.3.27) as shown in the figure.
4. Remove the Retard Roller Assembly.

NOTE Note that the Spacer (PL 2.3.29) and the Friction Clutch (PL 2.3.26) may be detached.
NOTE When removing, do not hold the rubber roller of the Retard Roller Assembly.


Figure 1 Retard Roller Assembly

## Replacement

1. Install the Retard Roller Assembly to the Retard Shaft (PL 2.3.27), and fix it using the hook.

NOTE When installing, do not hold the rubber roller of the Retard Roller Assembly.
2. Move the Front Chute(PL 2.3.12) in the opposite direction of the arrow (to the rear side).
3. Close the Tray 1 or Tray 2.

## RRP 2.26 Spacer

## Removal

1. Pull out the Tray 1 or Tray 2.
2. Remove the Retard Roller Assembly (PL 2.3.20).
3. Remove the Spacer.

NOTE Note that the Friction Clutch (PL 2.3.26) may be detached.


Figure 1 Spacer

## Replacement

1. Install the Spacer.
2. Install the Retard Roller Assembly (PL 2.3.20).
3. Close the Tray 1 or Tray 2.

## RRP 2.27 Gear (33T)

## Removal

1. Pull out the Tray 1 or Tray 2.
2. Remove the Nudger Roller Assembly (PL 2.3.20).
3. Remove the Gear (25T) (PL 2.3.33).
4. Remove the Gear (33T).


Figure 1 33T Gear

## Replacement

1. Install the Gear (33T).
2. Install the Gear (25T) (PL 2.3.33) (RRP 2.29).
3. Install the Nudger Roller Assembly (PL 2.3.20) (RRP 2.28).
4. Close the Tray 1 or Tray 2.

## RRP 2.28 Nudger Roller Assembly

## Removal

1. Pull out the Tray 1 or Tray 2
2. Move the Front Chute (PL 2.3.12) in the direction of the arrow.
3. Release the hook securing the Nudger Roller Assembly to the Nudger Shaft (PL 2.3.31) as shown in the figure.
4. Remove the Nudger Roller Assembly.

NOTE Note that the Gear (25T) (PL 2.3.33) may be detached.
NOTE When removing, do not hold the rubber roller of the Nudger Roller Assembly.


Figure 1 Nudger Roller Assembly

## Replacement

1. Install the Nudger Roller Assembly to the Nudger Shaft (PL 2.3.31), and fix it using the hook.

NOTE When installing, do not hold the rubber roller of the Nudger Roller Assembly.
2. Move the Front Chute (PL 2.3.12) in the opposite direction of the arrow (to the rear side).
3. Close the Tray 1 or Tray 2.

## RRP 2.29 Gear (25T)

## Removal

1. Pull out the Tray 1 or Tray 2.
2. Remove the Nudger Roller Assembly (PL 2.3.20).
3. Remove the Gear (25T).


Figure 1 25T Gear

## Replacement

1. Install the Gear (25T).
2. Install the Nudger Roller Assembly (PL 2.3.20) (RRP 2.28).
3. Close the Tray 1 or Tray 2.

## RRP 2.30 Gear (27T)

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Left Hand Cover Assembly (PL 4.2.8).
4. Remove the TA Bracket Assembly (PL 4.1.1).
5. Remove the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
6. Release the Wire Harness (PL 2.3.16) from the clamp on the Bracket (PL 2.3.3).
7. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 2.3.34).

NOTE Note that the Gears attached on the Bracket may be detached.
8. Release the hook securing the Gear (27T) to the Shaft (PL 2.3.23) as shown in the figure.
9. Remove the Gear (27T).


Figure 1 27T Gear

## Replacement

1. Install the Gear (27T) to the Shaft (PL 2.3.23) using the hook.
2. Install Bracket (PL 2.3.3) to Lower Frame (PL 2.3.34) using three screws (Del Tite, M3x6mm).

## NOTE Make sure that the Gears attached on the Bracket are properly installed.

3. Secure the Wire Harness (PL 2.3.16) to the clamp on the Bracket.
4. Install the Feeder 1 or Feeder 2 Assembly (PL 2.3.1).
5. Install the TA Bracket Assembly (PL 4.1.1).
6. Install the Left Hand Cover Assembly (PL 4.2.8).
7. Install the MPF Feeder Assembly (PL 3.1.1).
8. Install the MPF RR Cover (PL 3.1.14).

## RRP 3 MPF

## RRP 3.1 MPF Feeder Assembly

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Disconnect the connector (P/J605) of the MPF Harness Assembly A (PL 8.2.2) from the machine.
3. Release MPF Harness Assembly A from the clamp.
4. Remove the two screws (Del Tite, M3x8mm) securing the MPF Feeder Assembly to the machine.
5. Remove the MPF Feeder Assembly.


Figure 1 MPF Feeder Assembly

## Replacement

1. Install the MPF Feeder Assembly to the machine using two screws (Del Tite, M3x8mm).

NOTE Place the MPF Harness Assembly A (PL 8.2.2) along the slot on the left on the MPF Feeder Assembly so that it does not pinch the harness between the feeder and the machine.
2. Connect the connector ( $\mathrm{P} / \mathrm{J} 605$ ) of the MPF Harness Assembly $A$ to the machine.
3. Secure the MPF Harness Assembly A to the clamp.
4. Install the MPF RR Cover (PL 3.1.14).

## RRP 3.2 Actuator

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the two hooks securing the Upper Frame (PL 3.1.2) to the machine.
4. Remove the Upper Frame by moving it in the direction of the arrow.
5. Pull the right side of the Actuator toward you first, and pull out it from the hole on the Upper Frame.
6. Remove the Actuator.


Figure 1 Actuator

## Replacement

1. Install the Actuator in the opposite direction shown in the figure to the Upper Frame (PL 3.1.2)
2. Install the Upper Frame by moving it in the opposite direction of the arrow.
3. Fix the Upper Frame to the machine using the two hooks.
4. Install the MPF Feeder Assembly (PL 3.1.1).
5. Install the MPF RR Cover (PL 3.1.14).

## RRP 3.3 Photo In Sensor

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Release the two hook securing the Upper Frame (PL 3.1.2) to the MPF Feeder Assembly, and move the Upper Frame in the direction of the arrow to remove.
4. Disconnect the connector (P/J108) of the MPF Harness Assembly (PL 3.1.5) from the Photo In Sensor.
5. Release the hooks securing the Photo In Sensor to the Upper Frame.
6. Remove the Photo In Sensor.


Figure 1 Photo In Sensor

## Replacement

1. Secure the Photo In Sensor to the Upper Frame (PL 3.1.2) using the hooks.
2. Connect the connector (P/J108) of the MPF Harness Assembly (PL 3.1.5) to the Photo In Sensor.
3. Install the Upper Frame using the two hooks by moving it in the opposite direction of the arrow.
4. Install the MPF Feeder Assembly (PL 3.1.1).
5. Install the MPF RR Cover (PL 3.1.14).

## RRP 3.4 Pinch Roll Assembly

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the two screws (Silver, M3x8mm) securing the Pinch Chute (PL 3.1.8) to the MPF Lower Frame (P3.2.2) to remove the Pinch Chute.
4. Remove the screw (Silver, M3x8mm) securing the Pinch Roll Assembly to the Pinch Chute.
5. Release the bosses securing the Pinch Roll Assembly to the Pinch Chute.
6. Remove the Pinch Roll Assembly by moving it in the direction of the arrow.


Figure 1 Pinch Roll Assembly

## Replacement

1. Install the Pinch Roll Assembly by moving it in the opposite direction of the arrow.

NOTE Fit the bosses on the Pinch Roll Assembly in the holes on the Pinch Chute (PL 3.1.8).
2. Install the Pinch Roll Assembly to the Pinch Chute using the screw (Silver, M3x8mm).
3. Install the Pinch Chute to the MPF Lower Frame (PL 3.2.2) using the two screws (Silver, $\mathrm{M} 3 \times 8 \mathrm{~mm}$ ).
4. Install the MPF Feeder Assembly (PL 3.1.1).
5. Install the MPF RR Cover (PL 3.1.14).

## RRP 3.5 MPF RR Cover

## Removal

1. Remove the screw (Del Tite, M3x8mm) securing the MPF RR Cover to the machine.
2. Remove the MPF Cap Cover, RR.


Figure 1 MPF Cover

## Replacement

1. Secure the MPF RR Cover to the machine using the screw (Del Tite, M3x8mm).

## RRP 3.6 Collar

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Gear 18T (PL 3.2.7).
4. Remove the Collar from the Drive Roll Assembly (PL 3.2.14).


Figure 1 Collar

1. Install the Collar to the Drive Roll Assembly (PL 3.2.14).
2. Install the Gear 18T (PL 3.2.7) (RRP 3.8).
3. Install the MPF Feeder Assembly (PL 3.1.1).
4. Install the MPF RR Cover (PL 3.1.14).

## RRP 3.7 Pick Up Gear

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the MPF Spring (PL 3.1.6) from the Gear Bracket Assembly (PL 3.1.7).

NOTE Leave another hook of the MPF Spring hooked on the Pick Up Gear.
4. Remove the three screws (Silver, M3x8mm) securing the Gear Bracket Assembly to the MPF Feeder Assembly to remove the Gear Bracket Assembly.
5. Release the hooks securing the Pick Up Gear to the Pick Up Shaft Assembly (PL 3.2.16) (RRP 3.12).
6. Remove the Pick Up Gear.


Figure 1 Pick Up Gear

## Replacement

1. Install the Pick Up Gear to the Cam Gear (PL 3.2.22) using the CAM Spring Gear (PL 3.2.26).

NOTE Insert Pick Up Gear until the hooks on Stopper Lever (PL 3.2.3) securing Pick Up Gear are locked firmly.
2. Install the Gear Bracket Assembly (PL 3.1.7) to the MPF Feeder Assembly using the three screws (Silver, M3x8mm).
3. Secure the MPF Spring to the Gear Bracket Assembly.
4. Install the MPF Feeder Assembly (PL 3.1.1).
5. Install the MPF RR Cover (PL 3.1.14).

## RRP 3.8 Gear 18T

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove E-rings securing the Drive Roll Assembly (PL 3.2.14) to the MPF Lower Frame (PL 3.2.2).
4. Remove the Gear 18T.


Figure 1 18T Gear

## Replacement

1. Install the Gear 18T.
2. Install the Drive Roll Assembly (PL 3.2.14) to the MPF Lower Frame (PL 3.2.2) using the Erings.
3. Install the MPF Feeder Assembly (PL 3.1.1).
4. Install the MPF RR Cover (PL 3.1.14).

## RRP 3.9 Retard Pad Assembly

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Feed Roller Assembly (PL 3.2.20).
4. Remove the Pick Up Shaft Assembly (PL 3.2.16).
5. Remove two Spring PADs (PL 3.2.24) under the Retard Pad Assembly (PL 3.2.12).
6. Remove the Retard Pad Assembly and the Retard Shaft (PL 3.2.5) by moving it in the direction of the arrow, from the backside.
7. Remove the Retard Shaft from the Retard Pad Assembly.


Figure 1 Retard Pad Assembly

## Replacement

1. Move the Retard Pad Assembly and the Retard Shaft (PL 3.2.5) in the direction of the arrow and install them
2. Install two the Spring PADs (PL 3.2.24) between the Retard Pad Assembly and the MPF Lower Frame (PL 3.2.2).
3. Install the Pick Up Shaft Assembly (PL 3.2.16).
4. Install the Feed Roller Assembly (PL 3.2.20).
5. Install the MPF Feeder Assembly (PL 3.1.1).
6. Install the MPF RR Cover (PL 3.1.14).

## RRP 3.10 Drive Roll Assembly

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the two screws (Silver, M3x8mm) securing the Pinch Chute (PL 3.1.8) to the MPF Lower Frame (PL 3.2.2).
4. Remove Gear 18T (PL 3.2.7).
5. Remove the Collar (PL 3.2.4).
6. Remove the two Bearing Sleeves (PL 3.2.21) left and right, securing the Drive Roll Assembly to the MPF Lower Frame.
7. Remove the Drive Roll Assembly.

## NOTE When removing, do not hold the rubber rollers of the Drive Roll Assembly.



Figure 1 Drive Roll Assembly

## Replacement

1. Install the Drive Roll Assembly to the MPF Lower Frame (PL 3.2.2).

## NOTE When installing, do not hold the rubber rollers of the Drive Roll Assembly.

2. Install the Drive Roll Assembly to the MPF Lower Frame using the two Bearing Sleeves (PL 3.2.21) left and right.
3. Install the Collar (PL 3.2.4).
4. Install the Gear 18T (PL 3.2.7).
5. Install the Pinch Chute (PL 3.1.8) to MPF Lower Frame using the two screws (Silver, M3x8mm).
6. Install the MPF Feeder Assembly (PL 3.1.1).
7. Install the MPF RR Cover (PL 3.1.14).

## RRP 3.11 Pick Up Solenoid

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Pick Up Gear (PL 3.2.6).
4. Remove the Cam Gear (PL 3.2.22).
5. Remove the three screws (Silver, M3x8mm) securing the Gear Bracket Assembly (PL 3.1.7) to the MPF Lower Frame (PL 3.2.2).
6. Remove the screw (Del Tite, M3x6mm) securing the Pick Up Solenoid to the Gear Bracket Assembly.
7. Disconnect the connector (P/J205) of the MPF Harness Assembly (PL 3.1.5) from the Pick Up Solenoid.
8. Remove the Pick Up Solenoid.

## NOTE When removing, lower the LEVER-Gear (PL 3.2.8) as shown in the figure.



Figure 1 Pickup Solenoid

## Replacement

1. Install the Pick Up Solenoid to the Gear Bracket Assembly (PL 3.1.7) using the screw (Del Tite, M3x6mm).
NOTE When installing, lower the LEVER-Gear (PL 3.2.8) as shown in the figure.
2. Connect the connector (P/J205) of the MPF Harness Assembly (PL 3.1.5) to the Pick Up Solenoid.
3. Install the Gear Bracket Assembly to the MPF Lower Frame (PL 3.2.2) using the three screws (Silver, M3x8mm).

## NOTE Be careful not to pinch the harness.

4. Install the Cam Gear (PL 3.2.22).
5. Install the Pick Up Gear (PL 3.2.6).
6. Install the MPF Feeder Assembly (PL 3.1.1).
7. Install the MPF RR Cover (PL 3.1.14).

## RRP 3.12 Pick Up Shaft Assembly

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Feed Roller Assembly (PL 3.2.20).
4. Remove the Pick Up Gear (PL 3.2.6).
5. Remove the Cam Gear (PL 3.2.22).
6. Remove the Stopper Lever (PL 3.2.3).
7. Remove the three screws (Silver, M3x8mm) securing the Gear Bracket Assembly (PL 3.1.7) to the MPF Lower Frame (P3.2.2) to remove the Gear Bracket Assembly.
8. Remove E-rings left and right, which secures the Pick Up Shaft Assembly to the MPF Lower Frame.
9. Slide the two Bearing 8s (PL 3.2.9) left and right inward, and slide the Front Pick Up Cam (PL 3.2.18) and the Pick Up Cam 2 (PL 3.2.17) inward too.
10. Remove the Pick Up Shaft Assembly from the MPF Lower Frame, together with the two Bearing 8s, Front Pick Up Cam and Pick Up Cam 2.


Figure 1 Pickup Shaft Assembly

## Replacement

1. Install the Pick Up Shaft Assembly to the MPF Lower Frame (PL 3.2.2) together with the two Bearing 8s (PL 3.2.9), Front Pick Up Cam (PL 3.2.18) and Pick Up Cam 2 (PL 3.2.17).
2. Install the Pick Up Shaft Assembly to the MPF Lower Frame (PL 3.2.2) using the two E-rings left and right.
3. Install the Gear Bracket Assembly (PL 3.1.7) to the MPF Lower Frame using the three screws (Silver, M3×8mm).

## NOTE Be careful not to pinch the harness.

4. Install the Stopper lever (PL 3.2.3).
5. Install the Cam Gear (PL 3.2.22).
6. Install the Pick Up Gear (PL 3.2.6).
7. Install the Feed Roller Assembly (PL 3.2.20) (RRP 3.13).
8. Install the MPF Feeder Assembly (PL 3.1.1).
9. Install the MPF RR Cover (PL 3.1.14).

## RRP 3.13 Feed Roller Assembly

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the two screws (Silver, M3x8mm) securing the Pinch Chute (PL 3.1.8) to the MPF Lower Frame (P3.2.2) to remove the Pinch Chute.
4. While releasing the two hooks of the Core Roll (PL 3.2.19) left and right securing the Feed Roller Assembly to the Pick Up Shaft Assembly (PL 3.2.16) as shown in the figure, and slide the Feed Roller Assembly outward.
5. Remove the Feed Roller Assembly from the Pick Up Shaft Assembly by moving it in the direction of the arrow (to the front).
NOTE When removing, do not hold the rubber roller of the Feed Roller Assembly.


Figure 1 Feed Roll Assembly

## Replacement

1. Move the Feed Roller Assembly from the Pick Up Shaft Assembly (PL 3.2.16) in the opposite direction of the arrow to instal.

NOTE When installing, do not hold the rubber roller of the Feed Roller Assembly.
2. Slide the two Core Rolls (PL 3.2.19) left and right until their hooks are properly secured.
3. Install the Pinch Chute (PL 3.1.8) to the MPF Lower Frame (PL 3.2.2) using the two screws (Silver, M3x8mm).
4. Install the MPF Feeder Assembly (PL 3.1.1).
5. Install the MPF RR Cover (PL 3.1.14).

## RRP 3.14 Cam Gear

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the MPF Spring (PL 3.1.6) from the Gear Bracket Assembly (PL 3.1.7).

## NOTE Leave one end of the MPF Spring hooked on the Gear.

4. Remove the three screws (Silver, M3x8mm) securing the Gear Bracket Assembly (PL 3.1.7) to the MPF Lower Frame to remove the Gear Bracket Assembly.
5. While releasing the hooks securing the Pick Up Gear to the Pick Up Shaft Assembly (PL 3.2.16), remove the Pick Up Gear together with the MPF Spring and the Cam Gear.
6. Remove the Cam Gear Spring (PL 3.2.26) securing the Cam Gear to the Pick Up Gear.
7. Remove the Cam Gear.

NOTE When removing, lower the Lever-Gear (PL 3.2.8) as shown un the figure.


Figure 1 Cam Gear

## Replacement

1. Install the Cam Gear to the Pick Up Gear (PL 3.2.6) using the Cam Gear Spring (PL 3.2.26).

NOTE When installing, lower the LEVER-Gear (PL 3.2.8) as shown in the figure.
2. Install the Pick Up Gear together with the MPF Spring (PL 3.1.6) to the Pick Up Shaft Assembly (PL 3.2.16) (RRP 3.12).
NOTE Insert Pick Up Gear until the hooks on Stopper Lever (PL 3.2.3) securing Pick Up Gear are locked firmly.
3. Install the Gear Bracket Assembly to the MPF Lower Frame using the three screws (Silver, $\mathrm{M} 3 \times 8 \mathrm{~mm}$ ).
4. Secure the MPF Spring to the Gear Bracket Assembly.
5. Install the MPF Feeder Assembly (PL 3.1.1).
6. Install the MPF RR Cover (PL 3.1.14).

## RRP 3.15 Pinion Gear

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Spread the ribs on both ends of Exit Tray (PL 3.3.9) securing the Exit Tray to the MPF Tray (PL 3.3.8) and move the MPF Tray in the direction of the arrow to remove.
4. Remove the four screws (Silver, M3x6mm) securing the Tray Cover (PL 3.3.11) to the MPF Tray.
5. Disconnect the Terminal from the Tray Cover, and remove the Tray Cover.
6. Remove the Pinion Gears.


Figure 1 Pinion Gear

## Replacement

1. Install the Pinion Gears.

NOTE Be sure to move the Front Side Guide (PL 3.3.6) and the Rear Side Guide (PL 3.3.7) toward the most inward before install the Pinion Gears. Also, check that Front Side Guide and Rear Side Guide are moved smoothly.
2. Connect the Terminal to the Tray Cover (PL 3.3.11).
3. Install the Tray Cover.

## NOTE Fit the shafts of the Pinion Gear into the holes in the center of the Tray Cover.

4. Install the Tray Cover to the MPF Tray (PL 3.3.8) using the three screws (Silver, M3x6mm).
5. While spreading the both ends of Exit Tray (PL 3.3.9) outward, move the MPF Tray in the opposite direction of the arrow to install.
6. Install the MPF Feeder Assembly (PL 3.1.1).
7. Install the MPF RR Cover (PL 3.1.14).

## RRP 3.16 Front Side Guide

## Removal

1. Remove the MPF RR Cover (PL 3.1.14).
2. Remove the MPF Feeder Assembly (PL 3.1.1).
3. Remove the Pinion Gear (PL 3.3.2).
4. Remove the MPF Sensor Assembly (PL 3.3.10).
5. Release the hook securing the Front Side Guide to the Front Rack (PL 3.3.3).
6. Remove the Front Side Guide.


Figure 1 Front Side Guide

## Replacement

1. Secure the Front Side Guide to the Front Rack (PL3.3.3) using the hook.
2. Install the MSI Sensor Assembly (PL3.3.10).
3. Install the Pinion Gear (PL3.3.2) .
4. Install the MSI Feeder Assembly (PL3.1.1).
5. Install the MSI Cover, RR (PL3.1.14) .

NOTE After the installation, be sure to perform Side Guide Adjust.

## RRP 3.17 Rear Side Guide

## Removal

1. Remove the MSI Cover, RR (PL 3.1.14) .
2. Remove the MSI Feeder Assembly (PL 3.1.1) .
3. Remove the Pinion Gear (PL 3.3.2) .
4. Remove the MSI Sensor Assembly (PL 3.3.10).
5. Release the hook securing the Rear Side Guide to the Rear Rack (PL 3.3.4) .
6. Remove the Rear Side Guide.


Figure 1 Rear Side Guide

## Replacement

1. Install the Rear Side Guide to the Rear Rack (PL 3.3.4) using the hook.
2. Install the MSI Sensor Assembly (PL 3.3.10).
3. Install the Pinion Gear (PL 3.3.2) .
4. Install the MSI Feeder Assembly (PL 3.1.1) .
5. Install the MSI Cover, RR (PL 3.1.14) .

NOTE After the installation, be sure to perform Side Guide Adjust.

## RRP 3.18 MSI Sensor Assembly

## Removal

1. Remove the MSI Cover, RR (PL 3.1.14) .
2. Remove the MSI Feeder Assembly (PL 3.1.1) .
3. Remove the Pinion Gear (PL 3.3.2) .
4. Disconnect the connector (P/J107) of the Size Harness Assembly (PL 3.3.13) from the MSI Sensor Assembly .
5. Remove the five screws (Silver, M3x6mm) securing the MSI Sensor Assembly to the MSI Tray (PL 3.3.8).
6. Remove the MSI Sensor Assembly.


Figure 1 MSI Sensor Assembly

## Replacement

1. Install the MSI Sensor Assembly to the MSI Tray (PL 3.3.8) using five screws (Silver, M3x6mm).
2. Connect the connector (P/J107) of the Size Harness Assembly (PL 3.3.13) to MSI Sensor Assembly.
3. Install the Pinion Gear (PL 3.3.2) .
4. Install the MSI Feeder Assembly (PL 3.1.1) .
5. Install the MSI Cover, RR (PL 3.1.14).

## RRP 4 Transportation \& Registration

## RRP 4.1 TA Bracket Assembly

## Removal

1. Remove the MSI Cover, RR (PL 3.1.14).
2. Remove the MSI Feeder Assembly (PL 3.1.1) .
3. Remove the Left Hand Cover Assembly (PL4.2.8) .
4. Open the Lower Left Hand Cover Assembly C (PL4.1.10).
5. Remove the three screws (DEL TITE, M3x8mm) securing the TA Bracket Assembly to the printer .
6. Release the Exit Harness Assembly C (PL8.2.6) from the clamp on the TA Bracket Assembly.
7. Remove the TA Bracket Assembly.


FI34001A1
Figure 1 TA Bracket Assembly

## Replacement

1. Clamp the Exit Harness Assembly C (PL8.2.6) with the clamp on the TA Bracket Assembly.
2. Install the TA Bracket Assembly to the printer using the three screws (DEL TITE, M3x8mm).
3. Close the Lower Left Hand Cover Assembly C (PL4.1.10).
4. Install the Left Hand Cover Assembly (PL4.2.8) .
5. Install the MSI Feeder Assembly (PL 3.1.1) .
6. Install the MSI Cover, RR (PL 3.1.14) .

## RRP 4.2 CAB Switch I/L

## Removal

1. Remove the MSI Cover, RR (PL 3.1.14) .
2. Removethe MSI Feeder Assembly (PL 3.1.1) .
3. Remove the Left Hand Cover Assembly (PL 4.2.8) .
4. Remove the TA Bracket Assembly (PL 4.1.1) .
5. Disconnect the connector (P/J106) of the PH Harness Assembly C (PL 8.2.7) from the Cab Switch I/L .
6. Release the hooks securing the Cab Switch I/L to the TA Bracket Assembly.
7. Remove the Cab Switch I/L.


Figure 1 Cab Switch

## Replacement

1. Secure the Cab Switch I/L to the TA Bracket Assembly using the hooks.
2. Connect the connector (P/J106) of the PH Harness Assembly C (PL 8.2.7) to the Cab Switch I/L.
3. Install the TA Bracket Assembly (PL 4.1.1) .
4. Install the Left Hand Cover Assembly (PL 4.2.8) .
5. Install the MSI Feeder Assembly (PL 3.1.1) .
6. Install the MSI Cover, RR (PL 3.1.14).

## RRP 4.3 TA Roller Assembly

## Removal

1. Remove the MSI Cover, RR (PL 3.1.14) .
2. Remove the MSI Feeder Assembly (PL 3.1.1) .
3. Remove the Left Hand Cover Assembly (PL 4.2.8) .
4. Open the Lower Left Hand Cover Assembly C (PL 4.1.10).
5. Remove the two screws (DEL TITE, M3x6mm) securing the TA Chute (PL 4.5.9) to the machine and remove the TA Chute while pulling its center .
6. Remove the E-ring on the right side (front), securing the TA Roller Assembly to the machine.
7. Remove the TA Roller Assembly by moving it in the direction of the arrow.

NOTE Note that TA Bearing (PL 4.1.6), BEARING SLEEVE (PL 4.1.9) and 18T GEAR (PL 4.1.7) are detached.


Figure 1 TA Roller Assembly

## Replacement

1. Insert the TA Roller Assembly into the hole on the machine together with the TA Bearing (PL 4.1.6), Bearing Sleeve (PL 4.1.9) and 18T GEAR (PL 4.1.7).

NOTE When installing, do not hold the rubber rollers of the TA Roller Assembly.
2. Install the TA Roller Assembly using the E-ring.
3. Install the TA Chute (PL 4.5.9) to the machine using the two screws (DEL TITE, M3x6mm).

NOTE When installing the TA Chute, be sure to fit the hooks on TA Chute into the holes on the machine.
4. Close the Lower Left Hand Cover Assembly C (PL 4.1.10).
5. Install the Left Hand Cover Assembly (PL 4.2.8) .
6. Install the MSI Feeder Assembly (PL 3.1.1) .
7. Install the MSI Cover, RR (PL 3.1.14).

## RRP 4.4 Lower Left Hand Cover Assembly C

1. Open Lower Left Hand Cover Assembly C.
2. Remove the two screws (DEL TITE SEMS, M3x6mm) securing the Lower Chute (PL 4.1.5) to the machine
3. Remove the Lower Left Hand Cover Assembly C together with the Lower Chute.


Figure 1 Lower Cover Assembly

## Replacement

1. Install the Lower Left Hand Cover Assembly C together with the Lower Chute (PL 4.1.5) using the two screws (DEL TITE SEMS, M3x6mm).
2. Close the Lower Left Hand Cover Assembly C.

## RRP 4.5 Lower Left Hand Bracket Assembly C

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8) .
2. Remove the Lower Left Hand Cover Assembly C (PL 4.1.10) .
3. Lift the Lower Left Hand Chute C(PL 4.1.11) inside the Lower Left Hand Cover C, and remove the two screws (Silver, M3x8mm) and two washers securing Lower Left Hand Bracket Assembly C to the Lower Left Hand Cover C .

NOTE When removing the screws (Silver, M3x8mm) using a serewdriver by tilting it, with Lower Left Hand Chute Clifted, be careful not to damage Lower Left Hand Chute C.
4. Remove the two hooks securing the Lower Left Hand Bracket Assembly C to the Lower Left Hand Cover C.
5. Remove the Lower Left Hand Bracket Assembly C.


Figure 1 Lower C Bracket Assembly

## Replacement

1. Install the Lower Left Hand Bracket Assembly C to the Lower Left Hand Cover C (PL 4.1.14) using the two screws (Silver, M3x8mm) and two washers.

NOTE Fit the two hooks on the Lower Left Hand Bracket Assembly C into the Lower Left Hand Cover C.
2. Install the Lower Left Hand Cover Assembly C (PL 4.1.10).
3. Close the Left Hand Cover Assembly (PL 4.2.8) .

## RRP 4.6 TA Pinch Roller

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Lower Left Hand Bracket Assembly C (PL 4.1.16) .
3. Remove the hook only one side (lower side) of the three Lower Left Hand Springs (PL 4.1.21) as shown .
4. Remove the TA Pinch Roller.

NOTE Note that BEARING-IN (PL 4.1.20) and two BEARING-OUTs (PL 4.1.19) are detached.


Figure 1 Pinch Roller

## Replacement

1. Install the TA Pinch Roller to the Lower Left Hand Bracket Assembly C (PL 4.1.16). Then, install the BEARING-IN (PL 4.1.20) in the center of the shaft of the TA Pinch Roller, the BEARING-OUT (PL 4.1.19) on both sides of the shaft in the direction shown in the figure, and secure the bearings with the three Lower Left Hand Springs (PL 4.1.21).
2. Install the Lower Left Hand Bracket Assembly C (PL 4.1.16) .
3. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 4.7 BTR Housing Assembly

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8) .
2. Remove the BTR Housing Assembly toward upward by pinching the levers left and right which secures BTR Housing Assembly to the Left Hand Chute Cover (PL 4.3.1) .


Figure 1 BTR Housing Assembly

## Replacement

1. Install the BTR Housing Assembly.
2. Close the Left Hand Cover Assembly (PL 4.2.8) .

## RRP 4.8 Left Hand Cover Assembly

## Removal

1. Open the Left Hand Cover Assembly.
2. Remove the screw securing the Left Hand Support Cover (PL 4.4.10) to Left Hand Cover Assembly .
3. Remove the Left Hand Cover Assembly by moving it in the direction of the arrow.


Figure 1 Left Hand Cover Assembly

## Replacement

1. Install the Left Hand Cover Assembly.
2. Install the Left Hand Support Cover (PL 4.4.10) to Left Hand Cover Assembly using the one screw.
3. Close the Left Hand Cover Assembly.

## RRP 4.9 Registration Roller Assembly P

## Removal

1. Remove the Left Hand Cover Assembly (PL 4.2.8) .
2. Remove the two hooks securing the Left Hand Chute Assembly (PL 4.2.7) to the Left Hand Cover Assembly as shown .
3. Remove the BTR Housing Assembly (PL 4.2.1) .
4. Remove the hooks of the two Pinch Out Bearings left and right securing the Registration Roller Assembly P to the Chute Assembly as shown in the figure.
5. Move the Registration Roller Assembly P in the direction of the arrow to remove.

NOTE When removing, do not hold the rubber rollers of the Registration Roller Assembly P.


Figure 1 Registration Roller Assembly

## Replacement

1. Move the Registration Roller Assembly $P$ together with the two Pinch Out Bearings (PL 4.3.2) in the opposite direction of the arrow to install.

NOTE Insert the hooks of the two Pinch Out Bearings left and right, until they are secured firmly.

NOTE When installing, do not hold the rubber rollers of the Registration Roller Assembly P.
2. Install the BTR Housing Assembly (PL 4.2.1) .
3. Install the Left Hand Chute Assembly (PL 4.2.7) to the Left Hand Cover Assembly (PL 4.2.8) using the two hooks.
4. Install the Left Hand Cover Assembly (PL 4.2.8) .

## RRP 4.10 Registration Transport Assembly

## Removal

1. Remove the MSI Cover, RR (PL 3.1.14).
2. Remove the MSI Feeder Assembly (PL 3.1.1) .
3. Remove the Left Hand Cover Assembly (PL 4.2.8) .
4. Remove the bosses on both ends on the Feed Out Chute (PL2.1.13), the right one first, and remove the Feed Out Chute .
5. Remove the two screws (Silver, M3x8mm) securing the Right Chute Assembly (PL 4.5.10) to the Registration Transport Assembly (PL 4.5.1) to remove the Right Chute Assembly.
6. Remove the two screws (DEL TITE, M3x8mm) securing the Registration Transport Assembly to the machine and, while pushing the Registration Transport Assembly toward left fully and lifting its center upward, move it in the direction of the arrow to remove.

## NOTE When removing the Registration Transport Assembly, be careful not to damage the

 two harnesses located on the backside of it.7. Release the connector (P/J104) of the Front Harness Assembly A (PL5.1.9) from the clamp.
8. Disconnect the connector (P/J215) of the Front Harness Assembly A from the Registration Transport Assembly.
9. Release the harness of the Registration Clutch Assembly H from the clamp.


Figure 1 Registration Transport Assembly

## Replacement

1. Connect the connector (P/J215) of the Front Harness Assembly A (PL 5.1.9) to the machine.
2. Connect the connector ( $\mathrm{P} / \mathrm{J} 104$ ) of the Front Harness Assembly A to the Registration Transport Assembly.
3. Secure the harness of the Registration Clutch Assembly H to the clamp.
4. Install the Registration Transport Assembly by pushing it to the left fully, and moving it in the opposite direction of the arrow.
NOTE Fit the bosses on the center-rear of the Registration Transport Assembly in the holes on the machine.
5. Install the Registration Transport Assembly to the machine using the two screws (DEL TITE, M3x8mm).
6. Install the Right Chute Assembly (PL 4.5.10) to the Registration Transport Assembly (PL 4.5.1) using the two screws (Silver, M3x8mm).

NOTE Be sure to put the boss on the backside center of the Registration Transport Assembly into the hole on the printer, Also, be sure to secure the Right Chute Assembly with its left (rear) side on front of the boss on the printer.
7. Fit the bosses on the both ends on the Feeder Chute Assembly (PL 2.1.6) into the machine, the left one first, and install the Feeder Chute Assembly.
8. Install the Left Hand Cover Assembly (PL 4.2.8) .
9. Install the MSI Feeder Assembly (PL 3.1.1) .
10. Install the MSI Cover, RR (PL 3.1.14).

## RRP 4.11 Registration Clutch Assembly H

## Removal

1. Remove the MSI Cover, RR (PL 3.1.14).
2. Remove the MSI Feeder Assembly (PL 3.1.1) .
3. Remove the Left Hand Cover Assembly (PL 4.2.8) .
4. Remove the Registration Transport Assembly (PL 4.5.1) .
5. Remove the E-ring securing the Registration Clutch Assembly H to the Registration Roller Assembly (PL 4.5.5) .
6. Remove the Registration Clutch Assembly H together with the harness.


Figure 1 Registration Clutch Assembly

## Replacement

1. Install the Registration Clutch Assembly H together with the harness.

NOTE Put the harness through the hole of the Registration Chute Assembly H as shown in the figure. Be careful not to pinch the harness.
2. Install the Registration Clutch Assembly H to the Registration Roller Assembly (PL 4.5.5) using E-ring.
NOTE Fit the boss on the Registration Transport Assembly (PL 4.5.1) in the slot on the Registration Clutch Assembly H.
3. Install the Registration Transport Assembly (PL 4.5.1).
4. Install the Left Hand Cover Assembly (PL 4.2.8) .
5. Install the MSI Feeder Assembly (PL 3.1.1).
6. Install the MSI Cover, RR (PL 3.1.14) .

## RRP 4.12 Registration Roller Assembly

## Removal

1. The MSI Cover, RR (PL 3.1.14).
2. Remove the MSI Feeder Assembly (PL 3.1.1) .
3. Remove the Left Hand Cover Assembly (PL 4.2.8) .
4. Remove the Registration Transport Assembly (PL 4.5.1) .
5. Remove the Registration Clutch Assembly H (PL 4.5.2) .
6. Remove the two E-rings left and right which secure the Registration Roller Assembly to the Registration Transport Assembly. Remove the two Registration Bearings E (PL 4.5.6) left and right .
7. Remove the Registration Roller Assembly.

NOTE When removing, do not hold the rubber rollers of the Registration Roller Assembly.


Figure 1 Registration Roller Assembly

## Replacement

1. Install the Registration Roller Assembly to the Registration Transport Assembly (PL 4.5.1), together with the two Registration Bearings E (PL 4.5.6) left and right.

## NOTE While pressing the Earth Plate FG (PL 4.5.8), install the front side Registration Bear-

 ings E to the Registration Transport Assembly.NOTE When installing, do not hold the rubber rollers of the Registration Roller Assembly.
2. Secure the Registration Roller Assembly to the Registration Transport Assembly using the two E-rings left and right.
3. Install the Registration Clutch Assembly H (PL 4.5.2) .
4. Install the Registration Transport Assembly (PL 4.5.1) .
5. Install the Left Hand Cover Assembly (PL 4.2.8) .
6. Install the MSI Feeder Assembly (PL 3.1.1) .
7. Install the MSI Cover, RR (PL 3.1.14) .

## RRP 4.13 Registration Sensor Assembly

## Removal

1. Remove the MSI Cover, RR (PL 3.1.14) .
2. Remove the MSI Feeder Assembly (PL 3.1.1) .
3. Remove the Left Hand Cover Assembly (PL 4.2.8) .
4. Remove the Registration Transport Assembly (PL 4.5.1).
5. Release the three hooks securing the Registration Sensor Assembly to the Registration Transport Assembly
6. Remove the Registration Sensor Assembly.


Figure 1 Registration Sensor Assembly

## Replacement

1. Secure the Registration Sensor Assembly to the Registration Transport Assembly (PL 4.5.1) using the three hooks.
2. Install the Registration Transport Assembly (PL 4.5.1) .
3. Install the Left Hand Cover Assembly (PL 4.2.8) .
4. Install the MSI Feeder Assembly (PL 3.1.1) .
5. Install the MSI Cover, RR (PL 3.1.14) .

## RRP 4.14 TA Clutch Assembly

## Removal

1. Remove the ESS Cover Assembly (PL 8.1.20) .
2. Remove the Upper Rear Cover (PL 1.2.5) .
3. Disconnect the connector (P/J204) of the PH Harness Assembly C (PL 8.2.7) from the TA Clutch Assembly
4. Remove the screws securing the TA Bracket (PL 4.5.15) to the machine and the Motor Assembly 242 (PL 7.1.7) to remove the TA Bracket.
5. Remove the E-ring securing the TA Clutch Assembly to the machine.
6. Remove the TA Clutch Assembly.


Figure 1 TA Clutch Assembly

## Replacement

1. Install the TA Clutch Assembly to the machine using the E-ring.
2. Install the TA Bracket (PL 4.5.15) to the machine and the Motor Assembly 242 (PL 7.1.7) using the two screws.

## NOTE When installing the TA Clutch Assembly, be sure to fit the protrusion on the TA Bracket into the notch on the TA Clutch Assembly.

3. Connect the connector (P/J204) of the PH Harness Assembly C (PL 8.2.7) to the TA Clutch Assembly.
4. Install the Upper Rear Cover (PL 1.2.5) .
5. Install the ESS Cover Assembly (PL 8.1.20) .

## RRP 4.15 Sensor

Removal

1. Remove the MSI Feeder Assembly (PL 3.1.1) .
2. Remove the Left Hand Cover Assembly (PL 4.2.8) .
3. Open the Lower Left Hand Cover Assembly C (PL 4.1.10).
4. Remove the two screws (Del Tite, M3x6mm) securing the TA Chute (PL 4.5.9) to the machine.
5. Remove the TA Chute while pulling its center.
6. Disconnect the connector (P/J105) of the PH Harness Assembly C (PL 8.2.7) from the Sensor.
7. Release the hook securing the Sensor to the TA Chute as shown in the figure.
8. Remove the Sensor.


Figure 1 Sensor

## Replacement

1. Secure the Sensor to the TA Chute (PL 4.5.9) using the hook.
2. Connect the connector ( $\mathrm{P} / \mathrm{J} 105$ ) of the PH Harness Assembly C (PL 8.2.7) to the Sensor.
3. Install the TA Chute to the machine using the two screws (Del Tite, M3x6mm).

NOTE When installing the TA Chute, be sure to fit the bosses on the TA Chute into the holes on the machine.
4. Close the Lower Left Hand Cover Assembly C (PL 4.1.10).
5. Install the Left Hand Cover Assembly (PL 4.2.8) .
6. Install the MSI Feeder Assembly (PL 3.1.1) .

## RRP 5 ROS \& Xerographics

## RRP 5.1 Xerographic Interlock Switch Assembly

## Removal

1. Remove the Fuser Cover (FR, PR) (PL 1.1.2) .
2. Remove the Top Cover Assembly PR (PL 1.1.8) .
3. Pull out the CRU (PL 5.1.15).
4. Pull out the Toner Cartridge (PL 5.1.16).
5. Remove the Front Cover Assembly (PL 1.1.9) .
6. Remove the Inner Cover Assembly, MN (PL 1.1.13) .
7. Pull out the High Voltage Power Supply-Y2 (PL 8.1.1) .
8. Remove the CTG30 Sub-Guide Assembly (PL 5.1.10) .
9. Remove the Lower PR Rear Cover (PL 1.2.6) .
10. Disconnect the connector (P/J403) of the Front Harness Assembly A (PL5.1.9) and the connector (P/J404) of the Interlock Harness Assembly A (PL 8.2.10) from the MCU F PWBA (PL 8.1.5) .


Figure 1 Disconnect Harnesses
11. Release the Front Harness Assembly A and Interlock Harness Assembly A from the clamp on the machine.
12. Remove the Intake Duct (PL 5.1.17) .


Figure 2 Intake Duct
13. Release the CRUM B Harness Assembly (PL 8.2.13) from the clamp on the Laser C Housing Assembly .
14. Disconnect the connector (P/J126) of the CRUM B Harness Assembly from the Laser C Housing Assembly (PL 5.1.7).
15. Open the Left Hand Cover Assembly (PL 4.2.8).
16. Remove the Registration Transport Assembly (PL 4.5.1) .
17. Remove the two screws (Del Tite, M3x7mm) securing the Laser C Housing Assembly (PL 5.1.7) to the machine
18. Remove the Laser C Housing Assembly by moving it in the direction of the arrow.


Figure 3 Harness Assembly


Figure 4 Registration Transport Assembly
19. Remove the four screws (Del Tite, M3x8mm) securing the Sub-Guide Assembly (PL 5.1.6) to the machine .
20. Slide the Sub-Guide Assembly in the direction of the arrow and disconnect the connector of the Front Harness Assembly A (PL 5.1.9).


Figure 5 Sub Guide Assembly
21. Remove the two hooks securing the Contact Cover Assembly (PL 4.2.2) to the machine .
22. While pressing the drum motor gear located on the rear side of the Motor Assembly 242 (PL 7.1.7), lift the left side of the Sub-Guide Assembly upward.
23. Release the Interlock Harness Assembly A and Front Harness Assembly A from the clamp on the rear side of the Sub-Guide Assembly .


Figure 6 Drum Motor Gear


Figure 7 Sub Guide Assembly Clamps
24. While pressing the drum motor gear located on the rear side of Motor Assembly 242, lower the left side (left) of the Sub-Guide Assembly
25. Lift the right side of the Sub-Guide Assembly.
26. Remove the screw (PL 5.1.2) securing the Xerographic Interlock Switch Assembly and the Interlock Switch Plate (PL 5.1.3) to the Sub-Guide Assembly .
27. Remove the Xerographic Interlock Switch Assembly together with the Interlock Switch Plate.


Figure 8 Sub Guide Assembly


Figure 9 Xerographic Interlock Switch Assembly

## Replacement

1. Install the Xerographic Interlock Switch Assembly to the Sub-Guide Assembly (PL 5.1.6) together with the Interlock Switch Plate (PL 5.1.3) using the screw (PL 5.1.2).
2. Lower in the opposite direction of the arrow of the Sub-Guide Assembly.
3. While pressing the drum motor gear located on the rear side of the Motor Assembly 242 (PL 7.1.7), lift the left side of the Sub-Guide Assembly upward and secure the Interlock Harness Assembly A (PL 8.2.10) and the Front Harness Assembly A (PL 5.1.9) to the clamps on the rear side.
4. While pressing the drum motor gear located on the rear side of the Motor Assembly 242 (PL 7.1.7), lower in the opposite direction of the arrow of the Sub-Guide Assembly.
5. Install the Contact Cover Assembly (PL 4.2.2) to the machine using the two hooks.

## NOTE Fit the bosses on the Contact Cover Assembly into the holes on the machine.

6. Slide Sub-Guide Assembly in the direction of the arrow and connect the connector of the Front Harness Assembly A (PL 5.1.9) to the CRU Switch.
7. Slide Sub-Guide Assembly in the opposite direction of the arrow and install the Sub-Guide Assembly to the machine using the four screws (Del Tite, M3x8mm).
8. Laser C Housing Assembly (PL 5.1.7) in the opposite direction of the arrow and install the Laser C Housing Assembly to the machine using the two screws (Del Tite, M3x7mm).
9. Install the Registration Transport Assembly (PL 4.5.1) .
10. Close the Left Hand Cover Assembly (PL 4.2.8).
11. Secure the CRUM B Harness Assembly to the clamp on the Laser C Housing Assembly.
12. Connect the connector ( $\mathrm{P} / \mathrm{J} 126$ ) of the CRUM B Harness Assembly to the Laser C Housing Assembly.
13. Install the Intake Duct (PL 5.1.17) .
14. Connect the connector (P/J403) of the Front Harness Assembly A (PL 5.1.9) and the connector (P/J404) of the Interlock Harness Assembly A (PL 5.1.9) to the MCU F PWBA (PL 8.1.5).
15. Secure the Interlock Harness Assembly A and the Front Harness Assembly A to the clamps on the machine.
16. Install the Lower PR Rear Cover (PL 1.2.6) .
17. Install the CTG30 Sub-Guide Assembly (PL 5.1.10) .
18. Install the High Voltage Power Supply-Y2 (PL 8.1.1) .
19. Install the Inner Cover Assembly, MN (PL 1.1.13) .
20. Install the Front Cover Assembly (PL 1.1.9) .
21. Insert the Toner Cartridge (PL 5.1.16).
22. Insert the CRU (PL 5.1.15).
23. Install the Top Cover Assembly PR (PL 1.1.8) .
24. Install the Fuser Cover (FR, PR) (PL 1.1.2) .

## RRP 5.2 Humidity \& Temperature Sensor

## Removal

1. Remove the Left Front Cover (FR, PR) (PL 1.1.1).
2. Remove the Top Cover Assembly PR (PL 1.1.8) .
3. Pull out the CRU (PL 5.1.15).
4. Pull out the Toner Cartridge (PL 5.1.16).
5. Remove the Front Cover Assembly (PL 1.1.9) .
6. Remove the Inner Cover Assembly, MN (PL 1.1.13) .
7. Pull out the High Voltage Power Supply-Y2 (PL 8.1.1) .
8. Remove the CTG30 Sub-Guide Assembly (PL 5.1.10) .
9. Remove the Lower PR Rear Cover (PL 1.2.6) .
10. Disconnect the connector (P/J403) of the Front Harness Assembly A (PL5.1.9) and the connector (P/J404) of the Interlock Harness Assembly A (PL 8.2.10) from the MCU F PWBA (PL 8.1.5) .


Figure 1 Front Harness Assembly
11. Release the Front Harness Assembly A and Interlock Harness Assembly A from the clamp on the machine.
12. Remove the Intake Duct (PL 5.1.17)


Figure 2 Intake Duct
13. Release the CRUM B Harness Assembly (PL 8.2.13) from the clamp on the Laser C Housing Assembly .
14. Disconnect the connector ( $\mathrm{P} / \mathrm{J} 126$ ) of the CRUM B Harness Assembly from the Laser C Housing Assembly.
15. Open the Left Hand Cover Assembly (PL 4.2.8) .
16. Remove the Registration Transport Assembly (PL 4.5.1) .
17. Remove the two screws (Del. Tite, M3x7mm) securing the Laser C Housing Assembly (PL 5.1.7) to the machine.
18. Remove the Laser C Housing Assembly by moving it in the direction of the arrow.


Figure 3 CRUM Harness Assembly


Figure 4 Registration Transport Assembly
19. Remove the four screws (Del Tite, M3x8mm) securing the Sub-Guide Assembly (PL 5.1.6) to the machine .
20. Slide the Sub-Guide Assembly in the direction of the arrow and disconnect the connector of the Front Harness Assembly A (PL 5.1.9).


Figure 5 Sub Guide Assembly
21. Remove the two hooks securing the Contact Cover Assembly (PL 4.2.2) to the machine.
22. While pressing the drum motor gear located on the rear side of the Motor Assembly 242 (PL 7.1.7), lift the left side of the Sub-Guide Assembly upward .
23. Disconnect the connector ( $\mathrm{P} / \mathrm{J} 150$ ) of the Front Harness Assembly A from the Humidity \& Temperature Sensor.


Figure 6 Drum Motor Gear
24. Remove the screw (Del Tite, M3x8mm) securing the Humidity \& Temperature Sensor to the Sub-Guide Assembly
25. Remove the Humidity \& Temperature Sensor.


Figure 7 Humidity Sensor

## Replacement

1. Install the Humidity \& Temperature Sensor to the Sub-Guide Assembly (PL 5.1.6) using the one screw (Del Tite, M3x8mm).
2. Connect the connector (P/J150) of the Front Harness Assembly A (PL.5.1.9) to the Humidity \& Temperature Sensor.
3. While pressing the drum motor gear located on the rear side of the Motor Assembly 242 (PL 7.1.7), lower in the opposite direction of the arrow of the Sub-Guide Assembly.
4. Install the Contact Cover Assembly (PL 4.2.2) to the machine using the two hooks.

## NOTE Fit the bosses on the Contact Cover Assembly into the holes on the machine.

5. Slide Sub-Guide Assembly in the direction of the arrow and connect the connector of the Front Harness Assembly A (PL 5.1.9) to the CRU Switch.
6. Slide Sub-Guide Assembly in the opposite direction of the arrow and install the Sub-Guide Assembly to the machine using the four screws (Del Tite, M3x8mm).
7. Laser C Housing Assembly (PL5.1.7) in the opposite direction of the arrow and install the Laser C Housing Assembly to the machine using the two screws (Del Tite, M3x7mm).
8. Install the Registration Transport Assembly (PL 4.5.1) .
9. Close the Left Hand Cover Assembly (PL 4.2.8).
10. Secure the CRUM B Harness Assembly to the clamp on the Laser C Housing Assembly.
11. Connect the connector (P/J126) of the CRUM B Harness Assembly to the Laser C Housing Assembly.
12. Install the Intake Duct (PL 5.1.17) .
13. Connect the connector (P/J403) of the Front Harness Assembly A (PL5.1.9) and the connector (P/J404) of the Interlock Harness Assembly A (PL 8.2.10) to the MCU F PWBA (PL 8.1.5).
14. Secure the Interlock Harness Assembly A and the Front Harness Assembly A to the clamps on the machine.
15. Install the Lower PR Rear Cover (PL 1.2.6) .
16. Install the CTG30 Sub-Guide Assembly (PL5.1.10) .
17. Install the High Voltage Power Supply-Y2 (PL 8.1.1) .
18. Install the Inner Cover Assembly, MN (PL 1.1.13) .
19. Install the Front Cover Assembly (PL 1.1.9) .
20. Insert the Toner Cartridge (PL 5.1.16).
21. Insert the CRU (PL 5.1.15).
22. Install the Top Cover Assembly PR (PL 1.1.8) .
23. Install the Fuser Cover (FR, PR) (PL 1.1.2) .

## RRP 5.3 CP1 CRUM PWBA Housing

## Removal

1. Remove the Top Cover Assembly PR (PL 1.1.8) .
2. Remove the Intake Duct (PL 5.1.17) .
3. Disconnect the connector (P/J126) of the CRUM B Harness Assembly (PL 8.2.13) from the CP1 CRUM PWBA Housing .
4. Remove the CP1 CRUM PWBA Housing by moving it in the direction of the arrow.


Figure 1 CRUM PWBA

## Replacement

1. Install the CP1 CRUM PWBA Housing by moving it in the opposite direction of the arrow.
2. Connect the connector (P/J126) of the CRUM B Harness Assembly (PL 8.2.13) to the CP1 CRUM PWBA Housing.
3. Install the Intake Duct (PL 5.1.17) .
4. Install the Top Cover Assembly PR (PL 1.1.8) .

## RRP 5.4 CP1 Toner CRUM PWBA

## Removal

1. Remove Top Cover Assembly PR (PL 1.1.8) .
2. Disconnect the connector (P/J127) of the CRUM B Wire Harness Assembly (PL 8.2.13) from the PWBA CRUM CP1 .
3. Move the PWBA CRUM CP1 in the direction of the arrow to remove.


Figure 1 CP1 CRUM PWBA

## Replacement

1. Move the PWBA CRUM CP1 in the opposite direction of the arrow to install.
2. Connect the connector ( $\mathrm{P} / \mathrm{J} 127$ ) of the CRUM B Wire Harness Assembly (PL 8.2.13) to the PWBA CRUM CP1.
3. Install the Top Cover Assembly PR (PL 1.1.8) .

## RRP 5.5 CTG30 Sub-Guide Assembly

## Removal

1. Remove the Fuser Cover FR,PR (PL 1.1.2) .
2. Remove the Top Cover Assembly PR (PL 1.1.8) .
3. Pull out the CRU (PL 5.1.15) .
4. Pull out the Toner Cartridge (PL 5.1.16).
5. Remove the Front Cover Assembly (PL 1.1.9) .
6. Remove the Inner Cover Assembly, MN (PL 1.1.13) .
7. Remove the Intake Duct (PL 5.1.17) .
8. Release the Main Switch C Harness Assembly (PL 8.2.11) from the clamps on the rear side of the CTG30 Sub-Guide Assembly .
9. Remove the two screws (Del Tite, M3x8mm) securing the CTG30 Sub-Guide Assembly to the machine.
10. While pushing the CTG30 Sub-Guide Assembly toward the left side, remove the screw (Del Tite, M3x8mm) securing CTG30 Sub-Guide Assembly to the machine.
11. Remove the CTG30 Sub-Guide Assembly.

NOTE Toner comes out if the toner hose is detached. Be careful not to detach it.


Figure 1 CRU \& Toner Cartridge

## Replacement

1. Install the CTG30 Sub-Guide Assembly.

NOTE Fit the hole on the CTG30 Sub-Guide Assembly to the motor part of the Depense Motor Assembly 30K (PL 5.1.11). Also, fit the shaft into the hole on the Depense Motor Assembly 30K.
2. While pushing the CTG30 Sub-Guide Assembly toward the left side, install the CTG30 SubGuide Assembly to the machine using the one screw (Del Tite, M3x8mm).
3. Install the CTG30 Sub-Guide Assembly to the machine using the two screws (Del Tite, M3x8mm).
4. Secure the Main Switch C Harness Assembly (PL 8.2.11) to the clamp on the CTG30 SubGuide Assembly.
5. Install the Intake Duct (PL 5.1.17) .
6. Install the Inner Cover Assembly, MN (PL 1.1.13) .
7. Install the Front Cover Assembly (PL 1.1.9) .
8. Insert the Toner Cartridge (PL 5.1.16).
9. Insert the CRU (PL 5.1.15).
10. Install the Top Cover Assembly PR (PL 1.1.8) .
11. Install the Fuser Cover FR,PR (PL 1.1.2) .


Figure 2 Main Switch Harness

## RRP 5.6 Depense Motor Assembly 30K

## Removal

1. Remove the Fuser Cover FR,PR (PL 1.1.2) .
2. Remove the Top Cover Assembly PR (PL 1.1.8) .
3. Pull out the CRU (PL 5.1.15).
4. Pull out the Toner Cartridge (PL 5.1.16).
5. Remove the Front Cover Assembly (PL 1.1.9) .
6. Remove the Inner Cover Assembly, MN (PL 1.1.13) .
7. Remove the Intake Duct (PL 5.1.17) .
8. Remove the CTG30 Sub-Guide Assembly (PL 5.1.10) .
9. Disconnect the connector (P/J216) of the Low Voltage Power C Harness Assembly (PL 8.2.9) from the Depense Motor Assembly 30K .
10. Remove the four screws (Del Tite, M3x8mm) securing the Depense Motor Assembly 30 K to the machine.
11. Remove the Depense Motor Assembly 30K.


Figure 1 Dispense Motor Assembly

## Replacement

1. Install the Depense Motor Assembly 30K to the machine using the four screws (Del Tite, M3x8mm).

NOTE Fit the boss on the Depense Motor Assembly 30K in the hole on the machine.
2. Connect the connector ( $\mathrm{P} / \mathrm{J} 216$ ) of the Low Voltage Power C Harness Assembly (PL 8.2.9) to the Depense Motor Assembly 30K.
3. Install the CTG30 Sub-Guide Assembly (PL 5.1.10) .
4. Install the Intake Duct (PL 5.1.17) .
5. Install the Inner Cover Assembly, MN (PL 1.1.13) .
6. Install the Front Cover Assembly (PL 1.1.9) .
7. Insert the Toner Cartridge (PL 5.1.16).
8. Insert the CRU (PL 5.1.15).
9. Install the Top Cover Assembly PR (PL 1.1.8) .
10. Install the Fuser Cover FR,PR (PL 1.1.2) .

## RRP 5.7 Fuser Fan

## Removal

1. Remove the ESS Cover Assembly (PL 8.1.20) .
2. Remove the Upper Rear Cover (PL 1.2.5) .
3. Disconnect the connector ( $\mathrm{P} / \mathrm{J} 102$ ) of the harness of the Fuser Fan from the Motor Assembly 242 (PL 7.1.7) .
4. Release the hooks left and right securing the Fuser Fan to the Fuser Duct (PL 5.1.12) as shown in the figure.
5. Remove the Fuser Fan.


Figure 1 Fuser Fan

## Replacement

1. Install the Fuser Fan to the Fuser Duct (PL 5.1.12) using the hooks left and right.

NOTE Be sure to install the Fuser Fan with its label facing outward. Also, be sure to put the harness of the Fuser Fan in the slot as shown in the figure.
2. Connect the connector ( $\mathrm{P} / \mathrm{J} 102$ ) of the harness of the Fuser Fan to the Motor Assembly 242 (PL 7.1.7).
3. Install the Upper Rear Cover (PL 1.2.5) .
4. Install the ESS Cover Assembly (PL 8.1.20) .

## RRP 5.8 ROS Assembly 12

NOTE When performing the ROS Assembly 12 removal and/or installation, be sure to perform the operation on a level and smooth work surface desk or the like. If the operation is performed on a rough and/or inclined work top, the ROS Assembly 12 will be out of alighnment. Then, applying too much force to the LDD PWBA (board) can cause a ROS alignment displacement. To avoid this, hold the board when connecting/disconnecting the connector .


Figure 1 ROS Assembly

## Removal

1. Remove the Top Cover Assembly PR (PL 1.1.8) .
2. Open the Front Cover Assembly (PL 1.1.9).
3. Pull out the CRU (PL 5.1.15).
4. Pull out the Toner Cartridge (PL 5.1.16).
5. Remove the Front Cover Assembly (PL 1.1.9) .
6. Remove the Inner Cover Assembly, MN (PL 1.1.13) .
7. Remove the Intake Duct (PL 5.1.17) .
8. Remove the CTG30 Sub-Guide Assembly (PL 5.1.10) .
9. Disconnect the three connectors (P/J140, P/J160 and P/J170) of the ROS C Harness Assembly (PL 8.2.5) from the ROS Assembly 12.
NOTE Applying too much force to the LDD PWBA (board) can cause a ROS alignment displacement. To avoid this, hold the board when connecting/disconnecting the connector.
10. Disconnect the connector ( $\mathrm{P} / \mathrm{J} 620$ ) of the ROS C Harness Assembly from the junction connector.
NOTE Applying too much force to the LDD PWBA (board) can cause a ROS alignment displacement. To avoid this, hold the board when connecting/disconnecting the connector.
11. Remove the four screws (Del Tite, M3x10mm) securing the ROS Assembly 12 to the machine.

NOTE Never impact the ROS Assembly 12 with a screwdriver or other tools
12. Remove the ROS Assembly 12 toward upward.

## Replacement

1. Install the ROS Assembly 12 to the machine using the four screws (Del Tite, M3x10mm).

## NOTE Never impact the ROS Assembly 12 with a screwdriver or other tools

2. Connect the connector ( $\mathrm{P} / \mathrm{J} 620$ ) of the ROS C Harness Assembly to the junction connector.

NOTE Applying too much force to the LDD PWBA (board) can cause a ROS alignment displacement. To avoid this, hold the board when connecting/disconnecting the connector.
3. Connect the three connectors (P/J140, P/J160 and P/J170) of the ROS C Harness Assembly (PL 8.2.5) to ROS Assembly 12.

NOTE Applying too much force to the LDD PWBA (board) can cause a ROS alignment displacement. To avoid this, hold the board when connecting/disconnecting the connector.
4. Install the CTG30 Sub-Guide Assembly (PL 5.1.10) .
5. Install the Intake Duct (PL 5.1.17) .
6. Install the Inner Cover Assembly, MN (PL 1.1.13) .
7. Install the Front Cover Assembly (PL 1.1.9) .
8. Insert the Toner Cartridge (PL 5.1.16).
9. Insert the CRU (PL 5.1.15).
10. Close the Front Cover Assembly (PL 1.1.9).
11. Install the Top Cover Assembly PR (PL 1.1.8) .

## RRP 5.9 Intake Duct

## Removal

1. Remove the Top Cover Assembly PR (PL 1.1.8) .
2. Disconnect the harness connector coming from the printer from the junction connector $(P /$ J219)
3. Release the harness connector connected to the printer from the clamp on the Intake Duct
4. Release the hook securing the Intake Duct to the CTG30 Sub-Guide Assembly (PL 5.1.10).
5. Move the Intake Duct in the direction of the arrow while lifting the left side, to release the hook securing it to the CTG30 Sub-Guide Assembly (PL 5.1.10).


Figure 1 Intake Duct


Figure 2 Intake Duct Connector

## Replacement

1. Fit the three hooks on the CTG30 Sub-Guide Assembly (PL 5.1.10) to the three holes in the Intake Duct and install the Intake Duct.
2. Move the Intake Duct in the opposite direction of the arrow and secure it to the CTG30 Guide Assembly (PL 5.1.10) with the hook.
3. Secure the harness from the printer to the clamp on the Intake Duct.
4. Connect the harness connector from the printer to the junction connector (P/J219).
5. Install the Top Cover Assembly PR (PL 1.1.8).

## RRP 5.10 CRU Fan

## Removal

1. Remove the Top Cover Assembly PR (PL 1.1.8) .
2. Remove the Intake Duct (PL 5.1.17) .
3. Disconnect the harness of the CRU FAN from the junction connector (P/J219).
4. Release the two hooks securing the CRU FAN to the Intake Duct as shown .

NOTE Be careful when handling the hooks of the Intake Duct, as they are easy to break.
5. Release the harness of the CRU FAN from the slot in the Intake Duct.
6. Remove the CRU FAN.


Figure 1 CRU Fan

## Replacement

1. Install the CRU FAN to the Intake Duct (PL 5.1.17) with the two hooks.

NOTE Install the CRU FAN with the label facing rearward.
NOTE Be careful when handling the hooks of the Intake Duct, as they are easy to break.
2. Secure the harness of the CRU FAN to the slot in the Intake Duct.
3. Connect the harness connector of the CRU FAN to the junction connector (P/J219).
4. Install the Intake Duct (PL 5.1.17).
5. Install the Top Cover Assembly PR (PL 1.1.8) .

## RRP 6 Fuser \& Exit 1

## RRP 6.1 Photo Sensor

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Fuser Assembly (PL 6.1.7) .
3. Disconnect the connector (P/J125) of the PH Harness Assembly C (PL 8.2.7) from the Photo Sensor .
4. Remove the screw (Del Tite, M3x6mm) securing the Exit Sensor Bracket (PL 6.1.6) to the machine.
5. Release the three hooks securing the Photo Sensor to the Exit Sensor Bracket.
6. Remove the Photo Sensor.


Figure 1 Photo Sensor

## Replacement

1. Secure the Photo Sensor to the Exit Sensor Bracket (P6.1.6) using the three hooks.
2. Install the Exit Sensor Bracket to the machine using the one screw (Del Tite, M3x6mm).
3. Connect the connector (P/J125) of the PH Harness Assembly C (PL 8.2.7) to the Photo Sensor.
4. Install the Fuser Assembly (PL 6.1.7) .
5. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 6.2 Fuser Assembly

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Loosen the two knobs securing the Fuser Assembly to the machine
3. Remove the Fuser Assembly toward you by holding the two handles left and right.


Figure 1 Fuser Assembly

## Replacement

1. Install the Fuser Assembly to the machine by holding the two handles left and right.
2. Tighten the two knobs securing the Fuser Assembly to the machine.
3. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 6.3 Exit Transport Assembly

## Removal

1. Remove the two screws (Del Tite, M3x8mm) securing the Upper Rear Cover (PL 1.2.5) to the machine.
2. Open the Upper Rear Cover.
3. Remove the Top Rear Cover (PL 1.1.3) .
4. Open the Left Hand Cover Assembly (PL 4.2.8).
5. Remove the Exit 1 Top Cover (PL 6.2.22) .
6. Open the Front Cover Assembly (PL 1.1.9).
7. Remove the Fuser Cover FR,PR (PL 1.1.2) .
8. Remove the two screws (Del Tite, M3x6mm) securing the Exit 2 Bracket (PL 6.2.23) to the machine .
9. Remove the Exit 2 Bracket by moving it in the direction of the arrow.


Figure 1 Exit Bracket 2
10. Remove the Synchronous Ban Belt (PL 7.1.5) .
11. Disconnect the connector (P/J206) of the Exit Harness Assembly C (PL 8.2.6) in Offset Motor Assembly (PL 6.2.3) from the machine .
12. Disconnect the connector ( $\mathrm{P} / \mathrm{J} 117$ ) of the Exit Harness Assembly $C$ from the Photo In Sensor (Offset) (PL 6.2.5).
13. Disconnect the connector (P/J118) of the Exit Harness Assembly C from the Photo In Sensor (PL 6.2.5).
14. Remove the two screws securing the Exit Transport Assembly to the machine.
15. Remove the Exit Transport Assembly toward upward.


Figure 2 Exit Transport Assembly

## Replacement

1. Install the Exit Transport Assembly to the machine using two screws.
2. Connect the connector (P/J206) of the Exit Harness Assembly C (PL 8.2.6) in the Offset Motor Assembly (PL 6.2.3) to the machine.
3. Connect the connector (P/J117) of the Exit Harness Assembly C to the Photo In Sensor (Offset) (PL 6.2.5)
4. Connect the connector (P/J118) of the Exit Harness Assembly C to the Photo In Sensor (PL 6.2.5)
5. Install the Synchronous Ban Belt (PL 7.1.5) .
6. Move the Exit 2 Bracket (PL 6.2.23) in the opposite direction of the arrow and install it to the machine using the two screws (Del Tite, M3x6mm).
7. Install the Fuser Cover FR,PR (PL 1.1.2) .
8. Close the Front Cover Assembly (PL 1.1.9).
9. Install the Exit 1 Top Cover (PL 6.2.22) .
10. Close the Left Hand Cover Assembly (PL 4.2.8).
11. Install the Top Rear Cover (PL 1.1.3) .
12. Close the Upper Rear Cover (PL 1.2.5).
13. Install the Upper Rear Cover to the machine using the two screws (Del Tite, M3x8mm).

## RRP 6.4 Offset Motor Assembly

## Removal

1. Remove the two screws (Del Tite, M3x8mm) securing the Upper Rear Cover (PL 1.2.5) to the machine.
2. Open the Upper Rear Cover.
3. Remove the Top Rear Cover PR (PL 1.1.3) .
4. Open the Left Hand Cover Assembly (PL 4.2.8).
5. Remove the Exit 1 Top Cover (PL 6.2.22) .
6. Open the Front Cover Assembly (PL 1.1.9).
7. Remove the Fuser Cover FR,PR (PL 1.1.2) .
8. Remove the Exit Transport Assembly (PL 6.2.1) .
9. Disconnect the connector (P/J206) of the Exit Harness Assembly C (PL 8.2.6) to the Photo In Sensor (Offset) (PL 6.2.5) from the Offset Motor Assembly .
10. Remove the two screws (Bind, M3x10mm) securing the Offset Motor Assembly to the Exit Transport Assembly (PL 6.2.1).
11. Remove the Offset Motor Assembly.


Figure 1 Offset Motor Assembly

## Replacement

1. Install the Offset Motor Assembly to the Exit Transport Assembly (PL 6.2.1) using the two screws (Bind, M3x10mm).
NOTE Be sure to secure the Exit Harness Assembly C (PL 8.2.6) to the clamp shown in the figure.
2. Connect the connector (P/J206) of the Exit Harness Assembly C to the Offset Motor Assembly.
3. Install the Exit Transport Assembly (PL 6.2.1) .
4. Install the Fuser Cover FR,PR (PL 1.1.2) .
5. Close the Front Cover Assembly (PL 1.1.9).
6. Install the Exit 1 Top Cover (PL 6.2.22) .
7. Close the Left Hand Cover Assembly (PL 4.2.8).
8. Install the Top Rear Cover PR (PL 1.1.3) .
9. Close the Upper Rear Cover (PL 1.2.5).
10. Install the Upper Rear Cover to the machine using the two screws (Del Tite, M3×8mm).

## RRP 6.5 Photo In Sensor (Offset)

## Removal

1. Remove the two screws (Del Tite, M3x8mm) securing the Upper Rear Cover (PL 1.2.5) to the machine.
2. Open the Upper Rear Cover.
3. Remove the Top Rear Cover PR (PL 1.1.3) .
4. Open the Left Hand Cover Assembly (PL 4.2.8).
5. Remove the Exit 1 Top Cover (PL 6.2.22) .
6. Open the Front Cover Assembly (PL 1.1.9).
7. Remove the Fuser Cover FR,PR (PL 1.1.2) .
8. Remove the Exit Transport Assembly (PL 6.2.1) .
9. Remove the two screws (Silver, M3x8mm) securing the Sensor Bracket (PL 6.2.16) to the Exit Transport Assembly .
10. Release the three hooks securing the Photo In Sensor (Offset) to the Sensor Bracket.
11. Remove the Photo In Sensor (Offset).


Figure 1 Photo In Sensor

## Replacement

1. Secure the Photo In Sensor (Offset) to the Sensor Bracket (P6.2.16) using the three hooks.
2. Install the Sensor Bracket to the Exit Transport Assembly (PL 6.2.1) using the two screws (Silver, M3x8mm).
3. Install the Exit Transport Assembly (PL 6.2.1) .
4. Install the Fuser Cover FR,PR (PL 1.1.2) .
5. Close the Front Cover Assembly (PL 1.1.9).
6. Install the Exit 1 Top Cover (PL 6.2.22) .
7. Close the Left Hand Cover Assembly (PL 4.2.8).
8. Install the Top Rear Cover PR (PL 1.1.3) .
9. Close the Upper Rear Cover.
10. Install the Upper Rear Cover to the machine using the two screws (Del Tite, M3x8mm).

## RRP 6.6 Photo In Sensor

## Removal

1. Remove the two screws (Del Tite, M3x8mm) securing the Upper Rear Cover (PL 1.2.5) to the machine.
2. Open the Upper Rear Cover.
3. Remove the Top Rear Cover PR (PL 1.1.3) .
4. Open the Left Hand Cover Assembly (PL 4.2.8).
5. Remove the Exit 1 Top Cover (PL 6.2.22) .
6. Open the Front Cover Assembly (PL 1.1.9).
7. Remove the Fuser Cover FR,PR (PL 1.1.2) .
8. Remove the Exit Transport Assembly (PL 6.2.1) .
9. Release the three hooks securing the Photo In Sensor to the Exit Transport Assembly .
10. Remove the Photo In Sensor.


Figure 1 Photo In Sensor

## Replacement

1. Secure the Photo In Sensor to the Exit Transport Assembly (PL 6.2.1) using the three hooks.
2. Install the Exit Transport Assembly (PL 6.2.1) .
3. Install the Fuser Cover FR,PR (PL 1.1.2) .
4. Close the Front Cover Assembly (PL 1.1.9).
5. Install the Exit 1 Top Cover (PL 6.2.22) .
6. Close the Left Hand Cover Assembly (PL 4.2.8).
7. Install the Top Rear Cover PR (PL 1.1.3) .
8. Close the Upper Rear Cover (PL 1.2.5).
9. Install the Upper Rear Cover to the machine using the two screws (Del Tite, M3x8mm).

## RRP 6.7 19T Gear

## Removal

1. Remove the two screws (Del Tite, M3x8mm) securing the Upper Rear Cover (PL 1.2.5) to the machine.
2. Open the Upper Rear Cover.
3. Remove the Top Rear Cover PR (PL 1.1.3) .
4. Open the Left Hand Cover Assembly (PL 4.2.8).
5. Remove the Exit 1 Top Cover (PL 6.2.22) .
6. Open the Front Cover Assembly (PL 1.1.9).
7. Remove the Fuser Cover FR,PR (PL 1.1.2) .
8. Remove the Exit Transport Assembly (PL 6.2.1) .
9. Release the hook securing the 19T Gear to the OCT Roll Assembly (PL 6.2.14) to remove the 19T Gear .


Figure 1 19T Gear

## Replacement

1. Secure the 19T Gear to the OCT Roll Assembly (PL 6.2.14) using the hook.

## NOTE Insert the 19T Gear until the hook is secured firmly.

2. Install the Exit Transport Assembly (PL 6.2.1) .
3. Install the Fuser Cover FR,PR (PL 1.1.2) .
4. Close the Front Cover Assembly (PL 1.1.9).
5. Install the Exit 1 Top Cover (PL 6.2.22) .
6. Close the Left Hand Cover Assembly (PL 4.2.8).
7. Install the Top Rear Cover PR (PL 1.1.3) .
8. Close the Upper Rear Cover (PL 1.2.5).
9. Install the Upper Rear Cover to the machine using the two screws (Del Tite, M3x8mm).

## RRP 6.8 Exit Gear

## Removal

1. Remove the two screws (Del Tite, M3x8mm) securing the Upper Rear Cover (PL 1.2.5) to the machine.
2. Open the Upper Rear Cover.
3. Remove the Top Rear Cover PR (PL 1.1.3) .
4. Open the Left Hand Cover Assembly (PL 4.2.8).
5. Remove the Exit 1 Top Cover (PL 6.2.22) .
6. Open the Front Cover Assembly (PL 1.1.9).
7. Remove the Fuser Cover FR,PR (PL 1.1.2) .
8. Remove the Exit Transport Assembly (PL 6.2.1) .
9. Release the hook securing the CAP (PL 6.2.8) to the Exit Gear to remove the CAP .


Figure 1 Exit Gear

## Replacement

1. Install the Exit Gear.

## NOTE Be sure to install the Exit Gear in the orientation shown in the figure.

2. Install the CAP (PL 6.2.8) to the Exit Gear using the hook.

## NOTE Insert the CAP until the hook is secured firmly.

3. Install the Exit Transport Assembly (PL 6.2.1) .
4. Install the Fuser Cover FR,PR (PL 1.1.2) .
5. Close the Front Cover Assembly (PL 1.1.9).
6. Install the Exit 1 Top Cover (PL 6.2.22) .
7. Close the Left Hand Cover Assembly (PL 4.2.8).
8. Install the Top Rear Cover PR (PL 1.1.3) .
9. Close the Upper Rear Cover (PL 1.2.5).
10. Install the Upper Rear Cover to the machine using the two screws (Del Tite, M3x8mm).

## RRP 6.9 OCT Roll Assembly

## Removal

1. Remove the two screws (Del Tite, M3x8mm) securing the Upper Rear Cover (PL 1.2.5) to the machine.
2. Open the Upper Rear Cover.
3. Remove the Top Rear Cover PR (PL 1.1.3) .
4. Open the Left Hand Cover Assembly (PL 4.2.8).
5. Remove the Exit 1 Top Cover (PL 6.2.22) .
6. Open the Front Cover Assembly (PL 1.1.9).
7. Remove the Fuser Cover FR,PR (PL 1.1.2) .
8. Remove the Exit Transport Assembly (PL 6.2.1) .
9. Remove the 19T Gear (PL 6.2.7) .
10. Remove the two E-rings left and right which secures the OCT Roll Assembly to the OCT Chute 1 (PL 6.2.11) .
11. Release the hook on the left side of the Bearing (PL 6.2.20) securing the OCT Roll Assembly to the Exit Transport Assembly to remove the Bearing.
12. Move the OCT Roll Assembly in the direction of the arrow (to the front) to remove.

NOTE When removing, do not hold the rubber rollers of the OCT Roll Assembly.


Figure 1 OCT Roll Assembly

## Replacement

1. Move the OCT Roll Assembly in the opposite direction of the arrow to install.

NOTE When installing, do not hold the rubber rollers of the OCT Roll Assembly.
2. Install the Bearing (PL 6.2.20) to the Out Chute 1 (PL 6.2.11) using the hook.

NOTE Insert the Bearing until the hook is secured firmly.
3. Install the OCT Roll Assembly to the OCT Chute 1 using the two E-rings.

NOTE Be careful not to bend the Exit Pinch Spring (PL 6.2.12) attached on the OCT Chute 1.
4. Install the 19T Gear (PL 6.2.7) .
5. Install the Exit Transport Assembly (PL 6.2.1) .
6. Install the Fuser Cover FR,PR (PL 1.1.2) .
7. Close the Front Cover Assembly (PL 1.1.9).
8. Install the Exit 1 Top Cover (PL 6.2.22) .
9. Close the Left Hand Cover Assembly (PL 4.2.8).
10. Install the Top Rear Cover PR (PL 1.1.3) .
11. Close the Upper Rear Cover (PL 1.2.5).
12. Install the Upper Rear Cover to the machine using the two screws (Del Tite, M3x8mm).

## RRP 6.10 Offset Gear

## Removal

1. Remove the two screws (Del Tite, M3x8mm) securing the Upper Rear Cover (PL 1.2.5) to the machine.
2. Open the Upper Rear Cover.
3. Remove the Top Rear Cover PR (PL 1.1.3) .
4. Open the Left Hand Cover Assembly (PL 4.2.8).
5. Remove the Exit 1 Top Cover (PL 6.2.22) .
6. Open the Front Cover Assembly (PL 1.1.9).
7. Remove the Fuser Cover FR,PR (PL 1.1.2) .
8. Remove the Exit Transport Assembly (PL 6.2.1) .
9. Remove the screw (Silver, M3x8mm) securing the Sensor Bracket (PL 6.2.16) to the Exit Transport Assembly to remove the Sensor Bracket .
10. Slide the OCT Roll Assembly (PL 6.2.14) to right (front) first, and release the Boss on the OCT Chute 1 while pressing down the Boss portion of the Offset Gear. Then, remove the Offset Gear upward .


Figure 1 Sensor Bracket


Figure 2 Offset Gear

## Replacement

1. Put the boss on the Lower Chute (PL 6.2.15) into the hole on the Offset Gear, and slide the OCT Roll Assembly (PL 6.2.14) toward the right side (front) while pressing down the boss part of the Offset Gear to engage them.
2. Install the Sensor Bracket (PL 6.2.16) to the Exit Transport Assembly using the one screw (Silver, M3x8mm).
3. Install the Exit Transport Assembly (PL 6.2.1) .
4. Install the Fuser Cover FR,PR (PL 1.1.2) .
5. Close the Front Cover Assembly (PL 1.1.9).
6. Install the Exit 1 Top Cover (PL 6.2.22) .
7. Close the Left Hand Cover Assembly (PL 4.2.8).
8. Install the Top Rear Cover PR (PL 1.1.3) .
9. Close the Upper Rear Cover.
10. Install the Upper Rear Cover (PL 1.2.5) to the machine using the two screws (Del Tite, M3x8mm).

## RRP 6.11 Exit 1 Top Cover

## Removal

1. Remove the Exit 1 Top Cover by moving it in the direction of the arrow.


Figure 1 Exit 1 Top Cover

## Replacement

1. Install the Exit 1 Top Cover by moving it in the opposite direction of the arrow.

## RRP 7 Drives

## RRP 7.1 Synchronous Ban Belt

## Removal

1. Remove the ESS Cover Assembly (PL 8.1.20)
2. Remove the Upper Rear Cover (PL 1.2.5) .
3. Remove the Exit 1 Top Cover (PL 6.2.22) .
4. Release the hook on the Exit Flange(PL 7.1.9) securing Synchronous Ban Belt to the Motor Assembly 242 (PL 7.1.7) to remove the Exit Flange
5. Remove the Synchronous Ban Belt from the 25T Pulley (PL 7.1.8).

NOTE The 25T PULLEY is also detached. Be careful not to lose it.
6. Remove the Synchronous Ban Belt from the Exit Gear (PL 6.2.9)


Figure 1 Synchronous Belt

## Replacement

1. Install the 25T Pulley (PL 7.1.8) to the shaft of the Motor Assembly 242 (PL 7.1.7) shown in the figure.
2. Install the Synchronous Ban Belt onto the 25T Pulley.

NOTE Installing the Synchronous Ban Belt is made easy to rotate the Motor slowly by hand.
3. Install the Synchronous Ban Belt together with the 25T Pulley using the hook on the Exit Flange (PL 7.1.9).

NOTE Fit the flange to the D-shaped shaft, and install the flange until the hook is secured firmly.
4. Install the Exit 1 Top Cover (PL 6.2.22) .
5. Install the Upper Rear Cover (PL 1.2.5) .
6. Install the ESS Cover Assembly (PL 8.1.20) .

## RRP 7.2 Motor Assembly 242

## Removal

1. Remove the ESS Cover Assembly (PL 8.1.20) .
2. Remove the Upper Rear Cover (PL 1.2.5) .
3. Remove the Exit 1 Top Cover (PL 6.2.22) .
4. Open the Front Cover Assembly (PL 1.1.9).
5. Pull out the CRU (PL 5.1.15).
6. Remove the Synchronous Ban Belt (PL 7.1.5) .
7. Disconnect the connector (P/J214) of the Drive A Harness Assembly (PL 8.2.12) and the harness connector (CN102) of the Fuser Fan from the Motor Assembly 242 .
8. Remove the two screws securing the TA Bracket (PL 4.5.15) to the machine and the Motor Assembly 242 to remove the TA Bracket.
9. Remove the four screws (Del Tite, M3x8mm) securing the Motor Assembly 242 to the machine.
10. Remove the Motor Assembly 242.

NOTE Be sure to remove the Gear while pushing the Gear on the upper part of the Motor in the direction of the arrow.


Figure $1 \mathbf{2 4 2}$ Motor Assembly

## Replacement

1. Install the Motor Assembly 242 to the machine using the four screws (Del Tite, M3x8mm).

## NOTE Be sure to install the Gear while pushing the GEAR on the upper part of the Motor in

 the direction of the arrow.2. Install the TA Bracket (PL 4.5.15) to the machine and the Motor Assembly 242 using the two screws.
3. Connect the connector (P/J214) of the Drive A Harness Assembly (PL 8.2.12) and the harness connector (CN102) of the Fuser Fan to the Motor Assembly 242.
4. Install the Synchronous Ban Belt (PL 7.1.5) .
5. Insert the CRU (PL 5.1.15).
6. Close the Front Cover Assembly (PL 1.1.9).
7. Install the Exit 1 Top Cover (PL 6.2.22) .
8. Install the Upper Rear Cover (PL 1.2.5) .
9. Install the ESS Cover Assembly (PL 8.1.20) .

## RRP 8 Electrical

## RRP 8.1 High Voltage Power Supply-Y2

## Removal

1. Remove the Fuser Cover FR,PR (PL 1.1.2) .
2. Remove the Top Cover Assembly PR (PL 1.1.8) .
3. Pull out the CRU (PL 5.1.15).
4. Remove the Front Cover Assembly (PL 1.1.9) .
5. Remove the Inner Cover Assembly, MN (PL 1.1.13) .
6. Disconnect the connector (P/J500) of the Front Harness Assembly A (PL 5.1.9) connector from the High Voltage Power Supply-Y2 .
7. Release the Front Harness Assembly A from the clamps.
8. Remove the two screws (Del Tite, M3x6mm) securing the High Voltage Power Supply-Y2 to the machine.
9. Remove the High Voltage Power Supply-Y2 by moving it in the direction of the arrow.


Figure 1 Y2 High Voltage Power Supply

## Replacement

1. Install the High Voltage Power Supply-Y2 by moving it in the opposite direction of the arrow.

## NOTE Be sure to put the board into the grooves on both sides.

2. Install the High Voltage Power Supply-Y2 to the machine using the two screws (Del Tite, M3x6mm).
3. Secure the Front Harness Assembly A (PL 5.1.9) to the clamps.
4. Connect the connector ( $\mathrm{P} / \mathrm{J} 500$ ) of the Front Harness Assembly A to the High Voltage Power Supply-Y2.
5. Install the Inner Cover Assembly, MN (PL 1.1.13) .
6. Install the Front Cover Assembly (PL 1.1.9) .
7. Install the CRU (PL 5.1.15).
8. Install the Top Cover Assembly PR (PL 1.1.8) .
9. Install the Fuser Cover FR,PR (PL 1.1.2) .

## RRP 8.2 Power Switch

## Removal

1. Remove the Top Cover Assembly PR (PL 1.1.8) .
2. Open the Front Cover Assembly (PL 1.1.9).
3. Remove the Upper Right Cover (PL 1.2.1) .
4. Remove the screw (Del Tite, M3x6mm) securing the CPR Switch Bracket (PL 8.1.3) to the machine
5. Move the CPR Switch Bracket with Power Switch in the direction of the arrow (rear side) to remove.
6. Disconnect the four connectors ( $\mathrm{P} / \mathrm{J} 56, \mathrm{P} / \mathrm{J} 57, \mathrm{P} / \mathrm{J} 68$ and $\mathrm{P} / \mathrm{J} 69$ ) of the Main Switch C Harness Assembly (PL 8.2.11) from the Power Switch.
7. Release the hooks securing the Power Switch to the CPR Switch Bracket as shown in the figure.


Figure 1 Power Switch

## Replacement

1. Secure the Power Switch to the CPR Switch Bracket (PL 8.1.3) using the hooks.
2. Connect the four connectors (P/J56, P/J57, P/J68 and P/J69) of the Main Switch C Harness Assembly (PL 8.2.11) to the Power Switch.
3. Install the CPR Switch Bracket together with the Power Switch to the machine using the one screw (Del Tite, M3x6mm).

## NOTE Fit the notch on the Power Switch to the boss on the machine.

4. Install the Upper Right Cover (PL 1.2.1).
5. Close the Front Cover Assembly (PL 1.1.9).
6. Install the Top Cover Assembly PR (PL 1.1.8) .

## RRP 8.3 Exit PWBA

## Removal

1. Remove the Top Cover Assembly PR (PL 1.1.8) .
2. Disconnect all harness connectors from the Exit PWBA

NOTE Only connector P430 has a hook. Disconnect it while pushing the hook.
3. Remove the two screws (Del Tite, M3x6mm) securing the Lower Exit Bracket (PL 8.1.24) to the machine.
4. Release the locks of the SUPPORT PCs securing the Exit PWBA to the machine as shown in the figure.
5. Remove the Exit PWB Atogether with Lower Exit Bracket from the machine.
6. Remove the two screws (Del Tite, M3x6mm) securing the Exit PWBA to the Lower Exit Bracket.
7. Remove the Exit PWBA.


Figure 1 Exit PWBA

## Replacement

1. Install the Exit PWBA to the Lower Exit Bracket (PL 8.1.24) using the two screws (Del Tite, M3x6mm).
2. Install the Lower Exit Bracket to the machine using the two screws (Del Tite, M3x6mm).

## NOTE Be sure to fit the tips of the SUPPORT PCs on the machine into the holes on the Exit PWBA.

3. Connect all harness connectors to the Exit PWBA.

NOTE Only connector P430 has a hook. While pushing the lock of the connector, connect it until it locks firmly.
4. Install the Top Cover Assembly PR (PL 1.1.8) .

## RRP 8.4 MCU F PWBA

## Removal

1. Remove the ESS Cover Assembly (PL 8.1.20) .
2. Remove the Upper Rear Cover (PL 1.2.5) .
3. Remove the Lower PR Rear Cover (PL 1.2.6) .
4. Disconnect all harness connectors from the MCU F PWBA .

NOTE The connectors P/J400, P/J401, and TTM/2TM have a hook. Disconnect then while pushing the hook.
5. Remove the six screws (Del Tite, M3x6mm) securing the MCU F PWBA to the machine.
6. Remove the MCU F PWBA.


Figure 1 MCU F PWBA


Figure 2 MCU PWBA

## Replacement

1. Install the MCU F PWBA to the machine using the six screws (Del Tite, M3x6mm).
2. Connect all harness connectors to the MCU F PWBA.

NOTE The connectors P/J400, P/J414, P/J405, and TTM/2TM have a hook. While pushing the lock of these connectors, connect them until they lock firmly.
3. Install the Lower PR Rear Cover (PL 1.2.6) .
4. Install the Upper Rear Cover (PL 1.2.5)
5. Install the ESS Cover Assembly (PL 8.1.20) .

## RRP 8.5 Power Unit

## Removal

1. Remove the Upper Right Cover (PL 1.2.1)
2. Disconnect all harness connector from the Power Unit .

NOTE The connectors P1, P2, P6, P521 and P526 have a hook. Disconnect then while pushing the hook .
3. Remove the nine screws (Del Tite, M3x8mm) securing the Power Unit to the machine.
4. Remove the Power Unit.


Figure 1 Power Unit


Figure 2 Power Unit

## Replacement

1. Install the Power Unit to the machine using the nine screws (Del Tite, M3x8mm).

NOTE Be sure to fit the holes on the board to the two bosses on the machine.
2. Connect all harness connector to the Power Unit.

NOTE The connectors P1, P2, P6, P521 and P526 have a hook. Disconnect then while pushing the hook. While pushing the lock of these connectors, connect them until they lock firmly.
3. Install the Upper Right Cover (PL 1.2.1).

## RRP 8.6 AC Chassis Assembly XC

## Removal

1. Remove the ESS Cover Assembly (PL 8.1.20) .
2. Remove the Upper Rear Cover (PL 1.2.5) .
3. Remove the Lower PR Rear Cover (PL 1.2.6) .
4. Remove the Top Cover Assembly PR (PL 1.1.8) .
5. Remove the Upper Right Cover (PL 1.2.1) .
6. Disconnect the three connectors (P2, T11 (Black), T12 (White) of the AC Harness Assembly, US, EU (PL 8.1.15) from the Power Unit .


Figure 1 AC Chassis Assembly
7. Release the four AC Harness Assemblies, US, EU from the three clamps.
8. Remove the three screws (Del Tite, M3x6mm) securing the AC Chassis Assembly, XC to the printer.
9. Release the AC Harness Assembly, US, EU from the clamp.
10. Remove the AC Chassis Assembly, XC.

## Replacement

1. Connect the three Harness connectors (P2, T11 (Black), T12 (White) to the Power Unit (PL 8.1.8).
2. Secure the four AC Harness Assemblies, US, EU with three clamps.
3. Secure the AC Harness Assembly, US, EU to the clamp.
4. Install the AC Chassis Assembly, XC (PL 8.1.10) to the printer using the three screws (Del Tite, M3x6mm).
5. Install the Upper Right Cover (PL 1.2.1) .
6. Install the Top Cover Assembly PR (PL 1.1.8) .
7. Install the Lower PR Rear Cover (PL 1.2.6) .
8. Install the Upper Rear Cover (PL 1.2.5) .
9. Install the ESS Cover Assembly (PL 8.1.20) .

## RRP 8.7 Ground Fault Breaker INL

## Removal

1. Remove the ESS Cover Assembly (PL 8.1.20) .
2. Remove the Upper Rear Cover (PL 1.2.5) .
3. Remove the Lower PR Rear Cover (PL 1.2.6) .
4. Remove the three screws (Del Tite, M3x6mm) securing the AC Chassis Assembly, XC (PL 8.1.10) to the printer .
5. Disconnect the two connectors (P/J50) of the AC Harness Assembly, US, EU (PL 8.1.15) from the GIF Breaker INL.
6. Remove the two screws (M4x12mm) securing the GIF Breaker INL to the AC Chassis Assembly, XC.
7. Remove the GIF Breaker INL.


Figure 1 Ground Fault Breaker

## Replacement

1. Install the GIF Breaker INL to the AC Chassis Assembly, XC (PL 8.1.10) using the two screws (M4x12mm).
2. Connect the two connectors (P/J50) of the AC Harness Assembly. US, EU (PL 8.1.15) to the GIF Breaker INL.
3. Install the AC Chassis Assembly, XC to the printer using the three screws (Del Tite, M3x6mm).
4. Install the Lower PR Rear Cover (PL 1.2.6) .
5. Install the Upper Rear Cover (PL 1.2.5) .
6. Install the ESS Cover Assembly (PL 8.1.20) .

## RRP 8.8 MN Outlet

## Removal

1. Remove the ESS Cover Assembly (PL 8.1.20) .
2. Remove the Upper Rear Cover (PL 1.2.5) .
3. Remove the Lower PR Rear Cover (PL 1.2.6) .
4. Remove the three screws (Del Tite, M3x6mm) securing the AC Chassis Assembly, XC (PL 8.1.10) to the printer .
5. Disconnect the three connectors of the AC Harness Assembly, US, EU (PL 8.1.15) from the MN Outlet (PL 8.1.16).
6. Release the two hooks securing the MN Outlet to the AC Chassis Assembly, XC.
7. Remove the MN Outlet.


Figure 1 Outlet

## Replacement

1. Install the MN Outlet to the AC Chassis Assembly, XC (PL 8.1.10) using the two hooks.
2. Connect the three connectors of the AC Harness Assembly, US, EU (PL 8.1.15) to the MN Outlet.
3. Install the AC Chassis Assembly, XC to the printer using the three screws (Del Tite, M3x6mm).
4. Install the Lower PR Rear Cover (PL 1.2.6) .
5. Install the Upper Rear Cover (PL 1.2.5) .
6. Install the ESS Cover Assembly (PL 8.1.20) .

## RRP 8.9 ESS Cover Assembly

## Removal

1. Loosen the two special screws securing the ESS Cover Assembly to the machine .
2. Remove the ESS Cover Assembly by moving it in the direction of the arrow.


Figure 1 ESS Cover

## Replacement

1. Install the ESS Cover Assembly in the opposite direction of the arrow using two special screws.

## RRP 91000 Sheet Feeder

## RRP 9.1 Top Cover

## Removal

1. Pull out the Tray 3.
2. Remove the one screw (Del Tite, M3x8mm) securing the Top Cover to the machine .
3. Remove the Top Cover.


Figure 1 Top Cover

## Replacement

1. Put the Top Cover onto the frame on the right side of the machine.
2. Install the Top Cover to the machine using a screw (Del Tite, M3x8mm).
3. Push the Tray 3 in.

## RRP 9.2 Foot Cover

## Removal

1. Remove the Tray 4.
2. Remove the Right Cover (PL 9.1.3) .
3. Remove the screw (Del Tite, M3x8mm) securing the Foot Cover to the machine .
4. Remove the Foot Cover.


Figure 1 Foot Cover

## Replacement

1. Install the Foot Cover to the machine using the one screw (Del Tite, M3x8mm).
2. Install the Right Cover (PL 9.1.3) .
3. Install the Tray 4.

## RRP 9.3 Right Cover

## Removal

1. Remove the three screws (Del Tite, M3x8mm) securing the Right Cover to the machine .
2. Move the Right Cover in the direction of the arrow to remove.


Figure 1 Right Cover

## Replacement

1. Install the Right Cover to the machine using three screws (Del Tite, M3x8mm).

NOTE Be sure to put the three hooks on the lower part of the Right Cover into the holes on the frame.

## RRP 9.4 Left Cover

## Removal

1. Remove the two screws (Del Tite, M3x8mm) securing the Left Cover to the machine .
2. Move the Left Cover in the direction of the arrow to remove.


Figure 1 Left Cover

## Replacement

1. Install the Left Cover to the machine using two screws (Del Tite, M3x8mm).

NOTE Be sure to put the three hooks on the lower part of the Left Cover into the holes on the frame.

## RRP 9.5 Rear Cover

## Removal

1. Remove the four screws (Del Tite, M3x8mm) securing the Rear Cover to the machine .
2. Remove the Rear Cover.


Figure 1 Rear Cover

## Replacement

1. Install the Rear Cover to the machine using four screws (Del Tite, M3x8mm).

## RRP 9.6 Caster (Stopper)

## Removal

1. Remove the Tray 3.
2. Remove the Tray 4.
3. Place the machine with the right side down.

## NOTE Be careful not to damage the Right Cover (PL 9.1.3).

4. Remove the three screws (Del Tite, M4x6mm) securing the Caster (Stopper) to the machine
5. Remove the Caster (Stopper).


Figure 1 Caster with Stopper

## Replacement

1. Install the Caster (Stopper) to the machine using three screws (Del Tite, M4x6mm).
2. Install the Tray 4.
3. Install the Tray 3.

## RRP 9.7 Caster

## Removal

1. Remove the Tray 3.
2. Remove the Tray 4.
3. Place the machine with the right side down.

## NOTE Be careful not to damage the Right Cover (PL 9.1.3).

4. Remove the three screws (Del Tite, M4x6mm) securing the Caster to the machine .
5. Remove the Caster.


Figure 1 Caster

## Replacement

1. Install the Caster to the machine using three screws (Del Tite, M4x6mm).
2. Install the Tray 4.
3. Install the Tray 3.

## RRP 9.8 Tray 3 Paper Size Switch

## Removal

1. Remove the Tray 3.
2. Remove the Tray 4.
3. Disconnect the connector (P/J820) of Wire Harness (PL 9.6.13) from the Tray 3 Paper Size Switch.
4. Remove the one screw securing the Tray 3 Paper Size Switch to the machine.
5. Remove the Tray 3 Paper Size Switch.


Figure 1 Tray 3 Paper Size Switch

## Replacement

1. Install the Tray 3 Paper Size Switch to the machine using the one screw.

NOTE Be sure to fit the boss on the machine into the hole on the Tray 3 Paper Size Switch.
2. Connect the connector (P/J820) of Wire Harness (PL 9.6.13) to the Tray 3 Paper Size Switch.
3. Install the Tray 4
4. Install the Tray 3

## RRP 9.9 Tray 4 Paper Size Switch

## Removal

1. Remove the Tray 3.
2. Remove the Tray 4.
3. Disconnect the connector (P/J824) of Wire Harness (PL 9.6.13) from the Tray 4 Paper Size Switch .
4. Remove the one screw securing the Tray 4 Paper Size Switch to the machine.
5. Remove the Tray 4 Paper Size Switch.


Figure 1 Tray 4 Paper Size Switch

## Replacement

1. Install the Tray $3 / 4$ Paper Size Switch (Tray 4) to the machine using the one screw.

NOTE Be sure to fit the boss on the machine into the hole on the Tray 3/4 Paper Size Switch (Tray 4).
2. Connect the connector (P/J824) of Wire Harness (PL 9.6.13) to the Tray $3 / 4$ Paper Size Switch (Tray 4).
3. Install the Tray 4
4. Install the Tray 3

## RRP 9.10 Tray 3 Feeder

## Removal

1. Pull out the Tray 3.
2. Remove the Left Cover (PL 9.1.4).
3. Open the Left Cover Assembly (PL 9.5.10) .
4. Remove the one screw securing the Support (PL 9.5.25) on the front to the machine.
5. Remove the bosses left and right securing the Chute Assembly Feeder 2 (PL 9.2.9) to the machine to remove the Chute Assembly Feeder 2.


Figure 1 Left Cover Assembly
6. Remove the one screw securing the Bracket (PL 9.5.24) to the machine to remove the Bracket .
7. Release the Wire Harness (PL 20.4.16) from the clamp.
8. Disconnect the connector ( $\mathrm{P} / \mathrm{J} 661 \mathrm{~B}$ ) of the Wire Harness from the machine.
9. Remove the two screws securing the Tray 3 Feeder to the machine.
10. Move the Tray 3 Feeder in the direction of the arrow to remove.


Figure 2 Tray 3 Feeder

## Replacement

1. Put the Tray 3 Feeder into the machine from the rear side and install it using two screws.

NOTE Be sure to fit the two bosses on the machine into the two holes on the Tray 3 Feeder.
2. Connect the connector ( $\mathrm{P} / \mathrm{J} 661 \mathrm{~B}$ ) of the Wire Harness (PL 9.4.16) to the machine.
3. Secure the Wire Harness to the clamp.
4. Install the Bracket (PL 9.5.24) to the machine using the one screw.

## NOTE Be sure to fit the boss on the machine into the hole on the Bracket.

5. Install the Chute Assembly Feeder 2 (PL 9.2.9) to the machine with the bosses left and right.
6. Install the Support (PL 9.5.25) on the front to the machine using the one screw.
7. Close the Left Cover Assembly (PL 9.5.10).
8. Install the Left Cover (PL 9.1.4).
9. Insert the Tray 3.

## RRP 9.11 Tray 4 Feeder

## Removal

1. Pull out the Tray 4.
2. Open the Left Cover Assembly (PL 9.5.10) .
3. Remove the one screw each on left and right Supports (PL 9.5.25) securing them to the machine.
4. Remove the bosses left and right securing the Chute Feed Out (PL 9.2.12) to the machine to remove the Chute Feed Out.


Figure 1 Left Cover Assembly
5. Release the Wire Harness (PL 9.4.16) from the clamp .
6. Disconnect the connector (P/J661A) of Wire Harness (PL 9.4.16) from the machine.
7. Remove the two screws securing the Tray 4 Feeder to the machine.
8. Move the Tray 4 Feeder in the direction of the arrow to remove.


Figure 2 Tray 4 Feeder

## Replacement

1. Put the Tray 4 Feeder into the machine from the rear side and install it using two screws.

## NOTE Be sure to fit the two bosses on the machine into the two holes on the Tray 4 Feeder.

2. Connect the connector (P/J661A) of Wire Harness (PL 9.4.16) to the machine.
3. Secure the Wire Harness (PL 9.4.16) to the clamp.
4. Install the Chute Feed Out (PL 9.2.12) to the machine with the bosses left and right.
5. Install left and right Supports (PL 9.5.25) to the machine using one screw on each.
6. Close the Left Cover Assembly (PL 9.5.10).
7. Close the Tray 4

## RRP 9.12 Front Side Guide Assembly

## Removal

1. Remove the Tray Assembly (PL 9.3.1).
2. Remove E-rings on both ends (front/rear) securing the Bottom Plate (PL 9.3.10) to the Tray (PL 9.3.11) .
3. Push the guide on the front in the arrow direction shown in the figure by finger to release the boss on the Tray from the Bottom Plate.
4. Remove the Bottom Plate by moving it in the direction of the arrow.
5. Remove the one screw (Silver, M3x8mm) each securing the two Pinion Gears (PL 9.3.15) to the Tray .
6. Remove the Pinion Gears.
7. After sliding the Front Side Guide Assembly inward, remove the Front Side Guide Assembly in the direction of the arrow.


Figure 1 Paper Tray


Figure 2 Front Side Guide Assembly

## Replacement

1. Fit the bosses on the lower part of the Front Side Guide Assembly to the holes on the Tray (PL 9.3.11).
2. Slide the Front Side Guide Assembly fully outward.
3. Install the two Pinion Gears (PL 9.3.15) to the Tray using one screw (Silver, M3×8mm) each.

NOTE Before installing the Pinion Gears, make sure that the Front Side Guide Assembly and the Rear Side Guide (PL 9.3.9) are placed fully outward. After installing the Pinion Gears, make sure that the Front Side Guide Assembly and the Rear Side Guide slide smoothly.
4. Fit the rear guide hole on the Bottom Plate (PL 9.3.10) to the boss on the Tray.
5. Install the Bottom Plate to the Tray.

NOTE Be sure to fit the front guide hole on the Bottom Plate to the boss on the Tray.
6. Fix the Bottom Plate to the Tray using the two E-rings on front and rear.
7. Insert the Tray Assembly (PL 9.3.1).

## RRP 9.13 Rear Side Guide

## Removal

1. Remove the Tray Assembly(PL 9.3.1).
2. Remove E-rings on both ends (front/rear) securing the Bottom Plate (PL 9.3.10) to the Tray (PL 9.3.11) .
3. Push the guide on the front in the arrow direction shown in the figure by finger to release the boss on the Tray from the Bottom Plate.
4. Remove the Bottom Plate by moving it in the direction of the arrow.
5. Remove the one screw (Silver, M3x8mm) each securing the two Pinion Gears (PL 9.3.15) to the Tray .
6. Remove the Pinion Gears.
7. After sliding the Rear Side Guide inward, remove the Rear Side Guide in the direction of the arrow.

NOTE Be sure to release the bosses on the Rear Side Guide from the holes on the Side Guide Actuator (PL 9.3.12).


Figure 1 Paper Tray


Figure 2 Rear Side Guide

## Replacement

1. Fit the bosses on the lower part of the Rear Side Guide to the holes on the Tray (PL 9.3.11).

NOTE Be sure to fit the bosses on the Rear Side Guide into the holes on the Side Guide Actuator (PL 9.3.12).
2. Slide the Rear Side Guide fully outward.
3. Install the two Pinion Gears (PL 9.3.15) to the Tray using one screw (Silver, M3x8mm) each.

NOTE Before installing the Pinion Gears, make sure that the Rear Side Guide and the Front Side Guide Assembly (PL 9.3.6) are placed fully outward. After installing the Pinion Gears, make sure that the Front Side Guide Assembly and the Rear Side Guide slide smoothly.
4. Fit the rear guide hole on the Bottom Plate (PL 9.3.10) to the boss on the Tray.
5. Install the Bottom Plate to the Tray.

NOTE Be sure to fit the front guide hole on the Bottom Plate to the boss on the Tray.
6. Fix the Bottom Plate to the Tray using the two E-rings on front and rear.
7. Insert the Tray Assembly (PL 9.3.1).

## RRP 9.14 End Guide

## Removal

1. Remove the Tray Assembly (PL 9.3.1).
2. Remove the Front Side Guide Assembly (PL 9.3.6) .
3. Remove the Rear Side Guide (PL 9.3.9) .
4. Remove the Side Guide Actuator (PL 9.3.12) .
5. Remove the two hooks securing the Link (PL 9.3.19) to the Tray (PL 9.3.11).
6. Release the bosses of the End Guide Actuator (PL 9.3.18) from the holes on the LINK by moving the LINK in the direction of the arrow (A), with its center slightly lifted .
7. Release the bosses on the End Guide from the holes on the Link by moving the Link in the direction of the arrow (B).
8. After sliding the End Guide inward as shown in the figure, remove it.


Figure 1 End Guide


Figure 2 End Guide Actuator

## Replacement

1. Fit the bosses on the lower part of the End Guide to the holes on the Tray (PL 9.3.11).
2. The Slide End Guide to around the center of the slot on the Tray.
3. Fit the bosses on the End Guide to the holes on the LINK (PL 9.3.19).
4. Fit the bosses on the End Guide Actuator (PL 9.3.18) to the holes on the LINK by moving the LINK in the direction of the arrow (A).
5. Install the LINK to the Tray using the two hooks.
6. Install the Side Guide Actuator (PL 9.3.12).
7. Install the Rear Side Guide (PL 9.3.9) .
8. Install the Front Side Guide Assembly (PL 9.3.6) .
9. Insert the Tray Assembly (PL 9.3.1).

## RRP 9.15 Sector Gear (60T)

## Removal

1. Remove the Tray Assembly (PL 9.3.1).
2. Remove the two screws (Silver, M3x8mm) securing the Bracket (PL 9.3.23) to the Tray (PL 9.3.11) to remove the bracket .
3. Remove the Sector Gear (60T).


Figure 1 60T Sector Gear

## Replacement

1. Engage the Sector Gear (60T) with the Gear (13T/60T) (PL 9.3.21).
2. With the shaft (D-shaped) of the Lift Up Shaft fitted into the holes on the Sector Gear (60T), install the Bracket (PL 9.3.23) to the Tray (PL 9.3.11) using two screws (Silver, M3x8mm).
3. Insert the Tray Assembly (PL 9.3.1).

## RRP 9.16 Tray 1/2 Feed Lift Up Motor

## Removal

1. Remove the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .
2. Disconnect the connector (Tray3:P/J220B, Tray4:P/J220A) of the Wire Harness (PL 9.6.13) from the Tray $1 / 2$ Feed Lift Up Motor .
3. Remove the two screws ( $\mathrm{M} 3 \times 6 \mathrm{~mm}$ ) securing the Tray $1 / 2$ Feed Lift Up Motor to the Feeder Assembly (PL 9.4.1).
4. Remove the Tray $1 / 2$ Feed Lift Up Motor.


Figure 1 Lift Up Motor

## Replacement

1. Install the Tray $1 / 2$ Feed Lift Up Motor to the Feeder Assembly (PL 9.4.1) using two screws (M3x6mm).
2. Connect the connector (Tray3:P/J220B, Tray4:P/J220A) of the Wire Harness (PL 9.6.13) to the Tray 1/2 Feed Lift Up Motor.
3. Install the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .

## RRP 9.17 Spacer

## Removal

1. Remove the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL9.2.8) or .
2. Release the Wire Harness (PL 9.4.16) from the clamp on the Bracket (PL 9.4.3) .
3. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 9.4.34).

NOTE Note that the Gears attached on the Bracket may be detached.
4. Remove E-rings securing the Spacer, Gear (31T) (PL 9.4.5) and the Spring (PL 9.4.6) to the Bracket.

NOTE Note that the Spring may pop out.
5. Remove the Spacer.


Figure 1 Lower Frame

## Replacement

1. Install the Spacer to the Bracket (PL 9.4.3) together with the Gear (31T) (PL 9.4.5) and the Spring (PL 9.4.6), and fix them using E-ring.
2. Install the Bracket to the Lower Frame (PL 9.4.34) using the three screws (Del Tite, M3x6mm).

NOTE Make sure that the Gears attached on the Bracket are surely installed.
3. Secure the Wire Harness (PL 9.4.16) to the clamp on the Bracket.
4. Install the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .

## RRP 9.18 Gear (31T)

## Removal

1. Remove the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .
2. Release the Wire Harness (PL 9.4.16) from the clamp on the Bracket (PL 9.4.3) .
3. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 9.4.34).

## NOTE Note that the Gears attached on the Bracket may be detached.

4. Remove E-rings securing the Gear (31T), the Spacer (PL 9.4.4) and the Spring (PL 9.4.6) to the Bracket.

NOTE Note that the Spring can pop out.
5. Remove the Gear (31T).


Figure 1 31T gear

## Replacement

1. Install the Gear (31T) to Bracket (PL 9.4.3), together with the Spacer (PL 9.4.4) and the Spring (PL 9.4.6), using E-rings.
2. Install the Bracket to the Lower Frame (PL 9.4.34) using the three screws (Del Tite, M3x6mm).
NOTE Make sure that the Gears attached on the Bracket are surely installed.
3. Secure the Wire Harness (PL 9.4.16) to the clamp on the Bracket.
4. Install the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .

## RRP 9.19 Oneway Clutch

## Removal

1. Remove the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .
2. Release the Wire Harness (PL 9.4.16) from the clamp on the Bracket (PL 9.4.3) .
3. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 9.4.34)

NOTE Note that the Gears attached on the Bracket may be detached.
4. Remove the Oneway Clutch.


Figure 1 Oneway Clutch

## Replacement

1. Install the Oneway Clutch.
2. Install the Bracket (PL 9.4.3) to the Lower Frame (PL 9.4.34) using the three screws (Del Tite, M3x6mm).
NOTE Make sure that the Gears attached on the Bracket are surely installed.
3. Secure the Wire Harness (PL 9.4.16) to the clamp on the Bracket.
4. Install the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .

## RRP 9.20 Oneway Gear

## Removal

1. Remove the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .
2. Remove the Oneway Clutch (PL 9.4.7) .
3. Remove the Oneway Gear .


Figure 1 Oneway Gear

## Replacement

1. Install the Oneway Gear.
2. Install the Oneway Clutch (PL 9.4.7) .
3. Install the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .

## RRP 9.21 Gear (13T)

## Removal

1. Remove the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .
2. Remove the Oneway Clutch (PL 9.4.7) .
3. Remove the Oneway Gear (PL 9.4.8) .
4. Remove the Gear (13T) .


Figure 1 13T Gear

## Replacement

1. Install the Gear (13T).
2. Install the Oneway Gear (PL 9.4.8) .
3. Install the Oneway Clutch (PL 9.4.7) .
4. Install the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .

## RRP 9.22 Actuator

## Removal

1. Remove the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .
2. Remove the two bosses on the Actuator securing the Actuator to the Upper Frame (PL 9.4.40) .
3. Remove the Actuator.


FI3K040A1
Figure 1 Actuator

## Replacement

1. Install the Actuator.

NOTE Fit the bosses on the Actuator into the holes on the Upper Frame (PL 9.4.40).
2. Install the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .

## RRP 9.23 No Paper Sensor

## Removal

1. Remove the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .
2. Disconnect the connector (Tray3:P/J102B, Tray4:P/J102A) of the Wire Harness (PL 9.4.16) from the No Paper Sensor .
3. Release the hooks securing the No Paper Sensor to the Upper Frame (PL 9.4.40) as shown in the figure.
4. Remove the No Paper Sensor.


Figure 1 No Paper Sensor

## Replacement

1. Secure the No Paper Sensor to the Upper Frame (PL 9.4.40) using the hooks.
2. Connect the connector (Tray3:P/J102B, Tray4:P/J102A) of the Wire Harness (PL 9.4.16) to the No Paper Sensor.
3. Install the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .

## RRP 9.24 Level Sensor

## Removal

1. Remove the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .
2. Remove the Actuator (PL 9.4.13) .
3. Disconnect the connector (Tray3:P/J101B, Tray4:P/J101A) of the Wire Harness (PL 9.4.16) from the Level Sensor .
4. Release the hooks securing the Level Sensor to the Upper Frame (PL 9.4.40) as shown in the figure.
5. Remove the Level Sensor.


Figure 1 Level Sensor

## Replacement

1. Secure the Level Sensor to the Upper Frame (PL 9.4.40) using the hooks.
2. Connect the connector (Tray3:P/J101B, Tray4:P/J101A) of the Wire Harness (PL 9.4.16) to the Level Sensor.
3. Install the Actuator (PL 9.4.13) .
4. Install the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .

## RRP 9.25 Pre Feed Sensor

## Removal

1. Remove the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .
2. Remove the Pre Feed Sensor from the Front Chute (PL 9.4.12) .
3. Disconnect the connector (Tray3:P/J103B, Tray4:P/J103A) of the Wire Harness (PL 9.4.16) from the Pre Feed Sensor.


FI3K043A1
Figure 1 Pre feed Sensor

## Replacement

1. Connect the connector (Tray3:P/J103B, Tray4:P/J103A) of the Wire Harness (PL 9.4.16) to the Pre Feed Sensor.
2. Install the Pre Feed Sensor to the Front Chute (PL 9.4.12).
3. Install the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .

## RRP 9.26 28T/21T Gear

## Removal

1. Remove the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .
2. Release the Wire Harness (PL 9.4.16) from the clamp on the Bracket (PL 9.4.3) .
3. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 9.4.34).

NOTE Note that the Gears attached on the Bracket may be detached.
4. Remove the Gear (28T/21T).


Figure 1 Gear

## Replacement

1. Install the Gear (28T/21T).
2. Install the Bracket (PL 9.4.3) to the Lower Frame (PL 9.4.34) using the three screws (Del Tite, M3x6mm).

## NOTE Make sure that the Gears attached on the Bracket are surely installed.

3. Secure the Wire Harness (PL 9.4.16) to the clamp on the Bracket.
4. Install the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .

## RRP 9.27 Gear (29T)

## Removal

1. Remove the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL9.2.8) or .
2. Release the Wire Harness (PL 9.4.16) from the clamp on the Bracket (PL 9.4.3) .
3. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 9.4.34).

NOTE Note that the Gears attached on the Bracket may be detached.
4. Remove the Gear (29T).


## Replacement

1. Install the Gear (29T).
2. Install the Bracket (PL 9.4.3) to the Lower Frame (PL 9.4.34) using three screws (Del Tite, M3x6mm).

NOTE Make sure that the Gears attached on the Bracket are surely installed.
3. Secure the Wire Harness (PL 9.4.16) to the clamp on the Bracket.
4. Install the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .

## RRP 9.28 Feed Roller Assembly

## Removal

1. Pull out the Tray3 or the Tray4.
2. Move the Front Chute (PL 9.4.12) in the direction of the arrow
3. Release the hook securing the Feed Roller Assembly to the Shaft (PL 9.4.23) as shown in the figure.
4. Remove the Feed Roller Assembly.

NOTE Note that the Oneway Clutch (PL 9.4.21) and the Oneway Gear (22T) (PL 9.4.22) may be detached.

NOTE When removing, do not hold the rubber roller of the Feed Roller Assembly.


Figure 1 Feed Roll Assembly

## Replacement

1. Install the Feed Roller Assembly to the Shaft (PL 9.4.23), and fix it using hook.

NOTE When installing, do not hold the rubber roller of the Feed Roller Assembly.
2. Move the Front Chute (PL 9.4.12) in the opposite direction of the arrow (to the rear side).
3. Insert the Tray3 or the Tray4.

## RRP 9.29 Oneway Clutch

## Removal

1. Pull out the Tray3 or the Tray4.
2. Remove the Feed Roller Assembly (PL 9.4.20) .
3. Remove the Oneway Clutch .

NOTE Note that Oneway Gear (22T) (PL 9.4.22) may be detached.


Figure 1 Oneway Clutch

## Replacement

1. Install the Oneway Clutch.
2. Install the Feed Roller Assembly (PL 9.4.20) .
3. Insert the Tray3 or the Tray4.

## RRP 9.30 Oneway Gear (22T)

## Removal

1. Pull out the Tray3 or the Tray4.
2. Remove the Feed Roller Assembly (PL 9.4.20) .
3. Remove the Oneway Clutch (PL 9.4.21) .
4. Remove the Oneway Gear (22T) .


Figure 1 Oneway Gear 22T

## Replacement

1. Install the Oneway Gear (22T).
2. Install the Oneway Clutch (PL 9.4.21) .
3. Install the Feed Roller Assembly (PL 9.4.20) .
4. Insert the Tray3 or the Tray4.

## RRP 9.31 Friction Clutch

## Removal

1. Pull out the Tray3 or the Tray4.
2. Remove the Roller Assembly (Retard) (PL 9.4.20) .
3. Remove the Spacer (PL 9.4.29) .
4. Remove the Friction Clutch .


Figure 1 Friction Clutch

## Replacement

1. Install the Friction Clutch.
2. Install the Spacer (PL 9.4.29) .
3. Install the Roller Assembly (Retard) (PL 9.4.20) .
4. Insert the Tray3 or the Tray4.

## RRP 9.32 Retard Roller Assembly

## Removal

1. Pull out the Tray3 or the Tray4.
2. Move the Front Chute (PL 9.4.12) in the direction of the arrow
3. Release the hook securing the Retard Roller Assembly to the Shaft-Retard (PL 9.4.27) as shown in the figure.
4. Remove the Retard Roller Assembly.

NOTE Note that the Spacer (PL 9.4.29) and the Friction Clutch (PL 9.4.26) may be detached.
NOTE When removing, do not hold the rubber roller of the Retard Roller Assembly.


Figure 1 Retard Roller Assembly

## Replacement

1. Install the Retard Roller Assembly to the Shaft-Retard (PL 9.4.27), and fix it using the hook.

NOTE When installing, do not hold the rubber roller of the Retard Roller Assembly.
2. Move the Front Chute (PL 9.4.12) in the opposite direction of the arrow (to the rear side).
3. Insert the Tray3 or the Tray4.

## RRP 9.33 Spacer

## Removal

1. Pull out the Tray3 or the Tray4.
2. Remove the Roller Assembly (Retard) (PL 9.4.20) .
3. Remove the Spacer .

NOTE Note that the Friction Clutch (PL 9.4.26) may be detached.


Figure 1 Spacer

## Replacement

1. Install the Spacer.
2. Install the Roller Assembly (Retard) (PL 9.4.20) .
3. Insert the Tray3 or the Tray4.

## RRP 9.34 Gear (33T)

## Removal

1. Pull out the Tray3 or the Tray4.
2. Remove the Roller Assembly (Nudger) (PL 9.4.20) .
3. Remove the Gear (25T) (PL 9.4.33)
4. Remove the Gear (33T) .


Figure 1 33T Gear

## Replacement

1. Install the Gear (33T).
2. Install the Gear (25T) (PL 9.4.33) .
3. Install the Roller Assembly (Nudger) (PL 9.4.20) .
4. Insert the Tray3 or the Tray4.

## RRP 9.35 Nudger Roller Assembly

## Removal

1. Pull out the Tray3 or the Tray4.
2. Move the Front Chute (PL 9.4.12) in the direction of the arrow .
3. Release the hook securing the Nudger Roller Assembly to the Shaft-Nudger (PL 9.4.31) as shown in the figure.
4. Remove the Nudger Roller Assembly.

NOTE Note that the Gear (25T) (PL 9.4.33) may be detached.
NOTE When removing, do not hold the rubber roller of the Nudger Roller Assembly.


Figure 1 Nudger Roller Assembly

## Replacement

1. Install the Nudger Roller Assembly to the Shaft-Nudger (PL 9.4.31), and fix it using the hook.

NOTE When installing, do not hold the rubber roller of the Nudger Roller Assembly.
2. Move the Front Chute (PL 9.4.12) in the opposite direction of the arrow (to the rear side).
3. Insert the Tray3 or the Tray4.

## RRP 9.36 Gear (25T)

## Removal

1. Pull out the Tray 3 or the Tray 4.
2. Remove the Nudger Roller Assembly (PL 9.4.20) .
3. Remove the Gear (25T) .


Figure 1 25T Gear

## Replacement

1. Install the Gear (25T).
2. Install the Nudger Roller Assembly (PL 9.4.20) .
3. Insert the Tray 3 or the Tray 4.

## RRP 9.37 Gear (27T)

## Removal

1. Remove the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .
2. Release the Wire Harness (PL 9.4.16) from the clamp on the Bracket (PL 9.4.3) .
3. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 9.4.34).

NOTE Note that the Gears attached on the Bracket may be detached.
4. Release the hook securing the Gear (27T) to the Shaft (PL 9.4.23) as shown in the figure.
5. Remove the Gear (27T).


Figure 1 27T Gear

## Replacement

1. Install the Gear (27T) to the Shaft (PL 9.4.23) using the hook.
2. Install the Bracket (PL 9.4.3) to the Lower Frame (PL 9.4.34) using three screws (Del Tite, M3x6mm).

## NOTE Make sure that the Gears attached on the Bracket are surely installed.

3. Secure the Wire Harness (PL 9.4.16) to the clamp on the Bracket.
4. Install the Tray 3 Feeder (PL 9.2.7) or the Tray 4 Feeder (PL 9.2.8) or .

## RRP 9.38 Tray 3 Feed Out Sensor

## Removal

1. Open the Left Cover Assembly (PL 9.5.10).
2. Remove the two screws (Del Tite, M3x8mm) securing the Chute (PL 9.5.1) to the machine .
3. Disconnect the connector (P/J821) of the Wire Harness (PL 9.5.4) from the Tray 3 Feed Out Sensor.
4. Release the hooks securing the Tray 3 Feed Out Sensor to the Chute as shown in the figure.


Figure 1 Tray 3 Feed Out Sensor

## Replacement

1. Secure the Tray 3 Feed Out Sensor to the Chute (PL 9.5.1) with the hooks.

## NOTE Be sure to put the Actuator attached to the Tray 3 Feed Out Sensor into the hole on the Chute.

2. Connect the connector (P/J821) of the Wire Harness (PL 9.5.4) to the Tray 3 Feed Out Sensor.
3. Install the Chute to the machine using two screws (Del Tite, M3x8mm).
4. Close the Left Cover Assembly (PL 9.5.10).

## RRP 9.39 Tray 4 Feed Out Sensor

## Removal

1. Open the Left Cover Assembly (PL 9.5.10).
2. Remove the screw securing the Support (PL 9.5.25) on the front to the machine .
3. Remove the two screw (Del Tite, M3x8mm) securing the Chute (PL 9.5.5) to the machine.
4. Disconnect the connector (P/J825) of the Wire Harness (PL 9.5.7) from the Tray 4 Feed Out Sensor.
5. Release the hooks securing the Tray 4 Feed Out Sensor to the Chute as shown in the figure.


Figure 1 Tray 4 Feed Out Sensor

## Replacement

1. Secure the Tray 4 Feed Out Sensor to the Chute (PL 9.5.5) with the hooks.

## NOTE Be sure to put the Actuator attached to the Tray 4 Feed Out Sensor into the hole on the Chute.

2. Connect the connector (P/J825) of the Wire Harness (PL 9.5.7) to the Tray 4 Feed Out Sensor.
3. Install the Chute to the machine using two screws (Del Tite, M3x8mm).
4. Install the Support (PL 9.5.25) on the front to the machine using the one screw.
5. Close the Left Cover Assembly (PL 9.5.10).

## RRP 9.40 Upper Takeaway Roll Assembly

## Removal

1. Open the Left Cover Assembly (PL 9.5.10).
2. Remove the two screws (Del Tite, M3x8mm) securing the Chute (PL 9.5.1) to the machine .
3. Disconnect the connector (P/J821) of the Wire Harness (PL 9.5.4) from the machine to remove the Chute.
4. Remove the E-ring securing the Upper Takeaway Roll Assembly to the machine using a mini screwdriver or the like.
5. Remove the Bearing (PL 9.5.9) from the machine.
6. Move the Upper Takeaway Roll Assembly in the direction of the arrow to remove.

NOTE Note that the Bearing (PL 9.5.9) may be detached.
7. Remove the left and right E-rings on the Upper Takeaway Roll Assembly, and remove the Gear and the Bearing (PL 9.5.9).


Figure 1 Upper Takeaway Roll Assembly

## Replacement

1. Install the Gear and the Bearing (PL 9.5.9) to the Upper Takeaway Roll Assembly, and using the E-rings on left and right.
NOTE Install the Gear by aligning it with the D-shape. Also, be careful not to install the Bearing in a wrong direction.
NOTE When installing, do not hold the rubber roller of the Upper Takeaway Roll Assembly.
2. Move the Upper Takeaway Roll Assembly in the opposite direction of the arrow to install.
3. Install the Bearing to the machine.
4. Secure the Upper Takeaway Roll Assembly to the machine with the one E-ring.
5. Connect the connector ( $\mathrm{P} / \mathrm{J821}$ ) of the Wire Harness ( PL 9.5 .4 ) to the machine.
6. Secure the Chute (PL 9.5.1) to the machine using two screws (Del Tite, M3x8mm).
7. Close the Left Cover Assembly (PL 9.5.10).

## RRP 9.41 Lower Takeaway Roll Assembly

## Removal

1. Open the Left Cover Assembly (PL 9.5.10).
2. Remove the two screws (Del Tite, M3x8mm) securing the Chute (PL 9.5.5) to the machine .
3. Disconnect the connector ( $\mathrm{P} / \mathrm{J825}$ ) of the Wire Harness (PL 9.5.7) from the machine to remove the Chute.
4. Remove the E-ring securing the Lower Takeaway Roll Assembly to the machine using a mini screwdriver or the like.
5. Remove the Bearing (PL 9.5.9) from the machine.
6. Move the Lower Takeaway Roll Assembly in the direction of the arrow to remove.
7. Note that the Bearing (PL 9.5.9) may be detached.
8. When removing, do not hold the rubber roller of the Lower Takeaway Roll Assembly.
9. Remove the left and right E-rings on the Lower Takeaway Roll Assembly and remove the Gear (PL 9.5.28) and the Bearing (PL 9.5.9).


Figure 1 Lower Takeaway Roll Assembly

## Replacement

1. Install the Gear and the Bearing (PL 9.5.9) to the Lower Takeaway Roll Assembly, and them using the E-rings on left and right.
2. Install the Gear by aligning it with the D-shape. Also, be careful not to install the Bearing in a wrong direction.
3. When installing, do not hold the rubber roller of the Lower Takeaway Roll Assembly.
4. Move the Lower Takeaway Roll Assembly in the opposite direction of the arrow to install.
5. Install the Bearing to the machine.
6. Install the Lower Takeaway Roll Assembly to the machine with the one E-ring.
7. Connect the connector (P/J825) of the Wire Harness (PL 9.5.7) to the machine.
8. Install the Chute (PL 9.5.5) to the machine using two screws (Del Tite, M3x8mm).
9. Close the Left Cover Assembly (PL 9.5.10).

## RRP 9.42 Upper Roll Assembly

## Removal

1. Open the Left Cover Assembly (PL 9.5.10).
2. Remove the screw (Silver, M3x8mm) securing the Chute (PL 9.5.17) to the Left Cover Assembly to remove the Chute .
3. Remove the two screws (Silver, M3x8mm) securing the Upper Roll Assembly to the Left Cover Assembly.
4. Remove the Upper Roll Assembly.


Figure 1 Upper Roll Assembly

## Replacement

1. Install the Upper Roll Assembly to the Left Cover Assembly (PL 9.5.10) using two screws (Silver, M3x8mm).
2. Install the Chute (PL 9.5.17) to the Left Cover Assembly using the one screw (Silver, M3x8mm).
3. Close the Left Cover Assembly.

## RRP 9.43 Lower Roll Assembly

## Removal

1. Open the Left Cover Assembly (PL 9.5.10).
2. Remove the two screws (Silver, M3x8mm) securing the Lower Roll Assembly to the Left Cover Assembly .
3. Remove the Lower Roll Assembly.


Figure 1 Lower Roll Assembly

## Replacement

1. Install the Lower Roll Assembly to the Left Cover Assembly (PL 9.5.10) using two screws (Silver, M3x8mm).
2. Close the Left Cover Assembly (PL 9.5.10).

## RRP 9.44 Upper Pinch Roll

## Removal

1. Open the Left Cover Assembly (PL 9.5.10).
2. Remove the Upper Roll Assembly (PL 9.5.11)
3. Place the Upper Roll Assembly upside down.
4. Remove the three Springs (PL 9.5.16) from the Bracket (PL 9.5.12) .

NOTE When the Spring is removed, two Bearings (PL 9.5.13) and one Bearing (PL 9.5.14) are detached. Be careful not to lose them.
5. Remove the Upper Pinch Roll.


Figure 1 Upper Pinch Roll

## Replacement

1. Secure the Upper Pinch Roll to the Bracket (PL 9.5.12) using the three Springs (PL 9.5.16).

NOTE Install the Bearing (PL 9.5.14) to the center of the shaft of the Upper Pinch Roll, and the Bearings (PL 9.5.13) on both ends of the shaft in the direction shown in the figure, secure them with three Springs.
2. Install the Upper Roll Assembly .
3. Close the Left Cover Assembly (PL 9.5.10).

## RRP 9.45 Lower Pinch Roll

## Removal

1. Open the Left Cover Assembly (PL 9.5.10).
2. Remove the Lower Roll Assembly (PL 9.5.11) .
3. Place the Lower Roll Assembly upside down .
4. Remove the three Springs (PL 9.5.16) from the Bracket (PL 9.5.12).

NOTE When the Spring is removed, two Bearings (PL 9.5.13) and one Bearing (PL 9.5.14) are detached. Be careful not to lose them.
5. Remove the Lower Pinch Roll.


Figure 1 Lower Pinch Roll

## Replacement

1. Secure the Lower Pinch Roll to Bracket (PL 9.5.12) using the three Springs (PL 9.5.16).

NOTE Install the Bearing (PL 9.5.14) to the center of the shaft of the Lower Pinch Roll, and Bearings (PL 9.5.13) on both ends of the shaft in the direction shown in the figure, secure them with three Springs.
2. Install the Lower Roll Assembly (PL 9.5.11) .
3. Close the Left Cover Assembly (PL 9.5.10).

## RRP 9.46 Left Cover Interlock Switch

## Removal

1. Open the Left Cover Assembly (PL 9.5.10).
2. Remove the one screw (Del Tite, M3x8mm) securing the Bracket Assembly (PL 9.5.26) to the machine .
3. Disconnect the connector (FS812) of the Wire Harness (PL 9.6.13) from the Left Cover Interlock Switch to remove the Bracket Assembly.
4. Release the hooks securing the Left Cover Interlock Switch to the Bracket Assembly.
5. Remove the Left Cover Interlock Switch.


Figure 1 Left Cover Interlock Switch

## Replacement

1. Secure the Left Cover Interlock Switch to the Bracket Assembly (PL 9.5.26) with the hook.
2. Connect the connector (FS812) of the Wire Harness (PL 9.6.13) to the Left Cover Interlock Switch.
3. Install the Bracket Assembly to the machine using the one screw (Del Tite, M3x8mm).
4. Close the Left Cover Assembly (PL 9.5.10).

## RRP 9.47 Tray Module PWB

## Removal

1. Remove the Rear Cover (PL 9.1.5) .
2. Disconnect all connectors of the Wire Harness from the Tray MODULE PWB .
3. Remove the four screws securing the Tray Module PWB to the machine
4. Remove the Tray Module PWB.


TRAY MODULE PWB (PL20.6.1)

Figure 1 Tray Module PWB


Figure 2 Tray Module PWB Removal

## Replacement

1. Install the Tray Module PWB to the machine using four screws.
2. Connect all connectors of the Wire Harness to the Tray Module PWB.
3. Install the Rear Cover (PL 9.1.5) .

## Removal

1. Remove the Rear Cover (PL 9.1.5) .
2. Disconnect the connector (P/J822) of the Wire Harness (PL 9.6.13) connected from the machine to the Bracket (PL 9.6.3)
3. Remove the two screws (Del Tite, M3×8mm) securing the Bracket to the machine to remove the Bracket.

NOTE The Bearing (PL 9.6.5) and the Washer (PL 9.6.15) are detached together. Be careful not to lose them.
4. Remove the E-ring securing the Gear (38T) (PL 9.6.6) to the Bracket (PL 9.6.3) using a mini screwdriver or the like, and remove the Gear (38T)

## NOTE The Shaft (PL 9.6.4) and the Bearing are detached together. Be careful not to lose them.

5. Disconnect the harness connector of the Clutch from the Bracket by releasing the hook.
6. Remove the Clutch.


Figure 1 Clutch Bracket


Figure 2 Clutch Assembly

## Replacement

1. Secure the harness connector of the Clutch to the Bracket (PL 9.6.3) with the hook.
2. Install the Clutch together with the Gear (38T) (PL 9.6.6), the Bearing (PL 9.6.5) and the Shaft (PL 9.6.4) to the Bracket using the one E-ring.
NOTE Fit the Gear (38T) to the D-shaped of the Shaft. Also, Install the Bracket with its boss fit to the notch on the Clutch.
3. Install the Bracket to the machine together with the Bearing and the Washer (PL 9.6.16) using two screws (Del Tite, M3x8mm).
4. Connect the connector (P/J822) of the Wire Harness (PL 9.6.13) to the Bracket.
5. Install the Rear Cover (PL 9.1.5) .

NOTE After the installation, be sure that the harness connected to the Clutch does not contact the gears.

## RRP 9.49 Main Motor

## Removal

1. Remove the Rear Cover (PL 9.1.5) .
2. Disconnect the connector (P/J826) of the Wire Harness (PL 9.6.13) from the Main Motor .
3. Remove the two screws (Del Tite, M3x8mm) securing the Main Motor to the machine.
4. Remove the Main Motor.


Figure 1 Main Motor

## Replacement

1. Install the Main Motor to the machine using two screws (Del Tite, M3x8mm).
2. Connect the connector (P/J826) of the Wire Harness (PL 9.6.13) to the Main Motor.
3. Install the Rear Cover (PL 9.1.5) .

## RRP 10 Duplex Unit

## RRP 10.1 Duplex Transport Unit

## Removal

1. Move the MCU Cap Cover (PL 1.2.7) in the direction of the arrow to remove it from the Lower Rear Cover (PL 1.2.6) .
2. Disconnect the connector (Duplex) of Duplex Harness Assembly A (PL 10.1.22) from the machine.
3. Release the Duplex Harness Assembly A from the clamp.
4. Open the Duplex Cover (PL 10.1.13).
5. Turn the Duplex Locks (PL 10.2.2) left and right on the Outer Chute (PL 10.2.5) by 90 degrees as shown in the figure to release the Outer Chute from the printer .

NOTE When the Duplex Lock is released, the Duplex Transport Unit may fall down. Be sure to rotate the Duplex Lock until them click while holding the Duplex Transport Unit by hand.
6. Remove the Duplex Transport Unit.


Figure 1 Cap Cover


Figure 2 Duplex Locks

## Replacement

1. Connect the Duplex connector of the Duplex Harness Assembly A (PL 10.1.22) to the machine.
2. Secure the Duplex Harness Assembly A to the clamp.
3. Move the MCU Cap Cover (PL 1.2.7) in the opposite direction of the arrow to install.

NOTE Be careful not to pinch harness.
4. Turn the Duplex Locks (PL 10.2.2) left and right on the Outer Chute (PL 10.2.5) by 90 degrees in the opposite direction of the arrow shown in the figure to lock them.
NOTE Fit the hooks on the lower part of the Duplex Transport Unit into the holes on the machine, and turn the Duplex Locks until them click.
5. Close the Duplex Cover (PL 10.1.13).

## RRP 10.2 Roll Gear 28

## Removal

1. Remove the Duplex Transport Unit (PL 10.1.1).
2. Remove the two screws (Silver, M3x8mm) securing the Lower Chute (PL 10.1.8) to the Outer Chute (PL 10.2.5) to remove the Lower Chute .
3. Open the Inner Chute (PL 10.2.6).


Figure 1 Lower Chute
4. Release the hook of the Duplex Stopper (PL 10.2.1) securing the Outer Chute to the Inner Chute .
5. Remove the four screws (Silver, $\mathrm{M} 3 \times 8 \mathrm{~mm}$ ) securing the Outer Chute and the Inner Chute to the Duplex Cover (PL 10.1.13) to remove the Outer Chute and the Inner Chute.


Figure 2 Outer Chute
6. Disconnect the junction connector (P/J212) of the Duplex Motor Harness Assembly (PL 10.1.21) from the Motor Harness of the Duplex Motor Assembly (PL 10.1.11) .
7. Release the Duplex Harness Assembly A from the clamps on the Outer Chute.
8. Remove the three screws (Silver, M3x8mm) securing the Motor Bracket (PL 10.1.16) to the Outer Chute and remove the Motor Bracket.
9. While releasing the hook securing the Roll Gear 28 to the Outer Chute as shown in the figure to remove the Roll Gear 28.


Figure 3 Duplex Motor Assembly

## Replacement

1. Install the Roll Gear 28.

NOTE Install the Roll Gear 28 to the Outer Chute (PL 10.2.5) until it is locked firmly.
2. Install the Motor Bracket (PL 10.1.16) to the Outer Chute using the three screws (Silver, M3x8mm).
3. Connect the junction connector (P/J212) of the Duplex Motor Harness Assembly (PL 10.1.21) to the Duplex Motor Assembly (PL 10.1.11), and secure the Duplex Harness Assembly A with the clamp on the Outer Chute.
4. Install the Outer Chute and the Inner Chute (PL 10.2.6) to the Duplex Cover (PL 10.1.13) using four screws (Silver, M3x8mm).

## NOTE Be careful not to let the Duplex Stopper (PL 10.2.1) detach from the Outer Chute.

5. Install the Duplex Stopper to the Inner Chute.
6. Close the Inner Chute.
7. Install the Lower Chute (PL 10.1.8) to the Outer Chute using the two screws (Silver, $\mathrm{M} 3 \times 8 \mathrm{~mm}$ ).
8. Install the Duplex Transport Unit (PL 10.1.1) .
9. Remove the Duplex Transport Unit (PL 10.1.1).
10. Remove the two screws (Silver, M3x8mm) securing the Lower Chute (PL 10.1.8) to the Outer Chute (PL 10.2.5) to remove the Lower Chute .


Figure 1 Lower Chute
3. Open the Inner Chute (PL 10.2.6).
4. Release the hook of the Duplex Stopper (PL 10.2.1) securing the Outer Chute to the Inner Chute .
5. Remove the four screws (Silver, M3x8mm) securing the Outer Chute and the Inner Chute to the Duplex Cover (PL 10.1.13) to remove the Outer Chute and the Inner Chute.
6. Disconnect the junction connector (P/J212) of the Duplex Motor Harness Assembly (PL 10.1.21) from the Motor Harness of the Duplex Motor Assembly (PL 10.1.11).
7. Release the Duplex Harness Assembly A from the clamps on the Outer Chute.
8. Remove the three screws (Silver, M3x8mm) securing the Motor Bracket (PL 10.1.16) to the Outer Chute to remove the Motor Bracket.
9. Remove the Idle Gear 3374.


Figure 2 Outer Chute


Figure 3 Duplex Motor Assembly

## Replacement

1. Install the Idle Gear 3374.
2. Install the Motor Bracket (PL 10.1.16) to the Outer Chute (PL 10.2.5) using the three screws (Silver, M3x8mm).
3. Connect the junction connector (P/J212) of the Duplex Motor Harness Assembly (PL 10.1.21) to the Motor Harness of the Duplex Motor Assembly (PL 10.1.11) and secure the the Duplex Harness Assembly A with the clamps on the Outer Chute.
4. Install the Outer Chute and the Inner Chute (PL 10.2.6) to the Duplex Cover (PL 10.1.13) using four screws (Silver, M3x8mm).

## NOTE Be careful not to let the Duplex Stopper (PL 10.2.1) detach from the Outer Chute.

5. Install the Duplex Stopper to the Inner Chute.
6. Close the Inner Chute.
7. Install the Lower Chute (PL 10.1.8) to the Outer Chute using the two screws (Silver, $\mathrm{M} 3 \times 8 \mathrm{~mm}$ ).
8. Install the Duplex Transport Unit (PL 10.1.1) .

## RRP 10.4 Idle Gear 33

1. Remove the Duplex Transport Unit (PL 10.1.1).
2. Remove the two screws (Silver, M3x8mm) securing the Lower Chute (PL 10.1.8) to the Outer Chute (PL 10.2.5) to remove the Lower Chute .


Figure 1 Lower Chute
3. Open the Inner Chute (PL 10.2.6).
4. Release the hook of the Duplex Stopper (PL 10.2.1) securing the Outer Chute to the Inner Chute .
5. Remove the four screws (Silver, M3x8mm) securing the Outer Chute and the Inner Chute to the Duplex Cover (PL 10.1.13) to remove the Outer Chute and the Inner Chute.
6. Disconnect the junction connector (P/J212) of the Duplex Motor Harness Assembly (PL 10.1.21) from the Motor Harness of the Duplex Motor Assembly (PL 10.1.11) .
7. Release the Duplex Harness Assembly A from the clamps on the Outer Chute.
8. Remove the three screws (Silver, M3x8mm) securing the Motor Bracket (PL 10.1.16) to the Outer Chute to remove the Motor Bracket.
9. Remove the Idle Gear 33.


Figure 2 Outer Chute


Figure 3 Duplex Motor Assembly

## Replacement

1. Install the Idle Gear 33.
2. Install the Motor Bracket (PL 10.1.16) to the Outer Chute (PL 10.2.5) using the three screws (Silver, M3x8mm).
3. Connect the junction connector (P/J212) of the Duplex Motor Harness Assembly (PL 10.1.21) to the Motor Harness of the Duplex Motor Assembly (PL 10.1.11) and secure the the Duplex Harness Assembly A with the clamps on the Outer Chute.
4. Install the Outer Chute and the Inner Chute (PL 10.2.6) to the Duplex Cover (PL 10.1.13) using four screws (Silver, M3x8mm).

## NOTE Be careful not to let the Duplex Stopper (PL 10.2.1) detach from the Outer Chute.

5. Install the Duplex Stopper to the Inner Chute.
6. Close the Inner Chute.
7. Install the Lower Chute (PL 10.1.8) to the Outer Chute using two screws (Silver, M3x8mm).
8. Install the Duplex Transport Unit (PL 10.1.1).

## RRP 10.5 Idle Gear 42

Removal

1. Remove the Duplex Transport Unit (PL 10.1.1).
2. Remove the two screws (Silver, M3x8mm) securing the Lower Chute (PL 10.1.8) to the Outer Chute (PL 10.2.5) to remove the Lower Chute.


Figure 1 Lower Chute
3. Open the Inner Chute (PL 10.2.6).
4. Release the hook of the Duplex Stopper (PL 10.2.1) securing the Outer Chute to the Inner Chute .
5. Remove the four screws (Silver, M3x8mm) securing the Outer Chute and the Inner Chute to the Duplex Cover (PL 10.1.13) to remove the Outer Chute and the Inner Chute.
6. Disconnect the junction connector (P/J212) of the Duplex Motor Harness Assembly (PL 10.1.21) from the Motor Harness of the Duplex Motor Assembly (PL 10.1.11) .
7. Release the Duplex Harness Assembly A from the clamps on the Outer Chute.
8. Remove the three screws (Silver, M3x8mm) securing the Motor Bracket (PL 10.1.16) to the Outer Chute to remove the Motor Bracket.
9. Remove the Idle Gear 42.


Figure 2 Outer Chute


Figure 3 Duplex Motor Assembly

## Replacement

1. Install the Idle Gear 42
2. Install the Motor Bracket (PL 10.1.16) to the Outer Chute (PL 10.2.5) using the three screws (Silver, M3x8mm).
3. Connect the junction connector (P/J212) of the Duplex Motor Harness Assembly (PL 10.1.21) to the Motor Harness of the Duplex Motor Assembly (PL 10.1.11) and secure the the Duplex Harness Assembly A with the clamps on the Outer Chute.
4. Install the Outer Chute and the Duplex Cover (PL 10.1.13) to the Inner Chute (PL 10.2.6) using four screws (Silver, M3x8mm).

NOTE Be careful not to let the Duplex Stopper (PL 10.2.1) detach from the Outer Chute.
5. Install the Duplex Stopper to the Inner Chute.
6. Close the Inner Chute.
7. Install the Lower Chute (PL 10.1.8) to the Outer Chute using two screws (Silver, M3x8mm).
8. Install the Duplex Transport Unit (PL 10.1.1) .

## RRP 10.6 I/L Switch, Cab

## Removal

1. Remove the Duplex Transport Unit (PL 10.1.1).
2. Remove the two screws (Silver, M3x8mm) securing the Lower Chute (PL 10.1.8) to the Outer Chute (PL 10.2.5) to remove the Lower Chute .


Figure 1 Lower Chute
3. Open the Inner Chute (PL 10.2.6).
4. Release the hook of the Duplex Stopper (PL 10.2.1) securing the Outer Chute to the Inner Chute .
5. Remove the four screws (Silver, M3x8mm) securing the Outer Chute and the Inner Chute to the Duplex Cover (PL 10.1.13) to remove the Outer Chute and the Inner Chute.
6. Disconnect the connector (P/J124) of the Duplex Sensor Harness Assembly (PL 10.1.20) from the I/L Switch, Cab.
7. Release the two hooks securing the I/L Switch, Cab to the Motor Bracket (PL 10.1.16) .
8. Remove the I/L Switch, Cab.


Figure 2 Outer Chute


Figure 3 Motor Bracket

## Replacement

1. Install the I/L Switch, Cab to the Motor Bracket (PL 10.1.16) using the two hooks.
2. Connect the connector (P/J124) of the Duplex Sensor Harness Assembly (PL 10.1.20) to the I/L Switch, Cab.
3. Install the Outer Chute (PL 10.2.5) and the Inner Chute (PL 10.2.6) to the Duplex Cover (PL 10.1.13) using four screws (Silver, M3×8mm).

## NOTE Be careful not to let the Duplex Stopper (PL 10.2.1) detach from the Outer Chute.

4. Install the Duplex Stopper to the Inner Chute.
5. Close the Inner Chute.
6. Install the Lower Chute (PL 10.1.8) to the Outer Chute using two screws (Silver, M3x8mm).
7. Install the Duplex Transport Unit (PL 10.1.1) .

## RRP 10.7 Duplex Actuator

## Removal

1. Remove the Duplex Transport Unit (PL 10.1.1) .
2. Remove the two screws (Silver, M3x8mm) securing the Lower Chute (PL 10.1.8) to the Outer Chute (PL 10.2.5) to remove the Lower Chute .


Figure 1 Lower Chute
3. Open the Inner Chute (PL 10.2.6).
4. Release the hook of the Duplex Stopper (PL 10.2.1) securing the Outer Chute to the Inner Chute .
5. Remove the four screws (Silver, M3x8mm) securing the Outer Chute and the Inner Chute to the Duplex Cover (PL 10.1.13) to remove the Outer Chute and the Inner Chute.
6. Remove the Duplex Actuator Spring (PL 10.1.15) from the Duplex Actuator and the Outer Chute .
7. Turn the Duplex Actuator by 180 degrees and move it in the direction of the arrow to remove.


Figure 2 Outer Chute


Figure 3 Duplex Actuator

## Replacement

1. Turn the Duplex Actuator by 180 degrees and move it in the opposite direction of the arrow to install
2. Hook the Duplex Actuator Spring (PL 10.1.15) to the Duplex Actuator and the Outer Chute.
3. Install the Outer Chute (PL 10.2.5) and the Inner Chute (PL 10.2.6) to the Duplex Cover (PL 10.1.13) using four screws (Silver, M3x8mm).

## NOTE Be careful not to let the Duplex Stopper (PL 10.2.1) detach from the Outer Chute.

4. Install the Duplex Stopper to the Inner Chute.
5. Close the Inner Chute.
6. Install the Lower Chute (PL 10.1.8) to the Outer Chute using two screws (Silver, M3x8mm).
7. Install the Duplex Transport Unit (PL 10.1.1) .

## RRP 10.8 Duplex Motor Assembly

## Removal

1. Remove the Duplex Transport Unit (PL 10.1.1) .
2. Remove the two screws (Silver, M3x8mm) securing the Lower Chute (PL 10.1.8) to the Outer Chute (PL 10.2.5) to remove the Lower Chute .


Figure 1 Lower Chute
3. Open the Inner Chute (PL 10.2.6).
4. Release the hook of the Duplex Stopper (PL 10.2.1) securing the Outer Chute to the Inner Chute .
5. Remove the four screws (Silver, M3x8mm) securing the Outer Chute and the Inner Chute to the Duplex Cover (PL 10.1.13) to remove the Outer Chute and the Inner Chute.
6. Disconnect the junction connector (P/J212) of the Duplex Motor Harness Assembly (PL 10.1.21) of the Duplex Motor Assembly (PL 10.1.11).
7. Release the Duplex Motor Harness Assembly from the clamps on the Outer Chute.
8. Remove the two screws (BIND, M3x6mm) securing the Duplex Motor Assembly to the Outer Chute .
9. Remove the Duplex Motor Assembly.
10. Remove the DUCT-DUP (PL 10.1.24) from the Duplex Motor Assembly.
11. Remove E-rings securing the Duplex Fan (PL 10.1.23) to the Duplex Motor Assembly, using a mini-screwdriver or the like.
12. Remove the Duplex Fan.


Figure 2 Outer Chute


Figure 3 Duplex Motor Assembly

## Replacement

1. Fit the Screw onto the shaft of the Duplex Motor Assembly and secure the screw with the Ering.

## NOTE Install the SCREW with the engraved mark facing outward.

2. Install the DUCT-DUP (PL 10.1.24) to the Duplex Motor Assembly.
3. Install the Duplex Motor Assembly to the Outer Chute (PL 10.2.5) using two screws (BIND, M3x6mm).
4. Connect the junction connector (P/J212) of the Duplex Motor Harness Assembly (PL 10.1.21) to the Duplex Motor Assembly (PL 10.1.11), and secure Duplex Motor Harness Assembly (PL 10.1.21) with the clamps on the Outer Chute.
5. Install the Outer Chute and the Inner Chute (PL 10.2.6) to the Duplex Cover (PL 10.1.13) using four screws (Silver, M3x8mm).

## NOTE Be careful not to let the Duplex Stopper (PL 10.2.1) detach from the Outer Chute.

6. Install the Duplex Stopper to the Inner Chute.
7. Close the Inner Chute.
8. Install the Lower Chute (PL 10.1.8) to the Outer Chute using two screws (Silver, M3x8mm).
9. Install the Duplex Transport Unit (PL 10.1.1) .

## RRP 10.9 Duplex PWBA

1. Remove the Duplex Transport Unit (PL 10.1.1).
2. Remove the two screws (Silver, M3x8mm) securing the Lower Chute (PL 10.1.8) to the Outer Chute (PL 10.2.5) to remove the Lower Chute.


Figure 1 Lower Chute
3. Open the Inner Chute (PL 10.2.6).
4. Release the hook of the Duplex Stopper (PL 10.2.1) securing the Outer Chute to the Inner Chute .
5. Remove the four screws (Silver, M3x8mm) securing the Outer Chute and the Inner Chute to the Duplex Cover (PL 10.1.13) to remove the Outer Chute and the Inner Chute.
6. Disconnect the three connectors (P/J540, P/J541 and P/J542) of Duplex Harness Assembly A (PL 10.1.22) from the Duplex PWBA .
7. Remove the two screws (Silver, M3x8mm) securing the Duplex PWBA to the Outer Chute.
8. Remove the Duplex PWBA.


Figure 2 Outer Chute


Figure 3 Duplex PWBA

## Replacement

1. Install the Duplex PWBA to the Outer Chute (PL 10.2.5) using two screws (Silver, M3x8mm).
2. Connect the three connectors (P/J540, P/J541 and P/J542) of Duplex Harness Assembly A (PL 10.1.22) to the Duplex PWBA.
3. Install the Outer Chute and the Inner Chute (PL 10.2.6) to the Duplex Cover (PL 10.1.13) using four screws (Silver, M3x8mm).

## NOTE Be careful not to let the Duplex Stopper (PL 10.2.1) detach from the Outer Chute.

4. Install the Duplex Stopper to the Inner Chute.
5. Close the Inner Chute.
6. Install the Lower Chute (PL 10.1.8) to the Outer Chute using two screws (Silver, M3x8mm).
7. Install the Duplex Transport Unit (PL 10.1.1) .

## RRP 10.10 Photo In Sensor

## Removal

1. Remove the Duplex Transport Unit (PL 10.1.1) .
2. Remove the two screws (Silver, M3x8mm) securing the Lower Chute (PL 10.1.8) to the Outer Chute (PL 10.2.5) to remove the Lower Chute .


FI3N003A1
Figure 1 Lower Chute
3. Open the Inner Chute (PL 10.2.6).
4. Release the hook of the Duplex Stopper (PL 10.2.1) securing the Outer Chute to the Inner Chute .
5. Remove the four screws (Silver, M3x8mm) securing the Outer Chute and the Inner Chute to the Duplex Cover (PL 10.1.13) to remove the Outer Chute and the Inner Chute.
6. Disconnect the connector (P/J123) of the Duplex Sensor Harness Assembly (PL 10.1.20)

7. Release the three hooks securing the Photo In Sensor to the Outer Chute as shown in the figure.
8. Remove the Photo In Sensor.


Figure 2 Outer Chute

## Replacement

1. Secure the Photo In Sensor to the Outer Chute (PL 10.2.5) using the three hooks.
2. Connect the connector ( $\mathrm{P} / \mathrm{J} 123$ ) of the Duplex Sensor Harness Assembly (PL 10.1.20) to the Photo In Sensor.
3. Install the Outer Chute and the Inner Chute (PL 10.2.6) to the Duplex Cover (PL 10.1.13) using f

NOTE Be careful not to let the Duplex Stopper (PL 10.2.1) detach from the Outer Chute.
4. Install the Duplex Stopper to the Inner Chute.
5. Close the Inner Chute.
6. Install the Lower Chute (PL 10.1.8) to the Outer Chute using two screws (Silver, M3x8mm).
7. Install the Duplex Transport Unit (PL 10.1.1) .


Figure 3 Photo In Sensor

## RRP 10.11 Duplex Roller A3L

## Removal

1. Remove the Duplex Transport Unit (PL 10.1.1).
2. Remove the Duplex PWBA (PL 10.1.12) .
3. Release the hook of the Duplex Bearing (PL 10.2.3) on the left and right to remove the Duplex Roller A3L from the Outer Chute (PL 10.2.5)
4. Remove the Duplex Roller A3L.

NOTE When removing, do not hold the rubber rollers of the Duplex Roller A3L.


Figure 1 Duplex Roller

## Replacement

1. Install the Duplex Roller A3L to the Outer Chute (PL 10.2.5).
2. Install the Duplex Bearing (PL 10.2.3) on right and left to secure the Duplex Roller A3L to the Outer Chute.

NOTE Insert the Duplex Bearing to the Outer Chute until it is locked firmly.
NOTE When installing, do not hold the rubber rollers of the Duplex Roller A3L.
3. Install the Duplex PWBA (PL 10.1.12) .
4. Install the Duplex Transport Unit (PL 10.1.1) .

## RRP 10.12 Duplex Roller Assembly

## Removal

1. Remove the Duplex Transport Unit (PL 10.1.1).
2. Remove the Duplex PWBA (PL 10.1.12).
3. Release the hook of the Duplex Bearing (PL 10.2.3) on left and right to remove the Duplex Roller Assembly to the Outer Chute (PL 10.2.5) .
4. Remove the Duplex Roller Assembly.

NOTE When removing, do not hold the rubber rollers of the Duplex Roller Assembly.


Figure 1 Duplex Roller Assembly

## Replacement

1. Install the Duplex Roller Assembly to the Outer Chute (PL 10.2.5).
2. Install the Duplex Bearing (PL 10.2.3) on right and left to secure the Duplex Roller Assembly to the Outer Chute.

NOTE Insert the Duplex Bearings to the Outer Chute until it is locked firmly.
NOTE When installing, do not hold the rubber rollers of the Duplex Roller Assembly.
3. Install the Duplex PWBA (PL 10.1.12) .
4. Install the Duplex Transport Unit (PL 10.1.1) .

## RRP 11 Exit 2

## RRP 11.1 Exit 2 Transport Assembly

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. While lifting the levers on both sides on the Exit 2 Transport Assembly, move it in the direction of the arrow to remove it .
3. When removing the Exit 2 Transport Assembly, since its left side is connected to the machine with a connector, it may require a little stronger force to remove it.


Figure 1 Transport Assembly

## Replacement

1. Install the Exit 2 Transport Assembly to the printer.
2. Move the levers in the opposite direction to lock the Exit 2 Transport Assembly to the printer.
3. Install it by aligning it with the guide on the machine. Also, be sure that the left side of the Exit 2 Transport Assembly is connected to the machine with a connector securely.
4. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 11.2 Inverter Roll Assembly

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Exit 2 Transport Assembly (PL 11.1.1) .
3. Open the Exit 2 Transport Assembly.
4. Remove the hook of the Exit 2 Stopper (PL 11.1.6) .
5. Remove the E-ring securing the FU Link (PL 11.1.23) to the Left Hand High Chute (PL 11.1.18).
6. Release the boss on the right side (front) of the Left Hand High Chute from the Lower Chute 2 (PL 11.2.33).
7. Release the boss on the left side (rear) of the Left Hand High Chute from the Lower Chute 2.

## NOTE Be sure to remove the right side (front) first, otherwise the Gear may be damaged.

8. Remove the Left Hand High Chute.


Figure 1 Chute
9. Remove the two screws (Silver, M3x8mm) securing the Left Hand High Chute to the Upper FU Chute (PL 11.1.5) to remove the Left Hand High Chute .
10. Remove the two screws (Silver, M3x8mm) securing the Gear Cover (PL 11.1.7) to the Left Hand High Chute to remove the Gear Cover .

## NOTE When removing the Gear Cover, note that Exit 2 Stopper may be detached together.

11. Remove the $52 Z$ Gear (PL 11.1.8) and the $19 Z$ Gear (PL 11.1.9).
12. Remove the E-ring securing the Inverter Roll Assembly to the Left Hand High Chute.


Figure 2 Upper Chute
13. Release the hook of the Bearing (PL 11.1.16) securing the Inverter Roll Assembly to the Left Hand High Chute.
NOTE The hook of the Bearing is easy to be damaged, therefore be careful when removing it.
14. Move the Inverter Roll Assembly in the direction of the arrow to remove.

NOTE When installing, do not hold the rubber rollers of the Inverter Roll Assembly.

## Replacement

1. Move the Inverter Roll Assembly in the opposite direction of the arrow to install it.

NOTE When removing, do not hold the rubber rollers of the Inverter Roll Assembly.
2. Secure the Inverter Roll Assembly to the Left Hand High Chute (PL 11.1.18) using the hook of the Bearing (PL 11.1.16).
NOTE The hook of the Bearing (PL 11.1.16) is easy to be damaged, therefore be careful when installing it.
3. Install the Inverter Roll Assembly to the Left Hand High Chute using the one E-ring.
4. Install the $19 Z$ Gear (PL 11.1.9) to the shaft (D-shaped) of the Inverter Roll Assembly.
5. Install the Gear Cover (PL 11.1.7) to the Left Hand High Chute together with the 52 Z Gear (PL 11.1.8) using two screws (Silver, M3x8mm).

NOTE Check that the Exit 2 Stopper (PL 11.1.6) is attached properly. When it is detached, install it by rotating the Gear Cover (PL 11.1.7) as shown in the figure.
6. Install the Left Hand High Chute to the Upper FU Chute (PL 11.1.5) using two screws (Silver, M3x8mm).
7. Fit the boss on the left side (rear) of the Left Hand High Chute into the hole on the Lower Chute 2 (PL 11.2.33).
8. Fit the boss on the right side (front) of the Left Hand High Chute into the hole on the Lower Chute 2 to install the Left Hand High Chute.


Figure 3 Gear Cover
9. Secure the FU Link (PL 11.1.23) to the Left Hand High Chute using the one E-ring.
10. Install the hook of the Exit 2 Stopper.
11. Close the Exit 2 Transport Assembly (PL 11.1.1).
12. Install the Exit 2 Transport Assembly .
13. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 11.3 Tray 2 Guide

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Exit 2 Transport Assembly (PL 11.1.1) .
3. Open the Exit 2 Transport Assembly.
4. Release the hook of the Exit 2 Stopper (PL 11.1.6).
5. Remove the E-ring securing the FU Link (PL 11.1.23) to the Left Hand High Chute (PL 11.1.18).
6. Release the boss on the right side (front) of the Left Hand High Chute from the Lower Chute 2 (PL 11.2.33).
7. Release the boss on the left side (rear) of the Left Hand High Chute from the Lower Chute 2.

NOTE Be sure to remove the right side (front) first, otherwise the Gear may be damaged.


Figure 1 Chute
8. Remove the Lower Chute 2 .
9. Remove the screw (Del Tite, M3x8mm) securing the Exit 2 Rear Cover (PL 11.1.26) to the Lower Chute 2.
10. Release the hook securing the Exit 2 Rear Cover to the Lower Chute 2, as shown in the figure.
11. Move the Exit 2 Rear Cover in the direction of the arrow to remove.
12. Remove the five screws (Silver, M3x8mm) securing the Tray 2 Guide to the Lower Chute 2.
13. Release the left and right (front/rear) hooks of the Tray 2 Guide securing it to the Lower Chute 2 and remove the Tray 2 Guide.


Figure 2 Lower Chute 2

## Replacement

1. Secure the Tray 2 Guide to the Lower Chute 2 (PL 11.2.33) with the left and right (front/rear) hooks.
2. Install the Tray 2 Guide to the Lower Chute 2 using five screws (Silver, M3x8mm).
3. Move the Exit 2 Rear Cover (PL 11.1.26) in the opposite direction of the arrow and install it with the hook.
4. Install the Exit 2 Rear Cover to the Lower Chute 2 using the one screw (Del Tite, M3x8mm).
5. Fit the boss on the left side (rear) of the Left Hand High Chute (PL 11.1.18) into the hole on the Lower Chute 2.
6. Fit the boss on the right side (front) of the Left Hand High Chute into the hole on the Lower Chute 2 and install the Lower Chute 2.
7. Secure the FU Link (PL 11.1.23) to the Left Hand High Chute using the one E-ring.
8. Install the hook of the Exit 2 Stopper (PL 11.1.6).
9. Close the Exit 2 Transport Assembly (PL 11.1.1).
10. Install the Exit 2 Transport Assembly .
11. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 11.4 Full B Actuator

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Exit 2 Transport Assembly (PL 11.1.1).
3. Open the Exit 2 Transport Assembly.
4. Remove the Tray Guide 2 (PL 11.2.1) .
5. Remove the Full A Actuator (PL 11.2.40) from the Actuator Spring (PL 11.2.42) .
6. Release the hook securing Full B Actuator to Tray 2 Guide (PL 11.2.1), as shown in the figure.

NOTE The hook of the Tray 2 Guide is easy to be damaged, therefore be careful when handling it.
7. Release the Actuator Spring from the hook of the Full B Actuator.


Figure 1 Full B Actuator

## Replacement

1. Install the Actuator Spring (PL 11.2.42) to the hook of the Full B Actuator.
2. Install the Full B Actuator to the Tray 2 Guide (PL 11.2.1) with the hook.

NOTE The hook of the Tray 2 Guide is easy to be damaged, therefore be careful when handling it.
3. Install the Full A Actuator (PL 11.2.40) to the Actuator Spring (PL 11.2.42).

NOTE When installing the Full A Actuator, fit the slit of the Full A Actuator to the Actuator Spring.
4. Install the Tray Guide 2 (PL 11.2.1) .
5. Close the Exit 2 Transport Assembly (PL 11.1.1).
6. Install the Exit 2 Transport Assembly
7. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 11.5 OCT Roll Assembly

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Exit 2 Transport Assembly (PL 11.1.1) .
3. Open the Exit 2 Transport Assembly.
4. Remove the Offset Gear 2 (PL 11.2.19)
5. Release the hook of the $19 Z$ Gear (PL 11.2.9) securing the OCT Roll Assembly to the Lower Chute 2 (PL 11.2.33) as shown in the figure to remove the $19 Z$ Gear .

NOTE The hook of the $19 Z$ Gear is easy to be damaged, therefore be careful when handling it.
6. Remove the two E-rings left and right securing the OCT Roll Assembly to the OCT Chute 2 (PL 11.2.5).
7. While releasing the hook of the Bearing (PL 11.2.3) on the left side securing the OCT Roll Assembly to the Lower Chute, remove the Bearing.
NOTE The hook of the Bearing is easy to be damaged, therefore be careful when handling it.
8. Move the OCT Roll Assembly in the direction of the arrow (to the front) to remove.

NOTE When removing, do not hold the rubber rollers of the OCT Roll Assembly.


Figure 1 OCT Roll Assembly

## Replacement

1. Move the OCT Roll Assembly in the opposite direction of the arrow to insert.

NOTE When installing, do not hold the rubber rollers of the OCT Roll Assembly.
2. Secure the Bearing (PL 11.2.3) to the Lower Chute 2 (PL 11.2.33) with the hook.

NOTE Insert the Bearing until the hook is firmly secured.
3. Install the OCT Roll Assembly to the OCT Chute 2 (PL 11.2.5) using the one E-ring.

NOTE Be careful not to bend the Spring (PL 11.2.11) installed on the OCT Chute 2.
4. Install the OCT Roll Assembly to the Lower Chute 2 with the hook of the $19 Z$ Gear (PL 11.2.9).

NOTE The hook of the $19 Z$ Gear is easy to be damaged, therefore be careful when handling it.
5. Install the Offset Gear 2 (PL 11.2.19) .
6. Close the Exit 2 Transport Assembly (PL 11.1.1).
7. Install the Exit 2 Transport Assembly .
8. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 11.6 Exit Pinch Roller

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Exit 2 Transport Assembly (PL 11.1.1) .
3. Open the Exit 2 Transport Assembly.
4. Remove the OCT Roll Assembly (PL 11.2.7) .
5. Release the hook securing the Exit Pinch Roller to the OCT Chute 2 (PL 11.2.5) .
6. Move the Exit Pinch Roller in the direction of the arrow to remove it.


Figure 1 Exit Pinch Roller

## Replacement

1. Move the Exit Pinch Roller in the opposite direction of the arrow and install it with the hook.
2. Install the OCT Roll Assembly (PL 11.2.7) .
3. Close the Exit 2 Transport Assembly (PL 11.1.1).
4. Install the Exit 2 Transport Assembly .
5. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 11.7 Exit Actuator

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Exit 2 Transport Assembly (PL 11.1.1) .
3. Open the Exit 2 Transport Assembly.
4. Remove the Tray Guide 2 (PL 11.2.1) .
5. Release the hook of the Actuator Spring (PL 11.2.34) .
6. Place the Exit Actuator in the position shown in the figure, move it in the direction of the arrow to release the hook on the Lower Chute securing the Exit Actuator.
7. Remove the Exit Actuator.
8. Remove the Actuator Spring attached to the Exit Actuator.


Figure 1 Exit Actuator

## Replacement

1. Install the Actuator Spring (PL 11.2.34).

## NOTE Be sure to install the Actuator Spring in the direction shown in the figure.

2. Move the Exit Actuator in the opposite direction of the arrow to install.

NOTE Check that the Exit Actuator goes into the gap (sensing area) of the Photo In Sensor (PL 11.2.35) smoothly.
3. Secure the hook of the Actuator Spring to the Exit Actuator.
4. Install the Tray Guide 2 (PL 11.2.1) .
5. Close the Exit 2 Transport Assembly (PL 11.1.1).
6. Install the Exit 2 Transport Assembly .
7. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 11.8 I/L CAB Switch

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Open the Exit 2 Transport Assembly (PL 11.1.1) .
3. Remove the Exit 2 Transport Assembly .
4. Remove the Tray Guide 2 (PL 11.2.1) .
5. Release the harness secured to the guide on the backside of the Lower Chute 2 (PL 11.2.33) .
6. Disconnect the connector (P/J116) of the Exit 2 C Harness Assembly (PL 11.2.36) from the I/L CAB Switch.


Figure 1 Harness Assembly
7. Release the hooks securing the I/L CAB Switch to the Lower Chute 2 .
8. Remove the I/L CAB Switch.


Figure 2 I/L Cab Switch

## Replacement

1. Secure the I/L CAB Switch to the Lower Chute 2 (PL 11.2.33) with the hooks.
2. Connect the connector ( $\mathrm{P} / \mathrm{J} 116$ ) of the Exit 2 C Harness Assembly (PL 11.2.36) to the $\mathrm{I} / \mathrm{L}$ CAB Switch.
3. Secure the harness to the guide on the backside of the LOWER CHUTE.

NOTE Be sure to put the three junction connectors into each guide.
4. Install the Tray Guide 2 (PL 11.2.1) .
5. Close the Exit 2 Transport Assembly (PL 11.1.1).
6. Install the Exit 2 Transport Assembly
7. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 11.9 Offset Gear 2

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Exit 2 Transport Assembly (PL 11.1.1) .
3. Open the Exit 2 Transport Assembly.
4. Remove the Tray Guide 2 (PL 11.2.1) .
5. Remove the screw (Del Tite, M3x8mm) securing the Exit 2 Front Cover (PL 11.1.25) to the Lower Chute 2 (PL 11.2.33) and remove the Exit 2 Front Cover .


Figure 1 Exit 2 Front Cover
6. Slide the OCT Roll Assembly (PL 11.2.7) fully to the right (Front) .
7. Move the Offset Gear 2 in the direction of the arrow to remove it from the shaft of the Lower Chute 2.
8. Remove the hook on the top of the Offset Gear 2 from the hole on the OCT Chute 2 (PL 11.2.5) to remove the Offset Gear 2.


Figure 2 Offset Gear 2

## Replacement

1. Secure the hook on the top of the Offset Gear 2 to the hole on the OCT Chute 2 (PL 11.2.5).
2. Slide the OCT Roll Assembly (PL 11.2.7) fully to the right (Front).
3. Move the Offset Gear 2 in the opposite direction of the arrow to install it to the shaft of the Lower Chute 2 (PL 11.2.33).
4. Install the Exit 2 Front Cover (Tentative PL 11.1.25) to the Lower Chute 2 (PL 11.2.33) using a screw (Del Tite, M3x8mm).
5. Install the Tray Guide 2 (PL 11.2.1).
6. Close the Exit 2 Transport Assembly (PL 11.1.1).
7. Install the Exit 2 Transport Assembly .
8. Close the Left Hand Cover Assembly (PL 4.2.8).
9. Open the Left Hand Cover Assembly (PL 4.2.8).
10. Remove the Exit 2 Transport Assembly (PL 11.1.1).
11. Open the Exit 2 Transport Assembly.
12. Remove the Tray Guide 2 (PL 11.2.1) .
13. Remove the screw (Del Tite, M3x8mm) securing the Exit 2 Front Cover (PL 11.1.25) to the Lower Chute 2 (PL 11.2.33) and remove the Exit 2 Front Cover .


Figure 1 Exit 2 Front Cover
6. Lift the harness and connector secured to the guide on the backside of the Lower Chute 2 .
7. Disconnect the harness connector ( $\mathrm{P} / \mathrm{J} 210$ ) of the FU Solenoid Assembly from the junction connector.
8. Remove the screw (Del Tite, M3x6mm) securing the FU Solenoid Assembly to the Lower Chute 2.
9. Remove the FU Solenoid Assembly.


Figure 2 FU Solenoid Assembly

## Replacement

1. Install the FU Solenoid Assembly to the Lower Chute 2 (PL 11.2.33) using a screw (Del Tite, M3x6mm).
NOTE Be sure to fit the iron core of the FU Solenoid Assembly to the Rear Latch Spring (PL 11.2.21) as shown in the figure. Also, put the boss on the Lower Chute 2 in to the hole on the FU Solenoid Assembly.
2. Connect the harness connector (P/J210) of the FU Solenoid Assembly to the junction connector.
3. Secure the harness to the guide on the backside of the Lower Chute 2.
4. Install the Exit 2 Front Cover (PL 11.1.25) to the Lower Chute 2 using a screw (Del Tite, M3x8mm).
5. Install the Tray Guide 2 (PL 11.2.1).
6. Close the Exit 2 Transport Assembly (PL 11.1.1).
7. Install the Exit 2 Transport Assembly .
8. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 11.11 Solenoid Assembly

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Exit 2 Transport Assembly (PL 11.1.1).
3. Open the Exit 2 Transport Assembly.
4. Remove the Tray Guide 2 (PL 11.2.1) .
5. Remove the screw (Del Tite, M3x8mm) securing the Exit 2 Front Cover (PL 11.1.25) to the Lower Chute 2 (PL 11.2.33) to remove the Exit 2 Front Cover .


Figure 1 Exit 2 Front Cover
6. Release the harness of the Solenoid Assembly from the guide on the Lower Chute 2 .
7. Release the harness of the Solenoid Assembly from the clamp.
8. Disconnect the harness connector (P/J209) of the Solenoid Assembly from the junction connector.
9. Remove the screw (Del Tite, M3x6mm) securing the Solenoid Assembly to the Lower Chute 2.
10. Remove the iron core of the Solenoid Assembly from the Exit Gate Link (PL 11.2.28).
11. Remove the Solenoid Assembly.


Figure 2 Solenoid Assembly

## Replacement

1. Install the Solenoid Assembly to the Lower Chute 2 (PL 11.2.33) using the one screw (Del Tite, M $3 \times 6 \mathrm{~mm}$ ).

NOTE Fit the iron core of the Solenoid Assembly to the Exit Gate Link (PL 11.2.28) as shown in the figure. Also, fit the boss on the Lower Chute 2 into the hole on the Solenoid Assembly.
2. Connect the harness connector (P/J209) of the Solenoid Assembly to the junction connector.
3. Secure the harness of the Solenoid Assembly to the clamp.
4. Secure the harness of the Solenoid Assembly to the guide on the Lower Chute 2.
5. Install the Exit 2 Front Cover (PL 11.1.25) to the Lower Chute 2 using the one screw (Del Tite, M3x8mm).
6. Install the Tray Guide 2 (PL 11.2.1) .
7. Close the Exit 2 Transport Assembly (PL 11.1.1).
8. Install the Exit 2 Transport Assembly .
9. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 11.12 Offset Motor Assembly

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Exit 2 Transport Assembly (PL 11.1.1) .
3. Open the Exit 2 Transport Assembly.
4. Remove the Tray Guide 2 (PL 11.2.1) .
5. Remove the FU Solenoid Assembly (PL 11.2.23) .
6. Disconnect the harness connector (P/J207) of the Exit 2 Motor Assembly (PL 11.2.37) from the junction connector .
7. Remove the two screws (Bind, M3x8mm) securing the Offset Motor Assembly to the Lower Chute 2 (PL 11.2.33).
8. Remove the Offset Motor Assembly.


Figure 1 Offset Motor Assembly

## Replacement

1. Secure the Offset Motor Assembly to the Lower Chute 2 (PL 11.2.33) using two screws (Bind, M3x8mm).
2. Connect the harness connector (P/J207) of the Exit 2 Motor Assembly (PL 11.2.37) to the junction connector.
3. Install the FU Solenoid Assembly (PL 11.2.23) .
4. Install the Tray Guide 2 (PL 11.2.1) .
5. Close the Exit 2 Transport Assembly (PL 11.1.1).
6. Install the Exit 2 Transport Assembly (PL 11.1.1) .
7. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 11.13 Photo In Sensor

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Exit 2 Transport Assembly (PL 11.1.1) .
3. Open the Exit 2 Transport Assembly.
4. Remove the Tray Guide 2 (PL 11.2.1) .
5. Disconnect the connector (P/J112) of the Exit 2 C Harness Assembly (PL 11.2.36) connected to the Photo In Sensor .
6. While moving the Exit Actuator (PL 11.2.17) in the direction of the arrow, remove the hook securing the Photo In Sensor to the Lower Chute 2 (PL 11.2.33) as shown in the figure.
7. Remove the Photo In Sensor.


Figure 1 Photo In Sensor

## Replacement

1. While moving the Exit Actuator (PL 11.2.17) in the direction of the arrow, install the Photo In Sensor to the Lower Chute 2 (PL 11.2.33) with the hook.
2. Connect the connector (P/J112) of the Exit 2 C Harness Assembly (PL 11.2.36) to the Photo In Sensor.
3. Install the Tray Guide 2 (PL 11.2.1) .
4. Close the Exit 2 Transport Assembly (PL 11.1.1).
5. Install the Exit 2 Transport Assembly .
6. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 11.14 OCT Photo In Position Sensor

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Exit 2 Transport Assembly (PL 11.1.1) .
3. Open the Exit 2 Transport Assembly.
4. Remove the Tray Guide 2 (PL 11.2.1) .
5. Remove the OCT Roll Assembly (PL 11.2.7) .
6. Disconnect the connector (P/J111) of the Exit 2 C Harness Assembly (PL 11.2.36) from the OCT Photo In Position Sensor .
7. Release the hook securing the OCT Photo In Position Sensor to the Lower Chute 2 (PL 11.2.33).
8. Remove the OCT Photo In Position Sensor.


Figure 1 Position Sensor

## Replacement

1. Install the OCT Photo In Position Sensor to the Lower Chute 2 (PL 11.2.33) with the hook.
2. Connect the connector ( $\mathrm{P} / \mathrm{J} 111$ ) of the Exit 2 C Harness Assembly (PL 11.2.36) to the OCT Photo In Position Sensor.
3. Install the OCT Roll Assembly (PL 11.2.7) .
4. Install the Tray Guide 2 (PL 11.2.1) .
5. Close the Exit 2 Transport Assembly (PL 11.1.1).
6. Install the Exit 2 Transport Assembly .
7. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 11.15 Exit 2 Motor Assembly

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Exit 2 Transport Assembly (PL 11.1.1) .
3. Open the Exit 2 Transport Assembly.
4. Remove the Tray Guide 2 (PL 11.2.1) .
5. Remove the screw (Del Tite, M3x8mm) securing the Exit 2 Front Cover (PL 11.1.25) to the Lower Chute 2 (PL 11.2.33) to remove the Exit 2 Front Cover .


Figure 1 Exit 2 Front Cover
6. Lift the harness and connector secured to the guide on the backside of the Lower Chute 2 .
7. Disconnect the harness connector (P/J208) of the Exit 2 Motor Assembly from the junction connector.
8. Remove the Exit Fan (PL 11.2.39) .
9. Disconnect the connector (P/J112) of the Exit 2 C Harness Assembly (PL 11.2.36) from the I/L CAB Switch (PL 11.2.53).
10. Remove the two screws (Del Tite, M3x10mm) securing the Exit 2 Connector to the Rear Plate Assembly (PL 11.2.20) to remove the Exit 2 Connector.
11. Remove the two screws (Silver, M3x8mm) securing the Rear Plate Assembly to the Lower Chute 2 to remove the Rear Plate Assembly.
12. Remove the two screws (M3x6mm) securing the Exit 2 Motor Assembly to the Rear Plate Assembly.
13. Remove the Exit 2 Motor Assembly.


Figure 2 Motor Assembly

## Replacement

1. Install the Exit 2 Motor Assembly to the Rear Plate Assembly (PL 11.2.20) using two screws (M3x6mm).
2. Install the Rear Plate Assembly to the Lower Chute 2 (PL 11.2.33) using two screws (Silver, M3x8mm).

## NOTE Install the Exit 2 Connector to the Rear Plate Assembly using two screws (Del Tite, M3x10mm).

3. Install the connector with its one end having more terminals facing toward the direction shown in the figure.
4. Connect the connector (P/J112) of the Exit 2 C Harness Assembly (PL 11.2.36) to the I/L CAB Switch (PL 11.2.18).
5. Install the Exit Fan (PL 11.2.39) .
6. Connect the harness connector (P/J208) of the Exit 2 Motor Assembly to the junction connector.
7. Secure the harness to the guide on the backside of the Lower Chute 2.
8. Install the Exit 2 Front Cover (PL 11.1.25) to the Lower Chute 2 using the one screw (Del Tite, M3x8mm).
9. Install the Tray Guide 2 (PL 11.2.1) .
10. Close the Exit 2 Transport Assembly (PL 11.1.1).
11. Install the Exit 2 Transport Assembly .
12. Close the Left Hand Cover Assembly (PL 4.2.8)

## RRP 11.16 Photo In Sensor

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Exit 2 Transport Assembly (PL 11.1.1) .
3. Open the Exit 2 Transport Assembly.
4. Remove the Tray Guide 2 (PL 11.2.1) .
5. Disconnect the connector (P/J113) of the Exit 2 C Harness Assembly (PL 11.2.36) connected to the Photo In Sensor.
6. Release the hooks securing the Photo In Sensor to the Lower Chute 2 (PL 11.2.33) as shown in the figure.
7. Remove the Photo In Sensor.


Figure 1 Photo In Sensor

## Replacement

1. Install the Photo In Sensor to the Lower Chute 2 (PL 11.2.33) with the hook.
2. Connect the connector (P/J113) of the Exit 2 C Harness Assembly (PL 11.2.36) to the Photo In Sensor.
3. Install the Tray Guide 2 (PL 11.2.1) .
4. Close the Exit 2 Transport Assembly (PL 11.1.1).
5. Install the Exit 2 Transport Assembly
6. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 11.17 Exit Fan

## Removal

1. Open the Left Hand Cover Assembly (PL 4.2.8).
2. Remove the Exit 2 Transport Assembly (PL 11.1.1) .
3. Open the Exit 2 Transport Assembly.
4. Remove the Tray Guide 2 (PL 11.2.1) .
5. Remove the screw (Del Tite, M3x8mm) securing the Exit 2 Front Cover (PL 11.1.25) to the Lower Chute 2 (PL 11.2.33) and remove the Exit 2 Front Cover .


Figure 1 Exit 2 Front Cover
6. Disconnect the harness of the Exit Fan from the junction connector (P/J606B)
7. Remove the harness of the Exit Fan from the hole in the Lower Chute (PL 11.2.33).
8. Remove the screw (Del Tite, M3x8mm) securing the Inner Cover (PL 11.2.44) to the Rear Plate Assembly (PL 11.2.20).
9. Lift the Inner Cover in the direction of the arrow.
10. Remove the screw (Del Tite, M3x8mm) securing the Exit Fan to the Inner Cover.
11. Release the harness of the Exit Fan from the clamp on the Inner Cover.
12. Remove the Exit Fan.


Figure 2 Exit Fan

## Replacement

1. Put the harness of the Exit Fan though the hole in the Lower Chute (PL 11.2.33).
2. Move the Inner Cover (PL 11.2.44) in the opposite direction of the arrow to install it to the Rear Plate Assembly (PL 11.2.20).
3. Secure the harness of the Exit Fan to the clamp on the Inner Cover.
4. Install the Exit Fan to the Inner Cover with the screw (Del Tite, M3x8mm).

NOTE Install the Exit Fan so that the label faces downward and the printed number comes to the rear.
5. Connect the harness of the Exit Fan to the junction connector (P/J606B).
6. Install the Inner Cover to the Rear Plate Assembly (PL 11.2.20) with the screw (Del Tite, M3x8mm).
7. Install the Exit 2 Front Cover (PL 11.1.25) to the Lower Chute 2 (PL 11.2.33) with the screw (Del Tite, M3x8mm).
8. Install the Tray Guide 2 (PL 11.2.1) .
9. Close the Exit 2 Transport Assembly (PL 11.1.1).
10. Install the Exit 2 Transport Assembly .
11. Close the Left Hand Cover Assembly (PL 4.2.8).

## RRP 12 Finisher Unit

## RRP 12.1 Transport Assembly

## Removal

1. Push the A portion of the H -Transport Connector Cover (PL 12.4.10) to disengage the lock from the Finisher, and remove it from the Finisher .
2. Disconnect the connection cable between the Transport Assembly and the Finisher.
3. Disengage the Finisher from the printer .


Figure 1 Finisher
4. Remove the two Screws (PL 12.1.1) on the right side .
5. Remove the Transport Assembly from the printer.


Figure 2 Transport Assembly

## Replacement

1. Place the Transport Assembly on the printer.
2. Secure the Transport Assembly to the right side of the printer using the two Screws (PL 12.1.1).
3. Move the Finisher toward the printer to engage them .
4. Connect the connection cable of the Transport Assembly to the Finisher.
5. Attach the H -Transport Connector Cover (PL 12.4.10) to the Finisher.

## NOTE Check that the H -Transport Connector Cover is securely attached to the Finisher.

## RRP 12.2 Staple Finisher

## Removal

1. Disconnect the power cord and connection cable of the Finisher from the rear side of the printer .
2. Remove the H -Transport Connector Cover (PL 12.4.10) on the rear side of the Finisher.
3. Disconnect the cable of the Transport Assembly from the Finisher.
4. Open the Front Cover Assembly (PL 12.5.3) on the front side of the Finisher.
5. Move the Finisher to the right while pulling the Docking Plate (PL 12.5.6) toward you .
6. Close the Front Cover Assembly.


Figure 1 Finisher


Figure 2 Docking Plate

## Replacement

1. Open the Front Cover Assembly (PL 12.5.3).
2. While pulling the Docking Plate (PL 12.5.6) toward you, move the Finisher to the left so that the bosses on the IOT Docking Plate Assembly (PL 12.5.10) attached to the printer fit to the holes on the Docking Plate on the Finisher .
3. Remove your hand from the Docking Plate to engage the IOT Docking Plate Assembly with the Docking Plate.
4. Close the Front Cover Assembly.
5. Connect the cable of the Transport Assembly to the rear side of the Finisher.
6. Attach the H -Transport Connector Cover (PL 12.4.10).
7. Connect the power cord and connection cable of the Finisher to the rear side of the printer.


Figure 3 Docking Plate

## RRP 12.3 Rear Cover

## Removal

1. Remove the two Screws (TP M3 x 8) securing the Rear Cover .
2. Remove the two hooks of the Rear Cover, and move it in the direction of the arrow to remove it from the H -Transport.


Figure 1 H Transport

1. Move the Rear Cover in the opposite direction of the arrow to install it to the Lower Chute Assembly (PL 12.3.27) with two hooks, and secure it using two Screws (TP M3 x 8).

## NOTE When installing the Rear Cover, be careful not to pinch the harness.

## RRP 12.4 Top Cover Assembly

## Removal

1. Remove the Rear Cover (PL 12.3.1).
2. Open the Top Cover Assembly.
3. Remove the six Screws (TP M3 x 6) securing the Left Hinge Assembly (PL 12.2.2) and the Right Hinge Assembly (PL 12.2.3) to the Drive Bracket (PL 12.3.5) on the Lower Chute Assembly (PL 12.3.27) .
4. Remove the Top Cover Assembly in the direction of the arrow.


Figure 1 Top Cover Assembly

## Replacement

1. Install the Top Cover Assembly to the Drive Bracket (PL 12.3.5) so that the square holes on the Top Cover Assembly fit to the two hooks at left and right on the Drive Bracket.
2. Secure the Top Cover Assembly using six Screws (TP M3 $\times 6$ ).
3. Close the Top Cover Assembly.
4. Install the Rear Cover (PL 12.3.1) .

## RRP 12.5 Drive Belt

1. Remove the Rear Cover (PL 12.3.1) .
2. Remove the E-ring securing the Drive Pulley (PL 12.3.3).
3. Remove the Drive Pulley and the Drive Belt together from the D-Belt Roller Assembly (PL 12.3.14)


Figure 1 Drive Belt


Figure 2 Drive Pulley

## Replacement

1. Place the Drive Belt onto the Drive Pulley (PL 12.3.3) and the pulley of the Motor Assembly (PL 12.3.7), and install the Drive Pulley to the D-Belt Roller Assembly (PL 12.3.14).

NOTE Be sure to install the Drive Pulley to the D-Belt Roller Assembly in the direction shown in the figure.
2. Secure the Drive Pulley to the D-Belt Roller Assembly using the E-ring.
3. Install the Rear Cover (PL 12.3.1) .

## RRP 12.6 D-Belt Roller Assembly

## Removal

1. Remove the Rear Cover (PL 12.3.1) .
2. Remove the Drive Belt (PL 12.3.2) and the Drive Pulley (PL 12.3.3) .
3. Remove the Bearing (PL 12.3.4) on the rear side .
4. Open the Top Cover Assembly (PL 12.2.9).
5. Remove the E-ring on the front.
6. Remove the Bearing (PL 12.3.11) on the front from the D-Belt Roller Assembly .
7. After moving the D-Belt Roller Assembly in the direction of the arrow to remove it from the hole on the Lower Chute (PL 12.3.25), and then remove D-Belt Roller Assembly from the hole on the Drive Bracket (PL 12.3.5)
8. Remove the D-Belt Roller Assembly from the two Transport Belts (PL 12.3.12).


Figure 1 Top Cover Assembly


Figure 2 Belt Transport

## Replacement

1. Put the D-Belt Roller Assembly through the two Transport Belts (PL 12.3.12).
2. Move the D-Belt Roller Assembly in the opposite direction of the arrow, and put it into the holes of the Drive Bracket (PL 12.3.5) and the Lower Chute (PL 12.3.25).
3. Install the Bearing (PL 12.3.11) to the D-Belt Roller Assembly on the front.
4. Secure the Bearing to the Lower Chute using the E-ring.
5. Install the Bearing (PL 12.3.4) to the D-Belt Roller Assembly on the rear.
6. Install the Drive Belt (PL 12.3.2) and the Drive Pulley (PL 12.3.3) .
7. Close the Top Cover Assembly (PL 12.2.9).
8. Install the Rear Cover (PL 12.3.1) .

## RRP 12.7 I-Belt Roller Assembly

## Removal

1. Open the Top Cover Assembly (PL 12.2.9).
2. Push the two Cover Bearings in the direction of the arrow to release the hooks, and remove them from the Lower Chute (PL 12.3.25) .
3. Remove the E-ring on the front of the I-Belt Roller Assembly.
4. Remove the Bearing (PL 12.3.10).
5. Move the I-Belt Roller Assembly in the direction of the arrow to remove it from the Bearing Bracket (PL 12.3.16).
6. Remove the I-Belt Roller Assembly from the two Transport Belts (PL 12.3.12) .
7. Remove the E-ring attached to the I-Belt Roller Assembly, and remove the Ball Bearing (PL 12.3.10).


Figure 1 Lower Chute


Figure 21 Belt Roller Assembly

## Replacement

1. Install the Ball Bearing (PL 12.3.10) to the I-Belt Roller Assembly and secure it using the Ering.
2. Put the I-Belt Roller Assembly through the two Transport Belts (PL 12.3.12) with the Ball Bearing facing the rear side.
3. Install the I-Belt Roller Assembly to the Bearing Bracket (PL 12.3.16) on the rear, and put the Ball Bearing into the hole of the Bearing Bracket.
4. Put the Ball Bearing through the I-Belt Roller Assembly on the front, and put it into the hole on the Bearing Bracket.
5. Secure the Ball Bearing using the E-ring.
6. Install the two Cover Bearings to the Lower Chute (PL 12.3.25), and secure them with the hooks.
7. Close the Top Cover Assembly (PL 12.2.9).

## RRP 12.8 Support Roller

## Removal

1. Open the Top Cover Assembly (PL 12.2.9).
2. Remove the D-Belt Roller Assembly (PL 12.3.14) or the I-Belt Roller Assembly (PL 12.3.15).
3. Put the Transport Belt (PL 12.3.12) aside, and lift the Support Roller up in the direction of the arrow to remove the Support Roller from the Lower Chute (PL 12.3.25) .
4. Remove the Support Roller Bearings (PL 12.3.28) from the both ends of the Support Roller.


Figure 1 Lower Chute

## Replacement

1. Install the Support Roller Bearings (PL 12.3.28) to both ends of the Support Roller in the direction shown in the figure.
2. Put the Transport Belt (PL 12.3.12) aside, and move the Support Roller in the opposite direction of the arrow to install it to the Lower Chute (PL 12.3.25).

## NOTE Install the Support Roller to the Lower Chute so that the flat surface of the Support Roller Bearing faces the direction shown in the figure.

3. Install the D-Belt Roller Assembly (PL 12.3.14) or the I-Belt Roller Assembly (PL 12.3.15).
4. Close the Top Cover Assembly (PL 12.2.9).

## RRP 12.9 Transport Belt

## Removal

1. Remove the Rear Cover (PL 12.3.1) .
2. Open the Top Cover Assembly (PL 12.2.9).
3. Remove the D-Belt Roller Assembly (PL 12.3.14) .
4. Remove the I-Belt Roller Assembly (PL 12.3.15) .
5. Remove the Support Roller (PL 12.3.13) .
6. Remove the Transport Belt from the Lower Chute (PL 12.3.25) .


Figure 1 Lower Chute

## Replacement

1. Place the Transport Belt in the position shown in the figure on the Lower Chute (PL 12.3.25).
2. Install the Support Roller (PL 12.3.13) .
3. Install the I-Belt Roller Assembly (PL 12.3.15) .
4. Install the D-Belt Roller Assembly (PL 12.3.14).
5. Close the Top Cover Assembly (PL 12.2.9).
6. Install the Rear Cover (PL 12.3.1) .

## RRP 12.10 Motor Assembly

## Removal

1. Remove the Rear Cover (PL 12.3.1) .
2. Remove the Drive Belt (PL 12.3.2) .
3. Disconnect the harness connector (P/J8379) of the Motor Assembly from the H-Transport Unit Harness Assembly (PL 12.3.26) .
4. Release the harness of the Motor Assembly from the Bush Saddle.
5. Open the Top Cover Assembly (PL 12.2.9).
6. Remove the two Screws securing the Motor Cover (PL 12.3.6) to remove the Motor Cover
7. Remove the two Screws (+ M3 x 6) securing the Motor Assembly to the Drive Bracket, and move the Motor Assembly in the direction of the arrow to remove.


Figure 1 H Transport


Figure 2 Motor Assembly

## Replacement

1. Put the Motor Assembly into the hole of the Drive Bracket (PL 12.3.5) in the direction shown in the figure, and secure it using two Screws (+ M3 $\times 6$ ) after moving it in the opposite direction of the arrow.
2. Install the Motor Cover (PL 12.3.6) using two Screws (M3 x 6).
3. Secure the harness of the Motor Assembly using the Bush Saddle.
4. Connect the harness connector (P/J8379)) of the Motor Assembly to the H-Transport Unit Harness Assembly (PL 12.3.26).
5. Close the Top Cover Assembly (PL 12.2.9).
6. Install the Drive Belt (PL 12.3.2) .
7. Install the Rear Cover (PL 12.3.1) .

## RRP 12.11 Left Top Cover

## Removal

1. Remove the Rear Cover (PL 12.3.1) .
2. Open the Top Cover Assembly (PL 12.2.9).
3. Remove the two Screws (WP M3 x 8) securing the Left Top Cover to the Lower Chute (PL 12.3.25) to remove the Left Top Cover .


Figure 1 Left Top Cover

## Replacement

1. Install the Left Top Cover to the Lower Chute (PL 12.3.25) using two Screws (WP M3 $\times 8$ ).
2. Close the Top Cover Assembly (PL 12.2.9).
3. Install the Rear Cover (PL 12.3.1) .

## RRP 12.12 DL PI-Sensor (H-Transport Interlock Sensor)

## Removal

1. Place the Transport Assembly (PL 12.1.2) up side down.
2. Remove the one Screw (Tapping M3 x 8) securing the IL Sensor Bracket (PL 12.3.20) to the Lower Chute (PL 12.3.25) to remove the IL Sensor Bracket .
3. Disconnect the connector (P/J8382) of the H-Transport Unit Harness Assembly (PL 12.3.26) from the DL PI-Sensor.
4. Release the hooks securing the DL PI-Sensor to the IL Sensor Bracket to remove the DL PISensor.


Figure 1 PI DL Sensor

## Replacement

1. Secure the DL PI-Sensor to the IL Sensor Bracket (PL 12.3.20) using the hooks.
2. Connect the connector ( $\mathrm{P} / \mathrm{J8382}$ ) of the H -Transport Unit Harness Assembly (PL 12.3.26) to the DL PI-Sensor.
3. Install the IL Sensor Bracket to the Lower Chute (PL 12.3.25) using one Screw (Tapping M3 $x 8$ ).
4. Place the Transport Assembly (PL 12.1.2) to the original position.

## RRP 12.13 Sensor Assembly (H-Transport Entrance Sensor)

## Removal

1. Place the Transport Assembly (PL 12.1.2) up side down.
2. Remove the one Screw (Tapping M3 $\times 8$ ) securing the Sensor Bracket (PL 12.3.24) to the Lower Chute (PL 12.3.25) to remove the Sensor Bracket .
3. Disconnect the connector (P/J8380) of the H-Transport Unit Harness Assembly (PL 12.3.26) from the Sensor Assembly.
4. Release the hooks securing the Sensor Assembly to the Sensor Bracket to remove the Sensor Assembly.


Figure 1 H Transport Sensor

## Replacement

1. Secure the Sensor Assembly to the Sensor Bracket (PL 12.3.24) using the hooks.
2. Connect the connector (P/J8380) of the H-Transport Unit Harness Assembly (PL 12.3.26) to the Sensor Assembly.
3. Install the Sensor Bracket to the Lower Chute (PL 12.3.25) using one Screw (Tapping M3 x 8).
4. Place the Transport Assembly (PL 12.1.2) to the original position.

## RRP 12.14 Sensor (H-Transport Exit Sensor)

## Removal

1. Place the Transport Assembly (PL 12.1.2) up side down.
2. Remove the one Screw (Tapping M3 $\times 8$ ) securing the Sensor Bracket (PL 12.3.22) to the Lower Chute (PL 12.3.25) to remove the Sensor Bracket .
3. Disconnect the connector (P/J8381) of the H-Transport Unit Harness Assembly (PL 12.3.26) from the Sensor.
4. Release the hooks securing the Sensor to the Sensor Bracket to remove the Sensor.


Figure 1 Exit Sensor

## Replacement

1. Secure the Sensor to the Sensor Bracket (PL 12.3.22) using the hooks.
2. Connect the connector (P/J8381) of the H-Transport Unit Harness Assembly (PL 12.3.26) to the Sensor.
3. Install the Sensor Bracket to the Lower Chute (PL 12.3.25) using one Screw (Tapping M3 x 8).
4. Place the Transport Assembly (PL 12.1.2) to the original position.

## RRP 12.15 Top Cover

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11).
3. Remove the SCT Tray Assembly (PL 12.4.3) .
4. Remove the two Screws each on the front and rear securing the Top Cover to the Finisher .
5. Remove the Top Cover.


Figure 1 Top Cover

## Replacement

1. Install the Top Cover to the Finisher using four Screws.
2. Install the SCT Tray Assembly (PL 12.4.3) .
3. Install the Upper Rear Cover (PL 12.4.11) .
4. Close the Front Cover Assembly (PL 12.5.3).
5. Loosen the two Screws (M3 x 8) securing the SCT Tray Assembly to the Finisher .
6. Lift the SCT Tray Assembly in the direction of the arrow to remove it from the Finisher.


Figure 1 SCT Tray Assembly

## Replacement

1. Put the four bosses on the top edge of the SCT Tray Assembly into the four holes on the Finisher, and move it in the opposite direction of the arrow to install.
2. Secure the SCT Tray Assembly to the Finisher using two Screws (M3 x 8).

NOTE Make sure that the SCT Tray Assembly moves smoothly when the SCT Tray Assembly is pushed down once and then released by hand.

## RRP 12.17 Eject Cover

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the two Screws ( $\mathrm{M} 3 \times 8$ ) securing the Eject Cover to the Finisher .
4. Remove the Eject Cover.


Figure 1 Eject Cover

## Replacement

1. Install the Eject Cover to the Finisher using two Screws (M3 x 8).
2. Install the Upper Rear Cover (PL 12.4.11) .
3. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.18 Stacker Tray Assembly

## Removal

1. Release the hooks left and right on the lower part of the Stacker Tray Assembly, and lift the Stacker Tray Assembly up to remove it from the Tray Carriage (PL 12.6.1) .


Figure 1 Stacker Tray Assembly

## Replacement

1. Move the Stacker Tray Assembly in the opposite direction of the arrow to install it to the Tray Carriage (PL 12.6.1).
2. Secure the Stacker Tray Assembly to the Tray Carriage using the hooks on left and right.

NOTE Make sure that the two hooks on the Stacker Tray Assembly are put into the square holes on the Tray Carriage.

## RRP 12.19 Bottom Cover

## Removal

1. Remove the two Screws ( $\mathrm{M} 3 \times 8$ ) securing the Bottom Cover to the Finisher .
2. Remove the Bottom Cover.


Figure 1 Bottom Cover

## Replacement

1. Install the Bottom Cover to the Finisher using two Screws (M3 $\times 8$ ).

NOTE When installing the Bottom Cover, be sure to put the power cord into the notch on the Bottom Cover.

## RRP 12.20 Lower Rear Cover

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11).
2. Remove the four Screws ( $\mathrm{M} 3 \times 8$ ) securing the Lower Rear Cover to the Finisher .
3. Remove the Lower Rear Cover.


Figure 1 Lower Rear Cover

## Replacement

1. Install the Lower Rear Cover to the Finisher using four Screws (M3 $\times 8$ ).
2. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.21 Upper Rear Cover

## Removal

1. Release the lock of the H-Transport Connector Cover (PL 12.4.10) by pushing the A portion to remove.
2. Disconnect the cable from the Finisher.
3. Remove the four Screws ( $\mathrm{M} 3 \times 8$ ) securing the Upper Rear Cover to the Finisher .
4. Remove the Upper Rear Cover from the Finisher.


COVER REAR UPPER
(PL25.4.11)

Figure 1 Upper Rear Cover

## Replacement

1. Install the Upper Rear Cover to the Finisher using four Screws (M3 $\times 8$ ).
2. Connect the cable to the connector of the Finisher.
3. Install the H-Transport Connector Cover (PL 12.4.10).

NOTE Make sure that the H-Transport Connector Cover is securely locked to the Finisher.

## RRP 12.22 Top Front Cover

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the SCT Tray Assembly (PL 12.4.3) .
3. Remove the two Screws ( $\mathrm{M} 3 \times 8$ ) securing the Top Front Cover to the Finisher .
4. Remove the Top Front Cover.


Figure 1 Top Front Cover

## Replacement

1. Install the Top Front Cover to the Finisher using two Screws (M3 $\times 8$ ).
2. Install the SCT Tray Assembly (PL 12.4.3) .

NOTE Make sure that the SCT Tray Assembly moves smoothly when the SCT Tray Assembly is pushed down once and then released by hand.
3. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.23 Interlock Switch (Finisher Front Door Switch)

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Pull the Dust Box Assembly (PL 12.7.20) toward the front to remove it from the Finisher.
3. Remove the three Screws on the front side and one Screw on the rear side securing the Dust Box Chute Assembly to the Finisher to remove the Dust Box Chute Assembly .
4. Disconnect the connector (J8365) of the Interlock Harness Assembly (PL 12.12.11) from the Interlock Switch.
5. Release the hooks of the Interlock Switch to remove.


Figure 1 Front Door Interlock Switch

## Replacement

1. Secure the Interlock Switch to the frame using the hooks.
2. Connect the connector (J8365) of the Interlock Harness Assembly (PL 12.12.11) to the Interlock Switch.
3. Install the Dust Box Chute Assembly to the Finisher using the three Screws on the front side and one Screw on the rear side.
4. Install the Dust Box Assembly (PL 12.7.20) to the Finisher.
5. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.24 Front Cover Assembly

## Removal

1. Open the Front Cover Assembly.
2. Remove the three Screws (M3 x 8) securing the Inner Cover (PL 12.5.5) on the Front Cover Assembly to the Finisher .
3. Remove the Front Cover Assembly.


Figure 1 Front Cover Assembly

## Replacement

1. Install the Inner Cover (PL 12.5.5) on the Front Cover Assembly to the Finisher using three Screws (M3 x 8).
2. Close the Front Cover Assembly.

NOTE Make sure that the rib of the Front Cover Assembly actuates the Interlock Switch (PL 12.5.2) without contacting the bracket of the switch.

NOTE Make sure that the two magnets on the Front Cover Assembly are fully attracted to the Finisher.

## RRP 12.25 Inner Cover

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the four Screws ( $\mathrm{M} 3 \times 8$ ) securing the Inner Cover to the Front Cover Assembly .
3. Remove the Inner Cover.


Figure 1 Inner Cover

## Replacement

1. Install the Inner Cover to the Front Cover Assembly (PL 12.5.3) using four Screws (M3 x 8).
2. Install the Front Cover Assembly .

## RRP 12.26 Left Hand Front Cover

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the two Screws ( $\mathrm{M} 3 \times 8$ ) securing the Left Hand Front Cover to the Finisher
3. Remove the Left Hand Front Cover.


F13P012A1
Figure 1 Left Hand Front Cover

## Replacement

1. Install the Left Hand Front Cover to the Finisher using two Screws ( $\mathrm{M} 3 \times 8$ ).
2. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.27 Left Hand Top Cover

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the two Screws (M3 x 8) securing the Left Hand Top Cover to the Finisher .
3. Move the Left Hand Top Cover to the front side to remove it from the Finisher.


Figure 1 Left Hand Top Cover

## Replacement

1. Move the Left Hand Top Cover to the rear to put the hooks on the Left Hand Top Cover to the Finisher, and secure it using two Screws (M3 x 8).
2. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.28 Left Carriage Assembly

NOTE Be sure not to remove Right Carriage Assembly (Rear Side) and Left Carriage Assembly (Front Side) together. When removing them, work on one at a time. After finishing the repairing operation for one of them, work on another.

NOTE When removing both of them at the same time, it may cause an out of phase at the front and rear of Stacker Tray Assembly (PL 12.4.5).

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11).
2. Remove the Front Cover Assembly (PL 12.5.3) .
3. Move the Document Pulley Clutch (PL 12.6.19) on the rear side of the Finisher in the direction of the arrow by hand to move the Stacker Tray Assembly (PL 12.4.5) to its lowest position.

NOTE At this time, be sure not to touch the Encoder (PL 12.6.23).
NOTE Be sure to move the Stacker Tray Assembly to the lowest position before performing the subsequent steps.
4. Remove the two Screws securing the Tray Carriage (PL 12.6.1).
5. Remove the Spring (PL 12.6.6) on the Left Carriage Assembly.
6. Remove the Screw (TP M3 x 8) securing upper side of the Belt Clamp (PL 12.6.5).
7. Remove upper side of the Belt Clamp. Then, the Left Carriage Assembly with the Stacker Belt (PL 12.6.3) is detached from the Finisher.


Figure 1 Clutch Pulley


Figure 2 Tray Carriage

## Replacement

1. Put the Stacker Belt (PL 12.6.3) of the Left Carriage Assembly onto the Pulley T18s (PL 12.6.16) on the top and bottom of the Finisher.
2. Install the upper side of the Belt Clamp (PL 12.6.5) to the Left Carriage Assembly using one Screw (TP M3 x 8).
NOTE Be sure to put the boss on the backside of the Belt Clamp into the hole on the Left Carriage Assembly.
3. Hook the Spring (PL 12.6.6) to the upper and lower sides of the Belt Clamp.
4. Install the Tray Carriage (PL 12.6.1) using two Screws.

NOTE Make sure that the Stacker Tray Assembly (PL 12.4.5) is installed horizontally.
5. Install the Front Cover Assembly (PL 12.5.3) .
6. Install the Upper Rear Cover (PL 12.4.11) .

NOTE Make sure that the Stacker Tray Assembly moves smoothly up and down.

## RRP 12.29 Right Carriage Assembly

NOTE Be sure not to remove Right Carriage Assembly (Rear Side) and Left Carriage Assembly (Front Side) together. When removing them, work on one at a time. After finishing the repairing operation for one of them, work on another.

NOTE When removing both of them at the same time, it may cause the out of phase at the front and rear of Stacker Tray Assembly (PL 12.4.5).

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11).
2. Remove the Lower Rear Cover (PL 12.4.9) .
3. Move the Document Pulley Clutch (PL 12.6.19) on the rear side of the Finisher in the direction of the arrow by hand to move the Stacker Tray Assembly (PL 12.4.5) to its lowest position.

NOTE At this time, be sure not to touch the Encoder (PL 12.6.23).
NOTE Be sure to move the Stacker Tray Assembly to the lowest position before performing the subsequent steps.
4. Remove the Stacker Bracket Assembly (PL 12.6.24) .
5. Remove the two Screws securing the Tray Carriage (PL 12.6.1) .
6. Remove the Spring (PL 12.6.6) on the Right Carriage Assembly.
7. Remove the one Screw (TP M3 x 8) securing the upper side of the Belt Clamp.
8. Remove upper side of the Belt Clamp.

Then, the Right Carriage Assembly with the Stacker Belt is detached from the Finisher.


Figure 1 Clutch Pulley


Figure 2 Tray Carriage

## Replacement

1. Put the Stacker Belt on the Right Carriage Assembly onto the Document Pulley Clutch (PL 12.6.18) and the Pulley T18 (PL 12.6.16) on the top and bottom of the Finisher.
2. Install the upper side of the Belt Clamp to the Right Carriage Assembly using one Screw (TP M3 x 8) .

NOTE Be sure to put the boss on the backside of the Belt Clamp into the hole on the Right Carriage Assembly.
3. Hook the Spring (PL 12.6.6) to the upper and lower sides of the Belt Clamp.
4. Install the Tray Carriage (PL 12.6.1) using two Screws.

NOTE Make sure that the Stacker Tray Assembly (PL 12.4.5) is installed horizontally.
5. Install the Stacker Bracket Assembly (PL 12.6.24) .
6. Install the Lower Rear Cover (PL 12.4.9) .
7. Install the Upper Rear Cover (PL 12.4.11) .

NOTE Make sure that the Stacker Tray Assembly moves smoothly up and down.

## RRP 12.30 Cover Assembly Sensor (Stacker Height Sensor 1)

NOTE Two Cover Assembly Sensors (PL 12.6.13) are installed to the Finisher, one is Stacker Height Sensor 1 attached to the front and the other is Stacker Height Sensor 2 attached to the rear. The removal and replacement procedures for Stacker Height Sensor 1 are described here.

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Disconnect the connector (J8331) of the Main Sensor Harness Assembly from the Cover Assembly Sensor (Stacker Height Sensor 1) .
3. Remove the one Screw ( $\mathrm{M} 3 \times 8$ ) securing the Cover Assembly Sensor.
4. Remove the Cover Assembly Sensor.


Figure 1 Stacker Height Sensor 1

## Replacement

1. Install the Cover Assembly Sensor (Stacker Height Sensor 1) to the Finisher using one Screw (M3 x 8).
NOTE Put the two bosses on the Cover Assembly Sensor into the two holes on the frame of the Finisher.
2. Connect the connector (J8331) of the Main Sensor Harness Assembly to the Cover Assembly Sensor.
3. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.31 Cover Assembly Sensor (Stacker Height Sensor 2)

NOTE Two Cover Assembly Sensors (PL 12.6.13) are installed to the Finisher, one is Stacker Height Sensor 1 attached to the front and the other is Stacker Height Sensor 2 attached to the rear. The removal and replacement procedures for Stacker Height Sensor 2 are described here

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11) .
2. Disconnect the connector (J8330) of the Main Sensor Harness Assembly from the Cover Assembly Sensor (Stacker Height Sensor 2) .
3. Remove the one Screw (M3 x 8) securing the Cover Assembly Sensor.
4. Remove the Cover Assembly Sensor.


Figure 1 Stacker Height Sensor 2

## Replacement

1. Install the Cover Assembly Sensor (Stacker Height Sensor 2) to the Finisher using one Screw (M3 x 8).

## NOTE Put the two bosses on the Cover Assembly Sensor into the two holes on the frame of the Finisher.

2. Connect the connector (J8330) of the Main Sensor Harness Assembly to the Cover Assembly Sensor.
3. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.32 Sensor (Stacker Encode Sensor)

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11).
2. Disconnect the connector (J8328) of the Main Sensor Harness Assembly (PL 12.15.1) from the Sensor (Stacker Encode Sensor) .
3. Release the Main Sensor Harness Assembly from the harness clamp.
4. Remove the one Screw ( $\mathrm{M} 3 \times 6$ ) securing the Bracket Assembly (PL 12.6.22) to remove it from the Stacker Bracket Assembly (PL 12.6.24).
5. Release the hooks of the Sensor to remove it from the Bracket Assembly.


Figure 1 Stacker Encoder Sensor

## Replacement

1. Secure the Sensor (Stacker Encode Sensor) to the Bracket Assembly (PL 12.6.22) using the hooks.
2. Install the Bracket Assembly to the Stacker Bracket Assembly (PL 12.6.24) using one Screw (M3 x 6).
3. Connect the connector (J8328) of the Main Sensor Harness Assembly (PL 12.15.1) to the Sensor.
4. Clamp the Main Sensor Harness Assembly using the harness clamp.
5. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.33 Sensor (Upper Limit Sensor/ Stacker No Paper Sensor)

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11).
2. Remove the Stacker Bracket Assembly (PL 12.6.24) .
3. Disconnect the connector (J8327 or J8326) of the Main Sensor Harness Assembly (PL 12.15.1) from the Sensor (Upper Limit Sensor or Stacker No Paper Sensor) .
4. Release the hooks of the Sensor.


Figure 1 Stacker No Paper Sensor

## Replacement

1. Secure the Sensor (Upper Limit Sensor or Stacker No Paper Sensor) to the frame using the hooks.
2. Connect the connector (J8327 or J8326) of the Main Sensor Harness Assembly (PL 12.15.1) to the Sensor.

NOTE Be sure to connect the yellow colored connector (J8326) to the Sensor (Stacker No Paper Sensor) on the bottom.
3. Install the Stacker Bracket Assembly (PL 12.6.24) .
4. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.34 Stacker Bracket Assembly

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11).
2. Remove the Lower Rear Cover (PL 12.4.9) .
3. Loosen the four Screws securing the Main Plate PWBA (PL 12.14.7), and move it in the direction of the arrow to remove .
4. Move the Document Clutch Pulley (PL 12.6.19) on the rear side of the Finisher in the direction of the arrow by hand to move the Stacker Tray Assembly (PL 12.4.5) to its lowest position.

NOTE At this time, be sure not to touch the Encoder (PL 12.6.23).


Figure 1 Main PWBA Plate


Figure 2 Document Clutch Pulley
5. Disconnect the connector (J8328) of the Main Sensor Harness Assembly (PL 12.15.1) from the Sensor (PL 12.6.17) (Stacker Encode Sensor) .
6. Release the Main Sensor Harness Assembly from the two clamps.
7. Disconnect the connector of the Harness Assembly from the connector (P8305) on the Main-C PWBA (PL 12.14.5) .
8. Remove the one Screw ( $\mathrm{M} 3 \times 6$ ) securing the Bracket Assembly (PL 12.6.22) to remove it from the Stacker Bracket Assembly .
9. Release the hook of the Encoder (PL 12.6.23) to remove .
10. Remove the three Screws ( $\mathrm{M} 3 \times 6$ ) securing the Stacker Bracket Assembly.


Figure 3 Stacker Encoder Sensor


Figure 4 Main C PWBA


Figure 5 Stacker Bracket Assembly

## Replacement

1. Install the Stacker Bracket Assembly to the Finisher using three Screw.
2. Install the Encoder (PL 12.6.23) and secure it using the hook.
3. Install the Bracket Assembly (PL 12.6.22) to the Stacker Bracket Assembly using one Screw (M3 x 6).
4. Connect the connector of the Harness Assembly to the connector (P8305) on the Main-C PWBA (PL 12.14.5).
5. Connect the connector (J8328) of the Main Sensor Harness Assembly (PL 12.15.1) to the Sensor (PL 12.6.17) (Stacker Encode Sensor).
6. Secure the Main Sensor Harness Assembly using two clamps.
7. Install the Main Plate PWBA (PL 12.14.7) by moving it in the opposite direction of the arrow, and secure it using four Screws.
8. Install the Lower Rear Cover (PL 12.4.9) .
9. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.35 DC Motor Assembly (Elevator Motor)

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11).
2. Remove the Stacker Bracket Assembly (PL 12.6.24) .
3. Remove the two Screws securing the DC Motor Assembly (Elevator Motor) to the Stacker Bracket Assembly .
4. Remove the DC Motor Assembly in the direction of the arrow while removing the Belt (PL 12.6.25).


Figure 1 DC Motor Assembly

## Replacement

1. Put the Belt (PL 12.6.25) onto the gear of the DC Motor Assembly (Elevator Motor) and the Pulley T60, and install the DC Motor Assembly to the Stacker Bracket Assembly (PL 12.6.24) using two Screws.
2. Install the Stacker Bracket Assembly (PL 12.6.24) .
3. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.36 Punch Frame Assembly

NOTE There are five options for the Puncher on the Finisher: 2\&3-hole type, 2\&4-hole type, 3hole type, 2-hole type and punch-less type.

NOTE Although the following removal and replacement procedures are for the 2\&3-hole type, the following procedures can also be applied for the other types.

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11).
3. Release the two harnesses of the Punch Frame Assembly from the clamp .
4. Remove the three Screws ( $\mathrm{M} 3 \times 6$ ) securing the OPB Punch Bracket (PL 12.7.24) to the Punch Frame Assembly to remove the OPB Punch Bracket.
5. Release the Punch Sensor Harness Assembly (PL 12.15.9) connected to the Sensor (PL 12.7.17) (Puncher Move Home Sensor) from the clamp on the Sensor Bracket Assembly (PL 12.7.18).
6. Disconnect the connector (J8352) of the Punch Sensor Harness Assembly from the Sensor.
7. Disconnect the connector (J8344) of the Punch Drive Harness Assembly (PL 12.15.8) from the Punch Motor Bracket Assembly (PL 12.7.4).
8. Disconnect the connector (J8332) of the Punch Unit Harness Assembly (PL 12.7.2) from the Punch Drive Harness Assembly.
9. Disconnect the connector (J8333) of the Punch Unit Harness Assembly from the Punch Sensor Harness Assembly.
10. Remove the three Screws ( $\mathrm{M} 3 \times 6$ ) on the front side of the Finisher securing the OPB Frame F Bracket (PL 12.7.25) to the Finisher to remove the OPB Frame F Bracket.


Figure 1 Punch Frame Assembly
11. Remove the two Screws (M3 x 6) on the front side of the Finisher securing the Punch Frame Assembly to the Finisher.
12. Remove the two Screws ( $\mathrm{M} 3 \times 6$ ) on the rear side of the Finisher securing the Punch Frame Assembly to the Finisher.
13. While pushing the Belt (PL 12.13.27) in the arrow direction shown in the figure with finger, remove the Punch Frame Assembly to the rear.

NOTE Be sure to hold the Punch Frame Assembly by hand to prevent it from falling.


FI3P116A1
Figure 2 Punch Frame Assembly

## Replacement

1. While pushing the Belt (PL 12.13.27) on the rear in the arrow direction shown in the figure with finger, install the Punch Frame Assembly to the Finisher from the rear side.

## NOTE Be sure to hold the Punch Frame Assembly by hand to prevent it from falling.

2. Install the Punch Frame Assembly to the Finisher from the rear side using two Screws (M3 x 6).
3. Install the Punch Frame Assembly to the Finisher from the front side using two Screws (M3 x 6 ).
4. Install the OPB Frame F Bracket (PL 12.7.25) to the Finisher from the front side using three Screws (M3 x 6).
5. Connect the connector (J8352) of the Punch Sensor Harness Assembly (PL 12.15.9) to the Sensor (PL 12.7.17) (Puncher Move Home Sensor).
6. Secure the harness of the Sensor (Puncher Move Home Sensor) using the two clamps.
7. Connect the connector (J8333) of the Punch Unit Harness Assembly (PL 12.7.2) to the Punch Sensor Harness Assembly.
8. Connect the connector (J8332) of the Punch Unit Harness Assembly to the Punch Drive Harness Assembly (PL 12.15.8).
9. Connect the connector (J8344) of the Punch Drive Harness Assembly to the Punch Motor Bracket Assembly (PL 12.7.4).
10. Install the OPB Punch Bracket (PL 12.7.24) to the Punch Frame Assembly from the rear side using three Screws (M3 x 6).
11. Secure the two harnesses of the Punch Frame Assembly using the clamp.
12. Install the Upper Rear Cover (PL 12.4.11) .
13. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.37 Punch Motor Bracket Assembly (Puncher Move Motor)

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Punch Frame Assembly (PL 12.7.1) .
4. Remove the two Screws (M3 x 6) securing the Motor Cover, Punch (PL 12.7.3) to the Punch Frame Assembly to remove the Motor Cover, Punch
5. Remove the two Screws (M3 x 6) securing the Punch Motor Bracket Assembly to the Punch Frame Assembly to remove the Punch Motor Bracket Assembly.


Figure 1 Puncher Move Motor

## Replacement

1. Install the Punch Motor Bracket Assembly to the Punch Frame Assembly (PL 12.7.1) using two Screws (M3 x 6).
2. Install the Motor Cover, Punch (PL 12.7.3) to the Punch Frame Assembly using two Screws (M3 x 6).
3. Install the Punch Frame Assembly .
4. Install the Upper Rear Cover (PL 12.4.11) .
5. Close the Front Cover Assembly (PL 12.5.3).

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Punch Frame Assembly (PL 12.7.1).
4. Remove the one Screw (TP M3 x 6) securing the Punch Front Cover (PL 12.7.7) .
5. Remove the two Screws (TP M3 x 6) securing the Registration Chute S Assembly to the Punch Frame Assembly to remove the Registration Chute S Assembly.

NOTE Since the harness is connected to the Registration Chute S Assembly and the Punch Frame Assembly, the Registration Chute S Assembly cannot be detached from the Punch Frame Assembly.
6. Remove the two Screws (M3 x 6) securing the Sensor Holder Bracket Assembly (PL 12.7.6) to the Registration Chute S Assembly to remove the Sensor Holder Bracket Assembly.
7. Disconnect the connector (J8350) of the Punch Unit Harness Assembly (PL 12.7.2) from the Sensor (Side Registration Sensor 1), and the connector (J8351) from the Sensor (Side Registration Sensor 2).
8. Release the hooks of the Sensor to remove it from the Sensor Holder Bracket Assembly.


Figure 1 Side Registration Sensor 1 \& 2

## Replacement

1. Secure the Sensor to the Sensor Holder Bracket Assembly (PL 12.7.6) using the hooks.
2. Install the Sensor Holder Bracket Assembly to the Registration Chute S Assembly using two Screws (M3 x 6).
3. Connect the connector (J8350) of the Punch Unit Harness Assembly (PL 12.7.2) to the Sensor (Side Registration Sensor 1), and connect the connector (J8351) to the Sensor (Side Registration Sensor 2)
4. Install the Registration Chute S Assembly to the Punch Frame Assembly (PL 12.7.1) using two Screws (TP M3 x 6).
5. Install the Punch Front Cover (PL 12.7.7) to the Punch Frame Assembly using one Screw (TP M $3 \times 6$ ).
6. Install the Punch Frame Assembly
7. Install the Upper Rear Cover (PL 12.4.11) .
8. Close the Front Cover Assembly (PL 12.5.3)

## RRP 12.39 Punch Bracket Assembly 2\&3

NOTE There are five options for Puncher on the Finisher: 2\&3-hole type, 2\&4-hole type, 3hole type, 2-hole type and punch-less type.

NOTE Although the following removal and replacement procedures are for the 2\&3-hole type, the following procedures can also be applied for other types.

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11).
3. Remove the Punch Frame Assembly (PL 12.7.1) .
4. Remove the one Screw (TP M3 x 8) securing the Punch Front Cover (PL 12.7.7) .
5. Remove the two Screws ( $\mathrm{M} 3 \times 6$ ) securing the Punch Left Cover (PL 12.7.10).
6. Remove the three Screws (TP M3 x 6) securing the Holder Frame Assembly (PL 12.7.5) to the Punch Bracket Assembly $2 \& 3$ to remove the Holder Frame Assembly.


Figure 1 Punch Bracket Assembly

## Replacement

1. Install the Holder Frame Assembly (PL 12.7.5) to the Punch Bracket Assembly $2 \& 3$ using three Screws (TP M3 x 6).
2. Install the Punch Left Cover (PL 12.7.10) using two Screws (M3 $\times 6$ ).
3. Install the Punch Front Cover (PL 12.7.7) using one Screw (TP M3 x 8).
4. Install the Punch Frame Assembly (PL 12.7.1) .
5. Install the Upper Rear Cover (PL 12.4.11) .
6. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.40 Guide Assembly

NOTE There are five options for the Puncher on the Finisher: 2\&3-hole type, 2\&4-hole type, 3hole type, 2-hole type and punch-less type.
NOTE The Guide Assembly for 2\&3-hole type, 2\&4-hole type and 3-hole type are common parts, but the 2-hole type is different.

NOTE Although the following removal and replacement procedures of the Guide Assembly are for the $2 \& 3$-hole type, $2 \& 4$-hole type and 3-hole type, the following procedures can also be applied for 2-hole type.

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Punch Frame Assembly (PL 12.7.1).
4. Remove the Screw (TP M3 x 8) securing the Punch Front Cover (PL 12.7.7) .
5. Remove the two Screws ( $M 3 \times 6$ ) securing the Punch Left Cover (PL 12.7.10).
6. Remove the three Screws (TP M3 x 6) securing the Holder Frame Assembly (PL 12.7.5).
7. Remove the one Screw (TP M3 x 6) securing the Guide Assembly to Punch Frame Assembly (PL 12.7.1).
8. Remove the Guide Assembly.


Figure 1 Guide Assembly

## Replacement

1. Install the Guide Assembly to the Punch Frame Assembly (PL 12.7.1) using one Screw (TP M3 x 6).
2. Install the Holder Frame Assembly (PL 12.7.5) to the Punch Bracket Assembly (PL 12.7.9) using three Screws (TP M3 x6).
3. Install the Punch Left Cover (PL 12.7.10) using two Screws (M3 $\times 6$ ).
4. Install the Punch Front Cover (PL 12.7.7) using one Screw (TP M3 x 8).
5. Install the Punch Frame Assembly (PL 12.7.1) .
6. Install the Upper Rear Cover (PL 12.4.11) .
7. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.41 Bracket Assembly (Puncher Motor)

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11).
3. Remove the Punch Frame Assembly (PL 12.7.1) .
4. Disconnect the connector (J8345) of the Punch Unit Harness Assembly (PL 12.7.2) from the Motor .
5. Disconnect the connector (J8346) of the Punch Unit Harness Assembly from the Sensor (PL 12.7.13).
6. Remove the tube put on the harness connected to the Motor and the Sensor from the clamp.
7. Remove the two Screws (+B $4 \times 6$ ) securing the Bracket Assembly to the Punch Frame Assembly to remove the Bracket Assembly.


Figure 1 Puncher Motor Bracket Assembly

## Replacement

1. Install the Bracket Assembly to the Punch Frame Assembly (PL 12.7.1) using two Screws (+B $4 \times 6$ ).

## NOTE Be sure to engage the gears of the Motor and the Punch Frame Assembly.

2. Connect the connector (J8346) of the Punch Unit Harness Assembly (PL 12.7.2) to the Sensor.
3. Connect the connector (J8345) of the Punch Unit Harness Assembly to the Motor.
4. Clamp the tube put on the harness connected to the Motor and the Sensor using the clamp.
5. Install the Punch Frame Assembly .
6. Install the Upper Rear Cover (PL 12.4.11) .
7. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.42 Sensor (Puncher Motor Sensor)

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11).
3. Remove the Punch Frame Assembly (PL 12.7.1).
4. Disconnect the connector (J8345) of the Punch Unit Harness Assembly (PL 12.7.2) from the Motor .
5. Disconnect the connector (J8346) of the Punch Unit Harness Assembly from the Sensor.
6. Release the tube put on the harness connected to the Motor and the Sensor from the clamp.
7. Remove the two Screws (+B $3 \times 6$ ) securing the Bracket Assembly (PL 12.7.14) to the Motor to remove the Bracket Assembly.
8. Release the hooks of the Sensor to remove the Sensor from the Bracket Assembly.


Figure 1 Puncher Motor Sensor

## Replacement

1. Secure the Sensor to the Bracket Assembly (PL 12.7.14) using the hooks.
2. Install the Bracket Assembly to the Motor using two Screws (+B $3 \times 6$ ).

NOTE Be sure to put the Actuator of the Motor in the recess of the Sensor.
3. Connect the connector (J8346) of the Punch Unit Harness Assembly (PL 12.7.2) to the Sensor.
4. Connect the connector (J8345) of the Punch Unit Harness Assembly to the Motor.
5. Clamp the tube put on the harness connected to the Motor and the Sensor using the clamp.
6. Install the Punch Frame Assembly (PL 12.7.1) .
7. Install the Upper Rear Cover (PL 12.4.11) .
8. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.43 Sensor (Punch Hole Select/Puncher Front/Puncher Home)

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Punch Frame Assembly (PL 12.7.1) .
4. Remove the one Screw ( + B $4 \times 6$ ) securing the Bracket $2 \& 4$ (PL 12.7.16) .


Figure 1 Bracket
5. Disconnect the connector (J8346) of the Punch Unit Harness Assembly (PL 12.7.2) from the Sensor (Punch Hole Select Sensor), connector (J8347) from the Sensor (Puncher Front Sensor), or connector (J8348) from the Sensor (Puncher Home Sensor) .
6. Release the hooks of the Sensor to remove the Sensor from the Bracket $2 \& 4$.

## Replacement

1. Secure the Sensor to the Bracket $2 \& 4$ (PL 12.7.16) using the hooks.
2. Connect the connector (J8346) (Blue) of the Punch Unit Harness Assembly (PL 12.7.2) to the Sensor (Punch Hole Select Sensor), connector (J8347) (Black) to the Sensor (Puncher Front Sensor), or connector (J8348) (White) to the Sensor (Puncher Home Sensor).
3. Install the Bracket $2 \& 4$ to the Punch Frame Assembly (PL 12.7.1) using one Screw (+B 4 x 6).

NOTE When installing the Bracket 2\&4, engage each notch of the Bracket 2\&4 and the Punch Frame Assembly, and then tighten the Screw (+B $4 \times 6$ ) while pushing the Bracket 2\&4 toward the fixing Screw.
NOTE After tightening the Screw, make sure that both notches are engaged without extra space.
4. Install the Punch Frame Assembly .
5. Install the Upper Rear Cover (PL 12.4.11) .
6. Close the Front Cover Assembly (PL 12.5.3).


Figure 2 Punch Sensors

## RRP 12.44 Sensor (Puncher Move Home Sensor)

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11).
3. Remove the Punch Frame Assembly (PL 12.7.1).
4. Remove the one Screw (M3 x 6) securing the Sensor Bracket Assembly (PL 12.7.18) .
5. Release the hooks of the Sensor to remove the Sensor from the Sensor Bracket Assembly.


Figure 1 Puncher Move Home Sensor

## Replacement

1. Secure the Sensor (Puncher Move Home Sensor) to the Sensor Bracket Assembly (PL 12.7.18) using the hooks.
2. Install the Sensor Bracket Assembly to the Punch Frame Assembly (PL 12.7.1) using one Screw (M3 x 6).
3. Install the Punch Frame Assembly
4. Install the Upper Rear Cover (PL 12.4.11) .
5. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.45 Sensor (Punch Box Set Sensor)

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Pull out the Dust Box Assembly (PL 12.7.20) from the Finisher to remove the Dust Box Assembly.
3. Disconnect the connector (J8353) of the Punch Box Sensor Harness Assembly from the Sensor (Punch Box Set Sensor) .
4. Release the hooks of the Sensor to remove the Sensor from the Bracket Assembly.


Figure 1 Punch Box Set Sensor

## Replacement

1. Secure the Sensor (Punch Box Set Sensor) to the Bracket Assembly using the hooks.
2. Connect the connector (J8353) of the Punch Box Sensor Harness Assembly to the Sensor.
3. Install the Dust Box Assembly (PL 12.7.20) to the Finisher.
4. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.46 Stapler Unit

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the Stapler Cartridge Assembly (PL 12.8.1) .


Figure 1 Stapler Cartridge Assembly
3. Remove the Upper Rear Cover (PL 12.4.11) .
4. Remove the Lower Rear Cover (PL 12.4.9) .
5. Loosen the four Screws securing the Main Plate PWBA (PL 12.14.7), and move it in the direction of the arrow to remove the Main Plate PWBA .


Figure 2 Main Plate PWBA
6. Disconnect the connector of the Staple Harness Assembly (PL 12.8.7) from the connector (P8308) on the Main-C PWBA (PL 12.14.5).
7. Remove the one Screw securing the ground wire of the Staple Harness Assembly.


Figure 3 Main C PWBA
8. Release the Staple Harness Assembly from the harness clamp .
9. Remove the Stacker Bracket Assembly (PL 12.6.24) .
10. Disconnect the two connectors (J8327 and J8326 (yellow)) of the Main Sensor Harness Assembly (PL 12.15.1) from the two Sensors (PL 12.6.17) (Upper Limit Sensor and Stacker No Paper Sensor).
11. Remove the two Screws ( $\mathrm{M} 3 \times 6$ ) each on the front and rear securing the Stapler Unit.


Figure 4 Main Sensor Harness
12. Move the Stapler Unit in the direction of the arrow to disengage the hooks on the frame from the square holes on the front and rear of the Stapler Unit, and remove the Stapler Unit to the front .


Figure 5 Stapler Unit

## Replacement

1. Put the Stapler Unit into the Finisher from its front, and move the Stapler Unit in the opposite direction of the arrow to put the hooks on the frame into the square holes on the front and rear of the Stapler Unit.
NOTE When installing the Stapler Unit, be careful not to drop it.
2. Secure the Stapler Unit to the frame using two Screws $(M 3 \times 6)$ each on the front and rear.
3. Connect the connectors (J8327 and J8326 (yellow)) of the Main Sensor Harness Assembly (PL 12.15.1) to the connectors of the two Sensors (PL 12.6.17) (Upper Limit Sensor and Stacker No Paper Sensor).
4. Install the Stacker Bracket Assembly (PL 12.6.24) .
5. Connect the connector of the Staple Harness Assembly (PL 12.8.7) to the connector (P8308) on the Main-C PWBA (PL 12.14.5).
6. Secure the ground wire of the Staple Harness Assembly to the frame using one Screw.
7. Secure the Staple Harness Assembly using the harness clamp.
8. Install the Main Plate PWBA (PL 12.14.7) to the frame by moving it in the opposite direction of the arrow, and secure it using four Screws.
9. Install the Lower Rear Cover (PL 12.4.9) .
10. Install the Upper Rear Cover (PL 12.4.11) .
11. Install the Front Cover Assembly (PL 12.5.3).
12. Install the Stapler Cartridge Assembly (PL 12.8.1).

## RRP 12.47 Stapler Assembly

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the Stapler Cartridge Assembly (PL 12.8.1).
3. Remove the Upper Rear Cover (PL 12.4.11) .
4. Remove the Lower Rear Cover (PL 12.4.9) .
5. Remove the Stapler Unit (PL 12.8.14) .
6. Remove the five Screws ( $\mathrm{M} 3 \times 6$ ) securing the Stapler Frame Assembly (PL 12.8.11) to remove the Stapler Frame Assembly .
7. Release the Staple Harness Assembly (PL 12.8.7) from the two harness clamps of the Stapler Frame Assembly.


Figure 1 Stapler Frame Assembly
8. Remove the two Screws securing the Stapler Lower Carriage Assembly (PL 12.8.9) to remove the Stapler Lower Carriage Assembly .

NOTE Since the harnesses are connected to the Stapler Lower Carriage Assembly and the head of the Stapler, the Stapler Lower Carriage Assembly cannot be detached from the head of the Stapler.
9. Remove the one Screw securing the Stapler Cover (PL 12.8.3) to remove the Stapler Cover
10. Disconnect the two connectors (J8356 and J8357) from the Stapler Assembly, and the one connector (J8354) from the Sensor.
11. Remove the two Screws on the sides on the Stapler Assembly securing the Stapler Upper Carriage Assembly (PL 12.8.8) to remove the Stapler Upper Carriage Assembly. At the same time, the ground terminal is also detached.
12. Remove the two Screws securing the Stapler Assembly to the Stapler Holder (PL 12.8.4) to remove the Stapler Assembly.


Figure 2 Lower Stapler Carriage Assembly


Figure 3 Stapler Assembly

## Replacement

1. Install the Stapler Assembly to the Stapler Holder (PL 12.8.4) using two Screws.
2. Put the Staple Harness Assembly (PL 12.8.7) under the ribs of the Stapler Guide Harness (PL 12.8.6) as shown in the figure.
3. Install the Stapler Upper Carriage Assembly (PL 12.8.8) to the Stapler Holder attached with the Stapler Assembly using two Screws.
NOTE Make sure that the wires of the Staple Harness Assembly are not pinched between the Stapler Upper Carriage Assembly and the Stapler Holder.
NOTE Secure the ground terminal in the position shown in the figure using one Screw.
4. Connect the two connectors (J8356 and J8357) of the Staple Harness Assembly to the Stapler Assembly, and the connector (J8354) to the Sensor (PL 12.8.5).
5. Install the Stapler Cover (PL 12.8.3) to the Stapler Assembly using one Screw.
6. Install the Stapler Lower Carriage Assembly (PL 12.8.9) to the head of the Stapler using two Screws.
7. Secure the Staple Harness Assembly with the two harness clamps of the Stapler Frame Assembly (PL 12.8.11).
8. Install the Stapler Frame Assembly using five Screws (M3 x 6).
9. Install the Stapler Unit (PL 12.8.14) .
10. Install the Lower Rear Cover (PL 12.4.9) .
11. Install the Upper Rear Cover (PL 12.4.11) .
12. Install the Front Cover Assembly (PL 12.5.3) .
13. Install the Stapler Cartridge Assembly (PL 12.8.1).

## RRP 12.48 Sensor (Stapler Move Home Position Sensor)

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the Stapler Cartridge Assembly (PL 12.8.1).
3. Remove the Upper Rear Cover (PL 12.4.11) .
4. Remove the Lower Rear Cover (PL 12.4.9) .
5. Remove the Stapler Unit (PL 12.8.14) .
6. Remove the Stapler Assembly (PL 12.8.2) .
7. Release the hooks of the Sensor (Stapler Move Home Position Sensor) from the Stapler Guide Harness (PL 12.8.6) to remove the Sensor.


Figure 1 Stapler Move Home Position Sensor

## Replacement

1. Secure the Sensor (Stapler Move Home Position Sensor) to the Stapler Guide Harness (PL 12.8.6) using the hooks.
2. Install the Stapler Assembly (PL 12.8.2) .
3. Install the Stapler Unit (PL 12.8.14)
4. Install the Lower Rear Cover (PL 12.4.9) .
5. Install the Upper Rear Cover (PL 12.4.11) .
6. Install the Stapler Cartridge Assembly (PL 12.8.1).
7. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.49 Eject Unit Chute Assembly

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the SCT Tray Assembly (PL 12.4.3) .
4. Remove the Eject Cover (PL 12.4.4) .
5. Remove the two Pinch Springs(PL 12.9.5) while pushing them downward .
6. Disconnect the harness connector (J8340) of the Solenoid Assembly (PL 12.9.3) (Sub Paddle Solenoid) from the Main Drive Harness Assembly (PL 12.15.2).
7. Release the harness of the Sub Paddle Solenoid from the two harness clamps.


Figure 1 Pinch Springs
8. While pushing the Lever Assembly (PL 12.9.14) in the direction of the arrow, remove the Screw (M3 x 6) securing the Lever Assembly to the Eject Pinch Shaft Assembly to remove the Lever Assembly .
9. Remove the E-ring securing the Eject Pinch Shaft Assembly (PL 12.9.7) on the rear of the Finisher .
10. Remove the Bearing (PL 12.9.15) on the rear side.
11. Remove the E-ring securing the Eject Pinch Shaft Assembly on the front of the Finisher.
12. Remove the Bearing (PL 12.9.15) on the front side.
13. While pulling the Eject Unit Chute Assembly toward you from the right side of the Finisher, tilt it slightly to remove the front end of the Eject Pinch Shaft Assembly from the hole on the front frame .
14. Remove the Eject Unit Chute Assembly from the Finisher .


Figure 2 Lever Assembly


Figure 3 Eject Pinch Shaft Assembly


Figure 4 Eject Unit Chute Assembly


Figure 5 Sensor Assembly

## Replacement

1. Put the rear end of the Eject Pinch Shaft Assembly (PL 12.9.7) on the Eject Unit Chute Assembly into the longitudinal hole on the frame.
2. Put the front end of the Eject Pinch Shaft Assembly into the longitudinal hole on the front frame, then install the Eject Unit Chute Assembly to the Finisher.
NOTE When installing, be sure to install the Sensor Assembly so that the actuator of the Sensor Assembly is placed under the Interlock Bracket on Eject Unit Chute Assembly.
3. Install the Bearing (PL 12.9.15) to the Eject Pinch Shaft Assembly on the rear.

NOTE Install the Bearing so that its flat surfaces fits to the hole on the frame.
4. Secure the Bearing using the E-ring.
5. Install the Bearing (PL 12.9.15) to the front end of the Eject Pinch Shaft Assembly.

NOTE Install the Bearing with its flat surfaces fit to the hole on the frame of the Finisher.
6. Secure the Bearing using the E-ring.
7. Install the Lever Assembly (PL 12.9.14) to the Eject Pinch Shaft Assembly, and secure it to the Screw hole on the Eject Pinch Shaft Assembly using one Screw (M3 x 6).
NOTE It is easy to tightening the Screw by pressing the Lever Assembly in the direction of the arrow.
8. Connect the harness connector (J8340) of the Solenoid Assembly (PL 12.9.3) to the Main Drive Harness Assembly (PL 12.15.2).
9. Secure the harness of the Solenoid Assembly with the two harness clamps.
10. Install the two Pinch Springs (PL 12.9.5) while pushing them downward.
11. Install the Eject Cover (PL 12.4.4) .
12. Install the SCT Tray Assembly (PL 12.4.3) .
13. Install the Upper Rear Cover (PL 12.4.11) .
14. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.50 Solenoid Assembly (Sub Paddle Solenoid)

## Removal

1. Remove the SCT Tray Assembly (PL 12.4.3) .
2. Disconnect the harness connector (J8340) of the Solenoid Assembly (Sub Paddle Solenoid) from the Main Drive Harness Assembly (PL 12.15.2) .
3. Release the harness of the Solenoid Assembly from the two harness clamps.
4. Remove the three Screws securing the Solenoid Bracket (PL 12.9.4) attached with the Solenoid Assembly to the Eject Unit Chute Assembly (PL 12.9.27), and move it in the direction of the arrow shown in the figure to remove the Solenoid Bracket.
5. Remove the two Screws securing the Solenoid Assembly to the Solenoid Bracket to remove the Solenoid Assembly .


Figure 1 Solenoid Assembly


Figure 2 Solenoid Bracket

## Replacement

1. Install the Solenoid Assembly to the Solenoid Bracket (PL 12.9.4) in the direction shown in the figure using two Screws.
2. While putting the iron core of the Solenoid Assembly into the notch of the Solenoid Link, install the Solenoid Assembly to the Eject Unit Chute Assembly (PL 12.9.27).
3. Install the Solenoid Bracket to the Eject Unit Chute Assembly using three Screws.

NOTE When installing, be sure to put the boss on the Eject Unit Chute Assembly into the hole on the Solenoid Bracket.
4. Connect the harness connector (J8340) of the Solenoid Assembly to the Main Drive Harness Assembly (PL 12.15.2).
5. Secure the harness of the Solenoid Assembly with the two harness clamps.
6. Install the SCT Tray Assembly (PL 12.4.3) .

## RRP 12.51 Cyclone Paddle

NOTE Two Cyclone Paddles are attached to the Eject Unit Chute Assembly (PL 12.9.27). Their removal and replacement procedures are the same.

## Removal

1. Remove the SCT Tray Assembly (PL 12.4.3) .
2. Remove the Cyclone Paddle from the shaft of the T16 Pulley on the Eject Unit Chute Assembly (PL 12.9.27) by hand .


Figure 1 Cyclone Paddle

## Replacement

1. Install the Cyclone Paddle to the shaft of the T16 Pulley on the Eject Unit Chute Assembly (PL 12.9.27) in the direction shown in the figure.

NOTE After installation, make sure that the Cyclone Paddle does not in contact with the Eject Unit Chute Assembly when it is rotated by hand.
2. Install the SCT Tray Assembly (PL 12.4.3) .

## RRP 12.52 Paddle Shaft Assembly

## Removal

1. Open the Front Cover Assembly.
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Loosen the setscrew securing the Entrance Knob Assembly (PL 12.9.24) on the front .
4. Pull out the Entrance Knob Assembly from the Paddle Shaft Assembly.
5. Remove the one E-ring securing the Paddle Shaft Assembly on the front.
6. Remove the Bearing (PL 12.9.17).


Figure 1 Entrance Knob Assembly
7. Loosen the two Screws securing the Tension Bracket Assembly (PL 12.13.23) on the rear so that the tension of the Belt (PL 12.13.28) decreases .


Figure 2 Tension Bracket Assembly
8. Release the hook of the Z23 Gear (PL 12.9.16) attached to the Paddle Shaft Assembly on the rear to remove the Z23 Gear .
9. Remove the Bearing (PL 12.9.17).
10. Move the Paddle Shaft Assembly to the rear side to remove the front end of the Paddle Shaft Assembly from the hole on the front frame, then remove the Paddle Shaft Assembly from the Finisher.


Figure 3 Paddle Shaft Assembly

## Replacement

1. Put the rear end of the Paddle Shaft Assembly into the hole on the rear first, then put the front end of the Paddle Shaft Assembly into the hole on the front frame.
2. Install the Bearing (PL 12.9.17) to the Paddle Shaft Assembly on the front.
3. Fix the one E-ring to the Paddle Shaft Assembly.
4. Install the Bearing (PL 12.9.17) to the Paddle Shaft Assembly on the rear.
5. Install the Z23 Gear (PL 12.9.16), and fix it to the Paddle Shaft Assembly with the hook.
6. Fix the Tension Bracket Assembly to the frame using two Screws.

NOTE The tension of the belt is automatically adjusted by the force of the Tension Spring (PL 12.13.24) attached to the Tension Bracket Assembly. Therefore, when tightening the two Screws, be careful not to move the Tension Bracket Assembly.
NOTE Tighten the two Screws in order of (1) and (2) shown in the figure.
7. Install the Entrance Knob Assembly to the Paddle Shaft Assembly on the front.
8. Tighten the setScrew to secure the Entrance Knob Assembly to the Paddle Shaft Assembly.
9. Install the Upper Rear Cover (PL 12.4.11).
10. Close the Front Cover Assembly.

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11) .
2. Remove the SCT Tray Assembly (PL 12.4.3) .
3. Remove the two Pinch Springs (PL 12.9.5) attached to the Eject Chute Assembly (PL 12.9.1) while pushing them downward .


Figure 1 Pinch Springs
4. Disconnect the harness connector (J8339) of the DC Motor Assembly (PL 12.9.11) from the connector of the Main Drive Harness Assembly (PL 12.15.2) .
5. Disconnect the connector (J8324) of the Main Sensor Harness Assembly (PL 12.15.1) from the Sensor (PL 12.9.13).
6. Remove the three Screws (+M3 $\times 5$ ) securing the Eject Clamp Bracket Assembly to the Finisher.
7. Remove the Eject Clamp Bracket Assembly.

NOTE When removing the Eject Clamp Bracket Assembly, rotate the Z70 Cam Gear (PL 12.9.18) with finger so that the actuator on the Eject Clamp Bracket Assembly is retracted from the recess of the sensor.


Figure 2 Eject Bracket Assembly

## Replacement

1. Secure the Eject Clamp Bracket Assembly to the Finisher using three Screws (+M3 $\times 5$ ).

NOTE When installing the Eject Clamp Bracket Assembly, rotate the Z70 Cam Gear (PL 12.9.18) with finger so that the actuator on the Eject Clamp Bracket Assembly is retracted from the recess of the sensor.
2. Connect the connector (J8324) of the Main Sensor Harness Assembly (PL 12.15.1) to the Sensor (PL 12.9.13).
3. Connect the connector of the Main Drive Harness Assembly (PL 12.15.2) to the harness connector (J8339) of the DC Motor Assembly (PL 12.9.11).
4. Install the two Pinch Springs (PL 12.9.5) between the Eject Chute Assembly and the Tie Plate Assembly while pushing them downward.
5. Install the SCT Tray Assembly (PL 12.4.3) .
6. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.54 DC Motor Assembly (Eject Clamp Motor)

1. Remove the Upper Rear Cover (PL 12.4.11).
2. Remove the SCT Tray Assembly (PL 12.4.3) .
3. Remove the two Pinch Springs (PL 12.9.5) attached on the Eject Chute Assembly (PL 12.9.1) while pushing them downward .


Figure 1 Pinch Springs
4. Remove the Eject Clamp Bracket Assembly (PL 12.9.10) .
5. Remove the two Screws securing the DC Motor Assembly to the Eject Clamp Bracket Assembly .
6. Remove the DC Motor Assembly.


Figure 2 Eject Clamp Bracket Assembly

## Replacement

1. Install the DC Motor Assembly to the Eject Clamp Bracket Assembly (PL 12.9.10) using two Screws.
2. Install the Eject Clamp Bracket Assembly .
3. Install the two Pinch Springs between the Eject Chute Assembly (PL 12.9.1) and Tie Plate Assembly while pushing them downward.
4. Install the SCT Tray Assembly (PL 12.4.3) .
5. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.55 Sensor (Eject Clamp Home Sensor)

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11) .
2. Remove the SCT Tray Assembly (PL 12.4.3) .
3. Remove the two Pinch Springs (PL 12.9.5) attached on the Eject Chute Assembly (PL 12.9.1) while pushing them downward


Figure 1 Pinch Springs
4. Remove the Eject Clamp Bracket Assembly (PL 12.9.10) .
5. Release the hooks of the Sensor to remove the Sensor from the Eject Clamp Bracket Assembly .


Figure 2 Eject Clamp Bracket Assembly

## Replacement

1. Secure the Sensor to the Eject Clamp Bracket Assembly (PL 12.9.10) using the hooks.
2. Install the Eject Clamp Bracket Assembly .
3. Install the two Pinch Springs between the Eject Chute Assembly (PL 12.9.1) and Tie Plate Assembly while pushing them downward.
4. Install the SCT Tray Assembly (PL 12.4.3) .
5. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.56 Sensor Assembly (Eject Cover Switch)

## Removal

1. Remove the SCT Tray Assembly (PL 12.4.3) .
2. Disconnect the harness connector (J8364) of the Sensor Assembly from the connector of the Interlock Harness Assembly (PL 12.15.11) .
3. Release the harness of the Sensor Assembly from the two clamps.
4. Remove the one Screw (TP M $3 \times 6$ ) securing the Switch Bracket (PL 12.9.22) to the Tie Plate Assembly.
5. Remove the Switch Bracket attached with the Sensor Assembly from the square hole on the Tie Plate Assembly.
6. Remove the two Screws (TP M $3 \times 12$ ) securing the Sensor Assembly to the Switch Bracket.
7. Remove the Sensor Assembly from the Switch Bracket .


Figure 1 Interlock Harness Assembly


Figure 2 Sensor Assembly

## Replacement

1. Install the Sensor Assembly to the Switch Bracket (PL 12.9.22) using two Screws (TP M 3 x 12).
2. Install the Switch Bracket attached with the Sensor Assembly through the square hole on the Tie Plate Assembly.
NOTE When installing, be sure to install the Sensor Assembly so that the actuator of the Sensor Assembly is placed under the Interlock Bracket on the Eject Chute Assembly.
3. Install the Switch Bracket to the Tie Plate Assembly using one Screw (TP M $3 \times 6$ ).
4. Connect the harness connector (J8364) of the Sensor Assembly to the connector of the Interlock Harness Assembly (PL 12.15.11).
5. Secure the harness of the Sensor Assembly with the two clamps.
6. Install the SCT Tray Assembly (PL 12.4.3) .

## RRP 12.57 Compiler Tray Assembly

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Lower Rear Cover (PL 12.4.9) .
4. Remove the SCT Tray Assembly (PL 12.4.3) .
5. Remove the Eject Cover (PL 12.4.4) .
6. Remove the Stapler Unit (PL 12.8.14) .
7. Remove the Eject Clamp Bracket Assembly (PL 12.9.10) .
8. Remove the Eject Unit Chute Assembly (PL 12.9.27) .
9. Remove the Eject Bracket Assembly (PL 12.10.17) .
10. Loosen the four Screws securing the Main Plate PWBA (PL 12.14.7), and move it in the direction of the arrow to remove the Main Plate PWBA .


Figure 1 Main Plate PWBA
11. Disconnect the connector of the Compiler Harness Assembly (PL 12.10.8) from the connector (P8309) on the Main-C PWBA (PL 12.14.5) .


Figure 2 Main C PWBA
12. Release the Compiler Harness Assembly from the harness clamp.
13. Release the locks of the Compiler Tray Assembly by pushing the bosses on the front and rear toward the inside of the Finisher, and remove the Compiler Tray Assembly in the direction of the arrow .


Figure 3 Compiler Tray Assembly

## Replacement

1. Put the Compiler Tray Assembly into the Finisher from its front, move it in the opposite direction of the arrow and secure it to the frame with the bosses on the front and rear.
2. Connect the connector of the Compiler Harness Assembly (PL 12.10.8) to the connector (P8309) on the Main-C PWBA (PL 12.14.5).
3. Secure the Compiler Harness Assembly using the harness clamp.
4. Install the Main Plate PWBA (PL 12.14.7) by moving it in the opposite direction of the arrow, and secure it using four Screws.
5. Install the Eject Bracket Assembly (PL 12.10.17) .
6. Install the Eject Unit Chute Assembly (PL 12.9.27) .
7. Install the Eject Clamp Bracket Assembly (PL 12.9.10) .
8. Install the Stapler Unit (PL 12.8.14)
9. Install the Eject Cover (PL 12.4.4) .
10. Install the SCT Tray Assembly (PL 12.4.3)
11. Install the Lower Rear Cover (PL 12.4.9) .
12. Install the Upper Rear Cover (PL 12.4.11) .
13. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.58 Front Tamper Home Sensor \& Rear Tamper Home Sensor

## NOTE The removal and replacement procedures for two Sensors (Front Tamper Home Sensor and Rear Tamper Home Sensor) are the same. The removal and replacement procedures for the Front Tamper Home Sensor are described here.

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Lower Rear Cover (PL 12.4.9) .
4. Remove the SCT Tray Assembly (PL 12.4.3) .
5. Remove the Eject Cover (PL 12.4.4) .
6. Remove the Stapler Unit (PL 12.8.14) .
7. Remove the Eject Clamp Bracket Assembly (PL 12.9.10) .
8. Remove the Eject Unit Chute Assembly (PL 12.9.27) .
9. Remove the Eject Bracket Assembly (PL 12.10.17) .
10. Remove the Compiler Tray Assembly (PL 12.10.1) .
11. Disconnect the connector (J8360) of the Compiler Harness Assembly (PL 12.10.8) from the Sensor (Front Tamper Home Sensor) .


Figure 1 Front \& Rear Tamper Sensor
NOTE For the Rear Tamper Home Sensor, disconnect the connector (J8361) of the Compiler Harness Assembly.
12. Release the hooks of the Sensor to remove the Sensor from the Compiler Tray Assembly.

## Replacement

1. Secure the Sensor (Front Tamper Home Sensor) to the Compiler Tray Assembly (PL 12.10.1) with the hooks.
2. Connect the connector (J8360) of the Compiler Harness Assembly (PL 12.10.8) to the Sensor.
NOTE For the Rear Tamper Home Sensor, connect the connector (J8361) of the Compiler Harness Assembly.
3. Install the Compiler Tray Assembly .
4. Install the Eject Bracket Assembly (PL 12.10.17) .
5. Install the Eject Unit Chute Assembly (PL 12.9.27) .
6. Install the Eject Clamp Bracket Assembly (PL 12.9.10) .
7. Install the Stapler Unit (PL 12.8.14) .
8. Install the Eject Cover (PL 12.4.4).
9. Install the SCT Tray Assembly (PL 12.4.3) .
10. Install the Lower Rear Cover (PL 12.4.9) .
11. Install the Upper Rear Cover (PL 12.4.11) .
12. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.59 Compiler Tray No Paper Sensor \& Paper Actuator Sensor

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Lower Rear Cover (PL 12.4.9) .
4. Remove the SCT Tray Assembly (PL 12.4.3) .
5. Remove the Eject Cover (PL 12.4.4) .
6. Remove the Stapler Unit (PL 12.8.14) .
7. Remove the Eject Clamp Bracket Assembly (PL 12.9.10) .
8. Remove the Eject Unit Chute Assembly (PL 12.9.27) .
9. Remove the Eject Bracket Assembly (PL 12.10.17) .
10. Remove the Compiler Tray Assembly (PL 12.10.1)
11. Disconnect the connector (J8359) of the Compiler Harness Assembly (PL 12.10.8) from the Sensor (Compiler Tray No Paper Sensor) .
12. Release the hooks of the Sensor to remove the Sensor from the Compiler Tray Assembly.
13. Move the Paper Actuator in the direction of the arrow to remove the Paper Actuator.


Figure 1 No Paper Sensor Compiler Tray

## Replacement

1. Install the Paper Actuator to the Compiler Tray Assembly (PL 12.10.1) by moving it in the opposite direction of the arrow.
2. Secure the Sensor (Compiler Tray No Paper Sensor) to the Compiler Tray Assembly with the hooks.
3. Connect the connector (J8359) of the Compiler Harness Assembly (PL 12.10.8) to the Sensor.
4. Install the Compiler Tray Assembly .
5. Install the Eject Bracket Assembly (PL 12.10.17) .
6. Install the Eject Unit Chute Assembly (PL 12.9.27) .
7. Install the Eject Clamp Bracket Assembly (PL 12.9.10) .
8. Install the Stapler Unit (PL 12.8.14) .
9. Install the Eject Cover (PL 12.4.4) .
10. Install the SCT Tray Assembly (PL 12.4.3) .
11. Install the Lower Rear Cover (PL 12.4.9) .
12. Install the Upper Rear Cover (PL 12.4.11) .
13. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.60 Motor Assembly 2 (Front Tamper Motor)

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Lower Rear Cover (PL 12.4.9) .
4. Remove the SCT Tray Assembly (PL 12.4.3) .
5. Remove the Eject Cover (PL 12.4.4) .
6. Remove the Stapler Unit (PL 12.8.14) .
7. Remove the Eject Clamp Bracket Assembly (PL 12.9.10) .
8. Remove the Eject Unit Chute Assembly (PL 12.9.27) .
9. Remove the Eject Bracket Assembly (PL 12.10.17) .
10. Remove the Compiler Tray Assembly (PL 12.10.1) .
11. Pull out the tube put on the harness of the Sensor (Front Tamper Home Sensor) in the direction of the arrow .
12. Disconnect the connector of the Compiler Harness Assembly (PL 12.10.8) from the harness connector (J8363) of the Motor Assembly 2 (Front Tamper Motor).
13. Remove the two Screws securing the Motor Assembly 2 to the Compiler Tray Assembly to remove the Motor Assembly 2.


Figure 1 Front Tamper Motor

## Replacement

1. Install the Motor Assembly 2 (Front Tamper Motor) to the Compiler Tray Assembly (PL 12.10.1) using two Screws.

## NOTE Be sure to install the Motor Assembly in the direction shown in the figure.

2. Connect the connector of the Compiler Harness Assembly (PL 12.10.8) to the harness connector (J8363) of the Motor Assembly 2.
3. Push the connected connector in the opposite direction of the arrow.
4. Push in the tube put on the harness of the Sensor (Front Tamper Home Sensor) in the opposite direction of the arrow to press the harness connector of the Motor Assembly 2.
5. Install the Compiler Tray Assembly .
6. Install the Eject Bracket Assembly (PL 12.10.17) .
7. Install the Eject Unit Chute Assembly (PL 12.9.27) .
8. Install the Eject Clamp Bracket Assembly (PL 12.9.10) .
9. Install the Stapler Unit (PL 12.8.14) .
10. Install the Eject Cover (PL 12.4.4) .
11. Install the SCT Tray Assembly (PL 12.4.3) .
12. Install the Lower Rear Cover (PL 12.4.9) .
13. Install the Upper Rear Cover (PL 12.4.11) .
14. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.61 Motor Assembly (Rear Tamper Motor)

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Lower Rear Cover (PL 12.4.9) .
4. Remove the SCT Tray Assembly (PL 12.4.3) .
5. Remove the Eject Cover (PL 12.4.4) .
6. Remove the Stapler Unit (PL 12.8.14) .
7. Remove the Eject Clamp Bracket Assembly (PL 12.9.10) .
8. Remove the Eject Unit Chute Assembly (PL 12.9.27) .
9. Remove the Eject Bracket Assembly (PL 12.10.17) .
10. Remove the Compiler Tray Assembly (PL 12.10.1)
11. Remove the harness connector of the Motor Assembly (Rear Tamper Motor) from underneath the rib of the Compiler Tray Assembly .
12. Disconnect the connector of the Compiler Harness Assembly (PL 12.10.8) from the harness connector (J8362) of the Motor Assembly.
13. Remove the two Screws securing the Motor Assembly to the Compiler Tray Assembly to remove the Motor Assembly.


Figure 1 Rear Tamper Motor

## Replacement

1. Install the Motor Assembly (Rear Tamper Motor) to the Compiler Tray Assembly using two Screws.

## NOTE Be sure to install the Motor Assembly in the direction shown in the figure.

2. Connect the connector of the Compiler Harness Assembly (PL 12.10.8) to the harness connector (J8362) of the Motor Assembly.
3. Put the connected connector underneath the rib of the Compiler Tray Assembly.
4. Install the Compiler Tray Assembly .
5. Install the Eject Bracket Assembly (PL 12.10.17) .
6. Install the Eject Unit Chute Assembly (PL 12.9.27) .
7. Install the Eject Clamp Bracket Assembly (PL 12.9.10) .
8. Install the Stapler Unit (PL 12.8.14) .
9. Install the Eject Cover (PL 12.4.4) .
10. Install the SCT Tray Assembly (PL 12.4.3)
11. Install the Lower Rear Cover (PL 12.4.9) .
12. Install the Upper Rear Cover (PL 12.4.11) .
13. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.62 Eject Roll Shaft Assembly

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Move the Document Pulley Clutch (PL 12.6.19) on the rear side of the Finisher in the direction of the arrow by hand to move the Stacker Tray Assembly (PL 12.4.5) to its lowest position.

NOTE At this time, be sure not to touch the Encoder (PL 12.6.23).
4. Remove the Stacker Tray Assembly .
5. Remove the four Screws securing the Guide Assembly TRAY, and shift the Guide Assembly TRAY a little downward.
6. Remove the Eject Bracket Assembly (PL 12.10.17) .
7. Release the hook of the Gear (PL 12.10.14) on the rear to remove the Gear from the shaft.
8. Remove the Bearing (PL 12.10.13) .
9. Remove the E-ring on the rear.
10. Remove the Bearing (PL 12.10.12).


Figure 1 Bearing
11. Remove the two E-rings on the front securing the Eject Roll Shaft Assembly .
12. Remove the two Bearings (PL 12.10.12 and PL 12.10.13).
13. Move the Eject Roll Shaft Assembly to the rear first to remove the front end of the two shafts from the two holes on the frame, and move the Eject Roll Shaft Assembly in the direction of the arrow to remove the two shafts from the rear holes. Then, remove the Eject Roll Shaft Assembly from the Finisher .


Figure 2 Eject Roll Shaft Assembly


Figure 3 Eject Roll Shaft Assembly

## Replacement

1. Move the Eject Roll Shaft Assembly in the opposite direction of the arrow to install it to the Finisher.
2. Install the two Bearings (PL 12.10.12 and PL 12.10.13) to the two shafts on the front.
3. Secure the Bearings using two E-rings.
4. Install the two Bearings (PL 12.10.12 and PL 12.10.13) to the two shafts on the rear.
5. Secure the Bearing (PL 12.10.12) using the E-ring.
6. Install the Gear (PL 12.10.14) and secure it using the hook.
7. Install the Eject Bracket Assembly (PL 12.10.17) .
8. Install the Guide Assembly TRAY using the four Screws.
9. Install the Stacker Tray Assembly .
10. Install the Upper Rear Cover (PL 12.4.11) .
11. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.63 Paddle-set Clamp

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Eject Roll Shaft Assembly (PL 12.10.9) .
4. Remove the Paddle-set Clamp from the Paddle Holder by hand .


Figure 1 Paddle Set Clamp

## Replacement

1. Install the Paddle-set Clamp to the Paddle Holder in the direction shown in the figure.
2. Install the Eject Roll Shaft Assembly (PL 12.10.9) .
3. Install the Upper Rear Cover (PL 12.4.11) .
4. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.64 Z34 Clutch

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11) .
2. Disconnect the connector (J8336) of the Main Drive Harness Assembly (PL 12.15.2) from the Motor on the Eject Bracket Assembly (PL 12.10.17).
3. Disconnect the connector (J8325) of the Main Sensor Harness Assembly (PL 12.15.1) from the Sensor (PL 12.10.18) on the Eject Bracket Assembly .
4. Release the harness from the clamp.
5. Disconnect the harness connector of the Z34 Clutch from the connector (J8338) of the Main Drive Harness Assembly.
6. Release the harness from the clamp.
7. Remove the Set Clamp Actuator (PL 12.10.16) from the shaft by releasing the hook.
8. Remove the Screw securing the Set Clamp Spring to remove the Set Clamp Spring.
9. Remove the Z34 Clutch.


Figure 1 Z34 Clutch

## Replacement

1. Install the Z34 Clutch to the shaft.

NOTE Fit the notch of the Z34 Clutch into the dented portion of the Eject Bracket Assembly (PL 12.10.17).
2. Put the tip of the Set Clamp Spring into the square hole on the Eject Bracket Assembly, and fix it using one Screw from the backside of the Eject Bracket Assembly.
3. Install the Set Clamp Actuator (PL 12.10.16) to the shaft, and secure it with the hook.
4. Connect the harness connector (J8338) of the Z34 Clutch to the Main Drive Harness Assembly (PL 12.15.2).
5. Connect the connector (J8325) of the Main Sensor Harness Assembly (PL 12.15.1) to the Sensor (PL 12.10.18).
6. Connect the connector (J8336) of the Main Drive Harness Assembly to Motor.
7. Secure the harness with the clamp.
8. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.65 Eject Bracket Assembly

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11).
2. Remove the Z34 Clutch .
3. Remove the three Screws securing the Eject Bracket Assembly .


Figure 1 Eject Bracket Assembly

## Replacement

1. Install the Eject Bracket Assembly to the Finisher using three Screws.
2. Install the Z34 Clutch (PL 12.10.15) .

NOTE Put the notch of the Z34 Clutch into the dented portion of the Eject Bracket Assembly.
3. Install Upper Rear Cover (PL 12.4.11) .

## RRP 12.66 Set Clamp Home Sensor

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11) .
2. Disconnect the connector (J8325) of the Main Sensor Harness Assembly (PL 12.15.1) from the Sensor (Set Clamp Home Sensor) .
3. Rotate the Set Clamp Actuator (PL 12.10.16) by hand so that the actuator of the Set Clamp Actuator is retracted from the recess of the sensor.
4. Release the hooks of the Sensor to remove it from the Eject Bracket Assembly (PL 12.10.17).


Figure 1 Set Clamp Home Sensor

## Replacement

1. Secure the Sensor (Set Clamp Home Sensor) to the Eject Bracket Assembly (PL 12.10.17) using the hook.
2. Rotate the Set Clamp Actuator (PL 12.10.16) by hand and make sure that the actuator fits securely into the recess of the Sensor (Set Clamp Home Sensor).
3. Connect the connector (J8325) of the Main Sensor Harness Assembly (PL 12.15.1) to the Sensor.
4. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.67 Sensor Assembly (Compile Exit Sensor)

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the SCT Tray Assembly (PL 12.4.3) .
3. Release the harness clamp of the Compiler Sensor Harness Assembly (PL 12.11.2) from the front side of the Finisher, and disconnect the connector of the Compiler Sensor Harness Assembly from the Sensor Assembly (Compile Exit Sensor) .
4. Insert the Screwdriver into the space of the Guide Spring, and remove the two Screws securing the Sensor Bracket Assembly (PL 12.11.1) to the Finisher .
5. Remove the Sensor Bracket Assembly from the front side of the Finisher.
6. Remove the Sensor Assembly from the Sensor Bracket Assembly.


Figure 1 Harness Assembly


Figure 2 Sensor Assembly

## Replacement

1. Secure the Sensor Assembly (Compile Exit Sensor) to the Sensor Bracket Assembly (PL 12.11.1).
2. Install the Sensor Bracket Assembly from the front side of the Finisher.
3. Insert the Screwdriver into the space of the Guide Spring, and fix the Sensor Bracket Assembly using two Screws to the Finisher.
4. Connect the connector of the Compiler Sensor Harness Assembly (PL 12.11.2) to the Sensor Assembly.
5. Install the SCT Tray Assembly (PL 12.4.3).
6. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.68 Lower Exit Roll Assembly

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the SCT Tray Assembly (PL 12.4.3) .
4. Remove the Eject Cover (PL 12.4.4) .
5. Remove the Stapler Unit (PL 12.8.14) .
6. Remove the Eject Clamp Bracket Assembly (PL 12.9.10) .
7. Remove the Eject Unit Chute Assembly (PL 12.9.27) .
8. Remove the Compiler Tray Assembly (PL 12.10.1) .
9. Remove the Eject Bracket Assembly (PL 12.10.17) .
10. Remove the Eject Roll Shaft Assembly (PL 12.10.9) .
11. Remove the Right Lower Exit Chute Assembly (PL 12.11.7) .
12. Loosen the two Screws securing the Tension Bracket Assembly (PL 12.13.23) for the Motor Assembly (PL 12.13.30) (Exit Motor) .
13. Move the Tension Bracket Assembly in the direction of the arrow so that the tension of the Belt (PL 12.13.28) decreases, and remove the Belt from each pulley.
14. Disconnect the connector of the Compiler Sensor Harness Assembly (PL 12.11.2) from the Sensor Assembly (PL 12.11.3) (Compile Exit Sensor).


Figure 1 Tension Bracket Assembly
15. Remove the two Screws each on the front and rear securing the Upper Exit Chute (PL 12.11.5) .
16. Remove the Upper Exit Chute.


Figure 2 Upper Exit Chute
17. Release the hook of the T20 Pulley (PL 12.11.18) attached to the Lower Exit Roll Assembly on the rear to remove the T20 Pulley .
18. Remove the Bearing (PL 12.11.17).
19. Remove the E-ring securing the Lower Exit Roll Assembly on the front .
20. Remove the Bearing (PL 12.11.9).
21. Move the Lower Exit Roll Assembly to the rear first to remove the front end of the shaft from the hole on the frame, and remove the Lower Exit Roll Assembly from the Finisher .


Figure 3 T20 Pulley


Figure 4 Exit Roll Assembly Bearing


Figure 5 Lower Exit Roll Assembly

## Replacement

1. Put the rear end of the Lower Exit Shaft Assembly into the hole on the rear first, then put the front end of the Lower Exit Shaft Assembly into the hole on the frame.
2. Install the Bearing (PL 12.11.9) to the Lower Exit Roll Assembly on the front.
3. Secure the Bearing using the E-ring.
4. Install the Bearing (PL 12.11.17) to the Lower Exit Roll Assembly on the rear.
5. Install the T20 Pulley (PL 12.11.18) and secure it using the hook.
6. Install the Upper Exit Chute (PL 12.11.5) to the frame using two Screws each on the front and rear.
7. Connect the connector of the Compiler Sensor Harness Assembly (PL 12.11.2) to the Sensor Assembly (PL 12.11.3) (Compile Exit Sensor).
8. While pushing the Tension Bracket Assembly (PL 12.13.23) in the direction of the arrow, install the Belt (PL 12.13.28) onto each pulley.
9. Fix the Tension Bracket Assembly to the frame using two Screws.

NOTE The tension of the belt is automatically adjusted by the force of the Tension Spring (PL 12.13.24) attached to the Tension Bracket Assembly. Therefore, when tightening the two Screws, be careful not to move the Tension Bracket Assembly.

NOTE Tighten the two Screws in order of (1) and (2) shown in the figure.
10. Install the Right Lower Exit Chute Assembly (PL 12.11.7) .
11. Install the Eject Roll Shaft Assembly (PL 12.10.9) .
12. Install the Eject Bracket Assembly (PL 12.10.17) .
13. Install the Compiler Tray Assembly (PL 12.10.1) .
14. Install the Eject Unit Chute Assembly (PL 12.9.27) .
15. Install the Eject Clamp Bracket Assembly (PL 12.9.10) .
16. Install the Stapler Unit (PL 12.8.14) .
17. Install the Eject Cover (PL 12.4.4).
18. Install the SCT Tray Assembly (PL 12.4.3) .
19. Install the Upper Rear Cover (PL 12.4.11) .
20. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.69 Right Lower Exit Chute Assembly

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Lower Rear Cover (PL 12.4.9) .
4. Remove the SCT Tray Assembly (PL 12.4.3) .
5. Remove the Eject Cover (PL 12.4.4) .
6. Remove the Stapler Unit (PL 12.8.14) .
7. Remove the Eject Clamp Bracket Assembly (PL 12.9.10) .
8. Remove the Eject Unit Chute Assembly (PL 12.9.27) .
9. Remove the Compiler Tray Assembly (PL 12.10.1) .
10. Remove the Eject Bracket Assembly (PL 12.10.17) .
11. Remove the Eject Roll Shaft Assembly (PL 12.10.9) .
12. Loosen the two Screws securing the Tension Bracket Assembly (PL 12.13.23) for the Motor Assembly (PL 12.13.30) (Exit Motor) .
13. Move the Tension Bracket Assembly in the direction of the arrow so that the tension of the Belt (PL 12.13.28) decreases, and remove the Belt from each pulley.


Figure 1 Tension Bracket Assembly
14. Loosen the two Screws securing the Tension Bracket Assembly (PL 12.12.26) for the Motor Assembly (PL 12.12.21) (Finisher Transport Motor) .
15. Move the Tension Bracket Assembly in the direction of the arrow so that the tension of the Belt (PL 12.12.23) decreases, and remove the Belt from each pulley.


Figure $\mathbf{2}$ Motor Assembly Tension
16. Release the hook of the T17 Pulley (PL 12.11.14) inside the Finisher to remove the T17 Pulley. At the same time, the Z55 Synchronous Belt (PL 12.11.13) put onto the T17 Pulley is also detached .
17. Remove the Z55 Synchronous Belt from the Paddle Drive Shaft (PL 12.11.15).

## NOTE Since the Belt is put onto the Paddle Shaft Assembly (PL 12.11.12) on the Right Lower Exit Chute Assembly (PL 12.11.7), the Belt cannot be detached from the Finisher.

18. Remove the Bearing (PL 12.11.9) adjacent to the removed T17 Pulley.


Figure 3 T17 Pulley
19. Release the hook of the T44/Z20 Pulley (PL 12.11.21) from the rear to remove .
20. Pull out the Paddle Drive Shaft.
21. Remove the Bearing (PL 12.11.9) from the Paddle Drive Shaft.
22. Remove the Z23 Gear (PL 12.11.19).


Figure 4 T44IZ20 Pulley
23. Remove the two Screws each on the front and rear securing the Right Lower Exit Chute Assembly to the Finisher .
24. While moving the Right Lower Exit Chute Assembly to the front, move the rear side of the Right Lower Exit Chute Assembly downward to remove it from the frame, and then remove the Right Lower Exit Chute Assembly from the Finisher.


Figure 5 Lower Exit Chute Assembly

## Replacement

1. Put the Right Lower Exit Chute Assembly into the Finisher. Move the Right Lower Exit Chute Assembly to the front first, and lift its rear side up to install it to the frame.
2. Fix the Right Lower Exit Chute to the Finisher using two Screws each on the front and rear.
3. Install the Z23L Gear (PL 12.11.19).
4. Install the Bearing (PL 12.11.9) to the frame on the rear.
5. Install the T44/Z20 Pulley (PL 12.11.21) to the Paddle Drive Shaft (PL 12.11.15), and secure it with the hook.
6. Insert the Paddle Drive Shaft into the Bearing.
7. Put the Bearing (PL 12.11.9) to the Paddle Drive Shaft inside the Finisher, and install the Bearing to the bracket.
8. Put the $\mathbf{Z 5 5}$ Synchronous Belt (PL 12.11.13) attached with the Right Lower Exit Chute Assembly onto the Paddle Drive Shaft.
9. Install the T17 Pulley (PL 12.11.14) to the Paddle Drive Shaft while installing the Belt, and secure the T17 Pulley with the hook.
10. While pushing the Tension Bracket Assembly (PL 12.12.26) for the Motor Assembly (PL 12.12.21) (Finisher Transport Motor) in the direction of the arrow, install the Belt (PL 12.12.23) onto each pulley.
11. Fix the Tension Bracket Assembly to the frame using two Screws.

NOTE The tension of the belt is automatically adjusted by the force of the Tension Spring attached to the Tension Bracket Assembly. Therefore, when tightening the two Screws, be careful not to move the Tension Bracket Assembly.
NOTE Tighten the two Screws in order of (1) and (2) shown in the figure.
12. While pushing the Tension Bracket Assembly (PL 12.13.23) for the Motor Assembly (PL 12.13.30) (Exit Motor) in the direction of the arrow, install the Belt (PL 12.13.28) onto each pulley.
13. Fix the Tension Bracket Assembly to the frame using two Screws.

NOTE The tension of the belt is automatically adjusted by the force of the Tension Spring attached to the Tension Bracket Assembly. Therefore, when tightening the two Screws, be careful not to move the Tension Bracket Assembly.
NOTE Tighten the two Screws in order of (1) and (2) shown in the figure.
14. Install the Eject Roll Shaft Assembly (PL 12.10.9) .
15. Install the Eject Bracket Assembly (PL 12.10.17) .
16. Install the Compiler Tray Assembly (PL 12.10.1) .
17. Install the Eject Unit Chute Assembly (PL 12.9.27) .
18. Install the Eject Clamp Bracket Assembly (PL 12.9.10) .
19. Install the Stapler Unit (PL 12.8.14) .
20. Install the Eject Cover (PL 12.4.4) .
21. Install the SCT Tray Assembly (PL 12.4.3) .
22. Install the Lower Rear Cover (PL 12.4.9) .
23. Install the Upper Rear Cover (PL 12.4.11) .
24. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.70 Exit 1 \& Exit 2 Pinch Roller Assembly

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Lower Rear Cover (PL 12.4.9) .
4. Remove the SCT Tray Assembly (PL 12.4.3) .
5. Remove the Eject Cover (PL 12.4.4).
6. Remove the Stapler Unit (PL 12.8.14) .
7. Remove the Eject Clamp Bracket Assembly (PL 12.9.10) .
8. Remove the Eject Unit Chute Assembly (PL 12.9.27) .
9. Remove the Compiler Tray Assembly (PL 12.10.1) .
10. Remove the Eject Bracket Assembly (PL 12.10.17) .
11. Remove the Eject Roll Shaft Assembly (PL 12.10.9) .
12. Remove the Right Lower Exit Chute Assembly (PL 12.11.7) .
13. Remove the Paddle Shaft Assembly (PL 12.11.12) .
14. Remove the two Screws ( $\mathrm{M} 3 \times 6$ ) securing the two Exit 1 Pinch Roller Assemblies .
15. Remove the two Exit 1 Pinch Roller Assemblies.
16. Remove the two Screws ( $\mathrm{M} 3 \times 6$ ) securing the two Exit 2 Pinch Roller Assemblies.
17. Remove the two Exit 2 Pinch Roller Assemblies.


Figure 1 Lower Exit Chute Assembly

## Replacement

1. Install the two Exit 2 Pinch Roller Assemblies to the Right Lower Exit Chute Assembly (PL 12.11.7) using two Screws (M3 x 6).

NOTE Be careful of the installing place of the Exit 1 Pinch Roller Assembly and the Exit 2 Pinch Roller Assembly.
NOTE Be sure to put the bosses of the Lower Exit Chute Assembly into the two slots on the bracket of the Exit 1 Pinch Roller Assembly.
2. Install the two Exit 2 Pinch Roller Assemblies to the Right Lower Exit Chute Assembly using two Screws (M3 x 6).
NOTE Be sure to put the bosses of the Lower Exit Chute Assembly into the two slots on the bracket of the Exit 2 Pinch Roller Assembly.
3. Install the Paddle Shaft Assembly (PL 12.11.12) .
4. Install the Right Lower Exit Chute Assembly (PL 12.11.7) .
5. Install the Eject Roll Shaft Assembly (PL 12.10.9) .
6. Install the Eject Bracket Assembly (PL 12.10.17) .
7. Install the Compiler Tray Assembly (PL 12.10.1) .
8. Install the Eject Unit Chute Assembly (PL 12.9.27) .
9. Install the Eject Clamp Bracket Assembly (PL 12.9.10) .
10. Install the Stapler Unit (PL 12.8.14) .
11. Install the Eject Cover (PL 12.4.4) .
12. Install the SCT Tray Assembly (PL 12.4.3) .
13. Install the Lower Rear Cover (PL 12.4.9) .
14. Install the Upper Rear Cover (PL 12.4.11) .
15. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.71 Paddle Shaft Assembly

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Lower Rear Cover (PL 12.4.9) .
4. Remove the SCT Tray Assembly (PL 12.4.3) .
5. Remove the Eject Cover (PL 12.4.4) .
6. Remove the Stapler Unit (PL 12.8.14) .
7. Remove the Eject Clamp Bracket Assembly (PL 12.9.10) .
8. Remove the Eject Unit Chute Assembly (PL 12.9.27) .
9. Remove the Compiler Tray Assembly (PL 12.10.1) .
10. Remove the Eject Bracket Assembly (PL 12.10.17) .
11. Remove the Eject Roll Shaft Assembly (PL 12.10.9) .
12. Remove the Right Lower Exit Chute Assembly (PL 12.11.7) .
13. Remove the two E-rings securing the Paddle Shaft Assembly to the Right Lower Exit Chute Assembly .
14. Remove the Bearing (PL 12.11.9).
15. Move the Paddle Shaft Assembly to the front first to remove the Bearing on the front from the Right Lower Exit Chute Assembly, and then remove the Paddle Shaft Assembly from the Right Lower Exit Chute Assembly.
16. Remove the Belt (PL 12.11.13) from the Paddle Shaft Assembly.


Figure 1 Paddle Shaft Assembly

## Replacement

1. Install the Belt (PL 12.11.13) to the Paddle Shaft Assembly.
2. Put the Bearing attached with the Paddle Shaft Assembly into the hole of the bracket on the Right Lower Exit Chute Assembly (PL 12.11.7).
3. Install the Bearing (PL 12.11.9) to the Paddle Shaft Assembly.
4. Fix the Bearings using two E-rings.
5. Install the Right Lower Exit Chute Assembly (PL 12.11.7) .
6. Install the Eject Roll Shaft Assembly (PL 12.10.9)
7. Install the Eject Bracket Assembly (PL 12.10.17) .
8. Install the Compiler Tray Assembly (PL 12.10.1) .
9. Install the Eject Unit Chute Assembly (PL 12.9.27) .
10. Install the Eject Clamp Bracket Assembly (PL 12.9.10) .
11. Install the Stapler Unit (PL 12.8.14) .
12. Install the Eject Cover (PL 12.4.4) .
13. Install the SCT Tray Assembly (PL 12.4.3) .
14. Install the Lower Rear Cover (PL 12.4.9) .
15. Install the Upper Rear Cover (PL 12.4.11) .
16. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.72 Upper Exit Open Chute Assembly

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Open the Upper Exit Open Chute Assembly to the right by hand.
3. Remove the one Screw on the front securing the Upper Exit Open Chute Assembly to the frame .
4. Remove the Upper Exit Open Chute Assembly from the front.


Figure 1 Upper Exit Open Chute Assembly

## Replacement

1. Put the Upper Exit Open Chute Assembly to the Finisher from the front, and put the Screw on the rear of the frame into the hole of the Upper Exit Open Chute Assembly.
2. Secure the Upper Exit Open Chute Assembly to the frame using one Screw on the front.
3. Close the Upper Exit Open Chute Assembly.
4. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.73 Pinch Roller

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Upper Exit Open Chute Assembly (PL 12.12.1).
4. Remove the 1.9N Spring (PL 12.12.3) left and right, and remove the Shaft (PL 12.12.4) attached with the two Pinch Rollers .
5. Remove the two Pinch Rollers from the Shaft.

## NOTE Remove another Pinch Roller using the same procedure.



Figure 1 Pinch Rollers

## Replacement

1. Install the two Pinch Rollers on both ends of the Shaft (PL 12.12.4).
2. Install the Shaft attached with two Pinch Rollers to the Upper Exit Open Chute Assembly (PL 12.12.1) using two 1.9N Springs (PL 12.12.3). (Refer to the detailed figure.)

## NOTE Install another Pinch Roller using the same procedure.

3. Install the Upper Exit Open Chute Assembly (PL 12.12.1).
4. Install the Upper Rear Cover (PL 12.4.11) .
5. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.74 Gate

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11).
3. Open the Lower Left Top Exit Chute Assembly (PL 12.13.10) to the right by hand .


Figure 1 Top Exit Chute Assembly
4. Remove the Solenoid Bracket Assembly (PL 12.12.32) (Transport Gate Solenoid) on the rear.
5. Remove the Link (PL 12.12.33) on the rear .
6. Move the Gate in the direction of the arrow from the front to remove the Gate.


Figure 2 Solenoid Bracket Assembly

## Replacement

1. Move the Gate in the opposite direction of the arrow from the front, and install it to the Finisher.

NOTE Install the Gate with its one end with the hole facing the rear.
2. Put the Link (PL 12.12.33) into the hole on the Gate from the rear.
3. Install the Solenoid Bracket Assembly (PL 12.12.32) (Transport Gate Solenoid) .
4. Close the Lower Left Top Exit Chute Assembly (PL 12.13.10) to the left by hand.
5. Install the Upper Rear Cover (PL 12.4.11) .
6. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.75 Buffer Gate

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11).
3. Remove the Solenoid Bracket Assembly (PL 12.12.32) (Buffer Gate Solenoid) on the rear .
4. Remove the Buffer Link (PL 12.12.30) on the rear .


Figure 1 Solenoid Bracket Assembly
5. Open the Upper Exit Open Chute Assembly (PL 12.12.1) to the right by hand .
6. Move the Buffer Gate in the direction of the arrows from the front to remove the Buffer Gate.


Figure 2 Upper Exit Chute Assembly

## Replacement

1. Move the Buffer Gate in the opposite direction of the arrow from the front, and install it to the Finisher.

## NOTE Install the Buffer Gate with its one end with the hole facing the rear

2. Put the Buffer Link (PL 12.12.30) into the hole on the Buffer Gate from the rear.
3. Install the Solenoid Bracket Assembly (PL 12.12.34) (Buffer Gate Solenoid) .
4. Install the Upper Rear Cover (PL 12.4.11) .
5. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.76 Buffer Path Sensor Assembly

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Top Cover (PL 12.4.1).
4. Remove the Left Hand Front Cover (PL 12.5.8) .
5. Remove the Left Hand Top Cover (PL 12.5.9) .
6. Remove the Punch Frame Assembly (PL 12.7.1) .
7. Disconnect the connector (J8392) of the Buffer Sensor Harness Assembly (PL 12.15.5) from the Sensor Assembly (Buffer Path Sensor) .
8. Remove the one Screw ( $\mathrm{M} 3 \times 8$ ) securing the Sensor Bracket (PL 12.12.11) attached with the Sensor Assembly to the Top Buffer Chute Assembly (PL 12.12.10).
9. Remove the Sensor Bracket.
10. Release the four hooks securing the Sensor Assembly to remove the Sensor Assembly from the Sensor Bracket.


Figure 1 Buffer Path Sensor

## Replacement

1. Install the Sensor Assembly to the Sensor Bracket (PL 12.12.11) and secure it with the four hooks.
2. Install the Sensor Bracket to the Top Buffer Chute Assembly (PL 12.12.10) using one Screw (M3 x 8).
NOTE When installing the Sensor Bracket, be sure to put the actuator of the Sensor Assembly into the hole of the Top Buffer Chute Assembly.
NOTE Put the boss on the Top Buffer Chute Assembly into the hole of the Sensor Bracket.
3. Connect the connector (J8392) of the Buffer Sensor Harness Assembly (PL 12.15.5) to the Sensor Assembly.
4. Install the Punch Frame Assembly (PL 12.7.1) .
5. Install the Left Hand Top Cover (PL 12.5.9) .
6. Install the Left Hand Front Cover (PL 12.5.8) .
7. Install the Top Cover (PL 12.4.1) .
8. Install the Upper Rear Cover (PL 12.4.11) .
9. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.77 Buffer Roll Assembly

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11) .
2. Open the Front Cover Assembly (PL 12.5.3).
3. Remove the Stapler Cartridge Assembly (PL 12.8.1).
4. Move the Stapler to the rear by hand as far as it will move.
5. Open the Upper Exit Open Chute Assembly (PL 12.12.14) to the right by hand .
6. Lift the Buffer Gate (PL 12.12.7) with finger.
7. Open the Bottom Buffer Chute Assembly (PL 12.12.1) downward by hand.

8. Remove the E-ring securing the shaft of the Buffer Roll Assembly on the front .
9. Remove the Bearing (PL 12.12.9).


Figure 2 Buffer Roll Assembly
10. Remove the Solenoid Bracket Assembly (PL 12.12.32) (Transport Gate Solenoid) on the rear.
11. Loosen the two Screws securing the Tension Bracket Assembly (PL 12.13.23) for the Motor Assembly (PL 12.13.30) (Registration Motor) .
12. Move the Tension Bracket Assembly in the direction of the arrow so that the tension of the Belt (PL 12.13.27) decreases, and remove the Belt from each pulley.


Figure 3 Registration Motor Tension Bracket
13. Remove the E-ring securing the T53/Z23 Pulley (PL 12.13.19) .
14. Remove the T53/Z23 Pulley.
15. Release the hook of the Z46 Gear (PL 12.12.28) to remove the Z46 Gear from the shaft on the Buffer Roll Assembly.
16. Remove the Bearing (PL 12.12.9).


Figure 4 T53IZ23 Pulley
17. Move the Buffer Roll Assembly to the rear to remove the front end of the shaft from the hole on the frame .
18. Move the Buffer Roll Assembly downward first, then remove it from the Finisher.

NOTE Do not hold the rubber roller of the Buffer Roll Assembly.


Figure 5 Buffer Roll Assembly

## Replacement

1. Put the rear end of the Buffer Roll Assembly into the hole on the rear frame first, and put the front end of the shaft into the hole on the front frame.
NOTE Install the Buffer Roll Assembly with its one end with the flat surface facing the rear.
NOTE Be careful not to hold the rubber roller of the Buffer Roll Assembly.
2. Install the Bearing (PL 12.12.9) to the shaft of the Buffer Roll Assembly on the rear.
3. Install the Z46 Gear (PL 12.12.28) and secure it using its hook.
4. Install the T53/Z23 Pulley (PL 12.13.19) and secure it using the E-ring.
5. While pushing the Tension Bracket Assembly (PL 12.13.23) in the direction of the arrow, install the Belt (PL 12.13.27) onto each pulley.
6. Fix the Tension Bracket Assembly to the frame using two Screws.

NOTE The tension of the belt is automatically adjusted by the force of the Tension Spring (PL 12.13.24) attached to the Tension Bracket Assembly. Therefore, when tightening the two Screws, be careful not to move the Tension Bracket Assembly.
NOTE Tighten the two Screws in order of (1) and (2) shown in the figure.
7. Install the Solenoid Bracket Assembly (PL 12.12.32) (Transport Gate Solenoid) .
8. Install the Bearing (PL 12.12.9) to the shaft on the Buffer Roll Assembly on the front, and secure it with the E-ring.
9. Lift the Bottom Buffer Chute Assembly (PL 12.12.14) by hand to close.
10. Move the Buffer Gate (PL 12.12.7) toward the Buffer Roll Assembly by hand.
11. Close the Upper Exit Open Chute Assembly (PL 12.12.1).
12. Move the Stapler to the front by hand.
13. Install the Stapler Cartridge Assembly (PL 12.8.1).
14. Close the Front Cover Assembly (PL 12.5.3).
15. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.78 Bottom Buffer Chute Assembly

## Removal

1. Remove the Front Cover Assembly (PL 12.5.3) .
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Stapler Unit (PL 12.8.14) .
4. Remove the two bosses on the rear of the Bottom Buffer Chute Assembly from the two holes on the rear frame .


Figure 1 Bottom Buffer Chute Assembly

## Replacement

1. Install the two bosses on the rear of the Bottom Buffer Chute into the two holes on the rear frame.
2. Install the Stapler Unit (PL 12.8.14) .
3. Install the Upper Rear Cover (PL 12.4.11) .
4. Install the Front Cover Assembly (PL 12.5.3) .

## RRP 12.79 Exit Pinch Roller Assembly

## Removal

1. Open the Front Cover Assembly.
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Buffer Roll Assembly (PL 12.12.13) .
4. Remove the Bottom Buffer Chute Assembly (PL 12.12.14) .
5. Remove the one Screw ( $\mathrm{M} 3 \times 8$ ) securing the Exit Pinch Roller Assembly to the Bottom Buffer Chute Assembly .

NOTE Remove the other three Pinch Rollers using the same procedure.


Figure 1 Exit Pinch Roller Assembly

## Replacement

1. Install the Exit Pinch Roller Assembly to the Bottom Buffer Chute Assembly using one Screw (M3 x 8).

NOTE Put the two bosses of the Bottom Buffer Chute Assembly into the two holes on the Exit Pinch Roller Assembly.
2. Ins
12.12.14) .
3. Install the Buffer Roll Assembly (PL 12.12.13) .
4. Install the Upper Rear Cover (PL 12.4.11) .
5. Close the Front Cover Assembly.

## RRP 12.80 Upper Entrance Chute Assembly

## Removal

1. Open the Front Cover Assembly.
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Left Hand Front Cover (PL 12.5.8) .
4. Remove the Left Hand Top Cover (PL 12.5.9) .
5. Disconnect the connector (J8319) of the Transport Entrance Sensor Harness Assembly (PL 12.15.4) from the Sensor (PL 12.12.19) (Transport Entrance Sensor) .
6. Release the Transport Entrance Sensor Harness Assembly from the clamp of the Sensor Bracket (PL 12.12.18).


Figure 1 Transport Entrance Sensor
7. Remove the three Screws securing the Upper Entrance Chute Assembly on the rear, and remove the hinge of the Upper Entrance Chute Assembly from the square hole on the rear frame .
8. Remove the Upper Entrance Chute Assembly from the front.


Figure 2 Upper Entrance Chute Assembly

## Replacement

1. Put the Upper Entrance Chute Assembly into the Finisher from the front, put the hinge of the Upper Entrance Chute Assembly into the square hole on the rear frame.
2. Install the Upper Entrance Chute Assembly at the rear using three Screws.
3. Secure the Transport Entrance Sensor Harness Assembly (PL 12.15.4) with the clamp of the Sensor Bracket (PL 12.12.18).
4. Connect the connector (J8319) of the Transport Entrance Sensor Harness Assembly to the Sensor (PL 12.12.19) (Transport Entrance Sensor).
5. Install the Left Hand Top Cover (PL 12.5.9) .
6. Install the Left Hand Front Cover (PL 12.5.8) .
7. Install the Upper Rear Cover (PL 12.4.11) .
8. Close the Front Cover Assembly.

## RRP 12.81 Entrance Pinch Roller Assembly

NOTE Upper Entrance Chute Assembly (PL 12.12.16) has four Entrance Pinch Roller Assemblies. Their removal and replacement procedures are the same.

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Top Cover (PL 12.4.1).
4. Remove the Left Hand Front Cover (PL 12.5.8) .
5. Remove the Left Hand Top Cover (PL 12.5.9) .
6. Remove the one Screw (M3 x 6) securing the Entrance Pinch Roller Assembly to the Upper Entrance Chute Assembly (PL 12.12.16) .
7. Remove the Entrance Pinch Roller Assembly.


Figure 1 Entrance Pinch Roller Assembly

## Replacement

 12.12.16) using one Screw (M3 x 6).

NOTE Be sure to put the two bosses of the Upper Entrance Chute Assembly into the two holes on the bracket of the Entrance Pinch Roller Assembly.
2. Install the Left Hand Top Cover (PL 12.5.9) .
3. Install the Left Hand Front Cover (PL 12.5.8) .
4. Install the Top Cover (PL 12.4.1) .
5. Install the Upper Rear Cover (PL 12.4.11) .
6. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.82 Transport Entrance Sensor

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Top Cover (PL 12.4.1) .
4. Remove the Left Hand Front Cover (PL 12.5.8) .
5. Remove the Left Hand Top Cover (PL 12.5.9) .
6. Disconnect the connector (J8319) of the Transport Entrance Sensor Harness Assembly (PL 12.15.4) from the Sensor (Transport Entrance Sensor) .
7. Release the Transport Entrance Sensor Harness Assembly from the clamp of the Sensor Bracket (PL 12.12.18).
8. Remove the one Screw (M3 x 6) securing the Sensor Bracket to the Upper Entrance Chute Assembly (PL 12.12.16).
9. Remove the Sensor Bracket.
10. Remove the one Screw ( $\mathrm{M} 3 \times 12$ ) securing the Sensor (Transport Entrance Sensor) to the Sensor Bracket.
11. Remove the Sensor.


Figure 1 Transport Entrance Sensor

## Replacement

1. Install the Sensor (Transport Entrance Sensor) to the Sensor Bracket (PL 12.12.18) using one Screw (M3 x 12).
NOTE Install the Sensor in the direction shown in the figure.
2. Install the Sensor Bracket to the Upper Entrance Chute Assembly (PL 12.12.16) using one Screw (TP M3 x 6).
3. Connect the connector (J8319) of the Transport Entrance Sensor Harness Assembly (PL 12.15.4) to the Sensor.
4. Secure the Transport Entrance Sensor Harness Assembly with the clamp of the Sensor Bracket.
5. Install the Left Hand Top Cover (PL 12.5.9) .
6. Install the Left Hand Front Cover (PL 12.5.8) .
7. Install the Top Cover (PL 12.4.1) .
8. Install the Upper Rear Cover (PL 12.4.11) .
9. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.83 Entrance Roll Assembly

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Left Hand Top Cover (PL 12.5.9) .
4. Pull the Dust Box Assembly toward you to remove it from the Finisher .
5. Remove the three Screws on the front and one Screw on the rear securing the Dust Box Chute Assembly to the Finisher to remove the Dust Box Chute Assembly.
6. Open the lever of the Upper Entrance Chute Assembly (PL 12.12.16) upward by hand.
7. Remove the Punch Frame Assembly (PL 12.7.1) .


Figure 1 Punch Frame Assembly
8. Loosen the two Screws securing the Tension Bracket Assembly (PL 12.12.26) for the Motor Assembly (PL 12.12.21) (Finisher Transport Motor) .
9. Move the Tension Bracket Assembly in the direction of the arrow so that the tension of the Belt (PL 12.12.23) decreases, and remove the Belt from each pulley.


Figure 2 Tension Bracket Assembly
10. Release the hook of the Z23 Gear (PL 12.12.31) on the rear attached to the Entrance Roll Assembly to remove the Z23 Gear .
11. Remove the T20 Pulley (PL 12.12.29).
12. Remove the Bearing (PL 12.12.27).


Figure 3 Z23 Gear
13. Remove the E-ring securing the Entrance Roll Assembly on the front .
14. Remove the Bearing (PL 12.12.9).
15. Push the Entrance Roll Assembly to the rear to remove the front end of the Entrance Roll Assembly from the hole on the frame first, and move the Entrance Roll Assembly downward to remove it from the front.


Figure 4 Entrance Roll Assembly

## Replacement

1. Move the Entrance Roll Assembly in the opposite direction of the arrow to install it to the Finisher.

NOTE Install the Entrance Roll Assembly with its one end with the flat surface facing the rear.
NOTE Be careful not to hold the rubber roller of the Entrance Roll Assembly.
2. Install the Bearing (PL 12.12.9) to the shaft of the Entrance Roll Assembly on the front.
3. Secure the Bearing using the E-ring.
4. Install the Bearing (PL 12.12.27) to the Entrance Roll Assembly on the rear.
5. Install the T20 Pulley (PL 12.12.29) to the Entrance Roll Assembly.
6. Install the Z23 Gear (PL 12.12.31) to the Entrance Roll Assembly, and secure it using the hook.
7. While pushing the Tension Bracket Assembly (PL 12.12.26) in the direction of the arrow, install the Belt (PL 12.12.23) onto each pulley.
8. Fix the Tension Bracket Assembly to the frame using two Screws.

NOTE The tension of the belt is automatically adjusted by the force of the Tension Spring attached to the Tension Bracket Assembly. Therefore, when tightening the two Screws, be careful not to move the Tension Bracket Assembly.
NOTE Tighten the two Screws in order of (1) and (2) shown in the figure.
9. Install the Dust Box Chute Assembly using the three Screws on the front and one Screw on the rear.
10. Install the Dust Box Assembly (PL 12.7.20).
11. Close the Upper Entrance Chute Assembly (PL 12.12.16).
12. Install the Punch Frame Assembly (PL 12.7.1) .
13. Install the Left Hand Top Cover (PL 12.5.9) .
14. Install the Upper Rear Cover (PL 12.4.11) .
15. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.84 Finisher Transport Motor \& Belt Assembly

1. Remove the Upper Rear Cover (PL 12.4.11).
2. Loosen the two Screws ( $\mathrm{M} 3 \times 6$ ) securing the Tension Bracket Assembly (PL 12.12.26) for the Motor Assembly (PL 12.12.21) (Finisher Transport Motor) .
3. Move the Tension Bracket Assembly in the direction of the arrow so that the tension of the Belt (PL 12.12.23) decreases, and remove the Belt from each pulley.


Figure 1 Tension Bracket Assembly
4. Disconnect the connector (J8342) of the Main Drive Harness Assembly (PL 12.15.2) from the Motor Assembly.
5. Remove the two Screws (M3 x 6) securing the Motor Assembly.
6. Remove the Motor Assembly.
7. Remove the two Screws securing the Motor Assembly to the Motor Bracket (PL 12.12.22) to remove the Motor Assembly.


Figure 2 Motor Assembly

## Replacement

1. Install the Motor Assembly (Finisher Transport Motor) to the Motor Bracket (PL 12.12.22) in the direction shown in the figure using two Screws.
2. Install the Motor Assembly to the Finisher using two Screws (M3 x 6).

NOTE Be sure to put the two bosses of the chassis into the two holes on the Bracket Assembly attached with the Motor Assembly.
3. Connect the connector (J8342) of the Main Drive Harness Assembly (PL 12.15.2) to the Motor Assembly.
4. While pushing the Tension Bracket Assembly (PL 12.12.26) in the direction of the arrow, install the Belt (PL 12.12.23) onto each pulley.
5. Fix the Tension Bracket Assembly to the frame using two Screws.

NOTE The tension of the belt is automatically adjusted by the force of the Tension Spring (PL 12.13.24) attached to the Tension Bracket Assembly. Therefore, when tightening the two Screws, be careful not to move the Tension Bracket Assembly.
NOTE Tighten the two Screws in order of (1) and (2) shown in the figure.
6. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.85 Transport Gate Solenoid Bracket Assembly

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Disconnect the harness connector (J8341) of the Solenoid Bracket Assembly (Transport Gate Solenoid) from the Main Drive Harness Assembly (PL 12.15.2) .
4. Release the harness of the Solenoid Bracket Assembly from the clamp.
5. Remove the two Screws securing the Harness Bracket (PL 12.14.1).

NOTE In this procedure, remove only two Screws securing the Harness Bracket to make easier to perform the removal and replacement procedures for the Solenoid Bracket Assembly, not to remove the Harness Bracket itself from the Finisher.
6. Remove the two Screws securing the Solenoid Bracket Assembly to the Finisher.

NOTE When removing, Link (PL 12.12.33) may be detached together with the Solenoid Bracket Assembly or it may remain on the frame. When it remains on the frame, remove it.
NOTE When the Link is removed, Gate (PL 12.12.6) will be detached inside of the Finisher. If it is detached, install it referring to .


Figure 1 Solenoid Bracket Assembly

## Replacement

1. While holding the Gate (PL 12.12.6) from the front, put the Link (PL 12.12.33) into the hole on the Gate in the direction shown in the figure from the rear.
2. Install the Solenoid Bracket Assembly (Transport Gate Solenoid) to the Finisher while putting the GUIDE attached with the iron core of the solenoid into the notch of the Link.
3. Install the Solenoid Bracket Assembly to the Finisher using two Screws.
4. Fix the Harness Bracket (PL 12.14.1) to the Finisher using two Screws.
5. Secure the harness of the Solenoid Bracket Assembly using the clamp.
6. Connect the harness connector (J8341) of the Solenoid Bracket Assembly to the Main Drive Harness Assembly (PL 12.15.2).
7. Install the Upper Rear Cover (PL 12.4.11) .
8. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.86 Buffer Gate Solenoid Bracket Assembly

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Disconnect the harness connector (J8394) of the Solenoid Bracket Assembly (Buffer Gate Solenoid) from the Main Drive Harness Assembly (PL 12.15.2) .
4. Release the harness of the Solenoid Bracket Assembly from the clamp.
5. Remove the two Screws securing the Solenoid Bracket Assembly to the Finisher.
6. Remove the Solenoid Bracket Assembly.

NOTE When removing, Buffer Link (PL 12.12.30) may be detached together with the Solenoid Bracket Assembly or it may remain on the frame. When it remains on the frame, remove it.

NOTE When the Buffer Link is removed, Buffer Gate (PL 12.12.7) will be detached inside of the Finisher. If it is detached, install it referring to .


Figure 1 Solenoid Bracket Assembly

## Replacement

1. While holding the Buffer Gate (PL 12.12.7) from the front, put the Buffer Link (PL 12.12.30) into the hole on the Buffer Gate in the direction shown in the figure from the rear.
2. Install the Solenoid Bracket Assembly (Buffer Gate Solenoid) to the Finisher while putting the GUIDE attached with the iron core of the solenoid into the notch of the Buffer Link.
3. Install the Solenoid Bracket Assembly to the Finisher using two Screws.
4. Secure the harness of the Solenoid Bracket Assembly with the clamp.
5. Connect the harness connector (J8394) of the Solenoid Bracket Assembly to the Main Drive Harness Assembly (PL 12.15.2).
6. Install the Upper Rear Cover (PL 12.4.11) .
7. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.87 Top Tray Exit Sensor

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11).
3. Remove the Top Cover (PL 12.4.1) .
4. Disconnect the connector (J8321) of the Top Exit Sensor Harness Assembly (PL 12.15.6) from the Sensor (Top Tray Exit Sensor) .
5. Release the hooks of the Sensor to remove the Sensor from the Upper Right Top Exit Chute Assembly (PL 12.13.1).


Figure 1 Top Tray Exit Sensor

## Replacement

1. Secure the Sensor (Top Tray Exit Sensor) to the Upper Right Top Exit Chute Assembly (PL 12.13.1) using the hooks.
2. Connect the connector (J8321) of the Top Exit Sensor Harness Assembly (PL 12.15.6) to the Sensor.
3. Install the Top Cover (PL 12.4.1) .
4. Install the Upper Rear Cover (PL 12.4.11) .
5. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.88 Exit Pinch Roller Assembly

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Top Cover (PL 12.4.1) .
4. Remove the one Screw (M3 x 6) securing the Exit Pinch Roller Assembly to the Upper Right Top Exit Chute Assembly (PL 12.13.1) to remove .

NOTE Remove the other three Exit Pinch Roller Assemblies using the same procedure.


Figure 1 Exit Pinch Roller Assembly

## Replacement

1. Install the Exit Pinch Roller Assembly to the Upper Right Top Exit Chute Assembly (PL 12.13.1) using one Screw (M3 x 6).

NOTE Be sure to put the two bosses of the Upper Right Top Exit Chute Assembly into the two holes on the Exit Pinch Roller Assembly.
2. Install the Top Cover (PL 12.4.1) .
3. Install the Upper Rear Cover (PL 12.4.11) .
4. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.89 Top Exit Roll Assembly

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Top Cover (PL 12.4.1) .
4. Remove the Motor Assembly (PL 12.13.30) (Exit Motor) .
5. Disconnect the connector (J8321) of the Top Exit Sensor Harness Assembly (PL 12.15.6) from the Sensor (PL 12.13.2) (Top Tray Exit Sensor) .
6. Release the Top Exit Sensor Harness Assembly from the harness clamps.


Figure 1 Top Tray Exit Sensor
7. Remove the two Screws each on the front and rear securing the Upper Right Top Exit Chute Assembly (PL 12.13.1) to the Finisher
8. Remove the two Screws each on the front and rear securing the Lower Top Right Exit Chute Assembly (PL 12.13.4) to the Finisher.


Figure 2 Upper \& Lower Top Exit Chutes


Figure 3 Upper \& Lower Top Exit Chutes
9. Remove the Upper Right Top Exit Chute Assembly and the Lower Top Right Exit Chute Assembly .


Figure 4 Exit Chutes
10. Release the hook of the Gear (PL 12.13.26) on the rear to remove the Gear from the Top Exit Roll Assembly .
11. Remove the Bearing (PL 12.13.9).


Figure 5 Gear
12. Remove the E-ring securing the Top Exit Roll Assembly on the front .
13. Remove the Bearing (PL 12.13.9).
14. Move the Top Exit Roll Assembly to the front to remove the rear end of the shaft from the rear hole on the frame, and remove the Top Exit Roll Assembly from the Finisher.

## NOTE Do not hold the rubber roller of the Top Exit Roll Assembly.



Figure 6 Roll Assembly Bearing

## Replacement

1. Put the front end of the Top Exit Roll Assembly into the hole on the front frame first, and put the rear end of the shaft into the hole on the rear frame.

NOTE Do not hold the rubber roller of the Top Exit Roll Assembly.
NOTE Install the Top Exit Roll Assembly with its one end with the flat surface facing the rear.
2. Install the Bearing (PL 12.13.9) to the Top Exit Roll Assembly on the front.
3. Secure the Bearing using the E-ring.
4. Install the Bearing (PL 12.13.9) to the Top Exit Roll Assembly on the rear.
5. Install the Gear (PL 12.13.26) to the Top Exit Roll Assembly on the rear, and secure it with the hook.
6. Install the Lower Top Right Exit Chute Assembly (PL 12.13.4) to the Finisher using two Screws each on the front and rear.
7. Install the Upper Right Top Exit Chute Assembly (PL 12.13.1) to the Finisher using two Screws each on the front and rear.
8. Connect the connector (J8321) of the Top Exit Sensor Harness Assembly (PL 12.15.6) to the Sensor (PL 12.13.2) (Top Tray Exit Sensor).
9. Secure the Top Exit Sensor Harness Assembly using a harness clamps.
10. Install the Motor Assembly (PL 12.13.30) (Exit Motor) .
11. Install the Top Cover (PL 12.4.1) .
12. Install the Upper Rear Cover (PL 12.4.11) .
13. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.90 Top Tray Full Sensor

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the one Screw ( $\mathrm{M} 3 \times 8$ ) on the front side securing the Sensor Bracket Assembly (PL 12.13.6) .
3. Pull the Sensor Bracket Assembly to the front.


Figure 1 Sensor Bracket Assembly
4. Move the Sensor Bracket Assembly downward so that the Sensor Bracket Assembly can be seen from the front side of the Finisher .
5. Release the Top Sensor Harness Assembly (PL 12.15.7) from the clamp on the Sensor Bracket Assembly.
6. Pull the Sensor Bracket Assembly to the front, and remove the one Screw securing the Sensor (Top Tray Full Sensor).
7. Disconnect the connector (J8322) of the Top Sensor Harness Assembly from the Sensor.


Figure 2 Top Tray Full Sensor

## Replacement

1. Connect the connector (J8322) of the Top Sensor Harness Assembly (PL 12.15.7) to the Sensor (Top Tray Full Sensor).
2. Install the Sensor to the Sensor Bracket Assembly (PL 12.13.6) using the one Screw.

NOTE Install the Sensor so that the sensing portion faces to the SCT Tray Assembly (PL 12.4.3).
3. Clamp the Top Sensor Harness Assembly to the Sensor Bracket Assembly using the clamp.
4. Move the Sensor Bracket Assembly upward, and place it to the installing position on the frame.
5. Secure the Sensor Bracket Assembly to the front frame using the one Screw (M3 $\times 8$ ).
6. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.91 Lower Left Top Exit Chute Assembly

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Motor Assembly (PL 12.13.30) (Registration Motor) .
4. Remove the three Screws securing the hinge of the Lower Left Top Exit Chute Assembly on the rear .


Figure 1 Top Exit Chute Assembly
5. Remove the Lower Left Top Exit Chute Assembly from the Finisher while removing the hinge of the Lower Left Top Exit Chute Assembly from the square hole on the rear frame .


Figure 2 Top Exit Chute Assembly

## Replacement

1. Put the Lower Left Top Exit Chute Assembly into the Finisher from the front, and put the hinge of the Lower Left Top Exit Chute Assembly into the square hole on the rear frame.
2. Install the hinge of the Lower Left Top Exit Chute Assembly to the rear frame using three Screws.
3. Install the Motor Assembly (PL 12.13.30) (Registration Motor) .
4. Install the Upper Rear Cover (PL 12.4.11) .
5. Close the Front Cover Assembly (PL 12.5.3).

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11) .
3. Remove the Motor Assembly (PL 12.13.30) (Registration Motor) .
4. Remove the Lower Left Top Exit Chute Assembly (PL 12.13.10) .
5. Remove the 1.5N Spring (PL 12.13.12) left and right, and remove the Shaft (PL 12.13.13) attached with the two Pinch Rollers.
6. Remove the two Pinch Rollers from the Shaft.

## NOTE Remove another Pinch Roller using the same procedure.



Figure 1 Lower Left Top Exit Chute Assembly

## Replacement

1. Install the two Pinch Rollers on both ends of the Shaft (PL 12.13.13).
2. Install the Shaft attached with the two Pinch Rollers to the Lower Left Top Exit Chute Assembly (PL 12.13.10) using the two 1.5N Springs (PL 12.13.12). (Refer to the detailed figure.)

## NOTE Install another Pinch Roller using the same procedure.

3. Install the Lower Left Top Exit Chute Assembly .
4. Install the Motor Assembly (PL 12.13.30) (Registration Motor) .
5. Install the Upper Rear Cover (PL 12.4.11) .
6. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.93 Gate Sensor

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11).
3. Remove the Top Cover (PL 12.4.1) .
4. Remove the Left Hand Front Cover (PL 12.5.8) .
5. Remove the Left Hand Top Cover (PL 12.5.9) .
6. Remove the Punch Frame Assembly (PL 12.7.1) .
7. Open the Upper Entrance Chute Assembly (PL 12.12.16).
8. Remove the three Screws securing the Sensor Bracket (PL 12.13.17) to the Upper Left Top Exit Chute Assembly to remove.
9. Disconnect the connector of the Sensor Harness Assembly (PL 12.13.16) from the Sensor (Gate Sensor).
10. Remove the one Screw securing the Sensor (Gate Sensor) to remove it from the Sensor Bracket.


Figure 1 Top Exit Chute Assembly

## Replacement

1. Install the Sensor (Gate Sensor) to the Sensor Bracket (PL 12.13.17) using one Screw.
2. Connect the connector of the Sensor Harness Assembly (PL 12.13.16) to the Sensor.
3. Install the Sensor Bracket to the Upper Left Top Exit Chute Assembly (PL 12.13.14) using three Screws.
4. Close the Upper Entrance Chute Assembly (PL 12.12.16).
5. Install the Punch Frame Assembly (PL 12.7.1) .
6. Install the Left Hand Top Cover (PL 12.5.9) .
7. Install the Left Hand Front Cover (PL 12.5.8) .
8. Install the Top Cover (PL 12.4.1) .
9. Install the Upper Rear Cover (PL 12.4.11) .
10. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.94 Transport Roll Assembly

Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Remove the Upper Rear Cover (PL 12.4.11).
3. Remove the Top Cover (PL 12.4.1) .
4. Remove the Left Hand Front Cover (PL 12.5.8) .
5. Remove the Left Hand Top Cover (PL 12.5.9) .
6. Remove the Punch Frame Assembly (PL 12.7.1) .
7. Open the Lower Left Top Exit Chute Assembly (PL 12.13.10) to the right by hand .


Figure 1 Lower Left Top Exit Chute Assembly
8. Remove the two Screws securing the Upper Left Top Exit Chute Assembly (PL 12.13.14) on the front .
9. Remove the two Screws securing the Upper Left Top Exit Chute Assembly on the rear .
10. Push the Upper Left Top Exit Chute Assembly toward the paper exit side slightly.

NOTE There is no need to remove the Upper Left Top Exit Chute Assembly from the Finisher. Move the Upper Left Top Exit Chute Assembly slightly so that the rubber roller of the Transport Roll Assembly can be easily removed from the square holes on the Upper Left Top Exit Chute Assembly.
11. Remove the two Screws securing the Harness Bracket (PL 12.14.1).

NOTE In this procedure, remove only two Screws securing the Harness Bracket to make easier to remove the gear from the Finisher, not to remove the Harness Bracket itself from the Finisher.
12. Loosen the two Screws securing the Tension Bracket Assembly (PL 12.13.23) for the Motor Assembly (PL 12.13.30) (Registration Motor) .
13. Move the Tension Bracket Assembly in the direction of the arrow so that the tension of the Belt (PL 12.13.27) decreases, and remove the Belt from each pulley.
14. Remove the Gear (PL 12.13.21) attached to the Transport Roll Assembly on the rear .
15. Remove the Bearing (PL 12.13.20).


Figure 2 Upper Left Top Exit Chute Assembly - Front


Figure 3 Upper Left Top Exit Chute Assembly - Rear
16. Remove the E-ring securing the Transport Roll Assembly on the front .
17. Remove the Bearing (PL 12.13.9).
18. Move the Transport Roll Assembly to the front to remove the rear end of the Transport Roll Assembly from the hole on the rear frame first, and remove it from the Finisher.

MOTOR ASSY (PL25.13.30)


Figure 4 Tension Bracket Assembly


Figure 5 Transport Roll Assembly


Figure 6 Transport Roll Assembly

## Replacement

1. Put the front end of the Transport Roll Assembly into the hole on the front frame first, and put the shaft into the hole on the rear frame.

## NOTE Do not to hold the rubber roller of the Transport Roll Assembly.

2. Install the Bearing (PL 12.13.9) to the Transport Roll Assembly on the front.
3. Secure the Bearing using the E-ring.
4. Install the Bearing (PL 12.13.20) to the Transport Roll Assembly on the rear.
5. Install the Gear (PL 12.13.21) to the shaft of the Transport Roll Assembly on the rear.
6. Install the Upper Left Top Exit Chute Assembly (PL 12.13.14) using two Screws each on the front and rear.
7. While pushing the Tension Bracket Assembly (PL 12.13.23) in the direction of the arrow, install the Belt (PL 12.13.27) onto each pulley.
8. Fix the Tension Bracket Assembly to the frame using two Screws.

NOTE The tension of the belt is automatically adjusted by the force of the Tension Spring (PL 12.13.24) attached to the Tension Bracket Assembly. Therefore, when tightening the two Screws, be careful not to move the Tension Bracket Assembly.
NOTE Tighten the two Screws in order of (1) and (2) shown in the figure.
9. Secure the Harness Bracket (PL 12.14.1) using two Screws.
10. Install the Punch Frame Assembly (PL 12.7.1) .
11. Install the Left Hand Top Cover (PL 12.5.9) .
12. Install the Left Hand Front Cover (PL 12.5.8) .
13. Install the Top Cover (PL 12.4.1) .
14. Install the Upper Rear Cover (PL 12.4.11) .
15. Close the Lower Left Top Exit Chute Assembly (PL 12.13.10) to the left by hand.
16. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.95 Exit Motor Assembly \& Belt

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11).
2. Loosen the two Screws securing the Tension Bracket Assembly (PL 12.13.23) for the Motor Assembly (Exit Motor) .
3. Move the Tension Bracket Assembly in the direction of the arrow so that the tension of the Belt (PL 12.13.28) decreases, and remove the Belt from each pulley.


Figure 1 Tension Bracket Assembly
4. Disconnect the connector (J8334) of the Main Drive Harness Assembly (PL 12.15.2) from the Motor Assembly .
5. Remove the two Screws securing the Motor Assembly.
6. Remove the Motor Assembly.
7. Remove the two Screws securing the Motor Assembly to the Motor Bracket (PL 12.13.29) to remove.


Figure 2 Exit Motor Assembly

1. Install the Motor Assembly (Exit Motor) to the Motor Bracket (PL 12.13.29) in the direction shown in the figure using two Screws.
2. Install the Motor Assembly to the Finisher using two Screws.

NOTE Be sure to put the two bosses of chassis into the two holes on the Bracket Assembly attached with the Motor Assembly.
3. Connect the connector (J8334) of the Main Drive Harness Assembly (PL 12.15.2) to the Motor Assembly.
4. While pushing the Tension Bracket Assembly (PL 12.13.23) in the direction of the arrow, install the Belt (PL 12.13.28) onto each pulley.
5. Fix the Tension Bracket Assembly to the frame using two Screws.

NOTE The tension of the belt is automatically adjusted by the force of the Tension Spring (PL 12.13.24) attached to the Tension Bracket Assembly. Therefore, when tightening the two Screws, be careful not to move the Tension Bracket Assembly.
NOTE Tighten the two Screws in order of (1) and (2) shown in the figure.
6. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.96 Registration Motor Assembly \& Belt

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11) .
2. Remove the two Screws securing the Harness Bracket (PL 12.14.1).

NOTE In this procedure, remove only two Screws securing the Harness Bracket to make easier to remove the gear or the like from the Finisher, not to remove the Harness Bracket itself from the Finisher.
3. Loosen the two Screws securing the Tension Bracket Assembly (PL 12.13.23) for the Motor Assembly (Registration Motor) .
4. Move the Tension Bracket Assembly in the direction of the arrow so that the tension of the Belt (PL 12.13.27) decreases, and remove the Belt from each pulley.


Figure 1 Tension Bracket Assembly
5. Disconnect the connector (J8335) of the Main Drive Harness Assembly (PL 12.15.2) from the Motor Assembly
6. Remove the two Screws securing the Motor Assembly.
7. Remove the Motor Assembly.
8. Remove the two Screws securing the Motor Assembly to the Motor Bracket (PL 12.13.29) to remove.


Figure 2 Motor Assembly

## Replacement

1. Install the Motor Assembly (Registration Motor) to the Motor Bracket (PL 12.13.29) in the direction shown in the figure using two Screws.
2. Install the Motor Assembly to the Finisher using two Screws.

NOTE Be sure to put the two bosses of the chassis into the two holes on the Bracket Assembly attached with the Motor Assembly.
3. Connect the connector (J8335) of the Main Drive Harness Assembly (PL 12.15.2) to the Motor Assembly.
4. While pushing the Tension Bracket Assembly (PL 12.13.23) in the direction of the arrow, install the Belt (PL 12.13.27) onto each pulley.
5. Fix the Tension Bracket Assembly to the frame using two Screws.

NOTE The tension of the belt is automatically adjusted by the force of the Tension Spring (PL 12.13.24) attached to the Tension Bracket Assembly. Therefore, when tightening the two Screws, be careful not to move the Tension Bracket Assembly.
NOTE Tighten the two Screws in order of (1) and (2) shown in the figure.
6. Secure the Harness Bracket (PL 12.14.1) to the frame using two Screws.
7. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.97 Horizontal Transport PWBA

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11).
2. Disconnect the three connectors on the Horizontal Transport PWBA.
3. Remove the two Screws (M3 x 6) securing the Horizontal Transport PWBA to the Finisher to remove.


Figure 1 Horizontal Transport PWBA

## Replacement

1. Install the Horizontal Transport PWBA in the direction shown in the figure, and secure it using two Screws (M3 x 6).
2. Connect the connectors (J8371) of the Horizontal Transport Harness Assembly, (J8373) of the DL Harness Assembly, and (J8372) of the Horizontal Transport Harness Assembly I/F to the H Transport PWBA.
3. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.98 Main-C PWBA

## Removal

1. Remove the Upper Rear Cover (PL 12.4.11) .
2. Remove the Lower Rear Cover (PL 12.4.9) .
3. Loosen the four Screws (M3 x 6) securing the Main Plate PWBA (PL 12.14.7).
4. Move the Main Plate PWBA in the direction of the arrow to remove.


Figure 1 Main Plate PWBA
5. Disconnect all the connectors on the Main-C PWBA .
6. Remove the six Screws $(M 3 \times 6)$ securing the Main-C PWBA.
7. Remove the Main-C PWBA.


Figure 2 Main C PWBA

## Replacement

1. Install the Main-C PWBA in the direction shown in the figure, and secure it using six Screws (M3 x 6).
2. Connect the harness connectors to the Main-C PWBA.
3. Install the Main Plate PWBA (PL 12.14.7) to the frame by moving it in the opposite direction of the arrow, and secure it using four Screws (M3 x 6).
4. Install the Lower Rear Cover (PL 12.4.9) .
5. Install the Upper Rear Cover (PL 12.4.11) .

## RRP 12.99 C LVPS

## Removal

1. Remove the Bottom Cover (PL 12.4.6).
2. Disconnect the three connectors on the C LVPS .
3. Remove the two Screws $(M 3 \times 6)$ securing the C LVPS to the Finisher.
4. Remove the C LVPS.


Figure 1 C LVPS

## Replacement

1. Install the C LVPS to the Finisher using two Screws (M3 $\times 6$ ).
2. Connect the connector of the AC Inlet Harness Assembly (PL 12.14.8) to the connector (J2) on the C LVPS and connect the connector of the LVPS Harness Assembly (PL 12.15.10) to the connectors (J502 and J505).
3. Install the Bottom Cover (PL 12.4.6) .

## RRP 12.100 Punch Full Sensor

## Removal

1. Open the Front Cover Assembly (PL 12.5.3).
2. Pull out the Dust Box Assembly (PL 12.7.20) from the Finisher to remove the Dust Box Assembly.
3. Disconnect the connector (J8452) of the Punch Full Sensor Harness Assembly from the Sensor (Punch Full Sensor) .
4. Release the hooks of the Sensor to remove the Sensor from the Bracket Assembly.


Figure 1 Punch Full Sensor

## Replacement

1. Secure the Sensor (Punch Full Sensor) to the Bracket Assembly using the hooks.
2. Connect the connector (J8452) of the Punch Full Sensor Harness Assembly to the Sensor.
3. Install the Dust Box Assembly (PL 12.7.20) to the Finisher.
4. Close the Front Cover Assembly (PL 12.5.3).

## RRP 12.101 Left Hinge Assembly/Right Hinge Assembly

NOTE The removal and replacement procedures for the Left Hinge Assembly and Right Hinge Assembly are the same.
NOTE The removal and replacement procedures for Left Hinge Assembly are described in this chapter.

## Removal

1. Remove the Rear Cover (PL 12.3.1) .
2. Remove the Top Cover Assembly (PL 12.2.9) .
3. Remove the Upper Chute Spring .
4. Remove the two Screws (M3 x 8) securing the Left Hinge Assembly to the Top Cover (PL 12.2.1) to remove the Left Hinge Assembly .


Figure 1 Top Cover Assembly

## Replacement

1. Secure the Left Hinge Assembly to the Top Cover (PL 12.2.1) using two Screws (M3 $\times 8$ ).

NOTE Be sure to install the two bosses on the Top Cover into the holes on the Left Hinge Assembly.
2. Install the Upper Chute Spring .
3. Install the Top Cover Assembly (PL 12.2.9) .
4. Install the Rear Cover (PL 12.3.1) .

## RRP 12.102 Upper Chute Spring

## Removal

1. Remove the Rear Cover (PL 12.3.1).
2. Remove the Top Cover Assembly (PL 12.2.9) .
3. Place the Top Cover Assembly up side down.
4. Remove the two Screws (M3 x 6) securing the two Magnet Brackets (PL 12.2.4) to the Top Cover (PL 12.2.1) to remove the two Magnet Brackets .
5. Release the two hooks securing the Upper Chute to the Top Cover to remove the Upper Chute. At the same time, four Chute Spring are removed.


Figure 1 Upper Chute

## Replacement

1. Put the four Chute Springs into the four holes on the Top Cover (PL 12.2.1).
2. While putting the four bosses of the Upper Chute into the four Chute Springs installed on the Top Cover install the Upper Chute to the Top Cover, and then fix it to the Top Cover using two hooks.
3. Secure the two Magnet Brackets (PL 12.2.4) to the Top Cover using two Screws (M3 x 6).
4. Install the Top Cover Assembly (PL 12.2.9) .
5. Install the Rear Cover (PL 12.3.1) .

## RRP 12.103 Pinch Roller \& Pinch Spring

NOTE The six Pinch Rollers are attached to the Upper Chute.
NOTE Their removal and replacement procedures are the same.

## Removal

1. Open the Top Cover Assembly (PL 12.2.9).
2. While releasing the hook of the Upper Chute (PL 12.2.8) remove the Pinch Roller from the Upper Chute .
3. Remove the Pinch Spring.


Figure 1 Pinch Roller

## Replacement

1. Install the Pinch Spring to the Upper Chute (PL 12.2.8) in the direction shown in the figure.
2. Install the Pinch Roller to the Upper Chute, and fix it using the hook.
3. Close the Top Cover Assembly (PL 12.2.9).

## RRP 12.104 Top Paper Guide

NOTE The two Top Paper Guides are attached to the Left Top Cover (PL 12.3.8).
NOTE Their removal and replacement procedures are the same.

## Removal

1. Remove the Rear Cover (PL 12.3.1) .
2. Open the Top Cover Assembly (PL 12.2.9).
3. Remove the Left Top Cover (PL 12.3.8) .
4. Release the two hooks securing the Top Paper Guide to the Left Top Cover to remove the Top Paper Guide .


Figure 1 Top Left Cover

## Replacement

1. Install the Top Paper Guide to the Left Top Cover (PL 12.3.8) using the two hooks.
2. Install the Left Top Cover .
3. Close the Top Cover Assembly (PL 12.2.9).
4. Install the Rear Cover (PL 12.3.1) .

## RRP 12.105 25N Magnet

## Removal

1. Open the Top Cover Assembly.
2. Release the hooks of the 25 N Magnet securing the Lower Chute Assembly (PL 12.3.27) to remove the 25N Magnet .


Figure 1 25N Magnet

## Replacement

1. Install the 25 N Magnet to the Lower Chute Assembly (PL 12.3.27), and secure it using the hooks.
2. Close the Top Cover Assembly.

## RRP 13 High Capacity Feeder (HCF)

## RRP 13.1 HCF Top Cover LG

## Removal

1. Pull out the Tray Unit from the machine .
2. Remove the two screws each on the front and rear securing the HCF Top Cover LG to the machine.
3. Remove the HCF Top Cover LG.


Figure 1 Top Cover

## Replacement

1. Install the HCF Top Cover LG to the machine and secure it using the two screws each on the front and rear.
2. Push Tray Unit into the machine.

## RRP 13.2 HCF Right Hand Cover

## Removal

1. Pull out the Tray Unit from the machine
2. Remove the four screws securing the HCF Right Hand Cover to the machine.
3. Remove the HCF Right Hand Cover.


Figure 1 Right Hand Cover

## Replacement

1. Install the HCF Right Hand Cover to the machine and secure it using the four screws.
2. Push the Tray Unit into the machine.

## RRP 13.3 HCF Tray Set Sensor

## Removal

1. Pull out the Tray Unit from the machine.
2. Remove the HCF Left Hand Cover (PL 13.1.11) .
3. Remove the HCF Rear Cover (PL 13.1.14) .
4. Disconnect the connector (JF53) of the Main Harness Assembly (PL 13.8.2) from the HCF Tray Set Sensor .
5. Release the hooks securing the Sensor to the frame to remove the Sensor.


Figure 1 Tray Set Sensor

## Replacement

1. Install the HCF Tray Set Sensor to the frame and secure it using the hooks.
2. Connect the connector (JF53) of Main Harness Assembly (PL 13.8.2) to the Sensor.

NOTE Push the Tray Unit into the machine once and make sure that the Tray Unit shutter fits securely into the recess of the Sensor. After confirmation, pull out the Tray Unit.
3. Install the HCF Rear Cover (PL 13.1.14) .
4. Install the HCF Left Hand Cover (PL 13.1.11) .
5. Push the Tray Unit into the machine.

## RRP 13.4 HCF Size Sensor R/L

## Removal

1. Pull out the Tray Unit from the machine.
2. Remove the HCF Top Cover LG (PL 13.1.1).
3. Remove the HCF Rear Cover (PL 13.1.14) .
4. Disconnect the connector (JF51 or JF52) of the Main Harness Assembly (PL 13.8.2) from the HCF Right or Left Size Sensor
5. Release the hooks securing the HCF Right or Left Size Sensor to the frame, to remove the Sensor.


Figure 1 Right \& Left Size Sensor

## Replacement

1. Install the HCF Right or Left Size Sensor to the frame and secure it using the hooks.
2. Connect the connector (JF51 or JF52) of the Main Harness Assembly (PL 13.8.2) to the Sensor.

NOTE Push the Tray Unit into the machine once and make sure that the Right Size Guide Assembly (PL 13.3.1) of Tray Unit fits securely into the recess of the HCF Right or Left Size Sensor. After confirmation, pull out the Tray Unit.
3. Install the HCF Rear Cover (PL 13.1.14).
4. Install the HCF Top Cover LG (PL 13.1.1) .
5. Push the Tray Unit into the machine.

## RRP 13.5 Frame Rack Caster

NOTE The machine has four Frame Rack Casters. Their removal and replacement procedures are the same.

## Removal

1. Remove the Tray Unit from the machine.
2. Place the machine so that the HCF Left Hand Cover (PL 13.1.11) faces down.

NOTE Be careful not to scratch the HCF Left Hand Cover.
NOTE When placing the machine, be careful not to injure your finger with the frame.
3. Remove the three screws securing the Frame Rack Caster to the machine .
4. Remove the Frame Rack Caster.


Figure 1 Frame Rack Caster

## Replacement

1. Install the Frame Rack Caster to the machine, and secure it with three screws.
2. Place the machine back to its original position.
3. Install the Tray Unit to the machine.

## RRP 13.6 HCF Left Hand Cover

## Removal

1. Remove the HCF Top Cover LG (PL 13.1.1) .
2. Remove the five screws securing the HCF Left Hand Cover to the machine .
3. Remove the HCF Left Hand Cover.


Figure 1 Left Hand Cover

## Replacement

1. Install the HCF Left Hand Cover to the machine and secure it using the five screws.
2. Install the HCF Top Cover LG (PL 13.1.1) .

## RRP 13.7 HCF Rear Cover

## Removal

1. Remove the four screws securing the HCF Rear Cover to the machine
2. Remove the HCF Rear Cover.


Figure 1 Rear Cover

## Replacement

1. Install the HCF Rear Cover to the machine and secure it using the four screws.

## RRP 13.8 Front Cover Assembly

## Removal

1. Remove the Tray Unit from the machine.
2. Remove the screws, two on the upper portion, one on the right side, and two on the left side, securing the Front Cover Assembly to the Tray Unit .
3. Remove the Front Cover Assembly.


Figure 1 Front Cover Assembly

## Replacement

1. Install the Front Cover Assembly to Tray Unit using the screws, two on the upper portion, one on the right side, and two on the left side.
NOTE Make sure that the Front Cover Assembly indicator moves up-and-down smoothly when the Bottom Plate Assembly (PL 13.3.5) of the Tray Unit is moved by hand.
2. Install the Tray Unit to the machine.

## RRP 13.9 Guide Pin / End Plate

## Removal

1. Remove the Tray Unit from the machine.
2. Remove the End Guide Assembly (PL 13.2.14) .
3. Remove the two screws securing the Top End Plate (PL 13.2.12) to the Frame End Bracket (PL 13.2.8) .
4. Remove the Top End Plate.
5. Remove the E ring securing the Guide Pin to the Top End Plate to remove the Guide Pin.

NOTE When the E ring is removed, the Compression Spring (PL 13.2.10) and Washer (PL 13.2.11) will be detached. Be careful not to lose them.
6. Remove the shafts at the top and bottom of the End Plate from the holes on the Frame End Bracket to remove the End Plate.


Figure 1 End Plate and Bracket

## Replacement

1. Fit the shafts at the top and bottom of the End Plate to the holes on the Frame End Bracket to install the End Plate.
2. Fit the Guide Pin into the hole on the Top End Plate (PL 13.2.12). Pass the Guide Pin through the Washer (PL 13.2.11) and Compression Spring (PL 13.2.10), and secure them with the E ring.
3. Install the Top End Plate to the Frame End Bracket using the two screws.
4. Install the End Guide Assembly (PL 13.2.14) .

NOTE Make sure that the End Plate moves smoothly when lifting the Guide Pin up and moving it to other position.
5. Install the Tray Unit to the machine.

## RRP 13.10 End Guide Assembly

## Removal

1. Remove the Tray Unit from the machine.
2. Remove the E ring securing the End Guide Assembly to the Tray Unit .
3. Lift the End Guide Assembly upward to release the holes on the End Guide Assembly from the shafts on the top and bottom of the Tray Unit to remove the End Guide Assembly.
NOTE When the End Guide Assembly is removed, the Wave Washer (PL 13.2.16) will be detached. Be careful not to lose it.


Figure 1 End Guide Assembly

## Replacement

1. Put the Wave Washer (PL 13.2.16) to the shaft on the bottom of the Tray Unit.
2. Fit the holes on the End Guide Assembly onto the shafts on the top and bottom of the Tray Unit.
3. Secure the End Guide Assembly to the Tray Unit using the E ring.
4. Install the Tray Unit to the machine.

## RRP 13.11 Cable

NOTE It is recommended to replace the Cable at front side and rear side together. When replacing the Cable, be sure to use the Tray Cable Kit (PL 13.3.99).

## Removal

1. Remove the Tray Unit from the machine.
2. Remove the Right PF2 Gear Bracket Assembly (PL 13.3.8) .
3. Remove the E ring securing the Powered Bearing (PL 13.3.9) to the Lift Shaft (PL 13.3.10) at the rear on the right side of the Tray Unit .
4. Move the Powered Bearing in the direction of the arrow (1) to remove it from the frame.
5. Move the Lift Shaft in the direction of the arrow (2) to remove it from the frame.
6. Move the Tray Pulley (PL 13.3.15) in the direction of the arrow (3). Then, the tips of the two Cables at the rear side are detached from the Lift Shaft.
7. Remove the two E rings securing the two S Pulleys (PL 13.3.13) at the upper portion on the rear side to remove the two $S$ Wire Guide (PL 13.3.14) and two S Pulleys.
8. Remove the E ring securing the L Pulley (PL 13.3.17) at the lower portion to remove the $L$ Wire Guide (PL 13.3.18) and L Pulley.
9. Remove the two Cables from the Bottom Plate Assembly (PL 13.3.5).


BEARING POWERED (PL22.3.9)


Figure 1 Rear Side
10. Remove the Cable at the front side of the Tray Unit .
11. Remove the E ring securing the Powered Bearing to the Lift Shaft at the front on the right side of the Tray Unit.
12. Move the Powered Bearing (PL 13.3.11) in the direction of the arrow (4) to remove it from the frame.
13. Move the Lift Shaft in the direction of the arrow (5) to remove it from the frame.
14. Move the Tray Pulley in the direction of the arrow (6). Then, the tips of the two Cables at the front are detached from the Lift Shaft.
15. Remove the two $E$ rings securing the two $S$ Pulleys at the upper portion to remove the two $S$ Wire Guide and two S Pulleys.
16. Remove the E ring securing the L Pulley at the lower portion to remove the $L$ Wire Guide and L Pulley.
17. Remove the tips of the two Cables from the Bottom Plate Assembly.


Figure 2 Front Side

## Replacement

1. Install the Cable on the front side first.
2. Fit the tips of the two Cables to the holes on the Bottom Plate Assembly (PL 13.3.5).

## NOTE Place the Bottom Plate Assembly so that the arrow mark on it points to the direction as shown in the figure.

3. Hang the Cable onto the S Pulley (PL 13.3.13), and install the S Pulley and the S Guide Wire (PL 13.3.14) to the upper shaft. Fix them with two E rings.
4. Hang the Cable onto the L Pulley (PL 13.3.17), and install the L Pulley and the L Wire Guide (PL 13.3.18) to the lower shaft. Fix them with E ring.
5. Fit the tips of the two Cables into the two holes on the Lift Shaft (PL 13.3.10).

NOTE When fitting the two Cables into the holes, be careful not to twist them.
6. Press the Tray Pulley (PL 13.3.15) in the opposite direction of the arrow (6) so that the tips of the Cables are not detached from the Lift Shaft.
7. Move the Lift Shaft in the opposite direction of the arrow (5) to fit it to the notch on the frame.
8. Move the Powered Bearing in the opposite direction of the arrow (4) to install it to the frame.
9. Fix the Powered Bearing to the Lift Shaft using the E ring.
10. Install the Cable at the rear side.
11. Fit the tips of the two Cables to the holes on the Bottom Plate Assembly.
12. Hang the Cable onto the S Pulley, and install the S Pulley and the S Guide Wire to the upper shaft. Fix them with the two E rings.
13. Hang the Cable onto the L Pulley, and install the L Pulley and the L Wire Guide to the lower shaft. Fix them with the E ring.
14. Fit the tips of the two Cables into the two holes on the Lift Shaft.

## NOTE When fitting the two Cables into the holes, be careful not to twist them.

15. Press the Tray Pulley in the opposite direction of the arrow (3) so that the tips of the Cables are not detached from the Lift Shaft.
16. Move the Lift Shaft in the opposite direction of the arrow (2) to fit it to the notch on the frame.
17. Move the Powered Bearing in the opposite direction of the arrow (1) to install it to the frame.
18. Fix the Powered Bearing to the Lift Shaft using the E ring.
19. Install the Right PF2 Gear Bracket Assembly (PL 13.3.8) .
20. When the Lift Gear is turned by hand, make sure that the Bottom Plate Assembly moves up-and-down at the rear and front sides simultaneously.
21. Install the Tray Unit to the machine.

## RRP 13.12 Right PF2 Gear Bracket Assembly

## Removal

1. Remove the Tray Unit from the machine.
2. Remove the three screws securing the Right PF2 Gear Bracket Assembly .
3. Remove the Right PF2 Gear Bracket Assembly.


Figure 1 Gear Bracket

## Replacement

1. Install the Right PF2 Gear Bracket Assembly to the Tray Unit using the three screws.

NOTE When installing the Right PF2 Gear Bracket Assembly, engage the gears of the Right PF2 Gear Bracket Assembly and the Tray Unit.
2. Install the Tray Unit to the machine.

## RRP 13.13 Bottom Plate Assembly

## Removal

1. Remove the Tray Unit from the machine.
2. Remove the Front Cover Assembly (PL 13.2.1) .
3. Remove the Right PF2 Gear Bracket Assembly (PL 13.3.8) .
4. Remove the Cable (PL 13.3.6) .
5. Remove the Tray Guide Screw (PL 13.3.7) to remove the Right Size Guide Assembly (PL 13.3.1) .
6. Remove the Front Size Guide Assembly (PL 13.3.2).
7. Remove the Bottom Plate Assembly from the Tray Unit.


Figure 1 Bottom Plate Assembly

## Replacement

1. Install the Bottom Plate Assembly to the Tray Unit in the direction shown in the figure.
2. Install the Cable (PL 13.3.6) .
3. Install the Right PF2 Gear Bracket Assembly (PL 13.3.8) .
4. Install the Front Cover Assembly (PL 13.2.1) .
5. Install the Front Size Guide Assembly (PL 13.3.2).
6. Install the Right Size Guide Assembly (PL 13.3.1) to the Tray Unit, and fix it using the Tray Guide Screw (PL 13.3.7).
7. Install the Tray Unit to the machine.

## RRP 13.14 HCF Feeder Assembly

## Removal

1. Remove the Tray Unit from the machine.
2. Remove the two screws securing the HCF Feeder Assembly on the front side
3. Pull the FRONT FRAME of the HCF Feeder Assembly to front until it slides out from the machine.

NOTE Since the connector (JF56) of the HCF Feeder Assembly is tightly fit to the connector on the frame, it may require a little stronger force to remove the HCF Feeder Assembly.


Figure 1 Feeder Assembly

## Replacement

1. Put the HCF Feeder Assembly into the machine from the front side, and insert the guide shaft of the frame into the hole of the HCF Feeder Assembly.
2. Push the HCF Feeder Assembly towards the rear side firmly, and connect the connector (JF56) of the HCF Feeder Assembly to the connector on the frame.
3. Install the HCF Feeder Assembly to the front side of the machine using the two screws.
4. Install the Tray Unit to the machine.

## RRP 13.15 HCF Motor Assembly

## Removal

1. Remove the Tray Unit from the machine.
2. Remove the HCF Feeder Assembly (PL 13.4.1) .
3. Disconnect the connector (PF58) of the HCF Motor Assembly from the HCF Feeder Assembly .
4. Remove the four screws securing the HCF Motor Assembly to the HCF Feeder Assembly.
5. Remove the HCF Motor Assembly.


Figure 1 Motor Assembly

## Replacement

1. Install the HCF Motor Assembly to the HCF Feeder Assembly (PL 13.4.1) using the four screws.
2. Connect the connector (PF58) of the HCF Motor Assembly to the HCF Feeder Assembly.
3. Install the HCF Feeder Assembly .
4. Install the Tray Unit to the machine.

## RRP 13.16 Drive Frame Assembly

## Removal

1. Remove the Tray Unit from the machine.
2. Remove the HCF Feeder Assembly (PL 13.4.1) .
3. Remove the HCF Motor Assembly (PL 13.4.2) .
4. Remove the three screws securing the Drive Frame Assembly to the HCF Feeder Assembly
5. Remove the Drive Frame Assembly.


Figure 1 Drive Frame Assembly

## Replacement

1. Install the Drive Frame Assembly to the HCF Feeder Assembly using the three screws.
2. Install the HCF Motor Assembly (PL 13.4.2) .
3. Install the HCF Feeder Assembly (PL 13.4.1) .
4. Install the Tray Unit to the machine.

RRP 13.17 Solenoid Assembly

## Removal

1. Remove the Tray Unit from the machine.
2. Remove the HCF Feeder Assembly (PL 13.4.1) .
3. Remove the HCF Motor Assembly (PL 13.4.2) .
4. Remove the Drive Frame Assembly (PL 13.4.3) .
5. Remove the two screws securing the Rear Frame Assembly (PL 13.4.4) to the HCF Feeder Assembly, and remove the Rear Frame Assembly .
6. Disconnect the harness connector (PF59) of the Solenoid Assembly from the connector of Feeder Harness Assembly (PL 13.5.12).
7. Release the harness of the Solenoid Assembly from the clamp.
8. Remove the two screws securing the Solenoid Assembly to the Rear Frame Assembly.
9. Remove the Solenoid Assembly.


Figure 1 Solenoid Assembly

## Replacement

1. Install the Solenoid Assembly to the Rear Frame Assembly (PL 13.4.4) using the two screws.

## NOTE When installing the Solenoid Assembly, make sure to hang the iron-core pins of the Solenoid onto the Link Solenoid of the Rear Frame Assembly.

2. Install the Rear Frame Assembly (PL 13.4.4) to the HCF Feeder Assembly using the two screws.
3. Connect the harness connector (PF59) of the Solenoid Assembly to the connector of the Feeder Harness Assembly (PL 13.5.12), and secure the harness using a clamp.
4. Install the Drive Frame Assembly (PL 13.4.3) .
5. Install the HCF Motor Assembly (PL 13.4.2) .
6. Install the HCF Feeder Assembly (PL 13.4.1) .
7. Install the Tray Unit to the machine.

## RRP 13.18 HCF Pre Feed Sensor

## Removal

1. Open the Top Cover Assembly S (PL 13.7.1).
2. Open the Upper Feeder Assembly (PL 13.5.1).
3. Remove the three screws securing the Upper Chute (PL 13.5.14) to the Upper Feeder Assembly
4. Remove the Upper Chute.
5. Remove the connector (PF61) of the Feeder Harness Assembly (PL 13.5.12) from the HCF Pre Feed Sensor.
6. Remove the one screw securing the Sensor to the Upper Feeder Assembly.
7. Remove the Sensor.


Figure 1 Pre Feed Sensor

## Replacement

1. Place the HCF Pre Feed Sensor so that the sensing surface faces the direction shown in the figure, and install it to the Upper Feeder Assembly (PL 13.5.1) using the one screw.
2. Connect the connector (PF61) of the Feeder Harness Assembly (PL 13.5.12) to the Sensor.
3. Install the Upper Chute (PL 13.5.14) to the Upper Feeder Assembly using the three screws.
4. Close the Upper Feeder Assembly (PL 13.5.1).
5. Close the Top Cover Assembly S (PL 13.7.1).

## Removal

1. Open the Top Cover Assembly S (PL 13.7.1).
2. Open the Upper Feeder Assembly (PL 13.5.1).
3. Remove the E ring securing the Actuator to the Upper Feeder Assembly .
4. Remove the Actuator.


Figure 1 Actuator

## Replacement

1. Install the Actuator to the Upper Feeder Assembly, and secure it using the E-ring.

NOTE After installing the Actuator, make sure that it falls smoothly into the recess on the Photo In Sensor (PL 13.5.16) (HCF No Paper Sensor) when it is moved.
2. Close the Upper Feeder Assembly (PL 13.5.1).
3. Close the Top Cover Assembly S (PL 13.7.1).

## RRP 13.20 HCF Level Sensor

## Removal

1. Open the Top Cover Assembly S (PL 13.7.1).
2. Open the Upper Feeder Assembly (PL 13.5.1).
3. Disconnect the connector (PF62) of the Feeder Harness Assembly (PL 13.5.12) from the HCF Level Sensor .
4. Release the hooks securing the Photo In Sensor to the Upper Feeder Assembly to remove the Photo In Sensor.


Figure 1 HCF Level Sensor

## Replacement

1. Install the HCF Level Sensor to the Upper Feeder Assembly (PL 13.5.1), and secure it with the hooks.
2. Connect the connector (PF62) of the Feeder Harness Assembly (PL 13.5.12) to the Photo In Sensor.
3. Close the Upper Feeder Assembly (PL 13.5.1).
4. Close the Top Cover Assembly S (PL 13.7.1).

## RRP 13.21 HCF No Paper Sensor

## Removal

1. Open the Top Cover Assembly S (PL 13.7.1).
2. Open the Upper Feeder Assembly (PL 13.5.1).
3. Disconnect the connector (PF60) of the Feeder Harness Assembly (PL 13.5.12) from the HCF No Paper Sensor .
4. Release the hooks securing the Photo In Sensor to the Upper Feeder Assembly to remove the Photo In Sensor.


Figure 1 No Paper Sensor

## Replacement

1. Install the HCF No Paper Sensor to the Upper Feeder Assembly (PL 13.5.1), and secure it with the hooks.

NOTE After installing the Photo In Sensor, make sure that the Actuator (PL 13.5.15) falls smoothly into the recess on the Photo In Sensor.
2. Connect the connector (PF60) of the Feeder Harness Assembly (PL 13.5.12) to the Photo In Sensor.
3. $\quad$ Close the Upper Feeder Assembly (PL 13.5.1).
4. Close the Top Cover Assembly S (PL 13.7.1).

## RRP 13.22 Feeder Shaft Assembly

## Removal

1. Open the Top Cover Assembly S (PL 13.7.1).
2. Open the Upper Feeder Assembly (PL 13.5.1).
3. Remove the Nudger Roll Assembly (PL 13.5.20) .
4. Remove the E ring securing the Feeder Shaft Assembly to the Upper Feeder Assembly .
5. Remove the Bearing (PL 13.5.17).
6. Remove the Bearing attached to the Feeder Shaft Assembly from the Upper Frame Assembly (PL 13.5.6) to remove the Feeder Shaft Assembly from the Upper Feeder Assembly.


Figure 1 Feeder Shaft Assembly

## Replacement

1. Install the Bearing attached to the Feeder Shaft Assembly to the Upper Frame Assembly (PL 13.5.6), and install the Feeder Shaft Assembly to the Upper Feeder Assembly (PL 13.5.1).
2. Install the Bearing (PL 13.5.17) to the Feeder Shaft Assembly, and secure it using the Ering.
3. Install the Nudger Roll Assembly (PL 13.5.20) .
4. Close the Upper Feeder Assembly (PL 13.5.1).
5. Close the Top Cover Assembly S (PL 13.7.1).

## RRP 13.23 Nudger Roll Assembly

## Removal

1. Open the Top Cover Assembly S (PL 13.7.1).
2. Open the Upper Feeder Assembly (PL 13.5.1).
3. Remove the Nudger Roll Assembly by pushing in the shaft ends with fingers .


Figure 1 Nudger Roll Assembly

## Replacement

1. Place the Nudger Roll Assembly so that the flat surface of the shaft faces the direction shown in the figure, and install it by pushing in the shaft ends with fingers.
2. Close the Upper Feeder Assembly (PL 13.5.1).
3. Close the Top Cover Assembly S (PL 13.7.1).

## RRP 13.24 Feed Roll Assembly

## Removal

1. Open the Top Cover Assembly S (PL 13.7.1).
2. Open the Upper Feeder Assembly (PL 13.5.1).
3. Remove the Feed Roll Assembly by pushing in the shaft ends with fingers .


Figure 1 Feed Roll Assembly

## Replacement

1. Place the Feed Roll Assembly so that the flat surface of the shaft faces the direction shown in the figure, and install it by pushing in the shaft ends with fingers.
2. Close the Upper Feeder Assembly (PL 13.5.1).
3. Close the Top Cover Assembly S (PL 13.7.1).

## RRP 13.25 Lower Feeder Assembly

## Removal

1. Remove the Tray Unit from the machine.
2. Remove the HCF Feeder Assembly (PL 13.4.1) .
3. Remove the HCF Motor Assembly (PL 13.4.2) .
4. Remove the Drive Frame Assembly (PL 13.4.3) .
5. Remove the Retard Roll Assembly (PL 13.6.17) .
6. Remove the two screws each on the rear and front securing the Lower Feeder Assembly to the HCF Feeder Assembly .
7. Remove the Lower Feeder Assembly.


Figure 1 Lower Feeder Assembly

## Replacement

1. Install the Lower Feeder Assembly to the HCF Feeder Assembly (PL 13.4.1) using the two screws each on the rear and front.
2. Install the Retard Roll Assembly (PL 13.6.17) .
3. Install the Drive Frame Assembly (PL 13.4.3) .
4. Install the HCF Motor Assembly (PL 13.4.2) .
5. Install the HCF Feeder Assembly (PL 13.4.1) .
6. Install the Tray Unit to the machine.

## RRP 13.26 Retard Shaft Assembly

## Removal

1. Remove the Tray Unit from the machine.
2. Remove the HCF Feeder Assembly (PL 13.4.1) .
3. Remove the Retard Roll Assembly (PL 13.6.17) .
4. Remove the Lower Feeder Assembly (PL 13.6.1) .
5. Remove the four screws securing the Lower Chute (PL 13.6.2) to the HCF Lower Frame Assembly (PL 13.6.3) .
6. Remove the Lower Chute.
7. Remove the two E-rings securing the Bearing (PL 13.6.12) and Bearing-6 (PL 13.6.14), and shift them to remove them from the two brackets on the HCF Lower Frame Assembly.
8. Remove the Retard Shaft Assembly from the HCF Lower Frame Assembly.

NOTE When the Retard Shaft Assembly is removed, the Retard Spring (PL 13.6.7) will be detached from the shaft of the HCF Lower Frame Assembly. Be careful not to lose it.


Figure 1 Retard Shaft Assembly

## Replacement

1. Install the Bearing (PL 13.6.12) and Bearing-6 (PL 13.6.14) of the Retard Shaft Assembly to the two brackets on the HCF Lower Frame Assembly (PL 13.6.3), and fix them using two Erings.
2. Install the Retard Spring (PL 13.6.7) to the shaft of the HCF Lower Frame Assembly.
3. Turn the Retard Lever so that hold the Retard Spring with the Retard Bracket of the Retard Shaft Assembly.
4. Install the Lower Chute (PL 13.6.2) to the HCF Lower Frame Assembly using the four screws.
5. Install the Lower Feeder Assembly (PL 13.6.1).
6. Install the Retard Roll Assembly (PL 13.6.17) .
7. Install the HCF Feeder Assembly (PL 13.4.1) .
8. Install the Tray Unit to the machine.

## RRP 13.27 Retard Roller Assembly

## Removal

1. Open the Top Cover Assembly S (PL 13.7.1).
2. Open the Upper Feeder Assembly (PL 13.5.1).
3. Remove the Retard Roller Assembly by pushing in the shaft ends with fingers .


Figure 1 Retard Roller Assembly

## Replacement

1. Place the Retard Roller Assembly so that the flat surface of the shaft faces the direction shown in the figure, and install it by pushing in the shaft ends with fingers.
2. Close the Upper Feeder Assembly (PL 13.5.1).
3. Close the Top Cover Assembly S (PL 13.7.1).

## RRP 13.28 Top Cover Assembly S

## Removal

1. Pull out the Tray Unit from the machine.
2. Remove the HCF Top Cover LG (PL 13.1.1) .
3. Remove the HCF Rear Cover (PL 13.1.14).
4. Open the Top Cover Assembly S.
5. Remove the two screws securing the Rear Hinge Bracket New (PL 13.7.11) to the frame .
6. Remove the Rear Hinge Bracket New.

NOTE When removing the Hinge Bracket New, leave the Top Pivot Shaft (PL 13.7.14) and the Right Torsion Spring (PL 13.7.15) attached to the Top Cover Assembly S.
7. Lift the Top Cover Assembly S, and remove the tip on the front of the Top Pivot Shaft attached to the Top Cover Assembly S from the hole on the frame. At the same time, remove the tip of the Left Torsion Spring (PL 13.7.16) attached to the front side from the longitudinal hole of the frame.
8. Remove the Top Pivot Shaft, Right Torsion Spring and Left Torsion Spring from the Top Cover Assembly S.


Figure 1 Top Cover Assembly

## Replacement

1. Install the Top Pivot Shaft (PL 13.7.14), Right Torsion Spring (PL 13.7.15) and Left Torsion Spring (PL 13.7.16) to the Top Cover Assembly S as shown in the figure.

## NOTE Install the Top Pivot Shaft so that its D-cut is positioned at the front side of the Top Cover Assembly S.

2. Put the front tip (D-cut portion) of the Top Pivot Shaft attached to the Top Cover Assembly S into the D-shaped hole on the frame.
3. Put the tip of the Left Torsion Spring into the longitudinal hole of the frame.

NOTE Twist the spring to install the Left Torsion Spring.
4. Fit the hole on the Rear Hinge Bracket New (PL 13.7.11) to the rear tip of the Top Pivot Shaft attached to the Top Cover Assembly S.
5. Put the tip of the Right Torsion Spring into the longitudinal hole on the Rear Hinge Bracket New.

NOTE Twist the spring to install the Right Torsion Spring.
6. Install the Rear Hinge Bracket New to the frame using the two screws.
7. Open the Top Cover Assembly S fully, and make sure that the spring force is applied to retain the Top Cover Assembly $S$ at that position.
8. Install the HCF Rear Cover (PL 13.1.14).
9. Install the HCF Top Cover LG (PL 13.1.1) .
10. Push the Tray Unit into the machine.

## RRP 13.29 Transport Interlock Switch

## Removal

1. Pull out the Tray Unit from the machine.
2. Remove the HCF Right Hand Cover (PL 13.1.2) .
3. Open the Top Cover Assembly S (PL 13.7.1).
4. Remove the two screws securing the Switch Bracket (PL 13.7.4) attached with the Switch
5. Remove the Switch Bracket to fitted with the Switch.
6. Disconnect the connector (FSOO2) of the Main Harness Assembly (PL 13.8.2) from the Switch.
7. Release the hooks securing the Switch to the Switch Bracket to remove the Switch.


Figure 1 Transport Interlock Switch

## Replacement

1. Install the Switch to the Switch Bracket (PL 13.7.4), and secure it with hooks.
2. Connect the connector (FSO02) of the Main Harness Assembly (PL 13.8.2) to the Switch.
3. Install the Switch Bracket (PL 13.7.4) fitted with the Switch using the two screws.
4. Close the Top Cover Assembly S (PL 13.7.1).
5. Install the HCF Right Hand Cover (PL 13.1.2) .
6. Push the Tray Unit into the machine.

## RRP 13.30 HCF TA Sensor Assembly

## Removal

1. Pull out the Tray Unit from the machine.
2. Remove the HCF Right Hand Cover (PL 13.1.2) .
3. Open the Top Cover Assembly S (PL 13.7.1).
4. Remove the two screws securing the TA Sensor Bracket (PL 13.7.7) to the frame .
5. Remove the TA Sensor Bracket.
6. Disconnect the connector (JF54) of the Main Harness Assembly (PL 13.8.2) from the TA Sensor Assembly.
7. Release the hooks securing the TA Sensor Assembly to the TA Sensor Bracket to remove the TA Sensor Assembly.


Figure 1 TA Sensor Assembly

## Replacement

1. Install the TA Sensor Assembly to the TA Sensor Bracket (PL 13.7.7) in the direction shown in the figure, and secure it with the hooks.
2. Connect the connector (JF54) of the Main Harness Assembly (PL 13.8.2) to the connector of the TA Sensor Assembly.
3. Install the TA Sensor Bracket to the Lower Chute (PL 13.7.5) using the two screws.

## NOTE When installing the TA Sensor Assembly, put the actuator into the hole of the Lower Chute.

4. Close the Top Cover Assembly S (PL 13.7.1).
5. Install the HCF Right Hand Cover (PL 13.1.2) .
6. Push the Tray Unit into the machine.

## RRP 13.31 TA Roller Assembly P

## Removal

1. Pull out the Tray Unit from the machine.
2. Remove the HCF Right Hand Cover (PL 13.1.2) .
3. Remove the E-ring on the front side securing the TA Roller Assembly P .
4. Shift the TA Roller Assembly $P$ towards the rear side to remove the front side of the shaft from the Conductive Bearing (PL 13.7.10).
NOTE When removing the TA Roller Assembly P, the Conductive Bearing will be detached from the frame. Be sure not to lose it.
NOTE When removing TA Roller Assembly P, do not hold its rubber rollers.


Figure 1 TA Roller Assembly P

## Replacement

1. Install the Conductive Bearing (PL 13.7.10) into the hole of the frame.
2. After putting the TA Roller Assembly $P$ into the hole on the rear side, put the tip of the shaft on another side into the Conductive Bearing on the front side.
NOTE When installing the TA Roller Assembly $P$, do not hold its rubber rollers.
3. Fix the E-ring to the TA Roller Assembly P on the front side.
4. Install the HCF Right Hand Cover (PL 13.1.2) .
5. Push the Tray Unit into the machine.

## RRP 13.32 Motor Assembly

## Removal

1. Remove the HCF Top Cover LG (PL 13.1.1).
2. Remove the HCF Rear Cover (PL 13.1.14) .
3. Disconnect the connector (PF57) of the Main Harness Assembly (PL 13.8.2) from the Motor Assembly
4. Release the Main Harness Assembly from the harness clamp and leave it detached.
5. Remove the three screws securing the Motor Assembly to the frame.
6. Remove the Motor Assembly.

NOTE Be sure not to disassemble the Motor from the Motor Assembly.


Figure 1 Motor Assembly

## Replacement

1. Install the Motor Assembly to the frame using the three screws.

NOTE When installing the Motor Assembly, engage the gears of the Motor Assembly and the TA Roller Assembly P securely.
2. Connect the connector (PF57) of the Main Harness Assembly (PL 13.8.2) to the Motor Assembly.
3. Secure the Main Harness Assembly using a harness clamp.
4. Install the HCF Rear Cover (PL 13.1.14).
5. Install the HCF Top Cover LG (PL 13.1.1) .

## RRP 13.33 Interlock Docking Switch Assembly (HCF Side Out Switch)

## Removal

1. Remove the HCF Right Hand Cover (PL 13.1.2) .
2. Remove the Tray Unit from the machine.
3. Disconnect the connector (FSOO4) attached to the Interlock Docking Switch Assembly (HCF Side Out Switch) from the connector of the Main Harness Assembly (PL 13.8.2) .
4. Release the hooks securing the Interlock Docking Switch Assembly to the frame to remove Interlock Docking Switch Assembly.


Figure 1 Interlock Switch Assembly

## Replacement

1. Install the Interlock Docking Switch Assembly (HCF Side Out Switch) to the frame, and secure it with the hooks.
2. Connect the connector of the Main Harness Assembly (PL 13.8.2) to the harness connector (FS004) of the Interlock Docking Switch Assembly.
3. Install the HCF Right Hand Cover (PL 13.1.2) .
4. Install the Tray Unit to the machine.

## RRP 13.34 PWB Assembly

## Removal

1. Remove the HCF Rear Cover (PL 13.1.14) .
2. Disconnect the seven connectors of Main Harness Assembly (PL 13.8.2) from the PWB Assembly
3. Remove the four screws securing the PWB Assembly to the frame.
4. Remove the PWB Assembly.


Figure 1 PWB Assembly

## Replacement

1. Install the PWB Assembly to the frame using the four screws.
2. Connect the seven connectors of the Main Harness Assembly (PL 13.8.2) to the PWB Assembly.
3. Install the HCF Rear Cover (PL 13.1.14) .

## RRP 14 Tandem Tray

## RRP 14.1 Top Cover

## Removal

1. Pull out the Tray 3 Assembly (PL 14.1.19).
2. Pull out the Tray 4 Assembly (PL 14.1.17).
3. Remove the one screw (Del Tite, M3x8mm) securing the Top Cover to the machine .
4. Move the Top Cover in the direction of the arrow to remove it.


Figure 1 Top Cover

## Replacement

1. Move the Top Cover in the opposite direction of the arrow and put the right side of the Top Cover onto the frame.
2. Install the Top Cover to the machine using the one screw (Del Tite, M3x8mm).
3. Close the Tray 4 Assembly (PL 14.1.17).
4. Close the Tray 3 Assembly (PL 14.1.19).

## RRP 14.2 Foot Cover

## Removal

1. Remove the Tray 3 Assembly (PL 14.1.19) .
2. Remove the Tray 4 Assembly (PL 14.1.17) .
3. Remove the Right Cover (PL 14.1.3) .
4. Remove the two screws (Del Tite, M3x8mm) securing the Foot Cover to the machine .
5. Remove the Foot Cover.


Figure 1 Foot Cover

## Replacement

1. Install the Foot Cover to the machine using the two screws (Del Tite, M3x8mm).
2. Install the Right Cover (PL 14.1.3) .
3. Install the Tray 4 Assembly (PL 14.1.17) .
4. Install the Tray 3 Assembly (PL 14.1.19).

## RRP 14.3 Right Cover

## Removal

1. Remove the two screws (Del Tite, M3x8mm) securing the Right Cover to the machine .
2. Move the Right Cover in the direction of the arrow to remove it.


Figure 1 Right Cover

## Replacement

1. Install the Right Cover to the machine using the two screws (Del Tite, M3x8mm).

NOTE Be sure to put the three hooks on the lower part of the Right Cover into the holes on the frame.

## RRP 14.4 Left Lower Cover

## Removal

1. Remove the two screws (Del Tite, M3x8mm) securing the Left Lower Cover to the machine .
2. Move the Left Lower Cover in the direction of the arrow to remove it.


## Replacement

1. Install the Left Lower Cover to the machine using two screws (Del Tite, M3x8mm).

NOTE Be sure to put the three hooks on the lower part of the Left Lower Cover into the holes on the frame.

## RRP 14.5 Rear Cover

## Removal

1. Remove the four screws (Del Tite, M3x8mm) securing the Rear Cover to the machine .
2. Remove the Rear Cover.


Figure 1 Rear Cover

## Replacement

1. Install the Rear Cover to the machine using the four screws (Del Tite, M3x8mm).

## RRP 14.6 Stopper Caster

## Removal

1. Remove the Tray 3 Assembly (PL 14.1.19) .
2. Remove the Tray 4 Assembly (PL 14.1.17) .
3. Place the machine on its right side down.

## NOTE Be careful not to damage the Right Cover (PL 14.1.3).

4. Remove the three screws (Del Tite, M4x6mm) securing the Stopper Caster to the machine .
5. Remove the Stopper Caster.


Figure 1 Stopper Caster

## Replacement

1. Install the Stopper Caster to the machine using three screws (Del Tite, M4x6mm).
2. Place the machine to the original position.
3. Install the Tray 4 Assembly (PL 14.1.17).
4. Install the Tray 3 Assembly (PL 14.1.19).

## RRP 14.7 Caster

## Removal

1. Remove the Tray 3 Assembly (PL 14.1.19) .
2. Remove the Tray 4 Assembly (PL 14.1.17) .
3. Place the machine on its right side down.

NOTE Be careful not to damage the Right Cover (PL 14.1.3).
4. Remove the three screws (Del Tite, M4x6mm) securing the Caster to the machine .
5. Remove the Caster.


Figure 1 Caster

## Replacement

1. Install the Caster to the machine using the three screws (Del Tite, M4x6mm).
2. Place the machine to the original position.
3. Install the Tray 4 Assembly (PL 14.1.17).
4. Install the Tray 3 Assembly (PL 14.1.19) .

## RRP 14.8 Roll (Center)

## Removal

1. Remove the Tray 3 Assembly (PL 14.1.19) .
2. Remove the Tray 4 Assembly (PL 14.1.17) .
3. Remove the Foot Cover (PL 14.1.2) .
4. Remove the one screw securing the Bracket (PL 14.1.11) to the machine and remove the Bracket .
5. Remove the E-ring securing the Roll to Bracket.
6. Remove the Roll together with the Shaft (PL 14.1.10).


Figure 1 Roll

## Replacement

1. Install the Roll to Bracket together with the Shaft (PL 14.1.10) using the one E-ring.
2. Install the Bracket (PL 14.1.11) to the machine using the one screw.

## NOTE Be sure to put the tip of the Bracket into the hole on the machine.

3. Install the Foot Cover (PL 14.1.2) .
4. Install the Tray 4 Assembly (PL 14.1.17) .
5. Install the Tray 3 Assembly (PL 14.1.19) .

## RRP 14.9 Roll (Outboard)

## Removal

1. Remove the Tray 4 Assembly (PL 14.1.17) .
2. Remove the E-ring securing the Roll to the machine .
3. Remove the Roll together with the Shaft (PL 14.1.13).


Figure 1 Roll

## Replacement

1. Install the Roll to the machine together with the Shaft (PL 14.1.13) using the one E-ring.
2. Install the Tray 4 Assembly (PL 14.1.17) .

## RRP 14.10 Tray 4 Assembly

## Removal

1. Pull out the Tray 4 Assembly.
2. Remove the two screws (Del Tite, M3x8mm) securing the Tray 4 Transport Assembly (PL 14.3.2) to the Tray 4 Assembly .
3. Push the Tray 4 Transport Assembly in the direction of the arrow until it touches the machine.
NOTE Be careful not to push it in too forcefully or it may damage the machine.
4. Pull out the Tray 4 Assembly fully toward you (to the front).
5. Remove the two screws securing the Tray 4 Stopper (PL 14.1.15) to the lower part of the Tray 4 Assembly to remove the Tray 4 Stopper.
6. Remove the Tray 4 Assembly.


Figure 1 Tray 4 Assembly

## Replacement

1. Insert the Tray 4 Assembly to the machine.
2. Secure the Tray 4 Stopper (PL 14.1.15) to the lower part of the Tray 4 Assembly using the two screws.
NOTE Make sure that the Tray 4 Assembly can be pulled out/pushed in smoothly in the machine, and also, it is not detached from the machine.
3. Pull out the Tray 4 Transport Assembly (PL 14.3.2) from the machine and install it to the Tray 4 Assembly using the two screws (Del Tite, M3x8mm).
4. Insert the Tray 4 Assembly.

## RRP 14.11 Tray 3 Assembly

## Removal

1. Remove the Left Lower Cover (PL 14.1.4).
2. Remove the Left Cover Assembly (PL 14.7.1) .
3. Loosen the screw (Del Tite, M3x8mm) securing the Tray 3 Stopper (PL 14.1.8) to the machine
4. Move the lower part of the Tray 3 Stopper in the direction of the arrow, and while keeping the position of it, move the Tray 3 Assembly toward you (to the front) to remove it.


Figure 1 Tray 3 Assembly

## Replacement

1. Move the lower part of the Tray 3 Stopper (PL 14.1.8) in the direction of the arrow, and while keeping the position of it, install the Tray 3 Assembly.
NOTE Make sure that the Tray 3 Assembly can be pulled out/pushed in smoothly in the machine, and also, it is not detached from the machine.
2. Install the Tray 3 Stopper (PL 14.1.8) to the machine using screw (Del Tite, M3x8mm).
3. Install the Left Cover Assembly (PL 14.7.1) .
4. Install the Left Lower Cover (PL 14.1.4) .

## RRP 14.12 Tray 3 Cover

## Removal

1. Pull out the Tray 3 Assembly (PL 14.1.19).
2. Remove the two screws (Del Tite, M3x8mm) securing the Tray 3 Cover to the Tray 3 Assembly
3. Remove the Tray 3 Cover.


Figure 1 Tray 3 Cover

## Replacement

1. Install the Tray 3 Cover to the Tray 3 Assembly (PL 14.1.19) using the two screws (Del Tite, M3x8mm).

NOTE Be sure to fit the two bosses on the lower part of the Tray 3 Cover into the holes on the Tray 3 Assembly.
2. Push in Tray 3 Assembly.

## RRP 14.13 Rear Tray Cables

NOTE When replacing cables, it is recommended to replace the Rear Tray Cables and the Front Left and Right Tray Cables at the same time.

## Removal

1. Remove the Left Lower Cover (PL 14.1.4) .
2. Remove the Left Cover Assembly (PL 14.7.1) .
3. Remove the Tray 3 Assembly (PL 14.1.19).
4. Remove the Tray 3 Cover (PL 14.2.1) .
5. Remove the two E-rings securing the Lift Shaft Assembly (PL 14.2.4) to the Frame Assembly (PL 14.2.28) and remove the Pulley (PL 14.2.3) .

## NOTE Note that the Front Right and Left Cables are detached.

6. Move the Left and Right Bearings securing the Lift Shaft Assembly to the Frame Assembly in the direction of the arrow and remove the Lift Shaft Assembly.
7. Remove the two Rear Tray Cables from the Lift Shaft Assembly.

NOTE Removing the Rear Tray Cables is made easy by moving the Pulley to the rear side of the Lift Shaft Assembly.


Figure 1 Tray Cables
8. Remove the E-ring securing the two Pulleys (PL 14.2.7) on the rear of the Frame Assembly and remove two each of the Cable Guides (PL 14.2.8) and the Pulleys (PL 14.2.7) .
9. Remove the E-ring securing the Cable Guide (PL 14.2.6) and the Pulley (PL 14.2.5) to the Frame Assembly and remove the Pulley and the Cable Guide.
10. Remove the two Tray Cables from the Bottom Plate (PL 14.2.12).


Figure 2 Removing Rear Tray Cables

## Replacement

1. Fit the tips of the two Tray Cables into the holes on the Bottom Plate (PL 14.2.12).

NOTE Place the Bottom Plate to the Tray 3 Assembly so that the arrow mark on the Bottom Plate points to the direction as shown in the figure.
2. Install the two Cable Guides (PL 14.2.8) on the rear to the Frame Assembly (PL 14.2.28) together with the Pulley (PL 14.2.7) using the E-rings.
NOTE Be sure that the two Tray Cables are put onto the two Pulleys on the rear in advance.
3. Install the Cable Guide (PL 14.2.6) to the Frame Assembly together with the Pulley (PL 14.2.5) using the one E-ring.

NOTE Be sure that the two Tray Cables are installed onto the Pulley in advance.
4. Fit two the Tray Cables into the hole on the Lift Shaft Assembly (PL 14.2.4).

NOTE When fitting the two Tray Cables into the holes, be careful not to twist them.
5. Install the Lift Shaft Assembly to the Frame Assembly by moving the left and right Bearings in the direction of the arrow.
NOTE Move the Pulley on the Lift Shaft Assembly to prevent the two Tray Cables from being detached.
6. Fit the Front Right Cable and Front Left Cable into the hole on the Lift Shaft Assembly.

NOTE When fitting the Front Right Cable and Front Left Cable into the holes, be careful not to twist them.
7. Fit the Front Right Cable (PL 14.2.10) and Front Left Cable (PL 14.2.11) into the hole on the Lift Shaft Assembly (PL 14.2.4).
8. Install the Lift Shaft Assembly to the Frame Assembly together with the Pulley (PL 14.2.3) using the one E -ring.
NOTE Be careful not to detach the Front Right Cable and Front Left Cable from the Lift Shaft Assembly.
9. Install the Tray 3 Cover (PL 14.2.1) .
10. Install the Tray 3 Assembly (PL 14.1.19) .
11. Install the Left Cover Assembly (PL 14.7.1) .


Figure 3 Replacing Tray Cables

## RRP 14.14 Front Right Tray Cable

NOTE When replacing cables, it is recommended to replace the Rear Tray Cables (PL 14.2.9) and the Front Left and Right Tray Cables at the same time.

## Removal

1. Remove the Left Lower Cover (PL 14.1.4).
2. Remove the Left Cover Assembly (PL 14.7.1) .
3. Remove the Tray 3 Assembly (PL 14.1.19) .
4. Remove the Tray 3 Cover (PL 14.2.1) .
5. Remove the two E-rings securing the Lift Shaft Assembly (PL 14.2.4) to the Frame Assembly (PL 14.2.28) and remove the Pulley (PL 14.2.3).

## NOTE Note that the Front Left Cable is detached.

6. Move the left and right Bearings securing the Lift Shaft Assembly to the Frame Assembly in the direction of the arrow and remove the Lift Shaft Assembly.

NOTE Note that the Tray Cables are detached.
7. Remove the Front Right Cable from the Lift Shaft Assembly .

NOTE Removing the Front Right Tray Cable is made easy by moving the Lift Shaft Assembly.
8. Remove the E-rings securing the two Pulleys (PL 14.2.7) on the front to the Frame Assembly and remove two each of the Cable Guides (PL 14.2.8) and the Pulleys .


Figure 1 Front Cables
9. Remove the tips of the Front Right Cable from the Bottom Plate (PL 14.2.12) .


Figure 2 Removing Front Cables


Figure 3 Removing Front Cables

## Replacement

1. Fit the tip of the Front Right Cable to the hole on the Bottom Plate (PL 14.2.12).

NOTE Place the Bottom Plate to the Tray 3 Assembly so that the arrow mark on the Bottom Plate points to the direction as shown in the figure.
2. Install the two Cable Guides (PL 14.2.8) on the front to the Frame Assembly (PL 14.2.28) together with the Pulleys (PL 14.2.7) using the one E-rings.

NOTE Be sure that the Front Right Cable and Front Left Cable (PL 14.2.11) are installed onto the two Pulleys on the front in advance.
3. Fit the Front Right Cable into the hole on the Lift Shaft Assembly (PL 14.2.4).

NOTE When fitting the Front Right Cable and Front Left Cable into the holes, be careful not to twist them.
4. Install the Lift Shaft Assembly to the Frame Assembly by moving the left and right Bearings in the direction of the arrow.

NOTE Move the Pulley on the Lift Shaft Assembly to prevent the Front Right Cable and Front Left Cable from being detached.
5. Install the Lift Shaft Assembly to the Frame Assembly together with the Pulley (PL 14.2.3) using an E-ring.

NOTE Be careful not to let the Front Right Cable and Front Left Cable be detached.
6. Install the Tray 3 Cover (PL 14.2.1) .
7. Install the Tray 3 Assembly (PL 14.1.19) .
8. Install the Left Cover Assembly (PL 14.7.1) .
9. Install the Left Lower Cover (PL 14.1.4) .

## RRP 14.15 Front Left Tray Cable

NOTE When replacing cables, it is recommended to replace the Rear Tray Cables (PL 14.2.9) and the Front Left and Right Tray Cables at the same time.

## Removal

1. Remove the Left Lower Cover (PL 14.1.4).
2. Remove the Left Cover Assembly (PL 14.7.1) .
3. Remove the Tray 3 Assembly (PL 14.1.19) .
4. Remove the Tray 3 Cover (PL 14.2.1) .
5. Remove the two E-rings securing the Lift Shaft Assembly (PL 14.2.4) to the Frame Assembly (PL 14.2.28) and remove the Pulley (PL 14.2.3) .

NOTE Note that the Front Right Cable is detached.
6. Move the left and right Bearings securing the Lift Shaft Assembly to the Frame Assembly in the direction of the arrow and remove the Lift Shaft Assembly.

## NOTE Note that the Tray Cables are detached.

7. Remove the Front Left Cable from the Lift Shaft Assembly.

## NOTE Removing the Front Left Tray Cable is made easy by moving the Lift Shaft Assembly.



Figure 1 Front Left Cable
8. Remove the E-rings securing the two Pulleys (PL 14.2.7) on the front to the Frame Assembly and remove two each of the Cable Guides (PL 14.2.8) and the Pulleys .
9. Remove the tips of the Front Left Cable from the Bottom Plate (PL 14.2.12).


Figure 2 Removing Front Left Cable

## Replacement

1. Fit the tip of the Front Left Cable to the hole on the Bottom Plate (PL 14.2.12).

NOTE Place the Bottom Plate to the Tray 3 Assembly so that the arrow mark on the Bottom Plate points to the direction as shown in the figure.
2. Install the two Cable Guides (PL 14.2.8) on the front to the Frame Assembly (PL 14.2.28) together with the Pulleys (PL 14.2.7) using the one E-rings.

NOTE Be sure that the Front Right Cable (PL 14.2.10) and the Front Left Cable are installed onto the two Pulleys on the front in advance.
3. Put the Front Left Cable into the hole on the Lift Shaft Assembly (PL 14.2.4).

NOTE When fitting the Front Right Cable and Front Left Cable into the holes, be careful not to twist them
4. Install the Lift Shaft Assembly to the Frame Assembly by moving the left and right Bearings in the direction of the arrow.

NOTE Move the Pulley on Lift Shaft Assembly to prevent the Front Right Cable and Front Left Cable from being detached.
5. Install Lift Shaft Assembly to Frame Assembly together with Pulley (PL 14.2.3) using an Ering.
NOTE Be careful not to let Front Right Cable and Front Left Cable be detached.
6. Install the Tray 3 Cover (PL 14.2.1) .
7. Install the Tray 3 Assembly (PL 14.1.19).
8. Install the Left Cover Assembly (PL 14.7.1) .
9. Install the Left Lower Cover (PL 14.1.4) .

## RRP 14.16 Bottom Plate

## Removal

1. Remove the Left Lower Cover (PL 14.1.4).
2. Remove the Left Cover Assembly (PL 14.7.1) .
3. Remove the Tray 3 Assembly (PL 14.1.19) .
4. Remove the Tray 3 Cover (PL 14.2.1) .
5. Remove the Rear Tray Cables (PL 14.2.9) .
6. Remove the Front Right Cable (PL 14.2.10)
7. Remove the Front Left Cable (PL 14.2.11) .
8. Remove the Bottom Plate .


Figure 1 Bottom Plate

## Replacement

1. Install the Bottom Plate.
2. Install the Front Left Cable (PL 14.2.11) .
3. Install the Front Right Cable (PL 14.2.10) .
4. Install the Rear Tray Cables (PL 14.2.9) .
5. Install the Tray 3 Cover (PL 14.2.1) .
6. Install the Tray 3 Assembly (PL 14.1.19) .
7. Install the Left Cover Assembly (PL 14.7.1) .
8. Install the Left Lower Cover (PL 14.1.4) .

## RRP 14.17 Rack Gear (Tray 3)

## Removal

1. Remove the Tray 3 Assembly (PL 14.1.19) .
2. Place the Tray 3 Assembly on its right side .


Figure 1 Tray 3
3. Remove the two Pinions (PL 14.2.21).
4. Remove the four screws (Silver, M3x8mm) securing the two Rack Gears to the Frame Assembly (PL 14.2.28) .
5. Remove the two Rack Gears.

## Replacement

1. Move the Front Side Guide (PL 14.2.14) and the Rear Side Guide (PL 14.2.18) in the Tray 3 Assembly (PL 14.1.19) fully outward.
2. Install the two Rack Gears to the Frame Assembly (PL 14.2.28) using the two screw each (Silver, M3x8mm).
3. Install the two Pinions (PL 14.2.21) .
4. Install the Tray 3 Assembly (PL 14.1.19).


Figure 2 Rack Gear

## RRP 14.18 Pinion (Tray 3)

## Removal

1. Remove the Tray 3 Assembly (PL 14.1.19)
2. Place the Tray 3 Assembly on its right side .
3. Remove the two E-rings securing the two Pinions to the Frame Assembly (PL 14.2.28) to remove the two Pinions .


Figure 1 Tray 3

## Replacement

1. Move the Front Side Guide (PL 14.2.14) and the Rear Side Guide (PL 14.2.18) in the Tray 3 Assembly (PL 14.1.19) fully outward.
2. Install the two Pinions to the Frame Assembly (PL 14.2.28) using the one E-ring each.
3. Install the Tray 3 Assembly (PL 14.1.19).


## RRP 14.19 Tray 4 Cover

## Removal

1. Remove the Tray 4 Assembly (PL 14.1.17) .
2. Remove the two screws (Del Tite, M3x8mm) securing the Tray 4 Cover to the Tray 4 Assembly .
3. Move the Tray 4 Cover in the direction of the arrow to remove it.


Figure 1 Tray 4 Cover

## Replacement

1. Install the Tray 4 Cover to the Tray 4 Assembly (PL 14.1.17) using the two screws (Del Tite, $\mathrm{M} 3 \times 8 \mathrm{~mm}$ ).
NOTE Be sure to fit the two bosses on the lower part of the Tray 4 Cover into the holes on the Tray 4 Assembly.
2. Install the Tray 4 Assembly (PL 14.1.17) .

## RRP 14.20 Tray 4 Transport Assembly

## Removal

1. Remove the Tray 4 Assembly (PL 14.1.17) .
2. Remove the Tray 4 Transport Assembly .


Figure 1 Tray 4 Transport

## Replacement

1. Insert the Tray 4 Transport Assembly to the frame.

NOTE Be sure to insert the Tray 4 Transport Assembly along the guide rails of the frame.
2. Install the Tray 4 Transport Assembly to the Tray 4 Assembly using the two screws.
3. Install the Tray 4 Assembly (PL 14.1.17) .

## RRP 14.21 Rear Tray Cables (Tray 4)

NOTE When replacing the cable, it is recommended to replace the Front Tray Cables (PL 14.3.9) together.

## Removal

1. Remove the Tray 4 Assembly (PL 14.1.17) .
2. Remove the Tray 4 Cover (PL 14.3.1) .
3. Place the Frame Assembly (PL 14.3.26) on its right side down .
4. Remove the two E-rings securing the Lift Shaft Assembly (PL 14.3.4) to the Frame Assembly and remove the Pulley (PL 14.3.5).

NOTE Note that the two Front Tray Cables are detached.
5. Move the left and right Bearings securing the Lift Shaft Assembly to the Frame Assembly in the direction of the arrow to remove the Lift Shaft Assembly.
6. Remove the two Rear Tray Cables from the Lift Shaft Assembly.

NOTE Removing the Rear Tray Cable is made easy by moving the Pulley to the rear side of the Lift Shaft Assembly.


Figure 1 Rear Tray Cables
7. Place the Frame Assembly back to its original position .
8. Remove the E-ring securing the two Pulleys (PL 14.3.6) on the rear to the Frame Assembly and remove two each of the Cable Guide (PL 14.3.7) and the Pulley .
9. Remove the two Rear Tray Cables from the Bottom Plate (PL 14.3.10).


Figure 2 Cable Guide


Figure 3 Lift Shaft Assembly

## Replacement

1. Fit the tips of the two Rear Tray Cables into the hole on the Bottom Plate (PL 14.3.10).

NOTE Place the Bottom Plate to the Tray 4 Assembly so that the arrow mark on the Bottom Plate points to the direction as shown in the figure.
2. Install the two Cable Guides (PL 14.3.7) on the rear to the Frame Assembly (PL 14.3.26) together with the Pulley (PL 14.3.6) using the E-rings.
NOTE Be sure that the two Rear Tray Cables are installed onto the two Pulleys on the rear in advance.
3. Place the Frame Assembly on its right side down.
4. Put the two Rear Tray Cables into the hole on the Lift Shaft Assembly (PL 14.3.4).

NOTE When fitting the Rear Tray Cables into the holes, be careful not to twist them.
5. Move the Pulley portion of the Lift Shaft Assembly to prevent the Rear Tray Cable from coming off of the Lift Shaft Assembly.
6. Secure the Lift Shaft Assembly to the Frame Assembly by moving the left and right Bearings in the direction of the arrow.

NOTE Move the Pulley on the Lift Shaft Assembly to prevent the two Rear Tray Cables from being detached.
7. Put the two Front Tray Cables (PL 14.3.9) into the hole on the Lift Shaft Assembly.

NOTE Install the two Front Tray Cables carefully not to twist them.
8. Install the Lift Shaft Assembly to the Frame Assembly together with the Pulley (PL 14.3.5) using the two E-rings.

## NOTE Be careful not to let the two Front Tray Cables be detached.

9. Place the Frame Assembly back to its original position.
10. Install the Tray 4 Cover (PL 14.3.1) .
11. Install the Tray 4 Assembly (PL 14.1.17) .

## RRP 14.22 Front Tray Cables (Tray 4)

NOTE When replacing the cable, it is recommended to replace the Rear Tray Cables together.

## Removal

1. Remove the Tray 4 Assembly (PL 14.1.17) .
2. Remove the Tray 4 Cover (PL 14.3.1) .
3. Place the Frame Assembly (PL 14.3.26) on its right side down
4. Remove the two E-rings securing the Lift Shaft Assembly (PL 14.3.4) to the Frame Assembly and remove the Pulley (PL 14.3.5).

## NOTE Note that the two Front Tray Cables are detached.

5. Move the left and right Bearings securing the Lift Shaft Assembly to the Frame Assembly in the direction of the arrow to remove the Lift Shaft Assembly.
6. Remove the two Front Tray Cables from the Lift Shaft Assembly.

## NOTE Removing the Front Tray Cable is made easy by moving the Lift Shaft Assembly.



Figure 1 Front Tray Cables
7. Place the Frame Assembly back to its original position
8. Remove the E-ring securing the two Pulleys (PL 14.3.6) on the front to the Frame Assembly (PL 14.2.28) and remove two each of the Cable Guide (PL 14.3.7) and the Pulley.
9. Remove the two Front Tray Cables from the Bottom Plate (PL 14.3.10) .


Figure 2 Front Cables


Figure 3 Cable Pulley

## Replacement

1. Fit the tips of the Front Tray Cables into the hole on the Bottom Plate (PL 14.3.10).

NOTE Place the Bottom Plate to the Tray 4 Assembly so that the arrow mark on the Bottom Plate points to the direction as shown in the figure.
2. Install the two Cable Guides (PL 14.3.7) on the front to the Frame Assembly (PL 14.3.26) together with the Pulley (PL 14.3.6) using the E-rings.
NOTE Be sure that each of the two Front Tray Cables is installed onto the two Pulleys on the front in advance.
3. Put the two Front Tray Cables into the hole on the Lift Shaft Assembly (PL 14.3.4).

NOTE When fitting the Front Tray Cables into the holes, be careful not to twist them.
4. Place the Frame Assembly on its right side down.
5. Move the Pulley of the Lift Shaft Assembly to prevent the two Front Tray Cables from coming off of the Lift Shaft Assembly.
6. Secure the Lift Shaft Assembly to the Frame Assembly by moving the left and right Bearings in the direction of the arrow.

NOTE Perform the service with the Pulley of the Lift Shaft Assembly pushed down, to prevent the two Front Tray Cables from being detached.
7. Install the Lift Shaft Assembly to the Frame Assembly together with the Pulley (PL 14.3.5) using the two E-rings.

NOTE Be careful not to let the two Front Tray Cables be detached.
8. Place the Frame Assembly back to its original position.
9. Install the Tray 4 Cover (PL 14.3.1) .
10. Install the Tray 4 Assembly (PL 14.1.17) .

## RRP 14.23 Bottom Plate (Tray 4)

## Removal

1. Remove the Tray 4 Assembly (PL 14.1.17) .
2. Remove the Tray 4 Cover (PL 14.3.1).
3. Remove the Rear Tray Cable (PL 14.3.8) .
4. Remove the Front Tray Cable (PL 14.3.9) .
5. Remove the Bottom Plate .


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Figure 1 Bottom Plate

## Replacement

1. Install the Bottom Plate.
2. Install the Front Tray Cable (PL 14.3.9) .
3. Install the Rear Tray Cable (PL 14.3.8) .
4. Install the Tray 4 Cover (PL 14.3.1).
5. Install the Tray 4 Assembly (PL 14.1.17) .

## RRP 14.24 Rack Gear (Tray 4)

## Removal

1. Remove the Tray 4 Assembly (PL 14.1.17) .
2. Place the Tray 4 Assembly on its right side down .
3. Remove the two Pinions (PL 14.3.19).
4. Remove the four screws (Del Tite, M3x8mm) securing the two Rack Gears to the Frame Assembly (PL 14.3.26) .
5. Remove the two Rack Gears.


Figure 1 Tray 4


Figure 2 Rack Gears

## Replacement

1. Move the Front Side Guide (PL 14.3.12) and the Rear Side Guide (PL 14.3.27) in the Tray 4 Assembly (PL 14.1.17) fully outward.
2. Install the two Rack Gears to the Frame Assembly (PL 14.3.26) using two screw each (Del Tite, M3x8mm).
3. Install the two Pinions (PL 14.3.19) .
4. Install the Tray 4 Assembly (PL 14.1.17) .

## RRP 14.25 Pinion (Tray 4)

## Removal

1. Remove the Tray 4 Assembly (PL 14.1.17).
2. Place the Tray 4 Assembly on its right side down .
3. Remove the two E-rings securing the two Pinions to the Frame Assembly (PL 14.3.26) to remove the two Pinions .


Figure 1 Tray 4


Figure 2 Pinion

## Replacement

1. Move the Front Side Guide (PL 14.3.12) and the Rear Side Guide (PL 14.3.27) in the Tray 4 Assembly (PL 14.1.17) fully outward.
2. Install the two Pinions to the Frame Assembly (PL 14.3.26) using the one E-ring each.
3. Install the Tray 4 Assembly (PL 14.1.17).

## RRP 14.26 Takeaway Roll Assembly

## Removal

1. Remove the Tray 3 Assembly (PL 14.1.19) .
2. Remove the Tray 4 Assembly (PL 14.1.17) .
3. Remove the Tray 4 Transport Assembly (PL 14.3.2) .
4. Open the Upper Chute (PL 14.4.4) .
5. Remove the E-ring securing the Takeaway Roll Assembly to the Lower Chute (PL 14.4.14) and remove the Bearing (PL 14.4.6).
6. Lift the Takeaway Roll Assembly in the direction of the arrow to remove.

NOTE Be careful not to hold the rubber roller part of the Takeaway Roll Assembly.


Figure 1 Takeaway Roll

## Replacement

1. Install the Takeaway Roll Assembly to the Lower Chute (PL 14.4.14) together with the Bearing (PL 14.4.6) using the E-ring.
NOTE Be careful not to hold the rubber roller of the Takeaway Roll Assembly. Also, be sure to fit the flat surface of the Bearing to the hole on the Lower Chute.
2. Close the Upper Chute (PL 14.4.4).
3. Install the Tray 4 Transport Assembly (PL 14.3.2) .
4. Install the Tray 4 Assembly (PL 14.1.17) .
5. Install the Tray 3 Assembly (PL 14.1.19) .

## RRP 14.27 Tray 4 Feeder

## Removal

1. Remove the Tray 3 Assembly (PL 14.1.19).
2. Remove the Tray 4 Assembly (PL 14.1.17) .
3. Remove the Tray 4 Transport Assembly (PL 14.3.2) .
4. Disconnect the two connectors (P/J661A and P/J549) of the Wire Harness (PL 14.8.18) from the Tray 4 Feeder .
5. Remove the two screws securing the Tray 4 Feeder to the machine.
6. Remove the front side screw securing the Stand Bracket (PL 14.4.22) to the machine to remove the Stand Bracket.
7. Move the Tray 4 Feeder in the direction of the arrow to remove it.


Figure 1 Tray 4 Feeder
8. Remove the two screws securing the F/O Lower Chute (PL 14.4.20) to the Tray 4 Feeder to remove the F/O Lower Chute .
9. Remove the two screws securing the Upper Chute (PL 14.4.19) to the Tray 4 Feeder to remove the Upper Chute.
10. Remove the one screw securing the Cover (PL 14.4.17) to the Tray 4 Feeder to remove Cover.


Figure 2 Feeder Assembly

## Replacement

1. Install the Cover (PL 14.4.17) to Tray 4 Feeder using the one screw.
2. Install the Upper Chute (PL 14.4.19) to Tray 4 Feeder using the two screws.
3. Install the F/O Lower Chute (PL 14.4.20) to Tray 4 Feeder using the two screws.
4. Move the Tray 4 Feeder in the opposite direction of the arrow to install it.
5. Install the Stand Bracket (PL 14.4.22) to the machine using the one screw.
6. Connect the two connectors (P/J661A and P/J549) of the Wire Harness (PL 14.8.18) to the Tray 4 Feeder.
7. Install the Tray 4 Transport Assembly (PL 14.3.2).
8. Install the Tray 4 Assembly (PL 14.1.17) .
9. Install the Tray 3 Assembly (PL 14.1.19).

## RRP 14.28 Tray 4 Feed Out Sensor

## Removal

1. Remove the Tray 3 Assembly (PL 14.1.19) .
2. Remove the Tray 4 Assembly (PL 14.1.17) .
3. Disconnect the connector (P/J825) of the Wire Harness (PL 14.6.16) from the Tray 4 Feed Out Sensor .
4. Release the hooks securing the Tray 4 Feed Out Sensor to the machine as shown in the figure.
5. Move the Tray 4 Feed Out Sensor in the direction of the arrow to remove it.


Figure 1 Feed Out Sensor

## Replacement

1. Move the Tray 4 Feed Out Sensor in the opposite direction of the arrow and install it with the hooks.
2. Connect the connector (P/J825) of the Wire Harness (PL 14.6.16) to the Tray 4 Feed Out Sensor.
3. Install the Tray 4 Assembly (PL 14.1.17) .
4. Install the Tray 3 Assembly (PL 14.1.19).

## RRP 14.29 Tray 3 Paper Size Switch

## Removal

1. Remove the Tray 3 Assembly (PL 14.1.19) .
2. Disconnect the connector ( $\mathrm{P} / \mathrm{J} 820$ ) of the Wire Harness (PL 14.8.18) from the Tray 3 Paper Size Switch .
3. Remove the screw securing the Tray 3 Paper Size Switch to the machine.
4. Remove the Tray 3 Paper Size Switch.


Figure 1 Paper Size Switch

## Replacement

1. Install the Tray 3 Paper Size Switch to the machine using the one screw.
2. Be sure to fit the boss on the machine into the hole on the Tray 3 Paper Size Switch.
3. Connect the connector (P/J820) of the Wire Harness (PL 14.8.18) to the Tray 3 Paper Size Switch.
4. Install the Tray 3 Assembly (PL 14.1.19) .

## RRP 14.30 Tray 4 Paper Size Switch

## Removal

1. Remove the Tray 4 Assembly (PL 14.1.17).
2. Disconnect the connector (P/J824) of the Wire Harness (PL 14.8.18) from the Tray 4 Paper Size Switch .
3. Remove the screw securing the Tray 4 Paper Size Switch to the machine.
4. Remove the Tray 4 Paper Size Switch.


Figure 1 Paper Size Switch

## Replacement

1. Install the Tray 4 Paper Size Switch to the machine using the one screw.
2. Be sure to fit the boss on the machine into the hole on the Tray 4 Paper Size Switch.
3. Connect the connector (P/J824) of the Wire Harness (PL 14.8.18) to the Tray 4 Paper Size Switch.
4. Install the Tray 4 Assembly (PL 14.1.17) .

## RRP 14.31 Tray 3 Feeder

## Removal

1. Pull out the Tray 3 Assembly (PL 14.1.19).
2. Pull out the Tray 4 Assembly (PL 14.1.17).
3. Open the Left Cover Assembly (PL 14.7.1).
4. Remove the screws (one each) securing the left and right Supports (PL 14.7.14) to the machine .
5. Remove the bosses left and right securing the Lower Chute (PL 14.5.9) to the machine to remove the Lower Chute.
6. Remove the bosses left and right securing the Feeder Chute Assembly (PL 14.5.10) to the Tray 3 Feeder to remove the Feeder Chute Assembly.


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Figure 1 Tray 3 Feeder
7. Release the Wire Harness (PL 14.8.18) from the clamp on the machine .
8. Disconnect the connector (P/J661B) of the Wire Harness (PL 14.8.18) from the machine.
9. Remove the three screws securing the Tray 3 Feeder to the machine.
10. Remove the Tray 3 Feeder.
11. Remove the screw securing the Cover (PL 14.5.2) to the Tray 3 Feeder to remove the Cover.


Figure 2 Tray 3 Feeder

## Replacement

1. Install the Cover (PL 14.5.2) to the Tray 3 Feeder using the one screw.
2. Install the Tray 3 Feeder to the machine using three screws.
3. Connect the connector (P/J661B) of the Wire Harness (PL 14.8.18) to the machine.
4. Secure the Wire Harness (PL 14.8.18) to the clamp.
5. Install the Feeder Chute Assembly (PL 14.5.10) to the Tray 3 Feeder with the left and right bosses.

NOTE Fit the boss on the machine into the hole on the Feeder Chute Assembly.
6. Install the Lower Chute (PL 14.5.9) to the machine with the left and right bosses.

NOTE Fit the boss on the machine into the hole on the Feeder Chute Assembly.
7. Install the left and right Supports (PL 14.7.14) to the machine using one screw each.
8. Close the Left Cover Assembly (PL 14.7.1).
9. Push in Tray 4 Assembly (PL 14.1.17).
10. Push in Tray 3 Assembly (PL 14.1.19).

## RRP 14.32 Takeaway Roll Assembly

## Removal

1. Open the Left Cover Assembly (PL 14.7.1).
2. Remove the two screws (Del Tite, M3x8mm) securing the Chute (PL 14.5.6) to the machine
3. Disconnect the connector (P/J821) of the Wire Harness (PL 14.5.7) connected to the Tray 3 Feed Out Sensor (PL 14.5.8).
4. Remove the Chute.
5. Remove the E-ring on the right (front) securing the Takeaway Roll Assembly to the machine.
6. Move the Takeaway Roll Assembly in the direction of the arrow and remove the Bearing (PL 14.5.4).
7. Remove the Takeaway Roll Assembly.

## NOTE The Bearing is detached. Be careful not to lose it.

## NOTE Be careful not to hold the rubber roller of the Takeaway Roll Assembly.



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Figure 1 Takeaway Roll

## Replacement

1. Move the Takeaway Roll Assembly in the opposite direction of the arrow, and secure it together with the Bearing (PL 14.5.4).

NOTE Be sure to put the boss on the Bearing on the left of the Takeaway Roll Assembly into the notch of the hole on the machine.

## NOTE

Be careful not to hold the rubber roller of the Takeaway Roll Assembly.
2. Install the Takeaway Roll Assembly to the machine together with the Bearing using the one E-ring.
3. Connect the connector (P/J821) of the Wire Harness (PL 14.5.7) to the Tray 3 Feed Out Sensor (PL 14.5.8).
4. Install the Chute (PL 14.5.6) to the machine using the two screws (Del Tite, M3x8mm).
5. Close the Left Cover Assembly (PL 14.7.1).

## RRP 14.33 Tray 3 Feed Out Sensor

## Removal

1. Open the Left Cover Assembly (PL 14.7.1).
2. Remove the two screws securing the Chute (PL 14.5.6) to the machine .
3. Disconnect the connector (P/J821) of the Wire Harness (PL 14.5.7) from the Tray 3 Feed Out Sensor.
4. Remove the Chute.
5. Release the hook securing the Tray 3 Feed Out Sensor to the Chute as shown in the figure.
6. Remove the Tray 3 Feed Out Sensor.


Figure 1 Feed Out Sensor

## Replacement

1. Install the Tray 3 Feed Out Sensor to the Chute (PL 14.5.6) with the hook.

NOTE Be sure to put the Actuator attached to the Tray 3 Feed Out Sensor into the hole on the Chute.
2. Connect the connector (P/J821) of the Wire Harness (PL 14.5.7) to the Tray 3 Feed Out Sensor.
3. Install the Chute to the machine using two screws.
4. Close the Left Cover Assembly (PL 14.7.1).

## RRP 14.34 Tray 3/4 Feed Lift Up Motor

## Removal

1. Remove the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .
2. Disconnect the connector (Tray 3:P/J220B, Tray 4:P/J220A) of the Wire Harness (PL 14.6.16) from the Tray 3/4 Feed Lift Up Motor .
3. Remove the two screws (M3x6mm) securing the Tray 3/4 Feed Lift Up Motor to the Tray 3 Feeder.
4. Remove the Tray 3/4 Feed Lift Up Motor.


Figure 1 Feed Lift Up Motor

## Replacement

1. Install the Tray $3 / 4$ Feed Lift Up Motor to the Tray 3 Feeder (PL 14.5.1) using the two screws (M3x6mm).
2. Connect the connector (Tray 3:P/J220B, Tray 4:P/J220A) of the Wire Harness (PL 14.6.16) to the Tray $1 / 2$ Feed Lift Up Motor.
3. Install the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .

NOTE Be sure to put the Actuator attached to the Tray 3 Feed Out Sensor into the hole on the Chute.

## RRP 14.35 Spacer

## Removal

1. Remove the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .
2. Release the Wire Harness (PL 14.6.16) from the clamp on the Bracket (PL 14.6.3) .
3. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 14.6.34).

NOTE Note that the Gears attached on the Bracket may be detached.
4. Remove E-rings securing the Spacer, 31T Gear (PL 14.6.5) and the Spring (PL 14.6.6) to the Bracket, using a mini-screwdriver or the like.
NOTE Note that Spring may pop out.
5. Remove the Spacer.


FI3L053A1
Figure 1 Spacer

## Replacement

1. Install the Spacer to the Bracket (PL 14.6.3) together with the 31T Gear (PL 14.6.5) and the Spring (PL 14.6.6), and fix them using E-ring.
2. Install the Bracket to the Lower Frame (PL 14.6.34) using the three screws (Del Tite, M3x6mm).
NOTE Make sure that the Gears attached on the Bracket are surely installed.
3. Secure the Wire Harness (PL 14.6.16) to the clamp on the Bracket.
4. Install the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .

## RRP 14.36 31T Gear

## Removal

1. Remove the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .
2. Release the Wire Harness (PL 14.6.16) from the clamp on the Bracket (PL 14.6.3).
3. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 14.6.34).

NOTE Note that the Gears attached on the Bracket may be detached.
4. Remove E-rings securing 31T Gear, Spacer (PL 14.6.4) and Spring (PL 14.6.6) to Bracket.

## NOTE Note that Spring can pop out.

5. Remove 31T Gear.


FI3L053A1
Figure 1 31T Gear

## Replacement

1. Install 31T Gear to Bracket (PL 14.6.3), together with Spacer (PL 14.6.4) and Spring (PL 1^のか ucinn C_rinnc
2. Install Bracket to Lower Frame (PL 14.6.34) using three screws (Del Tite, M3x6mm).

NOTE Make sure that the Gears attached on the Bracket are surely installed.
3. Secure the Wire Harness (PL 14.6.16) to the clamp on the Bracket.
4. Install the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .

## RRP 14.37 Oneway Clutch

## Removal

1. Remove the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .
2. Release the Wire Harness (PL 14.6.16) from the clamp on the Bracket (PL 14.6.3) .
3. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 14.6.34)

NOTE Note that the Gears attached on the Bracket may be detached.
4. Remove the Oneway Clutch.


Figure 1 Oneway Clutch

## Replacement

1. II
2. Install the Bracket (PL 14.6.3) to the Lower Frame (PL 14.6.34) using the three screws (Del Tite, M3x6mm).
NOTE Make sure that the Gears attached on the Bracket are surely installed.
3. Secure the Wire Harness (PL 14.6.16) to the clamp on the Bracket.
4. Install the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .

## RRP 14.38 Oneway Gear

## Removal

1. Remove the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .
2. Remove the Oneway Clutch (PL 14.6.7) .
3. Remove the Oneway Gear.


Figure 1 Oneway Clutch

## Replacement

1. Install the Oneway Gear.
2. Install the Oneway Clutch (PL 14.6.7).
3. Install the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .

## RRP 14.39 13T Gear

## Removal

1. Remove the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .
2. Release the Wire Harness (PL 14.6.16) from the clamp on the Bracket (PL 14.6.3) .
3. Remove the three screws securing the Bracket to the Lower Frame (PL 14.6.34)

NOTE Note that the Gears attached on the Bracket may be detached.
4. Remove the 13T Gear.


Figure 1 13T Gear

## Replacement

1. Install the 13T Gear.
2. Install the Bracket (PL 14.6.3) to the Lower Frame (PL 14.6.34) using the three screws.

NOTE Make sure that the Gears attached on the Bracket are surely installed.
3. Secure the Wire Harness (PL 14.6.16) to the clamp on the Bracket.
4. Install the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .

## RRP 14.40 Actuator

## Removal

1. Remove the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .
2. Remove the two bosses on the Actuator securing the Actuator to the Upper Frame (PL 14.6.40) .
3. Remove the Actuator.


Figure 1 Actuator

## Replacement

1. Install Actuator.

NOTE Fit the bosses on the Actuator into the holes on the Upper Frame (PL 14.6.40).
2. Install the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .

## RRP 14.41 Level Sensor

## Removal

1. Remove the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .
2. Remove the Actuator (PL 14.6.13).
3. Disconnect the connector (Tray 3:P/J102B, Tray 4:P/J102A) of the Wire Harness (PL 14.6.16) from the Level Sensor
4. Release the hooks securing the Level Sensor to the Upper Frame (PL 14.6.40) as shown in the figure.
5. Remove the Level Sensor.


## Replacement

1. Secure the Level Sensor to the Upper Frame (PL 14.6.40) using the hooks.
2. Connect the connector (Tray 3:P/J102B, Tray 4:P/J102A) of the Wire Harness (PL 14.6.16) to the Level Sensor.
3. Install the Actuator (PL 14.6.13).
4. Install the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .

## RRP 14.42 No Paper Sensor

## Removal

1. Remove the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .
2. Disconnect the connector (Tray 3:P/J101B, Tray 4:P/J101A) of the Wire Harness (PL 14.6.16) from the No Paper Sensor .
3. Release the hooks securing the No Paper Sensor to the Upper Frame (PL 14.6.40) as shown in the figure.
4. Remove the No Paper Sensor.


## Replacement

1. Secure the No Paper Sensor to the Upper Frame (PL 14.6.40) using the hooks.
2. Connect the connector (Tray 3:P/J101B, Tray 4:P/J101A) of the Wire Harness (PL 14.6.16) to No Paper Sensor.
3. Install the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .

## RRP 14.43 Pre Feed Sensor

## Removal

1. Remove the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .
2. Remove the Pre Feed Sensor from the Front Chute (PL 14.6.12)
3. Disconnect the connector (Tray 3:P/J103B, Tray 4:P/J103A) of the Wire Harness (PL 14.6.16) from the Pre Feed Sensor.


Figure 1 Pre Feed Sensor

## Replacement

1. Connect the connector (Tray 3:P/J103B, Tray 4:P/J103A) of the Wire Harness (PL 14.6.16) to the Pre Feed Sensor.
2. Install the Pre Feed Sensor to the Front Chute (PL 14.6.12).
3. Install the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .

## RRP 14.44 28T/21T Gear

## Removal

1. Remove the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .
2. Release the Wire Harness (PL 14.6.16) from the clamp on the Bracket (PL 14.6.3) .
3. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 14.6.34).

NOTE Note that the Gears attached on the Bracket may be detached.
4. Remove the 28T/21T Gear.


Figure 1 28T/21T Gear

## Replacement

1. Install the $28 \mathrm{~T} / 21 \mathrm{~T}$ Gear.
2. Install the Bracket (PL 14.6.3) to the Lower Frame (PL 14.6.34) using the three screws (Del Tite, M3x6mm).

## NOTE Make sure that the Gears attached on the Bracket are surely installed.

3. Secure the Wire Harness (PL 14.6.16) to the clamp on the Bracket.
4. Install the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .

## RRP 14.45 29T Gear

## Removal

1. Remove the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .
2. Release the Wire Harness (PL 14.6.16) from the clamp on the Bracket (PL 14.6.3) .
3. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 14.6.34).

NOTE Note that the Gears attached on the Bracket may be detached.
4. Remove the 29T Gear.


Figure 1 29T Gear

## Replacement

1. Install the 29T Gear.
2. Install the Bracket (PL 14.6.3) to the Lower Frame (PL 14.6.34) using three screws (Del Tite, M3x6mm).

NOTE Make sure that the Gears attached on the Bracket are surely installed.
3. Secure the Wire Harness (PL 14.6.16) to the clamp on the Bracket.
4. Install the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .

## RRP 14.46 Feed Roller Assembly

## Removal

1. Pull out the Tray 3 and Tray 4.
2. Move the Front Chute (PL 14.6.12) in the direction of the arrow .
3. Release the hook securing the Feed Roller Assembly to the Shaft (PL 14.6.23) as shown in the figure.
4. Remove the Feed Roller Assembly.

NOTE Note that the Oneway Clutch (PL 14.6.21) and the 22T Oneway Gear (PL 14.6.22) may be detached.

NOTE When removing, do not hold the rubber roller of the Feed Roller Assembly.


Figure 1 Feed Roller

## Replacement

1. Install the Feed Roller Assembly to the Shaft (PL 14.6.23), and fix it using hook.

NOTE When installing, do not hold the rubber roller of the Feed Roller Assembly.
2. Move the Front Chute (PL 14.6.12) in the opposite direction of the arrow (to the rear side).
3. Insert the Tray 3 and Tray 4.

## RRP 14.47 Oneway Clutch

## Removal

1. Pull out the Tray 3 and Tray 4.
2. Remove the Feed Roller Assembly (PL 14.6.20) .
3. Remove the Oneway Clutch

NOTE Note that 22T Oneway Gear (PL 14.6.22) may be detached.


Figure 1 Oneway Clutch

## Replacement

1. Install the Oneway Clutch.
2. Install the Feed Roller Assembly (PL 14.6.20) .
3. Insert the Tray 3 and Tray 4.

## RRP 14.48 22T Oneway Gear

## Removal

1. Pull out the Tray 3 and Tray 4.
2. Remove the Feed Roller Assembly (PL 14.6.20) .
3. Remove the Oneway Clutch (PL 14.6.21) .
4. Remove the 22T Oneway Gear .


Figure 1 Oneway Gear

## Replacement

1. Install the 22T Oneway Gear.
2. Install the Oneway Clutch (PL 14.6.21) .
3. Install the Feed Roller Assembly (PL 14.6.20) .
4. Insert the Tray 3 and Tray 4.

## RRP 14.49 Friction Clutch

## Removal

1. Pull out the Tray 3 and Tray 4.
2. Remove the Retard Roller Assembly (PL 14.6.20) .
3. Remove the Spacer (PL 14.6.29) .
4. Remove the Friction Clutch .


Figure 1 Friction Clutch

## Replacement

1. Install the Friction Clutch.
2. Install the Spacer (PL 14.6.29) .
3. Install the Retard Roller Assembly (PL 14.6.20) .
4. Insert the Tray 3 and Tray 4.

## RRP 14.50 Retard Roller Assembly

## Removal

1. Pull out the Tray 3 and Tray 4.
2. Move the Front Chute (PL 14.6.12) in the direction of the arrow .
3. Release the hook securing the Retard Roller Assembly to the Retard Shaft (PL 14.6.27) as shown in the figure.
4. Remove the Retard Roller Assembly.

NOTE Note that the Spacer (PL 14.6.29) and the Friction Clutch (PL 14.6.26) may be detached.
NOTE When removing, do not hold the rubber roller of the Retard Roller Assembly.


Figure 1 Retard Roller

## Replacement

1. Install the Retard Roller Assembly to the Retard Shaft (PL 14.6.27), and fix it using the hook.

NOTE When installing, do not hold the rubber roller of the Retard Roller Assembly.
2. Move the Front Chute (PL 14.6.12) in the opposite direction of the arrow (to the rear side).
3. Insert the Tray 3 and Tray 4.

## RRP 14.51 Spacer

## Removal

1. Pull out the Tray 3 and Tray 4.
2. Remove the Retard Roller Assembly (PL 14.6.20) .
3. Remove the Spacer .

NOTE Note that the Friction Clutch (PL 14.6.26) may be detached.


Figure 1 Spacer

## Replacement

1. Install the Spacer.
2. Install the Retard Roller Assembly (PL 14.6.20) .
3. Insert the Tray 3 and Tray 4.

## RRP 14.52 33T Gear

## Removal

1. Pull out the Tray 3 and Tray 4.
2. Remove the Nudger Roller Assembly (PL 14.6.20) .
3. Remove the 25T Gear (PL 14.6.33) .
4. Remove the 33T Gear .


Figure 1 Gear

## Replacement

1. Install the 33T Gear.
2. Install the 25T Gear (PL 14.6.33) .
3. Install the Nudger Roller Assembly (PL 14.6.20) .
4. Insert the Tray 3 and Tray 4.

## RRP 14.53 Nudger Roller Assembly

## Removal

1. Pull out the Tray 3 and Tray 4.
2. Move the Front Chute (PL 14.6.12) in the direction of the arrow .
3. Release the hook securing the Nudger Roller Assembly to the Nudger Shaft (PL 14.6.31) as shown in the figure.
4. Remove the Nudger Roller Assembly.

NOTE Note that the 25T Gear (PL 14.6.33) may be detached.
NOTE When removing, do not hold the rubber roller of the Nudger Roller Assembly.


Figure 1 Nudger Roller

## Replacement

1. Install the Nudger Roller Assembly to the Nudger Shaft (PL 14.6.31), and fix it using the hook.

NOTE When installing, do not hold the rubber roller of the Nudger Roller Assembly.
2. Move the Front Chute (PL 14.6.12) in the opposite direction of the arrow (to the rear side).
3. Insert the Tray 3 and Tray 4.

## RRP 14.54 25T Gear

## Removal

1. Pull out the Tray 3 and Tray 4.
2. Remove the Nudger Roller Assembly (PL 14.6.20) .
3. Remove the 25T Gear .


Figure 1 25T Gear

## Replacement

1. Install the 25 T Gear.
2. Install the Nudger Roller Assembly (PL 14.6.20) .
3. Insert the Tray 3 and Tray 4.

## RRP 14.55 27T Gear

## Removal

1. Remove the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .
2. Release the Wire Harness (PL 14.6.16) from the clamp on the Bracket (PL 14.6.3) .
3. Remove the three screws (Del Tite, M3x6mm) securing the Bracket to the Lower Frame (PL 14.6.34).

NOTE Note that the Gears attached on the Bracket may be detached.
4. Release the hook securing the 27T Gear to the Shaft (PL 14.6.23) as shown in the figure.
5. Remove the 27T Gear.


Figure 1 27T Gear

## Replacement

1. Install the 27T Gear to the Shaft (PL 14.6.23) using the hook.
2. Install Bracket (PL 14.6.3) to Lower Frame (PL 14.6.34) using three screws (Del Tite, M3x6mm).

## NOTE Make sure that the Gears attached on the Bracket are surely installed.

3. Secure the Wire Harness (PL 14.6.16) to the clamp on the Bracket.
4. Install the Tray 3 Feeder (PL 14.5.1) or Tray 4 Feeder (PL 14.4.15) .

## RRP 14.56 Left Cover Assembly

## Removal

1. Remove the Left Lower Cover (PL 14.1.4).
2. Remove the screws (one each) securing the left and right Supports (PL 14.7.14) to the machine .
3. Remove the one screw securing the Bracket (PL 14.7.17) to the machine to remove the Bracket.
4. Move the Left Cover Assembly in the direction of the arrow to remove the shaft on the rear of the Left Cover Assembly from the hole on the frame.
5. Remove the Left Cover Assembly.


Figure 1 Left Cover

## Replacement

1. Move the Left Cover Assembly in the opposite direction of the arrow to put the shaft on the rear of the Left Cover Assembly into the hole on the frame.
2. Put the shaft of the Bracket (PL 14.7.17) into the hole on the front of the Left Cover Assembly, and install the Bracket to the machine together with the Left Cover Assembly using the one screw.
3. Install the left and right Supports (PL 14.7.14) to the machine using one screw each.
4. Install the Left Lower Cover (PL 14.1.4).

## RRP 14.57 Pinch Roll

## Removal

1. Remove the Left Lower Cover (PL 14.1.4).
2. Remove the Left Cover Assembly (PL 14.7.1) .
3. Remove the screw (Silver, M3x8mm) securing the Chute (PL 14.7.6) to the Left Cover (PL 14.7.5) to remove the Chute .
4. Remove the two screws (Silver, M3x8mm) securing the Bracket (PL 14.7.9) to the Left Cover to remove the Bracket.


Figure 1 Chute
5. Turn over the removed Bracket and remove the three Springs (PL 14.7.10).

NOTE When the Spring is removed, two Bearings (PL 14.7.11) and one Bearing (PL 14.7.12) are detached. Be careful not to lose them.
6. Remove the Pinch Roll.


Figure 2 Pinch Roll

## Replacement

1. Install the Pinch Roll to the Bracket (PL 14.7.9), and install the Bearing (PL 14.7.12) to the center of the shaft of the Pinch Roll, and the Bearings (PL 14.7.11) on the left and right of the shaft in the direction shown in the figure, and secure them with the three Springs (PL 14.7.10).
2. Install the Bracket to the Left Cover (PL 14.7.5) using the wo screws (Silver, M3x8mm).
3. Install the Chute (PL 14.7.6) to the Left Cover using the one screw (Silver, M3x8mm).
4. Install the Left Cover Assembly (PL 14.7.1) .
5. Install the Left Lower Cover (PL 14.1.4) .

## RRP 14.58 Left Cover Interlock Switch

## Removal

1. Open the Left Cover Assembly (PL 14.7.1).
2. Remove the screw (Del Tite, $M 3 x 8 \mathrm{~mm}$ ) securing the Bracket (PL 14.7.16) to the machine to remove the Bracket .
3. Disconnect the connector (FS812) of the Wire Harness (PL 14.8.18) from the Left Cover Interlock Switch.
4. Release the hooks securing the Left Cover Interlock Switch to the Bracket as shown in the figure.
5. Remove the Left Cover Interlock Switch.


Figure 1 Left Cover Interlock Switch

## Replacement

1. Secure the Left Cover Interlock Switch to the Bracket (PL 14.7.16) with the hooks.
2. Connect the connector (FS812) of the Wire Harness (PL 14.8.18) to the Left Cover Interlock Switch.
3. Install the Bracket to the machine using the one screw (Del Tite, M3x8mm).
4. Close the Left Cover Assembly (PL 14.7.1).

## RRP 14.59 Tray 3 Gear Assembly

## Removal

1. Remove the Rear Cover (PL 14.1.5) .
2. Remove the Tray 3 Feeder (PL 14.5.1) .
3. Release the Wire Harness (PL 14.8.18) from the clamp of the Tray 3 Gear Assembly .
4. Remove the two screws securing the Tray 3 Gear Assembly to the machine.
5. Remove the Tray 3 Gear Assembly.


Figure 1 Tray 3 Gear Assembly

## Replacement

1. Install the Tray 3 Gear Assembly to the machine using the two screws.
2. Secure the Wire Harness (PL 14.8.18) to the clamp of the Tray 3 Gear Assembly.
3. Install the Tray 3 Feeder (PL 14.5.1) .
4. Install the Rear Cover (PL 14.1.5) .

## RRP 14.60 Tray 4 Gear Assembly

## Removal

1. Remove the Rear Cover (PL 14.1.5).
2. Remove the Tray Module PWB (PL 14.8.5) .
3. Release the two Wire Harnesses (PL 14.8.18) from the clamp of the Tray 4 Gear Assembly
4. Remove the two screws securing the Tray 4 Gear Assembly to the machine.
5. Remove the Tray 4 Gear Assembly.


Figure 1 Tray 4 Gear Assembly

## Replacement

1. Install the Tray 4 Gear Assembly to the machine using the two screws.
2. Secure the two Wire Harnesses (PL 14.8.18) to the clamp of the Tray 4 Gear Assembly.
3. Install the Tray Module PWB (PL 14.8.5) .
4. Install the Rear Cover (PL 14.1.5) .

## RRP 14.61 Main Motor

## Removal

1. Remove the Rear Cover (PL 14.1.5) .
2. Disconnect the connector (P/J826) of the Wire Harness (PL 14.8.18) from the Main Motor .
3. Remove the two screws (Del Tite, M3x8mm) securing the Main Motor to the machine.
4. Remove the Main Motor.


Figure 1 Main Motor

## Replacement

1. Install the Main Motor to the machine using the two screws (Del Tite, M3x8mm).
2. Connect the connector (P/J826) of the Wire Harness (PL 14.8.18) to the Main Motor.
3. Install the Rear Cover (PL 14.1.5) .

## RRP 14.62 Tray Module PWB

## Removal

1. Remove the Rear Cover (PL 14.1.5) .
2. Disconnect all connectors of the harnesses from the Tray Module PWB .


Figure 1 Tray Module PWB
3. Remove the four screws securing the Tray Module PWB to the machine .
4. Remove the Tray Module PWB.


Figure 2 Removing Tray Module PWB

1. Install the Tray Module PWB to the machine using the four screws.
2. Connect all connectors of the harnesses to the Tray Module PWB.
3. Install the Rear Cover (PL 14.1.5) .

## RRP 14.63 Takeaway Clutch

## Removal

1. Remove the Rear Cover (PL 14.1.5) .
2. Disconnect the connector (P/J822) of the Wire Harness connected from the machine to the Bracket (PL 14.8.8) .
3. Remove the two screws (Del Tite, M3x8mm) securing the Bracket to the machine to remove the Bracket.

NOTE The Bearing (PL 14.8.9) and the Washer (PL 14.8.17) are detached. Be careful not to lose them.
4. Remove the E-ring securing the 38T Gear (PL 14.8.10) to the Bracket to remove the 38T Gear.
5. Disconnect the connector of the Takeaway Clutch from the Bracket by releasing the hook.

## NOTE The Shaft (PL 14.8.11) and the Bearing are detached. Be careful not to lose them.

6. Remove the Takeaway Clutch.


Figure 1 Takeaway Clutch

## Replacement

1. Secure the connector of the Takeaway Clutch to the Bracket (PL 14.8.8) with the hook.
2. Install the Takeaway Clutch to the Bracket together with the 38T Gear (PL 14.8.10), Bearing (PL 14.8.9) and Shaft (PL 14.8.11) using the one E-ring.

NOTE Fit the 38T Gear to the D-shaped of the Shaft. Also, Install the Bracket with its boss fit to the notch on the Takeaway Clutch.
3. Install the Bracket to the machine together with the Bearing and the Washer (PL 14.8.17) using the two screws (Del Tite, M3x8mm).
4. Connect the connector (P/J822) of the Wire Harness to Bracket.
5. Install the Rear Cover (PL 14.1.5) .

NOTE After the installation, be sure that the harness connected to the Takeaway Clutch does not contact the gears.

## Chapter 7 Troubleshooting

NOTE This manual is based on the assumption that the printer controller is working properly. When the printer controller controls operation directly or has unique specifications, the operation may be different from description in this manual.

NOTE Troubleshooting in this manual assumes use of Diagnostic Tools (maintenance tools). However, the troubleshooting allows for the case where the Diagnostic tools are not used. You can correct troubles according to these troubleshooting procedures.

## Progressing with the Troubleshooting

After making sure of actual condition of a trouble, proceed with the troubleshooting process efficiently making use of the Fault Isolation Procedure (FIP), Operation of Diagnostic (Chapter 2), Wiring Diagrams (Chapter 7), and Principles of Operation (Chapter 6).

## Flow of Troubleshooting

Flow of the troubleshooting is as follows:


## Preparatory Requirements

Be sure to check the following items before starting the troubleshooting procedures:

1. Voltage of the power supply is within the specifications (measure the voltage at the electric outlet).
2. Power cord is free from breakage, short-circuit, disconnected wire, or incorrect connection in the power cord.
3. The laser printer is properly grounded.
4. The laser printer is not installed at a place subjected to too high temperature, too high humidity, too low temperature, too low humidity or rapid change of temperature.
5. The laser printer is not installed close to water service, humidifier, heat generating unit, or fire, in very dusty place, or a place exposed to air flow from the air conditioning system.
6. The laser printer is not installed in a place where volatile gas or inflammable gas is generated.
7. The laser printer is not installed under direct sunbeams.
8. The laser printer is installed in a well-ventilated place.
9. The laser printer is installed on a stout and stable plane.
10. Paper used meets specifications (standard paper is recommendable).
11. The laser printer is handled properly.
12. Parts which should be periodically replaced are replaced each time when specified number of sheets have been printed.

## Cautions for Service Operations

1. Be sure to remove the power cord except when it is specifically required.


If the printer is kept ON, never touch the conductive parts while it is not specifically required. The power switch, inlet and outlet are live even while the power supply is cut off. Never touch the live parts.
2. When checking some parts with covers removed and with the interlock and safety and power switches ON, remove the connector (P/J140, P/J160 and P/J170) on the ROS ASSY12 except when it is specifically required.

When checking some parts with covers removed and with the interlock and safety
WARNING and power switches ON, laser beams may be irradiated from the ROS ASSY-12. Since it is dangerous, be sure to remove the connector (P/J140, P/J160 and P/J170) while it is not required.
3. When checking the COVER ASSY-LH removed and power ON, be sure to remove the connector ( $\mathrm{P} / \mathrm{J} 500$ ) on the PSHV-Y2 while it is not required.

When checking the COVER ASSY-LH removed and power ON, high voltage may be applied by the PSHV-Y2. Be sure to remove the connector ( $\mathrm{P} / \mathrm{J} 500$ ) on the PSHV-Y2. When connecting the connector (P/J500) on the PSHV-Y2 according to the instructions of the FIP, never touch the HVPS and parts of high voltage.
4. When using Diagnostic tools or other tools of high voltage, be sure to keep them covered except when otherwise specified.

When using Diag.Tool or other tools of high voltage, never touch parts of high

## WARNING

 voltage. When using Diagnostic Tool or other tools of high voltage, be sure to follow the procedure of this manual.5. When operating the driving units using the Diagnostic or other tools, be sure to keep them covered unless otherwise specified.

When operating the driving units using the Diagnostic or other tools, never touch the driving units. When operating the driving units using Diagnostic or other tools, be sure to follow the procedures in this manual.
6. When touching hot parts, be careful not to get burnt.
7. Workers should wear a wrist band or the like to remove static electricity from their body, grounding their body while working.

## Cautions for FIP Use

1. It is assumed in the FIP that the printer controller (PWBA ESS) is normally functioning. If any trouble cannot be corrected by troubleshooting, replace the printer controller with a normal one and check for proper operation again.
If the trouble is not still corrected, replace the major parts and then related parts in succession and confirm according to the procedure of the "Check".
2. When troubleshooting according to the FIP, normal operation of PSHV-Y2, PWBA MCU F, FUSER ASSY, and HSG ASSY-BTR may be necessary for isolation of failed parts.
3. In the initial check according to the FIP, check only items which can be simply checked.
4. In the initial check according to the FIP, check the constitutive parts of the major check parts and related parts, as well as major check parts.
5. When working with the printer, be sure to remove the power cord except when required specifically. Never touch live parts if not required, while the power cord is connected.
6. Connector condition is denoted as follows:
[P/J12] $\rightarrow$ Connector (P/J12) is connected.
[P12] $\rightarrow$ Plug side with the connector (P/J12) removed (except when attached directly to the board).
[J12] $\rightarrow$ Jack side with the connector (P/J12) removed (except when attached directly to the board).
7. [P/J1-2PIN <=> P/J3-4PIN] in the FIP means measurement with the plus side of the measuring instrument connected to [2PIN] of [P/J1] and the minus side to [4PIN] of [P/J3].
8. $[P / J 1<=>P / J 2]$ in the FIP means measurement for all terminals corresponding between $[P /$ $\mathrm{J} 1]$ and $[\mathrm{P} / \mathrm{J} 2]$ referring to "Wiring Diagrams".
9. In [P/J1-2PIN <=> P/J3-4PIN] in the FIP where voltage is measured, [P/J3-4PIN] on the rear minus side is always at the AG (analog ground), SG (signal ground), or RTN (return).
Therefore, after checking of proper continuity between AGs, SGs, or RTNs respectively, the rear minus side can be connected to the PIN of AG, SG or RTN instead of [P/J3-4PIN]. However, care should be taken not to mistake since [AG], [SG], and [RTN] are not on the same level.
10. Measure the voltage of small connectors with the special tool. Handle the tool with care, as the leading edge of the tool is pointed.
11. When measuring the voltage, set the EP CARTRIDGE, HSG ASSY-BRT and paper tray, close the COVER ASSY TOP PR, and FUSER ASSY and power ON if not required specifically.
12. Numerical values in the FIP are only for standard. If numerical values are approximate, they should be considered permissible.
13. Parts which are always removed to check as indicated in the FIP and procedures for that purpose are not specifically referred to here. They should be handled carefully.
14. "Replacement" in the FIP indicates replacement of parts which are considered to be the source of trouble to be checked after replacing those parts, assemblies containing them (HIGH ASSY).
15. The FIP describes the first tray on the lower part of the device as "Tray 1 ," and the second tray as "Tray 2".
16. In the FIP, existence and non-existence of Diagnostic tools (maintenance tools) are distinguished in some cases. Correct troubles according to the instructions in the FIP.
17. In the FIP, procedures are differentiated depending on specifications. Correct troubles according to the instructions in the FIP.
18. For optional parts, some troubleshooting procedure may follow the manual for those options, of which you should take note. Keep those manuals for the optional parts when required.

## FIP

The FIP is the first step for trouble diagnosis. The FIP isolates the presence of various troubles including error codes, and guides the troubleshooting procedure.

## Flow of FIP



## Error/Status Code List

NOTE For information about the following FIP items not described in "Status Code" column in the following table, refer to the manual of each Option unit.

| Status Code | Error Contents | Error Description | FIP to be <br> referred |
| :---: | :--- | :--- | :---: |
| C1-2 | Prefeed SENSOR\#1 on JAM <br> (Tray 1 paper feed) | The Prefeed Sensor1 is not turned ON within the <br> specified time after the Tray 1 Feed/Lift Motor is <br> ON. | FIP 1.1 |


| Status Code | Error Contents | Error Description | FIP to be referred |
| :---: | :---: | :---: | :---: |
| C1-3 | Registration Sensor on JAM (Tray 1 paper feed) | The Registration Sensor is not turned ON within the specified time after the Prefeed Sensor1 is ON. | FIP 1.2 |
| C2-1 | Prefeed SENSOR\#2 on JAM (Tray 2 paper feed) | The Prefeed Sensor2 is not turned ON within the specified time after the Tray 2 Feed/Lift Motor is ON. | FIP 1.3 |
| C2-2 | Tray 2 Feed Out Sensor on JAM (Tray 2 paper feed) | The Tray 2 Feed Out Sensor2 is not turned ON within the specified time after the Prefeed Sensor2 is ON. | FIP 1.4 |
| C2-3 | Registration Sensor on JAM (Tray 2 paper feed) | The Registration Sensor is not turned ON within the specified time after the Tray 2 Feed Out Sensor is ON. | FIP 1.5 |
| C3-0 | Prefeed SENSOR\#3 on JAM (Tray 3 paper feed) | The Prefeed Sensor3 is not turned ON within the specified time after the Tray 3 Feed/Lift Motor is ON. | $\begin{aligned} & \text { FIP } 2.1 \\ & \text { FIP } 7.1 \end{aligned}$ |
| C3-1 | Tray 3 Feed Out Sensor on JAM (Tray 3 paper feed) | The Tray 3 Feed Out Sensor is not turned ON within the specified time after the Prefeed Sensor3 is ON. | $\begin{aligned} & \text { FIP } 2.2 \\ & \text { FIP } 7.2 \end{aligned}$ |
| C3-2 | Tray 2 Feed Out Sensor on JAM (Tray 3 paper feed) | The Tray 2 Feed Out Sensor is not turned ON within the specified time after the Tray 3 Feed Out Sensor is ON. | $\begin{aligned} & \text { FIP } 2.3 \\ & \text { FIP } 7.3 \end{aligned}$ |
| C3-3 | Registration Sensor on JAM (Tray 3 paper feed) | The Registration Sensor is not turned ON within the specified time after the Tray 3 Feed Out Sensor is ON. | $\begin{aligned} & \text { FIP } 2.4 \\ & \text { FIP } 7.4 \end{aligned}$ |
| C4-0 | Tray 4 Feed Out Sensor on JAM (Tray 4 paper feed) | The Tray 4 Feed Out Sensor is not turned ON within the specified time after the Prefeed Sensor4 is ON. | $\begin{aligned} & \text { FIP } 2.5 \\ & \text { FIP } 7.5 \end{aligned}$ |
| C4-1 | Tray 3 Feed Out Sensor on JAM (Tray 4 paper feed) | The Tray 3 Feed Out Sensor is not turned ON within the specified time after the Tray 4 Feed Out Sensor is ON. | $\begin{aligned} & \text { FIP } 2.6 \\ & \text { FIP } 7.6 \end{aligned}$ |
| C4-2 | Tray 2 Feed Out Sensor on JAM (Tray 3 paper feed) | The Tray 2 Feed Out Sensor is not turned ON within the specified time after the Tray 3 Feed Out Sensor is ON. | $\begin{aligned} & \text { FIP } 2.7 \\ & \text { FIP } 7.7 \end{aligned}$ |
| C4-3 | Registration Sensor on JAM (Tray 4 paper feed) | The Registration Sensor is not turned ON within the specified time after the Tray 4 Feed Out Sensor is ON. | $\begin{aligned} & \text { FIP } 2.8 \\ & \text { FIP } 7.8 \end{aligned}$ |
| C4-4 | Prefeed SENSOR\#4 on JAM (Tray 4 paper feed) | The Prefeed Sensor4 is not turned ON within the specified time after the Tray 4 Feed/Lift Motor is ON. | $\begin{aligned} & \text { FIP } 2.9 \\ & \text { FIP } 7.9 \end{aligned}$ |
| C5-1 | HCF F/O SENSOR On Jam | The HCF Feed Out Sensor is not turned ON within the specified time after the HCF Feed Start signal is ON. | FIP 6.1 |
| C5-2 | HCF F/O\#2 SENSOR On Jam | The F/O\#2 Sensor on the IOT is not turned ON within the specified time after the HCF Feed Start signal is ON. | FIP 6.2 |
| C5-3 | HCF Registration SENSOR On Jam | The Registration Sensor on the IOT is not turned ON within the specified time after the F/O\#2 Sensor on the IOT is ON. | FIP 6.3 |
| C6-1 | Registration Sensor on JAM (Duplex paper feed) | Registration Sensor is not turned ON within the specified time after the Duplex Motor is ON. | FIP 3.1 |
| C6-2 | Registration Sensor on JAM (Duplex paper feed) | Registration Sensor is not turned ON within the specified time after the Duplex Sensor is ON. | FIP 3.2 |


| Status Code | Error Contents | Error Description | FIP to be referred |
| :---: | :---: | :---: | :---: |
| C8-2 | Tray 2 Feed Out Sensor Static JAM | Paper remains on the Tray 2 Feed Out Sensor. | FIP 1.6 |
| C8-3 | Tray 3 Feed Out Sensor Static JAM | Paper remains on the Tray 3 Feed Out Sensor. | $\begin{aligned} & \text { FIP } 2.10 \\ & \text { FIP } 7.10 \end{aligned}$ |
| C8-4 | Tray 4 Feed Out Sensor Static JAM | Paper remains on the Tray 4 Feed Out Sensor. | $\begin{aligned} & \hline \text { FIP } 2.11 \\ & \text { FIP } 7.11 \end{aligned}$ |
| C8-5 | HCF F/O SENSOR Static Jam | Paper remains on the HCF F/O Sensor. | FIP 6.4 |
| C8-6 | Duplex Sensor Static JAM | Paper remains on the Duplex Sensor. | FIP 3.3 |
| C9-3 | Registration Sensor on JAM (MPF paper feed) | The Registration Sensor is not turned ON within the specified time after the MPF Feed Solenoid is ON. | FIP 1.7 |
| E1-1 | Registration Sensor off JAM (too long) | The Registration Sensor is not turned OFF within the specified time after the Registration Clutch is ON. | FIP 1.8 |
| E1-1 | Registration Sensor off JAM (too Short) | The Registration Sensor is turned OFF earlier than the specified time after the Registration Clutch is ON. | FIP 1.9 |
| E1-2 | Exit Sensor1 on JAM | The Exit Sensor1 is not turned ON within the specified time after the Registration Clutch is ON. | FIP 1.10 |
| E1-6 | Registration Sensor Static JAM | Paper remains on the Registration Sensor. | FIP 1.11 |
| E3-1 | Exit Sensor1 off JAM | The Exit Sensor1 is not turned OFF within the specified time after the Exit Sensor1 is ON. | FIP 1.12 |
| E3-2 | Exit Sensor1 off (too Short) JAM | The Exit Sensor1 is turned OFF earlier than the specified time after the Exit Sensor1 is ON. | FIP 1.13 |
| E3-6 | Exit Sensor1 Static JAM | Paper remains on the Exit Sensor1. | FIP 1.14 |
| E4-1 | Exit Sensor2 on JAM | The Exit Sensor2 is not turned ON within the specified time after the Exit Sensor1 is ON. | FIP 1.15 |
| E4-3 | Exit Sensor2 off JAM | The Exit Sensor2 is not turned OFF within the specified time after the Exit Sensor2 is ON. | FIP 1.16 |
| E4-5 | Exit Sensor2 ON, in FDT1/ Fin simp job | The Exit Sensor 2 was turned ON when the paper is delivered to the Exit 1 or Finisher. | FIP 4.1 |
| E4-6 | Exit Sensor2 Static JAM | Paper remains on the Exit Sensor2. | FIP 4.2 |
| E8-2 | Duplex Wait SENSOR ON JAM | The Duplex Wait SENSOR is not turned ON within the specified time after the Exit 2 MOTOR is ON . | FIP 3.4 |
| F4-12 | Finisher H-Transport Ent. SENSOR ON JAM | Finisher H-Transport Entrance Sensor is not turned ON within the specified time after the Exit Sensor in the IOT is ON. | FIP 5.1 |
| F4-22 | Finisher H-Transport Exit SENSOR ON JAM A | Finisher H-Transport Exit Sensor is not turned ON within the specified time after the Finisher HTransport Entrance Sensor is ON. At this time, the Exit Sensor 1 in the IOT is On state. | FIP 5.2 |
| F4-23 | Finisher H-Transport Exit SENSOR ON JAM B | Finisher H-Transport Exit Sensor is not turned ON within the specified time after the Finisher HTransport Entrance Sensor is ON. <br> At this time, the Finisher H-Transport Entrance Sensor is On state. | FIP 5.2 |


| Status Code | Error Contents | Error Description | FIP to be referred |
| :---: | :---: | :---: | :---: |
| F4-24 | Finisher H-Transport Exit SENSOR ON JAM C | Finisher H-Transport Exit Sensor is not turned ON within the specified time after the Finisher HTransport Entrance Sensor is ON. | FIP 5.2 |
| F4-32 | Finisher Transport Ent. SENSOR ON JAM | Finisher Transport Entrance Sensor is not turned ON within the specified time after the Finisher HTransport Exit Sensor is ON. | FIP 5.3 |
| F4-42 | Finisher Buffer Path SENSOR ON JAM A | Finisher Buffer Path Sensor is not turned ON within the specified time after the Finisher Transport Entrance Sensor is ON. | FIP 5.4 |
| F4-43 | Finisher Buffer Path SENSOR ON JAM B | Finisher Buffer Path Sensor is not turned ON within the specified time after the Finisher Transport Entrance Sensor is ON. <br> At this time, the Finisher Gate SENSOR is ON state. | FIP 5.4 |
| F4-52 | Finisher Compile Exit SENSOR ON JAM A | Finisher Buffer Path Sensor is not turned ON within the specified time after the Finisher Transport Entrance Sensor is ON. At this time, the Finisher H-Transport Exit Sensor is ON state. | FIP 5.5 |
| F4-53 | Finisher Compile Exit SENSOR ON JAM B | Finisher Buffer Path Sensor is not turned ON within the specified time after the Finisher Transport Entrance Sensor is ON. <br> At this time, the Finisher Transport Entrance Sensor is ON state. | FIP 5.5 |
| F4-54 | Finisher Compile Exit SENSOR ON JAM C | Finisher Compile Exit Sensor is not turned ON within the specified time after the Finisher Buffer Path Sensor is ON. | FIP 5.5 |
| F4-51 | Finisher Compile Exit SENSOR OFF JAM A | Finisher Compile Exit Sensor is not turned OFF within the specified time after the Finisher Compile Exit Sensor is ON. <br> At this time, the Finisher H-X'port Exit Sensor is ON state. | FIP 5.6 |
| F4-55 | Finisher Compile Exit SENSOR OFF JAM B | Finisher Compile Exit Sensor is not turned OFF within the specified time after the Finisher Compile Exit Sensor is ON. <br> At this time, the Finisher X'port Entrance Sensor is ON state. | FIP 5.6 |
| F4-61 | Finisher Set Eject JAM | Finisher Compile No Paper Sensor is not turned ON within the specified time after the Eject Motor is ON . | FIP 5.7 |
| F4-71 | Finisher Top Tray Exit SENSOR ON JAM A | Top Tray Exit Sensor is not turned ON within the specified time after the Finisher X'port Entrance Sensor is ON. <br> At this time, the Finisher H-X'port Exit Sensor is ON state. | FIP 5.8 |
| F4-73 | Finisher Top Tray Exit SENSOR ON JAM B | Top Tray Exit Sensor is not turned ON within the specified time after the Finisher Transport Entrance Sensor is ON. <br> At this time, the Finisher H-Transport Exit Sensor is ON state. | FIP 5.8 |


| Status Code | Error Contents | Error Description | FIP to be referred |
| :---: | :---: | :---: | :---: |
| F4-64 | Finisher Top Tray Exit SENSOR ON JAM C | Top Tray Exit Sensor is not turned ON within the specified time after the Finisher Transport Entrance Sensor is ON. <br> At this time, the Finisher H-Transport Exit Sensor is ON state. | FIP 5.8 |
| F4-72 | Finisher Top Tray Exit SENSOR OFF JAM A | Top Tray Exit Sensor is not turned OFF within the specified time after the Top Tray Exit Sensor is ON. <br> At this time, the Finisher H-X'port Exit Sensor is ON state. | FIP 5.9 |
| F4-75 | Finisher Top Tray Exit SENSOR OFF JAM B | Top Tray Exit Sensor is not turned OFF within the specified time after the Top Tray Exit Sensor is ON. <br> At this time, the Finisher H-X'port Exit Sensor is OFF state. | FIP 5.9 |
| F4-82 | Finisher Gate Sensor ON JAM | Finisher Gate Sensor is not turned ON within the specified time after the Finisher H-X'port Exit Sensor is ON. | FIP 5.10 |
| F4-16 | Finisher H-Transport Ent. SENSOR Static JAM A | Paper remains on the Finisher H-X'port Entrance Sensor. | FIP 5.11 |
| F4-17 | Finisher H-Transport Ent. SENSOR Static JAM B | Paper remains on the Finisher H-X'port Entrance Sensor. | FIP 5.11 |
| F4-26 | Finisher H-Transport Exit SENSOR Static JAM A | Paper remains on the Finisher H-X'port Exit Sensor. | FIP 5.12 |
| F4-36 | Finisher Transport Ent. SENSOR Static JAM A | Paper remains on the Finisher X'port Entrance Sensor. <br> At this time, the Finisher H-X'port Exit Sensor is ON state. | FIP 5.13 |
| F4-46 | Finisher Buffer Path SENSOR Static JAM A | Paper remains on the Finisher Buffer Path Sensor. <br> At this time, both Gate Sensor and X'port Exit Sensor are ON state. | FIP 5.14 |
| F4-47 | Finisher Buffer Path SENSOR Static JAM B | Paper remains on the Finisher Buffer Path Sensor. <br> At this time, the Gate Sensor is ON state but the X'port Entrance Sensor is OFF state. | FIP 5.14 |
| F4-48 | Finisher Buffer Path SENSOR Static JAM C | Paper remains on the Finisher Buffer Path Sensor. <br> At this time, the Gate Sensor is OFF state. | FIP 5.14 |
| F4-56 | Finisher Compile Exit SENSOR Static JAM | Paper remains on the Finisher Compile Exit Sensor. | FIP 5.15 |
| F4-66 | Finisher Compile No Paper SENSOR Static JAM | Paper remains on the Finisher Compile No Paper Sensor. | FIP 5.16 |
| F4-76 | Finisher Top Tray Exit SENSOR Static JAM A | Paper remains on the Finisher Top Tray Exit Sensor. <br> At this time, the H -X'port Exit Sensor is ON state. | FIP 5.17 |
| F4-77 | Finisher Top Tray Exit SENSOR Static JAM B | Paper remains on the Finisher Top Tray Exit Sensor. <br> At this time, the H-X'port Exit Sensor is OFF state but the Finisher X'port Entrance Sensor is ON state. | FIP 5.17 |


| Status Code | Error Contents | Error Description | FIP to be referred |
| :---: | :---: | :---: | :---: |
| F4-78 | Finisher Top Tray Exit SENSOR Static JAM C | Paper remains on the Finisher Top Tray Exit Sensor. <br> At this time, both H -X'port Exit Sensor and Finisher X'port Entrance Sensor are OFF state. | FIP 5.17 |
| F4-83 | Finisher Gate SENSOR Static JAM (to Top Tray) A | Paper remains on the Gate Sensor when the Finisher is in the Top Tray exit mode. At this time, the H-X'port Exit Sensor is ON state. | FIP 5.18 |
| F4-84 | Finisher Gate SENSOR Static JAM (to Top Tray) B | Paper remains on the Gate Sensor when the Finisher is in the Top Tray exit mode. <br> At this time, the X'port Entrance Sensor is ON state but the H-X'port Exit Sensor is OFF state. | FIP 5.18 |
| F4-85 | Finisher Gate SENSOR Static JAM (to Top Tray) C | Paper remains on the Gate Sensor when the Finisher is in the Top Tray exit mode. <br> At this time, both X'port Entrance Sensor and HX'port Exit Sensor are OFF state. | FIP 5.18 |
| F4-86 | Finisher Gate SENSOR Static JAM (to Stacker Tray) A | Paper remains on the Gate Sensor when the Finisher is in the Stacker Tray exit mode. <br> At this time, the H-X'port Exit Sensor is ON state. | FIP 5.19 |
| F4-87 | Finisher Gate SENSOR <br> Static JAM (to Stacker Tray) B | Paper remains on the Gate Sensor when the Finisher is in the Stacker Tray exit mode. At this time, the X'port Entrance Sensor is ON state but the H-X'port Exit Sensor is OFF state. | FIP 5.19 |
| F4-88 | Finisher Gate SENSOR <br> Static JAM (to Stacker Tray) <br> C | Paper remains on the Gate Sensor when the Finisher is in the Stacker Tray exit mode. At this time, both X'port Entrance Sensor and HX'port Exit Sensor are OFF state. | FIP 5.19 |
| H1-1 | Tray1 Lift up /No tray fail | - The TRAY1 LEVEL SENSOR is not turned ON within the specified time after the TRAY1 LEVEL MOTOR is ON. <br> - The TRAY1 SIZE SENSOR detected no tray. | FIP 1.17 |
| H1-2 | Tray2 Lift up /No tray fail | - The TRAY2 LEVEL SENSOR is not turned ON within the specified time after the TRAY2 FEED MOTOR is ON. <br> - The TRAY2 SIZE SENSOR detected no tray. | FIP 1.18 |
| H1-3 | Tray3 Lift up /No tray fail | - The 2TM-TRAY3 LEVEL SENSOR is not turned ON within the specified time after the 2TMTRAY3 FEED MOTOR is ON. <br> - The 2TM-TRAY3 SIZE SENSOR detected no tray. | $\begin{aligned} & \text { FIP } 2.12 \\ & \text { FIP } 7.12 \end{aligned}$ |
| H1-4 | Tray4 Lift up /No tray fail | - The 2TM-TRAY4 LEVEL SENSOR is not turned ON within the specified time after the 2TMTRAY4 FEED MOTOR is ON. <br> - The 2TM-TRAY4 SIZE SENSOR detected no tray. | $\begin{aligned} & \text { FIP } 2.13 \\ & \text { FIP } 7.13 \end{aligned}$ |
| H1-5 | HCF Lift Up Fail | The HCF Level Sensor is not turned ON within the specified time after the HCF Feed Motor is ON. | FIP 6.5 |
| H2-7 | Duplex Module Communication fail | A communication error occurred between the PWBA MCU F and the Duplex Module. | FIP 3.5 |
| H2-8 | DUP MODULE Type fail | A DUP MODULE of a different specification is installed. | FIP 3.6 |


| Status Code | Error Contents | Error Description | FIP to be referred |
| :---: | :---: | :---: | :---: |
| H3-2 | OCT2 fail | The OCT2 HOME POSITION SENSOR is not turned ON within the specified time after the OCT2 Motor is ON. | FIP 4.3 |
| H3-7 | Exit Module Communication fail | A communication error occurred between the PWBA MCU F and the PWBA EXIT. | FIP 1.19 |
| H4-1 | Tray 1 cassette Size fail | Although the Tray 1 is set in the printer, the paper size is not detected correctly. | FIP 1.20 |
| H4-2 | Tray 2 cassette Size fail | Although the Tray 2 is set in the printer, the paper size is not detected correctly. | FIP 1.21 |
| H4-3 | Tray 3 cassette Size fail | Although the Tray 3 is set in the 2TM, the paper size is not detected correctly. | $\begin{aligned} & \text { FIP } 2.14 \\ & \text { FIP } 7.14 \end{aligned}$ |
| H4-4 | Tray 4 cassette Size fail | Although the Tray 4 is set in the 2TM, the paper size is not detected correctly. | $\begin{aligned} & \hline \text { FIP } 2.15 \\ & \text { FIP } 7.15 \end{aligned}$ |
| H5-11 | Stacker Tray Fail | The Stacker Height Sensor is not turned ON within the specified period after the Stacker Tray starts rising. | FIP 5.20 |
| H5-12 | Stacker Tray Upper Limit Fail | The Stacker Tray abnormally rises beyond the specified upper limit position (Stacker Height). | FIP 5.21 |
| H5-13 | Stacker Tray Lower Limit Fail | The Stacker Tray abnormally lowers beyond the specified lower limit position (Full Stack). | FIP 5.22 |
| H5-21 | Front Tamper Home SENSOR ON Fail | The Front Tamper Home Sensor is not turned ON within 800 ms after the Front Tamper starts moving to the Front Tamper Home position. | FIP 5.23 |
| H5-22 | Rear Tamper Home SENSOR ON Fail | The Rear Tamper Home Sensor is not turned ON within 800 ms after the Rear Tamper starts moving to the Rear Tamper Home position. | FIP 5.24 |
| H5-23 | Front Tamper Home SENSOR OFF Fail | The Front Tamper Home Sensor is not turned OFF within the specified time after the Front Tamper starts leaving from the Front Tamper Home position. <br> Or the Front Tamper Home Sensor is turned ON again after the Front Tamper Home Sensor is turned OFF and the Front Tamper stopped its moving. | FIP 5.25 |
| H5-24 | Rear Tamper Home SENSOR OFF Fail | The Rear Tamper Home Sensor is not turned OFF within the specified time after the Rear Tamper starts leaving from the Rear Tamper Home position. <br> Or the Rear Tamper Home Sensor is turned ON again after the Rear Tamper Home Sensor is turned OFF and the Rear Tamper stopped its moving. | FIP 5.26 |
| H5-31 | Puncher SENSOR ON Fail | The Puncher Home Sensor is not turned ON even when the specified time passed after the Puncher Motor is ON. | FIP 5.27 |
| H5-32 | Puncher SENSOR OFF Fail | The Puncher Home Sensor is not turned OFF even when the specified time passed after the Puncher Motor is ON. | FIP 5.28 |


| Status Code | Error Contents | Error Description | FIP to be referred |
| :---: | :---: | :---: | :---: |
| H5-33 | Puncher Move Home SENSOR ON Fail | The Puncher Move Home Sensor is not turned ON even when the specified time passed after the Puncher Move Motor is ON. Or the Puncher Move Home Sensor is turned OFF again after the Puncher Move Home Sensor is turned ON and the Puncher Move Motor stopped its rotation. | FIP 5.29 |
| H5-34 | Puncher Move Home SENSOR OFF Fail | The Puncher Move Home Sensor is not turned OFF even when the specified time passed after the Puncher Move Motor is ON. <br> Or the Puncher Move Home Sensor is turned ON again after the Puncher Move Home Sensor is turned OFF and the Puncher Move Motor stopped its rotation. | FIP 5.30 |
| H5-81 | Eject Clamp Home SENSOR ON Fail | The Eject Clamp Home Sensor is not turned ON within 500 ms after the Eject Clamp Up starts. | FIP 5.31 |
| H5-82 | Eject Clamp Home SENSOR OFF Fail | The Eject Clamp Home Sensor is not turned OFF within 200 ms after the Eject Clamp Down starts. | FIP 5.32 |
| H5-83 | Set Clamp Home SENSOR ON Fail | The Set Clamp Home Sensor is not turned ON within 200 ms after the Set Clamp starts operating. | FIP 5.33 |
| H5-84 | Set Clamp Home SENSOR OFF Fail | The Set Clamp Home Sensor is not turned OFF within the specified time after the Set Clamp ends operating. | FIP 5.34 |
| H5-86 | Side Registration Sensor OFF Fail | The Side Registration Sensor is not turned OFF within 500 ms after the Puncher Move Motor is ON. <br> Or the Side Registration Sensor is turned ON again after the Side Registration Sensor is turned OFF and the Puncher stopped its moving. Or the <br> Or the Side Registration Sensor1 or the Side Registration Sensor2 to be targeted is not turned OFF when the Puncher Move Motor starts operating. | FIP 5.35 |
| H5-91 | Stapler Fail | The OFF-ON status of the Stapler Home Sensor is not detected within the specified time after the Stapler Move Motor is ON (Forward operation). Or the Stapler Home Sensor is not turned ON within the specified timer after the Stapler Move Motor is ON (Reverse operation). | FIP 5.36 |
| H5-95 | Stapler Move Position SENSOR ON Fail | The Staple Move Position Sensor is not turned ON within two seconds after the Stapler starts moving toward the Staple position and also the Staple Move Position Sensor is OFF. Or the Staple Move Position Sensor is not turned ON after the Stapler was moved to the Staple position. <br> Or the Stapler Move Position Sensor is turned OFF again after the Stapler Move Position Sensor is turned ON and the Stapler stopped its moving. | FIP 5.37 |


| Status Code | Error Contents | Error Description | FIP to be referred |
| :---: | :---: | :---: | :---: |
| H5-96 | Stapler Move Position SENSOR OFF Fail | The Staple Move Position Sensor is not turned OFF within 500 ms after Stapler starts moving to the Staple Position and Staple Move Position Sensor is OFF. <br> Or the Staple Move Position Sensor is not turned OFF after the Stapler was moved to the Staple position. <br> Or the Stapler Move Position Sensor is turned ON again after the Stapler Move Position Sensor is turned OFF and the Stapler stopped its moving. | FIP 5.38 |
| H5-4 | Finisher NVM R/W error | A read/write error occurred on the NVM of the PWB MAIN-C. | FIP 5.39 |
| H5-7 | MCU-Finisher comm. error | A communication error occurred between the PWBA MCU F and the Finisher. | FIP 5.40 |
| H5-8 | Finisher type error | A different type of Finisher is connected. | FIP 5.41 |
| H6-4 | HCF NVM R/W Error | A read/write error has occurred on the NVM of the HCF PWB. | FIP 6.6 |
| H6-7 | HCF NVM R/W Error | A communication error occurred between the PWBA MCU F and the HCF. | FIP 6.7 |
| H7-3 | Tray Module NVM out-oforder | A data error of the NVM on the TM PWB occurred. | $\begin{aligned} & \text { FIP } 2.16 \\ & \text { FIP } 7.16 \end{aligned}$ |
| H7-4 | Tray Module NVM R/W error | Read/write of the NVM on the TM PWB failed. | $\begin{aligned} & \text { FIP } 2.17 \\ & \text { FIP } 7.17 \end{aligned}$ |
| H7-7 | Tray Module Communication fail | A communication error occurred between the PWBA MCU F and the TM PWB. | $\begin{aligned} & \hline \text { FIP } 2.18 \\ & \text { FIP } 7.18 \end{aligned}$ |
| H7-8 | TM type error | An tray module of a different specification is connected. | $\begin{aligned} & \hline \text { FIP } 2.19 \\ & \text { FIP } 7.19 \end{aligned}$ |
| H8-3 | Tray3 Size sensor broken | Tray3 Size sensor is not detected. | $\begin{aligned} & \text { FIP } 2.20 \\ & \text { FIP } 7.20 \end{aligned}$ |
| H8-4 | Tray4 Size sensor broken | Tray4 Size sensor is not detected. | $\begin{aligned} & \text { FIP } 2.21 \\ & \text { FIP } 7.21 \end{aligned}$ |
| J1-2 | Toner Cartridge Empty fail | All toner in the Toner cartridge is consumed. | FIP 1.22 |
| J3-1 | Drum Cartridge Set fail | The Drum Cartridge is not installed. | FIP 1.23 |
| J4-1 | ATC Sensor fail | The ATC Sensor broke. | FIP 1.24 |
| J6-1 | Drum Cartridge Life Over | The Drum Cartridge needs to be replaced. | FIP 1.25 |
| J7-1 | Drum Cartridge CRUM Communication fail | A communication error occurred between the XERO CRUM Tag in the Drum Cartridge and the CRUM ASIC on the PWBA MCU F. | FIP 1.26 |
| J7-2 | Drum Cartridge CRUM Data Write fail | A write error occurred on the XERO CRUM Tag in the Drum Cartridge. | FIP 1.27 |
| J7-3 | Drum Cartridge CRUM ID fail | A Drum Cartridge of a different specification is attached. | FIP 1.28 |
| J8-1 | Toner Cartridge CRUM Communication fail | A communication error occurred between the Toner CRUM Tag in the Toner Cartridge and the CRUM ASIC on the PWBA MCU F. | FIP 1.29 |
| J8-2 | MCU Toner Cartridge CRUM Data Write fail | A data write error occurred on the XERO CRUM Tag in the Toner Cartridge. | FIP 1.30 |
| J8-3 | Toner Cartridge CRUM ID fail | A Toner Cartridge of a different specification is attached. | FIP 1.31 |


| Status Code | Error Contents | Error Description | FIP to be referred |
| :---: | :---: | :---: | :---: |
| U0-1 | Main Motor stop error | Due to the malfunction in the control system of the PWBA MCU F, the Main Motor does not stop when paper is not transported. | FIP 1.32 |
| U0-2 | Image Ready error | The PWBA MCU F does not receive the imageready signal from the PWBA ESS at the specified timing. | FIP 1.33 |
| U1-1 | Main Motor fail | The Main Motor does not rotate at the specified speed. | FIP 1.34 |
| U1-4 | Drum Motor fail | The Drum Motor does not rotate at the specified speed. | FIP 1.35 |
| U3-3 | Laser Power fail | Light intensity of the LD2 is less than the specified value. | FIP 1.36 |
| U3-5 | ROS Motor fail | - Rotation speed of the ROS motor is less than the specified value even when the specified time is passed after the motor starts rotating. <br> - Light intensity of the LD1 is less than the specified value. | FIP 1.37 |
| U4-1 | Fuser On Time fail | - During the Warm-Up period, the Control Thermistor does not detect the Ready temperature even when the specified time is passed after the Main Lamp is ON. <br> - During the Standby period, the Control Thermistor does not detect the specified temperature even when the specified time is passed after the Main Lamp is ON. <br> - During the Standby period, the Control Thermistor does not detect the specified temperature even when the specified time is passed after the Sub Lamp is ON. <br> - During idling after power-on, the Control Thermistor does not detect the idling stop temperature even after the specified time is passed. <br> - During print, the Control Thermistor does not detect the specified temperature even when the specified time is passed after the Main Lamp is ON. <br> - During print, the Control Thermistor does not detect the specified temperature even when the specified time is passed after the Sub Lamp is ON. | FIP 1.38 |
| U4-2 | Over Heat Temp fail | - The Control Thermistor detects a temperature higher than the specified value. <br> - The Lamp Change Thermistor detects a temperature higher than the specified value. | FIP 1.39 |
| U4-3 | Center STS fail | The Center STS broke. | FIP 1.40 |
| U4-4 | REAR STS fail | The REAR STS broke. | FIP 1.41 |
| U4-5 | P/R STS fail | The P/R STS broke. | FIP 1.42 |
| U4-7 | Cold-Sagging recovery fail | The Center STS/FS1 detects that it does not recover from Cold-Sagging after the specified time is passed. | FIP 1.43 |
| U4-8 | Hot-Sagging recovery fail | The Center STS/FS1 detects that it does not recover from Hot-Sagging after the specified time is passed. | FIP 1.44 |


| Status Code | Error Contents | Error Description | FIP to be referred |
| :---: | :---: | :---: | :---: |
| U4-9 | Fuser Fan fail | The Fuser Fan broke. | FIP 1.45 |
| U5-1 | Dispense Motor fail | The toner concentration in the Drum Cartridge does not increase even when the Dispense Motor is turned ON for more than the specified time. | FIP 1.46 |
| U6-2 | RAM read/write Check fail | Read/write of RAM on the PWBA MCU F failed. | FIP 1.47 |
| U6-3 | NVM data defect | A data error of NVM on the PWBA MCU F occurred. | FIP 1.48 |
| U6-4 | NVM read/write cannot be executed | Read/write of the NVM on the PWBA MCU F failed. | FIP 1.49 |
| U6-5 | CPU Power to access NVM is not enough | An internal process for data write of the NVM on the PWBA MCU F failed. | FIP 1.50 |
| U6-6 | CRUM ASIC fail | The CRUM control circuit broke. | FIP 1.51 |
| U6-7 | The PPM information is defect | An incorrect NVM data is saved on the PPM. | FIP 1.52 |
| H5-9 | CRU Fan defect | A defect in the CRU FAN was detected. | FIP 1.53 |
| H3-1 | OCT1 Defect | The OCT1 HOME POSITION SENSOR is not turned ON within the specified period after the OCT1 Motor is ON. | FIP 1.54 |
| H8-1 | Tray1 Size sensor broken | Tray1 Size sensor is not detected. | FIP 1.55 |
| H8-2 | Tray1 Size sensor broken | Tray2 Size sensor is not detected. | FIP 1.56 |
|  | L/H Cover Assembly open | The L/H Cover Assembly is open. | FIP 1.57 |
|  | IOT Front Cover open | The IOT Front Cover is open. | FIP 1.58 |
|  | L/H-L Cover open | The L/H Lower Cover is open. | FIP 1.59 |
|  | L/H-H Cover Open | The CHUTE LH HIGH is open | FIP 4.4 |
|  | TM Cover open | The 2TM Cover is open. | $\begin{aligned} & \hline \text { FIP } 2.22 \\ & \text { FIP } 7.22 \end{aligned}$ |
|  | DUP Cover open | The Duplex Cover is open. | FIP 3.7 |
|  | Toner Cartridge was PRENEAR empty | Although the toner in the Toner Cartridge have only a little amount left, it can still be used. | FIP 1.60 |
|  | Drum life was near to end | The Drum Cartridge needs to be replaced soon. | FIP 1.61 |
|  | No paper in the select paper tray | Paper is not loaded in the tray. | FIP 1.62 FIP 2.23 FIP 7.23 |
|  | Paper size mismatch in width | The paper width is inappropriate. | $\begin{aligned} & \text { FIP } 1.63 \\ & \text { FIP } 2.24 \\ & \text { FIP } 7.24 \end{aligned}$ |
|  | Tray 1 Paper size mismatch in length | The paper length detected by the Registration Sensor after the paper is fed from the Tray 1 does not match the length detected by the Tray 1 Size Switch. | FIP 1.64 |
|  | Tray 2 Paper size mismatch in length | The paper length detected by the Registration Sensor after the paper is fed from the Tray 2, does not match the length detected by the Tray 2 Size Switch. | FIP 1.65 |
|  | Tray 3 Paper size mismatch in length | The paper length detected by the Registration Sensor after the paper is fed from the Tray 3, does not match the length detected by the Tray 3 Size Switch. | $\begin{aligned} & \text { FIP } 2.25 \\ & \text { FIP } 7.25 \end{aligned}$ |


| Status Code | Error Contents | Error Description | FIP to be referred |
| :---: | :---: | :---: | :---: |
|  | Tray 4 Paper size mismatch in length | The paper length detected by the Registration Sensor after the paper is fed from the Tray 4, does not match the length detected by the Tray 4 Size Switch. | $\begin{aligned} & \text { FIP } 2.26 \\ & \text { FIP } 7.26 \end{aligned}$ |
|  | Face Down Tray1 FULL | Paper in the Face Down Tray1 stacks over. | FIP 1.66 |
|  | Face Down Tray2 FULL | Paper in the Face Down Tray2 stacks over. | FIP 1.67 |
|  | Temperature SENSOR fail | The Sensor HUM \& TE detected an abnormal temperature. | FIP 1.68 |
|  | Humidity SENSOR fail | The Sensor HUM \& TE detected an abnormal humidity. | FIP 1.69 |
|  | Stacker Tray Full (No Mix): Finisher | When the stack of the Finisher Stacker Tray reaches the specified value (same paper size). | FIP 5.42 |
|  | Stacker Tray Full (Mix size): Finisher | When the stack of the Finisher Stacker Tray reaches the specified value (mixed paper size). | FIP 5.43 |
|  | Finisher Top Tray Full | When the stack of the Finisher Top Tray reaches the specified value. | FIP 5.44 |
|  | Staple Pin Empty | Staple Pin reaches near end. Or the cartridge is not installed. | FIP 5.45 |
|  | Staple Pin Not Ready | When the Staple Pin does not reach the Stapler head end position. | FIP 5.46 |
|  | Staple NG: Finisher | The OFF-ON status of the Staple Home Sensor is not detected within the specified time after the Stapler Move Motor is ON (Forward operation). The Staple Home Sensor is not turned ON within the specified time after the Stapler Move Motor is ON (Reverse operation). | FIP 5.47 |
|  | Stacker Lower Safety: Finisher | The Stacker No Paper Sensor is not turned ON within the specified time after the Stacker Motor is ON (lowering). <br> The Stacker No Paper Sensor is not turned OFF within the specified time after the Stacker Motor is ON (lowering). | FIP 5.48 |
|  | Stacker Set Over Count: Finisher | When the stapled paper exceeds the specified value be able to stack on the Stacker Tray. | FIP 5.49 |
|  | Punch waste box overflow: Finisher | The Punch Dust Box is filled. | FIP 5.50 |
|  | No Punch waste Box | Punch Dust Box is open. | FIP 5.51 |
|  | Finisher Front Cover Open | he Finisher Front Cover is open. | FIP 5.52 |
|  | Finisher H-X'port Cover Open | Finisher H-X'port Cover is open. | FIP 5.53 |
|  | Finisher Eject Cover Open | The Finisher Eject Cover is open. | FIP 5.54 |
|  | HCF Top Cover Open | The HCF Top Cover is open. | FIP 6.8 |
|  | HCF Home Position S/W Open | The HCF is not placed in the Home Position. | FIP 6.9 |

## Error Code FIP

## Prefeed SENSOR \#1 on JAM (Tray 1 paper feed)

| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 2.3.20) <br> ROLLER ASSY (RETARD) (PL 2.3.28) <br> ROLLER ASSY (NUDGER) (PL 2.3.32) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 2.3.2) <br> SENSOR (PRE FEED SENSOR) (PL 2.3.15) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup <br> Does the paper size in use match the size set for the TRAY1? | Go to step 3. | Replace the paper, or change the paper size setup. |
| 3 | Checking the Rollers for the TRAY1 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn and/or contaminated with paper dust? <br> Pull out the TRAY1 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 2.21/RRP 2.25/RRP 2.28) |
| 4 | Checking paper position <br> Does the paper touch the SENSOR (PRE FEED SENSOR) in the FEEDER ASSY (FEEDER 1) (PL 2.1.7)? Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY1 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR (PRE FEED SENSOR) for the TRAY1? <br> Execute [Input 08-58 PreFEED SENSOR1] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 9. | Go to step 6. |
| 6 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY1 for connection Are P/J133, P/J601 and P/J409A connected surely? | Go to step 7. | Connect P/J133, P/J601 and P/ J409A surely. |
| 7 | Checking conductivity between the SENSOR (PRE FEED SENSOR) for the TRAY1 and the PWBA MCU F Is there conductivity on each wire between P/J133 <=> P/ J409A? | Go to step 8. | Fix open and short circuit. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 8 | Checking +5 VDC power supply to the SENSOR (PRE FEED SENSOR) for the TRAY1 Is the voltage across J133-1 (+) <=> ground +5 VDC? | Replace the SENSOR (PRE FEED SENSOR) for the TRAY1. (RRP 2.18) | Replace the PWBA MCU F. (RRP 8.4) |
| 9 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the <br> TRAY1 for operation (1) <br> Does the TRAY $1 / 2$ Feed Lift Up Motor for the Tray 1 Operate? <br> Execute [Output 08-12 Tray 1 Feed Motor] in Chapter 2 [diagnostic]. <br> Pull out Tray 1 and check it. | Reconnect the connector on the PWBA MCU F. | Go to step 10. |
| 10 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY1 for connection Are P/J201, P/J601 and P/J409A connected surely? | Go to step 11. | Connect P/J201 P/J601 and P/ J409A surely. |
| 11 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the <br> TRAY1 for operation (2) <br> Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the <br> TRAY1 with that for the TRAY2. <br> Does the replaced motor operate? <br> Execute [Output 08-13 TRAY2 FEED MOTOR] in Chapter <br> 2 [Diagnostic]. | Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY2 as it previously was and replace the motor for the TRAY1 with a new one. (RRP 2.9) | Go to step 12. |
| 12 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY1 for conductivity Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTORs for the TRAY1 and TRAY2 as they previously were. Is there conductivity on each wire between P/J201 <=> P/ J409A? | Go to step 13. | Fix open and short circuit. |
| 13 | Checking +24 VDC power supply to the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY1 <br> Is the voltage across J201-4 (+) <=> ground +24 VDC? | Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY1. (RRP 2.9) | Replace the PWBA MCU F (RRP 8.4) |

## Registration Sensor on JAM (Tray 1 paper feed)

| Step | Check | Yes | No |
| :--- | :--- | :--- | :--- |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 2.3.20) <br> ROLLER ASSY (RETARD) (PL 2.3.28) <br> ROLER ASSY (NUDGER) (PL 2.3.32) <br> SENSOR (PRE FEED SENSOR) (PL 2.3.15) |  |  |
|  | SENSOR ASSY REGI (PL 4.5.7) |  |  |
| PWBA MCU F (PL 8.1.5) |  |  |  |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup <br> Does the size of paper in use match the size set for the TRAY1? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY1 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY1 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 2.21/RRP 2.25/RRP 2.28) |
| 4 | Checking paper position Does the paper touch the SENSOR ASSY REGI or the SENSOR (PRE FEED SENSOR) in the FEEDER ASSY (FEEDER 1) (PL 2.1.7)? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking the SENSOR ASSY REGI for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR ASSY REGI? Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 9. | Go to step 6. |
| 6 | Checking the SENSOR ASSY REGI for connection Are P/J104 and P/J403B connected surely? | Go to step 7. | Connect P/J104 and P/J403B surely. |
| 7 | Checking conductivity between the SENSOR ASSY REGI and the PWBA MCU F <br> Is there conductivity on each wire between P/J104 <=> P/ J409B? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the SENSOR ASSY REGI <br> Is the voltage across J104-1 (+) <=> ground +5 VDC? | Replace the SENSORASSYREGI. (RRP 4.13) | Replace the PWBA MCU F. (RRP 8.4) |
| 9 | Checking the SENSOR (PRE FEED SENSOR) for operation <br> Does the Input Status change from "0x0" to "0x1" each time the paper touches the SENSOR (PRE FEED SENSOR)? <br> Execute [Input 08-58 PreFEED SENSOR1] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Reconnect the connector on the PWBA MCU F. | Go to step 10. |
| 10 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY1 for connection Are P/J133, P/J601 and P/J409A connected surely? | Go to step 11. | Connect P/J133, <br> P/J601 and P/ J409A surely. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 11 | Checking conductivity between the SENSOR (PRE FEED <br> SENSOR) for the TRAY1 and the PWBA MCU F <br> Is there conductivity on each wire between P/J133 <=> P/ <br> J409A? | Go to step 12. | Fix open and <br> short circuit. |
| 12 | Checking +5 VDC power supply to SENSOR (PRE FEED <br> SENSOR) for the TRAY1 <br> Is the voltage across J133-1 (+) <=> ground +5 VDC? | Replace the SEN- <br> SOR (PRE FEED <br> SENSOR) for the <br> TRAY1. (RRP | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Prefeed Sensor \#2 on JAM (Tray 2 paper feed)

| Step | Check | Yes | No |
| :--- | :--- | :--- | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 2.3.20) <br> ROLLER ASSY (RETARD) (PL 2.3.28) <br> ROLLER ASSY (NUDGER) (PL 2.3.32) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 2.3.2) <br> SENSOR (PRE FEED SENSOR) (PL 2.3.15) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition <br> Is the paper in the tray crumpled or damaged? | Replace the <br> paper with new <br> and dry one. | Go to step 2. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 5 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY2 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR (PRE FEED SENSOR) for the TRAY2? <br> Execute [Input 08-59 PreFEED SENSOR2] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH LOW C (PL 4.1.10) and check it. | Go to step 9. | Go to step 6. |
| 6 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY2 for connection Are P/J134, P/J602 and P/J409B connected surely? | Go to step 7. | Connect P/J134 <br> P/J602 and P/ <br> J409B surely. |
| 7 | Checking conductivity between the SENSOR (PRE FEED SENSOR) for the TRAY2 and the PWBA MCU F Is there conductivity on each wire between P/J134 <=> P/ J409B? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the SENSOR (PRE FEED SENSOR) for the TRAY2 Is the voltage across J134-1 (+) <=> ground +5 VDC? | Replace the SENSOR (PRE FEED SENSOR) for the TRAY2. (RRP 2.18) | Replace the PWBA MCU F. (RRP 8.4) |
| 9 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY2 for operation (1) <br> Does the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY2 operate properly? <br> Execute [Output 08-13 TRAY2 FEED MOTOR] in Chapter 2 [Diagnostic]. <br> Pull out the TRAY1 and check it. | Reconnect the connector on the PWBA MCU F. | Go to step 10. |
| 10 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY2 for connection Are P/J202, P/J602 and P/J409B connected surely? | Go to step 11. | Connect P/J202, <br> P/J602 and P/ <br> J409B surely. |
| 11 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY2 for operation (2) <br> Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY2 with that for the TRAY1. <br> Does the replaced motor operate properly? <br> Execute [Output 08-13 TRAY2 FEED MOTOR] in Chapter <br> 2 [Diagnostic]. <br> Pull out the TRAY2 and check it. | Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY1 as it previously was and replace the motor for the TRAY2 with a new one. (RRP 2.9) | Go to step 12. |
| 12 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY2 for conductivity Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTORs for the TRAY1 and TRAY2 as they previously were. Is there conductivity on each wire between P/J202 <=> P/ J409B? | Go to step 13. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 13 | Checking +24 VDC power supply to the TRAY 1/2 FEED <br> LIFT UP MOTOR for the TRAY2 <br> Is the voltage across J201-4 (+) <=> ground +24 VDC? | Replace the <br> TRAY 1/2 FEED <br> LIFT UP MOTOR <br> for the TRAY2. <br> (RRP 2.9) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray 2 Feed Out Sensor on JAM (Tray 2 paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 2.3.20) <br> ROLLER ASSY (RETARD) (PL 2.3.28) <br> ROLLER ASSY (NUDGER) (PL 2.3.32) <br> SENSOR (PRE FEED SENSOR) (PL 2.3.15) <br> SENSOR (PL 4.5.18) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup <br> Does the paper size in use match the size set for the TRAY2? | Go to step 3. | Replace the paper, or change the paper size setup. |
| 3 | Checking the Roll for the TRAY2 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY2 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). <br> (RRP 2.21/RRP <br> 2.25/RRP 2.28) |
| 4 | Checking paper position <br> Does the paper touch the SENSOR or the FEEDER ASSY (FEEDER 2) (PL 2.1.8)? <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking the SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR? <br> Execute [Input 08-06 FEED OUT\#2 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check it. | Go to step 9. | Go to step 6. |
| 6 | Checking the SENSOR for connection Are P/J105, P/J608 and P/J410 connected surely? | Go to step 7. | $\begin{aligned} & \text { Connect P/J105, } \\ & \text { P/J608 and P/ } \\ & \text { J410 securely } \end{aligned}$ |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 7 | Checking conductivity between the SENSOR and the PWBA MCU F <br> Is there conductivity on each wire between P/J105 <=> P/ J410? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the SENSOR Is the voltage across J105-1 (+) <=> ground +5 VDC? | Replace the SEN- <br> SOR. (RRP 4.15) | Replace the PWBA MCU F. (RRP 8.4) |
| 9 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY2 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR (PRE FEED SENSOR) for the TRAY2? <br> Execute [Input 08-59 PreFEED SENSOR2] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check it. | Reconnect the connector on the PWBA MCU F. | Go to step 10. |
| 10 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY2 for connection Are P/J134, P/J602 and P/J409B connected surely? | Go to step 11. | Connect P/J134, <br> P/J602 and P/ <br> J409B surely. |
| 11 | Checking conductivity between the SENSOR (PRE FEED SENSOR) for the TRAY2 and the PWBA MCU F Is there conductivity on each wire between P/J134 <=> P/ J409B? | Go to step 12. | Fix open and short circuit. |
| 12 | Checking +5 VDC power supply to the SENSOR (PRE FEED SENSOR) for the TRAY2 <br> Is the voltage across J134-1 (+) <=> ground +5 VDC? | Replace the SENSOR (PRE FEED SENSOR) for the TRAY2. (RRP 2.18) | Replace the PWBA MCU F. (RRP 8.4) |

## Registration Sensor on JAM (Tray 2 paper feed)

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 2.3.20) <br> ROLLER ASSY (RETARD) (PL 2.3.28) <br> ROLLER ASSY (NUDGER) (PL 2.3.32) <br> SENSOR (PL 4.5.18) <br> SENSOR ASSY REGI (PL 4.5.7) <br> PWBA MCU F (PL 8.1.5) | Replace the <br> paper with a new <br> and dry one. | Go to step 2. |
| 1 | Checking paper condition <br> Is the paper in the tray crumpled or damaged? | Checking paper size setup <br> Does the size of paper in use match the size set for the <br> TRAY2? | Replace the <br> paper or change <br> the paper size <br> setup. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 3 | Checking the Roll for the TRAY2 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY2 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). <br> (RRP 2.21/RRP <br> 2.25/RRP 2.28) |
| 4 | Checking paper position (1) <br> Does the paper touch the SENSOR ASSY REGI? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking paper position (2) <br> Does the paper touch the SENSOR? <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check it (visual check). | Remove the paper. | Go to step 6. |
| 6 | Checking the SENSOR ASSY REGI for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR ASSY REGI? Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 10. | Go to step 7. |
| 7 | Checking the SENSOR ASSY REGI for connection Are P/J104 and P/J403B connected surely? | Go to step 8. | Connect P/J104 and P/J403B surely. |
| 8 | Checking conductivity between the SENSOR ASSY REGI and the PWBA MCU F <br> Is there conductivity on each wire between P/J104 <=> P/ J409B? | Go to step 9. | Fix open and short circuit. |
| 9 | Checking +5 VDC power supply to the SENSOR ASSY REGI <br> Is the voltage across J104-1 (+) <=> ground +5 VDC? | Replace the SEN SORASSYREGI. (RRP 4.13) | Replace the PWBA MCU F. (RRP 8.4) |
| 10 | Checking the SENSOR for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR? <br> Execute [Input 08-06 FEED OUT\#2 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check it. | Reconnect the connector on the PWBA MCU F. | Go to step 11. |
| 11 | Checking the SENSOR for connection Are P/J105, P/J608 and P/J410 connected surely? | Go to step 12. | $\begin{aligned} & \text { Connect P/J105, } \\ & \text { P/J608 and P/ } \\ & \text { J410 surely. } \end{aligned}$ |
| 12 | Checking conductivity between the SENSOR and the PWBA MCU F <br> Is there conductivity on each wire between P/J105 <=> P/ J410? | Go to step 13. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 13 | Checking +5 VDC power supply to the SENSOR <br> Is the voltage across J105-1 $(+)<=>~ g r o u n d ~+5 ~ V D C ? ~$ | Replace the SEN- <br> SOR. (RRP 4.15) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray 2 Feed Out Sensor Static JAM

| Step | Check | Yes | No |
| :---: | :--- | :--- | :---: |
|  | Possible causative parts: <br> SENSOR (PL 4.5.18) <br> PWBA MCU F (PL 8.1.5) | Checking paper position <br> Does the paper touch the SENSOR? <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check <br> it (visual check). | Remove the <br> paper. |
| 2 | Checking the SENSOR for operation <br> Does the Input Status change from "0x0" to "0x1" each <br> time the paper touches the SENSOR? <br> Execute [Input 08-06 FEED OUT\#2 SENSOR] in Chapter <br> 2 [Diagnostic]. <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check <br> it. | Go to step 2. |  |
| 3 | Checking the SENSOR for connection <br> Are P/J105, P/J608 and P/J410 connected surely? | Go to step 3. |  |

## Registration Sensor on JAM (MPF paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY-FEED (PL 3.2.20) <br> ROLL ASSY-DRIVE (PL 3.2.14) <br> SENSOR ASSY REGI (PL 4.5.7) <br> SOLENOID PICK UP (PL 3.2.15) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the MPF tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup <br> Does the paper size in use match the size set for MPF tray? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking paper position <br> Does the paper touch the SENSOR ASSY REGI? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 4. |
| 4 | Checking the MPF guide for installation Does the MPF guide operate smoothly? | Go to step 5. | Install the MPF guide correctly. |
| 5 | Checking the MPF for installation <br> Remove the FEEDER ASSY MPF (PL 3.1.1) and reinstall it. <br> Does an error occur when a test print of MPF printing is carried out? <br> Execute [Test Print] in Chapter 2 [Diagnostic]. | Go to step 6. | End of work |
| 6 | Checking the Roll (1) <br> Remove the FEEDER ASSY MPF (PL 3.1.1). <br> Is the Roller of the ROLLER ASSY-FEED for transport worn or contaminated with paper dust? | Go to step 7. | Clean or replace the ROLLER ASSY-FEED. (RRP 3.13) |
| 7 | Checking the Roll (2) <br> Remove the FEEDER ASSY MPF (PL 3.1.1). <br> Is the Roller of the ROLL ASSY-DRIVE for transport worn or contaminated with paper dust? | Go to step 8. | Clean or replace the ROLLER ASSY-DRIVE. (RRP 3.10) |
| 8 | Checking the SENSOR ASSY REGI for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR ASSY REGI? Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 12. | Go to step 9. |
| 9 | Checking the SENSOR ASSY REGI for connection Are P/J104 and P/J403B connected surely? | Go to step 10. | Connect P/J104 and P/J403B surely. |
| 10 | Checking conductivity between the SENSOR ASSY REGI and the PWBA MCU F <br> Is there conductivity on each wire between P/J104 <=> P/ J403B? | Go to step 11. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 11 | Checking +5 VDC power supply to the SENSOR ASSY <br> REGI <br> Is the voltage across J104-1 (+) <=> ground +5 VDC? | Replace the SEN- <br> SOR ASSY REGI. <br> (RRP 4.13) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |
| 12 | Checking the SOLENOID PICK UP for operation <br> Does the SOLENOID PICK UP operate properly? <br> Execute [Output 08-17 SMH FEED CLUTCH] in Chapter 2 <br> [Diagnostic]. | Reconnect the <br> connector on the <br> PWBA MCU F. | Go to step 13. |
| 13 | Checking the SOLENOID PICK UP for connection <br> Are P/J205, P/J605 and P/J411 connected surely? | Go to step 14. | Connect P/J205, <br> P/J605 and P/ <br> J411 surely. |
| 14 | Checking the SOLENOID PICK UP for conductivity <br> Is there conductivity on each wire between P/J205 <=> P/ <br> J411? | Go to step 15. | Fix open and <br> short circuit. |
| 15 | Checking the SOLENOID PICK UP for resistance <br> Is the resistance across J205-1 and J205-2 approximately. <br> 90 ohm? | Go to step 16. | Replace the <br> SOLENOID PICK <br> UP. (RRP 3.11) |
| 16 | Check +24 VDC power supply to the SOLENOID PICK UP <br> Is the voltage across P205-1 (+) <=> ground +24 VDC? | Replace the <br> SOLENOID PICK <br> UP. (RRP 3.11) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Registration Sensor off JAM (Too Long)

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY-TA (PL 4.1.8) <br> SENSOR ASSY REGI (PL 4.5.7) <br> CLUTCH ASSY REGI H (PL 4.5.2) <br> PWBA MCU F (PL 8.1.5) | Checking paper position <br> Does the paper touch the SENSOR ASSY REGI? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual <br> check). | Remove the <br> paper. |
| 2 | Checking the Roll <br> Is the ROLLER ASSY-TA for transport worn or contami- <br> nated with paper dust? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 2. |  |
| 3 | Checking the SENSOR ASSY REGI for operation <br> Does the Input Status change from "0x0" to "Ox1" each <br> time the paper touches the SENSOR ASSY REGI? <br> Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diag- <br> nostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 7. | Go to s. <br> Go the ROLLER 4. <br> ASSY-TA. (RRP <br> $4.3)$ |
| 4 | Checking the SENSOR ASSY REGI for connection <br> Are P/J104 and P/J403B connected surely? | Go to step 5. | Connect P/J104 <br> and P/J403B <br> surely. |


| Step | Check | Yes | No |
| :---: | :--- | :--- | :---: |
| 5 | Checking conductivity between the SENSOR ASSY REGI <br> and the PWBA MCU <br> Is there conductivity on each wire between P/J104 <=> P/ <br> J403B? | Go to step 6. | Fix open and <br> short circuit. |
| 6 | Checking +5 VDC power supply to the SENSOR ASSY <br> REGI <br> Is the voltage across J104-1 (+) <=> ground +5 VDC? | Replace the SEN- <br> SORASSY REGI. <br> (RRP 4.13) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |
| 7 | Checking the CLUTCH ASSY REGI H for operation <br> Does the CLUTCH ASSY REGI H operate properly? <br> Execute [Output 08-10 REGI CLUTCH] in Chapter 2 [Diag- <br> nostic]. | Reconnect the <br> connector on the <br> PWBA MCU F. | Go to step 8. |
| 8 | Checking the CLUTCH ASSY REGI H for connection <br> Are P/J215 and P/J403B connected surely? | Go to step 9. | Connect P/J215 <br> and P/J403B <br> securely |
| 9 | Checking conductivity between the CLUTCH ASSY REGI <br> H and the PWBA MCU F <br> Is there conductivity on each wire between P/J215 <=> P/ <br> J403B? | Go to step 10. | Fix open and <br> short circuit. |
| 10 | Checking +24 VDC power supply to the CLUTCH ASSY H <br> Is the voltage across P215-2 (+) <=> ground +24 VDC? | Go to step 11. | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |
| 11 | Checking the CLUTCH ASSY REGI H for resistance <br> Is the resistance between J215-1 and J215-2 approxi- <br> mately 240 ohm? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | Replace the <br> CLUTCH ASSY <br> REGI H. (RRP <br> 4.11) |

## Registration Sensor off JAM (Too Short)

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY-TA (PL 4.1.8) <br> SENSOR ASSY REGI (PL 4.5.7) <br> CLUTCH ASSY REGI H (PL 4.5.2) <br> PWBA MCU F (PL 8.1.5) | Checking paper position <br> Does the paper touch the SENSOR ASSY REGI? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual <br> check). | Remove the <br> paper. |
| 2 | Checking the Roll <br> Is the ROLLER ASSY-TA for transport worn or contami- <br> nated with paper dust? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 2. |  |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 3 | Checking the SENSOR ASSY REGI for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR ASSY REGI? Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 7. | Go to step 4. |
| 4 | Checking the SENSOR ASSY REGI for connection Are P/J104 and P/J403B connected surely? | Go to step 5. | Connect P/J104 and P/J403B surely. |
| 5 | Checking conductivity between the SENSOR ASSY REGI and the PWBA MCU <br> Is there conductivity on each wire between P/J104 <=> P/ J409B? | Go to step 6. | Fix open and short circuit. |
| 6 | Checking +5 VDC power supply to the SENSOR ASSY REGI <br> Is the voltage across J104-1 (+) <=> ground +5 VDC? | Replace the SEN SORASSYREGI. (RRP 4.13) | Replace the PWBA MCU F. (RRP 8.4) |
| 7 | Checking the CLUTCH ASSY REGI H for operation Does the CLUTCH ASSY REGI H operate properly? Execute [Output 08-10 REGI CLUTCH] in Chapter 2 [Diagnostic]. | Reconnect the connector on the PWBA MCU F. | Go to step 8. |
| 8 | Checking the CLUTCH ASSY REGI H for connection Are P/J215 and P/J403B connected surely? | Go to step 9. | Connect P/J215 and P/J403B securely |
| 9 | Checking conductivity between the CLUTCH ASSY REGI H and the PWBA MCU F <br> Is there conductivity on each wire between P/J215 <=> P/ J403B? | Go to step 10. | Fix open and short circuit. |
| 10 | Checking +24 VDC power supply to the CLUTCH ASSY REGI H <br> Is the voltage across P215-2 (+) <=> ground +24 VDC? | Go to step 11. | Replace the PWBA MCU F. (RRP 8.4) |
| 11 | Checking the CLUTCH ASSY REGI H for resistance Is the resistance between J215-1 and J215-2 the correct resistance? | Replace the PWBA MCU F. (RRP 8.4) | Replace the CLUTCH ASSY REGI H. (RRP 4.11) |

## Exit Sensor 1 on JAM

| Step | Check | Yes | No |
| :--- | :--- | :--- | :--- |
|  | Possible causative parts: <br> SENSOR PHOTO (PL 6.1.4) <br> CLUTCH ASSY REGI H (PL 4.5.2) <br> ROLER ASSY-TA (PL 4.1.8) |  |  |
|  | PWBA MCU F (PL 8.1.5) |  |  |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking paper position <br> Does the paper touch the SENSOR PHOTO? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 2. |
| 2 | Checking the Roll Is the ROLLER ASSY-TA for transport worn or contaminated with paper dust? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 3. | Clean or replace the ROLLER ASSY-TA. (RRP 4.3) |
| 3 | Checking the SENSOR PHOTO for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR PHOTO? Execute [Input 10-23 EXIT SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 7. | Go to step 4. |
| 4 | Checking the SENSOR PHOTO for connection Are P/J125 and P/J410 connected surely? | Go to step 5. | Connect P/J125 and P/J410 surely. |
| 5 | Checking conductivity between the SENSOR PHOTO and the PWBA MCU F <br> Is there conductivity on each wire between $P / J 125$ <=> P/ J410? | Go to step 6. | Fix open and short circuit. |
| 6 | Checking +5 VDC power supply to the SENSOR PHOTO Is the voltage across J125-3 (+) <=> ground +5 VDC? | Replace the SENSOR PHOTO. (RRP 6.1) | Replace the PWBA MCU F. (RRP 8.4) |
| 7 | Checking the CLUTCH ASSY REGI H for operation Does the CLUTCH ASSY REGI H operate properly? Execute [Output 08-10 REGI CLUTCH] in Chapter 2 [Diagnostic]. | Reconnect the connector on the PWBA MCU F. | Go to step 8. |
| 8 | Checking the CLUTCH ASSY REGI H for connection Are P/J215 and P/J403B connected surely? | Go to step 9. | Connect P/J215 and P/J403B surely. |
| 9 | Checking conductivity between the CLUTCH ASSY REGI H and the PWBA MCU F Is there conductivity on each wire between P/J215 <=> P/ J403B? | Go to step 10. | Fix open and short circuit. |
| 10 | Checking +24 VDC power supply to the CLUTCH ASSY REGI H Is the voltage across P215-2 (+) <=> ground +24 VDC? | Go to step 11. | Replace the PWBA MCU F. (RRP 8.4) |
| 11 | Checking the CLUTCH ASSY REGI H for resistance Is the resistance between J215-1 and J215-2 the correct resistance? | Replace the PWBA MCU F. (RRP 8.4) | Replace the CLUTCH ASSY REGI H. (RRP 4.11) |

Registration Sensor Static on JAM

| Step | Check | Yes | No |
| :---: | :--- | :--- | :---: |
|  | Possible causative parts: <br> SENSOR ASSY REGI (PL 4.5.7) <br> PWBA MCU F (PL 8.1.5) | Checking paper position <br> Does the paper touch the SENSOR ASSY REGI? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual <br> check). | Remove the <br> paper. |
| 2 | Checking the SENSOR ASSY REGI for operation <br> Does the Input Status change from "Ox0" to "0x1" each <br> time the paper touches the SENSOR ASSY REGI? <br> Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diag- <br> nostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Ro to step 2. <br> Rennector on the <br> PWBA MCU F. | Go to step 3. |
| 3 | Checking the SENSOR ASSY REGI for connection <br> Are P/J104 and P/J403B connected surely? | Go to step 4. | Connect P/J104 <br> and P/J403B <br> surely. |
| 4 | Checking conductivity between the SENSOR ASSY REGI <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J104 <=> P/ | Go to step 5. | Fix open and <br> short circuit. |
| 5 | Checking +5 VDC power supply to the SENSOR ASSY <br> REGI <br> Is the voltage across J104-1 (+) <=> ground +5 VDC? | Replace the SEN- <br> SOR ASSY REGI. <br> (RRP 4.13) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Exit Sensor 1 off JAM

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> SENSOR PHOTO (PL 6.1.4) <br> ROLLER ASSY-TA (PL 4.1.8) <br> PWBA MCU F (PL 8.1.5) | Checking paper position <br> Does the paper touch the SENSOR PHOTO? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual <br> check). | Remove the <br> paper. |
| 2 | Checking the Roll (2) <br> Is the ROLLER ASSY-TA for transport worn or contami- <br> nated with paper dust? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 2. |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 3 | Checking the SENSOR PHOTO for operation <br> Does the Input Status change from "Ox0" to "Ox1" each <br> time the paper touches the SENSOR PHOTO? <br> Execute [Input 10-23 EXIT SENSOR] in Chapter 2 [Diag- <br> nostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Reconnect the <br> connector on the <br> PWBA MCU F. | Go to step 4. |
| 4 | Checking the SENSOR PHOTO for connection <br> Are P/J125 and P/J410 connected surely? | Go to step 5. | Connect P/J125 <br> and P/J410 <br> surely. |
| 5 | Checking conductivity between the SENSOR PHOTO and <br> the PWBA MCU F <br> Is there conductivity on each wire between P/J125 <=> P/ <br> J410? | Go to step 6. | Fix open and <br> short circuit. |
| 6 | Checking +5 VDC power supply to the SENSOR PHOTO <br> Is the voltage across J125-3 (+) <=> ground +5 VDC? | Replace the SEN- <br> SOR PHOTO. <br> (RRP 6.1) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Exit Sensor 1 off (too short) JAM

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SENSOR PHOTO (PL 6.1.4) <br> ROLLER ASSY-TA (PL 4.1.8) <br> FUSER ASSY (PL 6.1.7) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper position <br> Does the paper touch the SENSOR PHOTO? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 2. |
| 2 | Checking the FUSER ASSY for paper jam Is there a paper jam in the FUSER ASSY? Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 3. | Remove the paper. |
| 3 | Checking the FUSER ASSY for installation Is the FUSER ASSY installed securely? Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 4. | Install the FUSER ASSY securely. |
| 4 | Checking the Roll Is the ROLLER ASSY-TA for transport worn or contaminated with paper dust? Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 5. | Clean or replace the ROLLER ASSY-TA. (RRP 4.3) |
| 5 | Checking the SENSOR PHOTO for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR PHOTO? Execute [Input 10-23 EXIT SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Reconnect the connector of the PWBA MCU F. | Go to step 6. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 6 | Checking the SENSOR PHOTO for connection <br> Are P/J125 and P/J410 connected surely? | Go to step 7. | Connect P/J125 <br> and P/J410 <br> surely. |
| 7 | Checking conductivity between the SENSOR PHOTO and <br> the PWBA MCU F <br> Is there conductivity on each wire between P/J125 <=> P/ <br> J410? | Go to step 8. | Fix open and <br> short circuit. |
| 8 | Checking +5 VDC power supply to the SENSOR PHOTO <br> Is the voltage across J125-3 ( + \ll=> ground +5 VDC? | Replace the SEN- <br> SOR PHOTO. <br> (RRP 6.1) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Exit Sensor 1 Static JAM

| Step | Check | Yes | No |
| :---: | :--- | :--- | :---: |
|  | Possible causative parts: <br> SENSOR PHOTO (PL 6.1.4) <br> PWBA MCU F (PL 8.1.5) | Checking paper position <br> Does the paper touch the SENSOR PHOTO? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual <br> check). | Remove the <br> paper. |
| 2 | Checking the SENSOR PHOTO for operation (1) <br> Does the Input Status change from "0x0" to "01" each <br> time the paper touches the SENSOR PHOTO? <br> Execute [Input 10-23 EXIT SENSOR] in Chapter 2 [Diag- <br> nostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Reconnect the <br> connector of the <br> PWBA MCU F. | Go to step 3. |
| 3 | Checking the SENSOR PHOTO for connection <br> Are P/J125 and P/J410 connected surely? | Go to step 4. | Connect P/J125 <br> and P/J410 <br> surely. |
| 4 | Checking conductivity between the SENSOR PHOTO and <br> the PWBA MCU F <br> Is there conductivity on each wire between P/J125 <=> P/ <br> J410? | Go to step 5. | Fix open and <br> short circuit. |
| 5 | Checking +5 VDC power supply to the SENSOR PHOTO <br> Is the voltage across J125-3 (+) <=> ground +5 VDC? | Replace the SEN- <br> SOR PHOTO. <br> (RRP 6.1) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SENSOR PHOTO (PL 6.1.4) <br> SENSOR-PHOTO IN (PL 11.2.35) <br> PWBA EXIT (PL 8.1.4) <br> MOTOR ASSY EXIT 2 (PL 11.2.37) <br> SOLENOID ASSY (PL 11.2.29) |  |  |
| 1 | Checking paper position (1) <br> Does the paper touch the SENSOR PHOTO? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 2. |
| 2 | Checking paper position (2) <br> Does the paper touch the SENSOR-PHOTO IN? <br> Open the CHUTE LH HIGH (PL 11.1.18) and check it (visual check). | Remove the paper. | Go to step 3. |
| 3 | Checking the Roll <br> Open COVER ASSY-LH (PL 4.2.8). <br> Is the Roller of the ROLL ASSY OCT for transport worn or contaminated with paper dust? | Go to step 4. | Clean or replace the ROLL ASSY OCT. (RRP 6.9) |
| 4 | Checking the drive power transmission Do the ROLLER ASSY OCT for transport and the other gears rotate smoothly? | Go to step 5. | Replace obstacles for rotation. |
| 5 | Checking the SENSOR PHOTO for operation <br> Does the SENSOR PHOTO operate properly? <br> Execute [Input 10-23 EXIT SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 9. | Go to step 6. |
| 6 | Checking the SENSOR PHOTO for connection Are P/J125 and P/J410 connected surely? | Go to step 7. | Connect P/J125 and P/J410 surely. |
| 7 | Checking conductivity between the SENSOR PHOTO and the PWBA MCU F Is there conductivity on each wire between P/J125 <=> P/ J410? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the SENSOR PHOTO Is the voltage across P/J125-3 (+) <=> ground +5 VDC? | Replace the SEN- <br> SOR PHOTO. <br> (RRP 6.1) | Replace the PWBA MCU F. <br> (RRP 8.4) |
| 9 | Checking the MOTOR ASSY EXIT 2 for operation Does the MOTOR ASSY EXIT 2 operate properly? Check it using "Output 10-08 EXIT DRIVE MOTOR FORWARD (Eject Paper out)" in Chapter 2, Diag. | Go to step 13. | Go to step 10. |
| 10 | Checking the MOTOR ASSY EXIT 2 for connection Are P/J208, P/J606A and P/J433 connected securely? | Go to step 11. | Connect P/J208, P/J606A and P/ J433 surely. |
| 11 | Checking conductivity between the MOTOR ASSY EXIT 2 and PWBA EXIT <br> Is there normal conductivity between P/J208 and P/J433? | Go to step 12. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 12 | Checking the MOTOR ASSY EXIT 2 for power supply Is the voltage between P208-5 (+) and the ground (-) +24 VDC? | Replace the MOTOR ASSY EXIT 2. (RRP 11.16) | Replace the PWBA EXIT. (RRP 8.3) |
| 13 | Checking the SENSOR-PHOTO IN for operation Does the SENSOR-PHOTO IN operate properly? Execute [Input 10-52 EXIT SENSOR2] in Chapter 2 [Diagnostic]. | Go to step 17. | Go to step 14. |
| 14 | Checking the SENSOR-PHOTO IN for connection Are P/J112, P/J606B and P/J434 connected surely? | Go to step 15. | Connect P/J112, <br> P/J606B and P/ <br> J434 surely. |
| 15 | Checking conductivity between the SENSOR-PHOTO IN and the PWBA EXIT <br> Is there conductivity on each wire between P/J112 <=> P/ J434? | Go to step 16. | Fix open and short circuit. |
| 16 | Checking +5 VDC power supply to the SENSOR-PHOTO IN <br> Is the voltage across J112-3 (+) <=> ground +5 VDC? | Replace the SEN-SOR-PHOTO IN. (RRP 11.14) | Go to step 13. |
| 17 | Checking the SOLENOID ASSY for operation Does the SOLENOID ASSY actuate? <br> Check it using "Output 10-51 EXIT GATE SOLENOID" in Chapter 2, Diag. | Replace the PWBA EXIT. (RRP 8.3) | Go to step 18. |
| 18 | Checking the SOLENOID for connection Are P/J209, P/J606A and P/J433 connected securely? | Go to step 19. | Connect P/J209, P/J606A and P/ J433 surely. |
| 19 | Checking the SOLENOID ASSY for conductivity Is there normal conductivity between P/J209 and P/J433? | Go to step 20. | Fix open and short circuit. |
| 20 | Checking the SOLENOID ASSY for resistance Is each pair of pins connected normally with appropriate resistance? | Go to step 21. | Replace the SOLENOID ASSY. (RRP 3.11) |
| 21 | Checking the SOLENOID ASSY for power supply Is the voltage between P209-2 (+) and the ground (-) +24 VDC? | Replace the SOLENOID ASSY. (RRP 3.11) | Replace the PWBA EXIT. (RRP 8.3) |

## Exit Sensor2 off JAM

| Step | Check | Yes | No |
| :--- | :--- | :--- | :--- |
|  | Possible causative parts: |  |  |
|  | SENSOR-PHOTO IN (PL 11.2.35) |  |  |
|  | MOTOR ASSY EXIT 2(PL 11.2.37) |  |  |
|  | ROLL ASSY-FU (PL 11.1.19) |  |  |
| ROLL ASSY-INV (PL 11.1.20) |  |  |  |
|  | ROLL ASSY OCT (PL 11.2.7) |  |  |
|  | PWBA EXIT (PL 8.1.4) |  |  |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking the paper position <br> Does the paper touch the SENSOR-PHOTO IN? <br> Open the CHUTE LH HIGH (PL 11.1.18) and check it (visual check). | Remove the paper. | Go to step 2. |
| 2 | Checking the Roll (1) <br> Open CHUTE LH HIGH (PL 11.1.18). <br> Is the Roller of the ROLL ASSY-FU for transport worn or contaminated with paper dust? | Go to step 3. | Clean or replace the ROLL ASSYFU. (RRP 11.2) |
| 3 | Checking the drive power transmission (1) Do the ROLL ASSY-FU for transport and the other gears rotate smoothly? | Go to step 4. | Replace obstacles for rotation. |
| 4 | Checking the Roll (2) <br> Open the CHUTE LH HIGH (PL 11.1.18). <br> Is the Roller of the ROLL ASSY-INV for transport worn or contaminated with paper dust? | Go to step 5. | Clean or replace the ROLL ASSYINV. (RRP 11.3) |
| 5 | Checking the drive power transmission (2) <br> Do the ROLL ASSY-INV for transport and the other gears rotate smoothly? | Go to step 6. | Replace obstacles for rotation. |
| 6 | Checking the Roll (3) <br> Open CHUTE LH HIGH (PL 11.1.18). <br> Is the Roller of the ROLL ASSY OCT for transport worn or contaminated with paper dust? | Go to step 7. | Clean or replace the ROLL ASSY OCT. (RRP 11.6) |
| 7 | Checking the drive power transmission (3) Do the ROLLER ASSY OCT for transport and the other gears rotate smoothly? | Go to step 8. | Replace obstacles for rotation. |
| 8 | Checking the SENSOR-PHOTO IN for operation Does the SENSOR-PHOTO IN operate properly? Execute [Input 10-52 EXIT SENSOR2] in Chapter 2 [Diagnostic]. | Go to step 17. | Go to step 9. |
| 9 | Checking the SENSOR-PHOTO IN for connection Are P/J112, P/J606B and P/J434 connected surely? | Go to step 10. | Connect P/J112, P/J606B and P/ J434 surely. |
| 10 | Checking conductivity between the SENSOR-PHOTO IN and the PWBA EXIT <br> Is there conductivity on each wire between P/J112 <=> P/ J434? | Go to step 11. | Fix open and short circuit. |
| 11 | Checking +5 VDC power supply to the SENSOR-PHOTO IN <br> Is the voltage across J112-3 (+) <=> ground +5 VDC? | Replace the SEN SOR-PHOTO IN. (RRP 11.14) | Replace the PWBA EXIT. (RRP 8.3) |
| 12 | Checking the MOTOR ASSY EXIT 2 for operation Does the MOTOR ASSY EXIT 2 operate properly? Execute [Output 10-09 EXIT DRIVE MOTOR REVERSE (send paper into DUP)] in Chapter 2 [Diagnostic]. | Reconnect the connector of the PWBA MCU F. | Go to step 13. |
| 13 | Checking the MOTOR ASSY EXIT 2 for connection Are P/J208, P/J606A and P/J433 connected surely? | Go to step 14. | Connect P/J208, P/J606A and P/ J433 surely. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 14 | Checking conductivity between the MOTOR ASSY EXIT 2 <br> and PWBA EXIT <br> Is there conductivity on each wire between P/J208 <=> P/ <br> J433? | Go to step 15. | Fix open and <br> short circuit. |
| 15 | Checking +24 VDC power supply to the MOTOR ASSY <br> EXIT 2 <br> Is the voltage across P208-5 (+) <=> ground +24 VDC? | Replace the <br> MOTOR ASSY <br> EXIT 2. (RRP <br> 11.16) | Replace the <br> PWBA EXIT. <br> (RRP 8.3) |

## Tray1 Lift up /No tray fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> SECTOR GEAR (60T) (PL 2.2.22) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 2.3.2) <br> SENSOR (LEVEL SENSOR) (PL 2.3.14) <br> SWITCH ASSY P S (PL 2.1.4) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | Load paper. |
| 1 | Checking paper <br> Is any paper loaded in the Tray1? <br> Pull out the Tray1 to check it. (Visual check) | Checking the TRAY (1) <br> Replace the TRAY1 with the TRAY2. Is the replaced tray <br> lifted up? | Go to step 3. | Go to step 4.


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 6 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY1 for operation (2) <br> Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY1 with that for the TRAY2. <br> Does the replaced motor operate properly? <br> Execute [Output 07-18 TRAY1 LIFT UP (FEED MOTOR REVERSE)] in Chapter 2 [Diagnostic]. | Reinstall the <br> TRAY 1/2 FEED LIFT UP MOTOR for the TRAY2 as it previously was and replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY1 with a new one. (RRP 2.9) | Go to step 7. |
| 7 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY1 for conductivity Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTORs for the TRAY1 and TRAY2 as they previously were. Is there conductivity on each wire between P/J201 <=> P/ J409A? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +24 VDC power supply to the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY 1 <br> Is the voltage across J201-4 (+) <=> ground +24 VDC? | Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY1. (RRP 2.9) | Replace the PWBA MCU F. (RRP 8.4) |
| 9 | Checking the SENSOR (LEVEL SENSOR) for the TRAY1 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR (LEVEL SENSOR) for the TRAY1? <br> Execute [Input 07-13 TRAY1 LEVEL SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 13. | Go to step 10. |
| 10 | Checking the SENSOR (LEVEL SENSOR) for the TRAY1 for connection <br> Are P/J100, P/J601 and P/J409A connected surely? | Go to step 11. | $\begin{aligned} & \text { Connect P/J100, } \\ & \text { P/J601 and P/ } \\ & \text { J409A surely. } \end{aligned}$ |
| 11 | Checking conductivity between the SENSOR for the TRAY1 (LEVEL SENSOR) and the PWBA MCU F Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 100<=>$ P/ J409A? | Go to step 12. | Fix open and short circuit. |
| 12 | Checking +5 VDC power supply to the SENSOR (LEVEL SENSOR) for the TRAY1 <br> Is the voltage across J100-3 (+) <=> ground +5 VDC? | Replace the SENSOR (LEVEL SENSOR) for the TRAY1. (RRP 2.17) | Replace the PWBA MCU F. (RRP 8.4) |
| 13 | Checking the SWITCH ASSY P S for the TRAY1 for operation <br> Does the Input Status change each time the TRAY 1 with paper loaded is pulled out or pushed in? <br> Execute [Input 07-01 TRAY1 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Reconnect the connector of the PWBA MCU F. | Go to step 14. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 14 | Checking the SWITCH ASSY P S for the TRAY1 for con- <br> nection <br> Are P/J109 and P/J412 connected surely? | Go to step 15. | Connect P/J109 <br> and P/J412 <br> surely. |
| 15 | Checking conductivity between the SWITCH ASSY P S for <br> the TRAY1 and the PWBA MCU F <br> Is there conductivity on each wire between P/J109 <=> P/ <br> J412? | Go to step 16. | Fix open and <br> short circuit. |
| 16 | Checking +5 VDC power supply to the SWITCH ASSY P S <br> for the TRAY1 <br> Is the voltage across J109-1 (+) <=> ground +5 VDC? | Replace the <br> SWITCH ASSY P <br> S for the TRAY1. <br> (RRP 2.1) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray2 Lift up /No tray fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SECSTOR GEAR (60T) (PL 2.2.22) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 2.3.2) <br> SENSOR (LEVEL SENSOR) (PL 2.3.14) <br> SWITCH ASSY P S (PL 2.1.4) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper <br> Is any paper loaded in the TRAY2? <br> Pull out the TRAY2 to check it. (Visual check) | Go to step 2. | Load paper. |
| 2 | Checking the TRAY (1) Replace the TRAY2 with the TRAY1. Is the replaced tray lifted up? | Go to step 3. | Go to step 4. |
| 3 | Checking the TRAY (2) <br> Are the SECTOR GEAR (60T) of TRAY2 or the surrounding parts of it damaged? | Replace the TRAY2. | Replace the SECTOR GEAR (60T) (RRP 2.8) or the obstacles. |
| 4 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the <br> TRAY2 for operation (1) <br> Does the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY2 <br> operate properly? <br> Execute [Output 07-19 TRAY2 LIFT UP MOTOR (FEED <br> MOTOR Reverse)] in Chapter 2 [Diagnostic]. <br> Pull out the TRAY2 and check it. | Go to step 9. | Go to step 5. |
| 5 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY2 for connection Are P/J202, P/J602 and P/J409B connected surely? | Go to step 6. | Connect P/J202, P/J602 and P/ J409B surely. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 6 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the <br> TRAY2 for operation (2) <br> Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the <br> TRAY2 with that for the TRAY1. <br> Does the replaced motor operate properly? <br> Execute [Output 08-13 TRAY2 FEED MOTOR] in Chapter <br> 2 [Diagnostic]. | Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY1 as it previously was and then, replace the motor for the TRAY2 with a new one. (RRP 2.9) | Go to step 7. |
| 7 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY2 for conductivity Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTORs for the TRAY1 andTRAY2 as they previously were. Is there conductivity on each wire between P/J202 <=> P/ J409B? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +24 VDC power supply to the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY2 <br> Is the voltage across J202-4 (+) <=> ground +24 VDC? | Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY2. (RRP 2.9) | Replace the PWBA MCU F. (RRP 8.4) |
| 9 | Checking the SENSOR (LEVEL SENSOR) for the TRAY2 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR (LEVEL SENSOR) for the TRAY2? <br> Execute [Input 07-14 TRAY2 LEVEL SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check it. | Go to step 13. | Go to step 10. |
| 10 | Checking the SENSOR (LEVEL SENSOR) for the TRAY2 for connection <br> Are P/J102, P/J602 and P/J409B connected surely? | Go to step 11. | $\begin{aligned} & \text { Connect P/J102, } \\ & \text { P/J602 and P/ } \\ & \text { J409B surely. } \end{aligned}$ |
| 11 | Checking conductivity between the SENSOR (LEVEL SENSOR) for the TRAY2 and the PWBA MCU F Is there conductivity on each wire between P/J102 <=> P/ J409B? | Go to step 12. | Fix open and short circuit. |
| 12 | Checking +5 VDC power supply to the SENSOR (LEVEL SENSOR) for the TRAY2 <br> Is the voltage across J102-3 (+) <=> ground +5 VDC? | Replace the SENSOR (LEVEL SENSOR) for the TRAY2. (RRP 2.17) | Replace the PWBA MCU F. (RRP 8.4) |
| 13 | Checking the SWITCH ASSY P S for the TRAY2 for operation <br> Does the Input Status change each time the TRAY 2 with paper loaded is pulled out or pushed in? <br> Execute [Input 07-02 TRAY2 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Reconnect the connector of the PWBA MCU F. | Go to step 14. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 14 | Checking the SWITCH ASSY P S for the TRAY2 for con- <br> nection <br> Are P/J110 and P/J412 connected surely? | Go to step 15. | Connect P/J110 <br> and P/J412 <br> surely. |
| 15 | Checking conductivity between the SWITCH ASSY P S for <br> the TRAY2 and the PWBA MCU F <br> Is there conductivity on each wire between P/J110 <=> P/ <br> J412? | Go to step 16. | Fix open and <br> short circuit. |
| 16 | Checking +5 VDC power supply to the SWITCH ASSY P S <br> for the TRAY2 <br> Is the voltage across J110-1 (+) <=> ground +5 VDC? | Replace the <br> SWITCH ASSY P <br> S for the TRAY2. <br> (RRP 2.2) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Exit Module Communication fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> PWBA EXIT (PL 8.1.4) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the PWBA EXIT for connection Are P/J431 and P/J421 connected surely? | Go to step 2. | Connect P/J431 and P/J421 surely. |
| 2 | Checking conductivity between the PWBA EXIT and the PWBA MCU F <br> Is there conductivity on each wire between P/J431 <=> P/ J421? | Go to step 3. | Fix open and short circuit. |
| 3 | Checking the connection between the PWBA EXIT and the POWER UNIT <br> Are P/J430 and P/J526 connected surely? | Go to step 4. | Connect P/J430 and P/J526 surely. |
| 4 | Checking conductivity between the PWBA EXIT and the POWER UNIT <br> Is there conductivity on each wire between P/J430 <=> P/ J526? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking +24 VDC power supply to the PWBA EXIT Is the voltage across J430-1 (+) <=> ground +24 VDC? | Replace the PWBA EXIT. (RRP 8.3) | Reconnect the connector of the POWER UNIT. |

## Tray 1 cassette Size fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SWITCH ASSY P S (PL 2.1.4) <br> FRONT SIDE GUIDE (PL 2.2.6) <br> REAR SIDE GUIDE (PL 2.2.9) <br> END GUIDE (PL 2.2.16) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper (1) <br> Is paper loaded in the Tray1 properly? <br> Pull out the Tray1 to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the paper (2) <br> Are the FRONT SIDE GUIDE, REAR SIDE GUIDE and <br> END GUIDE of the TRAY1 set correctly? <br> Pull out the Tray1 to check it. (Visual check) | Go to step 3. | Set the parts properly. |
| 3 | Checking the SWITCH ASSY P S for the TRAY1 for installation <br> Is the SWITCH ASSY P S for the TRAY1 installed correctly? <br> Pull out the TRAY1 to check it. (Visual check) | Go to step 4. | Install the SWITCH ASSY P S for the TRAY1 correctly. (RRP 2.1) |
| 4 | Checking the SWITCH ASSY P S for the TRAY1 for operation <br> Does the Input Status change each time the TRAY 1 with paper loaded is pulled out or pushed in? <br> Execute [Input 07-01 TRAY1 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Reconnect the connector of the PWBA MCU F. | Go to step 5. |
| 5 | Checking the SWITCH ASSY P S for the TRAY1 for connection <br> Are P/J109 and P/J412 connected surely? | Go to step 6. | Connect P/J109 and P/J412 surely. |
| 6 | Checking conductivity between the SWITCH ASSY P S for the TRAY1 and the PWBA MCU F Is there conductivity on each wire between P/J109 <=> P/ J412? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +5 VDC power supply to the SWITCH ASSY P S for the TRAY1 <br> Is the voltage across J109-1 (+) <=> ground +5 VDC? | Replace the SWITCH ASSY P S for the TRAY1. (RRP 2.1) | Replace the PWBA MCU F. (RRP 8.4) |

## Tray 2 cassette Size fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SWITCH ASSY P S (PL 2.1.4) <br> FRONT SIDE GUIDE (PL 2.2.6) <br> REAR SIDE GUIDE (PL 2.2.9) <br> END GUIDE (PL 2.2.16) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper (1) <br> Is paper loaded in the TRAY2 properly? <br> Pull out the TRAY2 to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the paper (2) <br> Are the FRONT SIDE GUIDE, REAR SIDE GUIDE and <br> END GUIDE of the TRAY2 set correctly? <br> Pull out the TRAY2 to check it. (Visual check) | Go to step 3. | Set the parts properly. |
| 3 | Checking the SWITCH ASSY P S for the TRAY2 for installation <br> Is the SWITCH ASSY P S for the TRAY2 installed correctly? <br> Pull out the TRAY2 to check it. (Visual check) | Go to step 4. | Install the SWITCH ASSY P S for the TRAY2 correctly. (RRP 2.2) |
| 4 | Checking the SWITCH ASSY P S for the TRAY2 for operation <br> Does the Input Status change each time the TRAY 2 with paper loaded is pulled out or pushed in? <br> Execute [Input 07-02 TRAY2 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Reconnect the connector of the PWBA MCU F. | Go to step 5. |
| 5 | Checking the SWITCH ASSY P S for the TRAY2 for connection <br> Are P/J110 and P/J412 connected surely? | Go to step 6. | Connect P/J110 and P/J412 surely. |
| 6 | Checking conductivity between the SWITCH ASSY P S for the TRAY2 and the PWBA MCU F Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 110$ <=> P/ J412? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +5 VDC power supply to the SWITCH ASSY P S for the TRAY2 <br> Is the voltage across J110-1 (+) <=> ground +5 VDC? | Replace the SWITCH ASSY P S for the TRAY2. (RRP 2.2) | Replace the PWBA MCU F. (RRP 8.4) |

Toner Cartridge Empty fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TONER CARTRIDGE (PL 5.1.16) <br> GUIDE ASSY CTG30 SUB (PL 5.1.10) <br> MOTOR ASSY-DISP 30K (PL 5.1.11) <br> PWBA CRUM CP1 (TONER) (PL 5.1.8) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking remaining toner <br> Does the TONER CARTRIDGE contain sufficient toner? | Go to step 2. | Replace the TONER CARTRIDGE. |
| 2 | Checking the TRAY CARTRIDGE for installation Remove the TONER CARTRIDGE and reinstall it. Does it operate properly? | End of work | Go to step 3. |
| 3 | Checking the gear drive of the GUIDE ASSY CTG30 SUB Does the gear located at the lower part of the GUIDE ASSY CTG30 SUB rotate smoothly? | Go to step 4. | Replace the obstacles for rotation. |
| 4 | Checking the GUIDE ASSY CTG30 SUB for pipe clogging Is the pipe located at the lower part of the GUIDE ASSY CTG30 SUB clogged? | Go to step 5. | Clean the pipe. |
| 5 | Checking the PWBA CRUM CP1 (TONER) for installation Is the PWBA CRUM CP1 (TONER) installed correctly? | Go to step 6. | Install the PWBA CRUM CP1 (TONER) correctly. |
| 6 | Checking the PWBA CRUM CP1 (TONER) for connection Are P/J127 and P/J419 connected surely? | Go to step 7. | Connect P/J127 and P/J419 surely. |
| 7 | Checking conductivity between the PWBA CRUM CP1 (TONER) and the PWBA MCU F Is there conductivity on each wire between P/J127 <=> P/ J419? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the PWBA CRUM CP1 (TONER) <br> Is the voltage across P127-1 (+) <=> ground +5 VDC? | Go to step 9. | Replace the PWBA MCU F. (RRP 8.4) |
| 9 | Checking the MOTOR ASSY-DISP 30K for operation Execute [Output 15-63 Dispense Motor] in Chapter 2 [Diagnostic]. | Reconnect the connector of the PWBA MCU F. | Go to step 10. |
| 10 | Checking the MOTOR ASSY-DISP 30K for connection Are P/J216 and P/J420 connected surely? | Go to step 11. | Connect P/J216 and P/J420 surely. |
| 11 | Checking conductivity between the MOTOR ASSY-DISP 30K and the PWBA MCU F <br> Is there conductivity on each wire between P/J216 <=> P/ J420? | Go to step 12. | Fix open and short circuit. |
| 12 | Checking +24 VDC power supply to the MOTOR ASSYDISP 30K Is the voltage across $\mathrm{J} 216-1(+)<=>$ ground +24 VDC? | Replace the MOTOR ASSYDISP 30K. (RRP 5.6) | Replace the PWBA MCU F. (RRP 8.4) |

## Drum Cartridge Set fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> CRU (PL 5.1.15) <br> SWITCH ASSY XERO INTLK (PL 5.1.4) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the CRU for installation Is the CRU installed surely? | Go to step 2. | Install the CRU surely. |
| 2 | Checking the harness for connection Is P/J403B connected securely? | Go to step 3. | Connect P/J403B surely. |
| 3 | Checking the power supply Is the voltage between P401-1 (+) and the ground (-) +0 VDC when the CRU is installed? | Replace the CRU. | Go to step 4. |
| 4 | Checking conductivity between the ATC SENSOR and the PWBA MCU F (1) <br> Is there normal conductivity between P403B-11 and P610 when the CRU is installed? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking conductivity between the ATC SENSOR and the PWBA MCU F (2) <br> Is there normal conductivity between P610-3 and P610-7 when the CRU is installed? | Go to step 6. | Fix open and short circuit. |
| 6 | Checking conductivity between the ATC SENSOR and the PWBA MCU F (3) <br> Is there normal conductivity between P610-7 and P403-B when the CRU is installed? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking the SWITCH ASSY XERO INTLK for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the CRU is installed or removed? <br> Execute [Input 09-02 DRUM DETECT] in Chapter 2 [Diagnostic]. <br> Open COVER ASSY FRONT (PL 1.1.9) and check it. | Reconnect the connector of the PWBA MCU F. | Go to step 8. |
| 8 | Checking the SWITCH ASSY XERO INTLK for connection Is P/J404 connected surely? | Go to step 9. | Connect P/J404 surely. |
| 9 | Checking the SWITCH ASSY XERO INTLK for conductivity <br> Is there conductivity between P/J404-1 <=> P/J404-3 when the CRU is installed? | Go to step 10. | Fix open and short circuit. |
| 10 | Checking +5 VDC power supply to the SWITCH ASSY XERO INTLK <br> Is the voltage across P404-3 (+) <=> ground +5 VDC? | Replace the SWITCH ASSY XERO INTLK. (RRP 5.1) | Replace the PWBA MCU F. (RRP 8.4) |

ATC Sensor fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> CRU (PL 5.1.15) <br> HARN ASSY FRONT A (PL 5.1.9) <br> SWITCH ASSY XERO INTLK (PL 5.1.4) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | Install the CRU <br> surely. |
| 1 | Checking the CRU for installation <br> Is the CRU installed surely? | Go to step 3. | Connect P/J403B <br> surely. |
| 2 | Checking the harness for connection <br> Is P/J403B connected securely? | Reconnect the <br> Checking the ATC SENSOR for operation <br> Does the Input Status change each time the CRU is <br> installed or removed? <br> Execute [Input 15-62 ATC Sensor] in Chapter 2 [Diagnos- <br> tic]. <br> Open COVER ASSY FRONT (PL 1.1.9) and check it. | PWBA MCU F. |
| 4 | Checking the SWITCH ASSY XERO INTLK for connection <br> Is P/J404 connected surely? | Go to step 5. | Connect P/J304 <br> surely. |
| 5 | Checking the SWITCH ASSY XERO INTLK for conductiv- <br> ity <br> Is there conductivity between P/J404-1 <=> P/J404-3 <br> when the CRU is installed? | Go to step 6. | Fix open and <br> short circuit. |
| 6 | Checking +5 VDC power supply to the SWITCH ASSY <br> XERO INTLK <br> Is the voltage across P404-3 (+) <=> ground +5 VDC? | Replace the CRU. | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Drum Cartridge Life Over

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> CRU (PL 5.1.15) <br> PWBA CRUM CP1 (HSG) (PL 5.1.8) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | Install the CRU <br> surely. |
| 1 | Checking the CRU for installation <br> Is the CRU installed surely? | Go to step 3. | Install the PWBA <br> CRUM CP1 <br> (HSG) correctly. |
| 2 | Checking the PWBA CRUM CP1 (HSG) for installation <br> Is the PWBA CRUM CP1 (HSG) installed correctly? | Go to step 4. | Connect P/J126 <br> and P/J419 <br> surely. |
| 3 | Checking the PWBA CRUM CP1 (HSG) for connection <br> Are P/J126 and P/J419 connected surely? |  |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 4 | Checking conductivity between the PWBA CRUM CP1 <br> (HSG) and the PWBA MCU F <br> Is there conductivity on each wire between P/J126 <=> P/ <br> J419? | Go to step 5. | Fix open and <br> short circuit. |
| 5 | Checking +5 VDC power supply to the PWBA CRUM CP1 <br> (HSG) <br> Is the voltage across P126-6 (+) <=> ground +5 VDC? | Replace the <br> PWBA CRUM <br> CP1 (HSG). (RRP <br> 5.3) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Drum Cartridge CRUM Communication fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> CRU (PL 5.1.15) <br> PWBA CRUM CP1 (HSG) (PL 5.1.8) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | Install the CRU <br> surely. |
| 1 | Checking the CRU for installation <br> Is the CRU installed surely? | Go to step 3. | Install the PWBA <br> CRUM CP1 <br> (HSG) correctly. |
| 2 | Checking the PWBA CRUM CP1 (HSG) for installation <br> Is the PWBA CRUM CP1 (HSG) installed correctly? | Connect P/J126 <br> and P/J419 <br> surely. |  |
| 3 | Checking the PWBA CRUM CP1 (HSG) for connection <br> Are P/J126 and P/J419 connected surely? |  |  |
| 4 | Checking conductivity between the PWBA CRUM CP1 <br> (HSG) and the PWBA MCU F <br> Is there conductivity on each wire between P/J126 <=> P/ <br> J419? | Go to step 5. | Fix open and <br> short circuit. |
| 5 | Checking +5 VDC power supply to the PWBA CRUM CP1 <br> (HSG) <br> Is the voltage across P126-6 (+) <=> ground +5 VDC? | Replace the <br> PWBA CRUM <br> CP1 (HSG). (RRP <br> 5.3) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Drum Cartridge CRUM Data Write fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> CRU (PL 5.1.15) <br> PWBA CRUM CP1 (HSG) (PL 5.1.8) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | Install the CRU <br> surely. |
| 1 | Checking the CRU for installation <br> Is the CRU installed surely? |  |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 2 | Checking the PWBA CRUM CP1 (HSG) for installation <br> Is the PWBA CRUM CP1 (TONER) installed correctly? | Go to step 3. | Install the PWBA <br> CRUM CP1 <br> (TONER) cor- <br> rectly. |
| 3 | Checking the PWBA CRUM CP1 (HSG) for connection <br> Are P/J126 and P/J419 connected surely? | Go to step 4. | Connect P/J126 <br> and P/J419 <br> surely. |
| 4 | Checking conductivity between the PWBA CRUM CP1 <br> (HSG) and the PWBA MCU F <br> Is there conductivity on each wire between P/J126 <=> P/ <br> J419? | Go to step 5. | Fix open and <br> short circuit. |
| 5 | Checking +5 VDC power supply to the PWBA CRUM CP1 <br> (HSG) <br> Is the voltage across P126-6 (+) <=> ground +5 VDC? | Replace the <br> PWBA CRUM <br> CP1 (HSG). (RRP <br> 5.3) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Drum Cartridge CRUM ID fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | $\begin{array}{l}\text { Possible causative parts: } \\ \text { CRU (PL 5.1.15) } \\ \text { PWBA CRUM CP1 (HSG) (PL 5.1.8) } \\ \text { PWBA MCU F (PL 8.1.5) }\end{array}$ | Go to step 2. | $\begin{array}{c}\text { Install the CRU } \\ \text { surely. }\end{array}$ |
| 1 | $\begin{array}{l}\text { Checking the CRU for installation } \\ \text { Is the CRU installed surely? }\end{array}$ | $\begin{array}{l}\text { Checking the PWBA CRUM CP1 (HSG) for installation } \\ \text { Is the PWBA CRUM CP1 (HSG) installed correctly? }\end{array}$ | Go to step 3. | \(\left.\begin{array}{l}Install the PWBA <br>

CRUM CP1 <br>
(HSG) correctly.\end{array}\right]\)

## Toner Cartridge CRUM Communication fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> CRU (PL 5.1.15) <br> PWBA CRUM CP1 (TONER) (PL 5.1.8) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the CRU for installation Is the CRU installed surely? | Go to step 2. | Install the CRU surely. |
| 2 | Checking the PWBA CRUM CP1 (TONER) for installation Is the PWBA CRUM CP1 (TONER) installed correctly? | Go to step 3. | Install the PWBA CRUM CP1 (TONER) correctly. |
| 3 | Checking the PWBA CRUM CP1 (TONER) for connection Are P/J127 and P/J419 connected surely? | Go to step 4. | $\begin{aligned} & \text { Connect P/J127 } \\ & \text { and P/J419 } \\ & \text { surely. } \end{aligned}$ |
| 4 | Checking conductivity between the PWBA CRUM CP1 (TONER) and the PWBA MCU F Is there conductivity on each wire between P/J127 <=> P/ J419? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking +5 VDC power supply to the PWBA CRUM CP1 (TONER) <br> Is the voltage across P127-6 (+) <=> ground +5 VDC? | Replace the PWBA CRUM CP1 (TONER). (RRP 5.4) | Replace the PWBA MCU F. (RRP 8.4) |

## MCU Toner Cartridge CRUM Data Write fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | $\begin{array}{l}\text { Possible causative parts: } \\ \text { CRU (PL 5.1.15) } \\ \text { PWBA CRUM CP1 (TONER) (PL 5.1.8) } \\ \text { PWBA MCU F (PL 8.1.5) }\end{array}$ | Go to step 2. | $\begin{array}{c}\text { Install the CRU } \\ \text { surely. }\end{array}$ |
| 1 | $\begin{array}{l}\text { Checking the CRU for installation } \\ \text { Is the CRU installed surely? }\end{array}$ | $\begin{array}{l}\text { Checking the PWBA CRUM CP1 (TONER) for installation } \\ \text { Is the PWBA CRUM CP1 (TONER) installed correctly? }\end{array}$ | Go to step 3. | \(\left.\begin{array}{l}Install the PWBA <br>

CRUM CP1 <br>
(TONER) cor- <br>

rectly.\end{array}\right]\)| 3 | Checking the PWBA CRUM CP1 (TONER) for connection <br> Are P/J127 and P/J419 connected surely? | Go to step 4. |
| :---: | :--- | :--- |
| 4 | Connect P/J127 <br> and P/J419 <br> surely. |  |
| Checking conductivity between the PWBA CRUM CP1 <br> (TONER) and the PWBA MCU F <br> Is there conductivity on each wire between P/J127 <=> P/ <br> J419? | Go to step 5. | Fix open and <br> short circuit. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 5 | Checking +5 VDC power supply to the PWBA CRUM CP1 <br> (TONER) <br> Is the voltage across P127-6 (+) <<> ground +5 VDC? | Replace the <br> PWBA CRUM <br> CP1 (TONER). <br> (RRP 5.4) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Toner Cartridge CRUM ID fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> CRU (PL 5.1.15) <br> PWBA CRUM CP1 (TONER) (PL 5.1.8) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the CRU for installation Is the CRU installed surely? | Go to step 2. | Install the CRU surely. |
| 2 | Checking the PWBA CRUM CP1 (TONER) for installation Is the PWBA CRUM CP1 (TONER) installed correctly? | Go to step 3. | Install the PWBA CRUM CP1 (TONER) correctly. |
| 3 | Checking the PWBA CRUM CP1 (TONER) for connection Are P/J127 and P/J419 connected surely? | Go to step 4. | Connect P/J127 and P/J419 surely. |
| 4 | Checking conductivity between the PWBA CRUM CP1 (TONER) and the PWBA MCU F Is there conductivity on each wire between P/J127 <=> P/ J419? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking +5 VDC power supply to the PWBA CRUM CP1 (TONER) <br> Is the voltage across P127-6 (+) <=> ground +5 VDC? | Replace the PWBA CRUM CP1 (TONER). (RRP 5.4) | Replace the PWBA MCU F. (RRP 8.4) |

## Main Motor stop error

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> MOTOR ASSY 242 (PL 7.1.7) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | Install the CRU <br> surely. |
| 1 | Checking the MOTOR ASSY 242 for installation <br> Is the MOTOR ASSY 242 installed surely? <br> Open the COVER REAR UPR (PL 1.2.5) and check it. | ( |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 2 | Checking the MOTOR ASSY 242 for operation <br> Execute [Output 04-01 MAIN MOTOR ON] in Chapter 2 <br> [Diagnostic]. <br> Open the COVER REAR UPR (PL 1.2.5) and check it. | Go to step 6. | Go to step 3. |
| 3 | Checking the MOTOR ASSY 242 for connection <br> Are P/J214 and P/J408 connected surely? | Go to step 4. | Connect P/J214 <br> and P/J408 <br> surely. |
| 4 | Checking conductivity between the MOTOR ASSY 242 <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J214 <=> P/ <br> J408? | Go to step 5. | Fix open and <br> short circuit. |
| 5 | Checking +24 VDC power supply to the MOTOR ASSY <br> 242 <br> Are the voltages across P/J214-1/-2 (+) <=> ground +24 <br> VDC? | Replace the <br> MOTOR ASSY <br> 242. (RRP 7.2) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |
| 6 | Checking the ROM version <br> Check the ROM version. <br> Is the ROM version latest? | Replace the <br> PWBA MCU F. <br> (RRP) | Upgrade the ROM <br> to the latest ver- <br> sion. |

## Image Ready error

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> PWBA ESS (PL 8.1.25) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the ROM version Check the ROM version. Is the ROM version latest? | Go to step 2. | Upgrade the ROM to the latest version. |
| 2 | Checking the PWBA ESS for connection. Are P/J402 and P/J301 connected surely? | Go to step 3. | Connect P/J402 and P/J301 surely. |
| 3 | Checking the PWBA ESS for operation Disconnect all the connectors from the PWBA ESS and reconnect them. <br> Does the error still occur? | Replace the PWBA ESS. | Replace the PWBA MCU F. (RRP 8.4) |

## Main Motor fail

| Step | Check | Yes | No |
| :--- | :--- | :---: | :---: |
|  | Possible causative parts: <br> MOTOR ASSY 242 (PL 7.1.7) <br> PWBA MCU F (PL 8.1.5) |  |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking the MOTOR ASSY 242 for operation (1) <br> Does the MOTOR ASSY 242 operate properly? <br> Execute [Output 04-01 MAIN MOTOR ON] in Chapter 2 <br> [Diagnostic]. <br> Open the COVER REAR UPR (PL 1.2.5) and check it. | Go to step 2. | Go to step 3. |
| 2 | Checking the MOTOR ASSY 242 for installation <br> Is the MOTOR ASSY 242 installed securely? <br> Open the COVER REAR UPR (PL 1.2.5) and check it. | Reconnect the <br> connector of the <br> PWBA MCU F. | Install the <br> MOTOR ASSY <br> 242 securely. |
| 3 | Checking the rotation of the rotor of the MOTOR ASSY <br> 242 <br> Can the rotor be rotated by hand without excessive load? <br> Open the COVER REAR UPR (PL 1.2.5) and check it. | Go to step 4. | Install the <br> MOTOR ASSY <br> 242 surely. |
| 4 | Checking the MOTOR ASSY 242 for connection <br> Are P/J214 and P/J408 connected surely? | Go to step 5. | Connect P/J214 <br> and P/J408 <br> surely. |
| 5 | Checking conductivity between the MOTOR ASSY 242 <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J214 <=> P/ <br> J408? | Go to step 6. | Fix open and <br> short circuit. |
| 6 | Checking +24 VDC power supply to the MOTOR ASSY <br> 242 <br> Are the voltages across P214-1/-2 (+) <=> ground +24 <br> VDC? | Replace the <br> MOTOR ASSY <br> 242. (RRP 7.2) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Drum Motor fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| Possible causative parts: <br> CRU (PL 5.1.15) <br> MOTOR ASSY 242 (PL 7.1.7) <br> PWBA MCU F (PL 8.1.5) | Checking the CRU for installation <br> Is the CRU installed securely? | Checking the MOTOR ASSY 242 for operation (1) <br> Does the MOTOR ASSY 242 operate properly? <br> Execute [Output 08-04 DRUM MOTOR ON] in Chapter 2 <br> [Diagnostic]. <br> Open the COVER REAR UPR (PL 1.2.5) and check it. | Go to step 3. | Go to step 4.


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 5 | Checking the MOTOR ASSY 242 for connection <br> Are P/J214 and P/J408 connected surely? | Go to step 6. <br> and P/J408 <br> surely. |  |
| 6 | Checking conductivity between the MOTOR ASSY 242 <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J214 <=> P/ <br> J408? | Go to step 7. | Fix open and <br> short circuit. |
| 7 | Checking +24 VDC power supply to the MOTOR ASSY <br> 242 <br> Are the voltages across P214-1/-2 (+) <=> ground +24 <br> VDC? | Replace the <br> MOTOR ASSY <br> 242. (RRP 7.2) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Laser Power fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: ROS ASSY-12 (PL 5.1.14) PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the ROSS ASSY -12 for installation Is the ROSS ASSY-12 installed securely? | Go to step 2. | Install the ROS ASSY-12 securely. |
| 2 | Checking the ROSS ASSY-12 for connection Are P/J140 and P/J406 connected surely? | Go to step 3. | Connect P/J140 and P/J406 surely. |
| 3 | Checking conductivity between the ROS ASSY-12 and the PWBA MCU F <br> Is there conductivity on each wire between P/J140 <=> P/ J406? | Go to step 4. | Fix open and short circuit. |
| 4 | Checking +5 VDC power supply to the ROS ASSY-12 Is the voltage across P140-8 (+) <=> ground +5 VDC? | Replace the ROS ASSY-12. (RRP 5.8) | Replace the PWBA MCU F. (RRP 8.4) |

## ROS Motor fail

| Step | Check | Yes | No |
| :--- | :--- | :---: | :---: |
|  | Possible causative parts: <br> MOTOR ASSY-DISP 30K (PL 5.1.11) <br> ROS ASSY-12 (PL 5.1.14) <br> PWBA MCU F (PL 8.1.5) |  |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking the MOTOR ASSY-DISP 30K for operation <br> Does the MOTOR ASSY-DISP 30K operate properly? <br> Execute [Output 06-15 ROS MOTOR ON] in Chapter 2 <br> [Diagnostic]. | Go to step 4. | Go to step 2. |
| 2 | Checking the MOTOR ASSY-DISP 30K for connection <br> Are P/J216 and P/J420 connected surely? | Go to step 3. | Connect P/J216 <br> and P/J420 <br> surely. |
| 3 | Checking +24 VDC power supply to the MOTOR ASSY- <br> DISP 30K <br> Is the voltage across J216-1 (+) <=> ground +24 VDC? | Replace the <br> MOTOR ASSY- <br> DISP 30K. (RRP <br> $5.6)$ | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |
| 4 | Checking the ROSS ASSY -12 for installation <br> Is the ROSS ASSY-12 installed securely? | Go to step 5. | Install the ROS <br> ASSY-12 <br> securely. |
| 5 | Checking the ROSS ASSY-12 for connection <br> Are P/J130, P/J620 and P/J406 connected surely? | Go to step 6. | Connect P/J130, <br> P/J620 and P/ <br> J406 surely. |
| 6 | Checking conductivity between the ROS ASSY-12 and the <br> PWBA MCU F <br> Is there conductivity on each wire between P/J130 <=> P/ <br> J406? | Go to step 7. | Fix open and <br> short circuit. |
| 7 | Checking +24 VDC power supply to the ROS ASSY-12 <br> Is the voltage across J130-5 (+) <=> ground +24 VDC? | Replace the ROS <br> ASSY-12. (RRP <br> $5.8)$ | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Fuser On Time fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> FUSER ASSY (PL 6.1.7) <br> PWBA MCU F (PL 8.1.5) | Remove the <br> paper. | Go to step 2. |
| 1 | Checking the FUSER ASSY for paper jam <br> Is there a paper jam in the FUSER ASSY? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 3. | Install the FUSER <br> ASSY securely. |
| 2 | Checking the FUSER ASSY for installation <br> Is the FUSER ASSY installed securely? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 4. <br> Replace the <br> FUSER ASSY. <br> (RRP 6.2) |  |
|  | Checking conductivity between the junction connector pins <br> of the FUSER ASSY <br> Is there conductivity on each pin between the junction con- <br> nector pins? <br> Remove the FUSER ASSY and check it. <br> WARNING! Start the operation after the FUSER ASSY <br> has cooled down. |  |  |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 4 | Checking the resistance of the FUSER ASSY (1) Is the resistance of the MAIN LAMP across P/J600-1 and P/J600-11 less than or equal to 100 ohm? | Go to step 5. | Replace the FUSER ASSY. (RRP 6.2) |
| 5 | Checking the resistance of the FUSER ASSY (2) Is the resistance of the SUB LAMP1 across P/J600-4 and P/J600-11 less than or equal to 100 ohm? | Go to step 6. | Replace the FUSER ASSY. (RRP 6.2) |
| 6 | Checking the resistance of the FUSER ASSY (3) Is the resistance of the SUB LAMP2 across P/J600-7 and P/J600-11 less than or equal to 100 ohm? | Go to step 7 | Replace the FUSER ASSY. (RRP 6.2) |
| 7 | Checking the resistance of the FUSER ASSY (4) Is there a disconnection in the Center STS between P/ J131-1 and P/J131-2? <br> Is the resistance of the Center STS across P/J131-1 and P/J131-2 more than or equal to 3 k -ohm? | Go to step 8. | Replace the FUSER ASSY. (RRP 6.2) |
| 8 | Checking the resistance of the FUSER ASSY (5) Is there a disconnection in the 2nd STS between P/J132-1 and P/J132-2? <br> Is the resistance of the 2 nd STS more than or equal to 3 k ohm? | Go to step 9. | Replace the FUSER ASSY. (RRP 6.2) |
| 9 | Checking the resistance of the FUSER ASSY (6) Is there a disconnection in the Rear STS between P/J1331 and P/J133-2? Is the resistance of the Rear STS across P/J133-1 and P/ J133-2 more than or equal to 3 k -ohm? | Go to step 10. | Replace the FUSER ASSY. (RRP 6.2) |
| 10 | Checking the FUSER ASSY for connection Is P/J6 connected surely? | Go to step 11. | Connect P/J6 surely. |
| 11 | Checking conductivity between the FUSER ASSY and the POWER UNIT <br> Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 600<=>\mathrm{P} /$ J6? | Go to step 12. | Fix open and short circuit. |
| 12 | Checking power supply to the FUSER ASSY Is a voltage equivalent to the power voltage applied between the following pins? $\begin{aligned} & \text { P6-1 <=> P6-2 } \\ & \text { P6-1 <=> P6-3 } \\ & \text { P6-1 <=> P6-4 } \end{aligned}$ | Replace the FUSER ASSY. (RRP 6.2) | Go to step 13. |
| 13 | Checking between the Power Unit and the PWBA MCU F for connection. <br> Are P/J401 and P/J525 connected securely? | Replace the PWBA MCU F. (RRP 8.8) | $\begin{aligned} & \text { Connect P/J401 } \\ & \text { and P/J525 } \\ & \text { Securely } \end{aligned}$ |

## Over Heat Temp fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> FUSER ASSY (PL 6.1.7) <br> PWBA MCU F (PL 8.1.5) |  |  |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking the FUSER ASSY for installation Is the FUSER ASSY installed securely? Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 2. | Install the FUSER ASSY securely. |
| 2 | Checking the resistance of the FUSER ASSY (1) Is there a disconnection in the Center STS between J131-1 and J131-2? <br> Is the resistance of the Center STS across J131-1 and J131-2 more than or equal to 3 k -ohm? | Go to step 3. | Replace the FUSER ASSY. (RRP 6.2) |
| 3 | Checking the resistance of the FUSER ASSY (2) Is there a disconnection in the 2nd STS between J132-1 and J132-2? <br> Is the resistance of the 2nd STS across J132-1 and J132-2 more than or equal to 3 k -ohm? | Go to step 4. | Replace the FUSER ASSY. (RRP 6.2) |
| 4 | Checking the resistance of the FUSER ASSY (3) Is there a disconnection in the Rear STS between J133-1 and J133-2? <br> Is the resistance of the Rear STS across J133-1 and J1332 more than or equal to 3 k -ohm? | Go to step 5. | Replace the FUSER ASSY. (RRP 6.2) |
| 5 | Checking the FUSER ASSY for connection (1) Is P/J6 connected surely? | Go to step 6. | Connect P/J6 surely. |
| 6 | Checking the FUSER ASSY for connection (2) Are P/J410, P/J607, P/J600, P131, P132 and P133 connected surely? | Go to step 7. | $\begin{aligned} & \text { Connect P/J410, } \\ & \text { P/J607, P/J600, } \\ & \text { P131, P132 and } \\ & \text { P133 surely } \end{aligned}$ |
| 7 | Checking conductivity between the FUSER ASSY and the POWER UNIT <br> Is there conductivity on each wire between P/J600 <=> P/ J6? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking power supply to the FUSER ASSY Is a voltage equivalent to the power voltage applied between the following pins? $\begin{aligned} & \text { P6-1 <=> P6-2 } \\ & \text { P6-1 <=> P6-3 } \\ & \text { P6-1 <=> P6-4 } \end{aligned}$ | Replace the FUSER ASSY. (RRP 6.2) | Go to step 9. |
| 9 | Checking connection between the POWER UNIT and the PWBA MCU F <br> Are P/J401 and P/J525 connected surely? | Replace the PWBA MCU F. (RRP 8.4) | Connect P/J401 and P/J525 surely. |

## Center STS fail

| Step | Check | Yes | No |
| :---: | :--- | :--- | :--- |
|  | Possible causative parts: <br> FUSER ASSY (PL 6.1.7) <br> PWBA MCU F (PL 8.1.5) |  |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking the FUSER ASSY for installation <br> Is the FUSER ASSY installed securely? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 2. | Install the FUSER <br> ASSY securely. |
| 2 | Checking the FUSER CONTROL SENSOR (FS1) for <br> operation <br> Does the Input Status change each time the FUSER ASSY <br> is installed or removed? | Go to step 4. |  |
| Execute [Input 10-20 FUSER CONTROL SENSOR (FS1)] |  |  |  |
| in Chapter 2 [Diagnostic]. |  |  |  |$\quad$ Go to step 3.

## REAR STS fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: FUSER ASSY (PL 6.1.7) PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the FUSER ASSY for installation Is the FUSER ASSY installed securely? Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 2. | Install the FUSER ASSY securely. |
| 2 | Checking the FUSER CONTROL SENSOR (FS2) for operation <br> Does the Input Status change each time the FUSER ASSY is installed or removed? <br> Execute [Input 10-21 FUSER CONTROL SENSOR (FS2)] in Chapter 2 [Diagnostic]. | Go to step 4. | Go to step 3. |
| 3 | Checking the resistance of the FUSER ASSY Is there a disconnection in the REAR STS between J132-1 and J132-2? <br> Is the resistance of the REAR STS across J132-1 and J132-2 more than or equal to 3 k -ohm? | Go to step 4. | Replace the FUSER ASSY. (RRP 6.2) |
| 4 | Checking the FUSER ASSY for connection Are P/J410, P/J607, P/J600 and P132 connected surely? | Replace the PWBA MCU F. (RRP 8.4) | Connect P/J410, P/J607, P/J600 and P132 surely. |

## PIR STS fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: FUSER ASSY (PL 6.1.7) PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the FUSER ASSY for installation Is the FUSER ASSY installed securely? Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 2. | Install the FUSER <br> ASSY securely. |
| 2 | Checking the FUSER CONTROL SENSOR (PR) for operation <br> Does the Input Status change each time the FUSER ASSY is installed or removed? <br> Execute [Input 10-22 FUSER CONTROL SENSOR (PR)] in Chapter 2 [Diagnostic]. | Go to step 4. | Go to step 3. |
| 3 | Checking the resistance of the FUSER ASSY Is there a disconnection in the P/R STS between J133-1 and J133-2? <br> Is the resistance of the P/R STS across J133-1 and J133-2 more than or equal to 3 k -ohm? | Go to step 4. | Replace the FUSER ASSY. (RRP 6.2) |
| 4 | Checking the FUSER ASSY for connection Are P/J410, P/J607, P/J600 and P133 connected surely? | Replace the PWBA MCU F. (RRP 8.4) | $\begin{aligned} & \text { Connect P/J410, } \\ & \text { P/J607, P/J600 } \\ & \text { and P133 surely. } \end{aligned}$ |

## Cold-Sagging recovery fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> FUSER ASSY (PL 6.1.7) <br> POWER UNIT (PL 8.1.8) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | Remove the <br> paper. |
| 1 | Checking the FUSER ASSY for paper jam <br> Is there a paper jam in the FUSER ASSY? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 3. | Install the FUSER <br> ASSY securely. |
| 2 | Checking the FUSER ASSY for installation <br> Is the FUSER ASSY installed securely? <br> Open the COVER ASSSY-LH (PL 4.2.8) and check it. | Go to step 5. | Go to step 4. |
| 3 | Checking the FUSER CONTROL SENSOR (FSS1) for <br> operation <br> Does the Input Status change each time the FUSER ASSY <br> is installed or removed? <br> Execute [Input 10-20 FUSER CONTROL SENSOR (FS1)] <br> in Chapter 2 [Diagnostic]. |  |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 4 | Checking the resistance of the FUSER ASSY <br> Is there a disconnection in the Center STS between J131-1 <br> and J131-2? <br> Is the resistance of the Rear STS across J131-1 and J131- <br> 2 more than or equal to 3 k-ohm? | Go to step 7. | Replace the <br> FUSER ASSY. <br> (RRP 6.2) |
| 5 | Checking the FUSER CONTROL SENSOR (PR) for <br> operation <br> Does the Input Status change each time the FUSER ASSY <br> is installed or removed? <br> Execute [Input 10-22 FUSER CONTROL SENSOR (PR)] <br> in Chapter 2 [Diagnostic]. | Go to step 7. | Go to step 6. |
| 6 | Checking the resistance of the FUSER ASSY <br> Is there a disconnection in the P/R STS between J133-1 <br> and J133-2? <br> Is the resistance of the P/R STS across J133-1 and J133-2 <br> more than or equal to 3 k-ohm? | Go to step 7. | Replace the <br> FUSER ASSY. <br> (RRP 6.2) |
| 7 | Checking the FUSER ASSY for connection (1) <br> Is P/J6 connected surely? | Go to step 8. | Connect P/J66 <br> surely. |
| 8 | Checking the FUSER ASSY for connection (2) <br> Are P/J410, P/J607, P/J600, P131 and P133 connected <br> surely? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | Connect P/J410, <br> P/J607, P/J600, <br> P131 and P133 <br> surely. |

## Hot-Sagging recovery fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> FUSER ASSY (PL 6.1.7) <br> POWER UNIT (PL 8.1.8) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | Remove the <br> paper. |
| 1 | Checking the FUSER ASSY for paper jam <br> Is there a paper jam in the FUSER ASSY? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 3. | Install the FUSER <br> ASSY securely. |
| 2 | Checking the FUSER ASSY for installation <br> Is the FUSER ASSY installed securely? <br> Open the COVER ASSSY-LH (PL 4.2.8) and check it. | Go to step 5. | Go to step 4. |
| 3 | Checking the FUSER CONTROL SENSOR (FS1) for <br> operation <br> Does the Input Status change each time the FUSER ASSY <br> is installed or removed? <br> Execute [Input 10-20 FUSER CONTROL SENSOR (FS1)] <br> in Chapter 2 [Diagnostic]. |  |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 4 | Checking the resistance of the FUSER ASSY <br> Is there a disconnection in the Center STS between J131-1 <br> and J131-2? <br> Is the resistance of the Rear STS across J131-1 and J131- <br> 2 more than or equal to 3 k-ohm? | Go to step 7. | Replace the <br> FUSER ASSY. <br> (RRP 6.2) |
| 5 | Checking the FUSER CONTROL SENSOR (PR) for <br> operation <br> Does the Input Status change each time the FUSER ASSY <br> is installed or removed? <br> Execute [Input 10-22 FUSER CONTROL SENSOR (PR)] <br> in Chapter 2 [Diagnostic]. | Go to step 7. | Go to step 6. |
| 6 | Checking the resistance of the FUSER ASSY <br> Is there a disconnection in the P/R STS between J133-1 <br> and J1332? <br> Is the resistance of the P/R STS across J133-1 and J133-2 <br> more than or equal to 3 k-ohm? | Go to step 7. | Replace the <br> FUSER ASSY. <br> (RRP 6.2) |
| 7 | Checking the FUSER ASSY for connection (1) <br> Is P/J6 connected surely? | Go to step 8. | Connect P/J6 <br> surely. |
| 8 | Checking the FUSER ASSY for connection (2) <br> Are P/J410, P/J607, P/J600, P131 and P133 connected <br> surely? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | Connect P/J410, <br> P/J607, P/J600, <br> P131 and P133 <br> surely. |

## Fuser Fan fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> FAN FUSER (PL 5.1.13) <br> MOTOR ASSY 242 (PL 7.1.7) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | Install the FAN <br> FUSER securely. |
| 1 | Checking the FAN FUSER for installation <br> Is the FAN FUSER installed securely? | Go to step 7. | Go to step 3. |
| 2 | Checking the FAN FUSER for rotation <br> Does the FAN FUSER rotate? (Visual check) | Go to step 7. <br> Checking the FAN FUSER for operation (1) <br> Execute FAN FUSER operate properly? <br> SPEED)] in Chapter 2 [Diagnostic]. | Go to step 4. |
| 4 | Checking the FAN FUSER for operation (2) <br> Is CN102 connected surely? | Go to step 5. | Connect CN102 <br> surely. |
| 5 | Checking conductivity between the MOTOR ASSY 242 <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J214 <=> P/ <br> J408? | Go to step 6. | Fix open and <br> short circuit. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 6 | Checking +24 VDC power supply to the FAN FUSER <br> Is the voltage across P/J214-1 (+) <=> ground +24 VDC? | Go to step 7. | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |
| 7 | Checking the FAN FUSER for operation (1) <br> Does the FAN FUSER receive the signal? <br> Execute [Input 10-60 FUSER FAN MOTOR SIGNAL] in <br> Chapter 2 [Diagnostic]. | Replace the FAN <br> FUSER. (RRP <br> 5.7) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Dispense Motor fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TONER CARTRIDGE (PL 5.1.16) <br> GUIDE ASSY CTG30 SUB (PL 5.1.10) <br> MOTOR ASSY-DISP 30K (PL 5.1.11) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the TRAY CARTRIDGE for installation Remove the TONER CARTRIDGE and reinstall it. Does it operate properly? | End of work | Go to step 2. |
| 2 | Checking the rotation of the gear of the GUIDE ASSY CTG30 SUB <br> Does the gear located at the lower part of the GUIDE ASSY CTG30 SUB rotate smoothly? | Go to step 3. | Replace the obstacle part for rotation. |
| 3 | Checking the GUIDE ASSY CTG30 SUB for pipe clogging Is the pipe located at the lower part of the GUIDE ASSY CTG30 SUB clogged? | Go to step45. | Clean the pipe. |
| 4 | Checking the MOTOR ASSY-DISP 30K for operation Is the MOTOR ASSY-DISP 30K operated? <br> Execute [Output 15-63 Dispense Motor] in Chapter 2 [Diagnostic]. | Reconnect the connector of the PWBA MCU F. | Go to step 5. |
| 5 | Checking the MOTOR ASSY-DISP 30K for connection Are P/J216 and P/J420 connected surely? | Go to step 6. | Connect P/J216 and P/J420 securely |
| 6 | Checking conductivity between the MOTOR ASSY-DISP 30K and the PWBA MCU F <br> Is there conductivity on each wire between P/J216 <=> P/ J420? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +24 VDC power supply to the MOTOR ASSYDISP 30K <br> Is the voltage across J216-1 (+) <=> ground +24 VDC? | Replace the MOTOR ASSYDISP 30K. (RRP 5.6) | Replace the PWBA MCU F. (RRP 8.4) |

RAM read/write Check fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Does an error occur when the power is turned OFF/ON? | Go to step 2. | End of work |
| 2 | Does an error occur when the power is turned ON again? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | End of work |

## NVM data defect

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> PWBA MCU F (PL 8.1.5) | Go to step 3. | Go to step 2. |
| 1 | Does an error occur when the power is turned ON again? | Go to step 3. | End of work |
| 2 | Does the error still occur after the power is turned ON/OFF <br> repeatedly several times? | Go to step 4. <br> Is data on the NVRAM accessible? <br> Execute [NVM Edit] in Chapter 2 [Diagnostic]. | Contact a Techni- <br> cal Engineer |
| 4 | Checking data on the NVRAM (2) <br> Change NVRAM data to the correct setup value, and then <br> turn the power ON again. <br> Does the error still occur? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | End of work |

## NVM read/write cannot be executed

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> PWBA MCU F (PL 8.1.5) | Go to step 3. | Go to step 2. |
| 1 | Does an error occur when the power is turned ON again? | Go to step 3. | End of work |
| 2 | Does the error still occur after the power is turned ON/OFF <br> repeatedly several times? | Go to step 4. | Contact a Techni- <br> cal Engineer |
| 3 | Checking data on the NVRAM (1) <br> Is data on the NVRAM accessible? <br> Execute [NVM Edit] in Chapter 2 [Diagnostic]. | Checking data on the NVRAM (2) <br> Change NVRAM data to the correct setup value, and then <br> turn the power ON again. Does the error still occur? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |
| End of work |  |  |  |

## CPU Power to access NVM is not enough

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Possible causative parts: <br> PWBA MCU F (PL 8.1.5) | Does the error occur when the power is turned ON again? | Go to step 3. |
| 2 | Does the error still occur after the power is turned ON/OFF <br> repeatedly several times? | Go to step 2. |  |
| 3 | Checking data on the NVRAM (1) <br> Is data on the NVRAM accessible? <br> Execute [NVM Edit] in Chapter 2 [Diagnostic]. | End of work |  |
| 4 | Checking data on the NVRAM (2) <br> Change NVRAM data to the correct setup value, and then <br> turn the power ON again. Does the error still occur? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | End of work |
| 5 | Checking the ROM version <br> Check the ROM version. <br> Is the ROM version latest? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | Upgrade the ROM <br> to the latest ver- <br> sion. |

## CRUM ASIC fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | End of work |
| 1 | Does an error occur when the power is turned OFF/ON? | Go to step 3. | Connect P/J419, <br> P/J126 and P/ <br> J 127 surely. |
| 2 | Checking the PWBA MCU F for connection <br> Are P/J419, P/J126 and P/J127 connected surely? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | End of work |
| 3 | Does the error occur when the power is turned ON again? |  |  |

## The PPM information is defect

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Does the error occur when the power is turned ON again? | Go to step 3. | Go to step 2. |
| 2 | Does the error still occur after the power is turned ON/OFF <br> repeatedly several times? | Go to step 3. | End of work |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 3 | Checking data on the NVRAM (1) <br> Is data on the NVRAM accessible? <br> Execute [NVM Edit] in Chapter 2 [Diagnostic]. | Go to step 4. | Go to step 5. |
| 4 | Checking data on the NVRAM (2) <br> Change NVRAM data to the correct setup value, and then <br> turn the power ON again. Does the error still occur? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | End of work |
| 5 | Checking the ROM version <br> Check the ROM version. <br> Is the ROM version latest? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | Upgrade the ROM <br> to the latest ver- <br> sion. |

## CRU Fan defect

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> CRU FAN (PL 5.1.18) <br> PWBA MCU F (PL 8.1.5) | Go to step 7. | Go to step 2. |
| 1 | Checking the CRU FAN for rotation <br> Is the CRU FAN FUSER rotating? (Visual check) | Checking the CRU FAN <br> Is there any object blocking CRU FAN rotation? | Remove the <br> object blocking <br> the rotation. |
| 3 | Checking the CRU FAN for operation <br> Does the CRU FAN operate properly? <br> Check it using [Output 04-03 CRU FAN MOTOR ON] in <br> Chapter 2, Diag. | Geconnect the step 3. <br> connector of the <br> PWBA MCU F. | Go to step 4. |
| 4 | Checking the CRU FAN for connection <br> Is the harness connector of the CRU FAN connected to the <br> junction connector P/J221 securely? | Go to step 5. | Connect the har- <br> ness connector of <br> the CRU FAN <br> surely. |
| 5 | Checking the PWBA MCU F for connection <br> Is P407 connected surely? | Connect P407 <br> securely |  |
| 6 | Checking conductivity between the PWBA MCU F and the <br> junction connector P/J221 <br> Is there conductivity on each wire between P407 <=> P/ <br> J221? | Go to step 7. | Fix open and <br> short circuit. |
| 7 | Checking +24 VDC power supply to the CRU FAN <br> Is the voltage across J407-1 (+) <=> ground +24 VDC? | Replace the CRU <br> FAN. (RRP 5.10) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## OCT1 Defect

| Step | Check | Yes | No |
| :--- | :--- | :--- | :---: |
|  | Possible causative parts: <br> SENSOR-PHOTO IN (PL 6.2.5) <br> MOTOR ASSY-OFFSET (PL 6.2.3) <br> PWBA EXIT (PL 8.1.4) | Checking the SENSOR-PHOTO IN for operation <br> Does the Input Status change from "0x0" to "0x1" each <br> time the paper touches the SENSOR-PHOTO? <br> Check it using [Input 07-033 OCT1 HOME POSITION <br> SENSOR] in Chapter 2 [Diagnostic]. | Go to step 5. | Go to step 2.

## Tray1 Size sensor broken

| Step | Check | Yes | No |
| :--- | :--- | :--- | :--- |
|  | Possible causative parts: <br> SWWITCH ASSY P S (PL 2.1.4) <br> PWBA MCU F (PL 8.1.5) |  |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking the paper <br> Is paper loaded in the Tray1 properly? <br> Pull out the Tray1 to check it. (Visual check) | Go to step 2. | Load paper prop- <br> erly. |
| 2 | Checking the SWITCH ASSY P S for the TRAY1 for <br> installation <br> Is the SWITCH ASSY P S for the TRAY1 installed <br> correctly? <br> Pull out the TRAY1 to check it. (Visual check) | Go to step 3. | Reinstall the <br> SWITCH ASSY P <br> S for TRAY1. |
| 3 | Checking the SWITCH ASSY P S for the TRAY1 for <br> operation <br> Does the Input Status change each time the TRAY1 with <br> paper loaded is pulled out and pushed in? <br> Check it using [Input 07-01 TRAY1 SIZE SENSOR] in <br> Chapter 2, Diag. | Reconnect the <br> connector of the <br> PWBA MCU F. | Go to step 4. |
| 4 | Checking the TRAY1 SWITCH ASSY P S for connection <br> Are P/J109 and P/J412 connected surely? | Go to step 5. | Connect P/J109 <br> and P/J412 <br> securely |
| 5 | Checking conductivity between the TRAY1 SWITCH ASSY <br> P S and the PWBA MCU F <br> Is there conductivity on each wire between P/J109 <=> P/ | Go to step 6. | Fix open and <br> short circuit. |
| P/J412? | Checking +5 VDC power supply to the TRAY1 SWITCH <br> ASSY P S <br> Is the voltage across J109-1 (+) <=> ground +5 VDC? | Replace the <br> SWITCH ASSY P <br> S for TRAY1. <br> (RRP 2.1) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray2 Size sensor broken

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SWITCH ASSY P S (PL 2.1.4) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper Is paper loaded in the Tray2 properly? Pull out the Tray2 to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the SWITCH ASSY P S for the TRAY2 for installation <br> Is the SWITCH ASSY P S for the TRAY2 installed correctly? <br> Pull out the TRAY2 to check it. (Visual check) | Go to step 3. | Reinstall the SWITCH ASSY P S for TRAY2. |
| 3 | Checking the SWITCH ASSY P S for the TRAY2 for operation <br> Does the Input Status change each time the TRAY2 with paper loaded is pulled out and pushed in? <br> Check it using [Input 07-02 TRAY2 SIZE SENSOR] in Chapter 2, Diag. | Reconnect the connector of the PWBA MCU F. | Go to step 4. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 4 | Checking the SWITCH ASSY P S for TRAY2for connection <br> Are P/J110 and P/J412 connected surely? | Go to step 5. | Connect P/J110 <br> and P/J412 <br> securely |
| 5 | Checking conductivity between the SWITCH ASSY P S for <br> TRAY2and the PWBA MCU F <br> Is there conductivity on each wire between P/J110 <=> P/ <br> P/J412? | Go to step 6. | Fix open and <br> short circuit. |
| 6 | Checking +5 VDC power supply to the SWITCH ASSY P S <br> for TRAY2 <br> Is the voltage across J110-1 (+) <=> ground +5 VDC? | Replace the <br> SWITCH ASSY P <br> S for TRAY2. <br> (RRP 2.2) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## L/H Cover Assembly open

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SWITCH (PL 4.2.4) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the COVER ASSY-LH (PL 4.2.8) for opening and closing <br> Does the COVER ASSY-LH (PL 4.2.8) open or close normally? | Go to step 2. | Check the COVER ASSYLH for deformation and reinstall it. |
| 2 | Checking the SWITCH for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the SWITCH is pressed? <br> Execute [Input 01-01 L/H COVER] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Reconnect the connector of the PWBA MCU F. | Go to step 3. |
| 3 | Checking the SWITCH for connection Are P/J120 and P/J405 connected surely? | Go to step 4. | Connect P/J120 and P/J405 surely. |
| 4 | Checking conductivity between the SWITCH and the PWBA MCU F <br> Is there conductivity on each wire between P/J120 <=> P/ J405? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking +24 VDC power supply to the SWITCH Is the voltage across J120-B1 (+) <=> ground +24 VDC? | Replace the SWITCH. | Replace the PWBA MCU F. (RRP 8.4) |

## IOT Front Cover open

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: SWITCH (PL 1.1.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the COVER ASSY FRONT (PL 1.1.9) for opening and closing <br> Does the COVER ASSY FRONT (PL 1.1.9) open or close normally? | Go to step 2. | Check the COVER ASSY FRONT for deformation and reinstall it. |
| 2 | Checking the SWITCH for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the SWITCH is pressed? <br> Execute [Input 01-12 FRONT COVER] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY FRONT (PL 1.1.9) and check it. | Reconnect the connector of the PWBA MCU F. | Go to step 3. |
| 3 | Checking the SWITCH for connection Are P/J121 and P/J405 connected surely? | Go to step 4. | Connect P/J121 and P/J405 surely. |
| 4 | Checking conductivity between the SWITCH and the PWBA MCU F <br> Is there conductivity on each wire between P/J121 <=> P/ J405? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking +24 VDC power supply to the SWITCH Is the voltage across J121-B1 (+) <=> ground +24 VDC? | Replace the SWITCH. (RRP 1.3) | Replace the PWBA MCU F. (RRP 8.4) |

## L/H-L Cover open

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SWITCH-I/L, CAB (PL 4.1.3) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the COVER ASSY LH LOW C (PL 4.1.10) for opening and closing <br> Does the COVER ASSY LH LOW C (PL 4.1.10) open or close normally? | Go to step 2. | Check the COVERASSYLH LOW C for deformation and reinstall it. |
| 2 | Checking the SWITCH-I/L, CAB for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each <br> time the SWITCH-I/L, CAB is pressed? <br> Execute [Input 01-11 L/H Low COVER] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check it. | Reconnect the connector of the PWBA MCU F. | Go to step 3. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 3 | Checking the SWITCH-I/L, CAB for connection <br> Are P/J106 and P/J410 connected surely? | Go to step 4. | Connect P/J106 <br> and P/J410 <br> surely. |
| 4 | Checking conductivity between the SWITCH-I/L, CAB and <br> the PWBA MCU F <br> Is there conductivity on each wire between P/J106 <=> P/ <br> J410? | Go to step 5. | Fix open and <br> short circuit. |
| 5 | Checking +5 VDC power supply to the SWITCH-I/L, CAB <br> Is the voltage across J106-2 ( + \ll=> ground +5 VDC? | Replace the <br> SWITCH-I/L, <br> CAB. (RRP 4.2) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Toner Cartridge was PRENEAR empty

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TONER CARTRIDGE (PL 5.1.16) <br> GUIDE ASSY CTG30 SUB (PL 5.1.10) <br> MOTOR ASSY-DISP 30K (PL 5.1.11) <br> PWBA CRUM CP1 (TONER) (PL 5.1.8) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking remaining toner <br> Does the TONER CARTRIDGE contain sufficient toner? | Go to step 2. | Replace the TONER CARTRIDGE. |
| 2 | Checking the TRAY CARTRIDGE for installation Remove the TONER CARTRIDGE and reinstall it. Does it operate properly? | End of work | Go to step 3. |
| 3 | Checking the rotation of the gear of the GUIDE ASSY CTG30 SUB <br> Does the gear located at the lower part of the GUIDE ASSY CTG30 SUB rotate smoothly? | Go to step 4. | Replace the obstacle part for rotation. |
| 4 | Checking the GUIDE ASSY CTG30 SUB for pipe clogging Is the pipe located at the lower part of the GUIDE ASSY CTG30 SUB clogged? | Go to step 5. | Clean the pipe. |
| 5 | Checking the MOTOR ASSY-DISP 30K for operation Is he MOTOR ASSY-DISP 30K operated? <br> Execute [Output 15-63 Dispense Motor] in Chapter 2 [Diagnostic]. | Reconnect the connector of the PWBA MCU F. | Go to step 6. |
| 6 | Checking the MOTOR ASSY-DISP 30K for connection Are P/J216 and P/J420 connected surely? | Go to step 7. | Connect P/J216 and P/J420 surely. |
| 7 | Checking conductivity between the MOTOR ASSY-DISP 30K and the PWBA MCU F <br> Is there conductivity on each wire between P/J216 <=> P/ J420? | Go to step 8. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 8 | Checking +24 VDC power supply to the MOTOR ASSY- <br> DISP 30K <br> Is the voltage across J216-1 (+) <=> ground +24 VDC? | Replace the <br> MOTOR ASSY- <br> DISP 30K. (RRP <br> $5.6)$ | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Drum life was near to end

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> CRU (PL 5.1.15) <br> PWBA CRUM CP1 (HSG) (PL 5.1.8) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | Install the CRU <br> securely. |
| 1 | Checking the CRU for installation <br> Is the CRU installed securely? | Go to step 3. | Install the PWBA <br> CRUM CP1 <br> (HSG) correctly. |
| 2 | Checking the PWBA CRUM CP1 (HSG) for installation <br> Is the PWBA CRUM CP1 (HSG) installed correctly? | Connect P/J126 <br> and P/J419 <br> surely. |  |
| 3 | Checking the PWBA CRUM CP1 (HSG) for connection <br> Are P/J126 and P/J419 connected surely? |  |  |
| 4 | Checking conductivity between the PWBA CRUM CP1 <br> (HSG) and the PWBA MCU F <br> Is there conductivity on each wire between P/J126 <=> P/ <br> J419? | Go to step 5. | Fix open and <br> short circuit. |
| 5 | Checking +5 VDC power supply to the PWBA CRUM CP1 <br> (HSG) <br> Is the voltage across J126-1 (+) <=> ground +5 VDC? | Replace the <br> PWBA CRUM <br> CP1 (HSG). (RRP <br> 5.3) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## No paper in the select paper tray

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (NO PAPER SENSOR) (PL 2.3.14) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | Load paper. |
| 1 | Checking paper <br> Is Paper loaded in the selected TRAY? |  |  |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 2 | Checking the SENSOR (NO PAPER SENSOR) for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY with paper loaded is pulled out or pushed in? <br> For TRAY1: <br> Execute [Input 07-07 TRAY1 NO PAPER SENSOR] in Chapter 2 [Diagnostic]. <br> For TRAY2: <br> Execute [Input 07-08 TRAY2 NO PAPER SENSOR] in Chapter 2 [Diagnostic]. | Reconnect the connector of the PWBA MCU F. | Go to step 3. |
| 3 | Checking the SENSOR (NO PAPER SENSOR) for connection <br> For TRAY1: <br> Are P/J101 and P/J409A connected surely? <br> For TRAY2: <br> Are P/J103 and P/J409B connected surely? | Go to step 4. | Connect the connectors surely. |
| 4 | Checking conductivity between the SENSOR (NO PAPER SENSOR) and the PWBA MCU F <br> For TRAY1: <br> Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 101<=>P /$ J409A? <br> For TRAY2: <br> Is there conductivity on each wire between P/J103 <=> P/ J409B? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking +5 VDC power supply to the SENSOR (NO PAPER SENSOR) <br> For TRAY1: <br> Is the voltage across J101-3 (+) <=> ground +5 VDC? <br> For TRAY2: <br> Is the voltage across J103-3 (+) <=> ground +5 VDC? | Replace the SENSOR (NO PAPER SENSOR) for the TRAY. (RRP 2.16) | Replace the PWBA MCU F. (RRP 8.4) |

## Paper size mismatch in width

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SWITCH ASSY P S (PL 2.1.4) <br> FRONT SIDE GUIDE (PL 2.2.6) <br> REAR SIDE GUIDE (PL 2.2.9) <br> END GUIDE (PL 2.2.16) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper (1) <br> Is paper loaded in the Tray properly? <br> Pull out the TRAY to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the paper (2) <br> Are the FRONT SIDE GUIDE, REAR SIDE GUIDE and <br> END GUIDE of the TRAY1 or TRAY2 set correctly? <br> Pull out the TRAY to check it. (Visual check) | Go to step 3. | Set the parts properly. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 3 | Checking the SWITCH ASSY P S for installation Is the SWITCH ASSY P S for the TRAY1 or TRAY2 installed correctly? <br> Pull out the TRAY to check it. (Visual check) | Go to step 4. | Install the SWITCH ASSY P S for each TRAY correctly. (RRP 2.1/RRP 2.2) |
| 4 | Checking the SWITCH ASSY P S for operation <br> Does the Input Status change each time the TRAY 1 with paper loaded is pulled out or pushed in? <br> For TRAY1: <br> Execute [Input 07-01 TRAY1 SIZE SENSOR] in Chapter 2 [Diagnostic]. <br> For TRAY2: <br> Execute [Input 07-02 TRAY2 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Reconnect the connector of the PWBA MCU F. | Go to step 5. |
| 5 | Checking the SWITCH ASSY P S for connection <br> For TRAY1: <br> Are P/J109 and P/J412 connected surely? <br> For TRAY2 <br> Are P/J110 and P/J412 connected surely? | Go to step 6. | Connect P/J109, P/J110 and P/ J412 surely. |
| 6 | Checking conductivity between the SWITCH ASSY P S and the PWBA MCU F <br> For TRAY1: <br> Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 109$ <=> P/ J412? <br> For TRAY2 <br> Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 110$ <=> P/ J412? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +5 VDC power supply to the SWITCH ASSY P S For TRAY1: <br> Is the voltage across J109-1 (+) <=> ground +5 VDC? <br> For TRAY2 <br> Is the voltage across J110-1 (+) <=> ground +5 VDC? | Replace the SWITCH ASSY P S for the TRAY. (RRP 2.1/RRP 2.2) | Replace the PWBA MCU F. (RRP 8.4) |

## Tray 1 Paper size mismatch in length

| Step | Check | Yes | No |
| :--- | :--- | :--- | :---: |
|  | Possible causative parts: <br> SWITCH ASSY P S (PL 2.1.4) <br> FRONT SIDE GUIDE (PL 2.2.6) <br> REAR SIDE GUIDE (PL 2.2.9) <br> END GUIDE (PL 2.2.16) <br> ROLLER ASSY-TA (PL 4.1.8) <br> SENSOR ASSY REGI (PL 4.5.7) <br> CLUTCH ASSY REGI (PL 4.5.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper (1) <br> Is paper loaded in the Tray1 properly? <br> Pull out the Tray1 to check it. (Visual check) | Go to step 2. | Load paper prop- <br> erly. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 2 | Checking the paper (2) <br> Are the FRONT SIDE GUIDE, REAR SIDE GUIDE and <br> END GUIDE of the TRAY1 set correctly? <br> Pull out the TRAY1 to check it. (Visual check) | Go to step 3. | Set the parts properly. |
| 3 | Checking the SWITCH ASSY P S for the TRAY1 for installation <br> Is the SWITCH ASSY P S for the TRAY1 installed correctly? <br> Pull out the TRAY1 to check it. (Visual check) | Go to step 4. | Install the SWITCH ASSY P S for the TRAY1 correctly. (RRP 2.1) |
| 4 | Checking the SWITCH ASSY P S for the TRAY1 for operation <br> Does the Input Status change each time the TRAY 1 with paper loaded is pulled out or pushed in? <br> Execute [Input 07-01 TRAY1 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Go to step 8. | Go to step 5. |
| 5 | Checking the SWITCH ASSY P S for the TRAY1 for connection <br> Are P/J109 and P/J412 connected surely? | Go to step 6. | Connect P/J109 and P/J412 surely. |
| 6 | Checking conductivity between the SWITCH ASSY P S for the TRAY1 and the PWBA MCU F Is there conductivity on each wire between P/J109 <=> P/ J412? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +5 VDC power supply to the SWITCH ASSY P S for the TRAY1 <br> Is the voltage across J109-1 (+) <=> ground +5 VDC? | Replace the SWITCH ASSY P $S$ for the STRAY1. (RRP 2.1) | Replace the PWBA MCU F. (RRP 8.4) |
| 8 | Checking the Roll for the TRAY1 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY1 and check it. | Go to step 9. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). <br> (RRP 2.21/RRP <br> 2.25/RRP 2.28) |
| 9 | Checking paper position <br> Does the paper touch the SENSOR ASSY REGI? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 10. |
| 10 | Checking the Roll (1) Is the ROLLER ASSY-TA for transport worn or contaminated with paper dust? Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 11. | Clean or replace the ROLLER ASSY-TA. (RRP 4.3) |
| 11 | Checking the Roll (2) Is the ROLLER of the TRANS ASSY REGI for transport (PL 4.5.1) worn or contaminated with paper dust? Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 12. | Clean or replace the TRANS ASSY REGI. (RRP 4.10) |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 12 | Checking the SENSOR ASSY REGI for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR ASSY REGI? Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 16. | Go to step 13. |
| 13 | Checking the SENSOR ASSY REGI for connection Are P/J104 and P/J403B connected surely? | Go to step 14. | Connect P/J104 and P/J403B surely. |
| 14 | Checking conductivity between the SENSOR ASSY REGI and the PWBA MCU <br> Is there conductivity on each wire between P/J104 <=> P/ J403B? | Go to step 15. | Fix open and short circuit. |
| 15 | Checking +5 VDC power supply to the SENSOR ASSY REGI <br> Is the voltage across J104-1 (+) <=> ground +5 VDC? | Replace the SEN SORASSYREGI. (RRP 4.13) | Replace the PWBA MCU F. (RRP 8.4) |
| 16 | Checking the CLUTCH ASSY REGI H for operation Does the CLUTCH ASSY REGI H operate properly? Execute [Output 08-10 REGI CLUTCH] in Chapter 2 [Diagnostic]. | Reconnect the connector of the PWBA MCU F. | Go to step 17. |
| 17 | Checking the CLUTCH ASSY REGI H for connection Are P/J215 and P/J403B connected surely? | Go to step 18. | Connect P/J215 and P/J403B surely. |
| 18 | Checking conductivity between the CLUTCH ASSY REGI H and the PWBA MCU <br> Is there conductivity on each wire between P/J215 <=> P/ J403B? | Go to step 19. | Fix open and short circuit. |
| 19 | Checking +24 VDC power supply to the CLUTCH ASSY REGI H <br> Is the voltage across P215-2 (+) <=> ground +24 VDC? | Go to step 20. | Replace the PWBA MCU F. (RRP 8.4) |
| 20 | Checking the resistance of the CLUTCH ASSY REGI H Is the resistance across J215-1 and J215-2 approximately 240 ohm? | Replace the PWBA MCU F. (RRP 8.4) | Replace the CLUTCH ASSY REGI H. (RRP 4.11) |

Tray 2 Paper size mismatch in length

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SWITCH ASSY P S (PL 2.1.4) <br> FRONT SIDE GUIDE (PL 2.2.6) <br> REAR SIDE GUIDE (PL 2.2.9) <br> END GUIDE (PL 2.2.16) <br> SENSOR ASSY REGI (PL 4.5.7) <br> CLUTCH ASSY REGI (PL 4.5.5) <br> PWBA MCU F (PL 8.1.5) |  |  |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking the paper (1) <br> Is paper loaded in the TRAY2 properly? <br> Pull out the TRAY2 to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the paper (2) <br> Are the FRONT SIDE GUIDE, REAR SIDE GUIDE and <br> END GUIDE of the TRAY2 set correctly? <br> Pull out the TRAY2 to check it. (Visual check) | Go to step 3. | Set the parts properly. |
| 3 | Checking the SWITCH ASSY P S for the TRAY2 for installation <br> Is the SWITCH ASSY P S for the TRAY2 installed correctly? <br> Pull out the TRAY2 to check it. (Visual check) | Go to step 4. | Install the SWITCH ASSY P S for the TRAY2 correctly. (RRP 2.2) |
| 4 | Checking the SWITCH ASSY P S for the TRAY2 for operation <br> Does the Input Status change each time the TRAY 2 with paper loaded is pulled out or pushed in? <br> Execute [Input 07-02 TRAY2 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Go to step 8. | Go to step 5. |
| 5 | Checking the SWITCH ASSY P S for the TRAY2 for connection <br> Are P/J110 and P/J412 connected surely? | Go to step 6. | Connect P/J110 and P/J412 surely. |
| 6 | Checking conductivity between the SWITCH ASSY P S for the TRAY2 and the PWBA MCU F Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 110$ <=> P/ J412? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +5 VDC power supply to the SWITCH ASSY P S for the TRAY2 Is the voltage across J110-1 (+) <=> ground +5 VDC? | Replace the SWITCH ASSY P S for the TRAY2. (RRP 2.2) | Replace the PWBA MCU F. (RRP 8.4) |
| 8 | Checking the Roll for the TRAY2 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY2 and check it. | Go to step 9. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 2.21/RRP 2.25/ RRP 2.28) |
| 9 | Checking paper position Does the paper touch the SENSOR ASSY REGI? Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 10. |
| 10 | Checking the Roll (1) <br> Is the ROLLER ASSY-TA for transport worn or contami- <br> nated with paper dust? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 11. | ```Clean or replace the ROLLER ASSY-TA. (RRP 4.3)``` |


| Step | Check | Yes | No |
| :---: | :--- | :--- | :---: |
| 11 | Checking the Roll (2) <br> Is the ROLLER of the TRANS ASSY REGI for transport <br> (PL 4.5.1) worn or contaminated with paper dust? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 12. | Clean or replace <br> the TRANS ASSY <br> REGI. (RRP 4.10 |
|  | Checking the SENSOR ASSY REGI for operation <br> Does the Input Status change from "0x0" to "0x1" each <br> time the paper touches the SENSOR ASSY REGI? <br> Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diag- <br> nostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 16. | Go to step 13. |

Face Down Tray1 FULL

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ACTUATOR FULLSTACK (PL 6.2.26) <br> ACTUATOR (PL 6.2.27) <br> SENSOR-PHOTO IN (PL 6.2.5) <br> PWBA EXIT (PL 8.1.4) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the actuator for movement <br> Does the ACTUATOR move up and down normally? | Go to step 2. | Reinstall the ACTUATOR and ACTUATOR FULLSTACK. |
| 2 | Checking the SENSOR-PHOTO IN for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR-PHOTO IN? Execute [Input 07-30 FACE DOWN TRAY1 FULL STACK SENSOR] in Chapter 2 [Diagnostic]. | Reconnect the connector of the PWBA MCU F. | Go to step 3. |
| 3 | Checking the SENSOR-PHOTO IN for connection Are $\mathrm{P} / \mathrm{J} 118, \mathrm{P} / \mathrm{J} 613$ and $\mathrm{P} / \mathrm{J} 432$ connected surely? | Go to step 4. | $\begin{aligned} & \text { Connect P/J118, } \\ & \text { P/J613 and P/ } \\ & \mathrm{J} 432 \text { surely. } \end{aligned}$ |
| 4 | Checking conductivity between the SENSOR-PHOTO IN and the PWBA EXIT <br> Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 118$ <=> P/ J432? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking +5 VDC power supply to the SENSOR-PHOTO IN Is the voltage across J118-3 (+) <=> ground +5 VDC? | Replace the SEN SOR-PHOTO IN. (RRP 6.5) | Go to step 6. |
| 6 | Checking the PWBA EXIT for connection Are P/J421 and P/J431 connected surely? | Go to step 7. | Connect P/J421 and P/J431 surely. |
| 7 | Checking conductivity between the PWBA EXIT and the PWBA MCU F <br> Is there conductivity on each wire between P/J421 <=> P/ J431? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the PWBA EXIT Is the voltage across J421-8 (+) <=> ground +5 VDC? | Replace the PWBA EXIT. (RRP 8.3) | Replace the PWBA MCU F. (RRP 8.4) |

## Face Down Tray2 FULL

| Step | Check | Yes | No |
| :--- | :--- | :---: | :---: |
|  | Possible causative parts: <br> WEIGHT ASSY-PAPER (PL 11.2.6) <br> SENSOR (PL 11.2.52) <br> PWBA EXIT (PL 8.1.4) |  |  |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking the actuator for movement Does the WEIGHT ASSY-PAPER move up and down normally? | Go to step 2. | Reinstall the WEIGHT ASSYPAPER. |
| 2 | Checking the SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR? <br> Execute [Input 07-31 FACE DOWN TRAY2 FULL STACK SENSOR] in Chapter 2 [Diagnostic]. | Reconnect the connector of the PWBA MCU F. | Go to step 3. |
| 3 | Checking the SENSOR for connection Are P/J113, P/J606B and P/J434 connected surely? | Go to step 4. | Connect P/J113, <br> P/J606B and P/ <br> J434 surely. |
| 4 | Checking conductivity between the SENSOR and the PWBA EXIT <br> Is there conductivity on each wire between P/J113 <=> P/ J434? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking +5 VDC power supply to the SENSOR Is the voltage across J113-3 (+) <=> ground +5 VDC? | Replace the SENSOR. (RRP 11.17) | Go to step 6. |
| 6 | Checking the PWBA EXIT for connection Are P/J421 and P/J431 connected surely? | Go to step 7. | Connect P/J421 and P/J431 surely. |
| 7 | Checking conductivity between the PWBA EXIT and the PWBA MCU F <br> Is there conductivity on each wire between P/J421 <=> P/ J431? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the PWBA EXIT Is the voltage across J421-8 (+) <=> ground +5 VDC? | Replace the PWBA EXIT. (RRP 8.3) | Replace the PWBA MCU F. (RRP 8.4) |

## Temperature SENSOR fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> SENSOR HUM \& TE (PL 5.1.5) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | End of work |
| 1 | Does the error still occur after the power is turned ON/ <br> OFF? | Checking the SENSOR HUM \& TE for operation <br> Does the Input Status of the SENSOR HUM \& TE change <br> when the COVER ASSY-LH (PL 4.2.8) is opened? <br> Execute [Input 15-60 Temp Sensor] in Chapter 2 [Diagnos- <br> tic]. | Reconnect the <br> connector on the <br> PWBA MCU F. |
| 3 | Checking the SENSOR HUM \& TE for connection <br> Are P/J150 and P/J403B connected surely? | Go to step 3. |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 4 | Checking conductivity between the SENSOR HUM \& TE <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J150 <=> P/ <br> J403B? | Go to step 5. | Fix open or short <br> circuit. |
| 5 |  <br> TE <br> Is the voltage across J150-1 $(+)<=>$ ground (-) +5 VDC? | Replace the SEN- <br> SOR HUM \& TE. <br> (RRP 5.2) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Humidity Sensor fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SENSOR HUM \& TE (PL 5.1.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Does the error still occur after the power is turned ON/ OFF? | Go to step 2. | End of work |
| 2 | Checking the SENSOR HUM \& TE for operation Does the Input Status of the SENSOR HUM \& TE change when the COVER ASSY-LH (PL 4.2.8) is opened? Execute [Input 15-61 Hum Sensor] in Chapter 2 [Diagnostic]. | Reconnect the connector on the PWBA MCU F. | Go to step 3. |
| 3 | Checking the SENSOR HUM \& TE for connection Are P/J150 and P/J403B connected surely? | Go to step 4. | Connect P/J150 and P/J403B surely. |
| 4 | Checking conductivity between the SENSOR HUM \& TE and the PWBA MCU F <br> Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 150$ <=> P/ J403B? | Go to step 5. | Fix open or short circuit. |
| 5 | Checking +5 VDC power supply to the SENSOR HUM \& TE <br> Is the voltage across J150-1 (+) <=> ground (-) +5 VDC? | Replace the SENSOR HUM \& TE. (RRP 5.2) | Replace the PWBA MCU F. <br> (RRP 8.4) |

## Prefeed Sensor \#3 on JAM (Tray3 paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 9.4.20) <br> ROLLER ASSY (RETARD) (PL 9.4.28) <br> ROLLER ASSY (NUDGER) (PL 9.4.32) <br> TRAY $1 / 2$ FEED LIFT UP MOTOR (PL 9.4.2) <br> SENSOR (PRE FEED SENSOR) (PL 9.4.15) <br> TRAY MODULE PWB (PL 9.6.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup <br> Does the paper size in use match the size set for the TRAY3? | Go to step 3. | Replace the paper, or change the paper size setup. |
| 3 | Checking the Roll for the TRAY3 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) <br> or ROLLER ASSY (NUDGER) for transport worn or con- <br> taminated with paper dust? <br> Pull out the TRAY3 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 9.28/RRP 9.32/ RRP 9.35) |
| 4 | Checking paper position <br> Does the paper touch the SENSOR (PRE FEED SENSOR) of the TRAY3 FEEDER (PL 9.2.7)? <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY3 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR (PRE FEED SENSOR) for the TRAY3? <br> Execute [Input 08-20 PreFEED SENSOR3] in Chapter 2 [Diagnostic]. | Go to step 12. | Go to step 6. |
| 6 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY3 for connection Are P/J103, P/J661B and P/J549B connected surely? | Go to step 7. | Connect P/J103, P/J661 and P/ J549B surely. |
| 7 | Checking conductivity between the SENSOR (PRE FEED SENSOR) for the TRAY3 and the TRAY MODULE PWB Is there conductivity on each wire between P/J103B <=> P/ J549B? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the SENSOR (PRE FEED SENSOR) for the TRAY3 Is the voltage across P/J103B-1 (+) <=> ground +5 VDC? | Replace the SENSOR (PRE FEED SENSOR) for the TRAY3. (RRP 9.25) | Go to step 9. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 9 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F <br> Are P/J541 and P/J413 connected surely? | Go to step 10. | Connect P/J541 and P/J413B surely. |
| 10 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 11. | Fix open and short circuit. |
| 11 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |
| 12 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 for operation <br> Does the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 operate properly? <br> Execute [Output 08-14 TRAY3 FEED MOTOR] in Chapter 2 [Diagnostic]. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 13. |
| 13 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 for connection Are P/J220B, P/J661B and P/J549B connected surely? | Go to step 14. | Connect P/J220, <br> P/J661B and P/ J549B surely. |
| 14 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the <br> TRAY3 for operation (3) <br> Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the <br> TRAY3 with that for the TRAY4. <br> Does the replaced motor operate properly? <br> Execute [Output 08-14 TRAY3 FEED MOTOR] in Chapter <br> 2 [Diagnostic]. | Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 as it previously was and replace the motor for the TRAY3 with a new one. (RRP 9.16) | Go to step 15. |
| 15 | Checking conductivity the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 <br> Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTORs for the TRAY3 and TRAY4 as they previously were. <br> Check the conductivity between the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 and the TRAY MODULE PWB. Is there conductivity on each wire between $P / J 220 B<=>P /$ J549B? | Go to step 16. | Fix open and short circuit. |
| 16 | Checking +24 VDC power supply to the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 Is the voltage across P/J220B-3 (+) <=> ground +24 VDC? | Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3. (RRP 9.16) | Go to step 9. |

## Tray 3 Feed Out Sensor on JAM (Tray 3 paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 9.4.20) <br> ROLLER ASSY (RETARD) (PL 9.4.28) <br> ROLLER ASSY (NUDGER) (PL 9.4.32) <br> SENSOR (PRE FEED SENSOR) (PL 9.4.15) <br> TRAY 3 FEED OUT SENSOR (PL 9.5.3) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup <br> Does the size of paper in use match the size set for the TRAY3? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY3 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? <br> Pull out the TRAY3 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 9.28/RRP 9.32/ RRP 9.35) |
| 4 | Checking paper position <br> Does the paper touch the SENSOR (PRE FEED SENSOR) of the TRAY3 FEED OUT SENSOR or the TRAY 3 FEEDER (PL 9.2.7)? <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking the TRAY 3 FEED OUT SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 3 FEED OUT SENSOR? Execute [Input 08-08 T/A F/03 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it. | Go to step 12. | Go to step 6. |
| 6 | Checking the TRAY 3 FEED OUT SENSOR for connection Are P/J821, P/J841 and P/J548 connected surely? | Go to step 7. | ```Connect P/J821, P/J841 and P/ J548 surely.``` |
| 7 | Checking conductivity between the TRAY 3 FEED OUT SENSOR and the TRAY MODULE PWB <br> Is there conductivity on each wire between P/J821 <=> P/ J548? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the TRAY 3 FEED OUT SENSOR <br> Is the voltage across P/J821-3 (+) <=> ground +5 VDC? | Replace the TRAY 3 FEED OUT SNESOR. (RRP 9.39) | Go to step 9. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 9 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F (1) <br> Are P/J541 and P/J413 connected surely? | Go to step 10. | Connect P/J541 and P/J413 surely. |
| 10 | Checking conductivity between the TRAY MODULE and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 11. | Fix open and short circuit. |
| 11 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |
| 12 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY3 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR (PRE FEED SENSOR) for the TRAY3? <br> Execute [Input 08-20 PreFEED SENSOR3] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 13. |
| 13 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY3 for connection <br> Are P/J103B, P/J661B and P/J549B connected surely? | Go to step 14. | ConnectP/J103B P/J661B and P/ J549B surely. |
| 14 | Checking conductivity between the SENSOR (PRE FEED SENSOR) for the TRAY3 and the TRAY MODULE PWB Is there conductivity on each wire between P/J103B <=> P/ J549B? | Go to step 15. | Fix open and short circuit. |
| 15 | Checking +5 VDC power supply to the SENSOR (PRE FEED SENSOR) for the TRAY2 <br> Is the voltage across P/J103B-1 (+) <=> ground +5 VDC? | Replace the SENSOR (PRE FEED SENSOR). (RRP 9.25) | Go to step 16. |
| 16 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F <br> Are P/J541 and P/J413 connected surely? | Go to step 17. | Connect P/J541 and P/J413 surely. |
| 17 | Checking conductivity between the TRAY MODULE and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 18. | Fix open and short circuit. |
| 18 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |

Tray 2 Feed Out Sensor on JAM (Tray 3 paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 9.4.20) <br> ROLLER ASSY (RETARD) (PL 9.4.28) <br> ROLLER ASSY (NUDGER) (PL 9.4.32) <br> SENSOR (PL 4.5.18) <br> TRAY 3 FEED OUT SENSOR (PL 9.5.3) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking the paper size setup <br> Does the paper size in use match the size set for the TRAY3? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY3 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY3 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 9.28/RRP 9.32/ RRP 9.35) |
| 4 | Checking paper position (1) <br> Does the paper touch the SENSOR? <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking paper position (2) <br> Does the paper touch the TRAY 3 FEED SENSOR? Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it (visual check). | Remove the paper. | Go to step 6. |
| 6 | Checking the SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR? <br> Execute [Input 08-06 FEED OUT\#2 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check it. | Go to step 10. | Go to step 7. |
| 7 | Checking the SENSOR for connection Are P/J105, P/J608 and P/J410 connected surely? | Go to step 8. | Connect P/J105, P/J608 and P/ J410 surely. |
| 8 | Checking conductivity between the SENSOR and the PWBA MCU F <br> Is there conductivity on each wire between P/J105 <=> P/ J410? | Go to step 9. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 9 | Checking +5 VDC power supply to the SENSOR Is the voltage across P/J105-1 (+) <=> ground +5 VDC? | Replace the SEN- <br> SOR. (RRP 4.15) | Replace the PWBA MCU F. (RRP 8.4) |
| 10 | Checking the TRAY 3 FEED OUT SENSOR for the TRAY3 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 3 FEED OUT SENSOR for the TRAY3? <br> Execute [Input 08-20 PreFEED SENSOR3] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 11. |
| 11 | Checking the TRAY 3 FEED OUT SENSOR for connection Are P/J821, P/J841 and P/J548 connected surely? | Go to step 12. | Connect P/J821, P/J841 and P/ J548 surely. |
| 12 | Checking conductivity between the TRAY 3 FEED OUT SENSOR and the TRAY MODULE PWB <br> Is there conductivity on each wire between P/J821 <=> P/ J548? | Go to step 13. | Fix open and short circuit. |
| 13 | Checking +5 VDC power supply to the TRAY 3 FEED OUT SENSOR <br> Is the voltage across P/J821-3 (+) <=> ground +5 VDC? | Replace the TRAY 3 FEED OUT SNESOR. <br> (RRP 9.39) | Go to step 14. |
| 14 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F Are P/J541 and P/J413 connected surely? | Go to step 15. | $\begin{aligned} & \text { Connect P/J541 } \\ & \text { and P/J413 } \\ & \text { surely. } \end{aligned}$ |
| 15 | Checking conductivity between the TRAY MODULE and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 16. | Fix open and short circuit. |
| 16 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |

## Registration Sensor on JAM (Tray3 paper feed)

| Step | Check | Yes | No |
| :--- | :--- | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 9.4.20) <br> ROLLER ASSY (RETARD) (PL 9.4.28) <br> ROLLER ASSY (NUDGER) (PL 9.4.32) <br> SENSOR ASSY REGI (PL 4.5.7) <br> TRAY 3 FEED OUT SENSOR (PL 9.5.3) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition <br> Is the paper in the tray crumpled or damaged? | Replace the <br> paper with a new <br> and dry one. | Go to step 2. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 2 | Checking the paper size setup <br> Does the paper size in use match the size set for the TRAY3? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY3 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY3 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 9.28/RRP 9.32/ RRP 9.35) |
| 4 | Checking paper position (1) <br> Does the paper touch the SENSOR ASSY REGI? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking paper position (2) <br> Does the paper touch the TRAY 3 FEED SENSOR? Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it (visual check). | Remove the paper. | Go to step 6. |
| 6 | Checking the SENSOR ASSY REGI for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR ASSY REGI? Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 10. | Go to step 7. |
| 7 | Checking the SENSOR ASSY REGI for connection Are P/J104 and P/J403B connected surely? | Go to step 8. | Connect P/J104 and P/J403B surely. |
| 8 | Checking conductivity between the SENSOR ASSY REGI and the PWB A MCU F <br> Is there conductivity on each wire between P/J104 <=> P/ J409B? | Go to step 9. | Fix open and short circuit. |
| 9 | Checking +5 VDC power supply to the SENSOR ASSY REGI <br> Is the voltage across P/J104-1 (+) <=> ground +5 VDC? | Replace the SENSOR ASSY REGI. (RRP 4.13) | Replace the PWBA MCU F. (RRP 8.4) |
| 10 | Checking the TRAY 3 FEED OUT SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 3 FEED OUT SENSOR? Execute [Input 08-08 T/A F/03 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 11. |
| 11 | Checking the TRAY 3 FEED OUT SENSOR for connection Are P/J821, P/J841 and P/J548 connected surely? | Go to step 12. | Connect P/J821, P/J841 and P/ J548 surely |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 12 | Checking conductivity between the TRAY 3 FEED OUT <br> SENSOR and the TRAY MODULE PWB <br> Is there conductivity on each wire between P/J821 <=> P/ <br> J548? | Go to step 13. | Fix open and <br> short circuit. |
| 13 | Checking +5 VDC power supply to the TRAY 3 FEED OUT <br> SENSOR <br> Is the voltage across P/J821-3 (+) <=> ground +5 VDC? | Replace the <br> TRAY 3 FEED <br> OUT SNESOR. <br> (RRP 9.39) | Go to step 14. |
| 14 | Checking connection between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Are P/J541 and P/J413 connected surely? | Go to step 15. <br> (he PWBBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ <br> J413? | Connect P/J541 <br> and P/J413 <br> surely. |
| 16 | Checking +24 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across P/J541-8 (+) <=> ground +24 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP 9.47) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray 4 Feed Out Sensor on JAM (Tray 4 paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 9.4.20) <br> ROLLER ASSY (RETARD) (PL 9.4.28) <br> ROLLER ASSY (NUDGER) (PL 9.4.32) <br> SENSOR (PRE FEED SENSOR) (PL 9.4.15) <br> TRAY 4 FEED OUT SENSOR (PL 9.5.6) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking the paper size setup <br> Does the paper size in use match the size set for the TRAY4? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY4 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY4 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 9.28/RRP 9.32/ RRP 9.35) |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 4 | Checking the paper position <br> Does the paper touch the SENSOR (PRE FEED SENSOR) of the TRAY 4 FEEDER (PL 9.2.8) or the TRAY4 FEED OUT SENSOR? <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY4 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR (PRE FEED SENSOR) for the TRAY4? <br> Execute [Input 08-21 PreFEED SENSOR4] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it. | Go to step 12. | Go to step 6. |
| 6 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY4 for connection Are P/J103A, P/J661A and P/J549A connected surely? | Go to step 7. | ConnectP/J103A P/J661A and P/ J549A surely. |
| 7 | Checking conductivity between the SENSOR (PRE FEED SENSOR) for the TRAY4 and the TRAY MODULE PWB Is there conductivity on each wire between P/J103A <=> P/ J549A? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the SENSOR (PRE FEED SENSOR) for the TRAY4 Is the voltage across P/J103A-1 (+) <=> ground +5 VDC? | Replace the SENSOR (PRE FEED SENSOR). (RRP 9.25) | Go to step 9. |
| 9 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F (1) <br> Are P/J541 and P/J413 connected surely? | Go to step 10. | Connect P/J541 and P/J413 surely. |
| 10 | Checking conductivity between the TRAY MODULE and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 11. | Fix open and short circuit. |
| 11 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |
| 12 | Checking the TRAY 4 FEED OUT SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 4 FEED OUT SENSOR? Execute [Input 08-09 T/A F/04 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 13. |
| 13 | Checking the TRAY 4 FEED OUT SENSOR for connection Are P/J825, P/J842 and P/J548 connected surely? | Go to step 14. | Connect P/J825, P/J842 and P/ J548 surely. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 14 | Checking conductivity between the TRAY 4 FEED OUT <br> SENSOR and the TRAY MODULE PWB <br> Is there conductivity on each wire between P/J825 <=> P/ <br> J548? | Go to step 15. | Fix open and <br> short circuit. |
| 15 | Checking +5 VDC power supply to the TRAY 4 FEED OUT <br> SENSOR <br> Is the voltage across P/J825-3 (+) <=> ground +5 VDC? | Replace the <br> TRAY 4 FEED <br> OUT SNESOR. <br> (RRP 9.38) | Go to step 16. |
| 16 | Checking connection between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Are P/J541 and P/J413 connected surely? | Go to step 17. | Connect P/J541 <br> and P/J413 <br> surely. |
| 17 | Checking conductivity between the TRAY MODULE and <br> the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ <br> J413? | Go to step 18. | Fix open and <br> short circuit. |
| 18 | Checking +24 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across P/J541-8 (+) <=> ground +24 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP 9.47) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray 3 Feed Out Sensor on JAM (Tray 4 paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 9.4.20) <br> ROLLER ASSY (RETARD) (PL 9.4.28) <br> ROLLER ASSY (NUDGER) (PL 9.4.32) <br> TRAY 3 FEED OUT SENSOR (PL 9.5.3) <br> TRAY 4 FEED OUT SENSOR (PL 9.5.6) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup <br> Does the paper size in use match the size set for the TRAY4? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY4 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY4 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 9.28/RRP 9.32/ RRP 9.35) |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 4 | Checking paper position <br> Does the paper touch the TRAY 3 FEED OUT SENSOR or the TRAY 4 FEED OUT SENSOR? <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking the TRAY 4 FEED OUT SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 4 FEED OUT SENSOR? Execute [Input 08-09 T/A F/04 SENSOR] in Chapter 2 [Diagnostic]. | Go to step 12. | Go to step 6. |
| 6 | Checking the TRAY 4 FEED OUT SENSOR for connection Are P/J825, P/J842 and P/J548 connected surely? | Go to step 7. | Connect P/J825, P/J842 and P/ J548 surely. |
| 7 | Checking conductivity between the TRAY 4 FEED OUT SENSOR and the TRAY MODULE PWB Is there conductivity on each wire between P/J825 <=> P/ J548? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the TRAY 4 FEED OUT SENSOR <br> Is the voltage across P/J825-3 (+) <=> ground +5 VDC? | Replace the TRAY 4 FEED OUT SNESOR. (RRP 9.38) | Go to step 9. |
| 9 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F <br> Are P/J541 and P/J413 connected surely? | Go to step 10. | Connect P/J541 and P/J413 surely. |
| 10 | Checking conductivity between the TRAY MODULE and the PWBA MCU F Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 11. | Fix open and short circuit. |
| 11 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |
| 12 | Checking the TRAY 3 FEED OUT SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 3 FEED OUT SENSOR? Execute [Input 08-08 T/A F/03 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 13. |
| 13 | Checking the TRAY 3 FEED OUT SENSOR for connection Are P/J821, P/J841 and P/J548 connected surely? | Go to step 14. | Connect P/J821, P/J841 and P/ J548 surely. |
| 14 | Checking conductivity between the TRAY 3 FEED OUT SENSOR and the TRAY MODULE PWB Is there conductivity on each wire between P/J821 <=> P/ J548? | Go to step 15. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 15 | Checking +5 VDC power supply to the TRAY 3 FEED OUT <br> SENSOR <br> Is the voltage across P/J821-3 (+) <=> ground +5 VDC? | Replace the <br> TRAY 3 FEED <br> OUT SNESOR. <br> (RRP 9.39) | Go to step 16. |
| 16 | Checking connection between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Are P/J541 and P/J413 connected surely? | Go to step 17. | Connect P/J541 <br> and P/J413 <br> surely. |
| 17 | Checking conductivity between the TRAY MODULE and <br> the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ <br> J413? | Go to step 18. | Fix open and <br> short circuit. |
| 18 | Checking +24 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across P/J541-8 (+) <=> ground +24 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP 9.47) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray 2 Feed Out Sensor on JAM (Tray 3 paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 9.4.20) <br> ROLLER ASSY (RETARD) (PL 9.4.28) <br> ROLLER ASSY (NUDGER) (PL 9.4.32) <br> SENSOR (PL 4.5.18) <br> TRAY 3 FEED OUT SENSOR (PL 9.5.3) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup <br> Does the paper size in use match the size set for the TRAY3? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY3 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY3 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 9.28/RRP 9.32/ RRP 9.35) |
| 4 | Checking paper position (1) <br> Does the paper touch the SENSOR? <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check it (visual check). | Remove the paper. | Go to step 5. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 5 | Checking paper position (2) <br> Does the paper touch the TRAY 3 FEED SENSOR? Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it (visual check). | Remove the paper. | Go to step 6. |
| 6 | Checking the SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR? <br> Execute [Input 08-06 FEED OUT\#2 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check it. | Go to step 10. | Go to step 7. |
| 7 | Checking the SENSOR for connection Are P/J105, P/J608 and P/J410 connected surely? | Go to step 8. | $\begin{aligned} & \text { Connect P/J105, } \\ & \text { P/J608 and P/ } \\ & \text { J410 surely. } \end{aligned}$ |
| 8 | Checking conductivity between the SENSOR and the PWBA MCU F <br> Is there conductivity on each wire between P/J105 <=> P/ J410? | Go to step 9. | Fix open and short circuit. |
| 9 | Checking +5 VDC power supply to the SENSOR Is the voltage across P/J105-1 (+) <=> ground +5 VDC? | Replace the SEN- <br> SOR. (RRP 4.15) | Replace the PWBA MCU F. (RRP 8.4) |
| 10 | Checking the TRAY 3 FEED OUT SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 3 FEED OUT SENSOR? Execute [Input 08-20 PreFEED SENSOR3] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 11. |
| 11 | Checking the TRAY 3 FEED OUT SENSOR for connection Are P/J821, P/J841 and P/J548 connected surely? | Go to step 12. | $\begin{aligned} & \text { Connect P/J821, } \\ & \text { P/J841 and P/ } \\ & \text { J548 surely. } \end{aligned}$ |
| 12 | Checking conductivity between the TRAY 3 FEED OUT SENSOR and the TRAY MODULE PWB Is there conductivity on each wire between P/J821 <=> P/ J548? | Go to step 13. | Fix open and short circuit. |
| 13 | Checking +5 VDC power supply to the TRAY 3 FEED OUT SENSOR <br> Is the voltage across P/J821-3 (+) <=> ground +5 VDC? | Replace the TRAY 3 FEED OUT SNESOR. <br> (RRP 9.39) | Go to step 14. |
| 14 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F Are P/J541 and P/J413 connected surely? | Go to step 15. | Connect P/J541 and P/J413 surely. |
| 15 | Checking conductivity between the TRAY MODULE and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 16. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 16 | Checking +24 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across P/J541-8 $(+)$ <=> ground +24 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP 9.47) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Registration Sensor on JAM (Tray 4 paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 9.4.20) <br> ROLLER ASSY (RETARD) (PL 9.4.28) <br> ROLLER ASSY (NUDGER) (PL 9.4.32) <br> SENSOR ASSY REGI (PL 4.5.7) <br> TRAY 4 FEED OUT SENSOR (PL 9.5.6) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup <br> Does the paper size in use match the size set for the TRAY4? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY4 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) <br> or ROLLER ASSY (NUDGER) for transport worn or con- <br> taminated with paper dust? <br> Pull out the TRAY4 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 9.28/RRP 9.32/ RRP 9.35) |
| 4 | Checking paper position (1) <br> Does the paper touch the SENSOR ASSY REGI? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking paper position (2) <br> Does the paper touch the TRAY 4 FEED SENSOR? Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it (visual check). | Remove the paper. | Go to step 6. |
| 6 | Checking the SENSOR ASSY REGI for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR ASSY REGI? Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 10. | Go to step 7. |
| 7 | Checking the SENSOR ASSY REGI for connection Are P/J104 and P/J403B connected surely? | Go to step 8. | Connect P/J104 and P/J403B surely. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 8 | Checking conductivity between the SENSOR ASSY REGI and the PWB A MCU <br> Is there conductivity on each wire between P/J104 <=> P/ J409B? | Go to step 9. | Fix open and short circuit. |
| 9 | Checking +5 VDC power supply to the SENSOR ASSY REGI <br> Is the voltage across P/J104-1 (+) <=> ground +5 VDC? | Replace the SENSORASSY REGI. (RRP 4.13) | Replace the PWBA MCU F. (RRP 8.4) |
| 10 | Checking the TRAY 4 FEED OUT SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 4 FEED OUT SENSOR? Execute [Input 08-08 T/A F/04 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 11. |
| 11 | Checking the TRAY 4 FEED OUT SENSOR for connection Are P/J825, P/J842 and P/J548 connected surely? | Go to step 12. | $\begin{aligned} & \text { Connect P/J825, } \\ & \text { P/J842 and P/ } \\ & \text { J548 surely. } \end{aligned}$ |
| 12 | Checking conductivity between the TRAY 4 FEED OUT SENSOR and the TRAY MODULE PWB Is there conductivity on each wire between P/J825 <=> P/ J548? | Go to step 13. | Fix open and short circuit. |
| 13 | Checking +5 VDC power supply to the TRAY 4 FEED OUT SENSOR <br> Is the voltage across P/J821-3 (+) <=> ground +5 VDC? | Replace the TRAY 4 FEED OUT SNESOR. (RRP 9.38) | Go to step 14. |
| 14 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F <br> Are P/J541 and P/J413 connected surely? | Go to step 15. | Connect P/J541 and P/J413 surely. |
| 15 | Checking conductivity between the TRAY MODULE and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 16. | Fix open and short circuit. |
| 16 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |

Prefeed Sensor \#4 on JAM (Tray4 paper feed)

| Step | Check | Yes | No |
| :--- | :--- | :--- | :--- |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 9.4.20) <br> ROLLER ASSY (RETARD) (PL 9.4.28) |  |  |
| ROLLER ASSY (NUDGER) (PL 9.4.32) |  |  |  |
| TRAY 1/2 FEED LIFT UP MOTOR (PL 9.4.2) |  |  |  |
|  | SENSOR (PRE FEED SENSOR) (PL 9.4.15) |  |  |
| TRAY MODULE PWB (PL 9.6.1) |  |  |  |
|  | PWBA MCU F (PL 8.1.5) |  |  |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup <br> Does the paper size in use match the size set for the TRAY4? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY4 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY4 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 9.28/RRP 9.32/ RRP 9.35) |
| 4 | Checking paper position <br> Does the paper touch the SENSOR (PRE FEED SENSOR) of the TRAY4 FEEDER (PL 9.2.8)? | Remove the paper. | Go to step 5. |
| 5 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY4 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR (PRE FEED SENSOR) for the TRAY4? <br> Execute [Input 08-21 PreFEED SENSOR4] in Chapter 2 [Diagnostic]. | Go to step 12. | Go to step 6. |
| 6 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY4 for connection Are P/J103A, P/J661A and P/J549A connected surely? | Go to step 7. | $\begin{aligned} & \text { Connect P/J103A, } \\ & \text { P/J661A and P/ } \\ & \text { J549A surely. } \end{aligned}$ |
| 7 | Checking conductivity between the SENSOR (PRE FEED SENSOR) for the TRAY4 and the TRAY MODULE PWB Is there conductivity on each wire between P/J103A <=> P/ J549A? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the SENSOR (PRE FEED SENSOR) for the TRAY4 Is the voltage across P/J103A-1 (+) <=> ground +5 VDC? | Replace the SENSOR for the TRAY4 (PRE FEED SENSOR). (RRP 9.25) | Go to step 9. |
| 9 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F Are P/J541 and P/J413 connected surely? | Go to step 10. | Connect P/J541 and P/J413 surely. |
| 10 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 11. | Fix open and short circuit. |
| 11 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 12 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 for operation <br> Does the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 operate properly? <br> Execute [Output 08-15 TRAY4 FEED MOTOR] in Chapter 2 [Diagnostic]. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 13. |
| 13 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 for connection Are P/J220A, P/J661A and P/J549A connected surely? | Go to step 14. | ConnectP/J220A P/J661A and P/ J549A surely. |
| 14 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 for operation (3) <br> Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 with that for the TRAY3. <br> Does the replaced motor operate properly? <br> Execute [Output 08-15 TRAY4 FEED MOTOR] in Chapter 2 [Diagnostic]. | Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 as it previously was and then, replace the motor for the TRAY4 with a new one. (RRP 9.16) | Go to step 15. |
| 15 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 for operation (4) <br> Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTORs for the TRAY3 and TRAY4 as they previously were. Checking conductivity between the TRAY 1/2 FEED LIFT UP MOTOR for the TRAY3 and the TRAY MODULE PWB. Is there conductivity on each wire between P/J220A <=> P/ J549A? | Go to step 16. | Fix open and short circuit. |
| 16 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F Are P/J541 and P/J413 connected surely? | Go to step 17. | Connect P/J541 and $P / J 413$ surely. |
| 17 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 18. | Fix open and short circuit. |
| 18 | Checking +24 VDC power supply to the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 Is the voltage across P/J220B-3 (+) <=> ground +24 VDC? | Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4. (RRP 9.16) | Replace the PWBA MCU F. (RRP 8.4) |

## Tray 3 Feed Out Sensor Static JAM

| Step | Check | Yes | No |
| :--- | :--- | :---: | :---: |
|  | Possible causative parts: <br> TRAY 3 FEED OUT SENSOR (PL 9.5.3) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking paper position <br> Does the paper touch the TRAY 3 FEED OUT SENSOR? <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and <br> check it (visual check). | Remove the <br> paper. | Go to step 2. |
| 2 | Checking the TRAY 3 FEED OUT SENSOR for operation <br> Does the Input Status change from "0x0" to "Ox1" each <br> time the paper touches the TRAY 3 FEED OUT SENSOR? <br> Execute [Input 08-08 T/A F/03 SENSOR] in Chapter 2 <br> [Diagnotic]. <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and <br> check it. | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | Go to step 3. |
| 3 | Checking the TRAY 3 FEED OUT SENSOR for connection <br> Are P/J821, P/J841 and P/J548 connected surely? | Go to step 4. | Connect P/J821, <br> P/J841 and P/ <br> J548 surely. |
| 4 | Checking conductivity between the TRAY 3 FEED OUT <br> SENSOR and the TRAY MODULE PWB <br> Is there conductivity on each wire between P/J821 <=> P/ <br> J548? | Go to step 5. | Fix open and <br> short circuit. |
| 5 | Checking conductivity between the TRAY MODULE and <br> the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ <br> J413? | Go to step 6. | Fix open and <br> short circuit. |
| 6 | Checking +5 VDC power supply to the TRAY 3 FEED OUT <br> SENSOR <br> Is the voltage across P/J821-3 (+) <=> ground +5 VDC? | Replace the <br> TRAY 3 FEED <br> OUT SNESOR. <br> (RRP 9.39) | Go to step 7. |
| 7 | Checking +5 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across P/J541-5 (+) <=> ground +5 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP 9.47) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray 4 Feed Out Sensor Static JAM

| Step | Check | Yes | No |
| :--- | :--- | :--- | :---: |
|  | Possible causative parts: <br> TRAY 4 FEED OUT SENSOR (PL 9.5.6) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) | Checking paper position <br> Does the paper touch the TRAY 4 FEED OUT SENSOR? <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and <br> check it (visual check). | Remove the <br> paper. |
|  | Checking the TRAY 4 FEED OUT SENSOR for operation | Go to step 2. |  |
| Does the Input Status change from "Ox0" to "0x1" each <br> time the paper touches the TRAY 4 FEED OUT SENSOR? <br> Execute [Input 08-09 T/A F/O4 SENSOR] in Chapter 2 <br> [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and <br> check it. | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | Go to step 3. |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 3 | Checking the TRAY 4 FEED OUT SENSOR for connection <br> Are P/J825, P/J842 and P/J548 connected surely? | Go to step 4. | Connect P/J825, <br> P/J842 and P/ <br> J548 surely. |
| 4 | Checking conductivity between the TRAY 4 FEED OUT <br> SENSOR and the TRAY MODULE PWB <br> Is there conductivity on each wire between P/J825 <=> P/ <br> J548? | Go to step 5. | Fix open and <br> short circuit. |
| 5 | Checking conductivity between the TRAY MODULE and <br> the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ <br> J413? | Go to step 6. | Fix open and <br> short circuit. |
| 6 | Checking +5 VDC power supply to the TRAY 4 FEED OUT <br> SENSOR <br> Is the voltage across P/J825-3 (+) <=> ground +5 VDC? | Replace the <br> TRAY 4 FEED <br> OUT SNESOR. <br> (RRP 9.38) | Go to step 7. |
| 7 | Checking +5 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across P/J545-8 (+) <=> ground +5 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP 9.47) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray 3 Lift up /No tray fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SECTOR GEAR (60T) (PL 9.3.22) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 9.4.2) <br> SENSOR (LEVEL SENSOR) (PL 9.4.14) <br> TRAY 3/4 PAPER SIZE SWITCH (PL 9.2.4) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper <br> Is any paper loaded in the Tray3? <br> Pull out the Tray3 to check it. (Visual check) | Go to step 2. | Load paper. |
| 2 | Checking the TRAY <br> Are the SECTOR GEAR (60T) of TRAY2 or the surrounding parts of it damaged? | Go to step 3. | Replace the SECTOR GEAR (60T) (RRP 9.15) or the obstacles. |
| 3 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 for operation (1) <br> Does the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 operate properly? <br> Execute [Output 08-14 TRAY3 FEED MOTOR] in Chapter 2 [Diagnostic]. | Go to step 11. | Go to step 4. |
| 4 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 for connection Are P/J220B, P/J661B and P/J549B connected surely? | Go to step 5. | Connect P/J220B, P/J661B and P/ J549B surely. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 5 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the <br> TRAY3 for operation (2) <br> Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the <br> TRAY3 with that for the TRAY4. <br> Does the replaced motor operate properly? <br> Execute [Output 08-14 TRAY3 FEED MOTOR] in Chapter <br> 2 [Diagnostic]. | Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 as it previously was and replace the motor for the TRAY3 with a new one. (RRP 9.16) | Go to step 6. |
| 6 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 for operation (3) Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTORs for the TRAY3 and TRAY4 as they previously were. Checking conductivity between the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 and the TRAY MODULE PWB. Is there conductivity on each wire between P/J220B <=> P/ J549B? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +24 VDC power supply to the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 Is the voltage across P/J220B-3 (+) <=> ground +24 VDC? | Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3. (RRP 9.16) | Go to step 8. |
| 8 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 9. | Connect P/J413 and $P / 541$ surely. |
| 9 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 10. | Fix open and short circuit. |
| 10 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J413-B2 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |
| 11 | Checking the SENSOR (LEVEL SENSOR) for the TRAY3 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR (LEVEL SENSOR) for the TRAY3? <br> Execute [Input 07-15 TRAY3 LEVEL SENSOR] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it. | Go to step 18. | Go to step 12. |
| 12 | Checking the SENSOR (LEVEL SENSOR) for the TRAY3 for connection <br> Are P/J101B, P/J661B and P/J549B connected surely? | Go to step 13. | ConnectP/J101B P/J661B and P/ J549B surely. |
| 13 | Checking conductivity between the SENSOR (LEVEL SENSOR) for the TRAY3 and the TRAY MODULE PWB Is there conductivity on each wire between P/J101B <=> P/ J549B? | Go to step 14. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 14 | Checking +5 VDC power supply to the SENSOR (LEVEL SENSOR) for the TRAY3 <br> Is the voltage across P/J101B-3 (+) <=> ground +5 VDC? | Replace the SENSOR (LEVEL SENSOR) for the TRAY3. (RRP 9.24) | Go to step 16. |
| 15 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 16. | Connect P/J413 and $P / 541$ surely. |
| 16 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 17. | Fix open and short circuit. |
| 17 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J413-A5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |
| 18 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY 3 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY3 with paper loaded is pulled out or pushed in? <br> Execute [Input 07-03 TRAY3 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 19. |
| 19 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY 3 for connection Are P/J820 and P/J548 connected surely? | Go to step 20. | Connect P/J820 and P/J548 surely. |
| 20 | Checking conductivity between the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 and the PWBA MCU F Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 820<=>$ P/ J548? | Go to step 21. | Fix open and short circuit. |
| 21 | Checking +3.3 VDC power supply to the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 <br> Is the voltage across P/J820-1 (+) <=> ground +3.3 VDC? | Replace the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3. (RRP 9.8) | Go to step 22. |
| 22 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 23. | Connect P/J413 and $P / 541$ surely. |
| 23 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 24. | Fix open and short circuit. |
| 24 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J413-A5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |

## Tray 4 Lift up /No tray fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SECTOR GEAR (60T) (PL 9.3.22) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 9.4.2) <br> SENSOR (LEVEL SENSOR) (PL 9.4.14) <br> TRAY 3/4 PAPER SIZE SWITCH (PL 9.2.4) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper <br> Is any paper loaded in the Tray4? <br> Pull out the Tray4 to check it. (Visual check) | Go to step 2. | Load paper. |
| 2 | Checking the TRAY <br> Are the SECTOR GEAR (60T) of TRAY4 or the surrounding parts of it damaged? | Go to step 3. | Replace the SECTOR GEAR (60T) (RRP 9.15) or the obstacles. |
| 3 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 for operation <br> Does the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 operate properly? <br> Execute [Output 08-15 TRAY4 FEED MOTOR] in Chapter 2 [Diagnostic]. | Go to step 11. | Go to step 4. |
| 4 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 for connection Are P/J220A, P/J661A and P/J549A connected surely? | Go to step 5. | ConnectP/J220A, P/J661A and P/ J549A surely. |
| 5 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 for operation (3) <br> Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 with that for the TRAY3. <br> Does the replaced motor operate properly? <br> Execute [Output 08-15 TRAY4 FEED MOTOR] in Chapter <br> 2 [Diagnostic]. | Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 as it previously was and then, replace the motor for the TRAY4 with a new one. (RRP 9.16) | Go to step 6. |
| 6 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 for operation (4) Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTORs for the TRAY3 and TRAY4 as they previously were. Checking conductivity between the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 and the TRAY MODULE PWB. Is there conductivity on each wire between P/J220A <=> P/ J549A? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +24 VDC power supply to the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 Is the voltage across P/J220A-3 (+) <=> ground +24 VDC? | Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4. (RRP 9.16) | Go to step 8. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 8 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 9. | Connect P/J413 and $P / 541$ surely. |
| 9 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 10. | Fix open and short circuit. |
| 10 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J413-B2 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |
| 11 | Checking the SENSOR (LEVEL SENSOR) for the TRAY4 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR (LEVEL SENSOR) for the TRAY4? <br> Execute [Input 07-16 TRAY4 LEVEL SENSOR] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it. | Go to step 18. | Go to step 12. |
| 12 | Checking the SENSOR (LEVEL SENSOR) for the TRAY4 for connection <br> Are P/J101A, P/J661A and P/J549A connected surely? | Go to step 13. | $\begin{aligned} & \text { Connect P/J101A, } \\ & \text { P/J661A and P/ } \\ & \text { J549A surely. } \end{aligned}$ |
| 13 | Checking conductivity between the SENSOR (LEVEL SENSOR) for the TRAY4 and the TRAY MODULE PWB Is there conductivity on each wire between P/J101A <=> P/ J549A? | Go to step 14. | Fix open and short circuit. |
| 14 | Checking +5 VDC power supply to the SENSOR (LEVEL SENSOR) for the TRAY4 <br> Is the voltage across P/J101A-3 (+) <=> ground +5 VDC? | Replace the SENSOR (LEVEL SENSOR) for the TRAY4. (RRP 9.24) | Go to step 15. |
| 15 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 16. | Connect P/J413 and $P / 541$ surely. |
| 16 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J413-A5 (+) <=> ground +5 VDC? | Go to step 17. | Fix open and short circuit. |
| 17 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J413-B2 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |
| 18 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY4 with paper loaded is pulled out or pushed in? <br> Execute [Input 07-04 TRAY4 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 19. |
| 19 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 for connection Are P/J824 and P/J548 connected surely? | Go to step 20. | Connect P/J824 and P/J548 surely. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 20 | Checking conductivity between the TRAY 3/4 PAPER <br> SIZE SWITCH for the TRAY4 and the PWBA MCU F <br> Is there conductivity on each wire between P/J824 <=> P/ <br> J548? | Go to step 21. | Fix open and <br> short circuit. |
| 21 | Checking +3.3 VDC power supply to the TRAY 3/4 PAPER <br> SIZE SWITCH for the TRAY4 <br> Is the voltage across P/J824-1 (+) <=> ground +3.3 VDC? | Replace the <br> TRAY 3/4 PAPER <br> SIZE SWITCH for <br> the TRAY4. (RRP <br> 9.9) | Go to step 22. |
| 22 | Checking the TRAY MODULE PWB for connection <br> Are P/J413 and P/J541 connected surely? | Go to step 23. | Connect P/J413 <br> and P/541 surely. |
| 23 | Checking conductivity between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ <br> J541? | Go to step 24. | Fix open and <br> short circuit. |
| 24 | Checking +5 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across P/J413-A5 (+) <=> ground +5 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP 9.47) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray 3 cassette Size fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY 3/4 PAPER SIZE SWITCH (PL 9.2.4) <br> FRONT SIDE GUIDE (PL 9.3.6) <br> REAR SIDE GUIDE (PL 9.3.9) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper (1) <br> Is paper loaded in the TRAY3 properly? <br> Pull out the TRAY3 to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the paper (2) <br> Are the FRONT SIDE GUIDE and REAR SIDE GUIDE of the TRAY3 set correctly? <br> Pull out the TRAY3 to check it. (Visual check) | Go to step 3. | Set the parts properly. |
| 3 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 for operation Is the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 installed properly? <br> Pull out the TRAY3 to check it. (Visual check) | Go to step 4. | Install the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 correctly. (RRP 9.8) |
| 4 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY3 with paper loaded is pulled out or pushed in? <br> Execute [Input 07-03 TRAY3 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 5. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 5 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for connection <br> Are P/J820 and P/J548 connected surely? | Go to step 6. | Connect P/J820 and P/J548 surely. |
| 6 | Checking conductivity between the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 and the PWBA MCU F Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 820$ <=> P/ J548? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +3.3 VDC power supply to the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 Is the voltage across P/J820-1 (+) <=> ground +3.3 VDC? | Replace the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3. (RRP 9.8) | Go to step 8. |
| 8 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 9. | Connect P/J413 and $P / 541$ surely. |
| 9 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 10. | Fix open and short circuit. |
| 10 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J413-A5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |

## Tray 4 cassette Size fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY 3/4 PAPER SIZE SWITCH (PL 9.2.4) <br> FRONT SIDE GUIDE PL 9.3.6) <br> REAR SIDE GUIDE PL 9.3.9) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper (1) <br> Is paper loaded in the TRAY4 properly? <br> Pull out the TRAY4 to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the paper (2) <br> Are the FRONT SIDE GUIDE and REAR SIDE GUIDE of the TRAY4 set correctly? <br> Pull out the TRAY4 to check it. (Visual check) | Go to step 3. | Set the parts properly. |
| 3 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 for installation <br> Is the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 installed properly? <br> Pull out the TRAY4 to check it. (Visual check) | Go to step 4. | Install the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 correctly. (RRP 9.9) |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 4 | Checking the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY4 with paper loaded is pulled out or pushed in? <br> Execute [Input 07-04 TRAY4 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 5. |
| 5 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 for connection Are P/J824 and P/J548 connected surely? | Go to step 6. | Connect P/J824 and P/J548 surely. |
| 6 | Checking conductivity between the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 and the PWBA MCU F Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 824$ <=> P/ J548? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +3.3 VDC power supply to the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 Is the voltage across P/J824-1 (+) <=> ground +3.3 VDC? | Replace the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4. (RRP 9.9) | Go to step 8. |
| 8 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 9. | Connect P/J413 and $P / 541$ surely. |
| 9 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 10. | Fix open and short circuit. |
| 10 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J413-A5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |

## Tray Module NVM out-of-order

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) | Ge | Go |
| 1 | Does the error occur when the power is turned ON again? | Go to step 3. | Go to step 2. |
| 2 | Does the error still occur after the power is turned ON/OFF <br> repeatedly several times? | Go to step 3. | End of work *1 |
| 3 | Checking data on the NVRAM (1) <br> Is data on the NVRAM accessible? <br> Execute [NVM Edit] in Chapter 2 [Diagnostic]. | Go to step 4. | Go to step 5. |
| 4 | Checking data on the NVRAM (2) <br> Change NVRAM data to the correct setup value, and then <br> turn the power ON again. <br> Does the error still occur? | Go to step 5. | End of work |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 5 | Checking the TRAY MODULE PWB <br> Are P/J413 and P/J541 connected surely? | Go to step 6. | Connect P/J413 <br> and P/541 surely. |
| 6 | Checking conductivity between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ <br> J541? | Go to step 7. | Fix open and <br> short circuit. |
| 7 | Checking +5 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across P/J413-A5 (+) <=> ground +5 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP 9.47) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

*1: External noise is considered to be the cause, proceed to Procedure 5.1.

## Tray Module NVM R/W error

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Does the error still occur when the power is turned ON again? | Go to step 3. | Go to step 2. |
| 2 | Does the error still occur after the power is turned ON/OFF repeatedly several times? | Go to step 3. | End of work *1 |
| 3 | Checking data on the NVRAM (1) Is data on the NVRAM accessible? Execute [NVM Edit] in Chapter 2 [Diagnostic]. | Go to step 4. | Go to step 5. |
| 4 | Checking data on the NVRAM (2) Change NVRAM data to the correct setup value, and then turn the power ON again. Does the error still occur? | Go to step 5. | End of work |
| 5 | Checking the TRAY MODULE PWB Are P/J413 and P/J541 connected surely? | Go to step 6. | Connect P/J413 and $P / 541$ surely. |
| 6 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J413-A5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |

## Tray Module Communication fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) | Checking the TRAY MODULE for installation <br> Disconnect the connector P/J541 of the TRAY MODULE <br> and reconnect it. <br> Does the tray module operate properly? | End of work |
| 2 | Checking the TRAY MODULE PWB for connection <br> Is P/J413 connected surely? | Go to step 2. |  |
| 3 | Checking conductivity between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ <br> J541? | Go to step 4. | Fix open and <br> short circuit. |
| 4 | Checking +5 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across P/J413-A5 (+) <=> ground +5 VDC? | Connect P/J413 <br> surely. |  |
| RRAY MODCe the <br> PWB. (RRP 9.47) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |  |  |

## TM type error

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY MODULE PWB (PL 9.6.1) PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the TRAY MODULE for installation Disconnect the connector P/J541 of the TRAY MODULE and reconnect it. Does the tray module operate properly? | End of work | Go to step 2. |
| 2 | Checking the TRAY MODULE PWB for connection Is P/J413 connected surely? | Go to step 3. | Connect P/J413 surely. |
| 3 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 4. | Fix open and short circuit. |
| 4 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J413-A5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |

## Tray 3 Size sensor broken

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY 3/4 PAPER SIZE SWITCH (PL 9.2.4) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper <br> Is paper loaded in the TRAY3 properly? <br> Pull out the TRAY3 to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 for installation <br> Is the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 installed properly? <br> Pull out the TRAY3 to check it. (Visual check) | Go to step 3. | Install the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 correctly. (RRP 9.8) |
| 3 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY3 with paper loaded is pulled out or pushed in? <br> Check it using [Input 07-03 TRAY3 SIZE SENSOR] in Chapter 2, Diag. | Reconnect the connector of the PWBA MCU F. | Go to step 4. |
| 4 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for TRAY3 for connection Are P/J820 and P/J548 connected securely? | Go to step 5. | Connect P/J820 and P/J548 securely. |
| 5 | Checking conductivity between the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 and the PWBA MCU F Is there normal conductivity between $\mathrm{P} / \mathrm{J} 820$ and $\mathrm{P} / \mathrm{J} 548$ ? | Go to step 6. | Fix open or short circuit. |
| 6 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 for power supply Is the voltage between J820-1 (+) and the ground (-) +3.3 VDC? | Replace the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3. (RRP 9.8) | Go to step 7. |
| 7 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected securely? | Go to step 8. | Connect P/J413 and P/541 securely. |
| 8 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there normal conductivity between $\mathrm{P} / \mathrm{J} 541$ and $\mathrm{P} / \mathrm{J} 413$ ? | Go to step 9. | Fix open or short circuit. |
| 9 | Checking the TRAY MODULE PWB for power supply Is the voltage between J413-A5 (+) and the ground ( - ) +5 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |

## Tray4 Size sensor broken

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY 3/4 PAPER SIZE SWITCH (PL 9.2.4) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper <br> Is paper loaded in the TRAY4 properly? <br> Pull out the TRAY4 to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 for installation <br> Is the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 installed properly? <br> Pull out the TRAY4 to check it. (Visual check) | Go to step 3. | Install the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 correctly. (RRP 9.9) |
| 3 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY4 with paper loaded is pulled out or pushed in? <br> Check it using [Input 07-04 TRAY4 SIZE SENSOR] in Chapter 2, Diag. | Reconnect the connector of the PWBA MCU F. | Go to step 4. |
| 4 | Checking the TRAY 3/4 PAPER SIZE SWITCH for TRAY4 for connection <br> Are P/J824 and P/J548 connected securely? | Go to step 5. | Connect P/J824 and P/J548 securely. |
| 5 | Checking conductivity between the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 and the PWBA MCU F Is there normal conductivity between $\mathrm{P} / \mathrm{J} 824$ and $\mathrm{P} / \mathrm{J} 548$ ? | Go to step 6. | Fix open or short circuit. |
| 6 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 for power supply <br> Is the voltage between J824-1 (+) and the ground (-) +3.3 VDC? | Replace the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4. (RRP 9.9) | Go to step 7. |
| 7 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected securely? | Go to step 8. | Connect P/J413 and $P / 541$ securely. |
| 8 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there normal conductivity between $\mathrm{P} / \mathrm{J} 541$ and $\mathrm{P} / \mathrm{J} 413$ ? | Go to step 9. | Fix open or short circuit. |
| 9 | Checking the TRAY MODULE PWB for power supply Is the voltage between J413-A5 (+) and the ground (-) +5 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |

## TM Cover open

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> LEFT COVER INTERLOCK SWITCH (PL 9.5.27) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the LEFT COVER ASSEMBLY (PL 9.5.10) for opening and closing <br> Does the LEFT COVER ASSEMBLY (PL 9.5.10) open or close normally? | Go to step 2. | Check the LEFT COVER ASSMEBLY for deformation and reinstall it. |
| 2 | Checking the LEFT COVER INTERLOCK SWITCH for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the LEFT COVER INTERLOCK SWITCH is pressed? Execute [Input 01-10 TRAY MODULE COVER] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 9.5.10) and check it. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 3. |
| 3 | Checking the LEFT COVER INTERLOCK SWITCH for connection <br> Are FS812, FS813 and P/J554 connected surely? | Go to step 4. | Connect FS812, FS813 and P/ J554 surely. |
| 4 | Checking conductivity between the LEFT COVER INTERLOCK SWITCH and the TRAY MODULE PWB Is there conductivity on each wire between FS812 <=> P/ J554? <br> Is there conductivity on each wire between FS813 <=> P/ J554? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking +24 VDC power supply to the LEFT COVER INTERLOCK SWITCH <br> Is the voltage across FS813 <=> ground +24 VDC? | Replace the LEFT COVER INTERLOCK SWITCH. (RRP 9.46) | Go to step 6. |
| 6 | Checking the TRAY MODULE PWB for connection Are P/J541 and P/J413 connected surely? | Go to step 7. | Connect P/J541 and P/J413 surely. |
| 7 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |

No paper in the select paper tray

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (NO PAPER SENSOR) (PL 9.4.14) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper <br> Is Paper loaded in the selected TRAY? | Go to step 2. | Load paper. |
| 2 | Checking the SENSOR (NO PAPER SENSOR) for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY with paper loaded is pulled out or pushed in? <br> For TRAY3: <br> Execute [Input 07-09 TRAY3 NO PAPER SENSOR] in Chapter 2 [Diagnostic]. <br> For TRAY4: <br> Execute [Input 07-10 TRAY4 NO PAPER SENSOR] in Chapter 2 [Diagnostic]. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 3. |
| 3 | Checking the SENSOR (NO PAPER SENSOR) for connection <br> For TRAY3: <br> Are P/J102B, P/J661B and P/J549B connected surely? <br> For TRAY4: <br> Are P/J102A, P/J661A and P/J549A connected surely? | Go to step 4. | Connect the connectors surely. |
| 4 | Checking conductivity between the SENSOR (NO PAPER SENSOR) and the PWBA MCU F <br> For TRAY3: <br> Is there conductivity on each wire between P/J102B <=> P/ J549B? <br> For TRAY4: <br> Is there conductivity on each wire between P/J102A <=> P/ J549A? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking +5 VDC power supply to the SENSOR (NO PAPER SENSOR) <br> For TRAY3: <br> Is the voltage across P/J102B-3 (+) <=> ground +5 VDC? <br> For TRAY4: <br> Is the voltage across P/J102A-3 (+) <=> ground +5 VDC? | Replace the SENSOR (NO PAPER SENSOR) for the TRAY. (RRP 9.23) | Go to step 6. |
| 6 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 7. | Connect P/J413 and $P / 541$ surely. |
| 7 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J413-A5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. <br> (RRP 8.4) |

## Paper size mismatch in width

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY 3/4 PAPER SIZE SWITCH (PL 9.2.4) <br> FRONT SIDE GUIDE (PL 9.3.6) <br> REAR SIDE GUIDE (PL 9.3.9) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper (1) Is paper loaded in the Tray properly? Pull out the TRAY to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the paper (2) <br> Are the FRONT SIDE GUIDE and REAR SIDE GUIDE of the TRAY3 and TRAY4 set correctly? <br> Pull out each TRAY to check it. (Visual check) | Go to step 3. | Set the parts properly. |
| 3 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for installation <br> Are the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 and TRAY4 installed properly? <br> Pull out each TRAY to check it. (Visual check) | Go to step 4. | Install the TRAY 3/4 PAPER SIZE SWITCH for each TRAY correctly. (RRP 9.8/RRP 9.9) |
| 4 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY with paper loaded is pulled out or pushed in? <br> For TRAY3: <br> Execute [Input 07-03 TRAY3 SIZE SENSOR] in Chapter 2 [Diagnostic]. <br> For TRAY4: <br> Execute [Input 07-04 TRAY4 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 5. |
| 5 | Checking the TRAY 3/4 PAPER SIZE SWITCH for connection <br> For TRAY3: <br> Are P/J820 and P/J548 connected surely? <br> For TRAY4 <br> Are P/J824 and P/J548 connected surely? | Go to step 6. | Connect the connectors surely. |
| 6 | Checking conductivity between the TRAY 3/4 PAPER SIZE SWITCH and the TRAY MODULE PWB <br> For TRAY3: <br> Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 820$ <=> P/ J548? <br> For TRAY4 <br> Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 824$ <=> P/ J548? | Go to step 7. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 7 | Checking +3.3 VDC power supply to the TRAY 3/4 PAPER <br> SIZE SWITCH | Replace the <br> For TRAY3: <br> Is the voltage across P/J820-1 $(+)$ <=> ground +3.3 VDC? <br> For TRAY4 <br> Is the voltage across P/J824-1 ( + ) <=> ground +3.3 VDC? | SWITCH ASSY P <br> S for the TRAY. <br> (RRP 9.8/RRP <br> $9.9)$ | Go to step 8.

## Tray 3 Paper size mismatch in length

| Step | Check | Yes | No |
| :--- | :--- | :--- | :---: |
|  | Possible causative parts: <br> TRAY 3/4 PAPER SIZE SWITCH (PL 9.2.4) <br> FRONT SIDE GUIDE (PL 9.3.6) <br> REAR SIDE GUIDE (PL 9.3.9) <br> SENSOR ASSY REGI (PL 4.5.7) <br> CLUTCH ASSY REGI (PL 4.5.5) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | Load paper prop- <br> erly. |
| 1 | Checking the paper (1) <br> Is paper loaded in the TRAY3 properly? <br> Pull out the TRAY3 to check it. (Visual check) | Go to step 3. | Set the parts <br> properly. |
| 2 | Checking the paper (2) <br> Are the FRONT SIDE GUIDE and REAR SIDE GUIDE of <br> the TRAY3 set correctly? <br> Pull out the TRAY3 to check it. (Visual check) | Go to step 4. | 3/4 PAPER SIZE <br> SWITCH for the <br> TRAY3 correctly. <br> (RRP 9.8) |
| 3 | Checking the TRAY 3/4 PAPER SIZE SWITCH for the <br> TRAY3 for installation <br> Is the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 <br> installed properly? <br> Pull out the TRAY3 to check it. (Visual check) | Install the TRAY |  |
|  | Checking the TRAY 3/4 PAPER SIZE SWITCH for opera- <br> tion <br> Does the Input Status change from "0x0" to "0x1" each <br> time the TRAY3 with paper loaded is pulled out or pushed <br> in? <br> Execute [Input 07-03 TRAY3 SIZE SENSOR] in Chapter 2 <br> [Diagnostic]. | Go to step 11. | Go to step 5. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 5 | Checking the TRAY 3/4 PAPER SIZE SWITCH for connection <br> Are P/J820 and P/J548 connected surely? | Go to step 6. | Connect P/J820 and P/J548 surely. |
| 6 | Checking conductivity between the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 and the TRAY MODULE PWB <br> Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 820$ <=> P/ J548? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +3.3 VDC power supply to the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 <br> Is the voltage across P/J820-1 (+) <=> ground +3.3 VDC? | Replace the SWITCH ASSY P S for the TRAY3. (RRP 9.8) | Go to step 8. |
| 8 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 9. | Connect P/J413 and $P / 541$ surely. |
| 9 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 10. | Fix open and short circuit. |
| 10 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J413-A5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |
| 11 | Checking the Roll for the TRAY3 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) <br> or ROLLER ASSY (NUDGER) for transport worn or con- <br> taminated with paper dust? <br> Pull out the TRAY3 and check it. | Go to step 12. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 9.28/RRP 9.32/ RRP 9.35)) |
| 12 | Checking paper position <br> Does the paper touch the SENSOR ASSY REGI? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 13. |
| 13 | Checking the Roll (1) <br> Is the ROLLER ASSY-TA for transport worn or contami- <br> nated with paper dust? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 14. | Clean or replace the ROLLER ASSY-TA. (RRP 4.3) |
| 14 | Checking the Roll (2) <br> Is the ROLLER of the TRANS ASSY REGI for transport (PL 4.5.1) worn or contaminated with paper dust? Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 15. | Clean or replace the rolls. |
| 15 | Checking the SENSOR ASSY REGI for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR ASSY REGI? Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 19. | Go to step 16. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 16 | Checking the SENSOR ASSY REGI for connection Are P/J104 and P/J403B connected surely? | Go to step 17. | Connect P/J104 and P/J403B surely. |
| 17 | Checking conductivity between the SENSOR ASSY REGI and the PWB A MCU <br> Is there conductivity on each wire between P/J104 <=> P/ J403B? | Go to step 18. | Fix open and short circuit. |
| 18 | Checking +5 VDC power supply to the SENSOR ASSY REGI <br> Is the voltage across P/J104-1 (+) <=> ground +5 VDC? | Replace the SENSORASSYREGI. (RRP 4.13) | Replace the PWBA MCU F. (RRP 8.4) |
| 19 | Checking the CLUTCH ASSY REGI H for operation Does the CLUTCH ASSY REGI H operate properly? Execute [Output 08-39 REGI CLUTCH (EXIT)] in Chapter 2 [Diagnostic]. | Replace the PWBA MCU F. (RRP 8.4) | Go to step 20. |
| 20 | Checking the CLUTCH ASSY REGI H for connection Are P/J215 and P/J403B connected surely? | Go to step 21. | Connect P/J215 and P/J403B surely. |
| 21 | Checking conductivity between the CLUTCH ASSY REGI H and the PWB A MCU Is there conductivity on each wire between P/J215 <=> P/ J403B? | Go to step 22. | Fix open and short circuit. |
| 22 | Checking +24 VDC power supply to the CLUTCH ASSY H Is the voltage across P215-2 (+) <=> ground +24 VDC? | Go to step 23. | Replace the PWBA MCU F. (RRP 8.4) |
| 23 | Checking the resistance of the CLUTCH ASSY REGI H Is the resistance across J215-1 and J215-2 approximately 240 ohm? | Replace the PWBA MCU F. (RRP 8.4) | Replace the CLUTCH ASSY REGI H. (RRP 4.11) |

## Tray 4 Paper size mismatch in length

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY 3/4 PAPER SIZE SWITCH (PL 9.2.4) <br> FRONT SIDE GUIDE (PL 9.3.6) <br> REAR SIDE GUIDE (PL 9.3.9) <br> SENSOR ASSY REGI (PL 4.5.7) <br> CLUTCH ASSY REGI (PL 4.5.5) <br> TRAY MODULE PWB (PL 9.6.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper (1) <br> Is paper loaded in the TRAY4 properly? <br> Pull out the TRAY4 to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the paper (2) <br> Are the FRONT SIDE GUIDE and REAR SIDE GUIDE of the TRAY4 set correctly? <br> Pull out the TRAY4 to check it. (Visual check) | Go to step 3. | Set the parts properly. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 3 | Checking the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 for installation <br> Is the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 installed properly? <br> Pull out the TRAY4 to check it. (Visual check) | Go to step 4. | Install the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 correctly. (RRP 9.9) |
| 4 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY3 is pulled out or pushed in, when the TRAY4 is loaded with paper? <br> Execute [Input 07-04 TRAY4 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Go to step 11. | Go to step 5. |
| 5 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 for connection Are P/J824 and P/J548 connected surely? | Go to step 6. | Connect P/J820 and P/J548 surely. |
| 6 | Checking conductivity between the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 and the TRAY MODULE PWB <br> Is there conductivity on each wire between P/J824 <=> P/ J548? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +3.3 VDC power supply to the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 Is the voltage across P/J824-1 (+) <=> ground +3.3 VDC? | Replace the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4. (RRP 9.9) | Go to step 8. |
| 8 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 9. | Connect P/J413 and P/541 surely. |
| 9 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 10. | Fix open and short circuit. |
| 10 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across P/J413-A5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 9.47) | Replace the PWBA MCU F. (RRP 8.4) |
| 11 | Checking the Roll for the TRAY4 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY4 and check it. | Go to step 12. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 9.28/RRP 9.32/ RRP 9.35) |
| 12 | Checking paper position <br> Does the paper touch the SENSOR ASSY REGI? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 13. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 13 | Checking the Roll (1) <br> Is the ROLLER ASSY-TA for transport worn or contami- <br> nated with paper dust? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 14. | Clean or replace the ROLLER ASSY-TA. (RRP 4.3) |
| 14 | Checking the Roll (2) Is the ROLLER of the TRANS ASSY REGI for transport (PL 4.5.1) worn or contaminated with paper dust? Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 15. | Clean or replace the XXX. |
| 15 | Checking the SENSOR ASSY REGI for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR ASSY REGI? Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 19. | Go to step 16. |
| 16 | Checking the SENSOR ASSY REGI for connection Are P/J104 and P/J403B connected surely? | Go to step 17. | Connect P/J104 and P/J403B surely. |
| 17 | Checking conductivity between the SENSOR ASSY REGI and the PWB A MCU <br> Is there conductivity on each wire between P/J104 <=> P/ J403B? | Go to step 18. | Fix open and short circuit. |
| 18 | Checking +5 VDC power supply to the SENSOR ASSY REGI <br> Is the voltage across P/J104-1 (+) <=> ground +5 VDC? | Replace the SEN SOR ASSYREGI. (RRP 4.13) | Replace the PWBA MCU F. (RRP 8.4) |
| 19 | Checking the CLUTCH ASSY REGI H for operation Does the CLUTCH ASSY REGI H operate properly? Execute [Output 08-39 REGI CLUTCH] in Chapter 2 [Diagnostic]. | Replace the PWBA MCU F. (RRP)8.4 | Go to step 20. |
| 20 | Checking the CLUTCH ASSY REGI H for connection Are P/J215 and P/J403B connected surely? | Go to step 21. | Connect P/J215 and P/J403B surely. |
| 21 | Checking conductivity between the CLUTCH ASSY REGI H and the PWB A MCU Is there conductivity on each wire between P/J215 <=> P/ J403B? | Go to step 22. | Fix open and short circuit. |
| 22 | Checking +24 VDC power supply to the CLUTCH ASSY REGI H Is the voltage across P215-2 (+) <=> ground +24 VDC? | Go to step 23. | Replace the PWBA MCU F. (RRP 8.4) |
| 23 | Checking the resistance of the CLUTCH ASSY REGI H Is the resistance across J215-1 and J215-2 approximately 240 ohm? | Replace the PWBA MCU F. (RRP 8.4) | Replace the CLUTCH ASSY REGI H. (RRP 4.11) |

## Registration Sensor on JAM (Duplex paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER DUP A3L (PL 10.2.7) <br> ROLLER ASSY DUP (PL 10.2.8) <br> MOTOR ASSY DUP (PL 10.1.11) <br> PWBA DUPLEX (PL 10.1.12) |  |  |
| 1 | Checking paper position <br> Does the paper touch the SENSOR ASSY REGI? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 2. |
| 2 | Checking the Duplex for installation <br> Remove TRANS ASSY DUP (PL 10.1.1) and reinstall it. <br> Does the error occur again when a test print of duplex <br> printing is carried out? <br> Execute [Test Print] in Chapter 2 [Diagnostic]. | Go to step 3. | End of work |
| 3 | Checking the Roll (1) <br> Open the COVER DUP (PL 10.1.13). <br> Is the Roller of the ROLLER DUP A3L worn or contaminated with paper dust? | Go to step 4. | Clean or replace the ROLLER DUP A3L. (RRP 10.11) |
| 4 | Checking the drive power transmission (1) Open the COVER DUP (PL 10.1.13). Do the ROLLER DUP A3L and the other gears rotate smoothly? | Go to step 5. | Replace the obstacles. |
| 5 | Checking the Roll (2) <br> Open the COVER DUP (PL 10.1.13). <br> Is the Roller of the ROLLER ASSY DUP worn or contaminated with paper dust? | Go to step 6. | Clean or replace the ROLLER ASSY DUP. (RRP 10.8) |
| 6 | Checking the drive power transmission (2) Open the COVER DUP (PL 10.1.13). <br> Do the ROLLER ASSY DUP and the other gears rotate smoothly? | Go to step 7. | Replace the obstacles. |
| 7 | Checking the MOTOR ASSY DUP for operation Does the MOTOR ASSY DUP operate properly? Execute [Output 08-38 DUP MOTOR] in Chapter 2 [Diagnostic]. | Go to step 15. | Go to step 8. |
| 8 | Checking the MOTOR ASSY DUP for connection Are P/J212 and P/J542 connected surely? | Go to step 9. | Connect P/J212 <br> and $P / J 542$ surely |
| 9 | Checking the MOTOR ASSY DUP for conductivity Is there conductivity on each wire between P/J212 <=> P/ J542? | Go to step 10. | Fix open and short circuit. |
| 10 | Checking +24 VDC power supply to the MOTOR ASSY DUP <br> Is the voltage across P542-1 (+) <=> ground +24 VDC? | Go to step 14. | Go to step 11. |
| 11 | Checking the PWBA Duplex for connection Are P/J540 and P/J417 connected surely? | Go to step 12. | Connect P/J540 and P/J417 surely. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 12 | Checking conductivity between the PWBA DUPLEX and <br> the PWBA MCU F <br> Is there conductivity on each wire between P/J540 < <br> J417? P/ | Replace the <br> PWBA DUPLEX. <br> (RRP 10.9) | Fix open and <br> short circuit. |

## Registration Sensor on JAM (Duplex paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER DUP A3L (PL 10.2.7) <br> ROLLER ASSY DUP (PL 10.2.8) <br> MOTOR ASSY DUP (PL 10.1.11) <br> SENSOR-PHOTO IN (PL 10.1.18) <br> PWBA DUPLEX (23.1.12) |  |  |
| 1 | Checking paper position Does the paper touch the SENSOR ASSY REGI? Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 2. |
| 2 | Checking paper position <br> Does the paper touch the SENSOR-PHOTO IN? <br> Open the COVER DUP (PL 10.1.13) and check it (visual check). | Remove the paper. | Go to step 3. |
| 3 | Checking the Duplex for installation <br> Remove TRANS ASSY DUP (PL 10.1.1) and reinstall it. <br> Does the error occur again when a test print of duplex printing is carried out? <br> Execute [Test Print] in Chapter 2 [Diagnostic]. | Go to step 4. | End of work |
| 4 | Checking the Roll (1) <br> Open the COVER DUP (PL 10.1.13). <br> Is the Roller of the ROLLER DUP A3L worn or contaminated with paper dust? | Go to step 5. | Clean or replace the ROLLER DUP A3L. (RRP 10.11) |
| 5 | Checking the drive power transmission (1) <br> Do the ROLLER DUP A3L and the other gears rotate smoothly? <br> Remove COVER DUP (PL 10.1.13). | Go to step 6. | Replace the obstacles. |
| 6 | Checking the Roll (2) <br> Open the COVER DUP (PL 10.1.13). <br> Is the Roller of the ROLLER ASSY DUP for transport worn or contaminated with paper dust? | Go to step 7. | Clean or replace the ROLLER ASSY DUP. (RRP 10.8) |
| 7 | Checking the drive power transmission (2) <br> Do the ROLLER ASSY DUP and the other gears rotate smoothly? <br> Remove COVER DUP (PL 10.1.13). | Go to step 8. | Replace the obstacles. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 8 | Checking the SENSOR-PHOTO IN for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR-PHOTO IN? Execute [Input 08-31 DUP WAIT SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER DUP (PL 10.1.13) and check it (visual check). | Go to step 14. | Go to step 9. |
| 9 | Checking the SENSOR-PHOTO IN for connection Are P/J123 and P/J541 connected surely? | Go to step 10. | $\begin{aligned} & \text { Connect P/J123 } \\ & \text { and P/J541 } \\ & \text { surely. } \end{aligned}$ |
| 10 | Checking conductivity between the SENSOR-PHOTO IN and the PWBA DUPLEX <br> Is there conductivity on each wire between $P / J 123<=>P /$ J541? | Go to step 11. | Fix open and short circuit. |
| 11 | Checking +5 VDC power supply to the SENSOR-PHOTO IN <br> Is the voltage across J123-3 (+) <=> ground +5 VDC? | Replace the SEN-SOR-PHOTO IN. (RRP 10.10) | Go to step 12. |
| 12 | Checking conductivity between the PWBA DUPLEX and the PWBA MCU F <br> Is there conductivity on each wire between P/J540 <=> P/ J417? | Replace the PWBA DUPLEX. (RRP 10.9) | Fix open and short circuit. |
| 13 | Checking the MOTOR ASSY DUP for operation Does the MOTOR ASSY DUP operate properly? Execute [Output 08-38 DUP MOTOR] in Chapter 2 [Diagnostic]. | Replace the PWBA DUPLEX. (RRP 10.9) | Go to step 14. |
| 14 | Checking the MOTOR ASSY DUP for connection Are P/J212 and P/J542 connected surely? | Go to step 15. | Connect P/J212 and P/J542 surely. |
| 15 | Checking the MOTOR ASSY DUP for conductivity Is there conductivity on each wire between P/J212 <=> P/ J542? | Go to step 16. | Fix open and short circuit. |
| 16 | Checking +24 VDC power supply to the MOTOR ASSY DUP <br> Is the voltage across P212-5 (+) <=> ground +24 VDC? | Replace the MOTOR ASSY DUP. (RRP 10.8) | Go to step 17. |
| 17 | Checking the PWBA DUPLEX for connection Are P/J540 and P/J417 connected surely? | Replace the PWBA DUPLEX. (RRP 10.9) | Connect P/J540 and P/J417 surely. |

## Duplex Sensor Static JAM

| Step | Check | Yes | No |
| :--- | :--- | :---: | :---: |
|  | Possible causative parts: <br> SENSOR-PHOTO IN (PL 10.1.18) <br> PWBA DUPLEX (23.1.12) |  |  |


| Step | Check | Yes | No |
| :---: | :--- | :--- | :--- |
| 1 | Checking paper position <br> Does the paper touch the SENSOR-PHOTO IN? <br> Open the COVER DUP (PL 10.1.13) and check it (visual <br> check). | Remove the <br> paper. | Go to step 2. |
| 2 | Checking the SENSOR-PHOTO IN for operation <br> Does the Input Status change from "0x0" to "0x1" each <br> time the paper touches the SENSOR-PHOTO IN? <br> Execute [Input 08-31 DUP WAIT SENSOR] in Chapter 2 <br> [Diagnostic]. <br> Open the COVER DUP (PL 10.1.13) and check it (visual <br> check). | Reconnect the <br> connector on the <br> PWBA MCU F. <br> (RRP 8.4) | Go to step 3. |
| 3 | Checking the SENSOR-PHOTO IN for connection <br> Are P/J123 and P/J541 connected surely? | Go to step 4. | Connect P/J123 <br> and P/J541 <br> surely. |
| 4 | Checking conductivity between the SENSOR-PHOTO IN <br> and the PWBA DUPLEX <br> Is there conductivity on each wire between P/J123 <=> P/ <br> J541? | Go to step 5. | Fix open and <br> short circuit. |
| 5 | Checking +5 VDC power supply to the SENSOR-PHOTO <br> IN <br> Is the voltage across J123-3 (+) <=> ground +5 VDC? | Replace the SEN- <br> SOR-PHOTO IN. <br> (RRP 10.10) | Go to step 6. |
| 6 | Checking conductivity between the PWBA DUPLEX and <br> the PWBA MCU F <br> Is there conductivity on each wire between P/J540 <=> P/ <br> J417? | Go to step 7. | Fix open and <br> short circuit. |
| 7 | Checking +5 VDC power supply to the PWBA DUPLEX <br> Is the voltage across P/J541-2 (+) <=> ground +5 VDC? | Replace the <br> PWBA DUPLEX. <br> (RRP 10.9) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

FIP 3.1 Duplex Wait SENSOR ON JAM

| Step | Check | Yes | No |
| :--- | :--- | :---: | :---: |
|  | Possible causative parts: <br> ROLL ASSY-FU (PL 11.1.19) <br> ROLL ASSY-INV (PL 11.1.20) <br> ROLL ASSY OCT (PL 11.2.7) <br> MOTOR ASSY EXIT 2 (PL 11.2.37) <br> PWBA EXIT (PL 8.1.4) <br> SENSOR-PHOTO IN (PL 10.1.18) <br> PWBA DUPLEX (23.1.12) | Ger |  |
| 1 | Checking paper position <br> Does the paper remain in the EXIT 2? <br> Open the CHUTE LH HIGH (PL 11.1.18) and check it <br> (visual check). | Remove the <br> paper. | Go to step 2. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 11 | Checking +24 VDC power supply to the MOTOR ASSY EXIT 2 <br> Is the voltage across P208-5 (+) <=> ground +24 VDC? | Replace the MOTOR ASSY EXIT 2. (RRP 11.16) | Go to step 12. |
| 12 | Checking the connection between the PWBA EXIT and the PWBA MCU F <br> Are P/J431 and P/J421 connected surely? | Go to step 13. | Connect P/J431 and P/J421 surely. |
| 13 | Checking conductivity between the PWBA EXIT and the PWBA MCU F <br> Is there conductivity on each wire between P/J431 <=> P/ J421? | Replace the PWBA EXIT. (RRP 8.3) | Fix open and short circuit. |
| 14 | Checking the SENSOR-PHOTO IN for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR-PHOTO IN? Execute [Input 08-31 DUP WAIT SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER DUP (PL 10.1.13) and check it (visual check). | Reconnect the connector on the PWBA MCU F. | Go to step 15. |
| 15 | Checking the SENSOR-PHOTO IN for connection Are P/J123 and P/J541 connected surely? | Go to step 16. | Connect P/J123 and P/J541 surely. |
| 16 | Checking conductivity between the SENSOR-PHOTO IN and the PWBA DUPLEX <br> Is there conductivity on each wire between P/J123 <=> P/ J541? | Go to step 17. | Fix open and short circuit. |
| 17 | Checking +5 VDC power supply to the SENSOR-PHOTO IN Is the voltage across J123-3 (+) <=> ground +5 VDC? | Replace the SEN-SOR-PHOTO IN. (RRP 10.10) | Replace the PWBA DUPLEX (RRP 10.9) |

## Duplex Module Communication fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | $\begin{array}{l}\text { Possible causative parts: } \\ \text { PWBA DUPLEX (23.1.12) } \\ \text { PWBA MCU F (PL 8.1.5) }\end{array}$ | End of work | Go to step 2. |
| 1 | $\begin{array}{l}\text { Checking the DUPLEX UNIT for installation } \\ \text { Remove the TRANS ASSY DUP (PL 10.1.1) and reinstall } \\ \text { it. Does it operate properly? }\end{array}$ | Go to step 3. | $\begin{array}{l}\text { Connect P/J540 } \\ \text { and P/J417 } \\ \text { surely. }\end{array}$ |
| 2 | $\begin{array}{l}\text { Checking the PWBA DUPLEX for connection } \\ \text { Are P/J540 and P/J417 connected surely? }\end{array}$ | Go to step 4. | Fix open and |
| short circuit. |  |  |  |$]$| Checking conductivity between the PWBA DUPLEX and |
| :--- |
| the PWBA MCU F |
| Is there conductivity on each wire between P/J540 <=> P/ |
| J417? |$\quad$| ( |
| :--- |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 4 | Checking +24 VDC power supply to the PWBA DUPLEX <br> Is the voltage across P540-2 (+) <<> ground +24 VDC? | Replace the <br> PWBA DUPLEX. <br> (RRP 10.9) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## DUP MODULE Type fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> PWBA DUPLEX (23.1.12) | Ehecking the DUPLEX UNIT for installation <br> Remove the TRANS ASSY DUP (PL 10.1.1) and reinstall <br> it. Does it operate properly? | End of work | Go to step 2.

## DUP Cover open

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: SWITCH-I/L, CAB (PL 10.1.9) PWBA DUPLEX (PL 10.1. |  |  |
| 1 | Checking the COVER DUP (PL 10.1.13) for opening and closing. <br> Does the COVER DUP (PL 10.1.13) open or close normally? | Go to step 2. | Check the COVER DUP for deformation and reinstall it |
| 2 | Checking the SWITCH-I/L, CAB for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the SWITCH-I/L, CAB is pressed? <br> Execute [Input 08-33 DUP INTERLOCK] in Chapter 2 [Diagnostic]. <br> Open the COVER DUP (PL 10.1.13) and check it (visual check). | Reconnect the connector on the PWBA MCU F. (RRP 8.4) | Go to step 3. |
| 3 | Checking the SWITCH-I/L, CAB for connection Are P/J124 and P/J541 connected surely? | Go to step 4. | Connect P/J124 and P/J541 surely. |
| 4 | Checking conductivity between the SWITCH-I/L, CAB and the PWBA DUPLEX <br> Is there conductivity on each wire between P/J124 <=> P/ J541? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking +5 VDC power supply to the SWITCH-I/L, CAB Is the voltage across J124-2 (+) <=> ground +5 VDC? | Replace the SWITCH-I/L, CAB. (RRP 10.6) | Go to step 6. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 6 | Checking the PWBA Duplex for connection <br> Are P/J540 and P/J417 connected surely? | Go to step 7. | Connect P/J540 <br> and P/J417 <br> surely. |
| 7 | Checking conductivity between the PWBA DUPLEX and <br> the PWBA MCU F <br> Is there conductivity on each wire between P/J540 <=> P/ <br> J417? | Go to step 8. | Fix open and <br> short circuit. |
| 8 | Checking +5 VDC power supply to the PWBA DUPLEX <br> Is the voltage across P540-1 (+) <=> ground +5 VDC? | Replace the <br> PWBA DUPLEX. <br> (RRP 10.9) | Connect the con- <br> nector on the <br> PWBA MCU F. <br> (RRP 8.4) |

## Exit Sensor2 ON, in FDT1/Fin simp job

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SOLENOID ASSY FU(PL 11.2.23) <br> SENSOR-PHOTO IN (PL 11.2.35) <br> PWBA EXIT (PL 8.1.4) |  |  |
| 1 | Checking the position of the SOLENOID ASSY FU Is SOLENOID ASSY FU facing toward the Exit1? | Go to step 2. | Go to step 4. |
| 2 | Checking the GATE SENSOR for operation Does the GATE-EXIT, 2 move smoothly? | Go to step 4. | Go to step 3. |
| 3 | Checking the GATE EXIT, 2 for foreign particle Are there any foreign particles near the GATE-EXIT, 2? | Reinstall the GATE-EXIT, 2. | Remove foreign particles. |
| 4 | Checking the SOLENOID ASSY FU for operation Does the SOLENOID ASSY FU operate properly? Check it using input 10-53 FACE UP GATE Solenoid in Chapter 2, Diagnostics. | Go to step 8. | Go to step 5. |
| 5 | Checking the SOLENOID ASSY FU for connection Are P/J210, P/J606A and P/J433 connected securely? | Go to step 6. | Connect P/J210 P/J606A and P/ J433 securely. |
| 6 | Checking conductivity between the SOLENOID ASSY FU and PWBA EXIT <br> Is there normal conductivity between $\mathrm{P} / \mathrm{J} 210$ and $\mathrm{P} / \mathrm{J} 433$ ? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking the SOLENOID ASSY FU for power supply Is the voltage between P210-2 (+) and the ground (-)+24 VDC? | Replace the SOLENOID ASSY FU. (RRP 11.11) | Replace the PWBA EXIT. (RRP 8.3) |
| 8 | Checking paper position <br> Does the paper touch the SENSOR-PHOTO IN? <br> Open the CHUTE LH HIGH (PL 11.1.18) and check it (visual check). | Remove the paper. | Go to step 9. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 9 | Checking the SENSOR-PHOTO IN for operation <br> Does the SENSOR-PHOTO IN operate properly? <br> Check it using input 10-52 EXIT SENSOR2î in Chapter 2, <br> Diagnostics. | Reconnect the <br> connector on the <br> PWBA MCU F. | Go to step 10. |
| 10 | Checking the SENSOR-PHOTO IN for connection <br> Are P/J112, P/J606B and P/J434 connected securely? | Go to step 11. | Connect P/J112, <br> P/J606B and P/ <br> J434 securely. |
| 11 | Checking conductivity between the SENSOR-PHOTO IN <br> and the PWBA EXIT <br> Is there normal conductivity between P/J112 and P/J434? | Go to step 12. | Fix open and <br> short circuit. |
| 12 | Checking the SENSOR-PHOTO IN for power supply <br> Is the voltage between P/J112-3 (+) and the ground (-) +5 <br> VDC? | Replace the SEN- <br> SOR-PHOTO IN. <br> (RRP 11.14) | Replace the <br> PWBA EXIT. <br> (RRP 8.3) |

Exit Sensor 2 Static JAM

| Step | Check | Yes | No |
| :---: | :--- | :--- | :--- |
|  | Possible causative parts: <br> SENSOR-PHOTO IN (PL 11.2.35) <br> PWBA EXIT (PL 8.1.4) | Checking paper position <br> Does the paper touch the SENSOR-PHOTO IN? <br> Open the CHUTE LH HIGH (PL 11.1.18) and check it <br> (visual check). | Remove the <br> paper. |
| 2 | Checking the SENSOR-PHOTO IN for operation (1) <br> Execute [Input 10-52 EXIT SENSOR2] in Chapter 2 [Diag- <br> nostic]. <br> Does the Input Status change from "0x0" to "0x1" each <br> time the ACTUATOR EXIT (PL 11.2.17) of the SENSOR- <br> PHOTO IN is operated? | Reconnect the <br> connector on the <br> PWBA MCU F. <br> (RRP 8.4) | Go to step 2. |
| 3 | Checking the SENSOR-PHOTO IN for connection (2) <br> Are P/J112, P/J606B and P/J434 connected surely? | Go to step 4. | Connect P/J112, <br> P/J606B and P/ <br> J434 surely. |
| 4 | Checking conductivity between the SENSOR-PHOTO IN <br> and the PWBA EXIT <br> Is there conductivity on each wire between P/J112 <=> P/ <br> J434? | Go to step 5. | Fix open and <br> short circuit. |
| 5 | Checking +5 VDC power supply to the SENSOR-PHOTO <br> IN <br> Is the voltage across J112-3 (+) <=> ground +5 VDC? | Replace the SEN- <br> SOR-PHOTO IN. <br> (RRP 11.14) | Replace the <br> PWBA EXIT. <br> (RRP 8.3) |

OCT2 fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> OCT POSITION SENSOR-PHOTO IN (PL 11.2.54) <br> MOTOR ASSY-OFFSET (PL 11.2.30) <br> PWBA EXIT (PL 8.1.4) |  |  |
| 1 | Checking the OCT POSITION SENSOR-PHOTO IN for operation (1) <br> Execute [Input 07-34 OCT2 HOME POSITION SENSOR] in Chapter 2 [Diagnostic]. <br> Open the TRANS ASSY EXIT 2 (PL 11.1.1). | Go to step 5. | Go to step 2. |
| 2 | Checking the OCT POSITION SENSOR-PHOTO IN for connection <br> Are P/J111, P/J606B and P/J434 connected surely? | Go to step 3. | Connect P/J111, <br> P/J606B and P/ J434 surely. |
| 3 | Checking conductivity between the OCT POSITION SEN-SOR-PHOTO IN and the PWBA EXIT Is there conductivity on each wire between P/J111 <=> P/ J434? | Go to step 4. | Fix open and short circuit. |
| 4 | Checking +5 VDC power supply to the OCT POSITION SENSOR-PHOTO IN Is the voltage across J111-3 (+) <=> ground +5 VDC? | Replace the OCT POSITION SEN-SOR-PHOTO IN. (RRP 11.15) | Replace the PWBA EXIT. (RRP 8.3) |
| 5 | Checking the MOTOR ASSY-OFFSET for operation (1) Does the MOTOR ASSY-OFFSET operate properly? Execute [Output 10-25 OFFSET MOTOR2 REVERSE ROTATION] in Chapter 2 [Diagnostic]. | Reconnect the connector on the PWBA MCU F. | Go to step 11. |
| 6 | Checking the MOTOR ASSY-OFFSET for connection Are P/J207, P/J606A and P/J433 connected surely? | Go to step 7. | Connect P/J207 <br> P/J606A and P/ J433 surely. |
| 7 | Checking conductivity between the MOTOR ASSY-OFFSET and PWBA EXIT Is there conductivity on each wire between P/J207 <=> P/ J433? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +24 VDC power supply to the MOTOR ASSYOFFSET <br> Is the voltage across P207-5 (+) <=> ground +24 VDC? | Replace the MOTOR ASSYOFFSET. (RRP 11.13) | Replace the PWBA EXIT. (RRP 8.3) |

## L/H-H Cover open

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> SWITCH-I/L, CAB (PL 11.1.18) <br> PWBA EXIT (PL 8.1.4) |  |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking the CHUTE LH HIGH (PL 11.1.18) for opening <br> and closing <br> Does the CHUTE LH HIGH (PL 11.1.18) open or close nor- <br> mally? | Go to step 2. | Check the <br> for deformation, <br> and then reinstall <br> it. |
| 2 | Checking the SWITCH-I/L, CAB for operation <br> Does the Input Status change from "0x0" to "Ox1" each <br> time the SWITCH-I/L, CAB is pressed? <br> Check it using [Input 01-13 L/H High COVER] in Chapter 2, <br> Diagnostics. <br> Open the CHUTE LH HIGH (PL 11.1.18) and check it. | Reconnect the <br> connector of the <br> PWBA MCU F. | Go to step 3. |
| 3 | Checking the SWITCH-I/L, CAB for connection <br> Are P/J116, P/J606B and P/J434 connected securely? | Go to step 4. | Connect P/J116, <br> P/J606B and P/ <br> J434 securely. |
| 4 | Checking conductivity between the SWITCH-I/L, CAB and <br> the PWBA EXIT <br> Is there normal conductivity between P/J116 and P/J434? | Go to step 5. | Fix open or short <br> circuit. |
| 5 | Checking the SWITCH-I/L, CAB for power supply <br> Is the voltage between P/J116-2 (+) and the ground (-) +5 <br> VDC? | Replace the <br> SWITCH-I/L, <br> CAB. (RRP 11.9) | Replace the <br> PWBA EXIT. <br> (RRP 8.3) |

F4-12 Finisher H-Transport Entrance Sensor On Jam

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :--- | :---: |
|  | Possible causative parts: <br> BELT (PL 12.3.12) <br> PINCH ROLL (PL 12.2.6) <br> WIRE HARNESS (PL 12.3.26) <br> PWB H-TRA (PL 12.14.3) <br> H-TRANSPORT ENTRANCE SENSOR (PL 12.3.23) <br> H-TRANSPORT MOTOR (PL 12.3.7) <br> PWB MAIN-C (PL 12.14.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
|  | Checking the paper path <br> Open the COVER ASSY TOP (PL 12.2.9) of the H- <br> TRANSPORT ASSEMBLY (PL 12.1.2). <br> Are two BELTs (PL 12.3.12) and the PINCH ROLL (PL <br> 12.2.6) attached on the COVER ASSY TOP installed <br> correctly? <br> Also, are they not contaminated or damaged, and rotated <br> smoothly? <br> Check these items by turning them with your fingers. <br> Are there any stains such as paper dust on the paper <br> path? | Go to step 2. | PINCH ROLL, <br> and clean the <br> paper path. |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 2 | Checking the H-TRANSPORT ENTRANCE SENSOR (Finisher H-Transport Entrance Sensor) for operation Execute [Input 12-28 H-Transport Ent.SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the actuator of the H-TRANSPORT ENTRANCE SENSOR is operated? | Go to step 8. | Go to step 3. |
| 3 | Checking the WIRE HARNESS (PL 12.3.26) connection Are the connectors of the WIRE HARNESS connected to the H-TRANSPORT ENTRANCE SENSOR and H-TRA of the Finisher connected correctly? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the WIRE HARNESS for conductivity Disconnect J8380 of the H-TRANSPORT ENTRANCE SENSOR, and P8372 connected to the PWB H-TRA of the Finisher. <br> Check for conductivity at the following: $\begin{array}{\|l} \text { P8372-7 <=> J8380-3 } \\ \text { P8372-8 <=> J8380-2 } \\ \text { P8372-9 <=> J8380-1 } \end{array}$ | Go to step 6. | Replace the WIRE HARNESS |
| 6 | Checking +5 VDC power supply to the H-TRANSPORT ENTRANCE SENSOR <br> Is the voltage across J8372-9 <=> J8372-7 on the PWB HTRA of the Finisher +5 VDC? | Go to step 7. | Replace the PWB H-TRA. (RRP 12.97) |
| 7 | Checking the H-TRANSPORT ENTRANCE SENSOR for operation <br> Does the voltage across J8372-8 <=> J8372-7 on the PWB H-TRA of the Finisher change, every time the actuator of the H-TRANSPORT ENTRANCE SENSOR is operated? | Replace the PWB H-TRA. (RRP 12.97) | Replace the H-TRANSPORT ENTRANCE SENSOR. (RRP 12.13) |
| 8 | Checking the H-TRANSPORT MOTOR for operation Execute [Output 12-01 H XPORT Motor 145 ON/OFF] in [Diagnosis]. <br> Does the H-TRANSPORT MOTOR rotate normally? | Replace the PWB H-TRA. (RRP 12.97) | Go to step 9. |
| 9 | Checking the WIRE HARNESS connection Are the connectors of the WIRE HARNESS connected to the H-TRANSPORT MOTOR and H-TRA of the Finisher connected correctly? | Go to step 11. | After reconnecting, go to step 10 |
| 10 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 11. | End of work. |


| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 11 | Checking the WIRE HARNESS for conductivity <br> Disconnect P/J8379 of the H-TRANSPORT MOTOR, and P8372 on the PWB H-TRA of the Finisher. <br> Check for conductivity at the following: <br> P8372-13 <=> J8379-6 <br> P8372-12 <=> J8379-4 <br> P8372-11 <=> J8379-1 <br> P8372-10 <=> J8379-3 <br> P8372-15 <=> J8379-2 <br> P8372-14 <=> J8379-5 | Go to step 12. | Replace the WIRE HARNESS. |
| 12 | Checking the resistance of the H-TRANSPORT MOTOR Are there any resistances without disconnection across P8379-2/5(COM) and P8379-1/3/4/6 of the H-TRANSPORT MOTOR? | Go to step 13. | Replace the H-TRANSPORT MOTOR. (RRP 12.10) |
| 13 | Checking +24 VDC power supply to the H-TRANSPORT MOTOR <br> Is the voltage across J8372-15 <=> J8372-7, and J837214 <=> J8372-7 on the PWB H-TRA of the Finisher +24 VDC? | Go to step 14. | Replace the PWB H-TRA. (RRP 12.97) |
| 14 | Checking after replacing the H -TRANSPORT MOTO Replaced the H-TRANSPORT MOTOR. (RRP 12.10) Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 15. | End of work. |
| 15 | Checking after replacing the PWB H-TRA Replace the PWB H-TRA. (RRP 12.97) Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 16. | End of work. |
| 16 | Checking after replacing the PWB MAIN-C Replace the PWB MAIN-C. (RRP 12.98) Execute [Test Print] in [Diagnosis]. Does the error still occur? | Replace the PWBA MCU F. (RRP 8.4) | End of work. |

F4-22 Finisher H-Transport Exit Sensor On Jam A

## NOTE This FIP can also be applied for the followings.

NOTE F4-23 Finisher H-Transport Exit Sensor On Jam B
NOTE F4-24 Finisher H-Transport Exit Sensor On Jam C

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :--- | :--- |
|  | Possible causative parts: <br> BELT (PL 12.3.12) <br> PINCH ROLL (PL 12.2.6) <br> WIRE HARNESS (PL 12.3.26) |  |  |
|  | PWB H-TRA (PL 12.14.3) <br> H-TRANSPORT EXIT SENSOR (PL 12.3.21) <br> H-TRANSPORT MOTOR (PL 12.3.7) <br> PWB MAIN-C (PL 12.14.5) <br> PWBA MCU F (PL 8.1.5) |  |  |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking the paper path <br> Open the COVER ASSY TOP (PL 12.2.9) of the H- <br> TRANSPORT ASSEMBLY (PL 12.1.2). <br> Are two BELTs (PL 12.3.12) and the PINCH ROLL (PL <br> 12.2.6) attached on the COVER ASSY TOP installed correctly? <br> Also, are they not contaminated or damaged, and rotated smoothly? <br> Check these items by turning them with your fingers. Are there any stains such as paper dust on the paper path? | Go to step 2. | Clean or replace the BELTs and PINCH ROLL, and clean the paper path. |
| 2 | Checking the H-TRANSPORT EXIT SENSOR (Finisher <br> H-Transport Exit Sensor) for operation <br> Execute [Input 12-29 H-Transport Exit SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the actuator of the H-TRANSPORT EXIT SENSOR is operated? | Go to step 8. | Go to step 3. |
| 3 | Checking the WIRE HARNESS (PL 12.3.26) connection Are the connectors of the WIRE HARNESS connected to the H-TRANSPORT EXIT SENSOR and the PWB H-TRA of the Finisher connected correctly? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the WIRE HARNESS for conductivity Disconnect J8381 of the H-TRANSPORT EXIT SENSOR, and P/J8372 on the PWB H-TRA of the Finisher. Check for conductivity at the following: $\begin{aligned} & \text { P8372-4 <=> J8381-3 } \\ & \text { P8372-5 <=> J8381-2 } \\ & \text { P8372-6 <=> J8381-1 } \end{aligned}$ | Go to step 6. | Replace the WIRE HARNESS. |
| 6 | Checking +5 VDC power supply to the H-TRANSPORT EXIT SENSOR <br> Is the voltage across J8372-6 <=> J8372-4 on the PWB H -TRA of the Finisher +5 VDC ? | Go to step 7. | Replace the PWB H-TRA. (RRP 12.97) |
| 7 | Checking the H-TRANSPORT EXIT SENSOR for operation <br> Does the voltage across J8372-5 <=> J8372-4 on the PWB H-TRA of the Finisher change, every time the actuator of the H-TRANSPORT EXIT SENSOR is operated? | Replace the PWB H-TRA. (RRP 12.97) | Replace the H-TRANSPORT EXIT SENSOR. (RRP 12.14) |
| 8 | Checking the H-TRANSPORT MOTOR for operation Execute [Output 12-01 H XPORT Motor 145 ON/OFF] in [Diagnosis] <br> Does the H-TRANSPORT MOTOR rotate normally? | Replace the PWB H-TRA. (RRP 12.97) | Go to step 9. |
| 9 | Checking the WIRE HARNESS connection Are the connectors of the WIRE HARNESS connected to the H-TRANSPORT MOTOR and the H-TRA of the Finisher connected correctly? | Go to step 11. | After reconnecting, go to step 10. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 10 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 11. | End of work. |
| 11 | Checking the WIRE HARNESS for conductivity <br> Disconnect P/J8379 of the H-TRANSPORT MOTOR, and P8372 on the PWB H-TRA of the Finisher. <br> Check for conductivity at the following: <br> P8372-13 <=> J8379-6 <br> P8372-12 <=> J8379-4 <br> P8372-11 <=> J8379-1 <br> P8372-10 <=> J8379-3 <br> P8372-15 <=> J8379-2 <br> P8372-14 <=> J8379-5 | Go to step 12. | Replace the WIRE HARNESS. |
| 12 | Checking the resistance of the H-TRANSPORT MOTOR Are there any resistances without disconnection across P8379-2/5(COM) and P8379-1/3/4/6 of the H-TRANSPORT MOTOR? | Go to step 13. | Replace the H-TRANSPORT MOTOR. (RRP 12.10) |
| 13 | Checking +24 VDC power supply to the H-TRANSPORT MOTOR <br> Is the voltage across J8372-15 <=> J8372-7, and J837214 <=> J8372-7 on the PWB H-TRA of the Finisher +24 VDC? | Go to step 14. | Replace the PWB H-TRA. (RRP 12.97) |
| 14 | Checking after replacing the H-TRANSPORT MOTOR Replace the H-TRANSPORT MOTOR. (RRP 12.10) Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 15. | End of work. |
| 15 | Checking after replacing the PWB H-TRA Replace the PWB H-TRA. (RRP 12.97) Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 16. | End of work. |
| 16 | Checking after replacing the PWB MAIN-C <br> Replace the PWB MAIN-C. (RRP 12.98) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the PWBA MCU F. (RRP 8.4) | End of work. |

F4-32 Finisher Transport Entrance Sensor On Jam

| $\begin{aligned} & \text { Ste } \\ & \text { p } \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> BELT (PL 12.3.12) <br> PINCH ROLL (PL 12.2.6) <br> WIRE HARNESS (PL 12.3.26) <br> PWB H-TRA (PL 12.14.3) <br> H-TRANSPORT EXIT SENSOR (PL 12.3.21) <br> H-TRANSPORT MOTOR (PL 12.3.7) <br> HARNESS ASSY X'PORT ENT SENSOR (PL 12.15.4) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> SENSOR (PL 12.12.19) <br> PWB MAIN-C (PL 12.14.5) |  |  |
| 1 | Checking the paper path <br> Open the COVER ASSY TOP (PL 12.2.9) of the H- <br> TRANSPORT ASSEMBLY (PL 12.1.2). <br> Are two BELTs (PL 12.3.12) and the PINCH ROLL (PL <br> 12.2.6) attached on the COVER ASSY TOP installed correctly? <br> Also, are they not contaminated or damaged, and rotated smoothly? <br> Check these items by turning them with your fingers. Are there any stains such as paper dust on the paper path? | Go to step 2. | Clean or replace the BELTs and PINCH ROLL, and clean the paper path. |
| 2 | Checking H-TRANSPORT EXIT SENSOR (Finisher H- <br> Transport Exit Sensor) for operation <br> Execute [Input 12-29 H-Transport Exit SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the actuator of the H-TRANSPORT EXIT SENSOR is operated? | Go to step 8. | Go to step 3. |
| 3 | Checking the WIRE HARNESS (PL 12.3.26) connection Are the connectors of the WIRE HARNESS connected to the H-TRANSPORT EXIT SENSOR and the H-TRA of the Finisher connected correctly? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the WIRE HARNESS for conductivity Disconnect J 8381 of the H-TRANSPORT EXIT SENSOR, and P8372 on the PWB H-TRA of the Finisher. <br> Check for conductivity at the following: $\begin{aligned} & \text { P8372-4 <=> J8381-3 } \\ & \text { P8372-5 <=> J8381-2 } \\ & \text { P8372-6 <=> J8381-1 } \end{aligned}$ | Go to step 6. | Replace the WIRE HARNESS. |
| 6 | Checking +5 VDC power supply to the H-TRANSPORT EXIT SENSOR <br> Is the voltage across J8372-6 <=> J8372-4 on the PWB H -TRA of the Finisher +5 VDC ? | Go to step 7. | Replace the PWB H-TRA. (RRP 12.97) |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 7 | Checking the H-TRANSPORT EXIT SENSOR for operation <br> Does the voltage across J8372-5 <=> J8372-4 on the PWB H-TRA of the Finisher change, every time the actuator of the H-TRANSPORT EXIT SENSOR is operated? | Replace the PWB H-TRA. (RRP 12.97) | Replace the H-TRANSPORT EXIT SENSOR. (RRP 12.14) |
| 8 | Checking the H-TRANSPORT MOTOR for operation Execute [Output 12-01 H XPORT Motor 145 ON/OFF] in [Diagnosis]. <br> Does the H-TRANSPORT MOTOR rotate normally? | Go to step 16. | Go to step 9. |
| 9 | Checking the WIRE HARNESS connection Are the connectors of the WIRE HARNESS connected to the H-TRANSPORT MOTOR and the H-TRA of the Finisher connected correctly? | Go to step 11. | After reconnecting, go to step 10. |
| 10 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 11. | End of work. |
| 11 | Checking the WIRE HARNESSE for conductivity Disconnect P/J8379 of the H-TRANSPORT MOTOR, and P8372 on the PWB H-TRA of the Finisher. <br> Check for conductivity at the following: <br> P8372-13 <=> J8379-6 <br> P8372-12 <=> J8379-4 <br> P8372-11 <=> J8379-1 <br> P8372-10 <=> J8379-3 <br> P8372-15 <=> J8379-2 <br> P8372-14 <=> J8379-5 | Go to step 12. | Replace the WIRE HARNESS. |
| 12 | Checking the resistance of the H-TRANSPORT MOTOR Are there any resistances without disconnection across P8379-2/5(COM) and P8379-1/3/4/6 of the H-TRANSPORT MOTOR? | Go to step 13. | Replace the H-TRANSPORT MOTOR. (RRP 12.10) |
| 13 | Checking +24 VDC power supply to the H-TRANSPORT MOTOR <br> Is the voltage across J8372-15 <=> J8372-7, and J837214 <=> J8372-7 on the PWB H-TRA of the Finisher +24 VDC? | Go to step 14. | Replace the PWB H-TRA. (RRP 12.97) |
| 14 | Checking after replacing the H-TRANSPORT MOTOR <br> Replace the H-TRANSPORT MOTOR. (RRP 12.10) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 15. | End of work. |
| 15 | Checking after replacing the PWB H-TRA Replace the PWB H-TRA. (RRP 12.97) Execute [Test Print] in [Diagnosis]. Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |
| 16 | Checking the SENSOR (Transport Entrance Sensor) for operation <br> Execute [Input 12-30 Transport Entrance SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time a piece of white paper is placed over the sensing area of the SENSOR (Transport Entrance Sensor)? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 17. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 17 | Checking the HARNESS ASSY connection Are P/J8319 and P/J8303 of the HARNESS ASSY X'PORT ENT SENSOR, and P/J8302A of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 19. | After reconnecting, go to step 18. |
| 18 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 19. | End of work. |
| 19 | Checking the HARNESS ASSY X'PORT ENT SENSOR for conductivity <br> Disconnect P/J8319 and P/J8303 of the HARNESS ASSY X'PORT ENT SENSOR. <br> Check for conductivity at the following: $\begin{array}{\|l} \text { J8319-3 <=> J8303B-1 } \\ \text { J8319-2 <=> J8303B-2 } \\ \text { J8319-1 <=> J8303B-3 } \end{array}$ | Go to step 20. | Replace the HARNESSASSY X'PORT ENT SENSOR. |
| 20 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8303 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8303A-3 <=> J8302A-1 } \\ & \text { J8303A-2 <=> J8302A-2 } \\ & \text { J8303A-1 <=> J8302A-3 } \end{aligned}$ | Go to step 21. | Replace the HARNESSASSY MAIN SENSOR. |
| 21 | Checking +5 VDC power supply to the SENSOR (Transport Entrance Sensor) <br> Is the voltage across J8302A-3 <=> J8302A-1 on the PWB MAIN-C +5 VDC? | Go to step 22. | Replace the WB MAIN-C. (RRP 12.98) |
| 22 | Checking the SENSOR (Transport Entrance Sensor) for operation <br> Does the voltage across P8302A-2 <=> P8302A-1 on the PWB MAIN-C change, every time a piece of white paper is placed over the sensing area of the SENSOR (X'port Entrance Sensor)? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR. (RRP 12.82) |

## F4-42 Finisher Buffer Path Sensor On Jam A

NOTE This FIP can also be applied for the following.
NOTE F4-43 Finisher Buffer Path Sensor On Jam B

| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLL ASSY-ENT (PL 12.12.20) <br> ROLLER ASSY-PINCH, ENT (PL 12.12.17) <br> ROLL ASSY-BUFFER (PL 12.12.13) <br> ROLLER-PINCH (PL 12.12.2) <br> HARNESS ASSY X'PORT ENT SENSOR (PL 12.15.4) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> SENSOR (PL 12.12.19) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) <br> SENSOR (PL 12.13.15) <br> HARNESS ASSY-SENSOR (PL 12.13.16) <br> BRACKET ASSY SOL (PL 12.12.34) <br> MOTOR ASSY (PL 12.13.30) <br> HARNESS ASSY BUFFER SENSOR (PL 12.15.5) <br> SENSOR ASSY (PL 12.12.12) |  |  |
| 1 | Checking the paper path <br> Open the COVER ASSY FRONT (PL 12.5.3) of the Finisher. <br> Remove the COVER TOP (PL 12.4.1) and COVER LH TOP (PL 12.5.9). <br> Open the CHUTE ASSY-UPPER, ENT (PL 12.12.16) to upward. <br> Are the ROLL ASSY-ENT (PL 12.12.20) and the ROLLER ASSY-PINCH, ENT (PL 12.12.17) attached on the CHUTE ASSY-UPPER,ENT installed correctly? <br> Also, are they not contaminated or damaged, and rotated smoothly? <br> Check these items by turning them with your fingers. Are there any stains such as paper dust on the paper path? | Go to step 2. | Clean or replace the appropriate ROLLER, and clean the paper path. |
| 2 | Checking the paper path <br> Open the COVER ASSY FRONT (PL 12.5.3) of the Finisher. <br> Remove the COVER TOP (PL 12.4.1) and COVER LH TOP (PL 12.5.9). <br> Open the CHUTE ASSY-UPPER, EXIT OPEN (PL 12.12.1) to right. <br> Are the ROLL ASSY-BUFFER (PL 12.12.13) and the ROLLER-PINCH (PL 12.12.2) attached on the CHUTE ASSY-UPPER, EXIT OPEN installed correctly? <br> Also, are they not contaminated or damaged, and rotated smoothly? <br> Check these items by turning them with your fingers. Are there any stains such as paper dust on the paper path? | Go to step 3. | After cleaning or replacing the appropriate ROLLER, go to step 3. |
| 3 | Checking the SENSOR (Gate Sensor) for operation Execute [Input 12-51 Gate SENSOR] in [Diagnosis] Does the display on the screen change, every time a piece of white paper is placed over the sensing area of the SENSOR (Gate Sensor)? | Go to step 9. | Go to step 4. |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 4 | Checking the HARNESS ASSY-SENSOR connection <br> Is the connector of the HARNESS ASSY-SENSOR <br> connected correctly? | Go to step 6. | After reconnect- <br> ing, go to step 5. |
| 5 | Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 6. | End of work. |
| 6 | Checking the HARNESS ASSY-SENSOR for conductivity <br> Disconnect P/J8432 and P/J8376 of the HARNESS <br> ASSY-SENSOR. <br> Check for conductivity at the following: <br> J8432-3<=> J8376-1 <br> J8432-2 <=> J8376-2 <br> J8432-1 <=> J8376-3 | Checking +5 VDC power supply to the SENSOR (Gate <br> Sensor) <br> Is the voltage across P8376-3 <=> P8376-1 on the PWB <br> MAIN-C +5 VDC? | Go to step 8. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 15 | Checking the MOTOR ASSY (Registration Motor) for operation <br> Execute [Output 12-05 Registration Motor 285F ON/OFF] in [Diagnosis] <br> Does the MOTOR ASSY (Registration Motor) rotate normally? | Go to step 16. | Go to step 18. |
| 16 | Checking the MOTOR ASSY (Registration Motor) for power transmission <br> Execute [Output 12-05 Registration Motor 285F ON/OFF] in [Diagnosis]. <br> Does the rotation of the MOTOR ASSY transmit to the ROLL ASSY-BUFFER (PL 12.12.13) through the BELT (PL 12.13.27)? | Go to step 24. | After reinstalling the MOTOR ASSY and BELT, go to step 33. (RRP 12.96) |
| 17 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 24. | End of work. |
| 18 | Checking the HARNESS ASSY MAIN DRIVE connection Are P/J8335 and P/J8304 of the HARNESS ASSY MAIN DRIVE connected surely? | Go to step 20. | After reconnecting, go to step 19. |
| 19 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 20. | End of work. |
| 20 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8335 and P/J8304 of the HARNESS ASSY MAIN DRIVE. <br> Check for conductivity at the following: <br> J8335-1 <=> J8304-7 <br> J8335-2 <=> J8304-8 <br> J8335-3 <=> J8304-9 <br> J8335-4 <=> J8304-11 <br> J8335-5 <=> J8304-10 <br> J8335-6 <=> J8304-13 | Go to step 21. | Replace the HARNESSASSY MAIN DRIVE. |
| 21 | Checking the resistance of the MOTOR ASSY Are there any resistances without disconnection cross P8335-2/5(COM) and P8335-1/3/4/6 of the MOTOR ASSY? | Go to step 22 | Replace the MOTOR ASSY. (RRP 12.96) |
| 22 | Checking +24 VDC power supply to the MOTOR ASSY Are the voltages across J8304-8 <=> FRAME CHASSIS and J8304-10 <=> FRAME CHASSIS on the PWB MAINC + 24 VDC? | Go to step 23. | Replace the PWB MAIN-C. (RRP 12.98) |
| 23 | Checking after replacing the MOTOR ASSY (Registration Motor) <br> Replace the MOTOR ASSY (Registration Motor). (RRP 12.96) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 24 | Checking the SENSOR ASSY (Buffer Path Sensor) for operation <br> Execute [Input 12-31 Buffer Path SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the actuator of the SENSOR ASSY (Buffer Path Sensor) is operated? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 26. |
| 25 | Checking the HARNESS ASSY BUFFER SENSOR connection <br> Are P/J8392 and P/J8318 of the HARNESS ASSY BUFFER SENSOR connected surely? | Go to step 27. | After reconnecting, go to step 26. |
| 26 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 27. | End of work. |
| 27 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8318 and P/J8302A of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 29. | After reconnecting, go to step 28. |
| 28 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 29. | End of work. |
| 29 | Checking the HARNESS ASSY BUFFER SENSOR for conductivity <br> Disconnect P/J8392 and P/J8318 of the HARNESS ASSY BUFFER SENSOR. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8392-3 <=> J8318B-1 } \\ & \text { J8392-2 <=> J8318B-2 } \\ & \text { J8392-1 <=> J8318B-3 } \end{aligned}$ | Go to step 30. | Replace the HARNESSASSY BUFFER SENSOR. |
| 30 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8318 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: <br> J8318A-3 <=> J8302A-13 <br> J8318A-2 <=> J8302A-14 <br> J8318A-1 <=> J8302A-15 | Go to step 31. | Replace the HARNESSASSY MAIN SENSOR. |
| 31 | Checking +5 VDC power supply to the SENSOR ASSY (Buffer Path Sensor) Is the voltage across J8302A-15 <=> J8302A-13 on the PWB MAIN-C +5 VDC? | Go to step 32. | Replace the PWB MAIN-C. (RRP 12.98) |
| 32 | Checking the SENSOR ASSY (Buffer Path Sensor) for operation <br> Does the voltage across P8302A-14 <=> P8302A-13 on the PWB MAIN-C change, every time the actuator of the SENSOR ASSY (Buffer Path Sensor)) is operated? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR ASSY <br> (Buffer Path Sensor). <br> (RRP 12.76) |

## F4-52 Finisher Compile Exit Sensor On Jam A

## NOTE This FIP can also be applied for the followings. <br> NOTE F4-53 Finisher Compile Exit Sensor On Jam B

| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLL ASSY-BUFFER (PL 12.12.13) <br> ROLLER-PINCH (PL 12.12.2) <br> ROLLER ASSY-PINCH, EXIT (PL 12.12.15) <br> HARNESS ASSY BUFFER SENSOR (PL 12.15.5) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> SENSOR ASSY (PL 12.12.12) <br> SENSOR (PL 12.13.16) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) <br> MOTOR ASSY (PL 12.13.30) <br> HARNESS ASSY COMPILER (PL 12.10.8) <br> SENSOR ASSY (PL 12.11.3) |  |  |
| 1 | Checking the paper path <br> Open the COVER ASSY FRONT (PL 12.5.3) of the Finisher. <br> Open the CHUTE ASSY-UPPER, EXIT OPEN (PL 12.12.1) to right. <br> Open the CHUTE ASSY-BUFFER BOTTOM (PL 12.12.14) top downward. <br> Are the ROLL ASSY-BUFFER (PL 12.12.13), the ROLLER-PINCH (PL 12.12.2) attached on the CHUTE ASSY-UPPER, EXIT OPEN, and the ROLLER ASSYPINCH, EXIT (PL 12.12.15) attached on the CHUTE ASSY-BUFFER BOTTOM installed correctly? <br> Also, are they not contaminated or damaged, and rotated smoothly? <br> Check these items by turning them with your fingers. Are there any stains such as paper dust on the paper path? | Go to step 2. | Clean or replace the appropriate ROLLER, and clean the paper path. |
| 2 | Checking the SENSOR ASSY (Buffer Path Sensor) for operation <br> Execute [Input 12-31 Buffer Path SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the actuator of the SENSOR ASSY (Buffer Path Sensor) is operated? | Go to step 11. | Go to step 3. |
| 3 | Checking the HARNESS ASSY BUFFER SENSOR connection <br> Are P/J8392 and P/J8318 of the HARNESS ASSY BUFFER SENSOR connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8318 and P/J8302A of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 7. | After reconnecting, go to step 6 . |
| 6 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 7. | End of work. |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 7 | Checking the HARNESS ASSY BUFFER SENSOR for conductivity <br> Disconnect P/J8392 and P/J8318 of the HARNESS ASSY BUFFER SENSOR. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8392-3 <=> J8318B-1 } \\ & \text { J8392-2 <=> J8318B-2 } \\ & \text { J8392-1 <=> J8318B-3 } \end{aligned}$ | Go to step 8. | Replace the HARNESSASSY BUFFER SENSOR. |
| 8 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8318 of the HARNESS ASSY BUFFER SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8318A-3 <=> J8302A-13 } \\ & \text { J8318A-2 <=> J8302A-14 } \\ & \text { J8318A-1 <=> J8302A-15 } \end{aligned}$ | Go to step 9. | Replace the HARNESSASSY MAIN SENSOR. |
| 9 | Checking +5 VDC power supply to the SENSOR ASSY (Buffer Path Sensor) Is the voltage across J8302A-15 <=> J8302A-13 on the PWB MAIN-C +5 VDC? | Go to step 10. | Replace the PWB MAIN-C. (RRP 12.98) |
| 10 | Checking the ENSOR ASSY (Buffer Path Sensor) for operation <br> Does the voltage across P8302A-14 <=> P8302A-13 on the PWB MAIN-C change, every time the actuator of the SENSOR ASSY (Buffer Path Sensor) is operated? | Replace the PWB MAIN-C (RRP 12.98) | Replace the SENSOR ASSY <br> (Buffer Path Sensor). <br> (RRP 12.76) |
| 11 | Checking the MOTOR ASSY (Registration Motor) for operation <br> Execute [Output 12-05 Registration Motor 285F ON/OFF] in [Diagnosis]. <br> Does the MOTOR ASSY (Registration Motor) rotate normally? | Go to step 20. | Go to step 12. |
| 12 | Checking the MOTOR ASSY (Registration Motor) for power transmission <br> Execute [Output 12-05 Registration Motor 285F ON/OFF] in [Diagnosis]. <br> Does the rotation of the MOTOR ASSY transmit to the ROLL ASSY-BUFFER (PL 12.12.13) through the BELT (PL 12.13.27)? | Go to step 14. | After reinstalling the MOTOR ASSY and BELT, go to step 13. (RRP 12.96) |
| 13 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 14. | End of work. |
| 14 | Checking the HARNESS ASSY MAIN DRIVE connection Are P/J8335 and P/J8304 of the HARNESS ASSY MAIN DRIVE connected surely? | Go to step 16. | After reconnecting, go to step 15. |
| 15 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 16. | End of work. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 16 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8335 and P/J8304 of the HARNESS ASSY MAIN DRIVE. <br> Check for conductivity at the following: <br> J8335-1 <=> J8304-7 <br> J8335-2 <=> J8304-8 <br> J8335-3 <=> J8304-9 <br> J8335-4 <=> J8304-11 <br> J8335-5 <=> J8304-10 <br> J8335-6 <=> J8304-13 | Go to step 17. | Replace the HARNESSASSY MAIN DRIVE. |
| 17 | Checking the resistance of the Motor Assembly. Are there any resistances without disconnection across P8335-2/5 COM and P8335-1/3/4/6 of the motor assembly | Go to step 18. | Replace the Motor Assembly (RRP 12.96). |
| 18 | Checking +24 VDC power supply to the MOTOR ASSY Are the voltages across J8304-8 <=> FRAME CHASSIS, and J8304-10 <=> FRAME CHASSIS on the PWB MAINC, +24 VDC? | Go to step 19. | Replace the PWB MAIN-C. (RRP 12.98) |
| 19 | Checking after replacing the MOTOR ASSY (Registration Motor) <br> Replace the MOTOR ASSY (Registration Motor). (RRP 12.96) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |
| 20 | Checking the SENSOR (Gate Sensor) for operation Perform [Input 12-51 Gate SENSOR] in Chapter 2, Diagnostics. <br> Does the screen display change each time a piece of paper is placed at the front of the SENSOR (Gate Sensor)? | Go to step 26. | Go to step 21. |
| 21 | Checking the HARNESS ASSY-SENSOR for connection Are the connectors of the HARNESS ASSY-SENSOR connected securely? | Go to step 23. | After reconnecting, go to step 22. |
| 22 | Perform [Test Print] in Chapter 2, Diagnostics. Does the error still occur? | Go to step 23. | End of work. |
| 23 | Checking the HARNESS ASSY-SENSOR for conductivity Disconnect P/J8342 and P/J 8376 of the HARNESS ASSY-SENSOR. <br> Check for conductivity at the following: $\begin{aligned} & \mathrm{J} 8432-3 \text { <=> J8376-1 } \\ & \text { J8432-2 <=> J8376-2 } \\ & \text { J8432-1 <=> J8376-3 } \end{aligned}$ | Go to step 24. | Replace the HARNESS ASSY-SENSOR. |
| 24 | Checking the SENSOR (Gate Sensor) for +5 VDC power supply <br> Is the voltage between J8376-3 and J8376-1 of the PWB MAIN-C +5 VDC? | Go to step 24. | Replace the PWB MAIN-C. (RRP 12.98) |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 25 | Checking the SENSOR (Gate Sensor) for operation Does the voltage between P8376-2 and P8376-1 of the PWB MAIN-C change each time a piece of paper is placed at the front of the sensor? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR. (RRP 12.93) |
| 26 | Checking the SENSOR ASSY (Compile Exit Sensor) for operation <br> Execute [Input 12-34 Compile Exit SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the actuator of the SENSOR ASSY (Compile Exit Sensor) is operated? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 27. |
| 27 | Checking the HARNESS ASSY COMPILER connection Are P/J8320 and P/J8391 of the HARNESS ASSY COMPILER connected surely? | Go to step 29. | After reconnecting, go to step 28. |
| 28 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 29. | End of work. |
| 29 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8391 and P/J8302A of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 31. | After reconnecting, go to step 30. |
| 30 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 31. | End of work. |
| 31 | Checking the HARNESS ASSY COMPILER for conductivity <br> Disconnect P/J8320 and P/J8391 of the HARNESS ASSY COMPILER. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8320-3 <=> J8391B-1 } \\ & \text { J8320-2 <=> J8391B-2 } \\ & \text { J8320-1 <=> J8391B-3 } \end{aligned}$ | Go to step 32. | Replace the HARNESSASSY COMPILER. |
| 32 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8391 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8391A-3 <=> J8302A-4 } \\ & \text { J8391A-2 <=> J8302A-5 } \\ & \text { J8391A-1 <=> J8302A-6 } \end{aligned}$ | Go to step 33. | Replace the HARNESSASSY MAIN SENSOR. |
| 33 | Checking +5 VDC power supply to the SENSOR ASSY (Compile Exit Sensor) Is the voltage across J8302A-6 <=> J8302A-4 on the PWB MAIN-C +5 VDC? | Go to step 34. | Replace the PWB MAIN-C. (RRP 12.98) |
| 34 | Checking the SENSOR ASSY (Compile Exit Sensor) for operation <br> Does the voltage across P8302A-5 <=> P8302A-4 on the PWB MAIN-C change, every time the actuator of the SENSOR ASSY (Compile Exit Sensor) is operated? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR ASSY <br> (Compile Exit Sensor). <br> (RRP 12.67) |

## F4-51 Finisher Compile Exit Sensor Off Jam A

NOTE This FIP can also be applied for the following.
NOTE F4-55 Finisher Compile Exit Sensor Off Jam B

| $\begin{aligned} & \text { Ste } \\ & \text { p } \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLL ASSY-EXIT LOW (PL 12.11.6) <br> HARNESS ASSY COMPILER (PL 12.10.8) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> SENSOR ASSY (PL 12.11.3) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) <br> MOTOR ASSY (PL 12.13.30) |  |  |
| 1 | Checking the paper path <br> Open the COVER ASSY FRONT (PL 12.5.3) of the Finisher. <br> Is the ROLL ASSY-EXIT LOW (PL 12.11.6) installed correctly? <br> Also, is it not contaminated or damaged, and rotated smoothly? <br> Check this item by turning it with your fingers. <br> Are there any stains such as paper dust on the paper path? | Go to step 2. | Clean or replace the ROLL ASSYEXIT LOW, and clean the paper path. |
| 2 | Checking the SENSOR ASSY (Compile Exit Sensor) for operation <br> Execute [Input 12-34 Compile Exit SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the actuator of the SENSOR ASSY (Compile Exit Sensor) is operated? | Go to step 11. | Go to step 3. |
| 3 | Checking the HARNESS ASSY COMPILER connection Are P/J8320 and P/J8391 of the HARNESS ASSY COMPILER connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8391 and P/J8302A of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 7. | After reconnecting, go to step 6 |
| 6 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 7. | End of work. |
| 7 | Checking the HARNESS ASSY COMPILER for conductivity <br> Disconnect P/J8320 and P/J8391 of the HARNESS ASSY COMPILER. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8320-3 <=> J8391B-1 } \\ & \text { J8320-2 <=> J8391B-2 } \\ & \text { J8320-1 <=> J8391B-3 } \end{aligned}$ | Go to step 8. | Replace the HARNESSASSY COMPILER. |


| $\begin{aligned} & \text { Ste } \\ & \text { p } \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 8 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8391 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8391A-3 <=> J8302A-4 } \\ & \text { J8391A-2 <=> J8302A-5 } \\ & \text { J8391A-1 <=> J8302A-6 } \end{aligned}$ | Go to step 9. | Replace the HARNESSASSY MAIN SENSOR. |
| 9 | Checking +5 VDC power supply to the SENSOR ASSY (Compile Exit Sensor) Is the voltage across J8302A-6 <=> J8302A-4 on the PWB MAIN-C +5 VDC? | Go to step 10. | Replace the PWB MAIN-C. (RRP 12.98) |
| 10 | Checking the SENSOR ASSY (Compile Exit Sensor) for operation <br> Does the voltage across P8302A-5 <=> P8302A-4 on the PWB MAIN-C change, every time the actuator of the SENSOR ASSY (Compile Exit Sensor) is operated? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR ASSY (Compile Exit Sensor). (RRP 12.67) |
| 11 | Checking the MOTOR ASSY (Exit Motor) for operation Execute [Output 12-09 Exit Motor 285F ON/OFF] in [Diagnosis] <br> Does the MOTOR ASSY (Exit Motor) rotate normally? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 12. |
| 12 | Checking the MOTOR ASSY (Exit Motor) for power transmission <br> Execute [Output 12-09 Exit Motor 285F ON/OFF] in [Diagnosis]. <br> Does the rotation of the MOTOR ASSY transmit to the ROLL ASSY-EXIT LOW (PL 12.11.6) through the BELT (PL 12.13.28)? | Go to step 14. | After reinstalling the MOTOR ASSY and BELT, go to step 13. (RRP 12.95) |
| 13 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 14. | End of work. |
| 14 | Checking the HARNESS ASSY MAIN DRIVE connection Are P/J8334 and P/J8304 of the HARNESS ASSY MAIN DRIVE connected surely? | Go to step 16. | After reconnecting, go to step 15 . |
| 15 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 16. | End of work. |
| 16 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8334 and P/J8304 of the HARNESS ASSY MAIN DRIVE. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8334-1 <=> J8304-2 } \\ & \text { J8334-2 <=> J8304-4 } \\ & \text { J8334-3 <=> J8304-1 } \\ & \text { J8334-4 <=> J8304-3 } \\ & \text { J8334-5 <=> J8304-6 } \\ & \text { J8334-6 <=> J8304-5 } \end{aligned}$ | Go to step 17. | Replace the HARNESSASSY MAIN DRIVE. |


| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 17 | Checking the resistance of the MOTOR ASSY <br> Are there any resistances without disconnection across <br> P8334-2/5(COM) and P8334-1/3/4/6 of the MOTOR <br> ASSY? | Go to step 18. | Replace the <br> MOTOR ASSY. <br> (RRP 12.95) |
| 18 | Checking +24 VDC power supply to the MOTOR ASSY <br> Are the voltages across J8304-4 <=> FRAME CHASSIS, <br> and J8304-6 <=> FRAME CHASSIS on the PWB MAIN-C, <br> +24 VDC? | Go to step 19. | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) |
| 19 | Checking after replacing the MOTOR ASSY (Exit Motor) <br> Replace the MOTOR ASSY (Exit Motor). (RRP 12.95) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | End of work. |

## F4-61 Finisher Set Eject Jam

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> SHAFT ASSY-EJECT ROLL (PL 12.10.9) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) <br> MOTOR ASSY-DC (PL 12.9.11) <br> BRACKET ASSY-EJECT (PL 12.10.17) <br> PWB MAIN-C (PL 12.14.5) <br> HARNESS ASSY COMPILER (PL 12.10.8) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> ACTUATOR-PAPER (PL 12.10.4) <br> SENSOR (PL 12.10.3) | Go |  |
| 1 | Checking the paper path <br> Is the SHAFT ASSY-EJECT ROLL (PL 12.10.9) installed <br> correctly? <br> Does it rotate smoothly without contaminated or dam- <br> aged? <br> Check this item by turning it with your fingers. <br> Are there any stains such as paper dust on the paper <br> path? | Go to step 2. | Clean or replace <br> the ROLLER and <br> clean the paper <br> path. |
|  | Checking the MOTOR ASSY-DC (Eject Clamp Motor) for <br> rotation <br> Execute [Output 12-18 Eject Clamp Motor UP ON/OFF] <br> and [Output 12-19 Eject Clamp Motor DOWN ON/OFF] in <br> [Diagnosis]. <br> Deos the MOTOR ASSY-DC (Eject Clamp Motor) rotate <br> properly? | Go to step 7. | Go to step 3. |
| 3 | Checking the HARNESS ASSY MAIN DRIVE connection <br> Are P/J8339 and P/s 8304 of HARNESS ASSY MAIN <br> DRIVE connected surely? | Go to step 5. | Reconnect them <br> and go to step 4. |
| 4 | Does the error still occur? <br> Execute [Test Print] in [Diagnosis]. | Go to step 5. | End of work. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 5 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8339 and P/J 8304 of the HARNESS ASSY MAIN DRIVE. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8339-1 <=> J8304-33 } \\ & \text { J8339-2 <=> J8304-31 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY MAIN DRIVE. |
| 6 | Checking after replacing the MOTOR ASSY-DC (Eject Clamp Motor) <br> Replace the MOTOR ASSY-DC (Eject Clamp Motor) <br> (RRP 12.54). <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the PWB MAIN-C. (PL 12.98) | End of work. |
| 7 | Checking the BRACKET ASSY-EJECT (Eject Motor) for rotation <br> Execute [Output 12-20 Eject Motor Low FORWARD ON/ OFF] and [Output 12-22 Eject Motor Low REVERSE ON/ OFF] in [Diagnosis] alternately. <br> Does the BRACKET ASSY-EJECT (Eject Motor) rotate in the forward and reverse directions alternately? | Go to step 14. | Go to step 8. |
| 8 | Checking the HARNESS ASSY MAIN DRIVE connection Are P/J8336 and P/J 8304 of the HARNESS ASSY MAIN DRIVE connected surely? | Go to step 10. | Reconnect them and go to step 9 . |
| 9 | Does the error still occur? <br> Execute [Test Print] in [Diagnosis]. | Go to step 10. | End of work. |
| 10 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8336 and P/J 8304 of the HARNESS ASSY MAIN DRIVE. <br> Check for conductivity at the following: <br> J8336-1 <=> J8304-15 <br> J8336-2 <=> J8304-12 <br> J8336-3 <=> J8304-17 <br> J8336-4 <=> J8304-19 <br> J8336-5 <=> J8304-14 <br> J8336-6 <=> J8304-21 | Go to step 11. | Replace the HARNESSASSY MAIN DRIVE. |
| 11 | Checking the resistance of the BRACKET ASSY-EJECT (Eject Motor) <br> Are there any resistances without disconnection across P8336-2/5(COM) <=> P8336-1/3/4/6 of the BRACKET ASSY-EJECT (Eject Motor)? | Go to step 12. | Replace the BRACKET ASSY-EJECT. (RRP 12.65) |
| 12 | Checking +24 VDC power supply to the BRACKET ASSY-EJECT (Eject Motor) <br> Are the voltages across J8304-12 <=> FRAME CHASSIS, and J8304-14 <=> FRAME CHASSIS on the PWB MAINC, +24 VDC? | Go to step 13. | Replace the PWB MAIN-C. (RRP 12.98) |


| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 13 | Checking after replacing the BRACKET ASSY-EJECT <br> (Eject Motor) <br> Replace the BRACKET ASSY-EJECT (Eject Motor). <br> (RRP 12.65) <br> Does the error still occur? <br> Execute [Test Print] in [Diagnosis]. | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |
| 14 | Checking the ACTUATOR-PAPER for operation Is the ACTUATOR-PAPER operated correctly? | Go to step 15. | Reinstall the ACTUATORPAPER. |
| 15 | Checking the SENSOR (Compile Tray No Paper Sensor) for operation <br> Execute [Input 12-35 Compile Tray No Paper SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the ACTUATOR-PAPER (PL 12.10.4) of the SENSOR is operated? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 16. |
| 16 | Checking the HARNESS ASSY COMPILER connection Are P/J8359 and P/J8309 of the HARNESS ASSY COMPILER connected surely? | Go to step 18. | After reconnecting, go to step 17. |
| 17 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 18. | End of work. |
| 18 | Checking the HARNESS ASSY COMPILER for conductivity <br> Disconnect P/J8359 and P/J8309 of the HARNESS ASSY COMPILER. <br> Check for conductivity at the following: $\begin{aligned} & \mathrm{J} 8359-3 \text { <=> J8309-1 } \\ & \text { J8359-2 <=> J8309-2 } \\ & \text { J8359-1 <=> J8309-3 } \end{aligned}$ | Go to step 19. | Replace the HARNESSASSY COMPILER. |
| 19 | Checking +5 VDC power supply to the SENSOR (Compile Tray No Paper Sensor) Is the voltage across J8309-3 <=> J8309-1 on the PWB MAIN-C +5 VDC? | Go to step 20. | Replace the PWB MAIN-C. (RRP 12.98) |
| 20 | Checking the SENSOR (Compile Tray No Paper Sensor) for operation <br> Does the voltage across P8309-2 <=> P8309-1 on the PWB MAIN-C change, every time the ACTUATORPAPER (PL 12.10.4) of the SENSOR (Compile Tray No Paper Sensor) is operated? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Compile Tray No Paper Sensor). (RRP 12.59) |

## F4-71 Finisher Top Tray Exit Sensor On Jam A

NOTE This FIP can also be applied for the followings.
NOTE F4-73 Finisher Top Tray Exit Sensor On Jam B

| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLL ASSY-ENT (PL 12.12.20) <br> ROLLER ASSY-PINCH, ENT (PL 12.12.17) <br> ROLL ASSY-TRANSPORT (PL 12.13.18) <br> ROLLER-PINCH (PL 12.13.11) <br> MOTOR ASSY (PL 12.13.30) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) <br> PWB MAIN-C (PL 12.14.5) <br> HARNESS ASSY TOP EXIT SENSOR (PL 12.15.6) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> SENSOR (PL 12.13.2) |  |  |
| 1 | Checking the paper path <br> Open the COVER ASSY FRONT (PL 12.5.3) of the Finisher. <br> Remove the COVER TOP (PL 12.4.1) and COVER LH TOP (PL 12.5.9). <br> Open the CHUTE ASSY-UPPER, ENT (PL 12.12.16) to upward. <br> Are the ROLLER ASSY-PINCH, ENT (PL 12.12.17) of the CHUTE ASSY-UPPER, ENT and ROLL ASSY-ENT (PL 12.12.20) installed correctly? <br> Also, are they not contaminated or damaged, and rotated smoothly? <br> Check these items by turning them with your fingers. Are there any stains such as paper dust on the paper path? | Go to step 2. | Clean or replace the appropriate ROLLER, and clean the paper path. |
| 2 | Checking the paper path <br> Open the CHUTE ASSY-LOWER, TOP EXIT L (PL <br> 12.13.10) to right. <br> Are the ROLLER-PINCH (PL 12.13.11) of the CHUTE <br> ASSY-LOWER, TOP EXIT L and two ROLL ASSY- <br> TRANSPORTs (PL 12.13.18) installed correctly? <br> Also, are they not contaminated or damaged, and rotated smoothly? <br> Check these items by turning them with your fingers. | Go to step 3. | Clean or replace the appropriate ROLLER, and clean the paper path. |
| 3 | Checking the MOTOR ASSY (Registration Motor) for rotation <br> Perform [Output 12-05 Registration Motor 285F ON/OFF] in Chapter 2, Diagnostics. <br> Does the MOTOR ASSY (Registration Motor) rotate properly? | Go to step 12. | Go to step 4. |
| 4 | Checking the MOTOR ASSY (Registration Motor) for power transmission <br> Perform [Output 12-05 Registration Motor 285F ON/OFF] in Chapter 2, Diagnostics. <br> Does the rotation of the MOTOR ASSY transmit to the ROLL ASSY-BUFFER (PL 12.12.13) via the BELT (PL 12.13.27)? | Go to step 6. | Reinstall the MOTOR ASSY and the BELT, and then go to step 5. (RRP 12.96) |
| 5 | Perform [Test Print] in Chapter 2, Diagnostics. Does the error still occur? | Go to step 6. | End of work. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 6 | Checking the HARNESS ASSY MAIN DRIVE for connection <br> Are P/J8335 and P/J 8304 of the HARNESS ASSY MAIN DRIVE connected securely? | Go to step 8. | After reconnecting, go to step 7. |
| 7 | Perform [Test Print] in Chapter 2, Diagnostics. Does the error still occur? | Go to step 8. | End of work. |
| 8 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8335 and P/J 8304 of the HARNESS <br> ASSY MAIN DRIVE. <br> Check for conductivity at the following: <br> J8335-1 <=> J8304-7 <br> J8335-2 <=> J8304-8 <br> J8335-3 <=> J8304-9 <br> J8335-4 <=> J8304-11 <br> J8335-5 <=> J8304-10 <br> J8335-6 <=> J8304-13 | Go to step 9. | Replace the HARNESSASSY MAIN DRIVE. |
| 9 | Checking the resistance of the MOTOR ASSY Are there any resistances without disconnection across P8335-2/5(COM) and P8335-/3/4/6 of the MOTOR ASSY? | Go to step 10. | Replace the MOTOR ASSY. (RRP 12.96) |
| 10 | Checking the MOTOR ASSY for +24 VDC power supply Is the voltage between J8304-8 and the FRAME CHASSIS, and J8304-10 and the FRAME CHASSIS of the PWB MAIN-C, +24VDC? | Go to step 11. | Replace the PWB MAIN-C. (RRP 12.98) |
| 11 | Checking the MOTOR ASSY (Registration Motor) after the replacement <br> Replace the MOTOR ASSY (Registration Motor). (RRP 12.96) <br> Perform [Test Print] in Chapter 2, Diagnostics. Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |
| 12 | Checking the SENSOR (Top Tray Exit Sensor) for operation <br> Execute [Input 12-32 Top Tray Exit SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the actuator of the SENSOR is operated? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 13. |
| 13 | Checking the HARNESS ASSY TOP EXIT SENSOR and HARNESS ASSY MAIN SENSOR connections Are P/J8321 and P/J8312 of the HARNESS ASSY TOP EXIT SENSOR, and P/J8312 and P/J8302 of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 15. | After reconnecting, go to step 14. |
| 14 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 15. | End of work. |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :--- | :---: |
| 15 | Checking the HARNESS ASSY TOP EXIT SENSOR for <br> conductivity <br> Disconnect P/J8321 and P/J8312 of the HARNESS ASSY <br> TOP EXIT SENSOR. <br> Check for conductivity at the following: <br> J8321-3 <=> J8312B-1 <br> J8321-2 <=> J8312B-2 <br> J8321-1 <=> J8312B-3 | Go to step 16. | Neplace the <br> HARNESS ASSY <br> TOP EXIT SEN- <br> SOR. |
| 16 | Checking the HARNESS ASSY MAIN SENSOR for con- <br> ductivity <br> Disconnect P/J8312 of the HARNESS ASSY MAIN SEN- <br> SOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: <br> J8312A-3 <=> J8302A-7 <br> J8312A-2 <=> J8302A-8 <br> J8312A-1 <=> J8302A-9 | Go to step 17. | HARNESS ASSY <br> MAIN SENSOR. |
| 17 | Checking +5 VDC power supply to the SENSOR (Top <br> Tray Exit Sensor) <br> Is the voltage across J8302A-9 <=> J8302A-7 on the <br> PWB MAIN-C +5 VDC? | Go to step 18. | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) |
|  | Checking the SENSOR (Top Tray Exit Sensor) for opera- <br> tion <br> Does the voltage across P8302A-8 <=> P8302A-7 on the <br> PWB MAIN-C change, every time a piece of white paper <br> is placed over the sensing area of the SENSOR (Top Tray <br> Exit Sensor)? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | Replace the <br> SENSOR (Top <br> Tray Exit <br> Sensor). <br> (RRP 12.87) |

## F4-72 Finisher Top Tray Exit Sensor Off Jam A

NOTE This FIP can also be applied for the following.
NOTE F4-75 Finisher Top Tray Exit Sensor Off Jam B

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :--- | :--- |
|  | Possible causative parts: <br> ROLL ASSY-TRANSPORT (PL 12.13.18) <br> ROLLER-PINCH (PL 12.13.11) <br> MOTOR ASSY (PL 12.12.21) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) <br> PWB MAIN-C (PL 12.14.5) <br> HARNESS ASSY TOP EXIT SENSOR (PL 12.15.6) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> SENSOR (PL 12.13.2) |  |  |
|  | PWB MAIN-C (PL 12.14.5) |  |  |
|  | SENSOR (PL 12.13.2) |  |  |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking the paper path <br> Open the CHUTE ASSY-LOWER, TOP EXIT L (PL 12.13.10)to right. <br> Are the ROLLER-PINCH (PL 12.13.11) on the CHUTE ASSY-LOWER, TOP EXIT L and two ROLL ASSYTRANSPORTs (PL 12.13.18) installed correctly? <br> Also, are they not contaminated or damaged, and rotated smoothly? <br> Check these items by turning them with your fingers. Are there any stains such as paper dust on the paper path? | Go to step 2. | Clean or replace the appropriate ROLLER, and clean the paper path. |
| 2 | Checking the MOTOR ASSY (Registration Motor) for rotation <br> Perform [Output 12-05 Registration Motor 285F ON/OFF] in Chapter 2, Diagnostics. <br> Does the MOTOR ASSY (Registration Motor) rotate properly? | Go to step 11. | Go to step 3. |
| 3 | Checking the MOTOR ASSY (Registration Motor) for power transmission <br> Perform [Output 12-05 Registration Motor 285F ON/OFF] in Chapter 2, Diagnostics. <br> Does the rotation of the MOTOR ASSY transmit to the ROLL ASSY-BUFFER (PL 12.12.13) via the BELT (PL 12.13.27)? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Perform [Test Print] in Chapter 2, Diagnostics. Does the error still occur? | Go to step 6. | End of work. |
| 5 | Checking the HARNESS ASSY MAIN DRIVE for connection <br> Are P/J8335 and P/J 8304 of the HARNESS ASSY MAIN DRIVE connected securely? | Go to step 8. | After reconnecting, go to step 7. |
| 6 | Perform [Test Print] in Chapter 2, Diagnostics. Does the error still occur? | Go to step 8. | End of work. |
| 7 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8335 and P/J 8304 of the HARNESS <br> ASSY MAIN DRIVE. <br> Check for conductivity at the following: <br> J8335-1 <=> J8304-7 <br> J8335-2 <=> J8304-8 <br> J8335-3 <=> J8304-9 <br> J8335-4 <=> J8304-11 <br> J8335-5 <=> J8304-10 <br> J8335-6 <=> J8304-13 | Go to step 8. | Replace the HARNESSASSY MAIN DRIVE. |
| 8 | Checking the resistance of the MOTOR ASSY Are there any resistances without disconnection across P8335-2/5(COM) and P8335-/3/4/6 of the MOTOR ASSY? | Go to step 9. | Replace the MOTOR ASSY. (RRP 12.96) |


| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 9 | Checking the MOTOR ASSY for +24 VDC power supply Is the voltage between J8304-8 and the FRAME CHASSIS, and J8304-10 and the FRAME CHASSIS of the PWB MAIN-C, +24VDC? | Go to step 10. | Replace the PWB MAIN-C. (RRP 12.98) |
| 10 | Checking the MOTOR ASSY (Registration Motor) after the replacement <br> Replace the MOTOR ASSY (Registration Motor). (RRP 12.96) <br> Perform [Test Print] in Chapter 2, Diagnostics. <br> Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |
| 11 | Checking the MOTOR ASSY (Exit Motor) for operation Execute [Output 12-09 Exit Motor 285F ON/OFF] in [Diagnosis] <br> Does the MOTOR ASSY (Exit Motor) rotate normally? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 12. |
| 12 | Checking the MOTOR ASSY (Exit Motor) for power transmission <br> Execute [Output 12-09 Exit Motor 285F ON/OFF] in [Diagnosis]. <br> Does the rotation of the MOTOR ASSY transmit to the ROLL ASSY-EXIT LOW (PL 12.11.6) through the BELT (PL 12.13.28)? | Go to step 20. | After reinstalling the MOTOR ASSY and BELT, go to step 13. (RRP 12.95) |
| 13 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 14. | End of work. |
| 14 | Checking the HARNESS ASSY MAIN DRIVE connection Are P/J8334 and P/J8304 of the HARNESS ASSY MAIN DRIVE connected surely? | Go to step 16. | After reconnecting, go to step 15. |
| 15 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 16. | End of work. |
| 16 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8334 and P/J8304 of the HARNESS ASSY MAIN DRIVE. <br> Check for conductivity at the following: <br> J8334-1 <=> J8304-2 <br> J8334-2 <=> J8304-4 <br> J8334-3 <=> J8304-1 <br> J8334-4 <=> J8304-3 <br> J8334-5 <=> J8304-6 <br> J8334-6 <=> J8304-5 | Go to step 17. | Replace the HARNESSASSY MAIN DRIVE. |
| 17 | Checking the resistance of the MOTOR ASSY <br> Are there any resistances without disconnection across P8334-2/5(COM) and P8334-1/3/4/6 of the MOTOR ASSY? | Go to step 18. | Replace the MOTOR ASSY. (RRP 12.95) |
| 18 | Checking +24 VDC power supply to the MOTOR ASSY Are the voltages across J8304-4 <=> FRAME CHASSIS, and J8304-6 <=> FRAME CHASSIS on the PWB MAIN-C, +24 VDC? | Go to step 19. | Replace the PWB MAIN-C. (RRP 12.98) |


| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 19 | Checking after replacing the MOTOR ASSY (Exit Motor) Replace the MOTOR ASSY (Exit Motor). (RRP 12.95) Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |
| 20 | Checking the SENSOR (Top Tray Exit Sensor) for operation <br> Execute [Input 12-32 Top Tray Exit SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the actuator of the SENSOR is operated? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 21. |
| 21 | Checking the HARNESS ASSY TOP EXIT SENSOR and HARNESS ASSY MAIN SENSOR connections Are P/J8321 and P/J8312 of the HARNESS ASSY TOP EXIT SENSOR, and P/J8312 and P/J8302 of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 23. | After reconnecting, go to step 22 . |
| 22 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 23. | End of work. |
| 23 | Checking the HARNESS ASSY TOP EXIT SENSOR for conductivity <br> Disconnect P/J8321 and P/J8312 of the HARNESS ASSY TOP EXIT SENSOR. <br> Check for conductivity at the following: $\begin{array}{\|l} \text { J8321-3 <=> J8312B-1 } \\ \text { J8321-2 <=> J8312B-2 } \\ \text { J8321-1 <=> J8312B-3 } \end{array}$ | Go to step 24. | Replace the HARNESSASSY TOP EXIT SENSOR. |
| 24 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8312 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8312A-3 <=> J8302A-7 } \\ & \text { J8312A-2 <=> J8302A-8 } \\ & \text { J8312A-1 <=> J8302A-9 } \end{aligned}$ | Go to step 25. | Replace the HARNESSASSY MAIN SENSOR. |
| 25 | Checking +5 VDC power supply to the SENSOR (Top Tray Exit Sensor) Is the voltage across J8302A-9 <=> J8302A-7 on the PWB MAIN-C +5 VDC? | Go to step 26. | Replace the PWB MAIN-C. (RRP 12.98) |
| 26 | Checking the SENSOR (Top Tray Exit Sensor) for operation <br> Does the voltage across P8302A-8 <=> P8302A-7 on the PWB MAIN-C change, every time a piece of white paper is placed over the sensing area of the SENSOR (Top Tray Exit Sensor)? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Top Tray Exit Sensor). (RRP 12.87) |

## F4-82 Finisher Gate Sensor On Jam

| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> BELT (PL 12.3.12) <br> PINCH ROLL (PL 12.2.6) <br> ROLL ASSY-ENT (PL 12.12.20) <br> ROLLER ASSY-PINCH, ENT (PL 12.12.17) <br> H-TRANSPORT EXIT SENSOR (PL 12.3.21) <br> WIRE HARNESS (PL 12.3.26) <br> PWB H-TRA (PL 12.14.3) <br> SENSOR (PL 12.12.19) <br> HARNESS ASSY X'PORT ENT SENSOR (PL 12.15.4) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> MOTOR ASSY (PL 12.12.21) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) <br> SENSOR (PL 12.13.15) <br> HARNESS ASSY-SENSOR (PL 12.13.16) |  |  |
| 1 | Checking the paper path <br> Open the COVER ASSY TOP (PL 12.2.9) of the H- <br> TRANSPORT ASSEMBLY (PL 12.1.2). <br> Are the PINCH ROLL (PL 12.2.6) on the COVER ASSY <br> TOP and two BELTs (PL 12.3.12) installed correctly? <br> Also, are they not contaminated or damaged, and rotated smoothly? <br> Check these items by turning them with your fingers. Are there any stains such as paper dust on the paper path? | Go to step 2. | Clean or replace the appropriate BELTs and PINCH ROLL, and clean the paper path. |
| 2 | Checking the paper path <br> Open the COVER ASSY FRONT (PL 12.5.3) of the Finisher. <br> Remove the COVER TOP (PL 12.4.1) and COVER LH TOP (PL 12.5.9). <br> Open the CHUTE ASSY-UPPER, ENT (PL 12.12.16) to upward. <br> Are the ROLLER ASSY-PINCH, ENT (PL 12.12.17) on the CHUTE ASSY-UPPER, ENT and ROLL ASSY-ENT (PL 12.12.20) installed correctly? <br> Also, are they not contaminated or damaged, and rotated smoothly? <br> Check these items by turning them with your fingers. Are there any stains such as paper dust on the paper path? | Go to step 3. | Clean or replace the appropriate ROLLER, and clean the paper path. |
| 3 | Checking the H-TRANSPORT EXIT SENSOR (Finisher <br> H-Transport Exit Sensor) for operation <br> Execute [Input 12-29 H-Transport Exit SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the actuator of the H-TRANSPORT EXIT SENSOR is operated? | Go to step 9. | Go to step 4. |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 4 | Checking the WIRE HARNESS (PL 12.3.26) connection <br> Are the connectors of the WIRE HARNESS connected to <br> the H-TRANSPORT EXIT SENSOR and the PBW H-TRA <br> of the Finisher connected surely? | Go to step 6. | After reconnect- <br> ing, go to step 5. |
| 5 | Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 6. | End of work. |
| 6 | Checking the WIRE HARNESS for conductivity <br> Disconnect J8381 of the H-TRANSPORT EXIT SENSOR, <br> and P/J8372 on the PWB H-TRA of the Finisher. <br> Check for conductivity at the following: <br> J8372-4 <=> J8381-3 <br> J8372-5 <=> J8381-2 <br> J8372-6 <=> J8381-1 | Checking +5 VDC power supply to the H-TRANSPORT <br> EXIT SENSOR <br> Is the voltage across J8372-6 <=> J8372-4 on the PWB <br> H-TRA of the Finisher +5 VDC? | Go to step 8. |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 13 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8303 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8303A-3 <=> J8302A-1 } \\ & \text { J8303A-2 <=> J8302A-2 } \\ & \text { J8303A-1 <=> J8302A-3 } \end{aligned}$ | Go to step 14. | Replace the HARNESSASSY MAIN SENSOR. |
| 14 | Checking +5 VDC power supply to the SENSOR (Transport Entrance Sensor) <br> Is the voltage across J8302A-3 <=> J8302A-1 on the PWB MAIN-C +5 VDC? | Go to step 15. | Replace the PWB MAIN-C. (RRP 12.98) |
| 15 | Checking the SENSOR (Transport Entrance Sensor) for operation <br> Does the voltage across P8302A-2 <=> P8302A-1 on the PWB MAIN-C change, every time a piece of white paper is placed over the sensing area of the SENSOR (X'port Entrance Sensor)? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR. (RRP 12.82) |
| 16 | Checking the MOTOR ASSY (Finisher Transport Motor) for operation <br> Execute [Output 12-03 Fin Transport Motor 350 ON/OFF] in [Diagnosis]. <br> Does the MOTOR ASSY (Finisher Transport Motor) rotate normally? | Go to step 25. | Go to step 17. |
| 17 | Checking the MOTOR ASSY (Finisher Transport Motor) for power transmission <br> Execute [Output 12-03 Fin Transport Motor 350 ON/OFF] in [Diagnosis]. <br> Does the rotation of the MOTOR ASSY transmit to the ROLL ASSY-ENT (PL 12.12.10) through the BELT (PL 12.12.23)? | Go to step 19. | After reinstalling the MOTOR ASSY and BELT, go to step 18. (RRP 12.84) |
| 18 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 19. | End of work. |
| 19 | Checking the HARNESS ASSY MAIN DRIVE connection Are P/J8342 and P/J8304 of the HARNESS ASSY MAIN DRIVE connected surely? | Go to step 21. | After reconnecting, go to step 20. |
| 20 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 21. | End of work. |
| 21 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8342 and P/J8304 of the HARNESS ASSY MAIN DRIVE. <br> Check for conductivity at the following: <br> J8342-1 <=> J8304-23 <br> J8342-2 <=> J8304-16 <br> J8342-3 <=> J8304-25 <br> J8342-4 <=> J8304-27 <br> J8342-5 <=> J8304-18 <br> J8342-6 <=> J8304-29 | Go to step 22. | Replace the HARNESSASSY MAIN DRIVE. |


| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 22 | Checking the resistance of the MOTOR ASSY Are there any resistances without disconnection across P8342-2/5(COM) and P8342-1/3/4/6 of the MOTOR ASSY? | Go to step 23. | Replace the MOTOR ASSY. (RRP 12.84) |
| 23 | Checking +24 VDC power supply to MOTOR ASSY Are the voltages across J8304-16 <=> FRAME CHASSIS, and J8304-18 <=> FRAME CHASSIS on the PWB MAINC, +24 VDC? | Go to step 24. | Replace the PWB MAIN-C. (RRP 12.98) |
| 24 | Checking after replacing the MOTOR ASSY <br> Replace the MOTOR ASSY.(RRP 12.84) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |
| 25 | Checking the SENSOR (Gate Sensor) for operation Execute [Input 12-51 Gate SENSOR] in [Diagnosis]. Does the display on the screen change, every time a piece of white paper is placed over the sensing area of the SENSOR (Gate Sensor)? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 26. |
| 26 | Checking the HARNESS ASSY-SENSOR connection Are the connectors of the HARNESS ASSY-SENSOR connected surely? | Go to step 28. | After reconnecting, go to step 27 |
| 27 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 28. | End of work. |
| 28 | Checking the HARNESS ASSY-SENSOR for conductivity Disconnect P/J8432 and P/J8376 of the HARNESS ASSY-SENSOR. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8432-3 <=> J8376-1 } \\ & \text { J8432-2 <=> J8376-2 } \\ & \text { J8432-1 <=> J8376-3 } \end{aligned}$ | Go to step 29. | Replace the HARNESS ASSY-SENSOR. |
| 29 | Checking +5 VDC power supply to the SENSOR (Gate Sensor) Is the voltage across P8376-3 <=> P8376-1 on the PWB MAIN-C +5 VDC? | Go to step 30. | Replace the PWB MAIN-C. (RRP 12.98) |
| 30 | Checking the SENSOR (Gate Sensor) for operation Does the voltage across P8376-2 <=> P8376-1 on the PWB MAIN-C change, every time a piece of white paper is placed over the SENSOR (Gate Sensor)? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR. (RRP 12.93) |

## F4-16 Finisher H-Transport Entrance Sensor Static Jam A

NOTE This FIP can also be applied for the following.
NOTE F4-17 Finisher H-Transport Entrance Sensor Static Jam B

| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> WIRE HARNESS (PL 12.3.26) <br> PWB H-TRA (PL 12.14.3) <br> H-TRANSPORT ENTRANCE SENSOR (PL 12.3.23) <br> H-TRANSPORT MOTOR (PL 12.3.7) |  |  |
| 1 | Checking the H-TRANSPORT ENTRANCE SENSOR (Finisher H -Transport Entrance Sensor) for operation Execute [Input 12-28 H-Transport Ent.SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the actuator of the H-TRANSPORT ENTRANCE SENSOR is operated? | Go to step 7. | Go to step 2. |
| 2 | Checking the WIRE HARNESS (PL 12.3.26) connection Are the connectors of the WIRE HARNESS connected to the H -TRANSPORT ENTRANCE SENSOR and PBW HTRA of the Finisher connected surely? | Go to step 4. | After reconnecting, go to step 3. |
| 3 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 4. | End of work. |
| 4 | Checking the WIRE HARNESS for conductivity Disconnect J8380 of the H-TRANSPORT ENTRANCE SENSOR, and P8372 on the PWB H-TRA of the Finisher. Check for conductivity at the following: <br> P8372-7 <=> J8380-3 <br> P8372-8 <=> J8380-2 <br> P8372-9 <=> J8380-1 | Go to step 5. | Replace the WIRE HARNESS. |
| 5 | Checking +5 VDC power supply to the H-TRANSPORT ENTRANCE SENSOR <br> Is the voltage across J8372-9 <=> J8372-7 on the PWB H-TRA of the Finisher +5 VDC? | Go to step 6. | Replace the PWB H-TRA. (RRP 12.97) |
| 6 | Checking the H -TRANSPORT ENTRANCE SENSOR for operation <br> Does the voltage across J8372-8 <=> J8372-7 on the PWB H-TRA of the Finisher change, every time the actuator of the H-TRANSPORT ENTRANCE SENSOR is operated? | Replace the PWB H-TRA. (RRP 12.97) | Replace the H-TRANSPORT ENTRANCE SENSOR. (RRP 12.13) |
| 7 | Checking the H-TRANSPORT MOTOR for operation Execute [Output 12-01 H XPORT Motor 145 ON/OFF] in [Diagnosis]. <br> Does the H-TRANSPORT MOTOR rotate normally? | Replace the PWB H-TRA. (RRP 12.97) | Go to step 8. |
| 8 | Checking the WIRE HARNESS connection Are the connectors of the WIRE HARNESS connected to the H-TRANSPORT MOTOR and PBW H-TRA of the Finisher connected surely? | Go to step 10. | After reconnecting, go to step 9. |
| 9 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 10. | End of work. |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 10 | Checking the WIRE HARNESS for conductivity <br> Disconnect P/J8379 of the H-TRANSPORT MOTOR, and P8372 on the PWB H-TRA of the Finisher. <br> Check for conductivity at the following: <br> P8372-13 <=> J8379-6 <br> P8372-12 <=> J8379-4 <br> P8372-11 <=> J8379-1 <br> P8372-10 <=> J8379-3 <br> P8372-15 <=> J8379-2 <br> P8372-14 <=> J8379-5 | Go to step 11. | Replace the WIRE HARNESS. |
| 11 | Checking the resistance of the H-TRANSPORT MOTOR Are there any resistances without disconnection across P8379-2/5(COM) and P8379-1/3/4/6 of the H-TRANSPORT MOTOR? | Go to step 12. | Replace the H-TRANSPORT MOTOR. (RRP 12.10) |
| 12 | Checking +24 VDC power supply to the H-TRANSPORT MOTOR <br> Are the voltages across J8372-15 <=> J8372-7, and J8372-14 <=> J8372-7 on the PWB H-TRA of the Finisher, +24 VDC? | Go to step 13. | Replace the PWB H-TRA. (RRP 12.97) |
| 13 | Checking after replacing the H-TRANSPORT MOTOR Replace the H-TRANSPORT MOTOR. (RRP 12.10) Execute [Test Print] in [Diagnosis]. Does the error still occur? | Replace the PWB H-TRA. (RRP 12.97) | End of work. |

## F4-26 Finisher H-Transport Exit Sensor Static Jam

| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> WIRE HARNESS (PL 12.3.26) <br> PWB H-TRA (PL 12.14.3) <br> H-TRANSPORT EXIT SENSOR (PL 12.3.21) <br> H-TRANSPORT MOTOR (PL 12.3.7) |  |  |
| 1 | Checking the H-TRANSPORT EXIT SENSOR (Finisher <br> H-Transport Exit Sensor) for operation <br> Execute [Input 12-29 H-Transport Exit SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the actuator of the H-TRANSPORT Exit SENSOR is operated? | Go to step 7. | Go to step 2. |
| 2 | Checking the WIRE HARNESS (PL 12.3.26) connection Are the connectors of the WIRE HARNESS connected to the H-TRANSPORT EXIT SENSOR and PBW H-TRA of the Finisher connected surely? | Go to step 4. | After reconnecting, go to step 3. |
| 3 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 4. | End of work. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 4 | Checking the WIRE HARNESS for conductivity Disconnect J8381 of the H-TRANSPORT EXIT SENSOR, and P8372 on the PWB H-TRA of the Finisher. <br> Check for conductivity at the following: <br> P8372-4 <=> J8381-3 <br> P8372-5 <=> J8381-2 <br> P8372-6 <=> J8381-1 | Go to step 5. | Replace the WIRE HARNESS. |
| 5 | Checking +5 VDC power supply to the H-TRANSPORT EXIT SENSOR <br> Is the voltage across J8372-6 <=> J8372-4 on the PWB H -TRA of the Finisher +5 VDC ? | Go to step 6. | Replace the PWB H-TRA. (RRP 12.97) |
| 6 | Checking the H-TRANSPORT EXIT SENSOR for operation <br> Does the voltage across J8372-5 <=> J8372-4 on the PWB H-TRA of the Finisher change, every time the actuator of the H-TRANSPORT EXIT SENSOR is operated? | Replace the PWB H-TRA. (RRP 12.97) | Replace the H-TRANSPORT EXIT SENSOR. (RRP 12.14) |
| 7 | Checking the H-TRANSPORT MOTOR for operation Execute [Output 12-01 H XPORT Motor 145 ON/OFF] in [Diagnosis]. <br> Does the H-TRANSPORT MOTOR rotate normally? | Replace the PWB H-TRA. (RRP 12.97) | Go to step 8. |
| 8 | Checking the WIRE HARNESS connection Are the connectors of the WIRE HARNESS connected to the H-TRANSPORT MOTOR and PBW H-TRA of the Finisher connected surely? | Go to step 10. | After reconnecting, go to step 9. |
| 9 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 10. | End of work. |
| 10 | Checking the WIRE HARNESS for conductivity <br> Disconnect P/J8379 of the H-TRANSPORT MOTOR, and P8372 on the PWB H-TRA of the Finisher. <br> Check for conductivity at the following: <br> P8372-13 <=> J8379-6 <br> P8372-12 <=> J8379-4 <br> P8372-11 <=> J8379-1 <br> P8372-10 <=> J8379-3 <br> P8372-15 <=> J8379-2 <br> P8372-14 <=> J8379-5 | Go to step 11. | Replace the WIRE HARNESS. |
| 11 | Checking the resistance of the H-TRANSPORT MOTOR Are there any resistances without disconnection across P8379-2/5(COM) and P8379-1/3/4/6 of the H-TRANSPORT MOTOR? | Go to step 12. | Replace the H-TRANSPORT MOTOR. (RRP 12.10) |
| 12 | Checking +24 VDC power supply to the H-TRANSPORT MOTOR <br> Are the voltages across J8372-15 <=> J8372-7, and J8372-14 <=> J8372-7 on the PWB H-TRA of the Finisher, +24 VDC? | Go to step 13. | Replace the PWB H-TRA. (RRP 12.97) |
| 13 | Checking after replacing the H -TRANSPORT MOTOR Replace the H-TRANSPORT MOTOR. (RRP 12.10) Execute [Test Print] in [Diagnosis]. Does the error still occur? | Replace the PWB H-TRA. (RRP 12.97) | End of work. |

F4-36 Finisher Transport Entrance Sensor Static Jam

| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (PL 12.12.19) <br> HARNESS ASSY TRANSPORT ENT SENSOR (PL <br> 12.15.4) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> MOTOR ASSY (PL 12.12.21) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) |  |  |
| 1 | Checking the SENSOR (Transport Entrance Sensor) for operation <br> Execute [Input 12-30 Transport Ent. SENSOR] in [Diagnosis]. <br> Does the display change, every time a piece of white paper is placed over the SENSOR (Transport Entrance Sensor)? | Go to step 8. | Go to step 2. |
| 2 | Checking the HARNESS ASSY connection Are P/J8319 and P/J8303 of the HARNESS ASSY X'PORT ENT SENSOR, and P/J8302A of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 4. | After reconnecting, go to step 3. |
| 3 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 4. | End of work. |
| 4 | Checking the HARNESS ASSY X'PORT ENT SENSOR for conductivity <br> Disconnect P/J8319 and P/J8303 of the HARNESS ASSY X'PORT ENT SENSOR. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8319-3 <=> J8303B-1 } \\ & \text { J8319-2 <=> J8303B-2 } \\ & \text { J8319-1 <=> J8303B-3 } \end{aligned}$ | Go to step 5. | Replace the HARNESSASSY X'PORT ENT SENSOR. |
| 5 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8303 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8303A-3 <=> J8302A-1 } \\ & \text { J8303A-2 <=> J8302A-2 } \\ & \text { J8303A-1 <=> J8302A-3 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY MAIN SENSOR. |
| 6 | Checking +5 VDC power supply to the SENSOR (Transport Entrance Sensor) <br> Is the voltage across J8302A-3 <=> J8302A-1 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |
| 7 | Checking the SENSOR (Transport Entrance Sensor) for operation <br> Does the voltage across P8302A-2 <=> P8302A-1 on the PWB MAIN-C change, every time a piece of white paper is placed over the SENSOR (X'port Entrance Sensor)? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR. (RRP 12.82) |


| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 8 | Checking the MOTOR ASSY (Finisher Transport Motor) <br> for operation <br> Execute [Output 12-03 Fin Transport Motor 350 ON/OFF] <br> in [Diagnosis]. <br> Does the MOTOR ASSY (Finisher Transport Motor) rotate <br> normally? | Go to step 9. |  | Go to step 10.

## F4-46 Finisher Buffer Path Sensor Static Jam A

## NOTE This FIP can also be applied for the followings.

NOTE F4-47 Finisher Buffer Path Sensor Static Jam B

| Ste <br> p | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SENSOR ASSY (PL 12.12.12) <br> HARNESS ASSY BUFFER SENSOR (PL 12.15.5) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) <br> MOTOR ASSY (PL 12.13.30) |  |  |
| 1 | Checking the SENSOR ASSY (Buffer Path Sensor) for operation <br> Execute [Input 12-31 Buffer Path SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the actuator of the SENSOR ASSY (Buffer Path Sensor) R is operated? | Go to step 10. | Go to step 2. |
| 2 | Checking the HARNESS ASSY BUFFER SENSOR connection <br> Are P/J8392 and P/J8318 of the HARNESS ASSY BUFFER SENSOR connected surely? | Go to step 4. | After reconnecting, go to step 3. |
| 3 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 4. | End of work. |
| 4 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8318 and P/J8302A of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 6. | After reconnecting, go to step 5. |
| 5 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 6. | End of work. |
| 6 | Checking the HARNESS ASSY BUFFER SENSOR for conductivity <br> Disconnect P/J8392 and P/J8318 of the HARNESS ASSY BUFFER SENSOR. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8392-3 <=> J8318B-1 } \\ & \text { J8392-2 <=> J8318B-2 } \\ & \text { J8392-1 <=> J8318B-3 } \end{aligned}$ | Go to step 7. | Replace the HARNESSASSY BUFFER SENSOR. |
| 7 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8318 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8318A-3 <=> J8302A-13 } \\ & \text { J8318A-2 <=> J8302A-14 } \\ & \text { J8318A-1 <=> J8302A-15 } \end{aligned}$ | Go to step 8. | Replace the HARNESSASSY MAIN SENSOR. |
| 8 | Checking +5 VDC power supply to the SENSOR ASSY (Buffer Path Sensor) <br> Is the voltage across J8302A-15 <=> J8302A-13 on the PWB MAIN-C +5 VDC? | Go to step 9. | Replace the PWB MAIN-C. (RRP 12.98) |


| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 9 | Checking the SENSOR ASSY (Buffer Path Sensor) for operation <br> Does the voltage across P8302A-14 <=> P8302A-13 on the PWB MAIN-C change, every time the actuator of the SENSOR ASSY (Buffer Path Sensor) is operated? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR ASSY (Buffer Path Sensor). <br> (RRP 12.76) |
| 10 | Checking the MOTOR ASSY (Registration Motor) for operation <br> Execute [Output 12-05 Registration Motor 285F ON/OFF] in [Diagnosis]. <br> Does the MOTOR ASSY (Registration Motor) rotate normally? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 11. |
| 11 | Checking the MOTOR ASSY (Registration Motor) for power transmission <br> Execute [Output 12-05 Registration Motor 285F ON/OFF] in [Diagnosis]. <br> Does the rotation of the MOTOR ASSY transmit to the ROLL ASSY-BUFFER (PL 12.12.13) through the BELT (PL 12.13.27)? | Go to step 13. | After reinstalling the MOTOR ASSY and BELT, go to step 12. (RRP 12.96) |
| 12 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 13. | End of work. |
| 13 | Checking the HARNESS ASSY MAIN DRIVE connection Are P/J8335 and P/J8304 of the HARNESS ASSY MAIN DRIVE connected surely? | Go to step 15. | After reconnecting, go to step 14. |
| 14 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 15. | End of work. |
| 15 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8335 and P/J8304 of the HARNESS ASSY MAIN DRIVE. <br> Check for conductivity at the following: <br> J8335-1 <=> J8304-7 <br> J8335-2 <=> J8304-8 <br> J8335-3 <=> J8304-9 <br> J8335-4 <=> J8304-11 <br> J8335-5 <=> J8304-10 <br> J8335-6 <=> J8304-13 | Go to step 16. | Replace the HARNESSASSY MAIN DRIVE. |
| 16 | Checking the resistance of the MOTOR ASSY Are there any resistances without disconnection across P8335-2/5(COM) and P8335-1/3/4/6 of the MOTOR ASSY? | Go to step 17. | Replace the MOTOR ASSY. (RRP 12.96) |
| 17 | Checking +24 VDC power supply to the MOTOR ASSY Are the voltages across J8304-8 <=> FRAME CHASSIS, and J8304-10 <=> FRAME CHASSIS on the PWB MAINC, +24 VDC ? | Go to step 18. | Replace the PWB MAIN-C. (RRP 12.98) |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| Checking after replacing the MOTOR ASSY (Registration <br> 18 | Motor) <br> Replace the MOTOR ASSY (Registration Motor). (RRP <br> 12.96) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | End of work. |

## F4-56 Finisher Compile Exit Sensor Static Jam

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> SENSOR ASSY (PL 12.11.3) <br> HARNESS ASSY COMPILER (PL 12.10.8) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) <br> MOTOR ASSY (PL 12.13.30) <br> BRACKET ASSY SOL (PL 12.12.34) | Go |  |
| 1 | Checking the SENSOR ASSY (Compile Exit Sensor) for <br> operation <br> Execute [Input 12-34 Compile Exit SENSOR] in [Diagno- <br> sis]. <br> Does the display on the screen change, every time the <br> actuator of the SENSOR ASSY (Compile Exit Sensor) is <br> operated? | Go to step 10. | Go to step 2. |
| 2 | Checking the HARNESS ASSY COMPILER connection <br> Are P/J8320 and P/J8391 of the HARNESS ASSY COM- <br> PILER connected surely? | Go to step 4. | After reconnect- <br> ing, go to step 3. |
| 3 | Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 4. | End of work. |
| 4 | Checking the HARNESS ASSY MAIN SENSOR connec- <br> tion <br> Are P/J8391 and P/J8302A of the HARNESS ASSY MAIN <br> SENSORE connected surely? | Go to step 6. | After reconnect- <br> ing, go to step 5. |
| 5 | Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 6. | End of work. |
| 6 | Checking the HARNESS ASSY COMPILER for conductiv- <br> ity <br> Disconnect P/J8320 and P/J8391 of the HARNESS ASSY <br> COMPILER. <br> Check for conductivity at the following: <br> J8320-3 <=> J8391B-1 <br> J8320-2 <=> J8391B-2 <br> J8320-1 <=> J8391B-3 | Replace the |  |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 7 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8391 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8391A-3 <=> J8302A-4 } \\ & \text { J8391A-2 <=> J8302A-5 } \\ & \text { J8391A-1 <=> J8302A-6 } \end{aligned}$ | Go to step 8. | Replace the HARNESSASSY MAIN SENSOR. |
| 8 | Checking +5 VDC power supply to the SENSOR ASSY (Compile Exit Sensor) Is the voltage across J8302A-6 <=> J8302A-4 on the PWB MAIN-C +5 VDC? | Go to step 9. | Replace the PWB MAIN-C. (RRP 12.98) |
| 9 | Checking the SENSOR ASSY (Compile Exit Sensor) for operation <br> Does the voltage across P8302A-5 <=> P8302A-4 on the PWB MAIN-C change, every time the actuator of the SENSOR ASSY (Compile Exit Sensor) is operated? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR ASSY <br> (Compile Exit Sensor). (RRP 12.67) |
| 10 | Checking the MOTOR ASSY (Exit Motor) for operation Execute [Output 12-09 Exit Motor 285F ON/OFF] in [Diagnosis]. <br> Does the MOTOR ASSY (Exit Motor) rotate normally? | Go to step 19. | Go to step 11. |
| 11 | Checking the MOTOR ASSY (Exit Motor) for power transmission <br> Execute [Output 12-09 Exit Motor 285F ON/OFF] in [Diagnosis]. <br> Does the rotation of the MOTOR ASSY transmit to the ROLL ASSY-ENT (PL 12.12.10) and the two ROLL ASSY-EXIT LOWs (PL 12.11.6) through the BELT (PL 12.13.28)? | Go to step 13. | After reinstalling the MOTOR ASSY and BELT, go to step 12. (RRP 12.95) |
| 12 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 13. | End of work. |
| 13 | Checking the HARNESS ASSY MAIN DRIVE connection Are P/J8334 and P/J8304 of the HARNESS ASSY MAIN DRIVE connected surely? | Go to step 15. | After reconnecting, go to step 14. |
| 14 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 15. | End of work. |
| 15 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8334 and P/J8304 of the HARNESS ASSY MAIN DRIVE. <br> Check for conductivity at the following: <br> J8334-1 <=> J8304-2 <br> J8334-2 <=> J8304-4 <br> J8334-3 <=> J8304-1 <br> J8334-4 <=> J8304-3 <br> J8334-5 <=> J8304-6 <br> J8334-6 <=> J8304-5 | Go to step 16. | Replace the HARNESSASSY MAIN DRIVE. |


| Ste <br> p | Check | Yes | No |
| :---: | :--- | :--- | :---: |
| 16 | Checking the resistance of the MOTOR ASSY <br> Are there any resistances without disconnection across <br> P8334-2/5(COM)and P8334-1/3/4/6 of the MOTOR <br> ASSY? | Go to step 17. | Replace the <br> MOTOR ASSY. <br> (RRP 12.95) |
| 17 | Checking +24 VDC power supply to the MOTOR ASSY <br> Are the voltages across J8304-4 <=> FRAME CHASSIS <br> and J8304-6 <=> FRAME CHASSIS on the PWB MAIN-C, <br> +24 VDC? | Go to step 18. | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) |
| 18 | Checking after replacing the MOTOR ASSY (Exit Motor) <br> Replace the MOTOR ASSY (Exit Motor). (RRP 12.95) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | End of work. |

F4-66 Finisher Compile No Paper Sensor Static Jam

| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> MOTOR ASSY-DC (PL 12.9.11) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) <br> BRACKET ASSY-EJECT (PL 12.10.17) <br> PWB MAIN-C (PL 12.14.5) <br> SENSOR (PL 12.10.3) <br> HARNESS ASSY COMPILER (PL 12.10.8) |  |  |
| 1 | Checking the MOTOR ASSY-DC (Eject Clamp Motor) for <br> operation <br> Execute [Output 12-18 Eject Clamp Motor UP ON/OFF] <br> and [Output 12-19 Eject Clamp Motor DOWN ON/OFF] in <br> [Diagnosis]. <br> Does the MOTOR ASSY-DC (Eject Clamp Motor) rotate <br> normally? | Go to step 6. | Go to step 2. |
| 2 | Checking the HARNESS ASSY MAIN DRIVE connection <br> Are P/J8339 and P/J 8304 of the HARNESS ASSY MAIN <br> DRIVE connected surely? | Go to step 4. | After reconnect- |
| ing, go to step 3. |  |  |  |
| 3 | Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 4. | End of work. |
| 7 | Checking the HARNESS ASSY MAIN DRIVE for conduc- <br> tivity <br> Disconnect P/J8339 and P/J8304 of the HARNESS ASSY <br> MAIN DRIVE. <br> Check for conductivity at the following: <br> J8339-1 <=> J8304-33 <br> J8339-2 <=> J8304-31 | Go to step 5. | HARNESS ASSY |
| MAIN DRIVE. |  |  |  |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 9 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8336 and P/J8304 of the HARNESS ASSY MAIN DRIVE. <br> Check for conductivity at the following: <br> J8336-1 <=> J8304-15 <br> J8336-2 <=> J8304-12 <br> J8336-3 <=> J8304-17 <br> J8336-4 <=> J8304-19 <br> J8336-5 <=> J8304-14 <br> J8336-6 <=> J8304-21 | Go to step 10. | Replace the HARNESSASSY MAIN DRIVE. |
| 10 | Checking the resistance of the MOTOR ASSY <br> Are there any resistances without disconnection across P8336-2/5(COM) and P8336-1/3/4/6 of the MOTOR ASSY? | Go to step 11. | Replace the BRACKET ASSY-EJECT. (RRP 12.65) |
| 11 | Checking +24 VDC power supply to the MOTOR ASSY Are the voltages across J8304-12 <=> FRAME CHASSIS, and J8304-14 <=> FRAME CHASSIS on the PWB MAINC, +24 VDC? | Go to step 12. | Replace the PWB MAIN-C. (RRP 12.98) |
| 12 | Checking after replacing the BRACKET ASSY-EJECT <br> (Eject Motor) <br> Replace the BRACKET ASSY-EJECT (Eject Motor). <br> (RRP 12.65) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |
| 13 | Checking the SENSOR (Compile Tray No Paper Sensor) for operation <br> Execute [Input 12-35 Compile Tray No Paper SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the ACTUATOR-PAPER (PL 12.10.4) of the SENSOR is operated? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 14. |
| 14 | Checking the HARNESS ASSY COMPILER connection Are P/J8359 and P/J8309 of the HARNESS ASSY COMPILER connected surely? | Go to step 16. | After reconnecting, go to step 15. |
| 15 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 16. | End of work. |
| 16 | Checking the HARNESS ASSY COMPILER for conductivity <br> Disconnect P/J8359 and P/J8309 of the HARNESS ASSY COMPILER. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8359-3 <=> J8309-1 } \\ & \text { J8359-2 <=> J8309-2 } \\ & \text { J8359-1 <=> J8309-3 } \end{aligned}$ | Go to step 17. | Replace the HARNESSASSY COMPILER. |
| 17 | Checking +5 VDC power supply to the SENSOR (Compile Tray No Paper Sensor) Is the voltage across J8309-3 <=> J8309-1 on the PWB MAIN-C +5 VDC? | Go to step 18. | Replace the PWB MAIN-C. (RRP 12.98) |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 18 | Checking the SENSOR (Compile Tray No Paper Sensor) <br> for operation <br> Does the voltage across P8309-2 <=> P8309-1 on the <br> PWB MAIN-C change, every time the ACTUATOR- <br> PAPER (PL 12.10.4) of the SENSOR (Compile Tray No <br> Paper Sensor) is operated? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | Replace the <br> SENSOR (Com- <br> pile Tray No <br> Paper Sensor). <br> (RRP 12.59) |

F4-76 Finisher Top Tray Exit Sensor Static Jam A
NOTE This FIP can also be applied for the followings.
NOTE F4-77 Finisher Top Tray Exit Sensor Static Jam B
NOTE F4-78 Finisher Top Tray Exit Sensor Static Jam C

| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (PL 12.13.2) <br> HARNESS ASSY TOP EXIT SENSOR (PL 12.15.6) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> MOTOR ASSY (PL 12.13.30) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) | Checking the SENSOR (Top Tray Exit Sensor) for opera- <br> tion <br> Execute [Input 12-32 Top Tray Exit SENSOR] in [Diagno- <br> sis]. <br> Does the display on the screen change, every time the <br> actuator of the SENSOR is operated? | Go to step 8. | Go to step 2.


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 5 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> DisconnectP/J8312 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8312A-3 <=> J8302A-7 } \\ & \text { J8312A-2 <=> J8302A-8 } \\ & \text { J8312A-1 <=> J8302A-9 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY MAIN SENSOR. |
| 6 | Checking +5 VDC power supply to the SENSOR (Top Tray Exit Sensor) <br> Is the voltage across J8302A-9 <=> J8302A-7 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |
| 7 | Checking the SENSOR (Top Tray Exit Sensor) for operation <br> Does the voltage across P8302A-8 <=> P8302A-7 on the PWB MAIN-C change, every time a piece of white paper is placed over the sensing area of the SENSOR (Top Tray Exit Sensor)? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Top Tray Exit Sensor). (RRP 12.87) |
| 8 | Checking the MOTOR ASSY (Registration Motor) for operation <br> Execute [Output 12-05 Registration Motor 285F ON/OFF] in [Diagnosis]. <br> Does the MOTOR ASSY (Registration Motor) rotate normally? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 9. |
| 9 | Checking the MOTOR ASSY (Registration Motor) for power transmission <br> Execute [Output 12-05 Registration Motor 285F ON/OFF] in [Diagnosis]. <br> Does the rotation of the MOTOR ASSY transmit to the ROLL ASSY-BUFFER (PL 12.12.13) through the BELT (PL 12.13.27)? | Go to step 11. | After reinstalling the MOTOR ASSY and BELT, go to step 10. (RRP 12.96) |
| 10 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 11. | End of work. |
| 11 | Checking the HARNESS ASSY MAIN DRIVE connection Are P/J8335 and P/J8304 of the HARNESS ASSY MAIN DRIVE connected surely? | Go to step 13. | After reconnecting, go to step 12. |
| 12 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 13. | End of work. |
| 13 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8335 and P/J8304 of the HARNESS ASSY MAIN DRIVE. <br> Check for conductivity at the following: $\begin{aligned} & \mathrm{J} 8335-1 \text { <=> J8304-7 } \\ & \mathrm{J} 8335-2 \text { <=> J8304-8 } \\ & \mathrm{J} 8335-3 \text { <=> J8304-9 } \\ & \mathrm{J} 8335-4 \text { <=> J8304-11 } \\ & \text { J8335-5 <=> J8304-10 } \\ & \mathrm{J} 8335-6 \text { <=> J8304-13 } \end{aligned}$ | Go to step 14. | Replace the HARNESSASSY MAIN DRIVE. |


| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 14 | Checking the resistance of the MOTOR ASSY <br> Are there any resistances without disconnection across <br> P8335-2/5(COM) and P8335-1/3/4/6 of the MOTOR <br> ASSY? | Go to step 15. <br> Are the voltages across J8304-8 <=> FRAME CHASSIS, <br> and J8304-10 <=> FRAME CHASSIS on the PWB MAIN- <br> C, +24 VDC? | Replace the <br> MOTOR ASSY. <br> (RRP 12.96) |
| 16 | Checking after replacing the MOTOR ASSY (Registration <br> Motor) <br> Replace the MOTOR ASSY (Registration Motor). (RRP <br> 12.96) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) |  |

## F4-83 Finisher Gate Sensor Static Jam (to Top Tray) A

NOTE This FIP can also be applied for the followings.
NOTE F4-84 Finisher Gate Sensor Static Jam (to Top Tray) B
NOTE F4-85 Finisher Gate Sensor Static Jam (to Top Tray) C

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> MOTOR ASSY (PL 12.12.21) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) <br> PWB MAIN-C (PL 12.14.5) <br> SENSOR (PL 12.13.15) <br> HARNESS ASSY-SENSOR (PL 12.13.16) | Checking the MOTOR ASSY (Finisher Transport Motor) <br> for operation <br> Execute [Output 12-03 Fin Transport Motor 350 ON/OFF] <br> in [Diagnosis]. <br> Does the MOTOR ASSY (Finisher Transport Motor) rotate <br> normally? | Go to step 2. |$\quad$ Go to step 3.


| $\begin{array}{c}\text { Ste } \\ p\end{array}$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 5 | $\begin{array}{l}\text { Checking the HARNESS ASSY MAIN DRIVE for conduc- } \\ \text { tivity } \\ \text { Disconnect P/J8342 and P/J8304 of the HARNESS ASSY } \\ \text { MAIN DRIVE. } \\ \text { Check for conductivity at the following: } \\ \text { J8342-1 <=> J8304-23 } \\ \text { J8342-2 <=> J8304-16 } \\ \text { J8342-3 <=> J8304-25 } \\ \text { J8342-4 <=> J8304-27 } \\ \text { J8342-5 <=> J8304-18 } \\ \text { J8342-6 <=> J8304-29 }\end{array}$ | Go to step 6. |  | \(\left.\begin{array}{c}HARNESS ASSY <br>

MAIN DRIVE.\end{array}\right\}\)

| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 14 | Checking the SENSOR (Gate Sensor) for operation <br> Does the voltage across P8376-2 <=> P8376-1 on the <br> PWB MAIN-C change, every time a piece of white paper <br> is placed over the sensing area of the SENSOR (Gate <br> Sensor)? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | Replace the <br> SENSOR. <br> (RRP 12.93) |

## F4-86 Finisher Gate Sensor Static Jam (to Stacker Tray) A

NOTE This FIP can also be applied for the followings.
NOTE F4-87 Finisher Gate Sensor Static Jam (to Stacker Tray) B
NOTE F4-88 Finisher Gate Sensor Static Jam (to Stacker Tray) C

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> MOTOR ASSY (PL 12.12.21) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) <br> PWB MAIN-C (PL 12.14.5) <br> SENSOR (PL 12.13.15) <br> HARNESS ASSY-SENSOR (PL 12.13.16) | Checking the MOTOR ASSY (Finisher Transport Motor) <br> for operation <br> Execute [Output 12-03 Fin Transport Motor 350 ON/OFF] <br> in [Diagnosis]. <br> Does the MOTOR ASSY (Finisher Transport Motor) rotate <br> normally? | Go to step 2. | Go to step 3.


| $\begin{array}{c}\text { Ste } \\ \text { p }\end{array}$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 5 | $\begin{array}{l}\text { Checking the HARNESS ASSY MAIN DRIVE for conduc- } \\ \text { tivity } \\ \text { Disconnect P/J8342 and P/J8304 of the HARNESS ASSY } \\ \text { MAIN DRIVE. } \\ \text { Check for conductivity at the following: } \\ \text { J8342-1 <=> J8304-23 } \\ \text { J8342-2 <=> J8304-16 } \\ \text { J8342-3 <=> J8304-25 } \\ \text { J8342-4 <=> J8304-27 } \\ \text { J8342-5 <=> J8304-18 } \\ \text { J8342-6 <=> J8304-29 }\end{array}$ | Go to step 6. |  | \(\left.\begin{array}{c}HARNESS ASSY <br>

MAIN DRIVE.\end{array}\right\}\)

| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 14 | Checking the SENSOR (Gate Sensor) for operation <br> Does the voltage across P8376-2 <=> P8376-1 on the <br> PWB MAIN-C change, every time a piece of white paper <br> is placed over the sensing area of the SENSOR (Gate <br> Sensor)? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | Replace the <br> SENSOR. <br> (RRP 12.93) |

## H5-11 Stacker Tray Fail

| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> COVER ASSY SENSOR (PL 12.6.13) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> MOTOR ASSY DC (PL 12.6.26) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the vertical transport mechanism of the Stacker Tray for obstacles and deformation Are there any obstacles in the vertical transport mechanism of the Stacker Tray? Is there any deformation in the vertical transport mechanism of the Stacker Tray? | Remove obstacles/replace deformed part. | Go to step 2. |
| 2 | Checking the COVER ASSY SENSOR (PL 12.6.13) <br> (Stacker Height Sensor 1) for operation <br> Execute [Input 13-50 Stack Height SENSOR 1] in [Diagnosis]. <br> Does the display on the screen change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Go to step 8. | Go to step 3. |
| 3 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8331 and P/J8302B of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> DisconnectP/J8331 of the HARNESS ASSY MAIN SENSOR, and P/J8302B on the PWB MAIN-C. <br> Check for conductivity at the following: <br> J8331-5 <=> J8302B-1 <br> J8331-4 <=> J8302B-2 <br> J8331-3 <=> J8302B-3 <br> J8331-2 <=> J8302B-4 <br> J8331-1 <=> J8302B-5 | Go to step 6. | Replace the HARNESSASSY MAIN SENSOR. |
| 6 | Checking +5 VDC power supply to the COVER ASSY SENSOR (Stacker Height Sensor 1) <br> Is the voltage across J8302B-3 <=> J8302B-1 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. <br> (RRP 12.98) |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 7 | Checking the COVER ASSY SENSOR (Stacker Height <br> Sensor 1) for operation <br> Does the voltage across P8302B-2 <=> P8302B-1 on the PWB MAIN-C change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. <br> (RRP 12.98) | Replace the COVER ASSY SENSOR <br> (Stacker Height Sensor 1). (RRP 12.30) |
| 8 | Checking the COVER ASSY SENSOR (PL 12.6.13) <br> (Stacker Height Sensor 2) for operation <br> Execute [Input 13-51 Stack Height SENSOR 2] in [Diagnosis]. <br> Does the display on the screen change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Go to step 14. | Go to step 9. |
| 9 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8330 and P/J8302A of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 11. | After reconnecting, go to step 10. |
| 10 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 11. | End of work. |
| 11 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8330 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8330-5 <=> J8302A-16 } \\ & \text { J8330-4 <=> J8302A-17 } \\ & \text { J8330-3 <=> J8302A-18 } \\ & \text { J8330-2 <=> J8302A-19 } \\ & \text { J8330-1 <=> J8302A-20 } \end{aligned}$ | Go to step 12. | Replace the HARNESSASSY MAIN SENSOR. |
| 12 | Checking +5 VDC power supply to the COVER ASSY SENSOR (Stacker Height Sensor 2) <br> Is the voltage across J8302A-18 <=> J8302A-16 on the PWB MAIN-C +5 VDC? | Go to step 13. | Replace the PWB MAIN-C. (RRP 12.98) |
| 13 | Checking the COVER ASSY SENSOR (Stacker Height <br> Sensor 2) for operation <br> Does the voltage across P8302A-17 <=> P8302A-16 on the PWB MAIN-C change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the COVER ASSY SENSOR (Stacker Height Sensor 2). (RRP 12.31) |
| 14 | Checking the MOTOR ASSY DC (Elevator Motor) for operation <br> Execute [Output 13-31 Stacker Motor UP ON/OFF] and [Output 13-32 Stacker Motor DOWN ON/OFF] in [Diagnosis] alternately. <br> Does the MOTOR ASSY DC (Elevator Motor) rotate normally in Forward/Reverse directions? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 16. |
| 15 | Checking the MOTOR ASSY DC (Elevator Motor) connection <br> Is P/J8305 of the MOTOR ASSY DC (Elevator Motor) connected to the PWB MAIN-C surely? | Go to step 17. | After reconnecting, go to step 16. |


| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 16 | Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 17. <br> 17 <br> Checking after replacing the MOTOR ASSY DC (Elevator <br> Replace the MOTOR ASSY DC (Elevator Motor). (RRP <br> 12.35) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? End of work. |  |
| 18 | Checking after replacing the PWB MAIN-C to step 18. <br> Replace the PWB MAIN-C. (RRP 12.98) <br> Does the error still occur when the power is turned ON? | End of work. <br> A MAIN F. | End of work. |

## H5-12 Stacker Tray Upper Limit Fail

| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ACTUATOR (PL 12.6.12) <br> COVER ASSY SENSOR (PL 12.6.13) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> SENSOR (PL 12.6.17) <br> MOTOR ASSY DC (PL 12.6.26) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the COVER ASSY SENSOR (PL 12.6.13) <br> (Stacker Height Sensor 1) for operation <br> Execute [Input 13-50 Stack Height SENSOR 1] in [Diagnosis]. <br> Does the display on the screen change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Go to step 7. | Go to step 2. |
| 2 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8331 and P/J8302B of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 4. | After reconnecting, go to step 3. |
| 3 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 4. | End of work. |
| 4 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> DisconnectP/J8331 of the HARNESS ASSY MAIN SENSOR, and P/J8302B on the PWB MAIN-C. <br> Check for conductivity at the following: <br> J8331-5 <=> J8302B-1 <br> J8331-4 <=> J8302B-2 <br> J8331-3 <=> J8302B-3 <br> J8331-2 <=> J8302B-4 <br> J8331-1 <=> J8302B-5 | Go to step 5. | Replace the HARNESSASSY MAIN SENSOR. |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 5 | Checking +5 VDC power supply to the COVER ASSY SENSOR (Stacker Height Sensor 1) <br> Is the voltage across J8302B-3 <=> J8302B-1 on the PWB MAIN-C +5 VDC? | Go to step 6. | Replace the PWB MAIN-C. (RRP 12.98) |
| 6 | Checking the COVER ASSY SENSOR (Stacker Height Sensor 1) for operation <br> Does the voltage across P8302B-2 <=> P8302B-1 on the PWB MAIN-C change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the COVER ASSY SENSOR (Stacker Height Sensor 1). (RRP 12.30) |
| 7 | Checking the COVER ASSY SENSOR (PL 12.6.13) <br> (Stacker Height Sensor 2) for operation <br> Execute [Input 13-51 Stack Height SENSOR 2] in [Diagnosis]. <br> Does the display on the screen change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Go to step 13. | Go to step 8. |
| 8 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8330 and P/J8302A of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 10. | After reconnecting, go to step 9. |
| 9 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 10. | End of work. |
| 10 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8330 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8330-5 <=> J8302A-16 } \\ & \text { J8330-4 <=> J8302A-17 } \\ & \text { J8330-3 <=> J8302A-18 } \\ & \text { J8330-2 <=> J8302A-19 } \\ & \text { J8330-1 <=> J8302A-20 } \end{aligned}$ | Go to step 11. | Replace the HARNESSASSY MAIN SENSOR. |
| 11 | Checking +5 VDC power supply to the COVER ASSY SENSOR (Stacker Height Sensor 2) <br> Is the voltage across J8302A-18 <=> J8302A-16 on the PWB MAIN-C +5 VDC? | Go to step 12. | Replace the PWB MAIN-C. (RRP 12.98) |
| 12 | Checking the COVER ASSY SENSOR (Stacker Height Sensor 2) for operation Does the voltage across P8302A-17 <=> P8302A-16 on the PWB MAIN-C change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the COVER ASSY SENSOR (Stacker Height Sensor 2). (RRP 12.31) |
| 13 | Checking the ACTUATOR (PL 12.6.12) for operation Is the ACTUATOR installed correctly? <br> Does it enter the sensing area of the SENSOR (Upper Limit Sensor)? | Go to step 14. | Replace the ACTUATOR. |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 14 | Checking the SENSOR (Upper Limit Sensor) for operation Execute [Input 13-46 Upper Limit SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 15. |
| 15 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8327 and P/J8302B of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 17. | After reconnecting, go to step 16 |
| 16 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 17. | End of work. |
| 17 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8327 of the HARNESS ASSY MAIN SENSOR, and P/J8302B on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8327-3 <=> J8302B-18 } \\ & \text { J8327-2 <=> J8302B-19 } \\ & \text { J8327-1 <=> J8302B-20 } \end{aligned}$ | Go to step 18. | Replace the HARNESSASSY MAIN SENSOR. |
| 18 | Checking +5 VDC power supply to the SENSOR (Upper Limit Sensor) <br> Is the voltage across J8302B-20 <=> J8302B-18 on the PWB MAIN-C +5 VDC? | Go to step 19. | Replace the PWB MAIN-C. (RRP 12.98) |
| 19 | Checking the SENSOR (Upper Limit Sensor) for operation Does the voltage across P8302B-19 <=> P8302B-18 on the PWB MAIN-C change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Upper Limit Sensor). (RRP 12.33) |
| 20 | Checking the MOTOR ASSY DC (Elevator Motor) for operation <br> Execute [Output 13-31 Stacker Motor UP ON/OFF] and [Output 13-32 Stacker Motor DOWN ON/OFF] in [Diagnosis] alternately. <br> Does the MOTOR ASSY DC (Elevator Motor) rotate normally in Forward/Reverse directions? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 21. |
| 21 | Checking the MOTOR ASSY DC (Elevator Motor) connection <br> Is P/J8305 of the MOTOR ASSY DC (Elevator Motor) connected to the PWB MAIN-C securely? | Go to step 23. | After reconnecting, go to step 22. |
| 22 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 23. | End of work. |
| 23 | Checking after replacing the MOTOR ASSY DC (Elevator Motor) <br> Replace the MOTOR ASSY DC (Elevator Motor). (RRP 12.35) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 24. | End of work. |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 24 | Checking after replacing the PWB MAIN-C <br> Replace the PWB MAIN-C. (RRP 12.98) <br> Does the error still occur when the power is turned ON? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | End of work. |

## H5-13 Stacker Tray Lower Limit Fail

| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ACTUATOR (PL 12.6.12) <br> COVER ASSY SENSOR (PL 12.6.13) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> SENSOR (PL 12.6.17) <br> MOTOR ASSY DC (PL 12.6.26) |  |  |
| 1 | Checking the ACTUATOR for operation Is the ACTUATOR installed correctly? <br> Does it enter the sensing area of the SENSOR (Upper Limit Sensor)? | Go to step 2. | Replace the ACTUATOR. |
| 2 | Checking the SENSOR (Stacker No Paper Sensor) for operation <br> Execute [Input 13-48 Stacker No Paper SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Go to step 8. | Go to step 3. |
| 3 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8326 and P/J8302B of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8326 of the HARNESS ASSY MAIN SENSOR, and P/J8302B on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8326-3 <=> J8302B-15 } \\ & \text { J8326-2 <=> J8302B-16 } \\ & \text { J8326-1 <=> J8302B-17 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY MAIN SENSOR. |
| 6 | Checking +5 VDC power supply to the SENSOR (Stacker No Paper Sensor) <br> Is the voltage across J8302B-17 <=> J8302B-15 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 7 | Checking the SENSOR (Stacker No Paper Sensor) for operation <br> Does the voltage across P8302B-16 <=> P8302B-15 on the PWB MAIN-C change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Stacker No Paper Sensor). (RRP 12.33) |
| 8 | Checking the COVER ASSY SENSOR (PL 12.6.13) <br> (Stacker Height Sensor 1) for operation <br> Execute [Input 13-50 Stack Height SENSOR 1] in [Diagnosis]. <br> Does the display on the screen change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Go to step 14. | Go to step 9. |
| 9 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8331 and P/J8302B of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 11. | After reconnecting, go to step 10 . |
| 10 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 11. | End of work. |
| 11 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> DisconnectP/J8331 of the HARNESS ASSY MAIN SENSOR, and P/J8302B on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8331-5 <=> J8302B-1 } \\ & \text { J8331-4 <=> J8302B-2 } \\ & \text { J8331-3 <=> J8302BB-3 } \\ & \text { J8331-2 <=> J8302B-4 } \\ & \text { J8331-1 <=> J8302B-5 } \end{aligned}$ | Go to step 12. | Replace the HARNESSASSY MAIN SENSOR. |
| 12 | Checking +5 VDC power supply to the COVER ASSY SENSOR (Stacker Height Sensor 1) <br> Is the voltage across J8302B-3 <=> J8302B-1 on the PWB MAIN-C +5 VDC? | Go to step 13. | Replace the PWB MAIN-C. (RRP 12.98) |
| 13 | Checking the COVER ASSY SENSOR (Stacker Height Sensor 1) for operation Does the voltage across P8302B-2 <=> P8302B-1 on the PWB MAIN-C change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the COVER ASSY SENSOR (Stacker Height Sensor 1). (RRP 12.30) |
| 14 | Checking the COVER ASSY SENSOR (PL 12.6.13) <br> (Stacker Height Sensor 2) for operation <br> Execute [Input 13-51 Stack Height SENSOR 2] in [Diagnosis]. <br> Does the display on the screen change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Go to step 20. | Go to step 15. |
| 15 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8330 and P/J8302A of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 17. | After reconnecting, go to step 16. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 16 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 17. | End of work. |
| 17 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8330 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8330-5 <=> J8302A-16 } \\ & \text { J8330-4 <> J8302A-17 } \\ & \text { J8330-3 <>> J8302A-18 } \\ & \text { J8330-2 <=> J8302A-19 } \\ & \text { J8330-1 }<\gg \text { J8302A-20 } \end{aligned}$ | Go to step 18. | Replace the HARNESSASSY MAIN SENSOR. |
| 18 | Checking +5 VDC power supply to the COVER ASSY SENSOR (Stacker Height Sensor 2) <br> Is the voltage across J8302A-18 <=> J8302A-16 on the PWB MAIN-C +5 VDC? | Go to step 19. | Replace the PWB MAIN-C. (RRP 12.98) |
| 19 | Checking the COVER ASSY SENSOR (Stacker Height Sensor 2) for operation Does the voltage across P8302A-17 <=> P8302A-16 on the PWB MAIN-C change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the COVER ASSY SENSOR (Stacker Height Sensor 2). (RRP 12.31) |
| 20 | Checking the SENSOR (Stacker Encode Sensor) for operation <br> Execute [Input 13-49 Stack Encoder SENSOR] in [Diagnosis]. <br> Does the display on the screen change when the BELT (PL 12.6.25) of the MOTOR ASSY-DC (PL 12.6.26) is moved by hand (when the ENCODER (PL 12.6.23) is rotated)? | Go to step 26. | Go to step 21. |
| 21 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8328 and P/J8302B of HARNESS ASSY MAIN SENSOR connected surely? | Go to step 23. | After reconnecting, go to step 22. |
| 22 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 23. | End of work. |
| 23 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8328 of the HARNESS ASSY MAIN SENSOR, and P/J8302B on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8328-3 <=> J8302B-12 } \\ & \text { J8328-2 }=\gg \text { J8302B-13 } \\ & \text { J8328-1 }=\gg \text { J8302B-14 } \end{aligned}$ | Go to step 24. | Replace the HARNESSASSY MAIN SENSOR. |
| 24 | Checking +5 VDC power supply to the SENSOR (Stacker Encode Sensor) <br> Is the voltage across J8302B-14 <=> J8302B-12 on the PWB MAIN-C +5 VDC? | Go to step 25. | Replace the PWB MAIN-C. (RRP 12.98) |


| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 25 | Checking the SENSOR (Stacker Encode Sensor) for <br> operation <br> Does the voltage across P8302B-13 and P8302B-12 of <br> the PWB MAIN-C change, every time the detection point <br> of the SENSOR is blocked or opened? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | Replace the <br> SENSOR <br> (Stacker Encode <br> Sensor). <br> (RRP 12.32) |
| 26 | Checking the MOTOR ASSY DC (Elevator Motor) for <br> operation <br> Execute [Output 13-31 Stacker Motor UP ON/OFF] and <br> [Output 13-32 Stacker Motor DOWN ON/OFF] in [Diagno- <br> sis] alternately. <br> Does the MOTOR ASSY DC (Elevator Motor) rotate nor- <br> mally in Forward/reverse directions? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | Go to step 27. |
| 27 | Checking the MOTOR ASSY DC (Elevator Motor) con- <br> nection <br> Is P/J8305 of the MOTOR ASSY DC (Elevator Motor) <br> connected to the PWB MAIN-C surely? | Go to step 28. | After reconnect- <br> ing, go to step 28. |
| 28 | Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 29. | End of work. |
| 29 | Checking after replacing the MOTOR ASSY DC (Elevator <br> Motor) <br> Replace the MOTOR ASSY DC (Elevator Motor). (RRP <br> 12.35) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | End of work. |

## H5-21 Front Tamper Home Sensor On Fail

| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (PL 12.10.2) <br> TRAY ASSY-COMPILER (PL 12.10.1) <br> HARNESS ASSY COMPILER (PL 12.10.8) <br> PWB MAIN-C (PL 12.14.5) <br> MOTOR ASSY 2 (PL 12.10.6) |  |  |
| 1 | Checking the Tamper mechanism for operation Does the tamper mechanism operate smoothly? Check this item by moving it with your fingers. | Go to step 2. | Replace the TRAY ASSYCOMPILER. (RRP 12.57) |
| 2 | Checking the SENSOR (Front Tamper Home Sensor) for operation <br> Execute [Input 13-39 Front Tamper Home SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Go to step 8. | Go to step 3. |
| 3 | Checking the HARNESS ASSY COMPILER connection Are P/J8360 and P/J8309 of the HARNESS ASSY COMPILER connected surely? | Go to step 5. | After reconnecting, go to step 4. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY COMPILER for conductivity <br> Disconnect P/J8360 of the HARNESS ASSY COMPILER, and P/J8309 on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \mathrm{J} 8360-3 \text { <=> J8309-4 } \\ & \mathrm{J} 8360-2 \text { <=> J8309-5 } \\ & \mathrm{J} 8360-1 \text { <=> J8309-6 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY COMPILER. |
| 6 | Checking +5 VDC power supply to the SENSOR (Front Tamper Home Sensor) Is the voltage across J8309-6 <=> J8309-4 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |
| 7 | Checking the SENSOR (Front Tamper Home Sensor) for operation <br> Does the voltage across P8309-5 <=> P8309-4 on the PWB MAIN-C change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Front Tamper Home Sensor). <br> (RRP 12.58) |
| 8 | Checking the MOTOR ASSY 2 (Front Tamper Motor) for operation <br> Execute [Output 13-11 Front Tamper Mot Low FRONT ON/OFF] and [Output 13-14 Front Tamper Mot Low REAR ON/OFF] in [Diagnosis] alternately. Does the MOTOR ASSY 2 (Front Tamper Motor) rotate, and does the tamper move front and rear? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 9. |
| 9 | Checking the HARNESS ASSY COMPILER connection Are P/J8363 and P/J8309 of the HARNESS ASSY COMPILER connected surely? | Go to step 11. | After reconnecting, go to step 10. |
| 10 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 11. | End of work. |
| 11 | Checking the HARNESS ASSY COMPILER for conductivity <br> Disconnect P/J8363 and P/J8309 of the HARNESS ASSY COMPILER. <br> Check for conductivity at the following: <br> J8363-6 <=> J8309-10 <br> J8363-5 <=> J8309-11 <br> J8363-4 <=> J8309-12 <br> J8363-3 <=> J8309-13 <br> J8363-2 <=> Non connection <br> J8363-1 <=> J8309-14 | Go to step 12. | Replace the HARNESSASSY COMPILER. |
| 12 | Checking +24 VDC power supply to the MOTOR ASSY 2 (Front Tamper Motor) <br> Is the voltage across J8309-11 <=> FRAME CHASSIS on the PWB MAIN-C +24 VDC? | Go to step 13. | Replace the PWB MAIN-C. (RRP 12.98) |


| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| Checking after replacing the MOTOR ASSY 2 (Front <br> Tamper Motor) <br> Replace the MOTOR ASSY 2 (Front Tamper Motor). <br> (RRP 12.60) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | End of work. |  |

## H5-22 Rear Tamper Home Sensor On Fail

| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY ASSY-COMPILER (PL 12.10.1) <br> SENSOR (PL 12.10.2) <br> HARNESS ASSY COMPILER (PL 12.10.8) <br> PWB MAIN-C (PL 12.14.5) <br> MOTOR ASSY (PL 12.10.7) |  |  |
| 1 | Checking the Tamper mechanism for operation Does the tamper mechanism operate smoothly? Check this item by moving it with your fingers. | Go to step 2. | Replace the TRAY ASSYCOMPILER. (RRP 12.57) |
| 2 | Checking the SENSOR (Rear Tamper Home Sensor) for operation <br> Execute [Input 13-40 Rear Tamper Home SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Go to step 8. | Go to step 3. |
| 3 | Checking the HARNESS ASSY COMPILER connection Are P/J8361 and P/J8309 of the HARNESS ASSY COMPILER connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY COMPILER for conductivity <br> Disconnect P/J8361 of the HARNESS ASSY COMPILER, and P/J8309 on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \mathrm{J} 8361-3 \text { <=> J8309-7 } \\ & \mathrm{J} 8361-2 \text { <=> J8309-8 } \\ & \mathrm{J} 8361-1 \text { <=> J8309-9 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY COMPILER. |
| 6 | Checking +5 VDC power supply to the SENSOR (Rear Tamper Home Sensor) Is the voltage across J8309-9 <=> J8309-7 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 7 | Checking the SENSOR (Rear Tamper Home Sensor) for operation <br> Does the voltage across P8309-8 <=> P8309-7 on the PWB MAIN-C change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Rear Tamper Home Sensor). <br> (RRP 12.58) |
| 8 | Checking the MOTOR ASSY (Rear Tamper Motor) for operation <br> Execute [Output 13-17 Rear Tamper Mot Low FRONT ON/OFF] and [Output 13-20 Rear Tamper Mot Low REAR ON/OFF] in [Diagnosis] alternately. <br> Does the MOTOR ASSY (Rear Tamper Motor) rotate, and does the tamper move front and rear? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 9. |
| 9 | Checking the HARNESS ASSY COMPILER connection Are P/J8362 and P/J8309 of the HARNESS ASSY COMPILER connected surely? | Go to step 11. | After reconnecting, go to step 10. |
| 10 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 11. | End of work. |
| 11 | Checking the HARNESS ASSY COMPILER for conductivity <br> Disconnect P/J8362 and P/J8309 of the HARNESS ASSY COMPILER. <br> Check for conductivity at the following: <br> J8362-6 <=> J8309-15 <br> J8362-5 <=> J8309-16 <br> J8362-4 <=> J8309-17 <br> J8362-3 <=> J8309-18 <br> J8362-2 <=> Non connection <br> J8362-1 <=> J8309-19 | Go to step 12. | Replace the HARNESSASSY COMPILER. |
| 12 | Checking +24 VDC power supply to the MOTOR ASSY (Rear Tamper Motor) <br> Is the voltage across J8309-16 <=> FRAME CHASSIS on the PWB MAIN-C + 24 VDC? | Go to step 13. | Replace the PWB MAIN-C. (RRP 12.98) |
| 13 | Checking after replacing the MOTOR ASSY (Rear <br> Tamper Motor) <br> Replace the MOTOR ASSY (Rear Tamper Motor). (RRP 12.61) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |

## H5-23 Front Tamper Home Sensor Off Fail

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :--- | :--- |
|  | Possible causative parts: <br> TRAY ASSY-COMPILER (PL 12.10.1) <br> SENSOR (PL 12.10.2) <br> HARNESS ASSY COMPILER (PL 12.10.8) <br> PWB MAIN-C (PL 12.14.5) <br> MOTOR ASSY 2 (PL 12.10.6) |  |  |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking the Tamper mechanism for operation Does the tamper mechanism operate smoothly? Check this item by moving it with your fingers. | Go to step 2. | Replace the TRAY ASSYCOMPILE. (RRP 12.57) |
| 2 | Checking the SENSOR (Front Tamper Home Sensor) for operation <br> Execute [Input 13-39 Front Tamper Home SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Go to step 8. | Go to step 3. |
| 3 | Checking the HARNESS ASSY COMPILER connection Are P/J8360 and P/J8309 of the HARNESS ASSY COMPILER connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY COMPILER for conductivity <br> Disconnect P/J8360 of the HARNESS ASSY COMPILER, and P/J8309 on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \mathrm{J} 8360-3 \text { <=> J8309-4 } \\ & \text { J8360-2 <=> J8309-5 } \\ & \text { J8360-1 <=> J8309-6 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY COMPILER. |
| 6 | Checking +5 VDC power supply to the SENSOR (Front Tamper Home Sensor) Is the voltage across J8309-6 <=> J8309-4 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |
| 7 | Checking the SENSOR (Front Tamper Home Sensor) for operation <br> Does the voltage across P8309-5 <=> P8309-4 on the PWB MAIN-C change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Front Tamper Home Sensor). (RRP 12.58) |
| 8 | Checking the MOTOR ASSY 2 (Front Tamper Motor) for operation <br> Execute [Output 13-11 Front Tamper Mot Low FRONT ON/OFF] and [Output 13-14 Front Tamper Mot Low REAR ON/OFF] in [Diagnosis] alternately. Does the MOTOR ASSY 2 (Front Tamper Motor) rotate, and does the tamper move front and rear? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 9. |
| 9 | Checking the HARNESS ASSY COMPILER connection Are P/J8363 and P/J8309 of the HARNESS ASSY COMPILER connected surely? | Go to step 11. | After reconnecting, go to step 10. |
| 10 | Execute [Test Print] in [Diagnosis] Does the error still occur? | Go to step 11. | End of work. |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 11 | Checking the HARNESS ASSY COMPILER for conductiv- <br> ity <br> Disconnect P/J8363 and P/J8309 of the HARNESS ASSY <br> COMPILER. <br> Check for conductivity at the following: <br> J8363-6 <=> J8309-10 <br> J8363-5 <=> J8309-11 <br> J8363-4 <=> J8309-12 <br> J8363-3 <=> J8309-13 <br> J8363-2 <=> Non connection <br> J8363-1 <=> J8309-14 | Go to step 12. | HARNESS ASSY <br> COMPILER. |
| 12 | Checking +24 VDC power supply to the MOTOR ASSY 2 <br> (Front Tamper Motor) <br> Is the voltage across J8309-11 <=> FRAME CHASSIS on <br> the PWB MAIN-C +24 VDC? | Go to step 13. | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) |
|  | Checking after replacing the MOTOR ASSY 2 (Front <br> Tamper Motor) | Replace the <br> Replace the MOTOR ASSY 2 (Front Tamper Motor). <br> (RRP 12.60) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | PWB MAIN-C. <br> (RRP 12.98) |
| End of work. |  |  |  |

## H5-24 Rear Tamper Home Sensor Off Fail

| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY ASSY-COMPILER (PL 12.10.1) <br> SENSOR (PL 12.10.2) <br> HARNESS ASSY COMPILER (PL 12.10.8) <br> PWB MAIN-C (PL 12.14.5) <br> MOTOR ASSY (PL 12.10.7) |  |  |
| 1 | Checking the Tamper mechanism for operation Does the tamper mechanism operate smoothly? Check this item by moving it with your fingers. | Go to step 2. | Replace the TRAY ASSYCOMPILER. (RRP 12.57) |
| 2 | Checking the SENSOR (Rear Tamper Home Sensor) for operation <br> Execute [Input 13-40 Rear Tamper Home SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Go to step 8. | Go to step 3. |
| 3 | Checking the HARNESS ASSY COMPILER connection Are P/J8361 and P/J8309 of the HARNESS ASSY COMPILER connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |


| $\begin{aligned} & \text { Ste } \\ & \text { p } \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 5 | Checking the HARNESS ASSY COMPILER for conductivity <br> Disconnect P/J8361 of the HARNESS ASSY COMPILER, and P/J8309 on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \mathrm{J} 8361-3 \text { <=> J8309-7 } \\ & \mathrm{J} 8361-2 \text { <=> J8309-8 } \\ & \mathrm{J} 8361-1 \text { <=> J8309-9 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY COMPILER. |
| 6 | Checking +5 VDC power supply to the SENSOR (Rear Tamper Home Sensor) Is the voltage across J8309-9 <=> J8309-7 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |
| 7 | Checking the SENSOR (Rear Tamper Home Sensor) for operation <br> Does the voltage across P8309-8 <=> P8309-7 on the PWB MAIN-C change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Rear Tamper Home Sensor). (RRP 12.58) |
| 8 | Checking the MOTOR ASSY (Rear Tamper Motor) for operation <br> Execute [Output 13-17 Rear Tamper Mot Low FRONT ON/OFF] and [Output 13-20 Rear Tamper Mot Low REAR ON/OFF] in [Diagnosis] alternately. <br> Does the MOTOR ASSY (Rear Tamper Motor) rotate, and does the tamper move front and rear? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 9. |
| 9 | Checking the HARNESS ASSY COMPILER connection Are P/J8362 and P/J8309 of the HARNESS ASSY COMPILER connected surely? | Go to step 11. | After reconnecting, go to step 10 . |
| 10 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 11. | End of work. |
| 11 | Checking the HARNESS ASSY COMPILER for conductivity <br> Disconnect P/J8362 and P/J8309 of the HARNESS ASSY COMPILER. <br> Check for conductivity at the following: <br> J8362-6 <=> J8309-15 <br> J8362-5 <=> J8309-16 <br> J8362-4 <=> J8309-17 <br> J8362-3 <=> J8309-18 <br> J8362-2 <=> Non connection <br> J8362-1 <=> J8309-19 | Go to step 12. | Replace the HARNESSASSY COMPILER. |
| 12 | Checking +24 VDC power supply to the MOTOR ASSY (Rear Tamper Motor) <br> Is the voltage across J8309-16 <=> FRAME CHASSIS on the PWB MAIN-C +24 VDC? | Go to step 13. | Replace the PWB MAIN-C. (RRP 12.98) |
| 13 | Checking after replacing the MOTOR ASSY (Rear <br> Tamper Motor) <br> Replace the MOTOR ASSY (Rear Tamper Motor). (RRP 12.61) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |

H5-31 Puncher Sensor On Fail

| $\begin{aligned} & \text { Ste } \\ & \text { p } \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (PL 12.7.15) <br> HARNESS ASSY PUNCH UNIT (PL 12.7.2) <br> HARNESS ASSY PUNCH SENSOR (PL 12.15.9) <br> PWB MAIN-C (PL 12.14.5) <br> MOTOR ASSY (PL 12.7.12) <br> HARNESS ASSY PUNCH DRIVE (PL 12.15.8) |  |  |
| 1 | Checking the Puncher for operation Does the puncher move smoothly? Check this item by moving it with your fingers. | Go to step 2. | Remove obstacles. |
| 2 | Checking the SENSOR (Puncher Home Sensor) for operation <br> Execute [Input 13-34 Puncher Home SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Go to step 9. | Go to step 3. |
| 3 | Checking the HARNESS ASSY PUNCH UNIT and HARNESS ASSY PUNCH SENSOR connection Are P/J8348 and P/J8333 of the HARNESS ASSY PUNCH UNIT, and P/J8333 and P/J8307 of the HARNESS ASSY PUNCH SENSOR connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY PUNCH UNIT for conductivity <br> Disconnect P/J8348 and P/J8333 of the HARNESS ASSY PUNCH UNIT. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8348-3 <=> P8333-7 } \\ & \text { J8348-2 <=> P8333-8 } \end{aligned}$ J8348-1 <=> P8333-9 | Go to step 6. | Replace the HARNESSASSY PUNCH UNIT. |
| 6 | Checking the HARNESS ASSY PUNCH SENSOR for conductivity <br> Disconnect P/J8333 and P/J8307 of the HARNESS ASSY PUNCH SENSOR. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8333-7 <=> J8307-B6 } \\ & \text { J8333-8 <=> J8307-B5 } \\ & \text { J8333-9 <=> J8307-B4 } \end{aligned}$ | Go to step 7. | Replace the HARNESSASSY PUNCH SENSOR. |
| 7 | Checking +5 VDC power supply to the SENSOR (Puncher Home Sensor) <br> Is the voltage across J8307-B6 <=> J8307-B5 on the PWB MAIN-C +5 VDC? | Go to step 8. | Replace the PWB MAIN-C. (RRP 12.98) |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 8 | Checking the SENSOR (Puncher Home Sensor) for oper- <br> ation <br> Does the voltage across P8307-B4 <=> P8307-B5 on the <br> PWB MAIN-C change, every time a piece of white paper <br> is inserted into the sensing area of the SENSOR? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | Replace the <br> SENSOR <br> (Puncher Home <br> Sensor). <br> (RRP 12.43) |
| 9 | Checking the MOTOR ASSY (Puncher Motor) for opera- <br> tion <br> Execute [Output 13-XX Puncher Mot XX Hole Home <br> Move] in [Diagnosis]. (Where XX varies depending on the <br> number of punch holes) (2 holes: 13-05, 3 Holes: 13-06 <br> and 4 Holes: 13-07) <br> Does the MOTOR ASSY (Puncher Motor) rotate? | Replace the PWB <br> MAIN-C. <br> (RRP 12.98) | Go to step 10. |

H5-32 Puncher Sensor Off Fail

| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (PL 12.7.15) <br> HARNESS ASSY PUNCH UNIT (PL 12.7.2) <br> HARNESS ASSY PUNCH SENSOR (PL 12.15.9) <br> PWB MAIN-C (PL 12.14.5) <br> MOTOR ASSY (PL 12.7.12) <br> HARNESS ASSY PUNCH DRIVE (PL 12.15.8) |  |  |
| 1 | Checking the Puncher for operation Does the puncher move smoothly? Check this item by moving it with your fingers. | Go to step 2. | Remove obstacles. |
| 2 | Checking the SENSOR (Puncher Home Sensor) for operation <br> Execute [Input 13-34 Puncher Home SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Go to step 9. | Go to step 3. |
| 3 | Checking the HARNESS ASSY PUNCH UNIT and HARNESS ASSY PUNCH SENSOR connection Are P/J8348 and P/J8333 of the HARNESS ASSY PUNCH UNIT, and P/J8333 and P/J8307 of the HARNESS ASSY PUNCH SENSOR connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY PUNCH UNIT for conductivity <br> Disconnect P/J8348 and P/J8333 of the HARNESS ASSY PUNCH UNIT. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8348-3 <=> P8333-7 } \\ & \text { J8348-2 <=> P8333-8 } \\ & \text { J8348-1 <=> P8333-9 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY PUNCH UNIT. |
| 6 | Checking the HARNESS ASSY PUNCH SENSOR for conductivity <br> Disconnect P/J8333 and P/J8307 of the HARNESS ASSY PUNCH SENSOR. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8333-7 <=> J8307-B6 } \\ & \text { J8333-8 <=> J8307-B5 } \\ & \text { J8333-9 <=> J8307-B4 } \end{aligned}$ | Go to step 7. | Replace the HARNESSASSY PUNCH SENSOR. |
| 7 | Checking +5 VDC power supply to the SENSOR (Puncher Home Sensor) <br> Is the voltage across J8307-B6 <=> J8307-B5 on the PWB MAIN-C +5 VDC? | Go to step 8. | Replace the PWB MAIN-C. (RRP 12.98) |


| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 8 | Checking the SENSOR (Puncher Home Sensor) for oper- <br> ation <br> Does the voltage across P8307-B4 <=> P8307-B on the <br> PWB MAIN-C change, every time a piece of white paper is <br> inserted into the sensing area of the SENSOR? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | Replace the <br> SENSOR <br> (Puncher Home <br> Sensor). <br> (RRP 12.43) |
|  | Checking the MOTOR ASSY (Puncher Motor) for opera- <br> tion <br> Execute [Output 13-XX Puncher Mot XX Hole Home <br> Move] in [Diagnosis]. (Where XX varies depending on the <br> number of punch holes) (2 holes: 13-05, 3 Holes: 13-06 <br> and 4 Holes: 13-07) <br> Does the MOTOR ASSY (Puncher Motor) rotate? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | Go to step 10. |

H5-33 Puncher Move Home Sensor On Fail

| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (PL 12.7.17) <br> HARNESS ASSY PUNCH SENSOR (PL 12.15.9) <br> PWB MAIN-C (PL 12.14.5) <br> BRACKET ASSY-MOTOR, PUNCH (PL 12.7.4) <br> HARNESS ASSY PUNCH DRIVE (PL 12.15.8) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the Puncher for operation Does the puncher move front and rear smoothly? Check this item by moving it with your fingers. | Go to step 2. | Remove obstacles. |
| 2 | Checking the SENSOR (Puncher Move Home Sensor) for operation <br> Execute [Input 13-33 Puncher Move Home SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Go to step 8. | Go to step 3. |
| 3 | Checking the HARNESS ASSY PUNCH SENSORE connection <br> Are P/J8352 and P/J8307 of the HARNESS ASSY PUNCH SENSOR connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY PUNCH SENSOR for conductivity <br> Disconnect P/J8352 and P/J8307 of the HARNESS ASSY PUNCH SENSOR. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8352-3 <=> J8307-A6 } \\ & \text { J8352-2 <=> J8307-A5 } \\ & \text { J8352-1 <=> J8307-A4 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY PUNCH SENSOR. |
| 6 | Checking +5 VDC power supply to the SENSOR (Puncher Move Home Sensor) Is the voltage across J8307-A4 <=> J8307-A6 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |
| 7 | Checking the SENSOR (Puncher Move Home Sensor) for operation <br> Does the voltage across P8307-A5 <=> P8307-A6 on the PWB MAIN-C change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Puncher Move Home Sensor). (RRP 12.44) |
| 8 | Checking the Bracket Assembly-Motor, Punch (Puncher Move Motor) for operation <br> Execute [Output 13-01 Puncher Move Motor Low Front ON/OFF] and [Output 13-03 Puncher Move Motor Low Rear ON/OFF] in [Diagnosis]. <br> Does the Bracket Assembly-Motor, Punch (Puncher Move Motor) rotate, and does the Holder-Frame Assembly move front and rear? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 9. |


| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 9 | Checking the HARNESS ASSY PUNCH DRIVE connec- <br> tion <br> Are P/J8344 and P/J8306 of the HARNESS ASSY <br> PUNCH DRIVE connected surely? | Go to step 11. | After reconnect- <br> ing, go to step 10. |
| 10 | Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 11. | End of work. |
| 11 | Checking the HARNESS ASSY PUNCH DRIVE for con- <br> ductivity <br> Disconnect P/J8344 and P/J8306 of the HARNESS ASSY <br> PUNCH DRIVE. <br> Check for conductivity at the following: <br> J8344-1 <=> J8306-7 <br> J8344-2 <=> J8306-3 <br> J8344-3 <=> J8306-6 <br> J8344-4 <=> J8306-5 <br> J8344-5 <=> J8306-2 <br> J8344-6 <=> J8306-1 | Go to step 12. | HARNESS ASSY <br> PUNCH DRIVE. |
|  | Checking after replacing the Bracket Assembly-Motor, <br> Punch (Puncher Move Motor) <br> Replace the Bracket Assembly-Motor, Punch (Puncher <br> Move Motor). (RRP 12.37) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 13. | End of work. |
| 13 | Checking after replacing the PWB MAIN-C <br> Replace the PWB MAIN-C. (RRP 12.98) <br> Does the error still occur when the power is turned ON? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | End of work. |

## H5-34 Puncher Move Home Sensor OFF Fail

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (PL 12.7.17) <br> HARNESS ASSY PUNCH SENSOR (PL 12.15.9) <br> PWB MAIN-C (PL 12.14.5) <br> Bracket Assembly-Motor, Punch (PL 12.7.4) <br> HARNESS ASSY PUNCH DRIVE (PL 12.15.8) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | Remove obsta- <br> cles. |
| 1 | Checking the Puncher for operation <br> Does the puncher move front and rear smoothly? <br> Check this item by moving it with your fingers. | Go to step 8. | Go to step 3. |
| 2 | Checking the SENSOR (Puncher Move Home Sensor) for <br> operation <br> Execute [Input 13-33 Puncher Move Home SENSOR] in <br> [Diagnosis]. <br> Does the display on the screen change, every time a piece <br> of white paper is inserted into the sensing area of the <br> SENSOR? |  |  |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 3 | Checking the HARNESS ASSY PUNCH SENSOR connection <br> Are P/J8352 and P/J8307 of the HARNESS ASSY PUNCH SENSOR connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY PUNCH SENSOR for conductivity <br> Disconnect P/J8352 and P/J8307 of the HARNESS ASSY PUNCH SENSOR. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8352-3 <=> J8307-A6 } \\ & \text { J8352-2 <=> J8307-A5 } \\ & \text { J8352-1 <=> J8307-A4 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY PUNCH SENSOR. |
| 6 | Checking +5 VDC power supply to the SENSOR (Puncher Move Home Sensor) Is the voltage across J8307-A4 <=> J8307-A6 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |
| 7 | Checking the SENSOR (Puncher Move Home Sensor) for operation <br> Does the voltage across P8307-A5 <=> P8307-A6 on the PWB MAIN-C change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Puncher Move Home Sensor). (RRP 12.44) |
| 8 | Checking the Bracket Assembly-Motor, Punch (Puncher Move Motor) for operation <br> Execute [Output 13-01 Puncher Move Motor Low Front ON/OFF] and [Output 13-03 Puncher Move Motor Low Rear ON/OFF] in [Diagnosis]. <br> Does the Bracket Assembly-Motor, Punch (Puncher Move Motor) rotate, and does the Holder-Frame Assembly move front and rear? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 9. |
| 9 | Checking the HARNESS ASSY PUNCH DRIVE connection <br> Are P/J8352 and P/J8306 of the HARNESS ASSY PUNCH DRIVE connected surely? | Go to step 11. | After reconnecting, go to step 10 . |
| 10 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 11. | End of work. |
| 11 | Checking the HARNESS ASSY PUNCH DRIVE for conductivity <br> Disconnect P/J8344 and P/J8306 of the HARNESS ASSY PUNCH DRIVE. <br> Check for conductivity at the following: <br> J8344-1 <=> J8306-7 <br> J8344-2 <=> J8306-3 <br> J8344-3 <=> J8306-6 <br> J8344-4 <=> J8306-5 <br> J8344-5 <=> J8306-2 <br> J8344-6 <=> J8306-1 | Go to step 12. | Replace the HARNESSASSY PUNCH DRIVE. |


| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 12 | Checking after replacing the Bracket Assembly-Motor, <br> Punch (Puncher Move Motor) <br> Replace the Bracket Assembly-Motor, Punch (Puncher <br> Move Motor). (RRP 12.37) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 13. | End of work. |
| 13 | Checking after replacing the PWB MAIN-C <br> Replace the PWB MAIN-C. (RRP 12.98) <br> Does the error still occur when the power is turned ON? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | End of work. |

## H5-81 Eject Clamp Home Sensor On Fail

| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (PL 12.9.13) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> MOTOR ASSY-DC (PL 12.9.11) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) |  |  |
| 1 | Checking the Eject clamp for operation Does the eject clamp mechanism move smoothly? Check this item by moving it with your fingers. | Go to step 2. | Remove obstacles. |
| 2 | Checking the SENSOR (Eject Clamp Home Sensor) for operation <br> Execute [Input 12-38 Eject Clamp Home SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Go to step 8. | Go to step 3. |
| 3 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8324 and P/J8302B of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8324 and P/J8302B of the HARNESS <br> ASSY MAIN SENSOR. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8324-3 <=> P8302B-6 } \\ & \text { J8324-2 <=> P8302B-7 } \\ & \text { J8324-1 <=> P8302B-8 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY MAIN SENSOR. |
| 6 | Checking +5 VDC power supply to the SENSOR (Eject Clamp Home Sensor) Is the voltage across J8302B-8 <=> J8302B-6 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |


| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 7 | Checking the SENSOR (Eject Clamp Home Sensor) for operation <br> Does the voltage across P8302B-7 <=> P8302B-6 on the PWB MAIN-C change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Eject Clamp Home Sensor). (RRP 12.55) |
| 8 | Checking the MOTOR ASSY-DC (Eject Clamp Motor) for operation <br> Execute [Output 12-18 Eject Clamp Motor UP ON/OFF] and [Output 12-19 Eject Clamp Motor DOWN ON/OFF] in [Diagnosis]. <br> Does the MOTOR ASSY-DC (Eject Clamp Motor) rotate normally? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 9. |
| 9 | Checking the HARNESS ASSY MAIN DRIVE connection Are P/J8339 and P/J8304B of the HARNESS ASSY MAIN DRIVE connected surely? | Go to step 11. | After reconnecting, go to step 10. |
| 10 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 11. | End of work. |
| 11 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8339 and P/J8304 of the HARNESS ASSY MAIN DRIVE. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8339-1 <=> J8304-33 } \\ & \text { J8339-2 <=> J8304-31 } \end{aligned}$ | Go to step 12. | Replace the HARNESSASSY MAIN DRIVE. |
| 12 | Checking after replacing the MOTOR ASSY-DC (Eject Clamp Motor) <br> Replace the MOTOR ASSY-DC (Eject Clamp Motor). <br> (RRP 12.54) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |

## H5-82 Eject Clamp Home Sensor Off Fail

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (PL 12.9.13) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> MOTOR ASSY-DC (PL 12.9.11) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) |  |  |
| 1 | Checking the Eject clamp block for operation <br> Does the eject clamp mechanism move smoothly? <br> Check this item by moving it with your fingers. | Go to step 2. | Remove obsta- <br> cles. |


| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 2 | Checking the SENSOR (Eject Clamp Home Sensor) for <br> operation <br> Execute [Input 12-38 Eject Clamp Home SENSOR] in <br> [Diagnosis]. <br> Does the display on the screen change, every time a <br> piece of white paper is inserted into the sensing area of <br> the SENSOR? | Go to step 8. | Go to step 3. |
| 3 | Checking the HARNESS ASSY MAIN SENSOR connec- <br> tion <br> Are P/J8324 and P/J8302B of the HARNESS ASSY MAIN <br> SENSOR connected surely? | Go to step 5. | After reconnect- <br> ing, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Checking the HARNESS ASSY MAIN SENSOR for con- <br> ductivity <br> Disconnect P/J8324 and P/J8302B of the HARNESS <br> ASSY MAIN SENSOR. <br> Check for conductivity at the following: <br> J8324-3 <=> P8302B-6 <br> J8324-2 <=> P8302B-7 <br> J8324-1 <=> P8302B-8 | Go to step 5. |


| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 12 | Checking after replacing the MOTOR ASSY-DC (Eject <br> Clamp Motor) <br> Replace the MOTOR ASSY-DC (Eject Clamp Motor). <br> (RRP 12.54) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | End of work. |

## H5-83 Set Clamp Home Sensor On Fail

| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (PL 12.10.18) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> BRACKET ASSY-EJECT (PL 12.10.17) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) <br> CLUTCH z34 (PL 12.10.15) | Go to step 2. | Remove obsta- <br> cles. |
| 1 | Checking the Eject clamp block for operation <br> Does the eject clamp mechanism move smoothly? <br> Check this item by moving it with your fingers. | Go to step 8. <br> Checking the SENSOR (Set Clamp Home Sensor) for <br> Exeration [Input 12-39 Set Clamp Home SENSOR] in <br> [Diagnosis]. <br> Does the display on the screen change, every time a <br> piece of white paper is inserted into the sensing area of <br> the SENSOR? | Go to step 3. |
| 3 | Checking the HARNESS ASSY MAIN SENSOR connec- <br> tion <br> Are P/J8325 and P/J8302B of the HARNESS ASSY MAIN <br> SENSOR connected surely? | Go to step 5. | After reconnect- <br> ing, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 5. | End of work. |
|  | Checking the HARNESS ASSY MAIN SENSOR for con- <br> ductivity <br> Disconnect P/J8325 and P/J8302B of the HARNESS <br> ASSY MAIN SENSORT. <br> Check for conductivity at the following: <br> J8325-3 <=> P8302B-9 <br> J8325-2 <=> P8302B-10 <br> J8325-1 <=> P8302B-11 | Checking +5 VDC power supply to the SENSOR (Set <br> Clamp Home Sensor) <br> Is the voltage across J8302B-11 <=> J8302B-94 on the <br> PWB MAIN-C +5 VDC? | Go to step 7. |


| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 7 | Checking the SENSOR (Set Clamp Home Sensor) for <br> operation <br> Does the voltage across P8302B-10 <=> P8302B-9 on the <br> PWB MAIN-C change, every time a piece of white paper <br> is inserted into the sensing area of the SENSOR? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | Replace the <br> SENSOR (Set <br> Clamp Home <br> Sensor). <br> (RRP 12.66) |
| 8 | Checking the BRACKET ASSY-EJECT (Eject Motor) for <br> operation <br> Execute [Output 12-20 Eject Motor Low FORWARD ON/ <br> OFF] and [Output 12-22 Eject Motor Low REVERSE ON/ <br> OFF] in [Diagnosis] alternately. <br> Does the BRACKET ASSY-EJECT (Eject Motor) rotate <br> normally in Forward/Reverse directions alternately? | Go to step 15. | Go to step 9. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 16 | Checking the HARNESS ASSY MAIN DRIVE connection Are P/J8338 and P/J8304 of the HARNESS ASSY MAIN DRIVE connected surely? | Go to step 18. | After reconnecting, go to step 17. |
| 17 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 18. | End of work. |
| 18 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8338 and P/J8304 of the HARNESS ASSY MAIN DRIVE. <br> Check for conductivity at the following: <br> J8338B-1 <=> J8304-20 <br> J8338B-2 <=> J8304-22 | Go to step 19. | Replace the HARNESSASSY MAIN DRIVE. |
| 19 | Checking +24 VDC power supply to the CLUTCH Z34 (Set Clamp Clutch) <br> Is the voltage across J8304-22 <=> FRAME CHASSIS on the PWB MAIN-C +24 VDC? | Go to step 20. | Replace the PWB MAIN-C. (RRP 12.98) |
| 20 | Checking after replacing the CLUTCH Z34 (Set Clamp Clutch) <br> Replace the CLUTCH Z34 (Set Clamp Clutch). (RRP 12.64) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |

## H5-84 Set Clamp Home Sensor Off Fail

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (PL 12.10.18) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> BRACKET ASSY-EJECT (PL 12.10.17) <br> HARNESS ASSY MAIN DRIVE (PL 12.15.2) <br> CLUTCH Z34 (PL 12.10.15) <br> PWB MAIN-C (PL 12.14.5) | Go to step 2. | Remove obsta- <br> cles. |
| 1 | Checking the Eject clamp block for operation <br> Does the eject clamp mechanism move smoothly? <br> Check this item by moving it with your fingers. | Go to step 8. | Go to step 3. |
| 2 | Checking the SENSOR (Set Clamp Home Sensor) for <br> operation <br> Execute [Input 12-39 Set Clamp Home SENSOR] in <br> [Diagnosis]. <br> Does the display on the screen change, every time a <br> piece of white paper is inserted into the sensing area of <br> the SENSOR? | Go to step 5. | After reconnect- |
| ing, go to step 14. |  |  |  |
| 3 | Checking the HARNESS ASSY MAIN SENSOR connec- <br> tion <br> Are P/J8325 and P/J8302B of the HARNESS ASSY MAIN <br> SENSOR connected surely? | ( |  |


| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8325 and P/J8302B of the HARNESS ASSY MAIN SENSORT. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8325-3 <=> P8302B-9 } \\ & \text { J8325-2 <=> P8302B-10 } \\ & \text { J8325-1 <=> P8302B-11 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY MAIN SENSOR. |
| 6 | Checking +5 VDC power supply to the SENSOR (Set Clamp Home Sensor) Is the voltage across J8302B-11 <=> J8302B-9 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |
| 7 | Checking the SENSOR (Set Clamp Home Sensor) for operation <br> Does the voltage across P8302B-10 <=> P8302B-9 on the PWB MAIN-C change, every time a piece of white paper is inserted into the sensing area of the SENSOR? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Set Clamp Home Sensor). (RRP 12.66) |
| 8 | Checking the BRACKET ASSY-EJECT (Eject Motor) for operation <br> Execute [Output 12-20 Eject Motor Low FORWARD ON/ OFF] and [Output 12-22 Eject Motor Low REVERSE ON/ OFF] in [Diagnosis] alternately. <br> Does the BRACKET ASSY-EJECT (Eject Motor) rotate normally in Forward/Reverse directions alternately? | Go to step 15. | Go to step 9. |
| 9 | Checking the HARNESS ASSY MAIN DRIVE connection Are P/J8336 and P/J8304 of the HARNESS ASSY MAIN DRIVE connected surely? | Go to step 11. | After reconnecting, go to step 10. |
| 10 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 11. | End of work. |
| 11 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8336 and P/J8304 of the HARNESS ASSY MAIN DRIVE. <br> Check for conductivity at the following: <br> J8336-1 <=> J8304-15 <br> J8336-2 <=> J8304-12 <br> J8336-3 <=> J8304-17 <br> J8336-4 <=> J8304-19 <br> J8336-5 <=> J8304-14 <br> J8336-6 <=> J8304-21 | Go to step 12. | Replace the HARNESSASSY MAIN DRIVE. |
| 12 | Checking the resistance of the MOTOR ASSY Are there any resistances without disconnection across P8336-2/5(COM) and P8336-1/3/4/6 of the MOTOR ASSY? | Go to step 13. | Replace the BRACKET ASSY-EJECT. (RRP 12.65) |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 13 | Checking +24 VDC power supply to the MOTOR ASSY Are the voltages across J8304-12 <=> FRAME CHASSIS, and J8304-14 <=> FRAME CHASSIS on the PWB MAINC, +24 VDC? | Go to step 14. | Replace the PWB MAIN-C. (RRP 12.98) |
| 14 | Checking after replacing the BRACKET ASSY-EJECT <br> (Eject Motor) <br> Replace the BRACKET ASSY-EJECT (Eject Motor). <br> (RRP 12.65) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |
| 15 | Checking the CLUTCH Z34 (Set Clamp Clutch) for operation <br> Execute [Output 12-16 Set Clamp CLUTCH ON/OFF] in [Diagnosis]. <br> Does the CLUTCH Z34 (Set Clam Clutch) operate? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 16. |
| 16 | Checking the HARNESS ASSY MAIN DRIVE connection Are P/J8338 and P/J8304 of the HARNESS ASSY MAIN DRIVE connected surely? | Go to step 18. | After reconnecting, go to step 17. |
| 17 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 18. | End of work. |
| 18 | Checking the HARNESS ASSY MAIN DRIVE for conductivity <br> Disconnect P/J8338 and P/J8304 of the HARNESS ASSY MAIN DRIVE. <br> Check for conductivity at the following: J8338B-1 <=> J8304-20 J8338B-2 <=> J8304-22 | Go to step 19. | Replace the HARNESSASSY MAIN DRIVE. |
| 19 | Checking +24 VDC power supply to the CLUTCH Z34 (Set Clamp Clutch) <br> Is the voltage across J8304-22 <=> FRAME CHASSIS on the PWB MAIN-C + 24 VDC? | Go to step 20. | Replace the PWB MAIN-C. (RRP 12.98) |
| 20 | Checking after replacing the CLUTCH Z34 (Set Clamp Clutch) <br> Replace the CLUTCH Z34 (Set Clamp Clutch). (RRP 12.64) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |

H5-86 Side Registration Sensor Off Fail

| Ste | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> Bracket Assembly-Motor, Punch (PL 12.7.4) <br> HARNESS ASSY PUNCH DRIVE (PL 12.15.8) <br> PWB MAIN-C (PL 12.14.5) <br> PWBA MCU F (PL 8.1.5) <br> SENSOR (PL 12.7.8) <br> HARNESS ASSY PUNCH SENSOR (PL 12.15.9) <br> HARNESS ASSY PUNCH UNIT (PL 12.7.2) |  |  |
| 1 | Checking the Puncher for operation <br> Does the puncher move front and rear smoothly? <br> Check this item by moving it with your fingers. | Go to step 2. | Remove obstacles. |
| 2 | Checking the Bracket Assembly-Motor, Punch (Puncher Move Motor) for operation <br> Execute [Output 13-01 Puncher Move Motor Low Front ON/OFF] and [Output 13-03 Puncher Move Motor Low Rear ON/OFF] in [Diagnosis]. <br> Does the Bracket Assembly-Motor, Punch (Puncher Move Motor) rotate, and does the Holder-Frame Assembly move front and rear? | Go to step 8. | Go to step 3. |
| 3 | Checking the HARNESS ASSY PUNCH DRIVE connection <br> Are P/J8344 and P/J8306 of the HARNESS ASSY PUNCH DRIVE connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY PUNCH DRIVE for conductivity <br> Disconnect P/J8344 and P/J8306 of the HARNESS ASSY PUNCH DRIVE. <br> Check for conductivity at the following: <br> J8344-1 <=> J8306-7 <br> J8344-2 <=> J8306-3 <br> J8344-3 <=> J8306-6 <br> J8344-4 <=> J8306-5 <br> J8344-5 <=> J8306-2 <br> J8344-6 <=> J8306-1 | Go to step 6. | Replace the HARNESSASSY PUNCH DRIVE. |
| 6 | Checking after replacing the Bracket Assembly-Motor, <br> Punch (Puncher Move Motor) <br> Replace the Bracket Assembly-Motor, Punch (Puncher <br> Move Motor). (RRP 12.37) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 7. | End of work. |
| 7 | Checking after replacing the PWB MAIN-C <br> Replace the PWB MAIN-C. (RRP 12.98) <br> Does the error still occur when the power is turned ON? | Replace the PWB A MAIN F. | End of work. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 8 | Checking the SENSOR (Side Registration Sensor 1) for operation <br> Execute [Input 12-36 Side Registration SENSOR 1] in [Diagnosis]. <br> Does the display on the screen change, every time a piece of white paper is placed over the sensing area of the SENSOR (Side Registration Sensor 1)? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 9. |
| 9 | Checking the SENSOR (Side Registration Sensor 2) for operation <br> Execute [Input 12-37 Side Registration SENSOR 2] in [Diagnosis]. <br> Does the display on the screen change, every time a piece of white paper is placed over the sensing area of the SENSOR (Side Registration Sensor 2)? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 10. |
| 10 | Checking the HARNESS ASSY PUNCH SENSOR and HARNESS ASSY PUNCH UNIT connection Are P/J8307, P/J8333 and P/J8350 (for Side Registration Sensor 1), and P/L8351 (for Side Registration Sensor 2) of the HARNESS ASSY PUNCH SENSOR and HARNESS ASSY PUNCH UNIT connected surely? | Go to step 12. | After reconnecting, go to step 11. |
| 11 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 12. | End of work. |
| 12 | Checking the HARNESS ASSY PUNCH SENSOR for conductivity <br> Disconnect P/J8307 and P/J8333 of the HARNESS ASSY PUNCH SENSOR. <br> Is there conductivity on each wire between J 8307 <=> J8333? | Go to step 13. | Replace the HARNESS ASSY PUNCH SENSOR. |
| 13 | Checking the HARNESS ASSY PUNCH UNIT for conductivity <br> Disconnect P/J8333, P/J8350 (Side Registration Sensor 1), and P/J8351 (Side Registration Sensor 2) of the HARNESS ASSY PUNCH UNIT. <br> Check for conductivity at the following: <br> P8333-13 <=> J8350-3 <br> P8333-14 <=> J8350-2 <br> P8333-15 <=> J8350-1 <br> P8333-16 <=> J8351-3 <br> P8333-17 <=> J8351-2 <br> P8333-18 <=> J8351-1 | Go to step 14. | Replace the HARNESSASSY PUNCH UNIT. |
| 14 | Checking after replacing the SENSOR (Side Registration Sensor 1) <br> Replace the SENSOR (Side Registration Sensor 1). (RRP 12.38) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 15. | End of work. |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 15 | Checking after replacing the SENSOR (Side Registration <br> Sensor 2) <br> Replace the SENSOR (Side Registration Sensor 2). (RRP <br> 12.38) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 16. | End of work. |
| 16 | Checking after replacing the PWB MAIN-C <br> Replace the PWB MAIN-C. (RRP 12.98) <br> Does the error still occur when the power is turned ON? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | End of work. |

## H5-91 Stapler Fail

| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> STAPLER ASSY (PL 12.8.2) <br> HARNESS ASSY STAPLE (PL 12.8.7) <br> PWB MAIN-C (PL 12.14.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the STAPLER ASSY (PL 12.8.2) for operation Execute [Output 13-29 Stapler Motor Forward ON/OFF] and [Output 13-30 Stapler Motor Reverse ON/OFF] in [Diagnosis]. <br> Does the MOTOR in the STAPLER ASSY (PL 12.8.2) rotate normally? | Go to step 5. | Go to step 2. |
| 2 | Checking the HARNESS ASSY STAPLE connection Are P/J8357 and P/J8308 of the HARNESS ASSY STAPLE connected surely? | Go to step 4. | After reconnecting, go to step 3. |
| 3 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 4. | End of work. |
| 4 | Checking the HARNESS ASSY STAPLE for conductivity Disconnect P/J8357 and P/J8308 of the HARNESS ASSY STAPLE. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8357-1 <=> J8308-10 } \\ & \text { J8357-2 <=> J8308-9 } \\ & \text { J8357-3 <=> J8308-8 } \\ & \text { J8357-4 <=> J8308-7 } \end{aligned}$ | Go to step 9. | Replace the HARNESSASSY STAPLE. |
| 5 | Checking the Staple Home Sensor for operation Execute [Input 13-45 Stapler Home SENSOR] in [Diagnosis], and then execute [Output 13-29 Staple Motor FORWARD ON/OFF] and [Output 13-30 Staple Motor REVERSE ON/OFF] in [Diagnosis] alternately. Does the display on the screen change, every time the Diagnosis is executed? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 6. |
| 6 | Checking the HARNESS ASSY STAPLE connection Are P/J8358 and P/J8308 of the HARNESS ASSY STAPLE connected surely? | Go to step 8. | After reconnecting, go to step 7. |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 7 | Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 8. | End of work. |
| 8 | Checking the HARNESS ASSY STAPLE for conductivity <br> Disconnect P/J8358 and P/J8308 of the HARNESS ASSY <br> STAPLE. <br> Check for conductivity at the following: <br> J8358-1 <=> J8308-15 <br> J8358-2<=> J8308-14 <br> J8358-3<=> J8308-13 <br> J8358-4 <=> J8308-12 <br> J8358-5 <=> J8308-11 | Go to step 9. | HARNESS ASSY <br> STAPLE. |
| 9 | Checking after replacing the STAPLER ASSY (PL 12.8.2) <br> Replace the STAPLER ASSY (PL 12.8.2). (RRP 12.47) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 10. | End of work. |
| 10 | Checking after replacing the PWB MAIN-C <br> Replace the PWB MAIN-C. (RRP 12.98) <br> Does the error still occur when the power is turned ON? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | End of work. |

## H5-95 Stapler Move Position Sensor On Fail

| $\begin{aligned} & \text { Ste } \\ & \text { p } \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> CARRIAGE ASSY LOWER, STAPLER (PL 12.8.9) <br> HARNESS ASSY STAPLE (PL 12.8.7) <br> PWB MAIN-C (PL 12.14.5) <br> SENSOR (PL 12.8.5) |  |  |
| 1 | Checking the Stapler for operation Does the Stapler move smoothly? Check this item by moving it with your fingers. | Go to step 2. | Remove obstacles. |
| 2 | Checking the CARRIAGE ASSY LOWER, STAPLER (PL 12.8.9) (Stapler Move Motor) for operation <br> Execute [Output 13-23 Stapler Move Mot Low FRONT ON/OFF] and [Output 13-26 Stapler Move Mot Low REAR ON/OFF] in [Diagnosis]. <br> Does the CARRIAGE ASSY LOWER, STAPLER (PL 12.8.9) (Stapler Move Motor) rotate normally? | Go to step 7. | Go to step 3. |
| 3 | Checking the HARNESS ASSY STAPLE connection Are P/J8358 and P/J8308 of the HARNESS ASSY STAPLE connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 5 | Checking the HARNESS ASSY STAPLE for conductivity Disconnect P/J8358 and P/J8308 of the HARNESS ASSY STAPLE. <br> Check for conductivity at the following: <br> J8358-1 <=> J8308-3 <br> J8358-2 <=> J8308-6 <br> J8358-3 <=> J8308-5 <br> J8358-4 <=> J8308-1 <br> J8358-5 <=> J8308-4 <br> J8358-6 <=> J8308-2 | Go to step 6. | Replace the HARNESSASSY STAPLE. |
| 6 | Checking after replacing the CARRIAGE ASSY LOWER, STAPLER (PL 12.8.9) (Stapler Move Motor) Replace the CARRIAGE ASSY LOWER, STAPLER (PL 12.8.9) (Stapler Move Motor). (RRP 12.47) Execute [Test Print] in [Diagnosis]. Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |
| 7 | Checking the SENSOR (Stapler Move Home Position Sensor) for operation <br> Execute [Output 13-42 Staple Move Position SENSOR] in [Diagnosis], and then execute [Output 13-23 Stapler Move Mot Low FRONT ON/OFF] and [Output 13-26 Stapler Move Mot Low REAR ON/OFF] in [Diagnosis] alternately. Does the display on the screen change? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 8. |
| 8 | Checking the HARNESS ASSY STAPLE connection Are P/J8354 and P/J8308 of the HARNESS ASSY STAPLE connected surely? | Go to step 10. | After reconnecting, go to step 9 . |
| 9 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 10. | End of work. |
| 10 | Checking the HARNESS ASSY STAPLE for conductivity DisconnectP/J8354 and P/J8308 of the HARNESS ASSY STAPLE. <br> Check for conductivity at the following: <br> J8354-1 <=> P8308-18 <br> J8354-2 <=> P8308-17 <br> J8354-3 <=> P8308-16 | Go to step 11. | Replace the HARNESSASSY STAPLE. |
| 11 | Checking +5 VDC power supply to the SENSOR (Stapler Move Home Position Sensor) Is the voltage across J8308-18 <=> J8308-16 on the PWB MAIN-C +5 VDC? | Go to step 12. | Replace the PWB MAIN-C. (RRP 12.98) |
| 12 | Checking the SENSOR (Stapler Move Home Position Sensor) for operation <br> Does the voltage across J8308-17 <=> J8308-16 on the PWB MAIN-C change, every time the sensing area of the SENSOR is placed to the protrusion of the RAIL-UPPER (PL 12.8.10) by moving the stapler by hand. | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Stapler Move Home Position Sensor). (RRP 12.48) |

H5-96 Stapler Move Position Sensor OFF Fail

| Ste | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> CARRIAGE ASSY LOWER, STAPLER (PL 12.8.9) <br> HARNESS ASSY STAPLE (PL 12.8.7) <br> PWB MAIN-C (PL 12.14.5) <br> SENSOR (PL 12.8.5) |  |  |
| 1 | Checking the Stapler for operation Does the Stapler move smoothly? Check this item by moving it with your fingers. | Go to step 2. | Remove obstacles. |
| 2 | Checking the CARRIAGE ASSY LOWER, STAPLER (PL 12.8.9) (Stapler Move Motor) for operation <br> Execute [Output 13-23 Stapler Move Mot Low FRONT ON/OFF] and [Output 13-26 Stapler Move Mot Low REAR ON/OFF] in [Diagnosis]. <br> Does the CARRIAGE ASSY LOWER, STAPLER (PL 12.8.9) (Stapler Move Motor) rotate normally? | Go to step 7. | Go to step 3. |
| 3 | Checking the HARNESS ASSY STAPLE connection Are P/J8358 and P/J8308 of the HARNESS ASSY STAPLE connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY STAPLE for conductivity Disconnect P/J8358 and P/J8308 of the HARNESS ASSY STAPLE. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8358-1 <=> J8308-3 } \\ & \text { J8358-2 <=> J8308-6 } \\ & \text { J8358-3 <>> J8308-5 } \\ & \text { J8358-4 <=> J8308-1 } \\ & \text { J8358-5 <=> J8308-4 } \\ & \text { J8358-6 <=> J8308-2 } \end{aligned}$ | Go to step 6. | Replace the HARNESS ASSY STAPLE. |
| 6 | Checking after replacing the CARRIAGE ASSY LOWER, STAPLER (PL 12.8.9) (Stapler Move Motor) Replace the CARRIAGE ASSY LOWER, STAPLER (PL 12.8.9) (Stapler Move Motor). (RRP 12.47) Execute [Test Print] in [Diagnosis]. Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |
| 7 | Checking the SENSOR (Stapler Move Home Position <br> Sensor) for operation <br> Execute [Output 13-42 Staple Move Position SENSOR] in [Diagnosis], and then execute [Output 13-23 Stapler Move Mot Low FRONT ON/OFF] and [Output 13-26 Stapler Move Mot Low REAR ON/OFF] in [Diagnosis] alternately. Does the display on the screen change? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 8. |
| 8 | Checking the HARNESS ASSY STAPLE connection Are P/J8354 and P/J8308 of the HARNESS ASSY STAPLE connected surely? | Go to step 10. | After reconnecting, go to step 9 . |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 9 | Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 10. | End of work. |
| 10 | Checking the HARNESS ASSY STAPLE for conductivity <br> Disconnect P/J8354 and P/J8308 of the HARNESS ASSY <br> STAPLE. <br> Check for conductivity at the following: <br> J8354-1 <=> P8308-18 <br> J8354-2 <=> P8308-17 <br> J8354-3 <=> P8308-16 | Go to step 11. | HARNESS ASSY <br> STAPLE. |
| 11 | Replace the <br> Checking +5 VDC power supply to the SENSOR (Stapler <br> Move Home Position Sensor) <br> Is the voltage across J8308-18 <=> J8308-16 on the PWB <br> MAIN-C +5 VDC? | Go to step 12. | RWB MAIN-C. <br> (RRP 12.98) |
|  | Checking the SENSOR (Stapler Move Home Position <br> Sensor) for operation <br> Does the voltage across J8308-17 <=> J8308-16 on the <br> PWB MAIN-C change, every time the protrusion of the <br> RAIL-UPPER (PL 12.8.10) is inserted into the sensing <br> area of the SENSOR (Stapler Move Home Position Sen- <br> sor) by moving the Stapler by hand? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | Replace the <br> SENSOR (Sta- <br> pler Move Home <br> Position Sensor). <br> (RRP 12.48) |

## H5-4 Finisher NVM R/W error

| Ste | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: PWB MAIN-C (PL 12.14.5) PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Turn off/on several times. <br> Does the error still occur when the power is on? | Go to step 2. | End of work. |
| 2 | Checking data on the NVRAM (1) Is data on the NVRAM accessible? Check it using [NVM Edit] in Chapter 2, Diag. | Go to step 3. | Go to step 4. |
| 3 | Checking data on the NVRAM (2) Change NVRAM data to the correct setup value, and then turn the power ON again. Does the error still occur? | Go to step 4. | End of work. |
| 4 | Checking the PWB MAIN-C for connection Are P/J8300 and P416 of the PWB MAIN-C connected surely? | Go to step 5. | Connect P/J8300 and P416 surely. |
| 5 | Checking conductivity between the PWB MAIN-C and PWBA MCU F <br> Is there conductivity on each wire between P/J8300 <=> P416? | Go to step 6. | Fix open and short circuit. |
| 6 | Checking +24 VDC power supply to the PWB MAIN-C Is the voltage across J416-6 (+) <=> ground +24 VDC? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the PWBA MCU F (RRP 8.4) |

H5-7 MCU-Finisher comm. error

| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> PWB MAIN-C (PL 12.14.5) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | After reinstalling, <br> go to step 2. |
| 1 | Checking the IOT and Finisher installation <br> Is the Finisher installed to the printer correctly? | Go to step 3. | End of work. |
| 2 | Turn ON/OFF the power. <br> Does the error still occur when the power is on? | Checking the PWB MAIN-C for connection <br> Are P/J8300 and P416 of the PWB MAIN-C connected <br> surely? | Go to step 4. <br> Checking conductivity between the PWB MAIN-C and <br> PWBA MCU F <br> P416? |
| 5 | Conductivity on each wire between P/J8300 <=> <br> and P416 surely. |  |  |
| Checking +24 VDC power supply to the PWB MAIN-C <br> Is the voltage across J416-6 (+) <=> ground +24 VDC? | Replace the PWB <br> MAIN-C. (RRP <br> 12.98) | Replace the <br> PWBA MCU F <br> (RRP 8.4) |  |

## H5-8 Finisher type error

| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :--- | :--- |
|  | Possible causative parts: <br> PWB MAIN-C (PL 12.14.5) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | Reinstall the Fin- <br> isher |
| 1 | Checking the IOT and Finisher installation (1). Is the Fin- <br> isher installed to the printer correctly? | Reinstall the Fin- <br> isher for FIO <br> printer. |  |
| 2 | Checking the IOT and Finisher installation (2). Is the Fin- <br> isher for FIO printer installed? | Go to step 3. | Go to step 4. |
| 3 | Turn ON/OFF the power. <br> Does the error still occur when the power is on? | Checking the PWB MAIN-C for connection <br> Are P/J8300 and P416 of the PWB MAIN-C connected <br> surely? | Gonnect P/J8300 <br> and P416 surely. |
| 5 | Checking conductivity between the PWB MAIN-C and <br> PWBA MCU F <br> Is there conductivity on each wire between P/J8300 <=> <br> P416? | Go to step 6. | Fix open and <br> short circuit. |
| 6 | Checking +24 VDC power supply to the PWB MAIN-C <br> Is the voltage across J416-6 (+) <=> ground +24 VDC? | Replace the PWB <br> MAIN-C. (RRP <br> 12.98) | Replace the <br> PWBA MCU F <br> (RRP 8.4) |

Stacker Tray Full (No Mix): Finisher

| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (PL 12.6.17) <br> COVER ASSY SENSOR (PL 12.6.13) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> MOTOR ASSY DC (PL 12.6.26) |  |  |
| 1 | Checking the Stacker Tray for obstacles Are there any obstacles on the upper and lower parts of the Stacker Tray? | Remove the obstacles. | Go to step 2. |
| 2 | Checking the COVER ASSY SENSOR (PL 12.6.13) <br> (Stacker Height Sensor 1) for operation <br> Execute [Input 13-50 Stack Height SENSOR 1] in [Diagnosis]. <br> Does the display on the screen change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Go to step 8. | Go to step 3. |
| 3 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8331 and P/J8302B of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> DisconnectP/J8331 of the HARNESS ASSY MAIN SENSOR, and P/J8302B on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} \text { J8331-5 } & \text { => J8302B-1 } \\ \text { J8331-4 } & =>\text { J8302BB-2 } \\ \text { J8331-3 } & =>\text { J8302BB-3 } \\ \text { J8331-2 } & =>\text { J8302BB-4 } \\ \text { J8331-1 } & \text { => J8302B-5 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY MAIN SENSOR. |
| 6 | Checking +5 VDC power supply to the COVER ASSY SENSOR (Stacker Height Sensor 1) <br> Is the voltage across J8302B-3 <=> J8302B-1 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |
| 7 | Checking the COVER ASSY SENSOR (Stacker Height <br> Sensor 1) for operation <br> Does the voltage across P8302B-2 <=> P8302B-1 on the PWB MAIN-C change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the COVER ASSY SENSOR (Stacker Height Sensor 1). (RRP 12.30) |


| Ste | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 8 | Checking the COVER ASSY SENSOR (PL 12.6.13) <br> (Stacker Height Sensor 2) for operation <br> Execute [Input 13-51 Stack Height SENSOR 2] in [Diagnosis]. <br> Does the display on the screen change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Go to step 14. | Go to step 9. |
| 9 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8330 and P/J8302A of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 11. | After reconnecting, go to step 10. |
| 10 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 11. | End of work. |
| 11 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8330 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8330-5 <=> J8302A-16 } \\ & \text { J8330-4 <=> J8302A-17 } \\ & \text { J8330-3 <=> J8302A-18 } \\ & \text { J8330-2 <=> J8302A-19 } \\ & \text { J8330-1 }<\gg \text { J8302A-20 } \end{aligned}$ | Go to step 12. | Replace the HARNESSASSY MAIN SENSOR. |
| 12 | Checking +5 VDC power supply to the COVER ASSY SENSOR (Stacker Height Sensor 2) <br> Is the voltage across J8302A-18 <=> J8302A-16 on the PWB MAIN-C +5 VDC? | Go to step 13. | Replace the PWB MAIN-C (RRP 12.98) |
| 13 | Checking the COVER ASSY SENSOR (Stacker Height Sensor 2) for operation Does the voltage across P8302A-17 <=> P8302A-16 on the PWB MAIN-C change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the COVER ASSY SENSOR (Stacker Height Sensor 2). (RRP 12.31) |
| 14 | Checking the ENCODER (PL 12.6.23) of the SENSOR <br> (Stacker Encode Sensor) installation. <br> Is the ENCODER installed correctly? <br> Does it enter the detection point of the SENSOR? | Go to step 16. | After reinstalling, go to step 15. |
| 15 | Checking the SENSOR (Stacker Encode Sensor) for operation <br> Execute [Input 13-49 Stack Encoder SENSOR] in [Diagnosis]. <br> Does the screen display change when the BELT (PL 12.6.25) of the MOTOR ASSY-DC (PL 12.6.26) is moved by hand (when the ENCODER (PL 12.6.23) is rotated)? | Go to step 21. | Go to step 16. |
| 16 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8328 and P/J8302B of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 18. | After reconnecting, go to step 17. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 17 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 18. | End of work. |
| 18 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8328 of the HARNESS ASSY MAIN SENSOR, and P/J8302B on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8328-3 <=> J8302B-12 } \\ & \text { J8328-2 <=> J8302B-13 } \\ & \text { J8328-1 <=> J8302B-14 } \end{aligned}$ | Go to step 19. | Replace the HARNESSASSY MAIN SENSOR. |
| 19 | Checking +5 VDC power supply to the SENSOR (Stacker Encode Sensor) Is the voltage across J8302B-14 <=> J8302B-12 on the PWB MAIN-C +5 VDC? | Go to step 20. | Replace the PWB MAIN-C. (RRP 12.98) |
| 20 | Checking the SENSOR (Stacker Encode Sensor) for operation <br> Does the voltage across P8302B-13 <=> P8302B-12 on the PWB MAIN-C change, every time the detection point of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Stacker Encode Sensor). (RRP 12.32) |
| 21 | Checking the MOTOR ASSY DC (Elevator Motor) for operation <br> Execute [Output 13-31 Stacker Motor UP ON/OFF] and [Output 13-32 Stacker Motor DOWN ON/OFF] in [Diagnosis] alternately. <br> Does the MOTOR ASSY DC (Elevator Motor) rotate normally in Forward /Reverse directions? | Replace the PWB MAIN-C. (RRP 12.98) | Go to step 22. |
| 22 | Checking the MOTOR ASSY DC (Elevator Motor) connection <br> Is P/J8305 of the MOTOR ASSY DC (Elevator Motor) connected to the PWB MAIN-C surely? | Go to step 24. | After reconnecting, go to step 23. |
| 23 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 24. | End of work. |
| 24 | Checking after replacing the MOTOR ASSY DC (Elevator Motor) <br> Replace the MOTOR ASSY DC (Elevator Motor). (RRP 12.35) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the PWB MAIN-C. (RRP 12.98) | End of work. |

## Stacker Tray Full (Mix Size): Finisher

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :--- | :--- |
|  | Possible causative parts: <br> SENSOR (PL 12.6.17) <br> COVER ASSY SENSOR (PL 12.6.13) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> MOTOR ASSY DC (PL 12.6.26) |  |  |


| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking the Stacker Tray for obstacles Are there any obstacles on the upper and lower parts of the Stacker Tray? | Remove the obstacles. | Go to step 2. |
| 2 | Checking the COVER ASSY SENSOR (PL 12.6.13) <br> (Stacker Height Sensor 1) for operation <br> Execute [Input 13-50 Stack Height SENSOR 1] in [Diagnosis]. <br> Does the display on the screen change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Go to step 8. | Go to step 3. |
| 3 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8331 and P/J8302B of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> DisconnectP/J8331 of the HARNESS ASSY MAIN SENSOR, and P/J8302B on the PWB MAIN-C. <br> Check for conductivity at the following: <br> J8331-5 <=> J8302B-1 <br> J8331-4 <=> J8302B-2 <br> J8331-3 <=> J8302B-3 <br> J8331-2 <=> J8302B-4 <br> J8331-1 <=> J8302B-5 | Go to step 6. | Replace the HARNESSASSY MAIN SENSOR. |
| 6 | Checking +5 VDC power supply to the COVER ASSY SENSOR (Stacker Height Sensor 1) <br> Is the voltage across J8302B-3 <=> J8302B-1 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |
| 7 | Checking the COVER ASSY SENSOR (Stacker Height <br> Sensor 1) for operation <br> Does the voltage across P8302B-2 <=> P8302B-1 on the PWB MAIN-C change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the COVER ASSY SENSOR (Stacker Height Sensor 1). (RRP 12.30) |
| 8 | Checking the COVER ASSY SENSOR (PL 12.6.13) <br> (Stacker Height Sensor 2) for operation <br> Execute [Input 13-51 Stack Height SENSOR 2] in [Diagnosis]. <br> Does the display on the screen change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Go to step 14. | Go to step 9. |
| 9 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8330 and P/J8302A of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 11. | After reconnecting, go to step 10. |
| 10 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 11. | End of work. |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 11 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8330 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8330-5 <=> J8302A-16 } \\ & \text { J8330-4 <=> J8302A-17 } \\ & \text { J8330-3 <=> J8302A-18 } \\ & \text { J8330-2 <=> J8302A-19 } \\ & \text { J8330-1 <=> J8302A-20 } \end{aligned}$ | Go to step 12. | Replace the HARNESSASSY MAIN SENSOR. |
| 12 | Checking +5 VDC power supply to the COVER ASSY SENSOR (Stacker Height Sensor 2) Is the voltage across J8302A-18 <=> J8302A-16 on the PWB MAIN-C +5 VDC? | Go to step 13. | Replace the PWB MAIN-C. (RRP 12.98) |
| 13 | Checking the COVER ASSY SENSOR (Stacker Height Sensor 2) for operation Does the voltage across P8302A-17 <=> P8302A-16 on the PWB MAIN-C change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the COVER ASSY SENSOR (Stacker Height Sensor 2). (RRP 12.31) |
| 14 | Checking the ENCODER (PL 12.6.23) of the SENSOR (Stacker Encode Sensor) installation. Is the ENCODER installed correctly? Does it enter the detection point of the SENSOR? | Go to step 15. | After reinstalling, go to step 15. |
| 15 | Checking the SENSOR (Stacker Encode Sensor) for operation <br> Execute [Input 13-49 Stack Encoder SENSOR] in [Diagnosis]. <br> Does the screen display change when the BELT (PL 12.6.25) of the MOTOR ASSY-DC (PL 12.6.26) is moved by hand (when the ENCODER (PL 12.6.23) is rotated)? | Go to step 21. | Go to step 16. |
| 16 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8328 and P/J8302B of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 18. | After reconnecting, go to step 17. |
| 17 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 18. | End of work. |
| 18 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8328 of the HARNESS ASSY MAIN SENSOR, and P/J8302B on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8328-3 <=> J8302B-12 } \\ & \text { J8328-2 <=> J8302B-13 } \\ & \text { J8328-1 <=> J8302B-14 } \end{aligned}$ | Go to step 19. | Replace the HARNESSASSY MAIN SENSOR. |
| 19 | Checking +5 VDC power supply to the SENSOR (Stacker Encode Sensor) <br> Is the voltage across J8302B-14 <=> J8302B-12 on the PWB MAIN-C +5 VDC? | Go to step 20. | Replace the PWB MAIN-C. (RRP 12.98) |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 20 | Checking the SENSOR (Stacker Encode Sensor) for <br> operation <br> Does the voltage across P8302B-13 <=> P8302B-12 on <br> the PWB MAIN-C change, every time the detection point <br> of the SENSOR is blocked by putting a piece of paper? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | Replace the <br> SENSOR <br> (Stacker Encode <br> Sensor). <br> (RRP 12.32) |
| 21 | Checking the MOTOR ASSY DC (Elevator Motor) for <br> operation <br> Execute [Output 13-31 Stacker Motor UP ON/OFF] and <br> [Output 13-32 Stacker Motor DOWN ON/OFF] in [Diagno- <br> sis] alternately. <br> Does the MOTOR ASSY DC (Elevator Motor) rotate nor- <br> mally in Forward/Reverse directions? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | Go to step 22. |
| 22 | Checking the MOTOR ASSY DC (Elevator Motor) con- <br> nection <br> Is P/J8305 of the MOTOR ASSY DC (Elevator Motor) <br> connected to the PWB MAIN-C surely? | Go to step 24. | After reconnect- <br> ing, go to step 23. |
| 23 | Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 24. | End of work. |
| 24 | Checking after replacing the MOTOR ASSY DC (Elevator <br> Motor) <br> Replace the MOTOR ASSY DC (Elevator Motor). (RRP <br> 12.35) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) | End of work. |

## Finisher Top Tray Full

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (PL 12.13.7) <br> HARNESS ASSY TOP SENSOR (PL 12.15.7) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) | Checking the SENSOR (Top Tray Full Sensor) for opera- <br> tion <br> Execute [Input 12-33 Top Tray Full SENSOR] in [Diagno- <br> sis]. <br> Does the display of the screen change, every time a piece <br> of white paper is placed over the sensing area of the SEN- <br> SOR (Top Tray Full Sensor)? | Replace the <br> PWB MAIN-C. <br> (RRP 12.98) |
| 2 | Checking the HARNESS ASSY TOP SENSOR and HAR- <br> NESS ASSY MAIN SENSOR connection <br> Are P/J8322 and P/J8393 of the HARNESS ASSY TOP <br> SENSOR, and P/J8393 and P/J8302A of the HARNESS <br> ASSY MAIN SENSOR connected surely? | Go to step 2. |  |
| 3 | Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 4. | After reconnect- |
| ing, go to step 3. |  |  |  |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 4 | Checking the HARNESS ASSY TOP SENSOR for conductivity <br> Disconnect P/J8322 and P/J8393 of the HARNESS ASSY TOP SENSOR. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8322-3 <=> J8393B-1 } \\ & \text { J8322-2 <=> J8393B-2 } \\ & \text { J8322-1 <=> J8393B-3 } \end{aligned}$ | Go to step 5. | Replace the HARNESSASSY TOP SENSOR. |
| 5 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8393 and P/J8302A of the HARNESS ASSY MAIN SENSOR. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8393A-3 <=> J8302A-10 } \\ & \text { J8393A-2 <=> J8302A-11 } \\ & \text { J8393A-1 <=> J8302A-12 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY MAIN SENSOR. |
| 6 | Checking +5 VDC power supply to the SENSOR (Top Tray Full Sensor) Is the voltage across J8302A-12 <=> J8302A-10 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |
| 7 | Checking the SENSOR (Top Tray Full Sensor) for operation <br> Does the voltage across P8302A-11 <=> P8302A-10 on the PWB MAIN-C change, every time a piece of white paper is placed over the sensing area of the SENSOR (Top Tray Full Sensor)? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Top Tray Full Sensor) (RRP 12.90) |

## Staple Pin Empty

| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> STAPLER ASSY (PL 12.8.2) <br> HARNESS ASSY STAPLE (PL 12.8.7) <br> PWB MAIN-C (PL 12.14.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the Low Staple Sensor in the Staple Cartridge for operation <br> Execute [Input 13-43 Low Staple SENSOR] in [Diagnosis]. Does the display on the screen change, every time the Staple Cartridge that stores the Staple pin is removed or installed? | Go to step 9. | Go to step 2. |
| 2 | Checking the mounting position of the Staple Cartridge on the STAPLER ASSY (PL 12.8.2) for faulty parts and foreign particles. <br> Is the component part damaged? <br> Or are there any foreign particles? | Replace faulty parts or remove foreign articles and/or clean. | Go to step 3. |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 3 | Checking the HARNESS ASSY STAPLE connection Are P/J8356 and P/J8308 of the HARNESS ASSY STAPLE connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Does the error still occur when the power is turned ON? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY STAPLE for conductivity Disconnect P/J8356 and P/J8308 of the HARNESS ASSY STAPLE. <br> Check for conductivity at the following: <br> J8356-1 <=> J8308-15 <br> J8356-2 <=> J8308-14 <br> J8356-3 <=> J8308-13 <br> J8356-4 <=> J8308-12 <br> J8356-5 <=> J8308-11 | Go to step 6. | Replace the HARNESSASSY STAPLE. |
| 6 | Checking +5 VDC power supply to the Low Staple Sensor in the Staple Cartridge Is the voltage across J8308-11 <=> J8308-15 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |
| 7 | Checking the Low Staple Sensor in the Staple Cartridge for operation <br> Does the voltage across P8308-14 <=> P8308-15 on the PWB MAIN-C change, every time the Staple Cartridge is installed or removed? | Go to step 8. | Replace the PWB MAIN-C. (RRP 12.98) |
| 8 | Checking after replacing the STAPLER ASSY <br> Replace the STAPLER ASSY. (RRP 12.47) <br> Does the error still occur when the power is turned ON? | Go to step 9. | End of work. |
| 9 | Checking after replacing the PWB MAIN-C <br> Replace the PWB MAIN-C. (RRP 12.98) <br> Does the error still occur when the power is turned ON? | Replace the PWBA MCU F. (RRP 8.4) | End of work. |

## Staple Pin Not Ready

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> STAPLER ASSY (PL 12.8.2) <br> HARNESS ASSY STAPLE (PL 12.8.7) <br> PWB MAIN-C (PL 12.14.5) <br> PWBA MCU F (PL 8.1.5) | Checking the Self Priming Sensor in the Staple Cartridge <br> for operation <br> Execute [Input 13-44 Self Priming SENSOR] in [Diagno- <br> sis]. <br> Does the display on the screen change, every time the | Go to step 11. |
| Staple Cartridge is installed or removed? |  |  |  |$\quad$ Go to step 2. $\quad$| Checking the Staple Cartridge and the STAPLER ASSY |
| :--- |
| for Staple Pin JAM |
| Is there Staple pin Jam in the Staple Cartridge or the |
| STAPLER ASSY. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 3 | Does the error still occur when the power is turned ON? | Go to step 4. | End of work. |
| 4 | Checking the mounting position of the Staple Cartridge on the STAPLER ASSY (PL 12.8.2) for faulty parts and foreign particles. <br> Is the component part damaged? <br> Or are there any foreign particles? | Replace faulty parts or remove foreign articles and/or clean. | Go to step 5. |
| 5 | Checking the HARNESS ASSY STAPLE connection Are P/J8356 and P/J8308 of the HARNESS ASSY STAPLE connected surely? | Go to step 7. | After reconnecting, go to step 6. |
| 6 | Does the error still occur when the power is turned ON? | Go to step 7. | End of work. |
| 7 | Checking the HARNESS ASSY STAPLE for conductivity Disconnect P/J8356 and P/J8308 of the HARNESS ASSY STAPLE. <br> Check for conductivity at the following: <br> J8356-1 <=> J8308-15 <br> J8356-2 <=> J8308-14 <br> J8356-3 <=> J8308-13 <br> J8356-4 <=> J8308-12 <br> J8356-5 <=> J8308-11 | Go to step 8. | Replace the HARNESSASSY STAPLE. |
| 8 | Checking +5 VDC power supply to the Self Priming Sensor in the Staple Cartridge Is the voltage across J8308-11 <=> J8308-15 on the PWB MAIN-C +5 VDC? | Go to step 9. | Replace the PWB MAIN-C. (RRP 12.98) |
| 9 | Checking the Self Priming Sensor in the Staple Cartridge for operation <br> Does the voltage across P8308-14 <=> P8308-15 on the PWB MAIN-C change, every time the Staple Cartridge is installed or removed? | Go to step 10. | Replace the PWB MAIN-C. (RRP 12.98) |
| 10 | Checking after replacing the STAPLER ASSY <br> Replace the STAPLER ASSY. (RRP 12.47) <br> Does the error still occur when the power is turned ON? | Go to step 11. | End of work. |
| 11 | Checking after replacing the PWB MAIN-C <br> Replace the PWB MAIN-C. (RRP 12.98) <br> Does the error still occur when the power is turned ON? | Replace the PWBA MCU F. (RRP 8.4) | End of work. |

## Staple NG: Finisher

| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> HARNESS ASSY STAPLE (PL 12.8.7) <br> PWB MAIN-C (PL 12.14.5) <br> STAPLER ASSY (PL 12.8.2) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the Compile Tray for foreign particle <br> Are there any foreign particles in the Compile Tray? | Remove the <br> obstacles. | Go to step 2. |


| Ste <br> p | $\quad$ Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 2 | Checking the Staple Motor in the Staple Cartridge for <br> operation <br> Execute [Output 13-29 Staple Motor FORWARD ON/OFF] <br> and [Output 13-30 Staple Motor REVERSE ON/OFF] in <br> [Diagnosis] alternately. <br> Does the Motor in the Staple Cartridge rotate? <br> Check by rotating sound of the Motor. | Go to step 6. | Go to step 3. |
| 3 | Checking the HARNESS ASSY STAPLE connection <br> Are P/J8357 and P/J8308 of the HARNESS ASSY <br> STAPLE connected surely? | Go to step 5. | After reconnect- |
| ing, go to step 4. |  |  |  |

Stacker Lower Safety: Finisher

| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> COVER ASSY SENSOR (PL 12.6.13) <br> HARNESS ASSY MAIN SENSOR (PL 12.15.1) <br> PWB MAIN-C (PL 12.14.5) <br> MOTOR ASSY DC (PL 12.6.26) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the vertical transport mechanism of the Stacker Tray for obstacles and deformation Are there any obstacles in the vertical transport mechanism of the Stacker Tray? Is there any deformation in the vertical transport mechanism of the Stacker Tray? | Remove obstacles/replace deformed part. | Go to step 2. |
| 2 | Checking the COVER ASSY SENSOR (PL 12.6.13) <br> (Stacker Height Sensor 1) for operation <br> Execute [Input 13-50 Stack Height SENSOR 1] in [Diagnosis]. <br> Does the display on the screen change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Go to step 8. | Go to step 3. |
| 3 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8331 and P/J8302B of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> DisconnectP/J8331 of the HARNESS ASSY MAIN SENSOR, and P/J8302B on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} \text { J8331-5 } & \text { => J8302B-1 } \\ \text { J8331-4 } & \text { => J8302BB-2 } \\ \text { J8331-3 } & \text { => J8302BB-3 } \\ \text { J8331-2 } & \text { => J8302BB-4 } \\ \text { J8331-1 } & <=>\text { J8302B-5 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY MAIN SENSOR. |
| 6 | Checking +5 VDC power supply to the COVER ASSY SENSOR (Stacker Height Sensor 1) Is the voltage across J8302B-3 <=> J8302B-1 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |
| 7 | Checking the COVER ASSY SENSOR (Stacker Height <br> Sensor 1) for operation <br> Does the voltage across P8302B-2 <=> P8302B-1 on the PWB MAIN-C change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the COVER ASSY SENSOR (Stacker Height Sensor 1). (RRP 12.30) |


| $\begin{aligned} & \text { Ste } \\ & \text { p } \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 8 | Checking the COVER ASSY SENSOR (PL 12.6.13) <br> (Stacker Height Sensor 2) for operation <br> Execute [Input 13-51 Stack Height SENSOR 2] in [Diagnosis]. <br> Does the display on the screen change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Go to step 14. | Go to step 9. |
| 9 | Checking the HARNESS ASSY MAIN SENSOR connection <br> Are P/J8330 and P/J8302A of the HARNESS ASSY MAIN SENSOR connected surely? | Go to step 11. | After reconnecting, go to step 10 . |
| 10 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 11. | End of work. |
| 11 | Checking the HARNESS ASSY MAIN SENSOR for conductivity <br> Disconnect P/J8330 of the HARNESS ASSY MAIN SENSOR, and P/J8302A on the PWB MAIN-C. <br> Check for conductivity at the following: <br> J8330-5 <=> J8302A-16 <br> J8330-4 <=> J8302A-17 <br> J8330-3 <=> J8302A-18 <br> J8330-2 <=> J8302A-19 <br> J8330-1 <=> J8302A-20 | Go to step 12. | Replace the HARNESSASSY MAIN SENSOR. |
| 12 | Checking +5 VDC power supply to the COVER ASSY SENSOR (Stacker Height Sensor 2) <br> Is the voltage across J8302A-18 <=> J8302A-16 on the PWB MAIN-C +5 VDC? | Go to step 13. | Replace the PWB MAIN-C. (RRP 12.98) |
| 13 | Checking the COVER ASSY SENSOR (Stacker Height Sensor 2) for operation Does the voltage across P8302A-17 <=> P8302A-16 on the PWB MAIN-C change, every time the sensing area of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the COVER ASSY SENSOR (Stacker Height Sensor 2). (RRP 12.31) |
| 14 | Checking the MOTOR ASSY DC (Elevator Motor) for operation <br> Execute [Output 13-31 Stacker Motor UP ON/OFF] and [Output 13-321 Stacker Motor DOWN ON/OFF] in [Diagnosis] alternately. <br> Does the MOTOR ASSY DC (Elevator Motor) rotate normally in Forward/reverse directions? | Go to step 18. | Go to step 15. |
| 15 | Checking the MOTOR ASSY DC (Elevator Motor) connection <br> Is P/J8305 of the MOTOR ASSY DC (Elevator Motor) connected to the PWB MAIN-C surely? | Go to step 17. | After reconnecting, go to step 16. |
| 16 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 17. | End of work. |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 17 | Checking after replacing the MOTOR ASSY DC (Elevator <br> Motor) <br> Replace the MOTOR ASSY DC (Elevator Motor). (RRP <br> 12.35) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 18. | End of work. |
| 18 | Checking after replacing the PWB MAIN-C <br> Replace the PWB MAIN-C. (RRP 12.98) <br> Does the error still occur when the power is turned ON? | Replace the PWB <br> A MAIN F. | End of work. |

## Stacker Set Over Count: Finisher

| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> PWB MAIN-C (PL 12.14.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking connectors of the PWB MAIN-C connection Are all the connectors connected to the PWB MAIN-C connected surely? | Go to step 3. | After reconnecting, go to step 2. |
| 2 | Does the error still occur when the power is turned ON? | Go to step 3. | End of work. |
| 3 | Checking after replacing the PWB MAIN-C <br> Replace the PWB MAIN-C. (RRP 12.98) <br> Does the error still occur when the power is turned ON? | Replace the PWBA MCU F. (RRP 8.4) | End of work. |

## Punch Waste Box Overflow: Finisher

| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SENSOR PI DH (PL 12.7. ) <br> HARNESS ASSY PUNCH FULL SENSOR <br> PWB H-TRA (PL 12.14.3) <br> PWB MAIN-C (PL 12.14.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the HARNESS ASSY PUNCH FULL SENSOR connection <br> Are P/J8452 and P/J8500 of the HARNESS ASSY PUNCH FULL SENSOR connected surely? | Go to step 3. | After reconnecting, go to step 2. |
| 2 | Does the error still occur when the power is turned ON? | Go to step 3. | End of work. |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 3 | Checking the HARNESS ASSY PUNCH FULL SENSOR <br> for conductivity <br> Disconnect P/J8452 and P/J8500 of the HARNESS ASSY <br> PUNCH FULL SENSOR. <br> Check for conductivity at the following: <br> J8452-3 <=> J8500-1 <br> J8452-2 <=> J8500-2 <br> J8452-1 <=> J8500-3 | Go to step 4. | NARNESS ASSY <br> PUNCH FULL <br> SENSOR. |
| 4 | Checking +5 VDC power supply to the SENSOR PI DH <br> (Punch Full Sensor) <br> Is the voltage across P8500-3 <=> P8500-1 on the PWB <br> H-TRA +5 VDC? | Go to step 7. | Go to step 5. |

## No Punch Waste Box

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :--- | :--- |
|  | Possible causative parts: <br> SENSOR (PL 12.7.21) <br> HARNESS PUNCH BOX SENSOR <br> HARNESS ASSY PUNCH SENSOR (PL 12.15.9) <br> PWB MAIN-C (PL 12.14.5) <br> PWBA MCU (PL 8.1.5) |  |  |


| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking the SENSOR (Punch Box Set Sensor) for operation <br> Remove the Dust Box (PL 12.7.20). <br> Execute [Input 13-38 Punch Box Set SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the detection point of the SENSOR is blocked by putting a piece of paper? | Go to step 8. | Go to step 2. |
| 2 | Checking the HARNESS PUNCH BOX SENSOR and HARNESS ASSY PUNCH SENSOR connection Are P/J8353 and P/J8355 of the HARNESS PUNCH BOX SENSOR, and P/J8355 and P/J8307 of the HARNESS ASSY PUNCH SENSOR connected surely? | Go to step 4. | After reconnecting, go to step 3. |
| 3 | Does the error still occur when the power is turned ON? | Go to step 4. | End of work. |
| 4 | Checking the HARNESS PUNCH BOX SENSOR for conductivity <br> Disconnect P/J8353 and P/J8355 of the HARNESS <br> PUNCH BOX SENSOR. <br> Check for conductivity at the following: <br> J8353-3 <=> P8355-3 <br> J8353-2 <=> P8355-2 <br> J8353-1 <=> P8355-1 | Go to step 5. | Fix open and short circuit. |
| 5 | Checking the HARNESS ASSY PUNCH SENSOR for conductivity <br> Disconnect P/J8355 and P/J8307 of the HARNESS ASSY PUNCH SENSOR. <br> Check for conductivity at the following: <br> J8355-3 <=> J8307-A3 <br> J8355-2 <=> J8307-A2 <br> J8355-1 <=> J8307-A1 | Go to step 6. | Replace the HARNESSASSY PUNCH SENSOR. |
| 6 | Checking +5 VDC power supply to the SENSOR (Punch Box Set Sensor) <br> Is the voltage across J8307-A1 <=> J8307-A3 on the PWB MAIN-C +5 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |
| 7 | Checking the SENSOR (Punch Box Set Sensor) for operation <br> Does the voltage across P8307-A2 <=> P8307-A3 on the PWB MAIN-C change, every time the detection point of the SENSOR is blocked by putting a piece of paper? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the SENSOR (Punch Box Set Sensor). (RRP 12.45) |
| 8 | Checking after replacing the PWB MAIN-C Replace the PWB MAIN-C. (RRP 12.98) Does the error still occur when the power is turned ON? | Replace the PWBA MCU F. (RRP 8.4) | End of work. |

Finisher Front Cover Open

| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> COVER ASSY FRONT (PL 12.5.3) <br> INTERLOCK SWITCH (PL 12.5.2) <br> HARNESS ASSY INTERLOCK (PL 12.15.11) <br> PWB MAIN-C (PL 12.14.5) <br> SENSOR ASSY (PL 12.9.23) <br> PWBA MCU (PL 8.1.5) |  |  |
| 1 | Checking the COVER ASSY FRONT for opening and closing <br> Open and close the COVER ASSY FRONT (PL 12.5.3). Does it open or close smoothly? | Go to step 2. | Check the COVER ASSY FRONT for installation, correct deformations, or replace it. |
| 2 | Checking the INTERLOCK SWITCH (Finisher Front Door SW) installation Is the INTERLOCK SIWTHC (PL 12.5.2) installed correctly? | Go to step 3. | Check the INTERLOCK SWITCH for installation or replace it. |
| 3 | Checking the INTERLOCK SWITCH (Finisher Front Door <br> SW) for operation <br> Execute [Input 13-54 Finisher Front Cover SW] in [Diagnosis]. <br> Does the display on the screen change, every time the detection point of the INTERLOCK SWITCH is pressed by the tip of the screwdriver? | Go to step 9. | Go to step 4. |
| 4 | Checking the HARNESS ASSY INTERLOCK connection Are P/J8365 of the HARNESS ASSYINTERLOCK, P/ J8364 of the Eject Cover SW, and P/J8388 and P/J8314 on the PWB MAIN-C connected surely? | Go to step 6. | After reconnecting, go to step 5. |
| 5 | Does the error still occur when the power is turned ON? | Go to step 6. | End of work. |
| 6 | Checking the HARNESS ASSY INTERLOCK for conductivity <br> Disconnect P/J8365 of the HARNESS ASSYINTERLOCK, P/J8364 of the Eject Cover SW, and P/J8388 and P/J8314 on the PWB MAIN-C. <br> Check for conductivity at the following: <br> J8365-1A <=> J8388-2 <br> J8365-1B <=> J8364-2 <br> J8365-2A <=> J8314-3 <br> J8365-2B <=> J8314-2 <br> J8364-1 <=> J8388-1 <br> J8364-3 <=> J8314-1 | Go to step 7. | Replace the HARNESSASSY INTERLOCK. |
| 7 | Checking +5/+24 VDC power supply to the INTERLOCK SWITCH (Finisher Front Door SW) <br> Is the voltage across J8314-2 <=> FRAME CHASSIS on the PWB MAIN-C +5 VDC? <br> Is the voltage across J8388-1 <=> FRAME CHASSIS on the PWB MAIN-C +24 VDC? | Go to step 8. | Replace the PWB MAIN-C. (RRP 12.98) |


| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 8 | Checking the INTERLOCK SWITCH (Finisher Front Door SW) for operation <br> Does the voltage across J8314-2 <=> J8314-3 on the PWB MAIN-C change, every time the sensing area of the INTERLOCK SWITCH (Finisher Front Door SW) is pushed by the tip of the screwdriver? | Replace the PWB MAIN-C. (RRP 12.98) | Replace the INTERLOCK SWITCH (Finisher Front Door SW). (RRP 12.23) |
| 9 | Checking the SENSOR ASSY (Eject Cover SW) for operation <br> Does the voltage across $\mathrm{J} 8365-1 \mathrm{~B}$ <=> FRAME CHASSIS of the HARNESS ASSY INTERLOCK change, every time the actuator of the SENSOR ASSY (Eject Cover SW) is pushed? | Go to step 10. | Replace the SENSOR ASSY <br> (Eject Cover SW). <br> (RRP 12.56) |
| 10 | Checking the INTERLOCK SWITCH (Finisher Front Door SW) for operation <br> Does the voltage across J8388-2 <=> FRAME CHASSIS on the PWB MAIN-C change, every time the actuator of the Eject Cover SW and the sensing area of the INTERLOCK SWITCH (Finisher Front Door SW) are pushed simultaneously by the tip of the screwdriver? | Go to step 11. | Replace the INTERLOCK SWITCH <br> (Finisher Front Door SW). (RRP 12.23) |
| 11 | Checking after replacing the PWB MAIN-C <br> Replace the PWB MAIN-C. (RRP 12.98) <br> Does the error still occur when the power is turned ON? | Replace the PWBA MCU F. (RRP 8.4) | End of work. |

## Finisher H-Transport Cover Open

| $\begin{array}{c}\text { Ste } \\ p\end{array}$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | $\begin{array}{l}\text { Possible causative parts: } \\ \text { COVER ASSY TOP (PL 12.2.9) } \\ \text { T-TRANSPORT INTERLOCK SENSOR (PL 12.3.19) } \\ \text { WIRE HARNESS (PL 12.3.26) } \\ \text { PWB MAIN-C (PL 12.14.5) } \\ \text { PWBA MCU F (PL 8.1.5) }\end{array}$ | $\begin{array}{l}\text { Checking the COVER ASSY TOP on the H-TRA for open- } \\ \text { ing and closing } \\ \text { Open and close the COVER ASSY TOP (PL 12.2.9). } \\ \text { Does it open or close smoothly? }\end{array}$ | Go to step 2. | \(\left.\left.\begin{array}{l}\begin{array}{l}TOP for installa- <br>

tion, correct <br>
deformations, or <br>
replace it.\end{array} <br>
\hline 2\end{array} $$
\begin{array}{l}\text { Checking the COVER ASSY TOP on the H-TRA for shape } \\
\text { and operation } \\
\text { Is the actuator of the COVER ASSY TOP that enters the } \\
\text { T-TRANSPORT INTERLOCK SENSOR damaged? }\end{array}
$$\right] $$
\begin{array}{l}\text { Replace the } \\
\text { COVER ASSY } \\
\text { TOP. }\end{array}
$$ \quad $$
\begin{array}{c}\text { Check the } \\
\text { Go to step 3. }\end{array}
$$\right\}\)

| $\begin{aligned} & \text { Ste } \\ & \text { p } \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 4 | Checking the T-TRANSPORT INTERLOCK SENSOR for operation <br> Execute [Input 13-53 H-Transport Interlock SENSOR] in [Diagnosis]. <br> Does the display on the screen change, every time the detection point of the T-TRANSPORT INTERLOCK SENSOR is blocked by putting a piece of paper? | Go to step 11. | Go to step 5. |
| 5 | Checking the WIRE HARNESS connection Are P/J8382 of the WIRE HARNESS, and P/J8372 on the PWB H-TRA of the Finisher connected surely? | Go to step 7. | After reconnecting, go to step 6. |
| 6 | Does the error still occur when the power is turned ON? | Go to step 7. | End of work. |
| 7 | Checking the WIRE HARNESS for conductivity Disconnect P/J8382 of the WIRE HARNESS, and P/ J8372 connected to the PWB H-TRA of the Finisher. Check for conductivity at the following: $\begin{aligned} & \mathrm{J} 8382-3 \text { <=> J8372-1 } \\ & \text { J8382-2 <=> J8372-2 } \\ & \text { J8382-1 <=> J8372-3 } \end{aligned}$ | Go to step 8. | Replace the WIRE HARNESS. |
| 8 | Checking +5 VDC power supply to the T-TRANSPORT INTERLOCK SENSOR <br> Is the voltage across J8372-3 <=> J8372-1 on the PWB H-TRA +5 VDC? | Go to step 9. | Replace the PWB MAIN-C. (RRP 12.98) |
| 9 | Checking the T-TRANSPORT INTERLOCK SENSOR for operation <br> Does the voltage across J8372-3 <=> J8372-1 on the HTRA change, every time the sensing area of the TTRANSPORT INTERLOCK SENSOR is blocked by putting a piece of paper? | Go to step 10. | Replace the T-TRANSPORT INTERLOCK SENSOR. (RRP 12.12) |
| 10 | Checking after replacing the T-TRANSPORT INTER- <br> LOCK SENSOR <br> Replace the T-TRANSPORT INTERLOCK SEN- <br> SOR.(RRP 12.12) <br> Does the error still occur when the power is turned ON? | Go to step 11. | End of work. |
| 11 | Checking after replacing the PWB MAIN-C <br> Replace the PWB MAIN-C. (RRP 12.98) <br> Does the error still occur when the power is turned ON? | Replace the PWBA MCU F. (RRP 8.4) | End of work. |

## Finisher Eject Cover Open

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> COVER ASSY FRONT (PL 12.5.3) <br> SENSOR ASSY (PL 12.9.23) <br> HARNESS ASSY INTERLOCK (PL 12.15.11) <br> INTERLOCK SWITCH (PL 12.5.2) <br> PWB MAIN-C (PL 12.14.5) <br> PWBA MCU F (PL 8.1.5) |  |  |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking the COVER ASSY FRONT for opening and closing <br> Open and close the COVER ASSY FRONT (PL 12.5.3). Does it open or close smoothly? | Go to step 2. | Check the COVER ASSY TOP for installation, correct deformations, or replace it. |
| 2 | Checking the SENSOR ASSY (Eject Cover SW) installation <br> Is the SENSOR ASSY (PL 12.9.23) installed correctly? | Go to step 3. | Check the SENSOR ASSY (Eject Cover SW) for installation, or replace it. |
| 3 | Checking the HARNESS ASSY INTERLOCK connection Are P/J8365 of the HARNESS ASSYINTERLOCK, and P/ J8364 of the Eject Cover SW, and P/J8388 and P/J8314 on the PWB MAIN-C connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Does the error still occur when the power is turned ON? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY INTERLOCK for conductivity <br> Disconnect P/J8365 of the HARNESS ASSY <br> INTERLOCK, P/J8364 of the Eject Cover SW, and P/ J8388 and P/J8314 on the PWB MAIN-C. <br> Check for conductivity at the following: $\begin{aligned} & \text { J8365-1A <=> J8388-2 } \\ & \text { J8365-1B <=> J8364-2 } \\ & \text { J8365-2A <=> J8314-3 } \\ & \text { J8365-2B <=> J8314-2 } \\ & \text { J8364-1 <=> J8388-1 } \\ & \text { J8364-3 <=> J8314-1 } \end{aligned}$ | Go to step 6. | Replace the HARNESSASSY INTERLOCK. |
| 6 | Checking +5/+24 VDC power supply to the INTERLOCK SWITCH (Finisher Front Door SW) <br> Is the voltage across J8314-2 <=> FRAME CHASSIS on the PWB MAIN-C +5 VDC? <br> Is the voltage across J8388-1 <=> FRAME CHASSIS on the PWB MAIN-C +24 VDC? | Go to step 7. | Replace the PWB MAIN-C. (RRP 12.98) |
| 7 | Checking the INTERLOCK SWITCH (Finisher Front Door SW) for operation <br> Does the voltage across J8314-2 <=> J8314-3 on the PWB MAIN-C change, every time the sensing area of the INTERLOCK SWITCH (Finisher Front Door SW) is pushed by the tip of the screwdriver? | Go to step 8. | Replace the INTERLOCK SWITCH <br> (Finisher Front Door SW). (RRP 12.23) |
| 8 | Checking the SENSOR ASSY (Eject Cover SW) for operation <br> Does the voltage across J8365-1B <=> FRAME CHASSIS on the HARNESS ASSY INTERLOCK change, every time the actuator of the Eject Cover SW is operated? | Go to step 9. | Replace the SENSOR ASSY <br> (Eject Cover SW). <br> (RRP 12.56) |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 9 | Checking the INTERLOCK SWITCH (Finisher Front Door <br> SW) for operation <br> Does the voltage across J8388-2 <=> FRAME CHASSIS <br> on the PWB MAIN-C change, every time the actuator of <br> the Eject Cover SW, and the sensing area of the <br> INTERLOCK SWITCH (Finisher Front Door SW) is <br> pushed simultaneously by the tip of the screwdriver? | Go to step 10. | INTERLOCK <br> SWITCH <br> (Finisher Front <br> Door SW). <br> (RRP 12.23) |
| 10 | Checking after replacing the PWB MAIN-C <br> Replace the PWB MAIN-C. (RRP 12.98) <br> Does the error still occur when the power is turned ON? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | End of work. |

## C5-1 HCF F/O Sensor On Jam (HCF T/A Sensor On Jam)

| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLL ASSY NUD (PL 13.5.20) <br> ROLL ASSY FEED (PL 13.5.21) <br> ROLLER ASSY RETARD (PL 13.6.17) <br> ROLLER ASSY TA P (PL 13.7.9) <br> COVER ASSY TOP S (PL 13.7.1) <br> SENSOR ASSY TA (PL 13.7.6) <br> HARNESS ASSY FEEDER (PL 13.5.12) <br> HARNESS ASSY MAIN (PL 13.8.2) <br> PWB ASSY (PL 13.8.1) <br> SENSOR ASSY (PL 13.5.9) <br> MOTOR ASSY HCF (PL 13.4.2) <br> SOLENOID ASSY (PL 13.4.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper path <br> Open the COVER ASSY TOP S (PL 13.7.1). <br> Open the FEEDER ASSY UPPER (PL 13.5.1). <br> Are the ROLLER ASSY NUD (PL 12.12.20), ROLL ASSY FEED (PL 13.5.21), ROLLER ASSY RETARD (PL 13.6.17), ROLLER ASSY TA P (PL 13.7.9), and Roller attached on the COVER ASSY TOP S installed correctly? Does they rotate smoothly without wear or/and paper dust? <br> Check these items by turning them with your fingers. Are there any stains such as paper dust on the paper path? | Go to step 2. | Clean or replace the appropriate ROLLER, and clean the paper path. |
| 2 | Checking the SENSOR ASSY (HCF Pre Feed Sensor) for operation <br> Execute [Input 08-22 HCF PreFEED SENSOR] in [Diagnosis]. <br> Open the COVER ASSY TOP S (PL 13.7.1). <br> Open the FEEDER ASSY UPPER (PL 13.5.1). <br> Does the display on the screen change, every time a piece of white paper is placed over the sensing area of the SENSOR ASSY (HCF Pre Feed Sensor)? | Go to step 10. | Go to step 3. |


| $\begin{gathered} \text { Ste } \\ p \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 3 | Checking the HARNESS ASSY FEEDER for connection Are PF61 and PF56B of the HARNESS ASSY FEEDER connected surely? | Go to step 4. | After reconnecting, go to step 4. |
| 4 | Checking the HARNESS ASSY MAIN for connection Are PF56B and JF02 of the HARNESS ASSY MAIN connected surely? | Go to step 6. | After reconnecting, go to step 5. |
| 5 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 6. | End of work. |
| 6 | Checking the HARNESS ASSY FEEDER for conductivity Disconnect PF61 and PF56B of the HARNESS ASSY FEEDER. <br> Check for conductivity at the following: <br> PF61-1 <=> JF56B-3 <br> PF61-2 <=> JF56B-2 <br> PF61-3 <=> JF56B-1 | Go to step 7. | Replace the HARNESS ASSY FEEDER. |
| 7 | Checking the HARNESS ASSY MAIN for conductivity Disconnect PF56B and JF02 of the HARNESS ASSY MAIN. <br> Check for conductivity at the following: <br> PF56B-4 <=> JF02-6 <br> PF56B-5 <=> JF02-5 <br> PF56B-6 <=> JF02-4 | Go to step 8. | Replace the HARNESS ASSY MAIN. |
| 8 | Checking +5 VDC power supply to the SENSOR ASSY (HCF Pre Feed Sensor) <br> Is the voltage across PF02-6 <=> PF02-4 on the PWB ASSY +5 VDC? | Go to step 9. | Replace the PWB ASSY. RRP 13.34) |
| 9 | Checking the SENSOR ASSY (HCF Pre Feed Sensor) for operation <br> Does the voltage across PF02-5 <=> PF02-4 on the PWB ASSY change, every time a piece of white paper is placed over the sensing area of the SENSOR ASSY (HCF Pre Feed Sensor)? | Go to step 35. | Replace the SENSOR ASSY. RRP 13.18) |
| 10 | Checking the SENSOR ASSY TA (HCF TA Sensor) for operation <br> Execute [Input 08-23 HCF F/O SENSOR] in [Diagnosis]. Does the display on the screen change, every time the actuator of the SENSOR ASSY TA (HCF TA Sensor) is operated? | Go to step 18. | Go to step 11. |
| 11 | Checking the HARNESS ASSY for connection Are PF67 and JF54 of the HARNESS ASSY connected to the SENSOR ASSY TA (HCF TA Sensor) connected surely? | Go to step 12. | After reconnecting, go to step 12. |
| 12 | Checking the HARNESS ASSY MAIN (PL 13.8.2) for connection <br> Are PF54 and JF01 of the HARNESS ASSY MAIN connected surely? | Go to step 14. | After reconnecting, go to step 13. |
| 13 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 14. | End of work. |


| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 14 | Checking the HARNESS ASSY for conductivity Disconnect PF67 and JF54 of the HARNESS ASSY. Check for conductivity at the following: $\begin{aligned} & \text { PF67-1 <=> JF54-3 } \\ & \text { PF67-2 <=> JF54-2 } \\ & \text { PF67-3 <=> JF54-1 } \end{aligned}$ | Go to step 15. | Replace the HARNESS ASSY. |
| 15 | Checking the HARNESS ASSY MAIN for conductivity Disconnect PF54 and JF01 of the HARNESS ASSY MAIN. Check for conductivity at the following: $\begin{aligned} & \text { PF54-1 <=> JF01-3 } \\ & \text { PF54-2 <=> JF01-2 } \\ & \text { PF54-3 <=> JF01-1 } \end{aligned}$ | Go to step 16. | Replace the HARNESS ASSY MAIN. |
| 16 | Checking +5 VDC power supply to the SENSOR ASSY TA (HCF TA Sensor) <br> Is the voltage across PF01-3 <=> PF01-1 on the PWB ASSY + 5 VDC? | Go to step 17. | Replace the PWB ASSY. RRP 13.34) |
| 17 | Checking the SENSOR ASSY TA (HCF TA Sensor) for operation <br> Does the voltage across PF01-2 <=> PF01-1 on the PWB ASSY change, every time the actuator of the SENSOR ASSY TA (HCF TA Sensor) is operated? | Go to step 35. | Replace the SENSOR ASSY. RRP 13.30) |
| 18 | Checking the MOTOR ASSY HCF (Feed Sensor) for operation <br> Execute [Output 08-16 HCF FEED MOTOR] in [Diagnosis]. <br> Does the MOTOR ASSY HCF (Feed Sensor) rotate normally? | Go to step 26. | Go to step 19. |
| 19 | Checking the HARNESS ASSY FEEDER and HARNESS ASSY MAIN for connection Are the connectors PF58 and PF56 of the HARNRESS ASSY FEEDER and HARNESS ASSY MAIN, and JF06 on the PWB ASSY connected surely? | Go to step 21. | After reconnecting, go to step 20. |
| 20 | Execute [Test Print] in [Diagnosis] Does the error still occur? | Go to step 21. | End of work. |
| 21 | Checking the HARNESS ASSY FEEDER for conductivity Disconnect PF58 and JF56 of the HARNESS ASSY FEEDER. <br> Check for conductivity at the following: <br> PF58-1 <=> JF56-1 <br> PF58-2 <=> JF56-2 <br> PF58-3 <=> JF56-3 <br> PF58-4 <=> JF56-4 <br> PF58-5 <=> JF56-5 <br> PF58-6 <=> JF56-6 | Go to step 22. | Replace the HARNRESS ASSY FEEDER. |


| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 22 | Checking the HARNESS ASSY MAIN for conductivity Disconnect PF56 and JF06 of the HARNRESS ASSY MAIN. <br> Check for conductivity at the following: <br> PF56-1 <=> JF06-1 <br> PF56-2 <=> JF06-3 <br> PF56-3 $<=>$ JF06-2 <br> PF56-4 <=> JF06-6 <br> PF56-5 <=> JF06-4 <br> PF56-6 <=> JF06-5 | Go to step 23. | Replace the HARNRESS ASSY MAIN. |
| 23 | Checking the conductivity (resistance) of the MOTOR ASSY HCF (Feed Motor) <br> Are the conductivity across PF58-2/5 (COM) and PF58-1/ 3/4/6 of the MOTOR ASSY HCF (Feed Motor) normal, or are there any resistance without disconnection? | Go to step 24. | Replace the MOTOR ASSY HCF. <br> RRP 13.15) |
| 24 | Checking +24 VDC power supply to the MOTOR ASSY HCF (Feed Motor) <br> Are the voltages across PF06-3 <=> GND and PF06-4 <=> GND on the PWB ASSY, +24 VDC? | Go to step 25. | Replace the PWB ASSY. RRP 13.34) |
| 25 | Checking after replacing the MOTOR ASSY HCF (Feed Motor) <br> Replace the MOTOR ASSY HCF (Feed Motor). RRP 13.15) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 35. | End of work. |
| 26 | Checking the SOLENOID ASSY (Nudger Solenoid) for operation <br> Execute [Output 08-41 HCF Nudger Solenoid (High Power)] in [Diagnosis]. <br> Does the SOLENOID ASSY activates? | Go to step 35. | Go to step 27. |
| 27 | Checking the HARNESS ASSY FEEDER and HARNESS ASSY MAIN for connection Are the connectors PF59 and PF56 of the HARNRESS ASSY FEEDER and HARNESS ASSY MAIN, and JF06 on the PWB ASSY connected surely? | Go to step 29. | After reconnecting, go to step 28. |
| 28 | Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 29. | End of work. |
| 29 | Checking the HARNESS ASSY FEEDER for conductivity Disconnect PF59 and JF56A of the HARNESS ASSY FEEDER. <br> Check for conductivity at the following: PF59-2 <=> JF56A-1 PF59-1 <=> JF56A-2 | Go to step 30. | Replace the HARNRESS ASSY FEEDER. |
| 30 | Checking the HARNESS ASSY MAIN for conductivity Disconnect PF56A and JF06 of the HARNESS ASSY MAIN. <br> Check for conductivity at the following: PF56A-6 <=> JF06-13 PF56A-5 <=> JF06-14 | Go to step 31. | Replace the HARNRESS ASSY MAIN. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 31 | Checking the conductivity (resistance) of the SOLENOID ASSY (Nudger Solenoid) <br> Is the conductivity across PF59-1 and PF59-2 of the SOLENOID ASSY (Nudger Solenoid) normal, or is there any resistance without disconnection? | Go to step 32. | Replace the SOLENOID ASSY. <br> RRP 13.17) |
| 32 | Checking +24.5 VDC power supply to the SOLENOID ASSY (Nudger Solenoid) <br> Execute [Output 08-41 HCF Nudger Solenoid (High Power)] in [Diagnosis]. <br> Is the voltage across PF06-13 <=> PF06-14 on the PWB ASSY + 24.5 VDC? | Go to step 33. | Replace the PWB ASSY. RRP 13.34) |
| 33 | Checking +13.8 VDC power supply to the SOLENOID ASSY (Nudger Solenoid) <br> Execute [Output 08-51 HCF Nudger Solenoid (Low Power)] in [Diagnosis]. <br> Is the voltage across PF06-13 <=> PF06-14 on the PWB ASSY +13.8 VDC? | Go to step 34. | Replace the PWB ASSY. <br> RRP 13.34) |
| 34 | Checking after replacing the SOLENOID ASSY (Nudger Solenoid) <br> Replace the SOLENOID ASSY (Nudger Solenoid). RRP 13.17) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 35. | End of work. |
| 35 | Checking after replacing the PWB ASSY Replace the PWB ASSY. RRP 13.34) Execute [Test Print] in [Diagnosis]. Does the error still occur? | Replace the PWBA MCU F. | End of work. |

## C5-2 HCF FIO\#2 Sensor On Jam

| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :--- | :--- |
|  | Possible causative parts: <br> ROLL ASSY NUD (PL 13.5.20) <br> ROLL ASSY FEED (PL 13.5.21) |  |  |
|  | ROLLER ASSY RETARD (PL 13.6.17) <br> ROLLER ASSY TA P (PL 13.7.9) |  |  |
|  | COVER ASSY TOP S (PL 13.7.1) |  |  |
| HARNESS ASSY MAIN (PL 13.8.2) |  |  |  |
|  | PWB ASSY (PL 13.8.1) |  |  |
| MOTOR ASSY (PL 13.7.12) |  |  |  |
| PWBA MCU F (PL 8.1.5) |  |  |  |


| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking the paper path <br> Open the COVER ASSY TOP S (PL 13.7.1). <br> Open the FEEDER ASSY UPPER (PL 13.5.1). <br> Are the ROLLER ASSY NUD (PL 12.12.20), ROLL ASSY <br> FEED (PL 13.5.21) ,ROLLER ASSY RETARD (PL <br> 13.6.17), ROLLER ASSY TA P (PL 13.7.9), and Roller attached on the COVER ASSY TOP S installed correctly? <br> Does they rotate smoothly without wear or/and paper dust? <br> Check these items by turning them with your fingers. Are there any stains such as paper dust on the paper path? | Go to step 2. | Clean or replace the appropriate ROLLER, and clean the paper path. |
| 2 | Checking the SENSOR (IOT Feed Out\#2 Sensor) on the IOT for operation <br> Execute [Input 08-06 FEED OUT\#2 SENSOR] in [Diagnosis]. <br> Open the COVER ASSY LH LOW C (PL 4.1.10). <br> Does the display on the screen change, every time the SENSOR is operated? | Go to step 7. | Go to step 3. |
| 3 | Checking the SENSOR for connection Are P/J105, P/J608 and P/J410 of the HARNESS connected to the SENSOR connected surely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS between SENSOR and PWBA MCU F for conductivity Is there conductivity on each wire between P/J105 <=> P/J410? | Go to step 6. | Replace the HARNESS. |
| 6 | Checking +5 VDC power supply to the SENSOR Is the voltage across P/J105-1 <=> GND on the PWBA MCU F +5 VDC? | Replace the SENSOR. <br> (RRP 4.15) | Replace the PWBA MCU F. (RRP 8.4) |
| 7 | Checking the MOTOR ASSY (T/A Motor) for operation Execute [Output 08-11 HCF T/A Motor( $242 \mathrm{~mm} / \mathrm{s}$ )] in [Diagnosis]. <br> Does the MOTOR ASSY (T/A Motor) rotate normally? | Go to step 14. | Go to step 8. |
| 8 | Checking the HARNESS ASSY MAIN for connection Are PF57 and JF06 of the HARNESS ASSY MAIN connected surely? | Go to step 10. | After reconnecting, go to step 9 |
| 9 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 10. | End of work. |
| 10 | Checking the HARNESS ASSY MAIN for conductivity Disconnect PF57 and JF06 of the HARNESS ASSY MAIN. Check for conductivity at the following: $\begin{aligned} & \text { PF57-7 <=> JF06-11 } \\ & \text { PF57-6 <=> JF06-8 } \\ & \text { PF57-5 <=> JF06-9 } \\ & \text { PF57-4 <=> JF06-10 } \\ & \text { PF57-3 <=> JF06-12 } \\ & \text { PF57-2 <=> JF06-7 } \end{aligned}$ | Go to step 11. | Replace the HARNRESS ASSY MAIN. |


| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 11 | Checking the conductivity (resistance) of the MOTOR <br> ASSY (T/A Motor) <br> Are the conductivity across JF57-3/4(COM) and JF57-1/2/ <br> 5/6 of the MOTOR ASSY (T/A Motor) normal, or are there <br> any resistance without disconnection? | Go to step 12. | Replace the <br> MOTOR ASSY. <br> RRP 13.32) |
| 12 | Checking +24 VDC power supply to the MOTOR ASSY <br> (T/A Motor) <br> Are the voltages across PF06-9 <=> PF04-3, and PF06-10 <br> <=> PF04-3 on the PWB ASSY, +24 VDC? | Go to step 13. | Replace the <br> PWB ASSY. <br> RRP 13.34) |
| 13 | Checking after replacing the MOTOR ASSY (T/A Motor) <br> Replace the MOTOR ASSY (T/A Motor). RRP 13.32) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 14. | End of work. |
| 14 | Checking after replacing the PWB ASSY <br> Replace the PWB ASSY. RRP 13.34) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | End of work. |

## C5-3 HCF Registration Sensor On Jam

| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> ROLER ASSY TA P (PL 13.7.9) <br> COVER ASSY TOP S (PL 13.7.1) <br> SENSOR ASSY REGI (PL 4.5.7) <br> HARNESS ASSY FRONT A (PL 5.1.9) <br> PWBA MCU F (PL 8.1.5) <br> MOTOR ASSY (PL 13.7.12) <br> PWB ASSY (PL 13.8.1) <br> HARNESS ASSY MAIN (PL 13.8.2) |  |  |
| 1 | Checking the paper path <br> Open the COVER ASSY TOP S (PL 13.7.1). <br> Are the ROLLER ASSY TA P (PL 13.7.9) and Roller <br> attached on the COVER ASSY TOP S installed correctly? <br> Does they rotate smoothly without wear or/and paper <br> dust? <br> Check these items by turning them with your fingers. <br> Are there any stains such as paper dust on the paper <br> path? | Go to step 2. | ROLLER, and <br> the appropriate <br> ROLean the paper <br> path. |
|  | Checking the paper path of the IOT <br> Open the COVER ASSY-LH (PL 4.2.8). <br> Are there any stains such as paper dust on the paper <br> path? | Go to step 3. | Clean the paper <br> path. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 3 | Checking the SENSOR ASSY REGI (Registration Sensor) in the IOT for operation <br> Execute [Input 08-05 REGI SENSOR] in [Diagnosis]. Open the COVER ASSY-LH (PL 4.2.8). <br> Does the display on the screen change, every time the actuator of the SENSOR ASSY REGI (Registration Sensor) is operated? | Go to step 9. | Go to step 4. |
| 4 | Checking the HARNESS ASSY FRONT A on the IOT for connection <br> Are P/J104 and P/J403 of the HARNESS ASSY FRONT A connected to the SENSOR ASSY REGI connected surely? | Go to step 6. | After reconnecting, go to step 5. |
| 5 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 6. | End of work. |
| 6 | Checking the HARNESS ASSY FRONT A on the IOT for conductivity <br> Disconnect P/J104 and P/J403 of the HARNESS ASSY FRONT A. <br> Check for conductivity at the following: $\begin{aligned} & \text { J104-3 <=> J403B-3 } \\ & \text { J104-2 <=> J403B-8 } \\ & \text { J104-1 <=> J403B-13 } \end{aligned}$ | Go to step 7. | Replace the HARNESS ASSY FRONT A. |
| 7 | Checking +5 VDC power supply to the SENSOR ASSY REG2 (Registration Sensor) on the IOT Is the voltage across P403-13 <=> P403-3 on the PWBA MCU F +5 VDC? | Go to step 8. | Replace the PWBA MCU F. (RRP 8.4) |
| 8 | Checking the SENSOR ASSY REG2 (Registration Sensor) on the IOT for operation <br> Does the voltage across P403-8 <=> P403-3 on the PWBA MCU F change, every time the actuator of the SENSOR ASSY REG2 (Registration Sensor) is operated? | Go to step 16. | Replace the SENSOR ASSY REGI. (RRP 4.13) |
| 9 | Checking the MOTOR ASSY (T/A Motor) for operation Execute [Output 08-11 HCF T/A Motor ( $242 \mathrm{~mm} / \mathrm{s}$ )] in [Diagnosis]. <br> Does the MOTOR ASSY (T/A Motor) rotate normally? | Go to step 16. | Go to step 10. |
| 10 | Checking the HARNESS ASSY MAIN for connection Are PF57 and JF06 of the HARNESS ASSY MAIN connected surely? | Go to step 12. | After reconnecting, go to step 11 |
| 11 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 12. | End of work. |
| 12 | Checking the HARNESS ASSY MAIN for conductivity Disconnect PF57 and JF06 of the HARNESS ASSY MAIN. Check for conductivity at the following: $\begin{aligned} & \text { PF57-7 <=> JF06-11 } \\ & \text { PF57-6 <=> JF06-8 } \\ & \text { PF57-5 <=> JF06-9 } \\ & \text { PF57-4 <=> JF06-10 } \\ & \text { PF57-3 <=> JF06-12 } \\ & \text { PF57-2 <=> JF06-7 } \end{aligned}$ | Go to step 13. | Replace the HARNRESS ASSY MAIN. |


| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 13 | Checking the conductivity (resistance) of the MOTOR <br> ASSY (T/A Motor) <br> Are the conductivity across JF57-3/4(COM) and JF57-1/2/ <br> 5/6 of the MOTOR ASSY (T/A Motor) normal, or are there <br> any resistance without disconnection? | Go to step 14. | Replace the <br> MOTOR ASSY. <br> RRP 13.32) |
| 14 | Checking +24 VDC power supply to the MOTOR ASSY <br> (T/A Motor) <br> Are the voltages across PF06-9 <=> PF04-3, and PF06-10 <br> <=> PF04-3 on the PWB ASSY, +24 VDC? | Go to step 15. | Replace the <br> PWB ASSY. <br> RRP 13.34) |
| 15 | Checking after replacing the MOTOR ASSY (T/A Motor) <br> Replace the MOTOR ASSY (T/A Motor). RRP 13.32) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 16. | End of work. |
| 16 | Checking after replacing the PWB ASSY <br> Replace the PWB ASSY. RRP 13.34) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | End of work. |

## C8-5 HCF F/O Sensor Static Jam

| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLL ASSY FEED (PL 13.5.21) <br> ROLLER ASSY RETARD (PL 13.6.17) <br> ROLLER ASSY TA P (PL 13.7.9) <br> COVER ASSY TOP S (PL 13.7.1) <br> SENSOR ASSY TA (PL 13.7.6) <br> HARNESS ASSY FEEDER (PL 13.5.12) <br> HARNESS ASSY MAIN (PL 13.8.2) <br> HARNESS ASSY XXXX (PL 13.XXX) <br> MOTOR ASSY (PL 13.7.12) <br> MOTOR ASSY HCF (PL 13.4.2) <br> PWB ASSY (PL 13.8.1) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper path <br> Open the COVER ASSY TOP S (PL 13.7.1). <br> Open the FEEDER ASSY UPPER (PL 13.5.1). <br> Are the ROLLER ASSY FEED (PL 13.5.21), ROLLER ASSY RETARD (PL 13.6.17), ROLLER ASSY TA P (PL 13.7.9) and Roller attached on the COVER ASSY TOP S installed correctly? <br> Does they rotate smoothly without wear or/and paper dust? <br> Check these items by turning them with your fingers. Are there any stains such as paper dust on the paper path? | Go to step 2. | Clean or replace the appropriate ROLLER, and clean the paper path. |


| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 2 | Checking the SENSOR ASSY TA (HCF TA Sensor) for operation <br> Execute [Input 08-23 HCF F/O SENSOR] in [Diagnosis]. Open the COVER ASSY TOP S (PL 13.7.1). <br> Does the display on the screen change, every time the actuator of the SENSOR ASSY TA (HCF TA Sensor) is operated? | Go to step 10. | Go to step 3. |
| 3 | Checking the HARNESS ASSY for connection Are PF67 and PF54 of the HARNESS ASSY connected to the SENSOR ASSY TA (HCF TA Sensor) connected surely? | Go to step 4. | After reconnecting, go to step 4. |
| 4 | Checking the HARNESS ASSY MAIN for connection Are PF54 and JF01 of the HARNESS ASSY MAIN connected surely? | Go to step 6. | After reconnecting, go to step 5. |
| 5 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 6. | End of work. |
| 6 | Checking the HARNESS ASSY for conductivity Disconnect PF67 and JF54 of the HARNESS ASSY. Check for conductivity at the following: $\begin{aligned} & \text { PF67-1 <=> JF54-3 } \\ & \text { PF67-2 <=> JF54-2 } \\ & \text { PF67-3 <=> JF54-1 } \end{aligned}$ | Go to step 7. | Replace the HARNESS ASSY. |
| 7 | Checking the HARNESS ASSY MAIN for conductivity Disconnect PF54 and JF01 of the HARNESS ASSY MAIN. Check for conductivity at the following: $\begin{aligned} & \text { PF54-1 <=> JF01-3 } \\ & \text { PF54-2 <=> JF01-2 } \\ & \text { PF54-3 <=> JF01-1 } \end{aligned}$ | Go to step 8. | Replace the HARNESS ASSY MAIN. |
| 8 | Checking +5 VDC power supply to the SENSOR ASSY TA (HCF TA Sensor) Is the voltage across PF01-3 <=> PF01-1 on the PWB ASSY +5 VDC? | Go to step 9. | Replace the PWB ASSY. RRP 13.34) |
| 9 | Checking the SENSOR ASSY TA (HCF TA Sensor) for operation <br> Does the voltage across PF01-2 <=> PF01-1 on the PWB ASSY change, every time the actuator of the SENSOR ASSY TA (HCF TA Sensor) is operated? | Go to step 25. | Replace the SENSOR ASSY. RRP 13.30) |
| 10 | Checking the MOTOR ASSY HCF (Feed Motor) for operation <br> Execute [Output 08-16 HCF FEED MOTOR] in [Diagnosis]. <br> Does the MOTOR ASSY HCF (Feed Motor) rotate normally? | Go to step 18. | Go to step 11. |
| 11 | Checking the HARNESS ASSY FEEDER and HARNESS ASSY MAIN for connection Are PF58 and PF56 of the HARNRESS ASSY FEEDER and HARNESS ASSY MAIN, and JF06 on the PWB ASSY connected surely? | Go to step 13. | After reconnecting, go to step 12. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 12 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 13. | End of work. |
| 13 | Checking the HARNRESS ASSY FEEDER for conductivity Disconnect PF58 and JF56 of the HARNESS ASSY FEEDER. <br> Check for conductivity at the following: <br> PF58-1 <=> JF56-1 <br> PF58-2 <=> JF56-2 <br> PF58-3 <=> JF56-3 <br> PF58-4 <=> JF56-4 <br> PF58-5 <=> JF56-5 <br> PF58-6 <=> JF56-6 | Go to step 14. | Replace the HARNRESS ASSY FEEDER. |
| 14 | Checking the HARNESS ASSY MAIN for conductivity Disconnect PF56 and JF06 of the HARNESS ASSY MAIN. Check for conductivity at the following: $\begin{aligned} & \text { PF56-1 <=> JF06-1 } \\ & \text { PF56-2 <=> JF06-3 } \\ & \text { PF56-3 <=> JF06-2 } \\ & \text { PF56-4 <=> JF06-6 } \\ & \text { PF56-5 <=> JF06-4 } \\ & \text { PF56-6 <=> JF06-5 } \end{aligned}$ | Go to step 15. | Replace the HARNRESS ASSY MAIN |
| 15 | Checking the conductivity (resistance) of the MOTOR ASSY HCF (Feed Motor) <br> Are the conductivity across PF58-2/5(COM) and PF58-1/3/ $4 / 6$ of the MOTOR ASSY HCF (Feed Motor) normal, or are there any resistance without disconnection? | Go to step 16. | Replace the MOTOR ASSY HCF. <br> RRP 13.15) |
| 16 | Checking +24 VDC power supply to the MOTOR ASSY HCF (Feed Motor) <br> Are the voltages across PF06-3 <=> GND, and PF06-4 <=> GND on the PWB ASSY + 24 VDC? | Go to step 17. | Replace the PWB ASSY. RRP 13.34) |
| 17 | Checking after replacing the MOTOR ASSY HCF (Feed Motor) <br> Replace the MOTOR ASSY HCF (Feed Motor). RRP 13.15) <br> Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 25. | End of work. |
| 18 | Checking the MOTOR ASSY (T/A Motor) for operation Execute [Output 08-11 HCF T/A Motor ( $242 \mathrm{~mm} / \mathrm{s}$ )] in [Diagnosis]. <br> Does the MOTOR ASSY (T/A Motor) rotate normally? | Go to step 25. | Go to step 19. |
| 19 | Checking the HARNESS ASSY MAIN for connection Are PF57 and JF06 of the HARNESS ASSY MAIN connected surely? | Go to step 21. | After reconnecting, go to step 20. |
| 20 | Execute [Test Print] in [Diagnosis]. Does the error still occur? | Go to step 21. | End of work. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 21 | Checking the HARNESS ASSY MAIN for conductivity Disconnect PF57 and JF06 of the HARNESS ASSY MAIN. Check for conductivity at the following: $\begin{aligned} & \text { PF57-7 <=> JF06-11 } \\ & \text { PF57-6 <=> JF06-8 } \\ & \text { PF57-5 <=> JF06-9 } \\ & \text { PF57-4 <=> JF06-10 } \\ & \text { PF57-3 <=> JF06-12 } \\ & \text { PF57-2 <=> JF06-7 } \end{aligned}$ | Go to step 22. | Replace the HARNRESS ASSY MAIN. |
| 22 | Checking the conductivity (resistance) of the MOTOR ASSY (T/A Motor) <br> Are the conductivity across JF57-3/4(COM) and JF57-1/2/ 5/6 of the MOTOR ASSY (T/A Motor) normal, or are there any resistance without disconnection? | Go to step 23. | Replace the MOTOR ASSY RRP 13.32) |
| 23 | Checking +24 VDC power supply to the MOTOR ASSY (T/A Motor) <br> Are the voltages across PF06-9 <=> GND, and PF06-10 <=> GND on the PWB ASSY +24 VDC? | Go to step 24. | Replace the PWB ASSY. RRP 13.34) |
| 24 | Checking after replacing the MOTOR ASSY (T/A Motor) Replace the MOTOR ASSY (T/A Motor). RRP 13.32) Execute [Test Print] in [Diagnosis]. <br> Does the error still occur? | Go to step 25. | End of work. |
| 25 | Checking after replacing the PWB ASSY Replace the PWB ASSY. RRP 13.34) Execute [Test Print] in [Diagnosis]. Does the error still occur? | Replace the PWBA MCU F. (RRP 8.4) | End of work. |

## H1-5 HCF Lift Up Fail

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (PL 13.1.4) <br> HARNESS ASSY MAIN (PL 13.8.2) <br> HARNESS ASSY FEEDER (PL 13.5.12) <br> PWB ASSY (PL 13.8.1) <br> KIT CABLE TRAY (PL 13.3.99) <br> SENSOR-PHOTO IN (PL 13.5.16) <br> SOLENOID ASSY (PL 13.4.5) <br> PWBA MCU F (PL 8.1.5) <br> MOTOR ASSY HCF (PL 13.4.2) |  |  |
|  | Checking the SENSOR-PHOTO IN (HCF Level Sensor) <br> for operation <br> Execute [Input 07-17 HCF LEVEL SENSOR] in <br> [Diagnosis]. <br> At the same time, execute [Output 08-41 HCF Nudger <br> Solenoid (High Power)] in [Diagnosis]. <br> Does the display on the screen change, every time [Output <br> 08-41 HCF Nudger Solenoid (High Power)] in [Diagnosis] <br> is operated? | Go to step 9. |  | Go to step 2.


| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 2 | Checking the HARNESS ASSY FEEDER for connection Are PF62 and PF56B of the HARNESS ASSY FEEDER connected securely? | Go to step 3. | After reconnecting, go to step 3. |
| 3 | Checking the HARNESS ASSY MAIN for connection Are PF56B and JF02 of the HARNESS ASSY MAIN connected securely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Does the error still occur when the power is on? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY FEEDER for conductivity Disconnect PF62 and JF56B of the HARNESS ASSY FEEDER. <br> Check for conductivity at the following: $\begin{aligned} & \text { PF62-1 <=> JF56B-6 } \\ & \text { PF62-2 <=> JF56B-5 } \\ & \text { PF62-3 <=> JF56B-4 } \end{aligned}$ | Go to step 6. | Replace the HARNESS ASSY FEEDER. |
| 6 | Checking the HARNESS ASSY MAIN for conductivity Disconnect PF56B and JF02 of the HARNESS ASSY MAIN. <br> Check for conductivity at the following: <br> JF56B-1 <=> JF02-3 <br> JF56B-2 <=> JF02-2 <br> JF56B-3 <=> JF02-1 | Go to step 7. | Replace the HARNESS ASSY MAIN. |
| 7 | Checking +5 VDC power supply to the SENSOR-PHOTO IN (HCF Level Sensor) <br> Is the voltage across PF02-3 <=> PF02-1 on the PWB ASSY +5 VDC? | Go to step 8. | Replace the PWB ASSY. RRP 13.34) |
| 8 | Checking the SENSOR-PHOTO IN (HCF Level Sensor) for operation <br> Open the COVER ASSY TOP S (PL 13.7.1). <br> Open the FEEDER ASSY UPPER (PL 13.5.1). <br> Does the voltage across PF02-2 <=> PF02-1 on the PWB ASSY change, every time a piece of paper is placed into the detection area of the SENSOR-PHOTO IN (HCF Level Sensor)? | Go to step 26. | Replace the SEN-SOR-PHOTO IN. RRP 13.20) |
| 9 | Checking the SOLENOID ASSY (Nudger Solenoid) for operation <br> Execute [Output 08-41 HCF Nudger Solenoid (High <br> Power)] in [Diagnosis]. <br> Does the SOLENOID ASSY activates? | Go to step 18. | Go to step 10. |
| 10 | Checking the HARNESS ASSY FEEDER and HARNESS ASSY MAIN for connection Are PF59 and PF56 of the HARNRESS ASSY FEEDER and HARNESS ASSY MAIN, and JF06 on the PWB ASSY connected surely? | Go to step 12. | After reconnecting, go to step 11. |
| 11 | Does the error still occur when the power is on? | Go to step 12. | End of work. |


| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 12 | Checking the HARNESS ASSY FEEDER for conductivity Disconnect PF59 and JF56A of the HARNESS ASSY FEEDER. <br> Check for conductivity at the following: PF59-2 <=> JF56A-1 PF59-1 <=> JF56A-2 | Go to step 13. | Replace the HARNRESS ASSY FEEDER |
| 13 | Checking the HARNESS ASSY MAIN for conductivity Disconnect PF56A and JF06 of the HARNESS ASSY MAIN. <br> Check for conductivity at the following: <br> PF56A-6 <=> JF06-13 PF56A-5 $<=>$ JF06-14 <br> PF56A-5 <=> JF06-14 | Go to step 14. | Replace the HARNRESS ASSY MAIN. |
| 14 | Checking the conductivity (resistance) of the SOLENOID ASSY (Nudger Solenoid) <br> Is the conductivity across PF59-1 and PF59-2 of the SOLENOID ASSY (Nudger Solenoid) normal, or is there any resistance without disconnection? | Go to step 15. | Replace the SOLENOID ASSY. RRP 13.17) |
| 15 | Checking +24.5 VDC power supply to the SOLENOID ASSY (Nudger Solenoid) <br> Execute [Output 08-41 HCF Nudger Solenoid (High Power)] in [Diagnosis]. <br> Is the voltage across PF06-13 <=> PF06-14 on the PWB ASSY + 24.5 VDC? | Go to step 16. | Replace the PWB ASSY. RRP 13.34) |
| 16 | Checking +13.8 VDC power supply to the SOLENOID ASSY (Nudger Solenoid) <br> Execute [Output 08-51 HCF Nudger Solenoid (Low Power)] in [Diagnosis]. <br> Is the voltage across PF06-13 <=> PF06-14 on the PWB ASSY +13.8 VDC? | Go to step 17. | Replace the PWB ASSY. RRP 13.34) |
| 17 | Checking after replacing the SOLENOID ASSY (Nudger Solenoid) <br> Replace the SOLENOID ASSY (Nudger Solenoid). RRP 13.17) <br> Does the error still occur when the power is on? | Go to step 26. | End of work. |
| 18 | Checking the MOTOR ASSY HCF (Feed Motor) for operation <br> Execute [Output 07-22 HCF LIFTER UP (FEED MOTOR REVERSE)] in [Diagnosis]. <br> Does the Feed Motor rotate reversely and the Tray raise? | Go to step 26. | Go to step 19. |
| 19 | Checking the HARNESS ASSY FEEDER and HARNESS ASSY MAIN for connection Are PF58 and PF56 of the HARNRESS ASSY FEEDER and HARNESS ASSY MAIN, and JF06 on the PWB ASSY connected surely? | Go to step 21. | After reconnecting, go to step 20. |
| 20 | Does the error still occur when the power is on? | Go to step 21. | End of work. |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 21 | Checking the HARNESS ASSY FEEDER for conductivity Disconnect PF58 and JF56 of the HARNESS ASSY FEEDER. <br> Check for conductivity at the following: <br> PF58-1 <=> JF56-1 <br> PF58-2 <=> JF56-2 <br> PF58-3 <=> JF56-3 <br> PF58-4 <=> JF56-4 <br> PF58-5 <=> JF56-5 <br> PF58-6 <=> JF56-6 | Go to step 22. | Replace the HARNRESS ASSY FEEDER. |
| 22 | Checking the HARNESS ASSY MAIN for conductivity Disconnect PF56 and JF06 of the HARNESS ASSY MAIN. Check for conductivity at the following: <br> PF56-1 <=> JF06-1 <br> PF56-2 <=> JF06-3 <br> PF56-3 <=> JF06-2 <br> PF56-4 <=> JF06-6 <br> PF56-5 <=> JF06-4 <br> PF56-6 <=> JF06-5 | Go to step 23. | Replace the HARNRESS ASSY MAIN. |
| 23 | Checking the conductivity (resistance) of the MOTOR ASSY HCF (Feed Motor) <br> Are the conductivity across PF58-2/5(COM) and PF58-1/3/ $4 / 6$ of the MOTOR ASSY HCF (Feed Motor) normal, or are there any resistance without disconnection? | Go to step 24. | Replace the MOTOR ASSY HCF. <br> RRP 13.15) |
| 24 | Checking +24 VDC power supply to the MOTOR ASSY HCF (Feed Motor) <br> Are the voltages across PF06-3 <=> GND, and PF06-4 <=> GND on the PWB ASSY + 24 VDC? | Go to step 25. | Replace the PWB ASSY. RRP 13.34) |
| 25 | Checking after replacing the MOTOR ASSY HCF (Feed Motor) <br> Replace the MOTOR ASSY HCF (Feed Motor). RRP 13.15) <br> Does the error still occur when the power is on? | Go to step 26. | End of work. |
| 26 | Checking after replacing the PWB ASSY <br> Replace the PWB ASSY. RRP 13.34) <br> Does the error still occur when the power is on? | Replace the PWBA MCU F. (RRP 8.4) | End of work. |

## H6-4 HCF NVM R/W Error

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> PWB ASSY (PL 13.8.1) | Go to step 2. | End of work. |
| 1 | Turn off/on several times. <br> Does the error still occur when the power is on? | Checking the PWB ASSY for connection <br> Are the connectors connected to the PWB ASSY surely? | Go to step 4. | | After reconnect- |
| :---: |
| ing the connec- |
| tors, go to step 3. |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 3 | Does the error still occur when the power is on? | Go to step 4. | End of work. |
|  | Reconnect the connectors on the PWB ASSY. <br> Disconnect all the connectors connected to the PWB <br> ASSY and reconnect them. <br> Does the error still occur when the power is on? | Replace the <br> PWB ASSY. <br> RRP 13.34) | End of work. |

## HCF Communication fail

| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Possible causative parts: | Go to step 2. | After reinstalling, <br> go to step 2. |
| 1 | Checking the HCF for installation <br> Is the HCF installed to the printer correctly? | Gurn ON/OFF the power. <br> Does the error still occur when the power is on? | Checking the HCF for connection <br> Are P/J800A, P/J800B, P/J800 and P/J414 connected <br> securely? |
| 4 | Checking conductivity between the PWB ASSY and the <br> PWBA MCU F <br> Is there normal conductivity at the following? <br> P/J800A <=> P/J415 <br> P/J800B <=> P/J415 <br> P/J800 <=> P/J414 | Go to step 4. | End of work. <br> P/J800B, P/J800 <br> and P/J414 <br> surely. |
| 5 | Checking the PWB ASSY for power supply <br> Is the voltage between P800-4 (+) and the ground ( - ) +24 <br> VDC? | Replace the <br> PWB ASSY. RRP <br> 13.34) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## HCF Top Cover Open

| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> PWB ASSY (PL 13.8.1) <br> SWITCH (PL 13.7.3) <br> HARNESS ASSY MAIN (PL 13.8.2) COVER ASSY TOP S (PL 13.7.1) PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the COVER ASSY TOP S for shape Is the actuator of the COVER ASSY TOP enters the sensing area of the SWITCH (PL 13.7.3) (Transport Cover Interlock Switch) damaged? | Go to step 2. | Replace the COVER ASSY TOP S. RRP 13.28) |


| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 2 | Checking the SWITCH (Transport Cover Interlock Switch) for operation <br> Execute [Input 07-23 HCF COVER] in [Diagnosis]. Does the display on the screen change, every time the COVER ASSY TOP S is opened/closed? | Go to step 9. | Go to step 3. |
| 3 | Checking the HARNESS ASSY MAIN for connection Are FS001, FS002 and JF05 of the HARNESS ASSY MAIN connected securely? | Go to step 5. | After reconnecting, go to step 4. |
| 4 | Does the error still occur when the power is on? | Go to step 5. | End of work. |
| 5 | Checking the HARNESS ASSY MAIN for conductivity Disconnect FS001, FS002 and JF05 of the HARNESS ASSY MAIN. <br> Check for conductivity at the following: $\begin{aligned} & \text { FSO02 <=> JF05-2 } \\ & \text { FS001 <=> JF05-1 } \end{aligned}$ | Go to step 6. | Replace the HARNESS ASSY MAIN. |
| 6 | Checking +24 VDC power supply to the SWITCH (Transport Cover Interlock Switch) Is the voltage across PF05-2 <=> PF04-3 on the PWB ASSY + 24 VDC? | Go to step 7. | Replace the PWB ASSY. RRP 13.34) |
| 7 | Checking the SWITCH (Transport Cover Interlock Switch) for operation <br> Does the voltage across PF05-1 <=> PF04-3 on the PWB ASSY change, every time the COVER ASSY TOP S (PL 13.7.1) is opened/closed? | Go to step 8. | Replace the SWITCH. RRP 13.29) |
| 8 | Checking after replacing the SWITCH (Transport Cover Interlock Switch) <br> Replace the SWITCH (Transport Cover Interlock Switch). RRP 13.29) <br> Does the error still occur when the power is on? | Go to step 9. | End of work. |
| 9 | Checking after replacing the PWB ASSY <br> Replace the PWB ASSY. RRP 13.34) <br> Does the error still occur when the power is on? | Replace the PWBA MCU F. (RRP 8.4) | End of work. |

## HCF Home Position S/W Open

| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> PWB ASSY (PL 13.8.1) <br> SW IL ASSY DOCKING (PL 13.7.17) <br> HARNESS ASSY MAIN (PL 13.8.2) <br> PWBA MCU F (PL 8.1.5) | Go to step 2. | After reinstalling, <br> go to step 2. |
| 1 | Checking the HCF for installation <br> Is the HCF installed to the printer correctly? |  |  |


| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 2 | Checking the SW IL ASSY DOCKING (HCF Home Position Switch) for shape <br> Is the SW IL ASSY DOCKING (HCF Home Position Switch) damaged? | Go to step 3. | Replace the SW <br> IL ASSY DOCKING. <br> RRP 13.33) |
| 3 | Checking the SW IL ASSY DOCKING (HCF Home Position Switch) for operation <br> Execute [Input 08-57 HCF SIDE OUT SW] in [Diagnosis]. Does the display on the screen change, every time the SWITCH (Transport Cover Interlock Switch) is pushed/ released? | Go to step 10. | Go to step 4. |
| 4 | Checking the HARNESS ASSY MAIN for connection Are FS003, FSOO4 and JF08 of the HARNESS ASSY MAIN connected securely? | Go to step 6. | After reconnecting, go to step 5. |
| 5 | Does the error still occur when the power is on? | Go to step 6. | End of work. |
| 6 | Checking the HARNESS ASSY MAIN for conductivity Disconnect FSOO3, FSOO4 and JF08 of the HARNESS ASSY MAIN. <br> Check for conductivity at the following: $\begin{aligned} & \text { FSO03 <=> JF08-1 } \\ & \text { FS004 <=> JF08-2 } \end{aligned}$ | Go to step 7. | Replace the HARNESS ASSY MAIN. |
| 7 | Checking +5 VDC power supply to the SW IL ASSY DOCKING (HCF Home Position Switch) Is the voltage across PF08-1 <=> PF04-2 on the PWB ASSY +0 VDC? | Go to step 8. | Replace the PWB ASSY. RRP 13.34) |
| 8 | Checking the SW IL ASSY DOCKING (HCF Home Position Switch) for operation Does the voltage across PF08-2 <=> PF04-3 on the PWB ASSY change, every time the SW IL ASSY DOCKING is pushed? | Go to step 9. | Replace the SW <br> IL ASSY <br> DOCKING. <br> RRP 13.33) |
| 9 | Checking after replacing the SW IL ASSY DOCKING (HCF Home Position Switch) <br> Replace the SW IL ASSY DOCKING (HCF Home Position Switch). RRP 13.33) <br> Does the error still occur when the power is on? | Go to step 10. | End of work. |
| 10 | Checking after replacing the PWB ASSY <br> Replace the PWB ASSY. RRP 13.34) <br> Does the error still occur when the power is on? | Replace the PWBA MCU F. (RRP 8.4) | End of work. |

## Prefeed SENSOR\#3 on JAM (Tray3 paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 14.6.20) <br> ROLLER ASSY (RETARD) (PL 14.6.28) <br> ROLLER ASSY (NUDGER) (PL 14.6.32) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 14.6.2) <br> SENSOR (PRE FEED SENSOR) (PL 14.6.15) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup Does the paper size in use match the size set for the TRAY3? | Go to step 3. | Replace the paper, or change the paper size setup. |
| 3 | Checking the Roll for the TRAY3 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY3 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 14.46/RRP 14.50/ RRP 14.53) |
| 4 | Checking paper position <br> Does the paper touch the SENSOR (PRE FEED SENSOR) of the TRAY3 FEEDER (PL 14.5.1)? <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY3 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR (PRE FEED SENSOR) for the TRAY3? <br> Execute [Input 08-20 PreFEED SENSOR3] in Chapter 2 [Diagnostic]. | Go to step 12. | Go to step 6. |
| 6 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY3 for connection Are P/J103, P/J661B and P/J549B connected surely? | Go to step 7. | Connect P/J103, P/J661B and P/ J549B surely. |
| 7 | Checking conductivity between the SENSOR (PRE FEED SENSOR) for the TRAY3 and the TRAY MODULE PWB Is there conductivity on each wire between P/J103B <=> P/ J549B? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the SENSOR (PRE FEED SENSOR) for the TRAY2 Is the voltage across J103B-1 (+) <=> ground +5 VDC? | Replace the SENSOR (PRE FEED SENSOR) for the TRAY3. (RRP 14.43) | Go to step 9. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 9 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F <br> Are P/J541 and P/J413 connected surely? | Go to step 10. | Connect P/J541 and P/J413 surely. |
| 10 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 11. | Fix open and short circuit. |
| 11 | Checking+24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |
| 12 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 for operation Does the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 operate properly? <br> Execute [Output 08-14 TRAY3 FEED MOTOR] in Chapter 2 [Diagnostic]. | Reconnect the connector on the PWBA MCU F. | Go to step 13. |
| 13 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 for connection Are P/J220B, P/J661B and P/J549B connected surely? | Go to step 14. | Connect P/J220B P/J661B and P/ J549B surely. |
| 14 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the <br> TRAY3 for operation (3) <br> Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the <br> TRAY3 with that for the TRAY4. <br> Does the replaced motor operate properly? <br> Execute [Output 08-14 TRAY3 FEED MOTOR] in Chapter <br> 2 [Diagnostic]. | Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 as it previously was and replace the motor for the TRAY3 with a new one. (RRP 14.34) | Go to step 15. |
| 15 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 for operation (4) Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTORs for the TRAY3 and TRAY4 as they previously were. Checking conductivity between the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 and the TRAY MODULE PWB. Is there conductivity on each wire between P/J220B <=> P/ J549B? | Go to step 16. | Fix open and short circuit. |
| 16 | Checking +24 VDC power supply to the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 <br> Is the voltage across J220-3 (+) <=> ground +24 VDC? | Replace the TRAY 1/2 FEED LIFT UP MOTOR for the TRAY3. (RRP 14.34) | Go to step 9. |

## Tray 3 Feed Out Sensor on JAM (Tray 3 paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 14.6.20) <br> ROLLER ASSY (RETARD) (PL 14.6.28) <br> ROLLER ASSY (NUDGER) (PL 14.6.32) <br> SENSOR (PRE FEED SENSOR) (PL 14.6.15) <br> TRAY 3 FEED OUT SENSOR (PL 14.5.8) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup Does the paper size in use match the size set for the TRAY3? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY3 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? <br> Pull out the TRAY3 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 14.46/RRP 14.50/ RRP 14.53) |
| 4 | Checking paper position Does the paper touch the TRAY3 FEED OUT SENSOR or the SENSOR (PRE FEED SENSOR) of the TRAY 3 FEEDER (PL 14.5.1)? <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking the TRAY 3 FEED OUT SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 3 FEED OUT SENSOR? Execute [Input 08-08 T/A F/03 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it. | Go to step 12. | Go to step 6. |
| 6 | Checking the TRAY 3 FEED OUT SENSOR for connection Are P/J821, P/J841 and P/J548 connected surely? | Go to step 7. | $\begin{aligned} & \text { Connect P/J821, } \\ & \text { P/J841 and P/ } \\ & \text { J548 surely. } \end{aligned}$ |
| 7 | Checking conductivity between the TRAY 3 FEED OUT SENSOR and the TRAY MODULE PWB <br> Is there conductivity on each wire between P/J821 <=> P/ J548? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the TRAY 3 FEED OUT SENSOR <br> Is the voltage across J821-3 (+) <=> ground +5 VDC? | Replace the TRAY 3 FEED OUT SNESOR. <br> (RRP 14.33) | Go to step 9. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 9 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F (1) Are P/J541 and P/J413 connected surely? | Go to step 10. | Connect P/J541 and P/J413 surely. |
| 10 | Checking conductivity between the TRAY MODULE and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 11. | Fix open and short circuit. |
| 11 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |
| 12 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY3 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR (PRE FEED SENSOR) for the TRAY3? <br> Execute [Input 08-20 PreFEED SENSOR3] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it. | Reconnect the connector on the PWBA MCU F. | Go to step 13. |
| 13 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY3 for connection Are P/J103B, P/J661B and P/J549B connected surely? | Go to step 14. | $\begin{aligned} & \text { ConnectP/J103B, } \\ & \text { P/J661B and P/ } \\ & \text { J549B surely. } \end{aligned}$ |
| 14 | Checking conductivity between the SENSOR (PRE FEED SENSOR) for the TRAY3 and the TRAY MODULE PWB Is there conductivity on each wire between P/J103B <=> P/ J549B? | Go to step 15. | Fix open and short circuit. |
| 15 | Checking +5 VDC power supply to the SENSOR for the TRAY2 (PRE FEED SENSOR) <br> Is the voltage across J103B-1 (+) <=> ground +5 VDC? | Replace the SENSOR (PRE FEED SENSOR). (RRP 14.43) | Go to step 16. |
| 16 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F <br> Are P/J541 and P/J413 connected surely? | Go to step 17. | Connect P/J541 and P/J413 surely. |
| 17 | Checking conductivity between the TRAY MODULE and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 18. | Fix open and short circuit. |
| 18 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |

Tray 2 Feed Out Sensor on JAM (Tray 3 paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 14.6.20) <br> ROLLER ASSY (RETARD) (PL 14.6.28) <br> ROLLER ASSY (NUDGER) (PL 14.6.32) <br> SENSOR (PL 4.5.18) <br> TRAY 3 FEED OUT SENSOR (PL 14.5.8) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup <br> Does the paper size in use match the size set for the TRAY3? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY3 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY3 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 14.46/RRP 14.50/ RRP 14.53) |
| 4 | Checking paper position (1) <br> Does the paper touch the SENSOR? <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking paper position (2) <br> Does the paper touch the TRAY 3 FEED SENSOR? Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it (visual check). | Remove the paper. | Go to step 6. |
| 6 | Checking the SENSOR for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches SENSOR? <br> Execute [Input 08-06 FEED OUT\#2 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check it. | Go to step 10. | Go to step 7. |
| 7 | Checking the SENSOR for connection Are P/J105, P/J608 and P/J410 connected surely? | Go to step 8. | Connect P/J105, P/J608 and P/ J410 surely. |
| 8 | Checking conductivity between the SENSOR and the PWBA MCU F <br> Is there conductivity on each wire between P/J105 <=> P/ J410? | Go to step 9. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 9 | Checking +5 VDC power supply to the SENSOR Is the voltage across J105-1 (+) <=> ground +5 VDC? | Replace the SEN- <br> SOR. (RRP 4.15) | Replace the PWBA MCU F. (RRP 8.4) |
| 10 | Checking the TRAY 3 FEED OUT SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 3 FEED OUT SENSOR? Execute [Input 08-20 PreFEED SENSOR3] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it. | Reconnect the connector on the PWBA MCU F. | Go to step 11. |
| 11 | Checking the TRAY 3 FEED OUT SENSOR for connection Are P/J821, P/J841 and P/J548 connected surely? | Go to step 12. | $\begin{aligned} & \text { Connect P/J821, } \\ & \text { P/J841 and P/ } \\ & \text { J548 surely. } \end{aligned}$ |
| 12 | Checking conductivity between the TRAY 3 FEED OUT SENSOR and the TRAY MODULE PWB Is there conductivity on each wire between P/J821 <=> P/ J548? | Go to step 13. | Fix open and short circuit. |
| 13 | Checking +5 VDC power supply to the TRAY 3 FEED OUT SENSOR <br> Is the voltage across J821-3 (+) <=> ground +5 VDC? | Replace the TRAY 3 FEED OUT SNESOR. (RRP 14.33) | Go to step 14. |
| 14 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F Are P/J541 and P/J413 connected surely? | Go to step 15. | Connect P/J541 and P/J413 surely. |
| 15 | Checking conductivity between the TRAY MODULE and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 16. | Fix open and short circuit. |
| 16 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |

Registration Sensor on JAM (Tray3 paper feed)

| Step | Check | Yes | No |
| :--- | :--- | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 14.6.20) <br> ROLLER ASSY (RETARD) (PL 14.6.28) <br> ROLLER ASSY (NUDGER) (PL 14.6.32) <br> SENSOR ASSY REGI (PL 4.5.7) <br> TRAY 3 FEED OUT SENSOR (PL 14.5.8) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition <br> Is the paper in the tray crumpled or damaged? | Replace the <br> paper with a new <br> and dry one. | Go to step 2. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 2 | Checking the paper size setup <br> Does the paper size in use match the size set for the TRAY3? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY3 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY3 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 14.46/RRP 14.50/ RRP 14.53) |
| 4 | Checking paper position (1) <br> Does the paper touch the SENSOR ASSY REGI? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking paper position (2) <br> Does the paper touch the TRAY 3 FEED SENSOR? Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it (visual check). | Remove the paper. | Go to step 6. |
| 6 | Checking the SENSOR ASSY REGI for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR ASSY REGI? Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 10. | Go to step 7. |
| 7 | Checking the SENSOR ASSY REGI for connection Are P/J104 and P/J403B connected surely? | Go to step 8. | Connect P/J104 and P/J403B surely. |
| 8 | Checking conductivity between the SENSOR ASSY REGI and the PWB A MCU F <br> Is there conductivity on each wire between P/J104 <=> P/ J409B? | Go to step 9. | Fix open and short circuit. |
| 9 | Checking +5 VDC power supply to the SENSOR ASSY REGI <br> Is the voltage across J104-1 (+) <=> ground +5 VDC? | Replace the SEN SOR ASSY REGI. (RRP 4.13) | Replace the PWBA MCU F. (RRP 8.4) |
| 10 | Checking the TRAY 3 FEED OUT SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 3 FEED OUT SENSOR? Execute [Input 08-08 T/A F/03 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it. | Reconnect the connector on the PWBA MCU F. | Go to step 11. |
| 11 | Checking the TRAY 3 FEED OUT SENSOR for connection Are P/J821, P/J841 and P/J548 connected surely? | Go to step 12. | Connect P/J821, P/J841 and P/ J548 surely |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 12 | Checking conductivity between the TRAY 3 FEED OUT <br> SENSOR and the TRAY MODULE PWB <br> Is there conductivity on each wire between P/J821 <=> P/ <br> J548? | Go to step 13. | Fix open and <br> short circuit. |
| 13 | Checking +5 VDC power supply to the TRAY 3 FEED OUT <br> Is the voltage across J821-3 (+) <=> ground +5 VDC? | Replace the <br> TRAY 3 FEED <br> OUT SNESOR. <br> (RRP 14.33) | Go to step 14. |
| 14 | Checking connection between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Are P/J541 and P/J413 connected surely? | Go to step 15. <br> Checking conductivity between the TRAY MODULE and <br> Is PWBA MCU F <br> J413? | Connect P/J541 <br> and P/J413 <br> surely. |
| 15 | Checking +24 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across J541-8 (+) <=> ground +24 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP <br> 14.62) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray 4 Feed Out Sensor on JAM (Tray 4 paper feed)

| Step | Check | Yes | No |
| :--- | :--- | :--- | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 14.6.20) <br> ROLLER ASSY (RETARD (PL 14.6.28) <br> ROLLER ASSY (NUDGER) (PL 14.6.32) <br> SENSOR (PRE FEED SENSOR) (PL 14.6.15) <br> TRAY 4 FEED OUT SENSOR (PL 14.4.18) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) | N |  |
| 1 | Checking paper condition <br> Is the paper in the tray crumpled or damaged? | Replace the <br> paper with a new <br> and dry one. | Go to step 2. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 4 | Checking paper position <br> Does the paper touch the SENSOR (PRE FEED SEN- <br> SOR) of the TRAY 4 FEEDER (PL 14.5.1) or the TRAY4 <br> FEED OUT SENSOR? <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and <br> check it (visual check). | Remove the <br> paper. | Go to step 5. |
| 5 | Checking the SENSOR (PRE FEED SENSOR) for the <br> TRAY4 for operation <br> Does the Input Status change from "0x0" to "Ox1" each <br> time the paper touches the SENSOR (PRE FEED SEN- <br> SOR) for the TRAY4? <br> Execute [Input 08-21 PreFEED SENSOR4] in Chapter 2 <br> [Diagnostic]. | Go to step 12. | Go to step 6. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 14 | Checking conductivity between the TRAY 4 FEED OUT SENSOR and the TRAY MODULE PWB <br> Is there conductivity on each wire between P/J825 <=> P/ J548? | Go to step 15. | Fix open and short circuit. |
| 15 | Checking +5 VDC power supply to the TRAY 4 FEED OUT SENSOR <br> Is the voltage across J825-3 (+) <=> ground +5 VDC? | Replace the TRAY 4 FEED OUT SNESOR. (RRP 14.28) | Go to step 16. |
| 16 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F Are P/J541 and P/J413 connected surely? | Go to step 17. | Connect P/J541 and P/J413 surely. |
| 17 | Checking conductivity between the TRAY MODULE and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 18. | Fix open and short circuit. |
| 18 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |

## Tray 3 Feed Out Sensor on JAM (Tray 4 paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 14.6.20) <br> ROLLER ASSY (RETARD) (PL 14.6.28) <br> ROLLER ASSY (NUDGER) (PL 14.6.32) <br> TRAY 3 FEED OUT SENSOR (PL 14.5.8) <br> TRAY 4 FEED OUT SENSOR (PL 14.4.18) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup Does the paper size in use match the size set for the TRAY4? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY4 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) <br> or ROLLER ASSY (NUDGER) for transport worn or con- <br> taminated with paper dust? <br> Pull out the TRAY4 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 14.46/RRP 14.50/ RRP 14.53) |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 4 | Checking paper position <br> Does the paper touch the TRAY 3 FEED OUT SENSOR or the TRAY 4 FEED OUT SENSOR? <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking the TRAY 4 FEED OUT SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 4 FEED OUT SENSOR? Execute [Input 08-09 T/A F/04 SENSOR] in Chapter 2 [Diagnostic]. | Go to step 12. | Go to step 6. |
| 6 | Checking the TRAY 4 FEED OUT SENSOR for connection Are P/J825, P/J842 and P/J548 connected surely? | Go to step 7. | $\begin{aligned} & \text { Connect P/J825, } \\ & \text { P/J842 and P/ } \\ & \text { J548 surely. } \end{aligned}$ |
| 7 | Checking conductivity between the TRAY 4 FEED OUT SENSOR and the TRAY MODULE PWB Is there conductivity on each wire between P/J825 <=> P/ J548? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the TRAY 4 FEED OUT SENSOR <br> Is the voltage across J825-3 (+) <=> ground +5 VDC? | Replace the TRAY 4 FEED OUT SNESOR. (RRP 14.28) | Go to step 9. |
| 9 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F <br> Are P/J541 and P/J413 connected surely? | Go to step 10. | Connect P/J541 and P/J413 surely. |
| 10 | Checking conductivity between the TRAY MODULE and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 11. | Fix open and short circuit. |
| 11 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |
| 12 | Checking the TRAY 3 FEED OUT SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 3 FEED OUT SENSOR? Execute [Input 08-08 T/A F/03 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it. | Reconnect the connector on the PWBA MCU F. | Go to step 13. |
| 13 | Checking the TRAY 3 FEED OUT SENSOR for connection Are P/J821, P/J841 and P/J548 connected surely? | Go to step 14. | $\begin{aligned} & \text { Connect P/J821, } \\ & \text { P/J841 and P/ } \\ & \text { J548 surely. } \end{aligned}$ |
| 14 | Checking conductivity between the TRAY 3 FEED OUT SENSOR and the TRAY MODULE PWB Is there conductivity on each wire between P/J821 <=> P/ J548? | Go to step 15. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 15 | Checking +5 VDC power supply to the TRAY 3 FEED OUT <br> SENSOR <br> Is the voltage across J821-3 $(+)$ <=> ground +5 VDC? | Replace the <br> TRAY 3 FEED <br> OUT SNESOR. <br> (RRP 14.33) | Go to step 16. |
| 16 | Checking connection between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Are P/J541 and P/J413 connected surely? | Go to step 17. | Connect P/J541 <br> and P/J413 <br> surely. |
| 17 | Checking conductivity between the TRAY MODULE and <br> the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ <br> J413? | Go to step 18. | Fix open and <br> short circuit. |
| 18 | Checking +24 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across J541-8 (+) <=> ground +24 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP <br> 14.62) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray 2 Feed Out Sensor on JAM (Tray 3 paper feed) TTM

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 14.6.20) <br> ROLLER ASSY (RETARD) (PL 14.6.28) <br> ROLLER ASSY (NUDGER) (PL 14.6.32) <br> SENSOR (PL 4.5.18) <br> TRAY 3 FEED OUT SENSOR (PL 14.5.8) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking the paper size setup <br> Does the paper size in use match the size set for the TRAY3? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY3 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY3 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 14.46/RRP 14.50/ RRP 14.53) |
| 4 | Checking paper position (1) <br> Does the paper touch the SENSOR? <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check it (visual check). | Remove the paper. | Go to step 5. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 5 | Checking paper position (2) <br> Does the paper touch the TRAY 3 FEED OUT SENSOR? <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it (visual check). | Remove the paper. | Go to step 6. |
| 6 | Checking the SENSOR for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR? <br> Execute [Input 08-06 FEED OUT\#2 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY LH LOW C (PL 4.1.10) and check it. | Go to step 10. | Go to step 7. |
| 7 | Checking the SENSOR for connection Are P/J105, P/J608 and P/J410 connected surely? | Go to step 8. | $\begin{aligned} & \text { Connect P/J105, } \\ & \text { P/J608 and P/ } \\ & \text { J410 surely. } \end{aligned}$ |
| 8 | Checking conductivity between the SENSOR and the PWBA MCU F <br> Is there conductivity on each wire between P/J105 <=> P/ J410? | Go to step 9. | Fix open and short circuit. |
| 9 | Checking +5 VDC power supply to the SENSOR Is the voltage across J105-1 (+) <=> ground +5 VDC? | Replace the SEN- <br> SOR. (RRP 4.15) | Replace the PWBA MCU F. (RRP 8.4) |
| 10 | Checking the TRAY 3 FEED OUT SENSOR for the TRAY 3 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 3 FEED OUT SENSOR for the TRAY3? <br> Execute [Input 08-20 PreFEED SENSOR3] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it. | Reconnect the connector on the PWBA MCU F. | Go to step 11. |
| 11 | Checking the TRAY 3 FEED OUT SENSOR for connection Are P/J821, P/J841 and P/J548 connected surely? | Go to step 12. | $\begin{aligned} & \text { Connect P/J821, } \\ & \text { P/J841 and P/ } \\ & \text { J548 surely. } \end{aligned}$ |
| 12 | Checking conductivity between the TRAY 3 FEED OUT SENSOR and the TRAY MODULE PWB Is there conductivity on each wire between P/J821 <=> P/ J548? | Go to step 13. | Fix open and short circuit. |
| 13 | Checking +5 VDC power supply to the TRAY 3 FEED OUT SENSOR <br> Is the voltage across J821-3 (+) <=> ground +5 VDC? | Replace the TRAY 3 FEED OUT SNESOR. (RRP 14.33) | Go to step 14. |
| 14 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F <br> Are P/J541 and P/J413 connected surely? | Go to step 15. | Connect P/J541 and P/J413 surely? |
| 15 | Checking conductivity between the TRAY MODULE and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 16. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 16 | Checking +24 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across J541-8 (+) <=> ground +24 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP <br> $14.62)$ | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Registration Sensor on JAM (Tray4 paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 14.6.20) <br> ROLLER ASSY (RETARD) (PL 14.6.28) <br> ROLLER ASSY (NUDGER) (PL 14.6.32) <br> SENSOR ASSY REGI (PL 4.5.7) <br> TRAY 4 FEED OUT SENSOR (PL 14.4.18) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup <br> Does the paper size in use match the size set for the TRAY4? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY4 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY4 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 14.46/RRP 14.50/ RRP 14.53) |
| 4 | Checking paper position (1) <br> Does the paper touch the SENSOR ASSY REGI? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 5. |
| 5 | Checking paper position (2) <br> Does the paper touch the TRAY 4 FEED OUT SENSOR? <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it (visual check). | Remove the paper. | Go to step 6. |
| 6 | Checking the SENSOR ASSY REGI for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR ASSY REGI? Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 10. | Go to step 7. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 7 | Checking the SENSOR ASSY REGI for connection Are P/J104 and P/J403B connected surely? | Go to step 8. | Connect P/J104 and P/J403B surely. |
| 8 | Checking conductivity between the SENSOR ASSY REGI and the PWB A MCU F <br> Is there conductivity on each wire between P/J104 <=> P/ J403B? | Go to step 9. | Fix open and short circuit. |
| 9 | Checking +5 VDC power supply to the SENSOR ASSY REGI <br> Is the voltage across J104-1 (+) <=> ground +5 VDC? | Replace the SENSORASSYREGI. (RRP 4.13) | Replace the PWBA MCU F. (RRP 8.4) |
| 10 | Checking the TRAY 4 FEED OUT SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 4 FEED OUT SENSOR? Execute [Input 08-08 T/A F/04 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it. | Reconnect the connector on the PWBA MCU F. | Go to step 11. |
| 11 | Checking the TRAY 4 FEED OUT SENSOR for connection Are P/J825, P/J842 and P/J548 connected surely? | Go to step 12. | Connect P/J825, P/J842 and P/ J548 surely. |
| 12 | Checking conductivity between the TRAY 4 FEED OUT SENSOR and the TRAY MODULE PWB Is there conductivity on each wire between P/J825 <=> P/ J548? | Go to step 13. | Fix open and short circuit. |
| 13 | Checking +5 VDC power supply to the TRAY 4 FEED OUT SENSOR <br> Is the voltage across J821-3 (+) <=> ground +5 VDC? | Replace the TRAY 4 FEED OUT SNESOR. (RRP 14.28) | Go to step 14. |
| 14 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F Are P/J541 and P/J413 connected surely? | Go to step 15. | Connect P/J541 and P/J413 surely. |
| 15 | Checking conductivity between the TRAY MODULE and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 16. | Fix open and short circuit. |
| 16 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |

## Prefeed Sensor \#4 on JAM (Tray4 paper feed)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> ROLLER ASSY (FEED) (PL 14.6.20) <br> ROLLER ASSY (RETARD) (PL 14.6.28) <br> ROLLER ASSY (NUDGER) (PL 14.6.32) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 14.6.2) <br> SENSOR (PRE FEED SENSOR) (PL 14.6.15) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper condition Is the paper in the tray crumpled or damaged? | Replace the paper with a new and dry one. | Go to step 2. |
| 2 | Checking paper size setup <br> Does the paper size in use match the size set for the TRAY4? | Go to step 3. | Replace the paper or change the paper size setup. |
| 3 | Checking the Roll for the TRAY4 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY4 and check it. | Go to step 4. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 14.46/RRP 14.50/ RRP 14.53) |
| 4 | Checking paper position Does the paper touch the SENSOR (PRE FEED SENSOR) of the TRAY4 FEEDER (PL 14.4.15)? | Remove the paper. | Go to step 5. |
| 5 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY4 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR (PRE FEED SENSOR) for the TRAY4? <br> Execute [Input 08-21 PreFEED SENSOR4] in Chapter 2 [Diagnostic]. | Go to step 12. | Go to step 6. |
| 6 | Checking the SENSOR (PRE FEED SENSOR) for the TRAY4 for connection <br> Are P/J103A, P/J661A and P/J549A connected surely? | Go to step 7. | ConnectP/J103A P/J661A and P/ J549A surely. |
| 7 | Checking conductivity between the SENSOR (PRE FEED SENSOR) for the TRAY4 and the TRAY MODULE PWB Is there conductivity on each wire between P/J103A <=> P/ J549A? | Go to step 8. | Fix open and short circuit. |
| 8 | Checking +5 VDC power supply to the SENSOR (PRE FEED SENSOR) for the TRAY4 Is the voltage across J103A-1 (+) <=> ground +5 VDC? | Replace the SENSOR (PRE FEED SENSOR) for the TRAY4. (RRP 14.43) | Go to step 9. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 9 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F <br> Are P/J541 and P/J413 connected surely? | Go to step 10. | Connect P/J541 and P/J413 surely. |
| 10 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 11. | Fix open and short circuit. |
| 11 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J541-8 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |
| 12 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 for operation <br> Does the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 operate properly? <br> Execute [Output 08-15 TRAY4 FEED MOTOR] in Chapter 2 [Diagnostic]. | Reconnect the connector on the PWBA MCU F. | Go to step 13. |
| 13 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 for connection <br> Are P/J220A, P/J661A and P/J549A connected surely? | Go to step 14. | ConnectP/J220A P/J661A and P/ J549A surely. |
| 14 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the <br> TRAY4 for operation (3) <br> Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the <br> TRAY4 with that for the TRAY3. <br> Does the replaced motor operate properly? <br> Execute [Output 08-15 TRAY4 FEED MOTOR] in Chapter <br> 2 [Diagnostic]. | Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 as it previously was and then, replace the motor for the TRAY4 with a new one. (RRP 14.34) | Go to step 15. |
| 15 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 for operation (4) <br> Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTORs for the TRAY3 and TRAY4 as they previously were. <br> Checking conductivity between the TRAY 1/2 FEED LIFT UP MOTOR for the TRAY3 and the TRAY MODULE PWB. Is there conductivity on each wire between P/J220A <=> P/ J549A? | Go to step 16. | Fix open and short circuit. |
| 16 | Checking connection between the TRAY MODULE PWB and the PWBA MCU F Are P/J541 and P/J413 connected surely? | Go to step 17. | Connect P/J541 and P/J413 surely. |
| 17 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 18. | Fix open and short circuit. |
| 18 | Checking +24 VDC power supply to the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 Is the voltage across J220A-3 (+) <=> ground +24 VDC? | Replace the TRAY 1/2 FEED LIFT UP MOTOR for the TRAY4. (RRP 14.34) | Replace the PWBA MCU F. (RRP 8.4) |

## Tray 3 Feed Out Sensor Static JAM

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY 3 FEED OUT SENSOR (PL 14.5.8) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper position <br> Does the paper touch the TRAY 3 FEED SENSOR? Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it (visual check). | Remove the paper. | Go to step 2. |
| 2 | Checking the TRAY 3 FEED OUT SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 3 FEED OUT SENSOR? Execute [Input 08-08 T/A F/03 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it. | Reconnect the connector on the PWBA MCU F. | Go to step 3. |
| 3 | Checking the TRAY 3 FEED OUT SENSOR for connection Are P/J821, P/J841 and P/J548 connected surely? | Go to step 4. | $\begin{aligned} & \text { Connect P/J821, } \\ & \text { P/J841 and P/ } \\ & \text { J548 surely. } \end{aligned}$ |
| 4 | Checking conductivity between the TRAY 3 FEED OUT SENSOR and the TRAY MODULE PWB Is there conductivity on each wire between P/J821 <=> P/ J548? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking conductivity between the TRAY MODULE and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 6. | Fix open and short circuit. |
| 6 | Checking +5 VDC power supply to the TRAY 3 FEED OUT SENSOR <br> Is the voltage across J821-3 (+) <=> ground +5 VDC? | Replace the TRAY 3 FEED OUT SNESOR. (RRP 14.43) | Go to step 7. |
| 7 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J541-5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |

Tray 4 Feed Out Sensor Static JAM

| Step | Check | Yes | No |
| :--- | :--- | :--- | :--- |
|  | Possible causative parts: <br> TRAY 4 FEED OUT SENSOR (PL 14.4.18) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking paper position Does the paper touch the TRAY 4 FEED OUT SENSOR? Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it (visual check). | Remove the paper. | Go to step 2. |
| 2 | Checking the TRAY 4 FEED OUT SENSOR for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the TRAY 4 FEED OUT SENSOR? Execute [Input 08-09 T/A F/04 SENSOR] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it. | Reconnect the connector on the PWBA MCU F. | Go to step 3. |
| 3 | Checking the TRAY 4 FEED OUT SENSOR for connection Are P/J825, P/J842 and P/J548 connected surely? | Go to step 4. | $\begin{aligned} & \text { Connect P/J825, } \\ & \text { P/J842 and P/ } \\ & \text { J548 surely. } \end{aligned}$ |
| 4 | Checking conductivity between the TRAY 4 FEED OUT SENSOR and the TRAY MODULE PWB Is there conductivity on each wire between P/J825 <=> P/ J548? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking conductivity between the TRAY MODULE and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 6. | Fix open and short circuit. |
| 6 | Checking +5 VDC power supply to the TRAY 4 FEED OUT SENSOR <br> Is the voltage across J821-5 (+) <=> ground +5 VDC? | Replace the TRAY 4 FEED OUT SNESOR. (RRP 14.28) | Go to step 7. |
| 7 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J541-5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |

## Tray3 Lift up /No tray fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> GEAR ASSEMBLY (TRAY 3) (PL 14.8.1) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 14.6.2) <br> SENSOR (LEVEL SENSOR) (PL 14.6.14) <br> TRAY 3/4 PAPER SIZE SWITCH (PL 14.4.23) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper <br> Is any paper loaded in the Tray3? <br> Pull out the Tray3 to check it. (Visual check) | Go to step 2. | Load paper. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 2 | Checking the TRAY <br> Are the GEAR ASSEMBLY (TRAY 3) of TRAY3 or the surrounding parts of it damaged? | Go to step 3. | Replace the GEAR ASSEMBLY (TRAY 3) (RRP 14.59) or the obstacles. |
| 3 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 for operation (1) <br> Does the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 operate properly? <br> Execute [Output 08-14 TRAY3 FEED MOTOR] in Chapter 2 [Diagnostic]. | Go to step 11. | Go to step 4. |
| 4 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 for connection Are P/J220B, P/J661B and P/J549B connected surely? | Go to step 5. | $\begin{aligned} & \text { Connect P/J220B, } \\ & \text { P/J661B and P/ } \\ & \text { J549B surely. } \end{aligned}$ |
| 5 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 for operation (2) <br> Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 with that for the TRAY4. <br> Does the replaced motor operate properly? <br> Execute [Output 08-14 TRAY3 FEED MOTOR] in Chapter <br> 2 [Diagnostic]. | Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 as it previously was and replace the motor for the TRAY3 with a new one. (RRP 14.34) | Go to step 6. |
| 6 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 for operation (3) Reinstall the TRAY $1 / 2$ FEED LIFT UP MOTORs for the TRAY3 and TRAY4 as they previously were. Checking conductivity between the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 and the TRAY MODULE PWB. Is there conductivity on each wire between $P / J 220 B<=>P /$ J549B? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +24 VDC power supply to the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3 <br> Is the voltage across J220-3 (+) <=> ground +24 VDC? | Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY3. (RRP 14.34) | Go to step 8. |
| 8 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 9. | Connect P/J413 and $P / 541$ surely. |
| 9 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 10. | Fix open and short circuit. |
| 10 | Checking +24 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J413-B2 (+) <=> ground +24 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 11 | Checking the SENSOR (LEVEL SENSOR) for the TRAY3 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR (LEVEL SENSOR) for the TRAY3? <br> Execute [Input 07-15 TRAY3 LEVEL SENSOR] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it. | Go to step 18. | Go to step 12. |
| 12 | Checking the SENSOR (LEVEL SENSOR) for the TRAY3 for connection <br> Are P/J101B, P/J661B and P/J549B connected surely? | Go to step 13. | Connect P/J101B, P/J661B and P/ J549B surely. |
| 13 | Checking conductivity between the SENSOR (LEVEL SENSOR) for the TRAY3 and the TRAY MODULE PWB Is there conductivity on each wire between P/J101B <=> P/ J549B? | Go to step 14. | Fix open and short circuit. |
| 14 | Checking +5 VDC power supply to the SENSOR (LEVEL SENSOR) for the TRAY3 <br> Is the voltage across J101B-3 (+) <=> ground +5 VDC? | Replace the SENSOR (LEVEL SENSOR) for the TRAY3. (RRP 14.41) | Go to step 15. |
| 15 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 16. | Connect P/J413 and P/541 surely. |
| 16 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 17. | Fix open and short circuit. |
| 17 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J413-A5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |
| 18 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY3 with paper loaded is pulled out or pushed in? <br> Execute [Input 07-03 TRAY3 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Reconnect the connector on the PWBA MCU F. | Go to step 19. |
| 19 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 for connection Are P/J820 and P/J548 connected surely? | Go to step 20. | Connect P/J820 and P/J548 surely. |
| 20 | Checking conductivity between the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 and the PWBA MCU F Is there conductivity on each wire between P/J820 <=> P/ J548? | Go to step 21. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 21 | Checking +3.3 VDC power supply to the TRAY 3/4 PAPER <br> SIZE SWITCH for the TRAY3 <br> Is the voltage across J820-1 (+) <=> ground +3.3 VDC? | Replace the <br> TRAY 3/4 PAPER <br> SIZE SWITCH for <br> the TRAY3. (RRP <br> $14.29)$ | Go to step 22. |

## Tray4 Lift up /No tray fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> GEAR ASSEMBLY (TRAY 4) (PL 14.8.2) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 14.6.2) <br> SENSOR (LEVEL SENSOR) (PL 14.6.14) <br> TRAY 3/4 PAPER SIZE SWITCH (PL 14.4.23) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper <br> Is any paper loaded in the Tray4? <br> Pull out the Tray4 to check it. (Visual check) | Go to step 2. | Load paper. |
| 2 | Checking the TRAY <br> Are the GEAR ASSEMBLY (TRAY 4) of TRAY4 or the surrounding parts of it damaged? | Go to step 3. | Replace the GEAR ASSEMBLY (TRAY 4) (RRP 14.60) or the obstacles. |
| 3 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 for operation <br> Does the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 operate properly? <br> Execute [Output 08-15 TRAY4 FEED MOTOR] in Chapter 2 [Diagnostic]. | Go to step 11. | Go to step 4. |
| 4 | Checking the TRAY $1 / 2$ FEED LIFT UP MOTOR for the TRAY4 for connection Are P/J220A, P/J661A and P/J549A connected surely? | Go to step 5. | Connect P/J220A, P/J661A and P/ J549A surely. |


| Step | Check | Yes | No |
| :--- | :--- | :--- | :---: |
| 5 | Checking the TRAY 1/2 FEED LIFT UP MOTOR for the <br> TRAY4 for operation (3) <br> Replace the TRAY 1/2 FEED LIFT UP MOTOR for the <br> TRAY4 with that for the TRAY3. <br> Does the replaced motor operate properly? <br> Execute [Output 08-15 TRAY4 FEED MOTOR] in Chapter <br> 2 [Diagnostic]. | Reinstall the <br> TRAY 1/2 FEED <br> LIFT UP MOTOR <br> for the TRAY3 as <br> it previously was <br> and then, replace <br> the motor for the <br> TRAY4 with a <br> new one. (RRP <br> 14.34) | Go to step 6. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 14 | Checking +5 VDC power supply to the SENSOR (LEVEL SENSOR) for the TRAY4 <br> Is the voltage across J101A-3 (+) <=> ground +5 VDC? | Replace the SENSOR (LEVEL SENSOR) for the TRAY4. (RRP 14.41) | Go to step 15. |
| 15 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 16. | Connect P/J413 and $P / 541$ surely. |
| 16 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 17. | Fix open and short circuit. |
| 17 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J413-A5 ( + ) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |
| 18 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY4 with paper loaded is pulled out or pushed in? <br> Execute [Input 07-04 TRAY4 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Reconnect the connector on the PWBA MCU F. | Go to step 19. |
| 19 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 for connection Are P/J824 and P/J548 connected surely | Go to step 20. | Connect P/J824 and P/J548 surely. |
| 20 | Checking conductivity between the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 and the PWBA MCU F Is there conductivity on each wire between P/J824 <=> P/ J548? | Go to step 21. | Fix open and short circuit. |
| 21 | Checking +3.3 V DC power supply to the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 Is the voltage across J824-1 (+) <=> ground +3.3 VDC? | Replace the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4. (RRP 14.30) | Go to step 22. |
| 22 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 23. | Connect P/J413 and P/541 surely. |
| 23 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 24. | Fix open and short circuit. |
| 24 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J413-A5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |

## Tray 3 cassette Size fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY 3/4 PAPER SIZE SWITCH (PL 14.4.23) <br> FRONT SIDE GUIDE (PL 14.2.14) <br> REAR SIDE GUIDE (PL 14.2.18) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper (1) <br> Is paper loaded in the TRAY3 properly? <br> Pull out the TRAY3 to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the paper (2) <br> Are the FRONT SIDE GUIDE and REAR SIDE GUIDE of the TRAY3 set correctly? <br> Pull out the TRAY3 to check it. (Visual check) | Go to step 3. | Set the parts properly. |
| 3 | Checking the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 for installation <br> Is the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 installed properly? <br> Pull out the TRAY3 to check it. (Visual check) | Go to step 4. | Install the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 correctly. (RRP 14.29) |
| 4 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY3 with paper loaded is pulled out or pushed in? <br> Execute [Input 07-03 TRAY3 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Reconnect the connector on the PWBA MCU F. | Go to step 5. |
| 5 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 for connection Are P/J820 and P/J548 connected surely? | Go to step 6. | ```Connect P/J820 and P/J548 surely.``` |
| 6 | Checking conductivity between the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 and the PWBA MCU F Is there conductivity on each wire between P/J820 <=> P/ J548? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +3.3 VDC power supply to the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 <br> Is the voltage across J820-1 (+) <=> ground +3.3 VDC? | Replace the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3. (RRP 14.29) | Go to step 8. |
| 8 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 9. | Connect P/J413 and P/541 surely. |
| 9 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 10. | Fix open and short circuit. |
| 10 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J413-A5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. <br> (RRP 8.4) |

## Tray 4 cassette Size fail

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY 3/4 PAPER SIZE SWITCH (PL 14.4.23) <br> FRONT SIDE GUIDE (PL 14.3.12) <br> REAR SIDE GUIDE (PL 14.3.27) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper (1) <br> Is paper loaded in the TRAY4 properly? <br> Pull out the TRAY4 to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the paper (2) <br> Are the FRONT SIDE GUIDE and REAR SIDE GUIDE of the TRAY4 set correctly? <br> Pull out the TRAY4 to check it. (Visual check) | Go to step 3. | Set the parts properly. |
| 3 | Checking the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 for installation <br> Is the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 installed properly? <br> Pull out the TRAY4 to check it. (RRP) (Visual check) | Go to step 4. | Install the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 correctly (RRP 14.30) |
| 4 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY4 with paper loaded is pulled out or pushed in? <br> Execute [Input 07-04 TRAY4 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Reconnect the connector on the PWBA MCU F. | Go to step 5. |
| 5 | Checking the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 for connection Are P/J824 and P/J548 connected surely? | Go to step 6. | ```Connect P/J824 and P/J548 surely.``` |
| 6 | Checking conductivity between the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 and the PWBA MCU F Is there conductivity on each wire between P/J824 <=> P/ J548? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking+3.3 VDC power supply to the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 <br> Is the voltage across J824-1 (+) <=> ground +3.3 VDC? | Replace the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4. (RRP 14.30) | Go to step 8. |
| 8 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 9. | Connect P/J413 and P/541 surely. |
| 9 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 10. | Fix open and short circuit. |
| 10 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J413-A5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. <br> (RRP 8.4) |

## Tray Module NVM out-of-order

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) | Go to step 3. | Go to step 2. |
| 1 | Does Error occur when the power is turned ON? | Go to step 3. | End of work *1 |
| 2 | Does the error still occur after the power is turned ON/OFF <br> repeatedly several times? | Go to step 4. | Go to step 5. |
| 3 | Checking data on the NVRAM (1) <br> Is data on the NVRAM accessible? <br> Execute [NVM Edit] in Chapter 2 [Diagnostic]. | Checking data on the NVRAM (2) <br> Change NVRAM data to the correct setup value, and then <br> turn the power ON again. <br> Does an error still occur? | Go to step 5. |
| 5 | Checking the TRAY MODULE PWB for connection <br> Are P/J413 and P/J541 connected surely? | End of work |  |
| 6 | Checking conductivity between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ <br> J541? | Go to step 7. | Connect P/J413 <br> and P/J541 <br> surely. |
| 7 | Fhecking open and <br> short circuit. <br> PWB <br> Is the voltage across J413-A5 (+) <=> ground +5 VDC? |  |  |

*1: External noise is considered to be the cause. Proceed to Procedure 5.1.
Tray Module NVM R/W error

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) | Go to step 3. | Go to step 2. |
| 1 | Does the error still occur when the power is turned ON <br> again? | Go to step 3. | End of work *1 |
| 2 | Does the error still occur after the power is turned ON/OFF <br> repeatedly several times? | Go to step 4. | Go to step 5. |
| 3 | Checking data on the NVRAM (1) <br> Is data on the NVRAM accessible? <br> Execute [NVM Edit] in Chapter 2 [Diagnostic]. | Go to step 5. | End of work |
| 4 | Checking data on the NVRAM (2) <br> Change NVRAM data to the correct setup value, and then <br> turn the power ON again. <br> Does the error still occur? |  |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 5 | Checking the TRAY MODULE PWB for connection <br> Are P/J413 and P/J541 connected surely? | Go to step 6. | Connect P/J413 <br> and P/J541 <br> surely. |
| 6 | Checking conductivity between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ <br> J541? | Go to step 7. | Fix open and <br> short circuit. |
| 7 | Checking +5 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across J413-A5 (+) <=> ground +5 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP <br> 14.62) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray Module Communication fail

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) | Checking the TRAY MODULE for installation <br> Disconnect the connector P/J541 of the TRAY MODULE <br> and reconnect it. <br> Does the tray module operate properly? | End of work |
| 2 | Checking the TRAY MODULE PWB for connection <br> Is P/J413 connected surely? | Go to step 2. |  |
| 3 | Checking conductivity between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ <br> J541? | Go to step 4. | Fix open and <br> short circuit. |
| 4 | Checking +5 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across J413-A5 (+) <=> ground +5 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP <br> 14.62) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## TM type error

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) | End of work | Go to step 2. |
| 1 | Checking the TRAY MODULE for installation <br> Disconnect the connector P/J541 of the TRAY MODULE <br> and reconnect it. <br> Does the tray module operate properly? |  |  |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 2 | Checking the TRAY MODULE PWB for connection <br> Is P/J413 connected surely? | Go to step 3. | Connect P/J413 <br> surely. |
| 3 | Checking conductivity between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ <br> J541? | Go to step 4. | Fix open and <br> short circuit. |
| 4 | Checking +5 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across J413-A5 (+) <=> ground +5 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP <br> 14.62) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray3 Size sensor broken

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY 3/4 PAPER SIZE SWITCH (PL 14.4.23) TRAY MODULE PWB (PL 14.8.5) PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper <br> Is paper loaded in the Tray3 properly? <br> Pull out the Tray3 to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 for installation <br> Is the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 installed correctly? <br> Pull out the TRAY3 to check it. (Visual check) | Go to step 3. | Reinstall the TRAY 3/4 PAPER SIZE SWITCH for TRAY3. |
| 3 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 for operation Does the Input Status change each time the TRAY3 with paper loaded is pulled out and pushed in? <br> Check it using [Input 07-03 TRAY3 SIZE SENSOR] in Chapter 2, Diag. | Reconnect the connector of the PWBA MCU F. | Go to step 4. |
| 4 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for TRAY3 for connection Are P/J820 and P/J548 connected surely? | Go to step 5. | Connect P/J820 and P/J548 securely |
| 5 | Checking conductivity between the TRAY $3 / 4$ PAPER SIZE SWITCH for TRAY3 and the PWBA MCU F Is there conductivity on each wire between P/J820 <=> P/ P/J548? | Go to step 6. | Fix open and short circuit. |
| 6 | Checking +5 VDC power supply to the TRAY 3/4 PAPER SIZE SWITCH for TRAY3 Is the voltage across J820-1 (+) <=> ground +5 VDC? | Replace the TRAY 3/4 PAPER SIZE SWITCH for TRAY3. (RRP 14.29) | Go to step 7. |
| 7 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 8. | Connect P/J413 and P/J541 surely. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 8 | Checking conductivity between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ <br> J541? | Go to step 9. | Fix open and <br> short circuit. |
| 9 | Checking +5 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across J413-A5 (+) <=> ground +5 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP <br> 14.62) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray4 Size sensor broken

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SWITCH ASSY P S (PL 2.1.4) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper Is paper loaded in the Tray4 properly? Pull out the Tray4 to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 for installation <br> Is the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 installed correctly? <br> Pull out the TRAY4 to check it. (Visual check) | Go to step 3. | Reinstall the TRAY 3/4 PAPER SIZE SWITCH for TRAY4. |
| 3 | Checking the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 for operation <br> Does the Input Status change each time the TRAY4 with paper loaded is pulled out and pushed in? <br> Check it using [Input 07-04 TRAY4 SIZE SENSOR] in Chapter 2, Diag. | Reconnect the connector of the PWBA MCU F. | Go to step 4. |
| 4 | Checking the TRAY 3/4 PAPER SIZE SWITCH for TRAY4 for connection <br> Are P/J824 and P/J548 connected surely? | Go to step 5. | Connect P/J824 <br> and P/J548 securely |
| 5 | Checking conductivity between the TRAY 3/4 PAPER SIZE SWITCH for TRAY4 and the PWBA MCU F Is there conductivity on each wire between P/J824 <=> P/ P/J548? | Go to step 6. | Fix open and short circuit. |
| 6 | Checking +5 VDC power supply to the TRAY $3 / 4$ PAPER SIZE SWITCH for TRAY4 <br> Is the voltage across J824-1 (+) <=> ground +5 VDC? | Replace the TRAY 3/4 PAPER SIZE SWITCH for TRAY4. (RRP 14.30) | Go to step 7. |
| 7 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 8. | Connect P/J413 and P/J541 surely. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 8 | Checking conductivity between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ <br> J541? | Go to step 9. | Fix open and <br> short circuit. |
| 9 | Checking +5 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across J413-A5 (+) <=> ground +5 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP <br> 14.62) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## TM Cover open

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> LEFT COVER INTERLOCK SWITCH (PL 14.7.15) PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the LEFT COVER ASSEMBLY (PL 14.7.1) for opening and closing <br> Does the LEFT COVER ASSEMBLY (PL 14.7.1) open or close normally? | Go to step 2. | Check the LEFT COVER ASSMEBLY for deformation and reinstall it. |
| 2 | Checking the LEFT COVER INTERLOCK SWITCH for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the LEFT COVER INTERLOCK SWITCH is pressed? Execute [Input 01-10 TRAY MODULE COVER] in Chapter 2 [Diagnostic]. <br> Open the LEFT COVER ASSEMBLY (PL 14.7.1) and check it. | Reconnect the connector on the PWBA MCU F. | Go to step 3. |
| 3 | Checking the LEFT COVER INTERLOCK SWITCH for connection <br> Are FS812, FS813 and P/J554 connected surely? | Go to step 4. | Connect FS812, FS813 and P/ J554 surely. |
| 4 | Checking conductivity between the LEFT COVER INTERLOCK SWITCH and the TRAY MODULE PWB <br> Is there conductivity on each wire between FS812 <=> P/ J554? <br> Is there conductivity on each wire between FS813 <=> P/ J554? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking +24 VDC power supply to the LEFT COVER INTERLOCK SWITCH <br> Is the voltage across J813-1 (+) <=> ground +24 VDC? | Replace the LEFT COVER INTERLOCK SWITCH. (RRP 14.58) | Go to step 6. |
| 6 | Checking the TRAY MODULE PWB for connection Are P/J541 and P/J413 connected surely? | Go to step 7. | Connect P/J541 and P/J413 surely. |
| 7 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J541 <=> P/ J413? | Go to step 8. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 8 | Checking +24 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across J541-8 (+) <=> ground +24 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP <br> $14.62)$ | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## No paper in the select paper tray

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> SENSOR (NO PAPER SENSOR) (PL 14.6.14) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking paper <br> Is Paper loaded in the selected TRAY? | Go to step 2. | Load paper. |
| 2 | Checking the SENSOR (NO PAPER SENSOR) for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY with paper loaded is pulled out or pushed in? <br> For TRAY3: <br> Execute [Input 07-09 TRAY3 NO PAPER SENSOR] in Chapter 2 [Diagnostic]. <br> For TRAY4: <br> Execute [Input 07-10 TRAY4 NO PAPER SENSOR] in Chapter 2 [Diagnostic]. | Reconnect the connector on the PWBA MCU F. | Go to step 3. |
| 3 | Checking the SENSOR (NO PAPER SENSOR) for connection <br> For TRAY3: <br> Are P/J102B, P/J661B and P/J549B connected surely? <br> For TRAY4: <br> Are P/J102A, P/J661A and P/J549A connected surely? | Go to step 4. | Connect the connectors surely. |
| 4 | Checking conductivity between the SENSOR (NO PAPER SENSOR) and the PWBA MCU F <br> For TRAY3: <br> Is there conductivity on each wire between P/J102B <=> P/ J549B? <br> For TRAY4: <br> Is there conductivity on each wire between P/J102A <=> P/ J549A? | Go to step 5. | Fix open and short circuit. |
| 5 | Checking +5 VDC power supply to the SENSOR (NO PAPER SENSOR) <br> For TRAY3: <br> Is the voltage across J102B-3 (+) <=> ground +5 VDC? <br> For TRAY4: <br> Is the voltage across J102A-3 (+) <=> ground +5 VDC? | Replace the SENSOR (NO PAPER SENSOR) for the TRAY. (RRP 14.42) | Go to step 6. |
| 6 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 7. | Connect P/J413 and P/541 surely. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 7 | Checking conductivity between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ <br> J541? | Go to step 8. | Fix open and <br> short circuit. |
| 8 | Checking +5 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across J413-A5 (+) <=> ground +5 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP <br> 14.62) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Paper size mismatch in width

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY 3/4 PAPER SIZE SWITCH (PL 14.4.23) <br> FRONT SIDE GUIDE (PL 14.2.14) <br> REAR SIDE GUIDE (PL 14.2.18) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper (1) <br> Is paper loaded in the Tray properly? <br> Pull out the TRAY to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the paper (2) <br> Are the FRONT SIDE GUIDE and REAR SIDE GUIDE of the TRAY3 or TRAY4 set correctly? <br> Pull out the TRAYs to check it. (Visual check) | Go to step 3. | Set the parts correctly. |
| 3 | Checking the TRAY 3/4 PAPER SIZE SWITCH for installation <br> Is the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 or TRAY4 installed properly? <br> Pull out the TRAY to check it. (Visual check) | Go to step 4. | Install the TRAY 3/4 PAPER SIZE SWITCH for each TRAY correctly. (RRP 14.29/RRP 14.30) |
| 4 | Checking the TRAY 3/4 PAPER SIZE SWITCH for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY with paper loaded is pulled out or pushed in? <br> For TRAY3: <br> Execute [Input 07-03 TRAY3 SIZE SENSOR] in Chapter 2 <br> [Diagnostic]. <br> For TRAY4: <br> Execute [Input 07-04 TRAY4 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Reconnect the connector on the PWBA MCU F. | Go to step 5. |
| 5 | Checking the TRAY 3/4 PAPER SIZE SWITCH for connection <br> For TRAY3: <br> Are P/J820 and P/J548 connected surely? <br> For TRAY4 <br> Are P/J824 and P/J548 connected surely? | Go to step 6. | Connect the connectors surely. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 6 | Checking conductivity between the TRAY 3/4 PAPER <br> SIZE SWITCH and the TRAY MODULE PWB <br> For TRAY3: <br> Is there conductivity on each wire between P/J820 <=> P/ <br> J548? <br> For TRAY4 <br> Is there conductivity on each wire between P/J824 <=> P/ <br> J548? | Go to step 7. | Fix open and <br> short circuit. |
| 7 | Checking +3.3 VDC power supply to the TRAY 3/4 PAPER <br> SIZE SWITCH <br> For TRAY3: <br> Is the voltage across J820-1 (+) <=> ground +3.3 VDC? <br> For TRAY4 <br> Is the voltage across J824-1 (+) <=> ground +3.3 VDC? | Replace the <br> TRAY 3/4 PAPER <br> SIZE SWITCH for <br> the TRAY. (RRP <br> 14.29/RRP 14.30) | Go to step 8. |
| 8 | Checking the TRAY MODULE PWB for connection <br> Are P/J413 and P/J541 connected surely? | Go to step 9. | Connect P/J413 <br> and P/541 surely. |
| 9 | Checking conductivity between the TRAY MODULE PWB <br> and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ <br> J541? | Go to step 10. | Fix open and <br> short circuit. |
| 10 | Checking +5 VDC power supply to the TRAY MODULE <br> PWB <br> Is the voltage across J413-A5 (+) <=> ground +5 VDC? | Replace the <br> TRAY MODULE <br> PWB. (RRP <br> 14.62) | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |

## Tray 3 Paper size mismatch in length

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY 3/4 PAPER SIZE SWITCH (PL 14.4.23) <br> FRONT SIDE GUIDE (PL 14.2.14) <br> REAR SIDE GUIDE (PL 14.2.18) <br> SENSOR ASSY REGI (PL 4.5.7) <br> CLUTCH ASSY REGI (PL 4.5.5) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper (1) <br> Is paper loaded in the TRAY3 properly? <br> Pull out the TRAY3 to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the paper (2) <br> Are the FRONT SIDE GUIDE and REAR SIDE GUIDE of the TRAY3 set correctly? <br> Pull out the TRAY3 to check it. (Visual check) | Go to step 3. | Set the parts properly. |
| 3 | Checking the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 for operation <br> Is the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 installed properly? <br> Pull out the TRAY3 to check it. (Visual check) | Go to step 4. | Install the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3 correctly. (RRP 14.29) |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 4 | Checking the TRAY 3/4 PAPER SIZE SWITCH for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY3 with paper loaded is pulled out or pushed in? <br> Execute [Input 07-03 TRAY3 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Go to step 11. | Go to step 5. |
| 5 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 for connection Are P/J820 and P/J548 connected surely? | Go to step 6. | Connect P/J820 and P/J548 surely. |
| 6 | Checking conductivity between the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 and the TRAY MODULE PWB <br> Is there conductivity on each wire between $\mathrm{P} / \mathrm{J} 820$ <=> P/ J548? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +3.3 VDC power supply to the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY3 <br> Is the voltage across J820-1 (+) <=> ground +3.3 VDC? | Replace the TRAY 3/4 PAPER SIZE SWITCH for the TRAY3. (RRP 14.29) | Go to step 8. |
| 8 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 9. | Connect P/J413 and $P / 541$ surely. |
| 9 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 10. | Fix open and short circuit. |
| 10 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J413-A5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |
| 11 | Checking the Roll for the TRAY3 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY3 and check it. | Go to step 12. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 14.46/RRP 14.50/ RRP 14.53) |
| 12 | Checking paper position <br> Does the paper touch the SENSOR ASSY REGI? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 13. |
| 13 | Checking the Roll (1) Is the ROLLER ASSY-TA for transport worn or contaminated with paper dust? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 14. | ```Clean or replace the ROLLER ASSY-TA. (RRP 4.3)``` |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 14 | Checking the Roll (2) <br> Is the ROLLER of the TRANS ASSY REGI for transport (PL 4.5.1) worn or contaminated with paper dust? Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 15. | Clean or replace the TRANS ASSY REGI. (RRP 4.10) |
| 15 | Checking the SENSOR ASSY REGI for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR ASSY REGI? Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 19. | Go to step 16. |
| 16 | Checking the SENSOR ASSY REGI for connection Are P/J104 and P/J403B connected surely? | Go to step 17. | Connect P/J104 and P/J403B surely. |
| 17 | Checking conductivity between the SENSOR ASSY REGI and the PWB A MCU <br> Is there conductivity on each wire between P/J104 <=> P/ J403B? | Go to step 18. | Fix open and short circuit. |
| 18 | Checking+5 VDC power supply to the SENSOR ASSY REGI <br> Is the voltage across J104-1 (+) <=> ground +5 VDC? | Replace the SENSOR ASSYREGI. (RRP 4.13) | Replace the PWBA MCU F. (RRP 8.4) |
| 19 | Checking the CLUTCH ASSY REGI H for operation Does the CLUTCH ASSY REGI H operate properly? Execute [Output 08-39 REGI CLUTCH (EXIT)] in Chapter 2 [Diagnostic]. | Reconnect the connector on the PWBA MCU F. | Go to step 20. |
| 20 | Checking the CLUTCH ASSY REGI H for connection Are P/J215 and P/J403B connected surely? | Go to step 21. | Connect P/J215 and P/J403B surely. |
| 21 | Checking conductivity between the CLUTCH ASSY REGI H and the PWB A MCU F Is there conductivity on each wire between P/J215 <=> P/ J403B? | Go to step 22. | Fix open and short circuit. |
| 22 | Checking +24 VDC power supply to the CLUTCH ASSY REGI H <br> Is the voltage across P215-2 (+) <=> ground +24 VDC? | Go to step 23. | Replace the PWBA MCU F. (RRP 8.4) |
| 23 | Checking the resistance of the CLUTCH ASSY REGI H Is the resistance across J215-1 <=> J215-2 approximately 240 ohm? | Replace the PWBA MCU F. (RRP 8.4) | Replace the CLUTCH ASSY REGI H. (RRP 4.11) |

## Tray 4 Paper size mismatch in length

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> TRAY 3/4 PAPER SIZE SWITCH (PL 14.4.23) <br> FRONT SIDE GUIDE (PL 14.2.14) <br> REAR SIDE GUIDE (PL 14.2.18) <br> SENSOR ASSY REGI (PL 4.5.7) <br> CLUTCH ASSY REGI (PL 4.5.5) <br> TRAY MODULE PWB (PL 14.8.5) <br> PWBA MCU F (PL 8.1.5) |  |  |
| 1 | Checking the paper (1) <br> Is paper loaded in the TRAY4 properly? <br> Pull out the TRAY4 to check it. (Visual check) | Go to step 2. | Load paper properly. |
| 2 | Checking the paper (2) <br> Are the FRONT SIDE GUIDE and REAR SIDE GUIDE of the TRAY4 set correctly? <br> Pull out the TRAY4 to check it. (Visual check) | Go to step 3. | Set the parts properly. |
| 3 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 for installation <br> Is the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 installed properly? <br> Pull out the TRAY4 to check it. (Visual check) | Go to step 4. | Install the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 correctly. (RRP 14.30) |
| 4 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the <br> TRAY4 for operation <br> Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the TRAY4 is pulled out or pushed in, when the TRAY4 is loaded with paper? <br> Execute [Input 07-04 TRAY4 SIZE SENSOR] in Chapter 2 [Diagnostic]. | Go to step 11. | Go to step 5. |
| 5 | Checking the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 for connection Are P/J824 and P/J548 connected surely? | Go to step 6. | Connect P/J824 and P/J548 surely. |
| 6 | Checking conductivity between the TRAY $3 / 4$ PAPER SIZE SWITCH for the TRAY4 and the TRAY MODULE PWB <br> Is there conductivity on each wire between P/J824 <=> P/ J548? | Go to step 7. | Fix open and short circuit. |
| 7 | Checking +3.3 VDC power supply to the TRAY 3/4 PAPER SIZE SWITCH for the TRAY4 <br> Is the voltage across J824-1 (+) <=> ground +3.3 VDC? | Replace the TRAY 3/4 PAPER SIZE SWITCH for the STRAY4. (RRP 14.30) | Go to step 8. |
| 8 | Checking the TRAY MODULE PWB for connection Are P/J413 and P/J541 connected surely? | Go to step 9. | Connect P/J413 and P/541 surely. |
| 9 | Checking conductivity between the TRAY MODULE PWB and the PWBA MCU F <br> Is there conductivity on each wire between P/J413 <=> P/ J541? | Go to step 10. | Fix open and short circuit. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 10 | Checking +5 VDC power supply to the TRAY MODULE PWB <br> Is the voltage across J413-A5 (+) <=> ground +5 VDC? | Replace the TRAY MODULE PWB. (RRP 14.62) | Replace the PWBA MCU F. (RRP 8.4) |
| 11 | Checking the Roll for the TRAY4 <br> Is the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER) for transport worn or contaminated with paper dust? Pull out the TRAY4 and check it. | Go to step 12. | Clean or replace the ROLLER ASSY (FEED), ROLLER ASSY (RETARD) or ROLLER ASSY (NUDGER). (RRP 14.46/RRP 14.50/ RRP 14.53)) |
| 12 | Checking paper position <br> Does the paper touch the SENSOR ASSY REGI? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it (visual check). | Remove the paper. | Go to step 13. |
| 13 | Checking the Roll (1) <br> Is the ROLLER ASSY-TA for transport worn or contami- <br> nated with paper dust? <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 14. | Clean or replace the ROLLER ASSY-TA. (RRP 4.3) |
| 14 | Checking the Roll (2) <br> Is the ROLLER of the TRANS ASSY REGI for transport (PL 4.5.1) worn or contaminated with paper dust? Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 15. | Clean or replace the TRANS ASSY REGI. <br> (RRP 4.10) |
| 15 | Checking the SENSOR ASSY REGI for operation Does the Input Status change from " $0 \times 0$ " to " $0 \times 1$ " each time the paper touches the SENSOR ASSY REGI? Execute [Input 08-05 REGI SENSOR] in Chapter 2 [Diagnostic]. <br> Open the COVER ASSY-LH (PL 4.2.8) and check it. | Go to step 19. | Go to step 16. |
| 16 | Checking the SENSOR ASSY REGI for connection Are P/J104 and P/J403B connected surely? | Go to step 17. | Connect P/J104 and P/J403B surely. |
| 17 | Checking conductivity between the SENSOR ASSY REGI and the PWB A MCU <br> Is there conductivity on each wire between P/J104 <=> P/ J403B? | Go to step 18. | Fix open and short circuit. |
| 18 | Checking +5 VDC power supply to the SENSOR ASSY REGI <br> Is the voltage across J104-1 (+) <=> ground +5 VDC? | Replace the SENSOR ASSYREGI. (RRP 4.13) | Replace the PWBA MCU F. (RRP 8.4) |
| 19 | Checking the CLUTCH ASSY REGI H for operation Does the CLUTCH ASSY REGI H operate properly? Execute [Output 08-39 REGI CLUTCH (EXIT)] in Chapter 2 [Diagnostic]. | Reconnect the connector on the PWBA MCU F. | Go to step 20. |
| 20 | Checking the CLUTCH ASSY REGI H for connection Are P/J215 and P/J403B connected surely? | Go to step 21. | Connect P/J215 and P/J403B surely. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 21 | Checking conductivity between the CLUTCH ASSY REGI <br> H and the PWB A MCU <br> Is there conductivity on each wire between P/J215 <=> P/ <br> J403B? | Go to step 22. | Fix open and <br> short circuit. |
| 22 | Checking +24 VDC power supply to the CLUTCH ASSY <br> REGI H <br> Is the voltage across P215-2 (+) <=> ground +24 VDC? | Go to step 23. | Replace the <br> PWBA MCU F. <br> (RRP 8.4) |
| 23 | Checking the resistance of the CLUTCH ASSY REGI H <br> Is the resistance across J215-1 and J215-2 approximately <br> 240 ohm? | Replace the <br> PWBA MCU F. <br> (RRP 8.4) | Replace the <br> CLUTCH ASSY <br> REGI H. (RRP <br> 4.11) |

## Image Quality Trouble

## Entry Chart for Image Quality Troubleshooting

## NOTE By printing a test print with the engine only, isolating problems between the Printer

 Controller or the engine can usually be diagnosed easily.- Test print result with the engine only is normal. ---> Malfunction on Printer Controller side
- Test print result with the engine only is also abnormal. ---> Malfunction on the engine side When it is the case of [Malfunction on Printer Controller side], replace with normal Printer Controller and normal Interface Cable, and check.
When the trouble still occurs after replacement, check the host side, and then perform troubleshooting using the following image quality FIP according to each phenomenon.
When the image quality trouble of print occurs, get a print to judge, understand and treat the trouble substance precisely and appropriately, and then troubleshoot efficiently, using the image quality FIP table according to each phenomenon.

When trouble restoration with image quality FIP is not possible, check again with the image quality FIP, and then replace [ESS and possible causative parts] in order and check, and operate Troubleshooting, using [Chapter 2 Diagnostic].

Image quality FIP states regarding the typical image quality trouble, as follows.

- FIP-1.P1 Faint print (Low contrast)
- FIP-1.P2 Blank print (No print)
- FIP-1.P3 Solid black
- FIP-1.P4 Vertical blank lines (White stripes in paper transport direction)
- FIP-1.P5 Horizontal band cross out
- FIP-1.P6 Vertical stripes
- FIP-1.P7 Horizontal stripes
- FIP-1.P8 Partial lack
- FIP-1.P9 Spots
- FIP-1.P10 Afterimage
- FIP-1.P11 Background (Fog)
- FIP-1.P12 Skew
- FIP-1.P13 Paper damage
- FIP-1.P14 No fix

NOTE When horizontal lines and/or spots occur periodically, it is possibly caused by a particular roll. In this case, measure the interval on the test print, and check the relation to the rolls in the machine. The interval does not necessarily match circumference of the roll. The trouble may be solved easily by the check.

### 18.1 Image Quality FIP

## Faint print (Low contrast)



Trouble substance
The density of the image is entirely too faint.
Possible causative parts

- CRU (PL 5.1.15)
- TONER CARTRIDGE (PL 5.1.16)
- PWBA MCU F (PL 8.1.5)
- HSG ASSY-BTR (PL 4.2.1)
- PSHV-Y2 (PL 8.1.1)
- PWBA ESS (PL 8.1.25)

Before starting troubleshooting, check the paper transfer route. Check that there is no foreign article, such as staples, paper clips and paper scraps, in the route.

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking paper condition <br> Load new, dry recommended paper, and perform Test <br> Print. <br> Is the density of the image normal? | End of work | Go to step 2. |
| 2 | Checking the TONER CARTRIDGE <br> Install a new TONER CARTRIDGE. <br> Re-print the defective image. <br> Is the image density normal? | End of work | Go to step 3. |
| 3 | Checking the HSG ASSY-BTR <br> Remove the HSG ASSY-BTR. (RRP 4.7) <br> Check the HSG ASSY-BTR for contamination and wear. <br> Is there any contamination or wear on the HSG ASSY- <br> BTR? | Go to step 4. | Replace the HSG <br> ASSY-BTR (RRP <br> $4.7)$. |
| 4 | Checking the CRU installation condition <br> Remove the CRU. <br> Check the CRU SWITCH on the printer side. <br> Check the CRU SWITCH pins for contamination or defor- <br> mation. | Go to step 5. | Correct and clean <br> defective pins or <br> replace the <br> switch. |
| 5 | Checking the CRU ground <br> Remove the CRU. <br> Check the Earth Plate located behind the CRU. <br> Is the Earth Plate contaminated or deformed? | Go to step 6. | Correct and clean <br> Earth Plate or <br> replace the CRU. |
|  | Checking image development process <br> Perform Test Print, and turn off the power of the printer <br> while printing. <br> Carefully remove the TONER CARTRIDGE, and check the <br> toner image formed on the drum right before the transfer <br> unit (BTR). <br> Is the image completely formed on the drum? <br> Is the area clear and black, and easy to read? | Go to step 7. | Go to step 9. <br> Git |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 7 | Checking image transfer process <br> Check the toner image formed on the drum, right after the <br> transfer unit (BTR). <br> Is the toner image completely transferred on the paper? | Go to step 8. | Go to step 9. |
| 8 | Checking the PSHV-Y2 <br> Replace the PSHV-Y2 (RRP 8.1). <br> Perform Test Print. <br> Is the trouble rectified? | End of work | Go to step 9. |
| 9 | Checking the PWBA MCU F <br> Replace the PWBA MCU F (RRP 8.4). <br> Perform Test Print. <br> Is the trouble rectified? | End of work | Replace the <br> PWBA ESS. |

## Blank print (No print)



Trouble substance
The entire paper is printed pure white.
Possible causative parts

- ROS ASSY-12 (PL 5.1.14)
- CRU (PL 5.1.15)
- TONER CARTRIDGE (PL 5.1.16)
- PWBA MCU F (PL 8.1.5)
- HSG ASSY-BTR (PL 4.2.1)
- PSHV-Y2 (PL 8.1.1)
- PWBA ESS (PL 8.1.25)

Before commencing troubleshooting, check the paper transfer course. Make sure there is no foreign articles on the transfer course, such as staples, paper clips, scraps of paper and so on.

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking the TONER CARTRIDGE <br> Install a new TONER CARTRIDGE. <br> Re-print the defective image. <br> Is the image density normal? | End of work | Go to step 2. |
| 2 | Checking the HSG ASSY-BTR <br> Remove the HSG ASSY-BTR (RRP 4.7). <br> Check the HSG ASSY-BTR for contamination and wear. <br> Is there any contamination or wear on the HSG ASSY- <br> BTR? | Go to step 3. | Replace the HSG <br> ASSY-BTR (RRP <br> $4.7)$. |
| 3 | Checking the CRU installation condition <br> Remove the CRU. <br> Check the CRU SWITCH on the printer side. <br> Check the CRU SWITCH pins for contamination or defor- <br> mation. | Go to step 4. | Correct and clean <br> defective pins or <br> replace the <br> switch. |


| Step | $\quad$ Check | Yes | No |
| :---: | :--- | :--- | :--- |
| 4 | Checking the CRU ground <br> Remove the CRU. <br> Check the Earth Plate located behind the CRU. <br> Is the Earth Plate contaminated or deformed? | Go to step 5. | Correct and clean <br> the Earth Plate or <br> replace the CRU. |
|  | Checking laser beam route <br> Check that there is no obstacle between the ROS ASSY- <br> 12 and the Drum. <br> Check the ROS ASSY-12 window for contamination. <br> Is there any obstacle on the laser beam route? <br> Is the ROS ASSY-12 window normal? | Go to step 6. | Remove obsta- <br> cles or clean the <br> ROS ASSY-12 <br> window. |
| 6 | Checking the ROS ASSY-12 installation (1) <br> Is the ROS ASSY-12 installed securely with four screws? | Go to step 8. | Go to step 7. |
| 7 | Checking the ROS ASSY-12 installation (2) <br> Install the ROS ASSY-12 securely and then perform Test <br> Print. <br> Is the trouble rectified? | End of work | Go to step 8. |
| 8 | Checking the ROSS ASSY-12 for connection <br> Are P/J130, P/J620 and P/J406 connected surely? <br> Warning! Be careful not to apply too much force to the <br> board when checking it or it can cause a ROS alignment <br> displacement. | Go to step 9. | Connect P/J130, <br> P/J620 and P/ <br> J406 surely. |
| 12 | Checking image development process <br> Perform Test Print, and turn off the power of the printer <br> while printing. <br> Carefully remove the TONER CARTRIDGE, and check the <br> toner image formed on the drum right before the transfer <br> unit (BTR). <br> Carefully remove the TONER CARTRIDGE, and check the <br> toner image formed on the drum right before the transfer <br> unit (BTR). <br> Is the image completely formed on the drum? Is the area <br> clear and black, and easy to read? | Go to step 10. | Go to step 11. |
| 10 | Checking image transfer process <br> Check the toner image formed on the drum right after the <br> transfer unit (BTR). <br> Perform Test Print. <br> Is the trouble rectified? | Go to step 11. | Go to step 12. |
| Is the toner image completely transferred on the paper? |  |  |  |

## Solid black



Before commencing troubleshooting, check the paper transfer course. Make sure there is no foreign articles on the transfer course, such as staples, paper clips, scraps of paper and so on.

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking the TONER CARTRIDGE <br> Install a new TONER CARTRIDGE. <br> Re-print the defective image. <br> Is the image density normal? | End of work <br> 2 | Checking the PSHV-Y2 <br> Replace the PSHV-Y2 (RRP 8.1). <br> Perform Test Print. <br> Is the trouble rectified? |
| 3 | Checking the PWBA MCU F to step 2. <br> Replace the PWBA MCU F (RRP 8.4). <br> Perform Test Print. <br> Is the trouble rectified? | End of work |  | Go to step 3. $\quad$ End of work | Replace the |
| :--- |
| PWBA ESS. |

## Vertical blank lines (White stripes in paper transport direction)



Trouble substance
There are some extremely faint or completely non-printed parts. Those non-printed parts cover a wide area vertically, along the paper feeding direction.
Possible causative parts

- TONER CARTRIDGE (PL 5.1.16)
- HSG ASSY-BTR (PL 4.2.1)
- ROS ASSY-12 (PL 5.1.14)
- FUSER ASSY (PL 6.1.7)
- PWBA MCU F (PL 8.1.5)
- PWBA ESS (PL 8.1.25)

Before commencing troubleshooting, check the paper transfer course. Make sure there is no foreign articles on the transfer course, such as staples, paper clips, scraps of paper and so on.

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Checking paper condition Load new and dry recommended paper. Re-print the defective image. Is the problem still occurs? | Go to step 2. | End of work |
| 2 | Checking paper transfer route Check the paper router for contamination or obstacles. Is there any obstacle on the paper route? | Go to step 3. | Remove obstacles or contamination. |
| 3 | Checking laser beam route Check that there is no obstacle between the ROS ASSY12 and the Drum. <br> Check the ROS ASSY-12 window for contamination. Is there any obstacle on the laser beam route? Is the ROS ASSY-12 window normal? | Go to step 4. | Remove obstacles or clean the ROS ASSY-12 window. |
| 4 | Checking the ROS ASSY-12 installation (1) Is the ROS ASSY-12 installed securely with four screws? | Go to step 6. | Go to step 5. |
| 5 | Checking the ROS ASSY-12 installation (2) Install the ROS ASSY-12 securely and then perform Test Print. <br> Is the trouble rectified? | End of work | Go to step 6. |
| 6 | Checking the TONER CARTRIDGE Install a new TONER CARTRIDGE. Re-print the defective image. Is the image density normal? | End of work | Go to step 7. |
| 7 | Checking the HSG ASSY-BTR <br> Remove the HSG ASSY-BTR (RRP 4.7). <br> Check the HSG ASSY-BTR for contamination and wear. Is there any contamination or wear on the HSG ASSYBTR? | Go to step 8. | Replace the HSG ASSY-BTR (RRP 4.7). |
| 8 | Checking the Heat Roll and Pressure Roll Remove the FUSER ASSY (RRP 6.2). <br> WARNING! Start the operation after the FUSER ASSY has cooled down. <br> Is there any contamination or crack on Heat Roll or Pressure Roll? | Replace the FUSER ASSY (RRP 6.2). | Go to step 9. |
| 9 | Checking the PWBA MCU F Replace the PWBA MCU F (RRP 8.4). Perform Test Print. Is the trouble rectified? | End of work | Go to step 10. |
| 10 | Checking the ROSS ASSY-12 for connection Are P/J130, P/J620 and P/J406 connected surely? Warning! Be careful not to apply too much force to the board when checking it or it can cause a ROS alignment displacement. | Replace the PWBA ESS. | ```Connect P/J130, P/J620 and P/ J406 surely.``` |

## Horizontal band cross out



Trouble substance
There are some extremely faint or completely non-printed parts. The non-printed parts cover a wide area perpendicular to the paper feed direction.
Possible causative parts

- CRU (PL 5.1.15)
- TONER CARTRIDGE (PL 5.1.16)
- HSG ASSY-BTR (PL 4.2.1)
- ROS ASSY-12 (PL 5.1.14)
- FUSER ASSY (PL 6.1.7)
- PWBA MCU F (PL 8.1.5)
- PWBA ESS (PL 8.1.25)

Before commencing troubleshooting, check the paper transfer course. Make sure there is no foreign articles on the transfer course, such as staples, paper clips, scraps of paper and so on.

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking paper condition <br> Load new and dry recommended paper. <br> Re-print the defective image. <br> Is the problem still occurs? | Go to step 2. | End of work |
| 2 | Checking paper transfer route <br> Check the paper router for contamination or obstacles. <br> Is there any obstacle on the paper route? | Go to step 3. | Remove obsta- <br> cles or contami- <br> nation. |
| 3 | Checking the TONER CARTRIDGE <br> Install a new TONER CARTRIDGE. <br> Re-print the defective image. <br> Is the image density normal? | End of work | Go to step 4. |
| 4 | Checking the HSG ASSY-BTR <br> Remove the HSG ASSY-BTR (RRP 4.7). <br> Check the HSG ASSY-BTR for contamination and wear. <br> Is there any contamination or wear on the HSG ASSY- <br> BTR? | Go to step 5. | Replace the HSG <br> ASSY-BTR (RRP <br> 4.7). |
| 5 | Checking white-band pitch <br> Is the white-band pitch approximately. 78 mm (Heat Roll <br> circumference)? | Go to step 9. | Go to step 6. |
| 6 | Checking the Heat Roll and Pressure Roll <br> Remove the FUSER ASSY (RRP 6.2). <br> WARNING! Start the operation after the FUSER ASSY has <br> cooled down.the <br> Is there any contamination or crack on Heat Roll and/or the <br> Pressure Roll? | Replace the <br> FUSER ASSY <br> (RRP 6.2). | Go to step 7. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 7 | Checking image development process <br> Perform Test Print, and turn off the power of the printer <br> while printing. <br> Carefully remove the TONER CARTRIDGE, and check the <br> toner image formed on the drum right before the transfer <br> unit (BTR). <br> Is the image completely formed on the drum? Is the area <br> clear and black, and easy to read? | Go to step 8. | Go to step 9. |
| 8 | Checking image transfer process <br> Check the toner image formed on the drum just after the <br> transfer unit (BTR) passed. <br> Is the toner image completely transferred on the paper? | Go to step 9. | Go to step 10. |
| 9 | Checking the PSHV-Y2 <br> Replace the PSHV-Y2 (RRP 8.1). <br> Perform Test Print. <br> Is the trouble rectified? | End of work | Go to step 10. |
| 10 | Checking the PWBA MCU F <br> Replace the PWBA MCU F (RRP 8.4). <br> Perform Test Print. |  |  |
| Is the trouble rectified? |  |  |  |$\quad$ End of work $\quad$ Replace the | PWBA ESS. |
| :--- |

## Vertical stripes



Trouble substance
There are vertical black stripes along the longer side of the paper.
Possible causative parts

- TONER CARTRIDGE (PL 5.1.16)
- HSG ASSY-BTR (PL 4.2.1)
- ROS ASSY-12 (PL 5.1.14)
- FUSER ASSY (PL 6.1.7)
- PWBA MCU F (PL 8.1.5)
- PWBA ESS (PL 8.1.25)

Before commencing troubleshooting, check the paper transfer course. Make sure there is no foreign articles on the transfer course, such as staples, paper clips, scraps of paper and so on.

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking paper condition <br> Load new and dry recommended paper. <br> Re-print the defective image. <br> Is the problem still occurs? | Go to step 2. | End of work |
| 2 | Checking paper transfer route <br> Check the paper router for contamination or obstacles. <br> Is there any obstacle on the paper route? | Go to step 3. | Remove obsta- <br> cles or contami- <br> nation. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 3 | Checking the TONER CARTRIDGE Install a new TONER CARTRIDGE. Re-print the defective image. Is the image density normal? | End of work | Go to step 4. |
| 4 | Checking the HSG ASSY-BTR <br> Remove the HSG ASSY-BTR (RRP 4.7). <br> Check the HSG ASSY-BTR for contamination and wear. <br> Is there any contamination or wear on the HSG ASSYBTR? | Go to step 5. | Replace the HSG ASSY-BTR (RRP 4.7). |
| 5 | Checking the CRU installation condition Remove the CRU. <br> Check the CRU SWITCH on the printer side. Check the CRU SWITCH pins for contamination or deformation. | Go to step 5. | Correct and clean defective pins or replace the switch. |
| 6 | Checking the CRU ground Remove the CRU. Check the Earth Plate located behind the CRU. Is the Earth Plate contaminated or deformed? | Go to step 6. | Correct and clean Earth Plate or replace the CRU. |
| 7 | Checking laser beam route <br> Check that there is no obstacle between the ROS ASSY12 and the Drum. <br> Check the ROS ASSY-12 window for contamination. Is there any obstacle on the laser beam route? <br> Is the ROS ASSY-12 window normal? | Go to step 4. | Remove obstacles or clean the ROS ASSY-12 window. |
| 8 | Checking the Heat Roll and Pressure Roll <br> Remove the FUSER ASSY (RRP 6.2). <br> WARNING! Start the operation after the FUSER ASSY has cooled down. <br> Is there any contamination or crack on Heat Roll and/or Pressure Roll? | Replace the FUSER ASSY (RRP 6.2). | Go to step 9. |
| 9 | Checking the PWBA MCU F <br> Replace the PWBA MCU F (RRP 8.4). <br> Perform Test Print. <br> Is the trouble rectified? | End of work | Replace the PWBA ESS. |

## Horizontal stripes



Trouble substance
There are horizontal black stripes along the shorter side of the paper.
Possible causative parts

- CRU ((PL 5.1.15)
- TONER CARTRIDGE (PL 5.1.16)
- HSG ASSY-BTR (PL 4.2.1)
- ROS ASSY-12 (PL 5.1.14)
- FUSER ASSY (PL 6.1.7)
- PWBA MCU F (PL 8.1.5)
- PWBA ESS (PL 8.1.25)

Before commencing troubleshooting, check the paper transfer course. Make sure there is no foreign articles on the transfer course, such as staples, paper clips, scraps of paper and so on.

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking paper condition <br> Load new and dry recommended paper. <br> Re-print the defective image. <br> Is the problem still occurs? | Go to step 2. | End of work |
| 2 | Checking paper transfer route <br> Check the paper router for contamination or obstacles. <br> Is there any obstacle on the paper route? | Go to step 3. | Remove obsta- <br> cles or contami- <br> nation. |
| 3 | Checking the TONER CARTRIDGE <br> Install a new TONER CARTRIDGE. <br> Re-print the defective image. <br> Is the image density normal? | End of work | Go to step 4. |
| 4 | Checking the HSG ASSY-BTR <br> Remove the HSG ASSY-BTR (RRP 4.7). <br> Check the HSG ASSY-BTR for contamination and wear. <br> Is there any contamination or wear on the HSG ASSY- <br> BTR? | Go to step 5. | Replace the HSG <br> ASSY-BTR (RRP |
| 5 | Checking white-band pitch <br> Is the white-band pitch approximately. 78 mm (Heat Roll <br> circumference)? | Go to step 9. |  | Go to step 6.


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 11 | Checking the ROSS ASSY-12 for connection <br> Are P/J130, P/J620 and P/J406 connected surely? <br> Warning! Be careful not to apply too much force to the <br> board when checking it or it can cause a ROS alignment <br> displacement. | Replace the <br> PWBA ESS. | Connect P/J130, <br> P/J620 and P/ <br> J406 surely. |

## Partial lack of Image



Trouble substance
There are some extremely faint or completely missing parts. Those missing parts are dotted in a limited area on the paper.
Possible causative parts

- TONER CARTRIDGE (PL 5.1.16)
- HSG ASSY-BTR (PL 4.2.1)
- FUSER ASSY (PL 6.1.7)
- PWBA MCU F (PL 8.1.5)
- PWBA ESS (PL 8.1.25)

Before commencing troubleshooting, check the paper transfer course. Make sure there is no foreign articles on the transfer course, such as staples, paper clips, scraps of paper and so on.

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking paper condition <br> Load new and dry recommended paper. <br> Re-print the defective image. <br> Is the problem still occurs? | Go to step 2. | End of work |
| 2 | Checking paper transfer route <br> Check the paper router for contamination or obstacles. <br> Is there any obstacle on the paper route? | Go to step 3. | Remove obsta- <br> cles or contami- <br> nation. |
| 3 | Checking the TONER CARTRIDGE <br> Install a new TONER CARTRIDGE. <br> Re-print the defective image. <br> Is the image density normal? | End of work | Go to step 4. |
| 4 | Checking the HSG ASSY-BTR <br> Remove the HSG ASSY-BTR (RRP 4.7). <br> Check the HSG ASSY-BTR for contamination and wear. <br> Is there any contamination or wear on the HSG ASSY- <br> BTR? | Go to step 5. | Replace the HSG <br> ASSY-BTR (RRP <br> 4.7). |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 5 | Checking the Heat Roll and the Pressure Roll <br> Remove the FUSER ASSY (RRP 6.2). <br> WARNING! Start the operation after the FUSER ASSY has <br> cooled down. <br> Is there any contamination or crack on the Heat Roll and/or <br> the Pressure Roll? | Replace the <br> FUSER ASSY <br> (RRP 6.2). | Go to step 6. |
| 6 | Checking the PWBA MCU F <br> Replace the PWBA MCU F (RRP 8.4). <br> Perform Test Print. <br> Is the trouble rectified? | End of work | Replace the <br> PWBA ESS. |

## Spots



Trouble substance
There are toner spots all over the paper disorderedly.
Possible causative parts

- TONER CARTRIDGE (PL 5.1.16)
- HSG ASSY-BTR (PL 4.2.1)
- FUSER ASSY (PL 6.1.7)
- PWBA MCU F (PL 8.1.5)
- PWBA ESS (PL 8.1.25)

Before commencing troubleshooting, check the paper transfer course. Make sure there is no foreign articles on the transfer course, such as staples, paper clips, scraps of paper and so on.

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking paper condition <br> Load new and dry recommended paper. <br> Re-print the defective image. <br> Is the problem still occurs? | Go to step 2. | End of work |
| 2 | Checking paper transfer route <br> Check the paper router for contamination or obstacles. <br> Is there any obstacle on the paper route? | Go to step 3. | Remove obsta- <br> cles or contami- <br> nation. |
| 3 | Checking the TONER CARTRIDGE <br> Install a new TONER CARTRIDGE. <br> Re-print the defective image. <br> Is the image density normal? | End of work | Go to step 4. |
| 4 | Checking the HSG ASSY-BTR <br> Remove the HSG ASSY-BTR (RRP 4.7). <br> Check the HSG ASSY-BTR for contamination and wear. <br> Is there any contamination or wear on the HSG ASSY- <br> BTR? | Go to step 5. | Replace the HSG <br> ASSY-BTR (RRP <br> 4.7). |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 5 | Checking the Heat Roll and the Pressure Roll <br> Remove the FUSER ASSY (RRP 6.2). <br> WARNING! Start the operation after the FUSER ASSY has <br> cooled down. <br> Is there any contamination or crack on the Heat Roll and/or <br> the Pressure Roll? | Replace the <br> FUSER ASSY <br> (RRP 6.2). | Go to step 6. |
| 6 | Checking the PWBA MCU F <br> Replace the PWBA MCU F (RRP 8.4). <br> Perform Test Print. <br> Is the trouble rectified? | End of work | Replace the <br> PWBA ESS. |

## Afterimage



Trouble substance
The ghost appears on the paper. The ghost may be the image of the previous page, or a part of the page currently printing.
Possible causative parts

- TONER CARTRIDGE (PL 5.1.16)
- FUSER ASSY (PL 6.1.7)
- PWBA MCU F (PL 8.1.5)
- PWBA ESS (PL 8.1.25)

Before commencing troubleshooting, check the paper transfer course. Make sure there is no foreign articles on the transfer course, such as staples, paper clips, scraps of paper and so on.

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking repeated printing <br> Check the afterimage. <br> Is the client printing a copy of the same image in large <br> quantity? | Go to step 2. | Go to step 3. |
| 2 | Print 30 pages of every kind of image. <br> Does the afterimage still appear? | Go to step 3. | End of work (Do <br> not make a copy <br> of the same <br> image in large <br> quantity.) |
| 3 | Checking paper condition <br> Load new and dry recommended paper. <br> Re-print the defective image. <br> Is the problem still occurs? | Go to step 4. | End of work |
| 4 | Checking the TONER CARTRIDGE <br> Install a new TONER CARTRIDGE. <br> Re-print the defective image. <br> Is the image density normal? | End of work | Go to step 5. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 5 | Checking the Heat Roll and the Pressure Roll <br> Remove the FUSER ASSY (RRP 6.2). <br> WARNING! Start the operation after the FUSER ASSY has <br> cooled down. <br> Is there any contamination or crack on Heat Roll and/or <br> Pressure Roll? | Replace the <br> FUSER ASSY <br> (RRP 6.2). | Go to step 6. |
| 6 | Checking the PWBA MCU F <br> Replace the PWBA MCU F (RRP 8.4). <br> Perform Test Print. <br> Is the trouble rectified? | End of work | Replace the <br> PWBA ESS. |

## Background (Fog)



## Trouble substance

There is toner stain all over or a part of the page. The stain appears as very bright gray stain.
Possible causative parts

- TONER CARTRIDGE (PL 5.1.16)
- HSG ASSY-BTR (PL 4.2.1)
- PSHV-Y2 (PL 8.1.1)
- PWBA MCU F (PL 8.1.5)
- PWBA ESS (PL 8.1.25)

Before commencing troubleshooting, check the paper transfer course. Make sure there is no foreign articles on the transfer course, such as staples, paper clips, scraps of paper and so on.

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking paper condition <br> Load new and dry recommended paper. <br> Re-print the defective image. <br> Is the problem still occurs? | Go to step 2. | End of work |
| 2 | Checking paper transfer route <br> Check the paper router for contamination or obstacles. <br> Is there any obstacle on the paper route? | Go to step 3. | Remove obsta- <br> cles or contami- <br> nation. |
| 3 | Checking the TONER CARTRIDGE <br> Install a new TONER CARTRIDGE. <br> Re-print the defective image. <br> Is the image density normal? | End of work | Go to step 4. |
| 4 | Checking the HSG ASSY-BTR <br> Remove the HSG ASSY-BTR (RRP 4.7). <br> Check the HSG ASSY-BTR for contamination and wear. <br> Is there any contamination or wear on the HSG ASSY- <br> BTR? | Go to step 5. | Replace the HSG <br> ASSY-BTR (RRP <br> 4.7). |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 5 | Checking image development process <br> Perform Test Print, and turn off the power of the printer <br> while printing. <br> Carefully remove the TONER CARTRIDGE, and check the <br> toner image formed on the drum just before the transfer <br> unit (BTR). <br> Is the image completely formed on the drum? <br> Is the area clear and black, and easy to read? | Go to step 6. | Go to step 7. |
| 6 | Checking image transfer process <br> Check the toner image formed on the drum just after the <br> transfer unit (BTR) passed. <br> Is the toner image completely transferred on the paper? | Go to step 7. | Go to step 8. |
| 7 | Checking the PSHV-Y2 <br> Replace the PSHV-Y2 (RRP 8.1). <br> Perform Test Print. <br> Is the trouble rectified? | End of work | Go to step 8. |
| 8 | Checking the PWBA MCU F <br> Replace the PWBA MCU F (RRP 8.4). <br> Perform Test Print. <br> Is the trouble rectified? | End of work | Replace the |

## Skew



Trouble substance
The printed image is not paralleled with both sides of the paper.
Possible causative parts

- CRU ((PL 5.1.15)
- TONER CARTRIDGE (PL 5.1.16)
- PWBA MCU F (PL 8.1.5)
- PWBA ESS (PL 8.1.25)
- TRAY ASSY (PL 2.1.3)

Before commencing troubleshooting, check the paper transfer course. Make sure there is no foreign articles on the transfer course, such as staples, paper clips, scraps of paper and so on.

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking installation place <br> Check the installation surface for irregularities. <br> Check for any missing Foot. <br> Is the setup surface normal? | Go to step 2. | Correct the instal- <br> lation place. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 2 | Load paper on the TRAY ASSY properly. <br> Install the TRAY ASSY properly to the printer. <br> Re-print the defective image. <br> Does the problem still occur? | Go to step 3. | End of work |
| 3 | Checking paper transfer route <br> Check the paper router for contamination or obstacles. <br> Is there any obstacle on the paper route? | Go to step 4. | Remove obsta- <br> cles or contami- <br> nation. |
| 4 | Checking rollers on the paper transfer route <br> Check all rollers on the entire route for contamination, wear <br> or damage. <br> Check whether pinch rollers rotate freely and spring pres- <br> sure is applied evenly. Is there any contamination, wear or <br> damage on the rollers? | Go to step 5. | Replace defec- <br> tive rollers. (Refer <br> to applicable <br> RRPs for replace- <br> ment.) |
| 5 | Checking the PWBA MCU F <br> Replace the PWBA MCU F (RRP 8.4). <br> Perform Test Print. <br> Is the trouble rectified? | End of work | Replace the <br> PWBA ESS. |

## Paper damage



Trouble substance
The paper comes out from the printer crumpled, folded or wornout.

Possible causative parts

- FUSER ASSY (PL 6.1.7)
- TRAY ASSY (PL 2.1.3)

Before commencing troubleshooting, check the paper transfer course. Make sure there is no foreign articles on the transfer course, such as staples, paper clips, scraps of paper and so on.

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking installation place <br> Check the installation surface for irregularities. <br> Check for any missing Foot. <br> Is the setup surface normal? | Go to step 2. | Correct the instal- <br> lation place. |
|  | Checking paper feeding <br> Remove the TRAY ASSY. <br> Load paper on the TRAY ASSY properly. <br> Install the TRAY ASSY properly to the printer. <br> Re-print the defective image. <br> Does the problem still occur? | Go to step 3. | End of work |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 3 | Checking paper condition Load new and dry recommended paper. Re-print the defective image. Is the problem still occurs? | Go to step 4. | End of work |
| 4 | Checking paper transfer route Check the paper router for contamination or obstacles. Is there any obstacle on the paper route? | Go to step 5. | Remove obstacles or contamination. |
| 5 | Checking rollers on the paper transfer route Check all rollers on the entire route for contamination, wear or damage. <br> Check whether pinch rollers rotate freely and spring pressure is applied evenly. Is there any contamination, wear or damage on the rollers? | Go to step 6. | Replace defective rollers. |
| 6 | Checking the Heat Roll and the Pressure Roll Remove the FUSER ASSY (RRP 6.2). <br> WARNING! Start the operation after the FUSER ASSY has cooled down. <br> Is there any contamination or crack on the Heat Roll and/or the Pressure Roll? | Replace the FUSER ASSY (RRP 6.2). | Contact the Technical Engineer. |

## No fix



Trouble substance
The printed image is not fixed on the paper properly. The image easily comes off when rubbed.
Possible causative parts

- FUSER ASSY (PL 6.1.7)
- PSHV-Y2 (PL 8.1.1)
- PWBA MCU F (PL 8.1.5)
- PWBA ESS (PL 8.1.25)

Before commencing troubleshooting, check the paper transfer course. Make sure there is no foreign articles on the transfer course, such as staples, paper clips, scraps of paper and so on.

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | Checking the FUSER ASSY installation <br> Check that the levers on both sides of the FUSER ASSY <br> are pushed down. <br> Re-print the defective image. <br> Does the problem still occur? | Go to step 2. | End of work |
| 2 | Checking paper condition <br> Load new and dry recommended paper. <br> Re-print the defective image. <br> Is the problem still occurs? | Go to step 3. | End of work |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 3 | Checking the Heat Roll and the Pressure Roll <br> Remove the FUSER ASSY (RRP 6.2). <br> WARNING! Start the operation after the FUSER ASSY <br> has cooled down. <br> Is there any contamination or crack on the Heat Roll and/or <br> the Pressure Roll? | Replace the <br> FUSER ASSY <br> (RRP 6.2). | Go to step 4. |
| 4 | Checking image development process <br> Perform Test Print, and turn off the power of the printer <br> while printing. <br> Carefully remove the TONER CARTRIDGE, and check the <br> toner image formed on the drum just before the transfer <br> unit (BTR). <br> Is the image completely formed on the drum? <br> Is the area clear and black, and easy to read? | Go to step 5. | Go to step 7. |
| 5 | Checking image transfer process <br> Check the toner image formed on the drum just after the <br> transfer unit (BTR) passed. <br> Is the toner image completely transferred on the paper? | Go to step 6. | Go to step 7. |
| 6 | Checking the PSHV-Y2 <br> Replace the PSHV-Y2 (RRP 8.1). <br> Perform Test Print. <br> Is the trouble rectified? | End of work | Go to step 7. |
| 7 | Checking the PWBA MCU F <br> Replace the PWBA MCU F (RRP 8.4). <br> Perform Test Print. <br> Is the trouble rectified? | End of work | Replace the |
| PWBA ESS. |  |  |  |

## Abnormal Noise Trouble

## Entry Chart for Abnormal Noise Troubleshooting




## Operation Mode Tables

## Normal Operation

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts <br> MOTOR ASSY 242 (PL 7.1.7) <br> BELT-SYNCHRONOUS BAN (PL 7.1.5) <br> PULLEY 25T (PL 7.1.8) <br> FUSER ASSY (PL 6.1.7) <br> HSG ASSY-BTR (PL 4.2.1) <br> ROLL ASSY OCT (PL 6.2.14) <br> FAN FUSER (PL 5.1.13) <br> SPACER (PL 2.3.4) <br> GEAR (31T) (PL 2.3.5) <br> SPRING (PL 2.3.6) <br> TRAY $1 / 2$ FEED LIFT UP MOTOR (PL 2.3.2) GEAR (13T/60T) <br> SECTOR GEAR (60T) (PL 2.2.22) <br> LIFT UP SHAFT (PL 2.2.24) <br> FEEDER ASSY (FEEDER 1) (PL 2.1.7) <br> FEEDER ASSY (FEEDER 2) (PL 2.1.8) <br> TRAY ASSY (PL 2.1.3) |  |  |
| 1 | Does noise arise from the MOTOR ASSY 242? | Go to step 2. | Go to step 7. |
| 2 | Is the MOTOR ASSY 242 fastened securely with the four screws? | Go to step 4. | Go to step 3. |
| 3 | Does noise arise after the MOTOR ASSY 242 is fastened with the four screws? | Go to step 4. | End of work. |
| 4 | Does noise arise from the PULLEY 25T or BELT-SYNCHRONOUS BAN? | Go to step 6. | Go to step 5. |
| 5 | Does noise arise after the gears of the MOTOR ASSY 242 are cleaned, and obstacles are removed? | Replace the MOTOR ASSY 242. (RRP 7.2) | End of work. |
| 6 | Does noise arise after the PULLEY 25T and BELT-SYNCHRONOUS BAN of the MOTOR ASSY 242 are cleaned, and obstacles are removed? | Replace the PUL- <br> LEY 25T and BELT-SYNCHRONOUS BAN. (RRP 7.1) | End of work. |
| 7 | Does noise arise from the FUSER ASSY? | Go to step 8. | Go to step 10. |
| 8 | Does noise arise from the HSG ASSY-BTR? | Go to step 9. | Replace the FUSER ASSY (RRP 6.2) |
| 9 | Does noise arise after the rollers of the HSG ASSY-BTR are cleaned, and obstacles are removed? | Replace the HSG ASSY-BTR. (RRP 4.7) | End of work. |
| 10 | Does noise arise from the ROLL ASSY OCT? | Clean or replace the ROLL ASSY OCT. (RRP 6.9) | Go to step 11. |
| 11 | Does noise arise from the Tray 1? | Go to step 12. | Go to step 24. |
| 12 | Does noise arise from the FEEDER ASSY (FEEDER 1)? | Go to step 13. | Go to step 17. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 13 | Is the FEEDER ASSY (FEEDER 1) fastened securely with the two screws? | Go to step 15. | Go to step 14. |
| 14 | Does noise arise after the FEEDER ASSY (FEEDER 1) is fastened with the two screws? | Go to step 15. | End of work. |
| 15 | Are the SPACER, GEAR (31T) and the SPRING installed in the correct orientation and order? | Go to step 16. | Reinstall the SPACER, GEAR (31T) and the SPRING in the correct orientation and order. (RRP 2.10/RRP 2.11) |
| 16 | Does noise arise from the TRAY $1 / 2$ FEED LIFT UP MOTOR? | Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR. (RRP 2.9) | Go to step 22. |
| 17 | Does noise arise from the GEAR (13T/60T)? | Clean or replace the GEAR (13T/ 60T). | Go to step 18. |
| 18 | Does noise arise from the SECTOR GEAR (60T)? | Clean or replace the SECTOR GEAR (60T). (RRP 2.8) | Go to step 19. |
| 19 | Is the LIFT UP SHAFT deformed? | Replace the LIFT UP SHAFT. | Go to step 20. |
| 20 | Are there any obstacles around the LIFT UP SHAFT? | Go to step 21. | Go to step 23. |
| 21 | Does noise arise after obstacles are removed? | Go to step 23. | End of work. |
| 22 | Does noise arise after the FEEDER ASSY (FEEDER 1) is replaced (RRP 2.3)? | Contact a Technical Engineer. | End of work. |
| 23 | Does noise arise after the TRAY ASSY is replaced? | Contact a Technical Engineer | End of work. |
| 24 | Does noise arise from the Tray 2? | Go to step 25. | Contact a Technical Engineer. |
| 25 | Does noise arise from the FEEDER ASSY (FEEDER 2)? | Go to step 26. | Go to step 30. |
| 26 | Is the FEEDER ASSY (FEEDER 2) fastened securely with the two screws? | Go to step 28. | Go to step 27. |
| 27 | Does noise arise after the FEEDER ASSY (FEEDER 2) is fastened with the two screws? | Go to step 28. | End of work. |


| Step | Check | Yes | No |
| :---: | :--- | :--- | :--- |
| 28 | Are the SPACER, GEAR (31T) and the SPRING installed <br> in the correct orientation and order? | Go to step 29. | Reinstall the <br> SPACER, GEAR <br> (31T) and the <br> SPRING in the <br> correct orienta- <br> tion and order. <br> (RRP) |
| 29 | Does noise arise from the TRAY 1/2 FEED LIFT UP <br> MOTOR? | TRAY 1/2 FEED <br> LIFT UP <br> MOTOR. (RRP <br> 2.9) | Go to step 35. |
| 30 | Does noise arise from the GEAR (13T/60T)? | Clean or replace <br> the GEAR (13T/ <br> 60T). | Go to step 31. |
| 31 | Does noise arise from the SECTOR GEAR (60T)? | Clean or replace <br> the SECTOR <br> GEAR (60T). <br> (RRP 2.8) | Go to step 32. |
| 32 | Is the LIFT UP SHAFT deformed? | Replace the LIFT <br> UP SHAFT. | Go to step 33. |
| 33 | Are there any obstacles around the LIFT UP SHAFT? | Go to step 34. | Go to step 36. |
| 34 | Does noise arise after obstacles are removed? | Go to step 36. | End of work. |
| 35 | Does noise arise after the FEEDER ASSY (FEEDER 2) is <br> replaced (RRP 2.4)? | Contact <br> a Technical <br> Engineer. | End of work. |
| 36 | Does noise arise after the TRAY ASSY is replaced? | Contact <br> a Technical <br> Engineer. | End of work. |

During Paper Feeding/Ejecting (Tray 1 - Exit1 Face Down Tray)

| Step | Check | Yes | No |
| :--- | :--- | :--- | :--- |
|  | Possible causative parts <br> FEEDER ASSY (FEEDER 1) (PL 2.1.7) <br> ROLLER ASSY (FEED) (PL 2.3.20) <br> ROLLER ASSY (RETARD) (PL 2.3.28) <br> ROLLER ASSY (NUDGER) (PL 2.3.32) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 2.3.2) <br> MOTOR ASSY 242 (PL 7.1.7) |  |  |
|  | PULLEY 25T (PL 7.1.8) |  |  |
|  | BELT-SYNCHRONOUS BAN (PL 7.1.5) |  |  |
| ROLLER ASSY REGI (4.5.5) |  |  |  |
| BRKT ASSY TA (PL 4.1.1) |  |  |  |
| FUSER ASSY (PL 6.1.7) |  |  |  |
| HSG ASSY-BTR (PL 4.2.1) |  |  |  |
| ROLL ASSY OCT (PL 6.2.14) |  |  |  |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Does noise arise from the Tray 1? | Go to step 2. | Go to step 10. |
| 2 | Does noise arise from the FEEDER ASSY (FEEDER 1)? | Go to step 3. | Contact a Technical Engineer. |
| 3 | Is the FEEDER ASSY (FEEDER 1) fastened securely with the two screws? | Go to step 5. | Go to step 4. |
| 4 | Does noise arise after the FEEDER ASSY (FEEDER 1) is fastened with the two screws? | Go to step 5. | End of work. |
| 5 | Does noise arise from the ROLLER ASSY (FEED)? | Clean or replace the ROLLER ASSY (FEED). (RRP 2.21) | Go to step 6. |
| 6 | Does noise arise from the ROLLER ASSY (RETARD)? | ```Clean or replace the ROLLER ASSY (RETARD). (RRP 2.25)``` | Go to step 7. |
| 7 | Does noise arise from the ROLLER ASSY (NUDGER)? | Clean or replace the ROLLER ASSY (NUDGER). (RRP 2.28) | Go to step 8. |
| 8 | Does noise arise from the TRAY $1 / 2$ FEED LIFT UP MOTOR? | Replace the TRAY 1/2 FEED LIFT UP MOTOR. (RRP 2.9) | Go to step 9. |
| 9 | Does noise arise after the FEEDER ASSY (FEEDER 1) is replaced (RRP 2.3)? | Contact <br> a Technical Engineer. | End of work. |
| 10 | Does noise arise from the MOTOR ASSY 242? | Go to step 11. | Go to step 16. |
| 11 | Is the MOTOR ASSY 242 fastened securely with the four screws? | Go to step 13. | Go to step 12. |
| 12 | Does noise arise after the MOTOR ASSY 242 is fastened with the four screws? | Go to step 13. | End of work. |
| 13 | Does noise arise from the PULLEY 25T or BELT-SYNCHRONOUS BAN? | Go to step 15. | Go to step 14. |
| 14 | Does noise arise after the gears of the MOTOR ASSY 242 are cleaned, and obstacles are removed? | Replace the MOTOR ASSY 242. (RRP 7.2) | End of work. |
| 15 | Does noise arise after the PULLEY 25T and BELT-SYNCHRONOUS BAN of the MOTOR ASSY 242 are cleaned, and obstacles are removed? | Replace the PUL- <br> LEY 25T and BELT-SYNCHRONOUS BAN. (RRP 7.1) | End of work. |


| Step | Check | Yes | No |
| :---: | :--- | :--- | :---: |
| 16 | Does noise arise from the ROLLER ASSY REGI? | Clean or replace <br> the ROLLER <br> ASSY REGI. <br> (RRP 4.12) | Go to step 17. |
| 17 | Does noise arise from the BRKT ASSY TA? | Clean or replace <br> the BRKT ASSY <br> TA. (RRP 4.1) | Go to step 18. |
| 18 | Does noise arise from the FUSER ASSY? | Go to step 19. | Go to step 21. |
| 19 | Does noise arise from the HSG ASSY-BTR? | Replace the <br> Go to step 20. <br> (RRR ASSY. |  |
| 20 | Does noise arise after the rollers of the HSG ASSY-BTR <br> are cleaned, and obstacles are removed? | Replace the HSG <br> ASSY-BTR. <br> (RRP 4.7) | End of work. |
| 21 | Does noise arise from the ROLL ASSY OCT? | Clean or replace <br> the ROLL ASSY <br> OCT. (RRP 6.9) | Contact <br> a Technical <br> Engineer. |

During Paper Feeding/Ejecting (Tray 2 - Exit 1 Face Down Tray)

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts <br> FEEDER ASSY (FEEDER 2) (PL 2.1.8) <br> ROLLER ASSY (FEED) (PL 2.3.20) <br> ROLLER ASSY (RETARD) (PL 2.3.28) <br> ROLLER ASSY (NUDGER) (PL 2.3.32) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 2.3.2) <br> MOTOR ASSY 242 (PL 7.1.7) <br> PULLEY 25T (PL 7.1.8) <br> BELT-SYNCHRONOUS BAN (PL 7.1.5) <br> ROLLER ASSY-TA (PL 4.1.8) <br> ROLLER ASSY REGI (4.5.5) <br> BRKT ASSY TA (PL 4.1.1) <br> FUSER ASSY (PL 6.1.7) <br> HSG ASSY-BTR (PL 4.2.1) <br> ROLLER ASSY OCT (PL 6.2.14) | Go |  |
| 1 | Does noise arise from the Tray 2? | Go to step 3. | a Technical |
| 2 | Engineer. |  |  |
| 3 | Does noise arise from the FEEDER ASSY (FEEDER 2)? <br> Is the FEEDER ASSY (FEEDER 2) fastened securely <br> with the two screws? | Go to step 5. | Go to step 4. |
| 4 | Does noise arise after the FEEDER ASSY (FEEDER 2) is <br> fastened with the two screws? | Go to step 5. | End of work. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 5 | Does noise arise from the ROLLER ASSY (FEED)? | Clean or replace the ROLLER ASSY (FEED). (RRP 2.21) | Go to step 6. |
| 6 | Does noise arise from the ROLLER ASSY (RETARD)? | Clean or replace the ROLLER ASSY (RETARD). (RRP 2.25) | Go to step 7. |
| 7 | Does noise arise from the ROLLER ASSY (NUDGER)? | Clean or replace the ROLLER ASSY (NUDGER). (RRP 2.28) | Go to step 8. |
| 8 | Does noise arise from the TRAY $1 / 2$ FEED LIFT UP MOTOR? | Replace the TRAY 1/2 FEED LIFT UP MOTOR. (RRP 2.9) | Go to step 9. |
| 9 | Does noise arise after the FEEDER ASSY (FEEDER 2) is replaced (RRP 2.4)? | Contact <br> a Technical Engineer. | End of work. |
| 10 | Does noise arise from the MOTOR ASSY 242? | Go to step 11. | Go to step 16. |
| 11 | Is the MOTOR ASSY 242 fastened securely with the four screws? | Go to step 13. | Go to step 12. |
| 12 | Does noise arise after the MOTOR ASSY 242 is fastened with the four screws? | Go to step 13. | End of work. |
| 13 | Does noise arise from the PULLEY 25T or BELT-SYNCHRONOUS BAN? | Go to step 15. | Go to step 14. |
| 14 | Does noise arise after the gears of the MOTOR ASSY 242 are cleaned, and obstacles are removed? | Replace the MOTOR ASSY 242. (RRP 7.1) | End of work. |
| 15 | Does noise arise after the PULLEY 25T and BELT-SYNCHRONOUS BAN of the MOTOR ASSY 242 are cleaned, and obstacles are removed? | Replace the PUL- <br> LEY 25T and BELT-SYNCHRONOUS BAN. (RRP 7.2) | End of work. |
| 16 | Does noise arise from the BRKT ASSY TA? | Clean or replace the BRKT ASSY TA. (RRP 4.1) | Go to step 17. |
| 17 | Does noise arise from the ROLLER ASSY REGI? | Clean or replace the ROLLER ASSY REGI. (RRP 4.12) | Go to step 18. |
| 18 | Does noise arise from the BRKT ASSY TA? | Clean or replace the BRKT ASSY TA. (RRP 4.1) | Go to step 19. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 19 | Does noise arise from the FUSER ASSY? | Go to step 20. | Go to step 22. |
| 20 | Does noise arise from the HSG ASSY-BTR? | Go to step 21. | Replace the <br> FUSER ASSY. <br> (RRP 6.2) |
| 21 | Does noise arise after the rollers of the HSG ASSY-BTR <br> are cleaned, and obstacles are removed? | Replace the HSG <br> ASSY-BTR. <br> (RRP 4.7) | End of work. |
| 22 | Does noise arise from the ROLL ASSY OCT? | Clean or replace <br> the ROLL ASSY <br> OCT. (RRP 6.9) | Contact <br> a Technical <br> Engineer. |

During Paper Feeding/Ejecting (MPF - Exit 1 Face Down Tray)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts <br> ROLLER ASSY-FEED (PL 3.2.20) <br> GEAR PICK UP (PL 3.2.6) <br> GEAR CAM (PL 3.2.22) <br> MOTOR ASSY 242 (PL 7.1.7) <br> PULLEY 25T (PL 7.1.8) <br> BELT-SYNCHRONOUS BAN (PL 7.1.5) <br> ROLLER ASSY REGI (4.5.5) <br> BRKT ASSY TA (PL 4.1.1) <br> FUSER ASSY (PL 6.1.7) <br> HSG ASSY-BTR (PL 4.2.1) <br> ROLL ASSY OCT (PL 6.2.14) |  |  |
| 1 | Does noise arise from the MPF? | Go to step 2. | Go to step 6. |
| 2 | Is the MPF fastened securely with the two screws? | Go to step 4. | Go to step 3. |
| 3 | Does noise arise after the MPF is fastened with the four screws? | Go to step 4. | End of work. |
| 4 | Does noise arise from the GEAR PICK UP? | Clean or replace the GEAR PICK UP. (RRP 3.7) | Go to step 5. |
| 5 | Does noise arise from the GEAR CAM? | Clean or replace the GEAR CAM. (RRP 3.14) | Go to step 6. |
| 6 | Does noise arise from the ROLLER ASSY-FEED? | Clean or replace the ROLLER ASSY-FEED. (RRP 3.13) | Go to step 7. |
| 7 | Does noise arise from the MOTOR ASSY 242? | Go to step 8. | Go to step 13. |
| 8 | Is the MOTOR ASSY 242 fastened securely with the four screws? | Go to step 10. | Go to step 9. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 9 | Does noise arise after the MOTOR ASSY 242 is fastened with the four screws? | Go to step 10. | End of work. |
| 10 | Does noise arise from the PULLEY 25T or BELT-SYNCHRONOUS BAN? | Go to step 12. | Go to step 11. |
| 11 | Does noise arise after the gears of the MOTOR ASSY 242 are cleaned, and obstacles are removed? | Replace the MOTOR ASSY 242. (RRP 7.2) | End of work. |
| 12 | Does noise arise after the PULLEY 25T and BELT-SYNCHRONOUS BAN of the MOTOR ASSY 242 are cleaned, and obstacles are removed? | Replace the PUL- <br> LEY 25T and BELT-SYNCHRONOUS BAN. (RRP 7.1) | End of work. |
| 13 | Does noise arise from the ROLLER ASSY REGI? | Clean or replace the ROLLER ASSY REGI. (RRP 4.12) | Go to step 14. |
| 14 | Does noise arise from the BRKT ASSY TA? | Clean or replace the BRKT ASSY TA. (RRP 4.1) | Go to step 15. |
| 15 | Does noise arise from the ROLLER ASSY REGI? | Clean or replace the ROLLER ASSY REGI. (RRP 4.12) | Go to step 16. |
| 16 | Does noise arise from the BRKT ASSY TA? | Clean or replace the BRKT ASSY TA. (RRP 4.1) | Go to step 17. |
| 17 | Does noise arise from the FUSER ASSY? | Go to step 18. | Go to step 20. |
| 18 | Does noise arise from the HSG ASSY-BTR? | Go to step 19. | Replace the FUSER ASSY. (RRP 6.2) |
| 19 | Does noise arise after the rollers of the HSG ASSY-BTR are cleaned, and obstacles are removed? | Replace the HSG ASSY-BTR. (RRP 4.7) | End of work. |
| 20 | Does noise arise from the ROLLER ASSY OCT? | Clean or replace the ROLL ASSY OCT. (RRP 6.9) | Contact a Technical Engineer |

During Paper Feeding (Tray 3)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts <br> TRAY 3 FEEDER (PL 9.2.7) <br> SPACER (PL 9.4.4) <br> GEAR (31T) (PL 9.4.5) <br> SPRING (PL 9.4.6) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 9.4.2) <br> GEAR (13T/60T) (PL 9.3.21) <br> SECTOR GEAR (60T) (PL 9.3.22) <br> LIFT UP SHAFT (PL 9.3.24) <br> MAIN MOTOR (PL 9.6.7) <br> GEAR (126T) (PL 9.6.9) <br> GEAR (60T) (PL 9.6.10) <br> GEAR (37T) (PL 9.6.12) <br> TAKEAWAY ROLL ASSEMBLY (UPPER) (PL 9.5.8) ROLL ASSY (UPPER) (PL 9.5.11) |  |  |
| 1 | Is the 2 TRAY MODULE fastened securely with the two screws? | Go to step 3. | Go to step 2. |
| 2 | Does noise still arise after the 2 TRAY MODULE is fastened with the two screws? | Go to step 3. | End of work. |
| 3 | Does noise arise from the Tray 3? | Go to step 4. | Go to step 16. |
| 4 | Does noise arise from the TRAY 3 FEEDER? | Go to step 5. | Go to step 9. |
| 5 | Is the TRAY 3 FEEDER fastened securely with the two screws? | Go to step 7. | Go to step 6. |
| 6 | Does noise still arise after the TRAY 3 FEEDER is fastened with the two screws? | Go to step 7. | End of work. |
| 7 | Are the SPACER, GEAR (31T) and the SPRING installed in the correct orientation and order? | Go to step 8. | Reinstall the SPACER, GEAR (31T) and the SPRING in the correct orientation and order. <br> (RRP 9.17/RRP 9.18) |
| 8 | Does noise arise from the TRAY $1 / 2$ FEED LIFT UP MOTOR? | Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR. (RRP 9.16) | Go to step 9. |
| 9 | Does noise arise from the GEAR (13T/60T)? | Clean or replace the GEAR (13T/ 60T). | Go to step 10. |
| 10 | Does noise arise from the SECTOR GEAR (60T)? | Clean or replace the SECTOR GEAR (60T). (RRP 9.15) | Go to step 11. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 11 | Is the LIFT UP SHAFT deformed? | Replace the LIFT UP SHAFT. | Go to step 12. |
| 12 | Are there any obstacles around the LIFT UP SHAFT? | Go to step 13. | Go to step 15. |
| 13 | Does noise still arise after obstacles are removed? | Go to step 14. | End of work. |
| 14 | Does noise still arise after the TRAY 3 FEEDER is replaced (RRP 9.10)? | Contact <br> a Technical Engineer | End of work. |
| 15 | Does noise still arise after the TRAY ASSY is replaced? | Contact a Technical Engineer. | End of work. |
| 16 | Does noise arise from the MAIN MOTOR? | Replace the MAIN MOTOR. | Go to step 17. |
| 17 | Does noise arise from the GEAR (126T)? | Clean or replace the GEAR (126T). | Go to step 18. |
| 18 | Does noise arise from the GEAR (60T)? | Clean or replace the GEAR (60T). | Go to step 19. |
| 19 | Does noise arise from the GEAR (37T)? | Clean or replace the GEAR (37T). | Go to step 20. |
| 20 | Does noise arise from the GEAR (32T)? | Clean or replace the GEAR (32T). | Go to step 21. |
| 21 | Does noise arise from the TAKEAWAY ROLL ASSEMBLY (UPPER)? | Clean or replace the TAKEAWAY ROLL ASSEMBLY (UPPER). (RRP 9.40) | Go to step 22. |
| 22 | Does noise arise from the ROLL ASSY (UPPER)? | Clean or replace the ROLL ASSY (UPPER). (RRP 9.44) | Contact a Technical Engineer. |

During Paper Feeding (Tray 4)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts <br> TRAY 4 FEEDER (PL 9.2.8) <br> SPACER (PL 9.4.4) <br> GEAR (31T) (PL 9.4.5) <br> SPRING (PL 9.4.6) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 9.4.2) <br> GEAR (13T/60T) (PL 9.3.21) <br> SECTOR GEAR (60T) (PL 9.3.22) <br> LIFT UP SHAFT (PL 9.3.24) <br> MAIN MOTOR (PL 9.6.7) <br> GEAR (126T) (PL 9.6.9) <br> GEAR (60T) (PL 9.6.10) <br> GEAR (37T) (PL 9.6.12) <br> TAKEAWAY ROLL ASSEMBLY (UPPER) (PL 9.5.8) <br> TAKEAWAY ROLL ASSEMBLY (LOWER) (PL 9.5.8) <br> ROLL ASSY (UPPER) (PL 9.5.11) <br> ROLL ASSY (LOWER) (PL 9.5.11) |  |  |
| 1 | Is the 2 TRAY MODULE fastened securely with the two screws? | Go to step 3. | Go to step 2. |
| 2 | Does noise still arise after the 2 TRAY MODULE is fastened with the two screws? | Go to step 3. | End of work. |
| 3 | Does noise arise from the Tray 4? | Go to step 4. | Go to step 16. |
| 4 | Does noise arise from the TRAY 4 FEEDER? | Go to step 5. | Go to step 9. |
| 5 | Is the TRAY 4 FEEDER fastened securely with the two screws? | Go to step 7. | Go to step 6. |
| 6 | Does noise still arise after the TRAY 4 FEEDER is fastened with the two screws? | Go to step 7. | End of work. |
| 7 | Are the SPACER, GEAR (31T) and the SPRING installed in the correct orientation and order? | Go to step 8. | Reinstall the SPACER, GEAR (31T) and the SPRING in the correct orientation and order. (RRP 9.17/RRP 9.18) |
| 8 | Does noise arise from the TRAY $1 / 2$ FEED LIFT UP MOTOR? | Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR. (RRP 9.16) | Go to step 9. |
| 9 | Does noise arise from the GEAR (13T/60T)? | Clean or replace the GEAR (13T/ 60T). | Go to step 10. |
| 10 | Does noise arise from the SECTOR GEAR (60T)? | Clean or replace the SECTOR GEAR (60T). (RRP 9.15) | Go to step 11. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 11 | Is the LIFT UP SHAFT deformed? | Replace the LIFT UP SHAFT. | Go to step 12. |
| 12 | Are there any obstacles around the LIFT UP SHAFT? | Go to step 13. | Go to step 15. |
| 13 | Does noise still arise after obstacles are removed? | Go to step 14. | End of work. |
| 14 | Does noise still arise after the TRAY 4 FEEDER is replaced (RRP 9.11)? | Contact <br> a Technical Engineer. | End of work. |
| 15 | Does noise still arise after the TRAY ASSY is replaced? | Contact a Technical Engineer. | End of work. |
| 16 | Does noise arise from the MAIN MOTOR? | Replace the MAIN MOTOR. | Go to step 17. |
| 17 | Does noise arise from the GEAR (126T)? | Clean or replace the GEAR (126T). | Go to step 18. |
| 18 | Does noise arise from the GEAR (60T)? | Clean or replace the GEAR (60T). | Go to step 19. |
| 19 | Does noise arise from the GEAR (37T)? | Clean or replace the GEAR (37T). | Go to step 20. |
| 20 | Does noise arise from the GEAR (32T)? | Clean or replace the GEAR (32T). | Go to step 21. |
| 21 | Does noise arise from the TAKEAWAY ROLL ASSEMBLY (LOWER)? | Clean or replace the TAKEAWAY ROLL ASSEMBLY (LOWER). (RRP 9.41) | Go to step 22. |
| 22 | Does noise arise from the TAKEAWAY ROLL ASSEMBLY (UPPER)? | Clean or replace the TAKEAWAY ROLL ASSEMBLY (UPPER). (RRP 9.40) | Go to step 23. |
| 23 | Does noise arise from the ROLL ASSY (LOWER)? | Clean or replace the ROLL ASSY (LOWER). (RRP 9.43) | Go to step 24. |
| 24 | Does noise arise from the ROLL ASSY (UPPER)? | Clean or replace the ROLL ASSY (UPPER). (RRP 9.44) | Contact a Technical Engineer. |

During Duplex Printing

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts <br> TRANS ASSY DUP (PL 10.1.1) <br> MOTOR ASSY 242 (PL 7.1.7) <br> PULLEY 25T (PL 7.1.8) <br> BELT-SYNCHRONOUS BAN (PL 7.1.5) <br> ROLL ASSY OCT (PL 6.2.14) <br> MOTOR ASSY EXIT 2 (PL 11.2.37) <br> ROLL ASSY-FU (PL 11.1.19) <br> ROLL ASSY-INV (PL 11.1.20) <br> MOTOR ASSY DUP (PL 10.1.11) <br> GEAR ROLL 28 (PL 10.1.2) <br> GEAR IDLE 3374 (PL 10.1.3) <br> GEAR IDLE 33 (PL 10.1.4) <br> GEAR IDLE 42 (PL 10.1.5) <br> ROLLER DUP A3L (PL 10.2.7) <br> ROLLER ASSY DUP (PL 10.2.8) |  |  |
| 1 | Is the TRANS ASSY DUP fastened to the printer securely? | Go to step 3. | Go to step 2. |
| 2 | Does noise still arise after the TRANS ASSY DUP is replaced? | Go to step 3. | End of work. |
| 3 | Does noise arise from the MOTOR ASSY 242? | Go to step 4. | Go to step 9. |
| 4 | Is the MOTOR ASSY 242 fastened securely with the four screws? | Go to step 6. | Go to step 5. |
| 5 | Does noise still arise after the MOTOR ASSY 242 is fastened with the four screws? | Go to step 6. | End of work. |
| 6 | Does noise arise from the PULLEY 25T or BELT-SYNCHRONOUS BAN? | Go to step 8. | Go to step 7. |
| 7 | Does noise still arise after the gears of the MOTOR ASSY 242 are cleaned and obstacles are removed? | Replace the MOTOR ASSY 242. (RRP 7.2) | End of work. |
| 8 | Does noise still arise after the PULLEY 25T and BELTSYNCHRONOUS BAN of the MOTOR ASSY 242 are cleaned and obstacles are removed? | Replace the PUL <br> LEY 25T and BELT-SYNCHRONOUS BAN. (RRP 7.1) | End of work. |
| 9 | Does noise arise from the ROLL ASSY OCT? | Clean or replace the ROLL ASSY OCT. (RRP 6.9) | Go to step 10. |
| 10 | Does noise arise from the MOTOR ASSY EXIT 2? | Replace the MOTOR ASSY EXIT 2. (RRP 11.16) | Go to step 11. |
| 11 | Does noise arise from the ROLL ASSY-FU? | Clean or replace the ROLL ASSYFU. (RRP 11.2) | Go to step 12. |


| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 12 | Does noise arise from the ROLL ASSY-IN? | Clean or replace <br> the ROLL ASSY- <br> INV. (RRP 11.3) | Go to step 13. |
| 13 | Does noise arise from the MOTOR ASSY DUP? | Replace the <br> MOTOR ASSY <br> DUP. (RRP 10.8) | Go to step 14. |
| 14 | Does noise arise from the GEAR ROLL 28? | Clean or replace <br> the GEAR ROLL <br> 28. (RRP 10.2) | Go to step 15. |
| 15 | Does noise arise from the GEAR IDLE 33 74? | Clean or replace <br> the GEAR IDLE <br> 33 74. (RRP <br> 10.3) | Go to step 16. |
| 16 | Does noise arise from the GEAR IDLE 33? | Clean or replace <br> the GEAR IDLE <br> 33. (RRP 10.4) | Go to step 17. |
| 18 | Does noise arise from the GEAR IDLE 42? | Clean or replace <br> the GEAR IDLE <br> 42. (RRP 10.5) | Go to step 18. |
| 19 | Does noise arise from the ROLLER ASSY DUP? | Clean or replace <br> the ROLLER <br> DUP A3L. (RRP <br> 10.11) | Go to step 19. |

When Ejecting Paper to Exit 2

| Step | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts <br> TRANS ASSY EXIT (PL 11.1.1) <br> MOTOR ASSY 242 (PL 7.1.7) <br> PULLEY 25T (PL 7.1.8) <br> BELT-SYNCHRONOUS BAN (PL 7.1.5) <br> ROLL ASSY OCT (PL 6.2.14) <br> MOTOR ASSY EXIT 2 (PL 11.2.37) <br> ROLL ASSY OCT (PL 11.2.7) <br> ROLL ASSY-FU (PL 11.1.19) <br> ROLL ASSY-INV (PL 11.1.20) | Go to step 3. | Go to step 2. |
| 1 | Is the TRANS ASSY EXIT fastened to the printer <br> securely? | Go to step 3. | End of work. |
| 2 | Does noise still arise after the TRANS ASSY EXIT is <br> replaced? |  |  |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 3 | Does noise arise from the MOTOR ASSY 242? | Go to step 4. | Go to step 9. |
| 4 | Is the MOTOR ASSY 242 fastened securely with the four screws? | Go to step 6. | Go to step 5. |
| 5 | Does noise still arise after the MOTOR ASSY 242 is fastened with the four screws? | Go to step 6. | End of work. |
| 6 | Does noise arise from the PULLEY 25T or BELT-SYNCHRONOUS BAN? | Go to step 8. | Go to step 7. |
| 7 | Does noise still arise after the gears of the MOTOR ASSY 242 are cleaned and obstacles are removed? | Replace the MOTOR ASSY 242. (RRP 7.2) | End of work. |
| 8 | Does noise still arise after the PULLEY 25T and BELTSYNCHRONOUS BAN of the MOTOR ASSY 242 are cleaned and obstacles are removed? | Replace the PUL- <br> LEY 25T and BELT-SYNCHRONOUS BAN. (RRP 7.1) | End of work. |
| 9 | Does noise arise from the ROLL ASSY OCT (PL 6.2.14)? | Clean or replace the ROLL ASSY OCT. (RRP 6.9) | Go to step 10. |
| 10 | Does noise arise from the MOTOR ASSY EXIT 2? | Replace the MOTOR ASSY EXIT 2. (RRP 11.16) | Go to step 11. |
| 11 | Does noise arise from the ROLL ASSY OCT (PL 11.2.7)? | Clean or replace the ROLL ASSY OCT. (RRP 11.6) | Go to step 12. |
| 12 | Does noise arise from the ROLL ASSY-FU? | Clean or replace the ROLL ASSYFU. (RRP 11.2) | Go to step 13. |
| 13 | Does noise arise from the ROLL ASSY-INV? | Clean or replace the ROLL ASSYINV. (RRP 11.3) | Contact <br> a Technical Engineer. |

During Paper Feeding (to Option DUPLEX)

| Step | Check | Yes | No |
| :--- | :--- | :--- | :--- |
|  | Possible causative parts <br> TRANS ASSY EXIT (PL 11.1.1) <br> MOTOR ASSY 242 (PL 7.1.7) <br>  <br> PULLEY 25T (PL 7.1.8) <br> BELT-SYNCHRONOUS BAN (PL 7.1.5) <br> ROLL ASSY OCT (PL 6.2.14) <br> MOTOR ASSY EXIT (PL 11.2.37) |  |  |
|  | ROLL ASSY OCT (PL 11.2.7) |  |  |
| ROLL ASSY-FU (PL 11.1.19) |  |  |  |
| ROLL ASSY-INV (PL 11.1.20) |  |  |  |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 1 | Is the TRANS ASSY EXIT fastened to the printer securely? | Go to step 3. | Go to step 2. |
| 2 | Does noise still arise after the TRANS ASSY EXIT is replaced? | Go to step 3. | End of work. |
| 3 | Does noise arise from the MOTOR ASSY 242? | Go to step 4. | Go to step 9. |
| 4 | Is the MOTOR ASSY 242 fastened securely with the four screws? | Go to step 6. | Go to step 5. |
| 5 | Does noise still arise after the MOTOR ASSY 242 is fastened with the four screws? | Go to step 6. | End of work. |
| 6 | Does noise arise from the PULLEY 25T or BELT-SYNCHRONOUS BAN? | Go to step 8. | Go to step 7. |
| 7 | Does noise still arise after the gears of the MOTOR ASSY 242 are cleaned and obstacles are removed? | Replace the MOTOR ASSY 242. (RRP 7.2) | End of work. |
| 8 | Does noise still arise after the PULLEY 25T and BELTSYNCHRONOUS BAN of the MOTOR ASSY 242 are cleaned and obstacles are removed? | Replace the PUL- <br> LEY 25T and BELT-SYNCHRONOUS BAN. (RRP 7.1) | End of work. |
| 9 | Does noise arise from the ROLL ASSY OCT (PL 6.2.14)? | Clean or replace the ROLL ASSY OCT. (RRP 6.9) | Go to step 10. |
| 10 | Does noise arise from the MOTOR ASSY EXIT 2? | Replace the MOTOR ASSY EXIT 2. (RRP 11.16) | Go to step 11. |
| 11 | Does noise arise from the ROLL ASSY OCT (PL 11.2.7)? | Clean or replace the ROLL ASSY OCT. (RRP 11.6) | Go to step 12. |
| 12 | Does noise arise from the ROLL ASSY-FU? | Clean or replace the ROLL ASSYFU. (RRP 11.2) | Go to step 13. |
| 13 | Does noise arise from the ROLL ASSY-INV? | Clean or replace the ROLL ASSYINV. (RRP 11.3) | Contact <br> a Technical Engineer. |


| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> H-TRANSPORT MOTOR (PL 12.3.7) <br> SHAFT ASSEMBLY (RIGHT) (PL 12.3.14) <br> BEARING (PL 12.3.11) <br> BEARING (PL 12.3.4) <br> SHAFT ASSEMBLY (LEFT) (PL 12.3.15) <br> BEARING (PL 12.3.10) <br> BELT (PL 12.3.12) <br> PINCH ROLL (PL 12.2.6) |  |  |
| 1 | Is the H -TRANSPORT secured surely to the printer with the two screws? | Go to step 2. | Secure the H-TRANSPORT using two screws. |
| 2 | Does noise arise from the H-TRANSPORT MOTOR? | Replace the H-TRANSPORT MOTOR. | Go to step 3. |
| 3 | Does noise arise from the SHAFT ASSEMBLY (RIGHT) actuated by the H-TRANSPORT MOTOR or from the BEARINGs (PL 12.3.11/PL 12.3.4) on its both ends? | Clean/replace the SHAFT ASSEMBLY (RIGHT), or replace the BEARINGs. | Go to step 4. |
| 4 | Does noise arise from the SHAFT ASSEMBLY (LEFT) actuated by the H-TRANSPORT MOTOR or from the BEARINGs (PL 12.3.10) on its both ends? | Clean/replace the SHAFT ASSEMBLY (LEFT), or replace the BEARINGs. | Go to step 5. |
| 5 | Does noise arise from the two BELTs or ROLL (PL 12.3.13)? | Clean/replace the BELTs or ROLL. | Go to step 6. |
| 6 | Does noise arise from the PINCH ROLL of the COVER ASSY TOP? | Clean/replace the PINCH ROLL. | Go to step 7. |
| 7 | Checking the IOT and Finisher installation Do the Finisher and the IOT keep an appropriate distance from each other? | Consult Technical Engineer in your area. | Reinstall. |

## Top Tray Exiting

| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> MOTOR ASSY (PL 12.12.21) <br> BELT (PL 12.12.23) <br> ROLL ASSY-ENT (PL 12.12.20) <br> ROLLER ASSY-PINCH, ENT (PL 12.12.17) <br> BEARING (PL 12.12.9) <br> BEARING (PL 12.12.27) <br> MOTOR ASSY (PL 12.13.30) <br> BELT (PL 12.13.27) <br> ROLL ASSY-TRANSPORT (PL 12.13.18) <br> ROLLER-PINCH (PL 12.13.11) <br> SHAFT (PL 12.13.13) <br> MOTOR ASSY (PL 12.13.30) <br> BELT (PL 12.13.28) <br> ROLL ASSY-EXIT TOP (PL 12.13.5) <br> BEARING (PL 12.13.9) <br> BEARING (PL 12.13.20) <br> ROLLER ASSY-PINCH, EXIT (PL 12.13.3) |  |  |
| 1 | Clean the paper path. Does noise still arise after cleaning? | Go to step 2. | End of work. |
| 2 | Does noise arise from the FINISHER TRANSPORT MOTOR (PL 12.12.21)? | Replace the MOTOR ASSY. | Go to step 3. |
| 3 | Does noise arise from the BELT or GEAR actuated from the FINISHER TRANSPORT MOTOR? | Clean/replace the BELT and GEAR. | Go to step 4. |
| 4 | Does noise arise from the ROLL ASSY-ENT (PL 12.12.20) or the BEARINGs (PL 12.12.9/PL 12.12.27) on its both ends? | Clean/replace the ROLL ASSYENT, or replace the BEARINGs. | Go to step 5. |
| 5 | Does noise arise from the ROLLER ASSY-PINCH, ENT (PL 12.12.17) opposing to the ROLL ASSY-ENT? | Clean/replace the ROLLER ASSYPINCH, ENT. | Go to step 6. |
| 6 | Does noise arise from the REGI MOTOR? | Replace the MOTOR ASSY. | Go to step 7. |
| 7 | Does noise arise from the BELT or GEAR actuated from the REGI MOTOR? | Clean/replace the BELT and GEAR. | Go to step 8. |
| 8 | Does noise arise from the two ROLL ASSY-TRANSPORTs (PL 12.13.18) or the BEARINGs (PL 12.13.9/PL 12.13.20) on its both ends? | Clean/replace the ROLL ASSYTRANSPORT, or replace the BEARINGs. | Go to step 9. |
| 9 | Does noise arise from the four ROLLER-PINCHs (PL 12.13.11) on the CHUTE ASSY-LOWER and TOP EXIT L (PL 12.13.10) opposing to the ROLL ASSY-TRANSPOR, and the SHAFT (PL 12.13.13)? | Clean/replace the ROLLER-PINCH and the SHAFT. | Go to step 10. |
| 10 | Does noise arise from the EXIT MOTOR? | Replace the MOTOR ASSY. | Go to step 11. |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 11 | Does noise arise from the BELT or GEAR actuated from <br> the EXIT MOTOR? | Clean/replace the <br> BELT and GEAR. | Go to step 12. |
| 12 | Does noise arise from the ROLL ASSY-EXIT TOP (PL <br> $12.13 .5) ~ o r ~ t h e ~ B E A R I N G ~(P L ~ 12.13 .9) ~ o n ~ i t s ~ b o t h ~ e n d s ? ~$ | Clean/replace the <br> ROLL ASSY- <br> EXIT TOP, or <br> replace the <br> BEARING. | Go to step 13. |
| 13 | Does noise arise from the ROLLER ASSY-PINCH, EXIT <br> (PL 12.13.3) opposing to the ROLL ASSY-EXIT TOP? | Clean/replace the <br> ROLLER ASSY- <br> PINCH, EXIT. | Consult Techni- <br> cal Engineer in <br> your area. |

Stacker Tray Exiting

| $\begin{gathered} \text { Ste } \\ \mathrm{p} \end{gathered}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> MOTOR ASSY (PL 12.12.21) <br> BELT (PL 12.12.23) <br> ROLL ASSY-ENT (PL 12.12.20) <br> ROLLER ASSY-PINCH, ENT (PL 12.12.17) <br> BEARING (PL 12.12.9) <br> BEARING (PL 12.12.27) <br> REGI MOTOR (PL 12.13.30) <br> BELT (PL 12.13.27) <br> ROLL ASSY-BUFFER (PL 12.12.13)j <br> ROLLER ASSY-PINCH, EXIT (PL 12.12.15) <br> ROLLER-PINCH (PL 12.12.2) <br> SHAFT (PL 12.12.4) <br> EXIT MOTOR (PL 12.13.30) <br> BELT (PL 12.13.28) <br> ROLL ASSY-EXIT LOW (PL 12.11.6) <br> BEARING (PL 12.11.9) <br> BEARING (PL 12.11.17) <br> ROLLER ASSY-PINCH,EXIT1 (PL 12.11.10) <br> ROLLER ASSY-PINCH,EXIT2 (PL 12.11.11) <br> MOTOR ASSY-DC (PL 12.9.11) <br> BRACKET ASSY-EJECT (PL 12.10.17) <br> SHAFT ASSY-EJECT ROLL (PL 12.10.9) <br> BEARING (PL 12.10.13) <br> BEARING (PL 12.10.12) <br> SHAFT ASSY-PADDLE (PL 12.11.12) <br> BEARING (PL 12.11.9) <br> BELT-SYNCRONUS Z55 (PL 12.11.13) <br> SHAFT-DRIVE PADDLE (PL 12.11.15) <br> SHAFT ASSY PADDLE (PL 12.9.9) <br> BEARING (PL 12.9.17) <br> PADDLE-CYCLONE (PL 12.9.6) <br> SHAFT ASSY-EJECT PINCH (PL 12.9.7) <br> BELT (PL 12.6.25) <br> MOTOR ASSY DC (PL 12.6.26) <br> SHAFT-ELEV (PL 12.6.14) <br> BEARING (PL 12.6.15) <br> BELT STACKER (PL 12.6.3) <br> BELT STACKER (PL 12.6.9) |  |  |
| 1 | Clean the paper path. <br> Does noise still arise after cleaning? | Go to step 2. | End of work. |
| 2 | Does noise arise from the FINISHER TRANSPORT MOTOR? | Replace the MOTOR ASSY. | Go to step 3. |
| 3 | Does noise arise from the BELT or GEAR actuated from the FINISHER TRANSPORT MOTOR? | Clean/replace the BELT and GEAR. | Go to step 4. |
| 4 | Does noise arise from the ROLL ASSY-ENT (PL 12.12.20) or the BEARINGs (PL 12.12.9/PL 12.12.27) on its both ends? | Clean/replace the ROLL ASSYENT, or replace the BEARINGs. | Go to step 5. |


| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 5 | Does noise arise from the ROLLER ASSY-PINCH, ENT (PL 12.12.17) opposing to the ROLL ASSY-ENT? | Clean/replace the ROLLER ASSYPINCH, ENT. | Go to step 6. |
| 6 | Does noise arise from the REGI MOTOR? | Replace the MOTOR ASSY. | Go to step 7. |
| 7 | Does noise arise from the BELT or GEAR actuated from the REGI MOTOR? | Clean/replace the BELT and GEAR. | Go to step 8. |
| 8 | Does noise arise from the ROLL ASSY-BUFFER (PL 12.12.13) or the BEARING (PL 12.12.9) on its both ends? | Clean/replace the ROLL ASSYBUFFER, or replace the BEARING. | Go to step 9. |
| 9 | Does noise arise from the ROLLER ASSY-PINCH, EXIT (PL 12.12.15) opposing to the ROLL ASSY-BUFFER, or from the four ROLLER-PINCHs (PL 12.12.2) on the CHUTE ASSY-UPPER,EXIT OPEN (PL 12.12.1), and SHAFT (PL 12.12.4)? | Clean/replace the ROLLER ASSYPINCH, EXIT, ROLLER-PINCH and SHAFT. | Go to step 10. |
| 10 | Does noise arise from the EXIT MOTOR? | Replace the MOTOR ASSY. | Go to step 11. |
| 11 | Does noise arise from the BELT or GEAR actuated from the EXIT MOTOR? | Clean/replace the BELT and GEAR. | Go to step 12. |
| 12 | Does noise arise from the ROLL ASSY-EXIT LOW (PL 12.11.6) or the BEARINGs (PL 12.11.9/PL 12.11.17) on its both ends? | Clean/replace the ROLL ASSYEXIT LOW, or replace the BEARING. | Go to step 13. |
| 13 | Does noise arise from the two ROLLER ASSY- <br> PINCH,EXIT1s (PL 12.11.10) and/or two ROLLER ASSYPINCH,EXIT2s (PL 12.11.11) on the ROLLER ASSYLOWER EXIT R (PL 12.11.7) opposing to the ROLL ASSY-EXIT LOW? | Clean/replace the ROLLER ASSYPINCH,EXIT1 and ROLLER ASSYPINCH,EXIT2. | Go to step 14. |
| 14 | Does noise arise from the BELT or GEAR actuated from the EJECT CLAMP MOTOR (PL 12.9.11)? | Replace the MOTOR ASSYDC. | Go to step 15. |
| 15 | Does noise arise from the BELT or GEAR actuated from the EJECT MOTOR (PL 12.10.17)? | Replace the BRACKET ASSYEJECT. | Go to step 16. |
| 16 | Does noise arise from the four ROLLER-PINCHs (PL 12.13.11) on the CHUTE ASSY-LOWER and TOP EXIT L (PL 12.13.10) opposing to the ROLL ASSY-TRANSPOR, or the SHAFT (PL 12.13.13)? | Clean/replace the SHAFT ASSYEJECT ROLL, or replace the BEARING. | Go to step 17. |
| 17 | Does noise arise from the SHAFT ASSY-PADDLE (PL 12.11.12)? | Clean/replace the SHAFT ASSYPADDLE. | Go to step 18. |


| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 18 | Does noise arise from the BELT-SYNCRONUS Z55 (PL 12.11.13)? | Clean/replace the BELT-SYNCRONUS $Z 55$. | Go to step 19. |
| 19 | Does noise arise from the SHAFT ASSY-EJECT ROLL (PL 12.10.9) or the BEARINGs (PL 12.10.12) on its both ends? | Clean/replace the SHAFT ASSYEJECT ROLL or replace the BEARINGs. | Go to step 20. |
| 20 | Does the PADDLE on the SHAFT ASSY-PADDLE (PL 12.11.12) contact with the surrounding parts when rotating? | Replace the SHAFT ASSYPADDLE. | Go to step 21. |
| 21 | Does noise arise from the SHAFT ASSY PADDLE (PL 12.9.9) or the BEARING (PL 12.9.17) on its both ends? | Clean/replace the SHAFT ASSY PADDLE, or replace the BEARING. | Go to step 22. |
| 22 | Does the PADDLE-CYCLONE (PL 12.9.6) actuated from the SHAFT ASSY PADDLE (PL 12.9.9) contact with the surrounding parts when rotating? | Reinstall the PADDLECYCLONE. | Go to step 26. |
| 23 | Does noise arise from the SHAFT ASSY-EJECT PINCH (PL 12.9.7)? | Clean/replace the SHAFT ASSYEJECT PINCH. | Go to step 24. |
| 24 | Does noise arise from the BELT (PL 12.6.25)? | Clean/replace the BELT. | Go to step 25. |
| 25 | Does noise arise from the SHAFT-ELEV (PL 12.6.14) or the BEARINGs (PL 12.6.15) on its both ends? | Clean/replace the SHAFT-ELEV or replace the BEARINGs. | Go to step 26. |
| 26 | Does noise arise from the ELEVATOR MOTOR when rotating it? | Replace the MOTOR ASSY DC. | Go to step 27. |
| 27 | Are the BELT STACKERs (PL 12.6.3/PL 12.6.9) installed correctly on the front and rear of the STACKER TRAY? | Consult Technical Engineer in your area. | Reinstall it. |

## During Punching

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :--- | :--- |
|  | Possible causative parts: <br> BRACKET ASSY-MOTOR, PUNCH (PL 12.7.4) <br> MOTOR ASSY (PL 12.7.12) <br> BRACKET ASSY-PUNCH (PL 12.7.9) |  |  |


| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
| 1 | When travelling the BRACKET ASSY-PUNCH, does the <br> contacting noise, which contact the BRACKET ASSY- <br> PUNCH with the component parts such as harness and <br> sensor inside of the Finisher, arise from the inside of the <br> Finisher? | Reinstall the com- <br> ponent part. | Go to step 2. |
| 2 | Clean the paper path of the FRAME ASSY-PUNCH, ALL <br> 2\&3. <br> Does noise still arise after cleaning? | Go to step 3. | End of work. |
| 3 | Does noise arise from the BRACKET ASSY-MOTOR, <br> PUNCH (PL 12.7.4)? | Replace the <br> BRACKET ASSY- <br> MOTOR, <br> PUNCH. | Go to step 4. |
| 4 | Does noise arise from the MOTOR ASSY (PL 12.7.12)? | Replace the <br> MOTOR ASSY. | Go to step 5. |
| 5 | Does noise arise from the inside of the BRACKET ASSY- <br> PUNCH? | Replace the <br> BRACKET ASSY- <br> PUNCH. | Consult Techni- <br> cal Engineer in <br> your area. |

## During Tamping

| Ste <br> $p$ | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> MOTOR ASSY 2 (PL 12.10.6) <br> MOTOR ASSY (PL 12.10.7) <br> TRAY ASSY-COMPILER (PL 12.10.1) | Does noise (rotating noise) arise from the compile tray <br> when front-tamping? | Replace the <br> MOTOR ASSY 2. |
| 2 | Does noise (scraping noise) arise from the compile tray <br> when front-tamping? | Replace the <br> TRAY ASSY- <br> COMPILER. | Go to step 3. |
| 3 | Does noise (rotating noise) arise from the compile tray <br> when rear-tamping? | Replace the <br> MOTOR ASSY. | Go to step 4. |
| 4 | Does noise (scraping noise) arise from the compile tray <br> when rear-tamping? | Replace the <br> TRAY ASSY- <br> COMPILER. | Go to step 5. |
| 5 | Does noise (rotating noise) arise from the compile tray <br> when center-tamping? | Replace the <br> MOTOR ASSY 2 <br> and MOTOR <br> ASSY. | Go to step 6. |
| 6 | Does noise (scraping noise) arise from the compile tray <br> when center-tamping? | Replace the <br> TRAY ASSY- <br> COMPILER. | Consult Techni- <br> cal Engineer in <br> your area. |

During Stapling

| Ste <br> p | Check | Yes | No |
| :---: | :--- | :---: | :---: |
|  | Possible causative parts: <br> CARRIAGE ASSY UPPER, STAPLE (PL 12.8.8) <br> CARRIAGE ASSY LOWER, STAPLE (PL 12.8.9) <br> CARRIAGE ASSY-STAPLER (PL 12.8.1) <br> STAPLE ASSY (PL 12.8.2) | ( |  |
| 1 | Does noise arise from the STAPLE UNIT when traveling it <br> to the front or rear? | Go to step 2. | Go to step 3. |
| 2 | Clean the surfaces of the RAIL-UPPER (PL 12.8.10) which <br> travelling the STAPLE UNIT. <br> Does noise still arise after cleaning? | Replace the CAR- <br> RIAGE ASSY <br> UPPER, STA- <br> PLE, or the CAR- <br> RIAGE ASSY <br> LOWER, STA- <br> PLE. | End of work. |
| 3 | Replace the CARRIAGE ASSY-STAPLER (PL 12.8.1). <br> Does noise still arise after replacing? | Go to step 4. | End of work. |
| 4 | Replace the CSTAPLE ASSY (PL 12.8.2). <br> Does noise still arise after replacing? | Consult Techni- <br> cal Engineer in <br> your area. | End of work. |

## When Power is Turned On / When Tray is Inserted

| $\begin{aligned} & \text { Ste } \\ & \mathrm{p} \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> FEEDER ASSY HCF (PL 13.4.1) <br> MOTOR ASSY HCF (PL 13.4.2) <br> BRKT ASSY GEAR R PF2 (PL 13.3.8) |  |  |
| 1 | Is the FEEDER ASSY HCF is fastened to the front side of the frame securely using the two screws? | Go to step 2. | Refastened. |
| 2 | Does noise arise from the MOTOR ASSY HCF in the FEEDER ASSY HCF? | Replace the MOTOR ASSY HCF. RRP 13.15) | Go to step 3. |
| 3 | Does noise arise from the BRKT ASSY GEAR R PF2 on the rear side of the Tray activated by the MOTOR ASSY HCF? | replace the BRKT <br> ASSY GEAR R PF2. <br> RRP 13.12) | Go to step 4. |
| 4 | Does noise arise from the Tray? | Replace defective parts or reassemble the Tray. | Consult Technical Engineer in your area. |


| $\begin{aligned} & \text { Ste } \\ & p \end{aligned}$ | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts: <br> MOTOR ASSY HCF (PL 13.4.2) <br> ROLL ASSY NUD (PL 13.5.20) <br> ROLL ASSY FEED (PL 13.5.21) <br> ROLLER ASSY RETARD (PL 13.6.17) <br> MOTOR ASSY (PL 13.7.12) <br> ROLLER ASSY TA P (PL 13.7.9) |  |  |
| 1 | Does noise arise from the MOTOR ASSY HCF in the FEEDER ASSY HCF? | Replace the MOTOR ASSY HCF. RRP 13.15) | Go to step 2. |
| 2 | Does noise arise from the ROLL ASSY NUD activated by the MOTOR ASSY HCF? | Replace the ROLL ASSY NUD. RRP 13.23) | Go to step 3. |
| 3 | Does noise arise from the ROLL ASSY FEED activated by the MOTOR ASSY HCF? | Replace the ROLL ASSY FEED. RRP 13.24) | Go to step 4. |
| 4 | Does noise arise from the ROLLER ASSY RETARD activated by the MOTOR ASSY HCF? | Replace the ROLLER ASSY RETARD. RRP 13.27) | Go to step 5. |
| 5 | Does noise arise from the MOTOR ASSY (T/A Motor)? | Replace the MOTOR ASSY. RRP 13.32) | Go to step 6. |
| 6 | Does noise arise from the ROLLER ASSY TA P activated by the MOTOR ASSY (T/A Motor)? | Replace the ROLLER ASSY TA P. <br> RRP 13.31) | Consult Technical Engineer in your area. |

During Paper Feeding (Tray 3)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts <br> TRAY 3 FEEDER (PL 14.5.1) <br> SPACER (PL 14.6.4) <br> GEAR (31T) (PL 14.6.5) <br> SPRING (PL 14.6.6) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 14.6.2) <br> LIFT SHAFT ASSEMBLY (PL 14.2.4) <br> PULLEY (PL 14.2.5) <br> TRAY CABLE (PL 14.2.9) <br> F/R CABLE (PL 14.2.10) <br> F/L CABLE (PL 14.2.11) <br> MAIN MOTOR (PL 14.8.3) <br> GEAR (37T) (PL 14.8.12) <br> GEAR (32T) (PL 14.8.13) <br> GEAR (60T) (PL 14.8.14) <br> GEAR (60T) (PL 14.8.15) <br> GEAR ASSEMBLY (TRAY 3) (PL 14.8.1) <br> TAKEAWAY ROLL ASSEMBLY (PL 14.5.3) <br> PINCH ROLL (PL 14.7.13) |  |  |
| 1 | Is the TANDEM TRAYMODULE fastened securely with the two screws? | Go to step 3. | Go to step 2. |
| 2 | Does noise still arise after the TANDEM TRAY MODULE is fastened with the two screws? | Go to step 3. | End of work. |
| 3 | Does noise arise from the Tray 3? | Go to step 4. | Go to step 16. |
| 4 | Does noise arise from the TRAY 3 FEEDER? | Go to step 5. | Go to step 9. |
| 5 | Is the TRAY 3 FEEDER fastened securely with the two screws? | Go to step 7. | Go to step 6. |
| 6 | Does noise still arise after the TRAY 3 FEEDER is fastened with the two screws? | Go to step 7. | End of work. |
| 7 | Are the SPACER, GEAR (31T) and the SPRING installed in the correct orientation and order? | Go to step 8. | Reinstall the SPACER, GEAR (31T) and the SPRING in the correct orientation and order. (RRP 14.35/RRP 14.36) |
| 8 | Does noise arise from the TRAY $1 / 2$ FEED LIFT UP MOTOR? | Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR. (RRP 14.34) | Go to step 14. |
| 9 | Does noise arise from the LIFT SHAFT ASSEMBLY? | Clean or replace the LIFT SHAFT ASSEMBLY. | Go to step 10. |
| 10 | Does noise arise from the PULLEY? | Clean or replace the PULLEY. | Go to step 11. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 11 | Is the TRAY CABLE installed properly? | Go to step 12. | Reinstall the TRAY CABLE properly or replace it. (RRP 14.13) |
| 12 | Is the F/R CABLE installed properly? | Go to step 13. | Reinstall the F/R CABLE properly or replace it. (RRP 14.14) |
| 13 | Is the F/L CABLE installed properly? | Go to step 15. | Reinstall the F/L CABLE properly or replace it. (RRP 14.15) |
| 14 | Does noise still arise after the TRAY 3 TRANSPORT ASSEMBLY is replaced (RRP 14.20)? | Contact a Technical Engineer. | End of work. |
| 15 | Does noise still arise after the TRAY ASSY is replaced? | Contact a Technical Engineer. | End of work. |
| 16 | Does noise arise from the MAIN MOTOR? | Replace the MAIN MOTOR. (RRP 14.61) | Go to step 17. |
| 17 | Does noise arise from the GEAR (37T)? | Clean or replace the GEAR (37T). | Go to step 18. |
| 18 | Does noise arise from the GEAR (32T)? | Clean or replace the GEAR (32T). | Go to step 19. |
| 19 | Does noise arise from the GEAR (60T)? | Clean or replace the GEAR (60T). | Go to step 20. |
| 20 | Does noise arise from the GEAR (60T)? | Clean or replace the GEAR (60T). | Go to step 21. |
| 21 | Does noise arise from the GEAR ASSEMBLY (TRAY 3)? | Clean or replace the GEAR ASSEMBLY (TRAY 3). (RRP 14.59) | Go to step 22. |
| 22 | Does noise arise from the TAKEAWAY ROLL ASSEMBLY? | Clean or replace the TAKEAWAY ROLL ASSEMBLY. (RRP 14.32) | Go to step 23. |
| 23 | Does noise arise from the PINCH ROLL? | Clean or replace the ROLL ASSY. (RRP 14.57) | Contact <br> a Technical Engineer. |

During Paper Feeding (Tray 4)

| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
|  | Possible causative parts <br> TRAY 4 FEEDER (PL 14.4.15) <br> SPACER (PL 14.6.4) <br> GEAR (31T) (PL 14.6.5) <br> SPRING (PL 14.6.6) <br> TRAY 1/2 FEED LIFT UP MOTOR (PL 14.6.2) <br> LIFT SHAFT ASSEMBLY (PL 14.2.4) <br> PULLEY (PL 14.2.5) <br> REAR TRAY CABLE (PL 14.3.8) <br> FRONT TRAY CABLE (PL 14.3.9) <br> MAIN MOTOR (PL 14.8.3) <br> GEAR (22/40) (PL 14.8.4) <br> GEAR ASSEMBLY (TRAY 4) (PL 14.8.2) <br> TAKEAWAY ROLL ASSEMBLY (PL 14.4.5) <br> TAKEAWAY ROLL ASSEMBLY (PL 14.5.3) <br> PINCH ROLL (PL 14.4.8) <br> PINCH ROLL (PL 14.7.13) |  |  |
| 1 | Is the TANDEM TRAYMODULE fastened securely with the two screws? | Go to step 3. | Go to step 2. |
| 2 | Does noise still arise after the TANDEM TRAY MODULE is fastened with the two screws? | Go to step 3. | End of work. |
| 3 | Does noise arise from the Tray 4? | Go to step 4. | Go to step 15. |
| 4 | Does noise still arise from the TRAY 4 FEEDER? | Go to step 5. | Go to step 9. |
| 5 | Is the TRAY 4 FEEDER fastened securely with the two screws? | Go to step 7. | Go to step 6. |
| 6 | Does noise still arise after the TRAY 4 FEEDER is fastened with the two screws? | Go to step 7. | End of work. |
| 7 | Are the SPACER, GEAR (31T) and the SPRING installed in the correct orientation and order? | Go to step 8. | Reinstall the SPACER, GEAR (31T) and the SPRING in the correct orientation and order. (RRP 14.35/RRP 14.36) |
| 8 | Does noise arise from the TRAY $1 / 2$ FEED LIFT UP MOTOR? | Replace the TRAY $1 / 2$ FEED LIFT UP MOTOR. (RRP 14.34) | Go to step 13. |
| 9 | Does noise arise from the LIFT SHAFT ASSEMBLY? | Clean or replace the LIFT SHAFT ASSEMBLY. | Go to step 10. |
| 10 | Does noise arise from the PULLEY? | Clean or replace the PULLEY. | Go to step 11. |


| Step | Check | Yes | No |
| :---: | :---: | :---: | :---: |
| 11 | Is the REAR TRAY CABLE installed properly? | Go to step 12. | Reinstall the REAR TRAY CABLE properly or replace it. (RRP 14.21) |
| 12 | Is the FRONT TRAY CABLE installed properly? | Go to step 13. | Reinstall the FRONT TRAY CABLE properly or replace it. (RRP 14.22) |
| 13 | Does noise still arise after the TRAY 4 FEEDER is replaced (RRP 14.27)? | Contact a Technical Engineer. | End of work. |
| 14 | Does noise still arise after the TRAY 4 TRANSPORT ASSEMBLY is replaced? | Contact a Technical Engineer. | End of work. |
| 15 | Does noise arise from the MAIN MOTOR? | Replace the MAIN MOTOR. (RRP 14.61) | Go to step 16. |
| 16 | Does noise arise from the GEAR (37T) or GEAR (22/40)? | Clean or replace the GEAR (37T) or GEAR (22/40). | Go to step 17. |
| 17 | Does noise arise from the GEAR ASSEMBLY (TRAY 4)? | Clean or replace the GEAR ASSEMBLY (TRAY 4). (RRP 14.60) | Go to step 18. |
| 18 | Does noise arise from the TAKEAWAY ROLL ASSEMBLY (PL 14.4.5)? | Clean or replace the TAKEAWAY ROLL ASSEMBLY (PL 14.4.5). (RRP 14.26) | Go to step 19. |
| 19 | Does noise arise from the TAKEAWAY ROLL ASSEMBLY (PL 14.5.3)? | Clean or replace the TAKEAWAY ROLL ASSEMBLY (PL 14.5.3). (RRP 14.32) | Go to step 20. |
| 20 | Does noise arise from the PINCH ROLL (PL 14.4.8)? | Clean or replace the RINCH ROLL. | Go to step 21. |
| 21 | Does noise arise from the PINCH ROLL (PL 14.7.13)? | Clean or replace the PINCH ROLL. (RRP 14.57) | Contact a Technical Engineer. |

## Judgment of Print Consistency

These instructions are used to judge print consistency printing with the standard paper (letter size).
Keep the paper packaged in the operating environment for 12 hours, and then use the paper fresh from the packaged.

NOTE The image quality cannot be evaluated when the machine is faulty.

Leading edge registration

- Measurement of the amount of print shift from the ideal position on the paper
- Measure the amount of shift from the ideal point 15 mm away from the front end at center of right-and-left of the paper.
- Reference: less than +/-2.0 mm


Side edge registration

- Measure the amount of shift from the ideal point 108.0 mm away from the left end at center of front-and-back of the paper.
- Reference: less than $+/-2.5 \mathrm{~mm}$

- Measurement of the inclined paper feeding
- Measure the vertical distance of two points 190 mm away each other on the top horizontal line.
- Reference: less than +/-1.2 mm



## Perpendicularity

- Measurement of the perpendicularity for suppressing inclines of ROS and OPC
- Check the perpendicular line to the horizontal line to measure the horizontal distance at the point 114.5 mm away vertically from center of top horizontal line.
- Reference: less than +/-0.8 mm


Parallelism

- The parallelism is difference of feeding speed between left and right sides of the paper.
- Measure the difference of length between two 234 mm long vertical lines 190 mm away each other.
- Reference: less than +/-1.2 mm



## Preventive maintenance

When visiting the customer, perform the maintenance work other than the original purpose to avoid any trouble that may arise.

Procedure for preventive maintenance

1. Check how the customer is using the machine.
2. Write down the cumulative print count.

NOTE Use the cumulative print count as a guide of replacing periodic replacement parts.
NOTE Replace the periodic replacement parts as required.
3. Perform some printings to check that there is no problem.
4. Remove foreign articles on the BTR ASSY, FUSER ASSY and paper transfer rolls, and clean stains with a brush and dry waste cloth.

NOTE When stains are heavy, clean with dampened cloth, and then clean with dry cloth.
NOTE Be careful not to damage the parts to be cleaned.
5. Cleaning the fan exhaust

Remove the COVER REAR, and clean the dust on the MAIN FAN with a brush.
Remove the COVER FRONT, and clean the dust on the FAN SUB.
NOTE The clogged exhaust and fan cause a temperature rise inside and failures.
6. Perform some printings again to check that there is no problem.

## Chapter 8 Diagnostics

This section provides procedures for performing various diagnostic functions including the following actions: display the accumulated print count, run input tests to check the function of sensors and switches, run output tests to check the operation and function of printer's components.

## Entering the Diagnostic Mode

To enter the diagnostic mode, hold down the MENU and SELECT control panel pushbuttons while turning the printer on. Continue to hold the buttons down until the control panel displays the text "Diagnostics" on the first line of the display. The diagnostic mode allows you to access various diagnostic menus and submenus. Pressing the NEXT button on the control repeatedly will cycle through the diagnostic menus in the following order:

- Input Tests
- Output Tests
- Alignment
- Maintenance Info
- Operator Panel
- Test Print
- Print Summary


## MENU STRUCTURE

## Input Tests

## Output Tests

## Alignment

## Chain 6

Function 20
Function 21
Function 22
Function 23
Function 24
Function 25
Function 26
Function 28
Function 29
Function 30
Function 31
Function 32
Function 33
Function 34
Chain 20
Function 1
Function 41
Function 42
Function 43
Function 45

Image Counter
Sheet Counter
Toner Page Count
Tray 1 Counter
Tray 2 Counter
Tray 3 Counter
Tray 4 Counter
Tray 5 Counter
Tray 6 Counter
Serial Number
Asset Tag
Reset Error Log
Power Saver 0
Sleep Mode 0

## Operator Panel Print Summary

LED Test
LCD Test
Key Test

## Test Print

Default Source
Duplex
Grid Page
Blank Page
Black Page
Test Page
Flash Summary
Print Summary

## Input Tests

## NOTES AND WARNINGS

NOTE When the power is on, do not touch energized parts unless absolutely necessary. Note that the wiring inside the power switch/inlet unit remains energized as long as the power cord is connected to the AC outlet, even when the switch is off.
NOTE Never work in the vicinity of drive units and operating units while executing tests that activate motors.

NOTE Never touch the high-voltage parts of the printer while executing tests that activate high voltage outputs. Always follow the procedures given in this manual.

NOTE Never touch drive units while the drive system is operating.
NOTE Never touch the fan while it is in operation.
NOTE Never test the interlock switch with the front cover open since there is a risk of activating the laser beam.

The Input Tests menu provides access to the diagnostic input tests. Use the following procedure to enter this menu:

1. Enter Diagnostic Mode.
2. Navigate through the Input Tests menu structure to select Chain and Function.

| Chain- <br> Function | Title | Function | Mode |
| :---: | :--- | :--- | :---: |
| $01-01$ | L/H COVER | Checking open/close of the COVER <br> ASSY-LH (PL4.2.8). | INPUT |
| $01-10$ | TRAY MODULE COVER | Checking open/close of the LEFT <br> COVER ASSEMBLY <br> (2TM:PL20.5.10/TTM:PL21.7.1). | INPUT |
| $01-11$ | L/H Low COVER | Checking open/close of the COVER <br> ASSY LH LOW C (PL4.1.10). | INPUT |
| $01-12$ | FRONT COVER | Checking open/close of the COVER <br> ASSY FRONT (PL1.1.9). | INPUT |
| $01-13$ | L/H High COVER | Checking open/close of the CHUTE <br> LH HIGH (EXIT2:PL24.1.18). | INPUT |
| $07-01$ | TRAY1 SIZE SENSOR | Checking operation of the TRAY1 <br> Size Sensor (SWITCH ASSY P S) <br> (PL2.1.4). | INPUT |
| $07-02$ | TRAY2 SIZE SENSOR | Checking operation of the TRAY2 <br> Size Sensor (SWITCH ASSYP S) <br> (PL2.1.4). | INPUT |
| $07-03$ | TRAY3 SIZE SENSOR | Checking operation of the optional <br> TRAY MODULE TRAY3 Size Sensor <br> (TRAY 3/4 PAPER SIZE SWITCH) <br> (2TM:PL20.2.4/TTM:21.4.23). | INPUT |
| $07-04$ | TRAY4 SIZE SENSOR | Checking operation of the optional <br> TRAY MODULE TRAY4 Size Sensor <br> (TRAY 3/4 PAPER SIZE SWITCH) <br> (2TM:PL20.2.4/TMM:21.4.23). | INPUT |
| $07-05$ | TRAY4 SIZE digital SENSOR | Checking operation of the TRAY4 <br> Size Sensor (TRAY 3/4 PAPER SIZE <br> SWITCH) (2TM:PL20.2.4/ <br> TTM:21.4.23). | INPUT |


| $07-06$ | MSI SIZE SENSOR | Checking operation of the MSI Size <br> Sensor (SENSOR ASSY-MSI) <br> (PL3.3.10). | INPUT |
| :---: | :--- | :--- | :---: |
| $07-07$ | TRAY1 NO PAPER SENSOR | Checking operation of the TRAY1 No <br> Paper Sensor (SENSOR) (NO <br> PAPER SENSOR) (PL2.3.14). | INPUT |
| $07-08$ | TRAY2 NO PAPER SENSOR | Checking operation of the TRAY2 No <br> Paper Sensor (SENSOR) (NO <br> PAPER SENSOR) (PL2.3.14). | INPUT |
| $07-09$ | TRAY3 NO PAPER SENSOR | Checking operation of the TRAY3 No <br> Paper Sensor (SENSOR) (NO <br> PAPER SENSOR) (2TM:PL20.4.14/ <br> TTM:21.6.14). | INPUT |
| $07-10$ | TRAY4 NO PAPER SENSOR | Checking operation of the TRAY4 No <br> Paper Sensor (SENSOR) (NO <br> PAPER SENSOR) (2TM:PL20.4.14// <br> TTM:21.6.14). | INPUT |
| $07-11$ | HCF NO PAPER SENSOR | Checking operation of the optional <br> HCF No Paper Sensor (SENSOR- <br> PHOTO IN (HCF NO PAPER SEN- <br> SOR)) (PL22.5.16). | INPUT |
| $07-12$ | SMH/ENV NO PAPER | Checking operation of the MSI No <br> Saper Sensor (SENSOR- PHOTO IN) | INPUT |
| SENSOR | (PL3.1.4). |  |  |


| $07-23$ | HCF COVER | Checking open/close of the optional <br> HCF COVER ASSY TOP S <br> (PL22.7.1). | INPUT |
| :---: | :--- | :--- | :---: |
| $07-24$ | FACE UP TRAY DETECTED | Checking whether the FACE UP <br> TRAY is installed. | INPUT |
| $07-25$ | OCT2 DETECTED | Checking whether the optional EXIT2 <br> is installed. | INPUT |
| $07-26$ | TRAY1 SIZE digital SENSOR | Checking operation of the TRAY1 No <br> Paper Sensor (SENSOR) (NO <br> PAPER SENSOR) (PL2.3.14). | INPUT |
| $07-27$ | TRAY2 SIZE digital SENSOR | Checking operation of the TRAY2 No <br> Paper Sensor (SENSOR) (NO <br> PAPER SENSOR) (PL2.3.14). | INPUT |
| $07-28$ | TRAY3 SIZE digital SENSOR | Checking operation of the TRAY3 No <br> Paper Sensor (SENSOR) (NO <br> PAPER SENSOR) (2TM:PL20.4.14/ <br> TTM:21.6.14). | INPUT |
| $07-30$ | FACE DOWN TRAY1 FULL <br> STACK SENSOR | Checking operation of the EXIT1 Full <br> Stack Sensor (SENSOR-PHOTO IN) <br> (PL6.2.5). | INPUT |
| $07-31$ | FACE DOWN TRAY2 FULL <br> STACK SENSOR | Checking operation of the optional <br> EXIT2 Full Stack Sensor (SENSOR) <br> (PL24.2.52). | INPUT |
| $07-32$ | FACE UP TRAY FULL STACK <br> SENSOR | Checking operation of the FACE UP <br> TRAY full stack sensor. | INPUT |
| $07-33$ | OCT1 HOME POSITION <br> SENSOR | Checking operation of the EXIT1 <br> Home Position Sensor (SENSOR- <br> PHOTO IN) (PL6.2.5). | INPUT |
| $08-21$ | PreFEED SENSOR4 | Checking operation of the optional <br> EXIT2 Home Position Sensor (OCT <br> POSITION SENSOR) (PL24.2.54). | INPUT |
| $08-34$ | OCT2 HOME POSITION |  |  |
| SENSOR |  |  |  |


| $08-23$ | HCF F/O SENSOR | Checking operation of the optional <br> HCF FEED OUT SENSOR (HCF TA <br> SENSOR) (PL22.7.6). | INPUT |
| :---: | :--- | :--- | :---: |
| $08-31$ | DUP WAIT SENSOR | Checking operation of the optional <br> DUPEX Wait Sensor (SENSOR- <br> PHOTO IN) (PL23.1.18). | INPUT |
| $08-32$ | REGI SENSOR (DM) | Checking operation of the optional <br> DUPLEX REGI Sensor (SNR ASSY <br> REGI) (PL4.5.7). | INPUT |
| $08-33$ | DUP INTERLOCK | Checking open/close of the optional <br> DUPLEX COVER DUP (PL23.1.13). | INPUT |
| $08-35$ | REGI CLUTCH (DM) | Checking operation of the optional <br> DUPLEX REGI Cutch (CLUTCH <br> ASSY REGI H) (PL4.5.2). | INPUT |
| $08-39$ | REGI CLUTCH (EXIT) | Checking operation of the EXIT REGI <br> Clutch (CLUTCH ASSY REGI H) <br> (PL4.5.2). | INPUT |
| $08-47$ | FEED READY SIGNAL | Checking the FEED READY signal. | INPUT |
| $08-48$ | T/A F/O3 SENSOR | Checking operation of the FEED OUT <br> SENSOR 3 (TRAY 3 FEED OUT | INPUT |
| SENSOR)(2TM:PL20.5.3/ <br> TTM:21.5.8). | INTion |  |  |
| $08-49$ | T/A F/O4 SENSOR | Checking operation of the FEED OUT <br> SENSOR 4 (TRAY 4 FEED OUT | INPUT |
| SENSOR) (2TM:PL20.5.6/ |  |  |  |
| TTM:21.4.18). |  |  |  |


| 10-20 | FUSER CONTROL SENSOR (FS1) | Checking forward rotation of the MOTOR ASSY-OFFSET <br> (PL24.2.30). | INPUT |
| :---: | :---: | :---: | :---: |
| 10-21 | FUSER CONTROL SENSOR (FS2) | Checking operation of the FUSER temperature sensor (FS1). | INPUT |
| 10-22 | FUSER CONTROL SENSOR (PR) | Checking operation of the FUSER temperature sensor (FS2). | INPUT |
| 10-23 | EXIT SENSOR | Checking operation of the SENSOR PHOTO (PL6.1.4). | INPUT |
| 10-26 | EXIT SENSOR1(EXIT) | Checking operation of the SENSOR PHOTO (PL6.1.4). | INPUT |
| 10-60 | FUSER FAN FAIL MONITOR SIGNAL | Checking signals to FAN FUSER (PL5.1.13) from the MOTOR ASSY 242 (PL7.1.7). | INPUT |
| 12-27 | IOT Exit SNR | Checking operation of the SENSOR PHOTO (PL6.1.4). | INPUT |
| 12-28 | H-Xport Ent. SNR | Checking operation of the optional FINISHER H-TRANSPORT <br> ENTRANCE SENSOR (PL25.3.23). | INPUT |
| 12-29 | H-Xport Exit SNR | Checking operation of the optional FINISHER H-TRANSPORT EXIT SENSOR (PL25.3.21). | INPUT |
| 12-30 | Xport Ent. SNR | Checking operation of the optional FINISHER SENSOR (PL25.12.19). | INPUT |
| 12-31 | Buffer Path SNR | Checking operation of the optional FINISHER SENSOR ASSY (PL25.12.12). | INPUT |
| 12-32 | Top Tray Exit SNR | Checking operation of the optional FINISHER SENSOR (PL25.13.2). | INPUT |
| 12-33 | Top Tray Full SNR | Checking operation of the optional FINISHER SENSOR (PL25.13.7). | INPUT |
| 12-34 | Compile Exit SNR | Checking operation of the optional FINISHER SENSOR ASSY (PL25.11.3). | INPUT |
| 12-35 | Compile Tray No Paper SNR | Checking operation of the optional FINISHER SENSOR (PL25.10.3). | INPUT |
| 12-36 | Side Regi SNR 1 | Checking the optional FINISHER Side Regi sensor (SIDE REGI SENSOR) (PL25.7.8). | INPUT |
| 12-37 | Side Regi SNR 2 | Checking operation of the optional FINISHER SENSOR (PL25.7.8). | INPUT |
| 12-38 | Eject Clamp Home SNR | Checking operation of the optional FINISHER SENSOR (PL25.9.13). | INPUT |
| 12-39 | Set Clamp Home SNR | Checking operation of the optional FINISHER SENSOR (PL25.10.18). | INPUT |
| 12-51 | Gate SNR | Checking operation of the optional FINISHER GATE SENSOR (SENSOR) (PL25.13.15). | INPUT |


| 13-33 | Puncher Move Home SNR | Checking operation of the optional FINISHER SENSOR (PL25.7.17). | INPUT |
| :---: | :---: | :---: | :---: |
| 13-34 | Puncher Home SNR | Checking operation of the optional FINISHER SENSOR (PL25.7.15 right) | INPUT |
| 13-35 | Puncher Front SNR | Checking operation of the optional FINISHER SENSOR (PL25.7.15 center) | INPUT |
| 13-36 | Punch Hole Select SNR | Checking operation of the optional FINISHER SENSOR (PL25.7.15 left). | INPUT |
| 13-37 | Puncher Motor SNR | Checking operation of the optional FINISHER SENSOR (PL25.7.13). | INPUT |
| 13-38 | Punch Box Set SNR | Check whether the optional FINISHER PUNCH BOX SENSOR (SENSOR) (PL25.7.21) is installed. | INPUT |
| 13-39 | Front Tamper Home SNR | Checking operation of the optional FINISHER SENSOR (PL25.10.2 right). | INPUT |
| 13-40 | Rear Tamper Home SNR | Checking operation of the optional FINISHER SENSOR (PL25.10.2 left). | INPUT |
| 13-42 | Stapler Move Position SNR | Checking operation of the optional FINISHER SENSOR (PL25.8.5). | INPUT |
| 13-43 | Low Staple SNR | Checking operation of the optional FINISHER Low Staple SNR. | INPUT |
| 13-44 | Self Priming SNR | Checking operation of the optional FINISHER Self Priming SNR. | INPUT |
| 13-45 | Staple Home SNR | Checking operation of the optional FINISHER Staple Home SNR. | INPUT |
| 13-46 | Upper Limit SNR | Checking operation of the optional FINISHER SENSOR (PL25.6.17 upper). | INPUT |
| 13-48 | Stacker No Paper SNR | Checking operation of the optional FINISHER SENSOR (PL25.6.17 lower). | INPUT |
| 13-49 | Stack Encoder SNR | Checking operation of the optional FINISHER SENSOR (PL25.6.17). | INPUT |
| 13-50 | Stack Hight SNR 1 | Checking operation of the optional FINISHER Stack Hight SNR 1. | INPUT |
| 13-51 | Stack Hight SNR 2 | Checking operation of the optional FINISHER Stack Hight SNR 2. | INPUT |
| 13-53 | H-Xport Interlock SNR | Checking open/close of the optional NISHER COVER TOP,C (PL25.2.1) | INPUT |
| 13-54 | Finisher Front Cover SW | Checking open/close of the optional FINISHER COVER ASSY FRONT (PL25.5.3). | INPUT |
| 13-55 | Eject Cover SW | Checking open/close of the optional FINISHER EJECT COVER (SENSOR ASSY) (PL25.9.23). | INPUT |
| 15-60 | Temp Sensor | Checking operation of the Temperature Sensor (SENSOR HUM\&TE) (PL5.1.5). | INPUT |
| 15-61 | Hum Sensor | Checking operation of the Temperature Sensor (SENSOR HUM\&TE) (PL5.1.5). | INPUT |
| 15-62 | ATC Sensor | Checking operation of the ATC Sensor. | INPUT |

## Output Tests

## NOTES AND WARNINGS

NOTE When the power is on, do not touch energized parts unless absolutely necessary. Note that the wiring inside the power switch/inlet unit remains energized as long as the power cord is connected to the AC outlet, even when the switch is off.

NOTE Never use any procedure other than the one specified for testing the operation of the LD switch in the CRU sensor assembly as there is a risk of activating the laser beam.

NOTE Never work in the vicinity of drive units and operating units while executing tests that activate motors.

NOTE Never touch the high-voltage parts of the printer while executing tests that activate high voltage outputs. Always follow the procedures given in this manual.

NOTE Never touch drive units while the drive system is operating.
NOTE Never touch the fan while it is in operation.
The Output Tests menu provides access to the diagnostic output tests. Use the following procedure to enter this menu:

1. Enter Diagnostic Mode.
2. Navigate through the Output Tests menu structure to select Chain and Function.

| ChainFunction | Title | Function | Mode |
| :---: | :---: | :---: | :---: |
| 04-01 | MAIN MOTOR ON | Checking operation of the MAIN Motor (MOTOR ASSY 242) (PL7.1.7). | OUTPUT |
| 04-02 | FUSER FAN MOTOR (HIGH SPEED) | Checking high-speed rotation of the FAN Motor (FAN FUSER) (PL5.1.13). | OUTPUT |
| 06-15 | ROS MOTOR ON | Checking operation of the ROS Motor (MOTOR ASSY-DISP 30K) (PL5.1.11). | OUTPUT |
| 07-18 | TRAY1 LIFTER UP (FEED MOTOR Reverse) | Checking reverse rotation of the TRAY1 Motor (TRAY1/2 FEED LIFT UP MOTOR) (PL2.3.2). | OUTPUT |
| 07-19 | TRAY2 LIFTER UP (FEED MOTOR Reverse) | Checking reverse rotation of the TRAY2 Motor (TRAY1/2 FEED LIFT UP MOTOR) (PL2.3.2). | OUTPUT |
| 07-20 | TRAY3 LIFTER UP (FEED MOTOR Reverse) | Checking reverse rotation of the optional TRAY MODULE TRAY3 Motor (TRAY $1 / 2$ FEED LIFT UP MOTOR) (2TM:PL20.4.2/ TTM:PL21.6.2). | OUTPUT |
| 07-21 | TRAY4 LIFTER UP (FEED MOTOR Reverse) | Checking reverse rotation of the optional TRAY MODULE TRAY4 Motor (TRAY 1/2 FEED LIFT UP MOTOR) (2TM:PL20.4.2/ TTM:PL21.6.2). | OUTPUT |
| 07-22 | HCF LIFTER UP (FEED MOTOR Reverse) | Checking reverse rotation of the optional HCF Tray Motor (MOTOR ASSY HCF) (PL22.4.2). | OUTPUT |


| 08-10 | REGI CLUTCH | Checking operation of the REGI Clutch (CLUTCH ASSY REGI H) (PL4.5.2). | OUTPUT |
| :---: | :---: | :---: | :---: |
| 08-11 | HCF T/A MOTOR ( $242 \mathrm{~mm} / \mathrm{s}$ ) | Checking low-speed rotation of the optional HCF T/A Motor (MOTOR ASSY) (PL22.7.12). | OUTPUT |
| 08-12 | TRAY1 FEED MOTOR | Checking forward rotation of the TRAY1 Motor (TRAY1/2 FEED LIFT UP MOTOR) (PL2.3.2). | OUTPUT |
| 08-13 | TRAY2 FEED MOTOR | Checking forward rotation of the TRAY2 Motor (TRAY1/2 FEED LIFT UP MOTOR) (PL2.3.2). | OUTPUT |
| 08-14 | TRAY3 FEED MOTOR | Checking forward rotation of the optional TRAY MODULE TRAY3 Motor (TRAY $1 / 2$ FEED LIFT UP MOTOR) (2TM:PL20.4.2/ TTM:PL21.6.2). | OUTPUT |
| 08-15 | TRAY4 FEED MOTOR | Checking forward rotation of the optional TRAY MODULE TRAY4 Motor (TRAY $1 / 2$ FEED LIFT UP MOTOR) (2TM:PL20.4.2/ TTM:PL21.6.2). | OUTPUT |
| 08-16 | HCF FEED MOTOR | Checking forward rotation of the optional HCF Tray Motor (MOTOR ASSY HCF) (PL22.4.2). | OUTPUT |
| 08-17 | SMH FEED CLUTCH | Checking operation of the MSI FEED Clutch (SOLENOID PICKUP) (PL3.2.15). | OUTPUT |
| 08-18 | TM T/A CL | Checking operation of the optional TRAY MODULE T/A Clutch (2TM:CLUTCH (PL20.6.2)/ TTM:TAKEAWAY CLUTCH (PL21.8.7)). | OUTPUT |
| 08-38 | DUP MOTOR | Checking operation of the optional DUPLEX Motor (MOTOR ASSY DUP) (PL23.1.11). | OUTPUT |
| 08-41 | HCF Nudger Solenoid ( High Power) | Checking high-power operation of the optional HCF Solenoid (SOLENOID ASSY) (PL22.4.5). | OUTPUT |
| 08-42 | HOT-LINE CHECK with alternative signal | Switching between the FEED and STOP signal. | OUTPUT |
| 08-44 | TRAY3 FEED MOTOR (HotLine) | Checking hot-line of the optional TRAY MODULE TRAY3 Motor (TRAY $1 / 2$ FEED LIFT UP MOTOR) (2TM:PL20.4.2/TTM:PL21.6.2). | OUTPUT |
| 08-45 | TRAY4 FEED MOTOR (HotLine) | Checking hot-line of the optional TRAY MODULE TRAY4 Motor (TRAY1/2 FEED LIFT UP MOTOR) (2TM:PL20.4.2/TTM:PL21.6.2). | OUTPUT |


| 08-50 | DUP MOTOR Rotate for sending paper out to regi | Checking operation of the optional DUPLEX Motor (MOTOR ASSY DUP) (PL23.1.11). | OUTPUT |
| :---: | :---: | :---: | :---: |
| 08-51 | HCF Nudger Solenoid( Low Power) | Checking low-power operation of the optional HCF Solenoid (SOLENOID ASSY) (PL22.4.5). | OUTPUT |
| 08-56 | HCF T/A MOTOR ( $500 \mathrm{~mm} / \mathrm{s}$ ) | Checking high-speed rotation of the optional HCF T/A Motor (MOTOR ASSY) (PL22.7.12). | OUTPUT |
| 09-01 | MAIN MOTOR ON | Checking operation of the MAIN Motor (MOTOR ASSY 242) (PL7.1.7). | OUTPUT |
| 09-03 | DRUM MOTOR ON | Checking operation of the DRUM Motor (MOTOR ASSY 242) (PL7.1.7). | OUTPUT |
| 09-23 | BCR AC BIAS | Checking AC BIAS of the MAIN Motor (MOTOR ASSY 242) (PL7.1.7). | OUTPUT |
| 09-24 | BCR DC BIAS | Checking DC BIAS of the MAIN Motor (MOTOR ASSY 242) (PL7.1.7). | OUTPUT |
| 09-27 | DTS | Checking DTS of the MAIN Motor (MOTOR ASSY 242) (PL7.1.7). | OUTPUT |
| 09-29 | BTR(+) BIAS | Checking BTR(+) BIAS of the MAIN Motor (MOTOR ASSY 242) (PL7.1.7). | OUTPUT |
| 09-33 | Deve DC BIAS | Checking Deve DC BIAS of the MAIN Motor (MOTOR ASSY 242) (PL7.1.7). | OUTPUT |
| 09-36 | BTR(-) BIAS | Checking BTR(-) BIAS of the MAIN Motor (MOTOR ASSY 242) (PL7.1.7). | OUTPUT |
| 10-01 | MAIN MOTOR | Checking operation of the MAIN Motor (MOTOR ASSY 242) (PL7.1.7). | OUTPUT |
| 10-04 | FUSER FAN MOTOR(HIGH SPEED) | Checking high-speed rotation of the FAN FUSER (PL5.1.13). | OUTPUT |
| 10-06 | OFFSET MOTOR1 FORWARD ROTATION | Checking forward rotation of the MOTOR ASSY-OFFSET (PL6.2.3). | OUTPUT |
| 10-07 | OFFSET MOTOR1 REVERSE ROTATION | Checking reverse rotation of the MOTOR ASSY-OFFSET (PL6.2.3). | OUTPUT |
| 10-08 | EXIT DRIVE MOTOR FORWARD (Eject Paper out) | Checking forward rotation of the MOTOR ASSY EXIT 2 (PL24.2.37). | OUTPUT |
| 10-09 | EXIT DRIVE MOTOR REVERSE (send paper into Dup) | Checking reverse rotation of the MOTOR ASSY EXIT 2 (PL24.2.37). | OUTPUT |


| $10-24$ | OFFSET MOTOR2 <br> FORWARD ROTATION | Checking forward rotation of the <br> MOTOR ASSY-OFFSET <br> (PL24.2.30). | OUTPUT |
| :---: | :--- | :--- | :---: |
| $10-25$ | OFFSET MOTOR2 REVERSE <br> ROTATION | Checking reverse rotation of the <br> MOTOR ASSY-OFFSET <br> (PL24.2.30). | OUTPUT |
| $10-51$ | EXIT GATE SOLENOID | Checking operation of the SOLE- <br> NOID ASSY (PL24.2.29). | OUTPUT |
| $10-53$ | FACE UP GATE SOLENOID | Checking operation of the SOLE- <br> NOID ASSY FU (PL24.2.23). | OUTPUT |
| $12-01$ | H XPORT Motor 145 ON/OFF | Checking low-speed rotation of the <br> optional FINISHER H-TRANSPORT <br> MOTOR (PL25.3.7). | OUTPUT |
| $12-02$ | H XPORT Motor 242 ON/OFF | Checking high-speed rotation of the <br> optional FINISHER H-TRANSPORT <br> MOTOR (PL25.3.7). | OUTPUT |
| $12-03$ | Fin Transport Motor 350 ON/ |  |  |
| OFF | Checking low-speed rotation of the <br> optional FINISHER MOTOR ASSY- <br> DC (PL25.9.11). | OUTPUT |  |
| $12-04$ | Fin Transport Motor 600 ON/ <br> OFF | Checking high-speed rotation of the <br> optional FINISHER MOTOR ASSY- <br> DC (PL25.9.11). | OUTPUT |


| 12-05 | Regi Motor 285F ON/OFF | Checking low-speed forward rotation of the optional FINISHER MOTOR ASSY (LEFT) (PL25.13.30). | OUTPUT |
| :---: | :---: | :---: | :---: |
| 12-06 | Regi Motor 350F ON/OFF | Checking medium-speed forward rotation of the optional FINISHER MOTOR ASSY (LEFT) (PL25.13.30) | OUTPUT |
| 12-07 | Regi Motor 600F ON/OFF | Checking high-speed forward rotation of the optional FINISHER MOTOR ASSY (LEFT) (PL25.13.30). | OUTPUT |
| 12-08 | Regi Motor 285R ON/OFF | Checking low-speed reverse rotation of the optional FINISHER MOTOR ASSY (LEFT) (PL25.13.30). | OUTPUT |
| 12-09 | Exit Motor 285F ON/OFF | Checking low-speed forward rotation of the optional FINISHER MOTOR ASSY (RIGHT) (PL25.13.30). | OUTPUT |
| 12-10 | Exit Motor 350F ON/OFF | Checking medium-speed forward rotation of the optional FINISHER MOTOR ASSY (RIGHT) (PL25.13.30). | OUTPUT |
| 12-11 | Exit Motor 600F ON/OFF | Checking high-speed forward rotation of the optional FINISHER MOTOR ASSY (RIGHT) (PL25.13.30). | OUTPUT |
| 12-12 | Exit Motor 285R ON/OFF | Checking low-speed forward rotation of the optional FINISHER MOTOR ASSY (RIGHT) (PL25.13.30). | OUTPUT |
| 12-13 | Transpoort Gate Solenoid TOP | Checking ON operation of the optional FINISHER BRACKET ASSY SOL (PL25.12.32). | OUTPUT |
| 12-14 | Transpoort Gate Solenoid STACKER | Checking OFF operation of the optional FINISHER BRACKET ASSY SOL (PL25.12.32). | OUTPUT |
| 12-15 | Sub Paddle Solenoid ON/OFF | Checking operation of the optional FINISHER SOLENOID ASSY (PL25.9.3). | OUTPUT |
| 12-16 | Set Clamp CLUTCH ON/OFF | Checking operation of the optional FINISHER Set Clamp CLUTCH. | OUTPUT |
| 12-18 | Eject Clamp Motor UP ON/ OFF | Checking UP operation of the optional FINISHER MOTOR ASSYDC (PL25.9.11). | OUTPUT |
| 12-19 | Eject Clamp Motor DOWN ON/OFF | Checking DOWN operation of the optional FINISHER MOTOR ASSYDC (PL25.9.11). | OUTPUT |
| 12-20 | Eject Motor Low FORWARD ON/OFF | Checking low-speed forward rotation of the optional FINISHER BRACKET ASSY-EJECT (PL25.10.17). | OUTPUT |
| 12-21 | Eject Motor High FORWARD ON/OFF | Checking high-speed forward rotation of the optional FINISHER BRACKET ASSY-EJECT (PL25.10.17). | OUTPUT |
| 12-22 | Eject Motor Low REVERSE ON/OFF | Checking low-speed reverse rotation of the optional FINISHER BRACKET ASSY-EJECT (PL25.10.17). | OUTPUT |


| $12-23$ | Eject Motor High REVERSE <br> ON/OFF | Checking high-speed reverse rotation <br> of the optional FINISHER BRACKET <br> ASSY-EJECT (PL25.10.17). | OUTPUT |
| :---: | :--- | :--- | :--- |
| $12-24$ | Buffer Gate SOL STK | Checking OFF operation of the <br> optional FINISHER BRACKET ASSY <br> SOL (PL25.12.34). | OUTPUT |
| $12-25$ | Buffer Gate SOL BUF | Checking ON operation of the <br> optional FINISHER BRACKET ASSY <br> SOL (PL25.12.34). | OUTPUT |
| $13-01$ | Puncher Move Motor Low <br> FRONT ON/OFF | Checking low-speed rotation <br> (FRONT) of the optional FINISHER <br> MOTOR ASSY (PL25.7.12). | OUTPUT |
| $13-02$ | Puncher Move Motor High <br> FRONT ON/OFF | Checking high-speed rotation <br> (FRONT) of the optional FINISHER <br> MOTOR ASSY (PL25.7.12). | OUTPUT |
| $13-03$ | Puncher Move Motor Low <br> REAR ON/OFF | Checking low-speed rotation (REAR) <br> of the optional FINISHER MOTOR <br> ASSY (PL25.7.12). | OUTPUT |


| 13-04 | Puncher Move Motor High REAR ON/OFF | Checking high-speed rotation (REAR) of the optional FINISHER MOTOR ASSY (PL25.7.12). | OUTPUT |
| :---: | :---: | :---: | :---: |
| 13-05 | Puncher Mot 2Hole Home Move | Move the optional FINISHER PUNCHER MOTOR (MOTOR ASSY) (PL25.7.12) to the 2Hole Home. | OUTPUT |
| 13-06 | Puncher Mot 3Hole Home Move | Move the optional FINISHER PUNCHER MOTOR (MOTOR ASSY) (PL25.7.12) to the 3Hole Home. | OUTPUT |
| 13-07 | Puncher Mot 4Hole Home Move | Move the optional FINISHER PUNCHER MOTOR (MOTOR ASSY) (PL25.7.12) to the 4Hole Home. | OUTPUT |
| 13-08 | Punch (2Hole) | Checking operation of the Motor (BRACKET ASSY-MOTOR,PUNCH) <br> (PL25.7.4) for driving the optional <br> FINISHER BRACKET ASSY <br> PUNCH2 \& 3 (PL25.7.9). | OUTPUT |
| 13-09 | Punch (3Hole) | Checking operation of the Motor (BRACKET ASSY-MOTOR,PUNCH) (PL25.7.4) for driving the optional FINISHER BRACKET ASSY PUNCH2\&3 (PL25.7.9). | OUTPUT |
| 13-10 | Punch (4Hole) | Checking operation of the Motor (BRACKET ASSY-MOTOR,PUNCH) (PL25.7.4) for driving the optional FINISHER BRACKET ASSY PUNCH (PL25.7.9). | OUTPUT |
| 13-11 | Front Tamper Mot Low FRONT ON/OFF | Checking low-speed rotation (FRONT) of the optional FINISHER MOTOR ASSY 2 (PL25.10.6). | OUTPUT |
| 13-12 | Front Tamper Mot Middle FRONT ON/OFF | Checking medium-speed rotation (FRONT) of the optional FINISHER MOTOR ASSY 2 (PL25.10.6) | OUTPUT |
| 13-13 | Front Tamper Mot High FRONT ON/OFF | Checking high-speed rotation (FRONT) of the optional FINISHER MOTOR ASSY 2 (PL25.10.6). | OUTPUT |
| 13-14 | Front Tamper Mot Low REAR ON/OFF | Checking low-speed rotation (REAR) of the optional FINISHER MOTOR ASSY 2 (PL25.10.6). | OUTPUT |
| 13-15 | Front Tamper Mot Middle REAR ON/OFF | Checking medium-speed rotation (REAR) of the optional FINISHER MOTOR ASSY 2 (PL25.10.6). | OUTPUT |
| 13-16 | Front Tamper Mot High REAR ON/OFF | Checking high-speed rotation (REAR) of the optional FINISHER MOTOR ASSY 2 (PL25.10.6). | OUTPUT |
| 13-17 | Rear Tamper Mot Low FRONT ON/OFF | Checking low-speed rotation (FRONT) of the optional FINISHER MOTOR ASSY (PL25.10.7). | OUTPUT |
| 13-18 | Rear Tamper Mot Middle FRONT ON/OFF | Checking medium-speed rotation (FRONT) of the optional FINISHER MOTOR ASSY (PL25.10.7). | OUTPUT |
| 13-19 | Rear Tamper Mot High FRONT ON/OFF | Checking high-speed rotation (FRONT) of the optional FINISHER MOTOR ASSY (PL25.10.7). | OUTPUT |


| 13-20 | Rear Tamper Mot Low REAR ON/OFF | Checking low-speed rotation (REAR) of the optional FINISHER MOTOR ASSY (PL25.10.7). | OUTPUT |
| :---: | :---: | :---: | :---: |
| 13-21 | Rear Tamper Mot Middle REAR ON/OFF | Checking medium-speed rotation (REAR) of the optional FINISHER MOTOR ASSY (PL25.10.7). | OUTPUT |
| 13-22 | Rear Tamper Mot High REAR ON/OFF | Checking high-speed rotation (REAR) of the optional FINISHER MOTOR ASSY (PL25.10.7). | OUTPUT |
| 13-23 | Stapler Move Mot Low FRONT ON/OFF | Checking low-speed rotation (FRONT) of optional FINISHER CARRIAGE ASSY LOWER,STAPLER (PL25.8.9) Motor. | OUTPUT |
| 13-24 | Stapler Move Mot Middle FRONT ON/OFF | Checking medium-speed rotation (FRONT) of the optional FINISHER CARRIAGE ASSY LOWER,STAPLER (PL25.8.9) Motor. | OUTPUT |
| 13-25 | Stapler Move Mot High FRONT ON/OFF | Checking high-speed rotation (FRONT) of the optional FINISHER CARRIAGE ASSY LOWER,STAPLER (PL25.8.9) Motor. | OUTPUT |
| 13-26 | Stapler Move Mot Low REAR ON/OFF | Checking low-speed rotation (REAR) of the optional FINISHER CARRIAGE ASSY LOWER,STAPLER (PL25.8.9) Motor. | OUTPUT |
| 13-27 | Stapler Move Mot Middle REAR ON/OFF | Checking medium-speed rotation (REAR) of the optional FINISHER CARRIAGE ASSY LOWER,STAPLER (PL25.8.9) Motor. | OUTPUT |
| 13-28 | Stapler Move Mot High REAR ON/OFF | Checking high-speed rotation (REAR) of the optional FINISHER CARRIAGE ASSY LOWER,STAPLER (PL25.8.9) Motor. | OUTPUT |
| 13-29 | Staple Motor FORWARD ON/ OFF | Checking forward rotation of the optional FINISHER STAPLER ASSY (PL25.8.2) Motor. | OUTPUT |
| 13-30 | Staple Motor REVERSE ON/ OFF | Checking reverse rotation of the optional FINISHER STAPLER ASSY (PL25.8.2) Motor. | OUTPUT |
| 13-31 | Stacker Motor UP ON/OFF | Checking Motor UP operation of the optional FINISHER MOTOR ASSY DC (PL25.6.26). | OUTPUT |
| 13-32 | Stacker Motor DOWN ON/OFF | Checking Motor DOWN operation of the optional FINISHER MOTOR ASSY DC (PL25.6.26). | OUTPUT |
| 15-63 | Dispense Motor | Checking operation of the Dispense Motor (Motor ASSY-DISP 30K) (PL5.1.11). | OUTPUT |

## Alignment

The Alignment menu provides access to the diagnostic alignments. Use the following procedure to enter this menu:

1. Enter Diagnostic Mode.
2. Navigate through the Alignmnet menu structure to select specific alignmnet tests.

| Chain Function | Name | Value |  | Initial Value | 1 Count |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min. | Max. |  |  |
| 06-20 | ALL TRAY-LASER SIDE REGI ADJUSTMENT | 1 | 99 | 50 | 0.254 mm |
| 06-21 | TRAY1-LASER SIDE REGI ADJUSTMENT | 1 | 99 | 50 | 0.254 mm |
| 06-22 | TRAY2-LASER SIDE REGI ADJUSTMENT | 1 | 99 | 50 | 0.254 mm |
| 06-23 | TRAY3-LASER SIDE REGI ADJUSTMENT | 1 | 99 | 50 | 0.254 mm |
| 06-24 | TRAY4-LASER SIDE REGI ADJUSTMENT | 1 | 99 | 50 | 0.254 mm |
| 06-25 | HCF-LASER SIDE REGI ADJUSTMENT | 1 | 99 | 50 | 0.254 mm |
| 06-26 | MSI-LASER SIDE REGI ADJUSTMENT | 1 | 99 | 50 | 0.254 mm |
| 06-28 | DUP ALL TRAY-LASER SIDE REGI ADJUSTMENT | 1 | 99 | 50 | 0.254 mm |
| 06-29 | DUP TRAY1-LASER SIDE REGI ADJUSTMENT | 1 | 99 | 50 | 0.254 mm |
| 06-30 | DUP TRAY2-LASER SIDE REGI ADJUSTMENT | 1 | 99 | 50 | 0.254 mm |
| 06-31 | DUP TRAY3-LASER SIDE REGI ADJUSTMENT | 1 | 99 | 50 | 0.254 mm |
| 06-32 | DUP TRAY4-LASER SIDE REGI ADJUSTMENT | 1 | 99 | 50 | 0.254 mm |
| 06-33 | DUP HCF-LASER SIDE REGI ADJUSTMENT | 1 | 99 | 50 | 0.254 mm |
| 06-34 | DUP MSI-LASER SIDE REGI ADJUSTMENT | 1 | 99 | 50 | 0.254 mm |
| 20-01 | LEAD REGI ADJUSTMENT - ALL TRAY | 0 | 66 | 33 | 0.363 mm |
| 20-41 | TRAY1 for Normal Paper - LEAD REGI ADJUSTMENT | 0 | 66 | 33 | 0.363 mm |
| 20-42 | "TRAY2-4,HCF for Normal Paper LEAD REGI ADJUSTMENT" | 0 | 66 | 33 | 0.363 mm |
| 20.43 | SMH for Normal Paper - LEAD REGI | 0 | 66 | 3.3 | 0.363 mm |

## Maintenance Info

The Maintenance Info menu provides access to the diagnostic maintenance information. Use the following procedure to enter this menu:

1. Enter Diagnostic Mode.
2. Navigate through the Maintenance menu structure to view information.

- Image Counter displays the total number of images printed.
- Sheet Counter displays the total number of sheets used.
- Toner Page Count Displays the total number of sheets printed with current toner cartridge.
- Tray 1 Counter displays the total number of sheets printed from Tray 1.
- Tray 2 Counter displays the total number of sheets printed from Tray 2.
- Tray 3 Counter displays the total number of sheets printed from Tray 3.
- Tray 4 Counter displays the total number of sheets printed from Tray 4.
- Tray 5 Counter displays the total number of sheets printed from Tray 5.
- Tray 6 Counter displays the total number of sheets printed from Tray 6.
- Serial Number displays printer serial number.
- Asset Tag displays and sets printer serial number.
- Reset Error Log resets error log.
- Power Saver 0 - setting to ON allows disabling Power Saver Mode
- Sleep Mode 0 - setting to ON allows disabling Sleep Mode.


## Operator Panel

The Operator Panel menu provides access to the diagnostic operator panel tests. Use the following procedure to enter this menu:

1. Enter Diagnostic Mode.
2. Navigate through the Operator Panel menu structure to to move through the available tests.
3. Use the procedures in the following table to execute specific operator panel tests:
\(\left.$$
\begin{array}{|l|l|l|}\hline \text { Operator Panel Tests } & \text { Function } & \text { Procedure } \\
\hline \text { LED Test } & \begin{array}{l}\text { Lights the operator panel LEDs in } \\
\text { various sequences and } \\
\text { combinations to verify that all are } \\
\text { functioning correctly. }\end{array} & \begin{array}{l}\text { 1. Press SELECT to execute the LED Test. } \\
\text { 2. Press CANCEL to stop the LED Test. } \\
\text { 3. Press RETURN to return to the Operator Panel } \\
\text { menu. }\end{array} \\
\hline \text { LCD Test } & \begin{array}{l}\text { Displays the operator panel } \\
\text { character set. }\end{array} & \begin{array}{l}\text { 1. Press SELECT to view the operator panel char- } \\
\text { acter set. }\end{array}
$$ <br>
2. Press NEXT or PREVIOUS to scroll through the <br>

characters.\end{array}\right\}\)| 3. Press RETURN to return to the Operator Panel |
| :--- |
| menu. |

## Test Print

The Operator Panel menu provides access to the diagnostic operator panel tests. Use the following procedure to enter this menu:

1. Enter Diagnostic Mode.
2. Navigate through the Test Print menu structure to move through the available tests.

- Grid Page prints a grid page to assist in adjusting alignment.
- Blank Page prints a blank page.
- Black Page prints a black page.
- Test Page prints a basic test page.


## Flash Summary

The Flash Summary menu prints Code and User Flash Summary. Use the following procedure to enter this menu:

1. Enter Diagnostic Mode.
2. Navigate through the Test Print menu structure to print Code and User Flash Summary

## Print Summary

The Print Summary menu prints Counter values from Maintenance Menu and Alignment Values from Alignment Menu. Use the following procedure to enter this menu:

1. Enter Diagnostic Mode.
2. Navigate through the Test Print menu structure to print Counter values from Maintenance Menu and Alignment Values from Alignment Menu.

## Chapter 9 Controller/ESS

## 50PPM Controller Architecture



This Controller is based on the standard Intelliprint architecture, with a MIPS RM7035C / 600Mhz PMC Processor. The Field Programmable Gate Array chip, a Xilinx (XC3S1000) which implements various core devices and controllers required by the Intelliprint architecture, such as:
DDR Memory Controller, Dual Video Channels, PCI and 16 bit Bus Interfaces, IDE Interface, IEEE-1284 Interface, Programmable Engine Interface, and I2C Interface. USB, Ethernet, and Serial RS232 are stand alone controller chips peripheral to the Gate Array device.

This Controller has 256MBytes standard on-board memory, with a DIMM/100 DDR memory expansion slot for memory upgrade modules ranging from 128MB to 512MB. The Video Channels deliver a dual laser differential video output signal to the engine's ROS unit, while the Programmable Engine Interface provides control for Keyboard, LCD Display and engine status. The onboard NVRAM device stores data ranging from User configuration to Page counts, LAN settings and miscellaneous internal information. There is also a Real Time Clock (RTC) feature that gives the user the ability to provide date indexing and Job accounting. There are a number of data storage devices available to the user ranging from a 12MB User Flash partition in the onboard Flash module, to the optional Compact Flash Module and an optional 2.5" IDE Hard Drive. The Compact Flash is available in a broad range of sizes, however, Compact Micro Drives are Not supported. The IDE Hard Drive is the largest supported User Storage device option. Also supported, is a User Upgradeable I/O Option via the Expansion PCI slot.

## Actual Controller Layout (PN 101K54690)



Connector Identification Chart

J1 Power Connector
J2 Keyboard \& LCD Display
J3 Parallel
J5 USB 2.0
J6 10/100 Ethernet
J7 Video Control (Laser)
J8 Expansion PCI
J10 Engine Control
J11 Serial RS232
J12 Compact Flash
J45 DIMM/100 DDR Socket
JF1 Flash Expansion (Allows Service Technician to perform Firmware capture or Code upgrades)

## Removal / Installation process

1. Turn off power to the unit and remove the power cord.
2. Loosen 2 Thumbscrews to release Back Cover

3. Release four internal engine connector cables from the controller $\mathrm{J} 1, \mathrm{~J} 2, \mathrm{~J} 7$ \& J10.
4. Remove three Phillips Pan Head Screws to release Controller from internal chassis mounts

5. Remove any external I/O Cables from the Controller
6. Remove the final two Phillips Screws from I/O Plate to release the controller \& I/O Bracket Assembly from the Engine


## Typical reasons for Controller removal

- No LCD display No panel LED's

NOTE Note: Deep Sleep Mode will interrupt +5V Power to the LCD, resulting in "No Display" this loss of +5 V during Deep Sleep Mode will not disrupt power to the LED's. And should not be mistaken for a "Dead Controller"

NOTE Note: Deep Sleep Mode will also affect any peripheral devices connected to the Centronics Connection that requires +5V Power to be supplied to it via J3 pin 18.

- Any Hard Fault Service Error reporting "Call Service" barring any issues with consumables.
- Obvious damage to the controller from misuse or abuse.
- Dysfunction of any I/O feature, from known good User I/O source.
- Engine not responding properly to Controller commands.
- Intermittent dysfunction relative to temperature differentials.


## Configuration Summary Snapshot



| INFORMATION | OPTIONS |
| :---: | :---: |
| Product Version | User FLASH Installed |
| PostScript Version | Extended Font Set 1 Installed |
| Engine Version | Duplex Installed |
| Network 1 Version | HCF Installed |
| Installed Memory | Finisher Installed |
| Printer Name | 2TM Installed |
| Serial Number |  |
| Asset Tag |  |
| Image Counter |  |
| Sheet Counter |  |
| Toner Page Count |  |
| HID |  |
| Date/Time |  |
| SF1 |  |

```
Status Menu
    Tray 1
        Media Size
        Media Type
        Level
    Tray 2
        Media Size
        Media Type
        Level
    Tray 3 (Optional)
        Media Size
        Media Type
        Level
    Tray 4 (Optional)
        Media Size
        Media Type
        Level
    Face Down Tray
    Offset Tray (optional)
    Toner
    Standard Top Bin
    Stacker Main
    Stacker Top
    Usage Count
```


## Chapter 10 Parts Identification

- The Item Numbers in the illustrations have the corresponding Item Numbers in the list.
- The notation of PL "X.Y.Z" is composed of the plate (PL), item "X.Y", and parts "Z".
- The alphabet characters in the illustrations represent screws and clips as follows: "S": screw, "E": E-ring, "KL": KL clip, "C": C-ring, and "N": nut
- " $\mathbf{V}$ " mark in the illustrations are attached to items indicating assembly parts in the illustrations.
- Encircled alphabetical figures in the illustrations indicate interrupted leader lines. Same characters in the illustrations represent lines to be connected.
- The mark "(with 2-5)" attached to assembly parts on the illustrations and lists represents that the items " $2,3,4$, and 5 " of that plate are contained and the mark "(with $2-5$, PL6.1.1) represent that the item " $2,3,4$, and 5 " of that plate and the item " 1 " of the plate " 6.1 " are contained.
- The mark "[Same PLX.Y.Z]" attached to parts in the illustrations and lists resents that the parts is the same as the parts of the item "Z" of the plate "X.Y".
- The mark "*" attached to parts in the list represents "Note" or "Reference" about parts that are contained in the same page.
- HIGH ASSY" in the list represent the high level assembly containing a specific part/s.
- PL numbers in this document correspond to the part numbers in the accompanying Excel Parts List spreadsheet as noted.
NOTE For spare parts, refer to the "Spare parts list" which is issued separately.
NOTE For the connector (P/J), parts such as harness, wire, etc. in the list, refer to "Chapter 7, Electric wiring"
NOTE It should be noted that configuration of parts may be different or some parts are not used depending on specifications of OEM.


## Engine

## 1 Covers

PL 1.1 Covers (illustration 1 of 2)


## PL 1.1 Covers (1 of 2)

Item
Part Name

COVER LEFT FR COVER-FSR FR,PR COVER-TOP RR,PR BRACKET ILSW SWITCH CONSOLE PANEL

PN 848K06630
HARN ASSY CONPANEL
COVER ASSY TOP PR
COVER ASSY FRONT (with 10-12)
MAGNET CATCH 30
COVER-FRONT
STRIP
COVER ASSY INNER,MN
FOOT FRONT
PLATE SER

## PL 1.2 Covers (illustration 2 of 2)



## PL 1.2 Covers (2 of 2)

| Item | Part Name |
| :---: | :--- |
|  |  |
| 1 | COVER RIGHT UPR |
| 2 | COVER RIGHT LOW |
| 3 | COVER ESS RH |
| 4 | COVER-ESS CAP,PR |
| 5 | COVER REAR UPR |
| 6 | COVER REAR LOW PR |
| 7 | COVER-CAP MCU |
| 8 | FOOT FRONT |
| 9 | FOOT REAR LEFT |
| 10 | -- |
| 11 | -- |

2 Tray \& Feeder


## PL 2.1 Tray (1/2) \& Feeder (1/2)

Item Part Name Remarks

1 STOPPER-TRAY,FR

2

10 LABEL TRAY NO1
SPACER TRAY G
TRAY ASSY (PL2.2)
SWITCH ASSY P S
BRACKET-SW
CHUTE ASSY FEEDER
FEEDER ASSY (PL2.3.1)

LABEL TRAY NO2
LABEL INST,M/N
CHUTE FEED OUT
PAD ASSY LH LOW
COVER SENSOR

CHUTE ASSY FEEDER 2 (with 13, 14)

KIT TRAY (with 3, 10, 11, 12, PL20.2.2, PL20.2.3)

## PL 2.2 Tray (2/2) illustration



PL 2.2 Tray (2/2)

| Item | Part Name |
| :--- | :--- |
| 1 | Remarks |
| 1 | TRAY ASSEMBLY (with 5-26) |
| 2 | TRAY COVER |
| 3 | -- |
| 4 | LABEL (MAX) |
| 5 | BOTTOM PAD |
| 6 | FRONT SIDE GUIDE ASSY |
| 7 | -- |
| 8 | TRAY PAD |
| 9 | REAR SIDE GUIDE |
| 10 | BOTTOM PLATE |
| 11 | TRAY |
| 12 | SIDE GUIDE ACTUATOR |
| 13 | GUIDE ACTUATOR |
| 14 | PINION GEAR |
| 15 | END GUIDE |
| 16 | SPRING |
| 17 | END GUIDE ACTUATOR |
| 18 | LINK |
| 19 | COUPLING GEAR (13T) |
| 20 | GEAR (13T/60T) |
| 21 | SECTOR GEAR (60T) |
| 22 | BRACKET |
| 23 | IFT UP SHAFT |
| 24 | STOPPER |
| 26 |  |

## PL 2.3 Feeder (2/2) illustration




PN 604K20530 Included in Maintenance kit (per 300K print)

## 3 MPF Assembly

## PL 3.1 MPF Assembly illustration



| PL 3.1 <br> Item | MPF Assembly <br> Part Name | Remarks |
| :--- | :--- | :--- |
|  |  |  |
| 1 | FEEDER ASSY MPF (with 2-12, 15-19) |  |
| 2 | FRAME UPPER |  |
| 3 | ACTUATOR |  |
| 4 | SENSOR-PHOTO IN |  |
| 5 | HARNESS ASSY MPF |  |
| 6 | SPRING MPF |  |
| 7 | BRKT ASSY-GEAR |  |
| 8 | CHUTE PINCH |  |
| 9 | ROLL ASSY-PINCH |  |
| 10 | CHUTE LOW |  |
| 11 | FRAME ASSY LOWER (PL3.2.1) |  |
| 12 | TRAY ASSY-MPF (PL3.3.1) P609 |  |
| 13 | COVER-MPF FR |  |
| 14 | COVER-MPF RR |  |
| 15 | CHUTE ASSY PINCH |  |
| 16 | GUIDE PINCH |  |
| 17 | SPRING PINCH |  |
| 18 | SPACER SPRING PINCH |  |
| 19 | SHAFT PINCH |  |
| 20 | WIRE SADDLE |  |

## PL 3.2 MPF Lower Frame Assembly illustration

マ 1 (with 2-28)


| PL 3.2 | MPF Lower Frame Assembly |  |
| :---: | :--- | :--- |
| Item | Part Name | Remarks |
|  |  |  |
| 1 | FRAME ASSY LOWER (with 2-28) |  |
| 2 | FRAME LOWER MPF |  |
| 3 | STOPPER LEVER |  |
| 4 | COLLAR |  |
| 5 | SHAFT-RETARD |  |
| 6 | GEAR PICK UP |  |
| 7 | GEAR 18T |  |
| 8 | LEVER-GEAR |  |
| 9 | BEARING 8 |  |
| 10 | PAD BOTTOM |  |
| 11 | PLATE BOTTOM |  |
| 12 | PAD ASSY RETARD |  |
| 13 | GUIDE PAPER MPF |  |
| 14 | ROLL ASSY-DRIVE |  |
| 15 | SOLENOID PICK UP |  |
| 16 | SHAFT ASSY-PICK UP |  |
| 17 | CAM PICK UP 2 |  |
| 18 | CAM PICK UP FRONT |  |
| 19 | ROLL CORE |  |
| 20 | ROLLER ASSY-FEED |  |
| 21 | BEARING SLEEVE |  |
| 22 | GEAR CAM |  |
| 23 | SPRING LEVER GE |  |
| 24 | SPRING PAD |  |
| 25 | SPRING N F |  |
| 26 | SPRING-GEAR CAM |  |
| 27 | PLATE EARTH BOTTOM |  |
| 28 | PLATE EARTH FRONT |  |
|  |  |  |

## PL 3.3 MPF Tray Assembly illustration



## PL 3.3 MPF Tray Assembly

Item Part Name Remarks

| 1 | TRAY ASSY-MPF (with 2-13) |
| :--- | :--- |
| 2 | GEAR-PINION |
| 3 | RACK-FRONT |
| 4 | RACK-REAR |
| 5 | LINK-SENSOR |
| 6 | GUIDE-SIDE FRONT |
| 7 | GUIDE-SIDE REAR |
| 8 | TRAY MPF |
| 9 | TRAY EXT |
| 10 | SENSOR ASSY-MPF |
| 11 | COVER TRAY |
| 12 | SPRING-SENSOR |
| 13 | HARNESS ASSY SIZE |

## 4 L/H Lower

$\boldsymbol{\nabla} 1$ (with 2, 3)


| PL 4.1 L/H Lower |  |
| :---: | :--- |
| Item | Part Name |
|  |  |
| 1 | BRKT ASSY TA (with 2, 3) |
| 2 | BRACKET ASSY IDLER |
| 3 | SWITCH-I/L,CAB |
| 4 | RIVET |
| 5 | CHUTE-LOWER |
| 6 | BEARING TA |
| 7 | GEAR-18T |
| 8 | ROLLER ASSY-TA |
| 9 | BEARING SLEEVE |
| 10 | COVER ASSY LH LOW C (with 11-22) |
| 11 | CHUTE LH LOW C |
| 12 | HANDLE LH LOW |
| 13 | SPRING-COMP LH LOW |
| 14 | COVER LH LOW C |
| 15 | PLATE-EARTH |
| 16 | BRKT ASSY LH LOW C (with 17-22) |
| 17 | BRKT LH LOW |
| 18 | ROLLER-TA PINCH |
| 19 | BEARING-OUT |
| 20 | BEARING-IN |
| 21 | SPRING LH LOW |
| 22 | SPRING |

## PL 4.2 L/H Upper illustration




## PL 4.3 L/H Chute Assembly illustration

- 1 (with 2-9)



## PL 4.3 L/H Chute Assembly

| Item | Part Name | Remarks |
| :--- | :--- | :--- |
|  |  |  |
| 1 | CHUTE ASSY LH (with 2-9) | PN 054K24054 |
| 2 | BEARING-PINCH OUT |  |
| 3 | ROLLER ASSY-REGI-P | PN 059K32931 |
| 4 | CHUTE-ASSY |  |
| 5 | SPRING COMP FL |  |
| 6 | GUIDE |  |
| 7 | SPRING COMP PINCH |  |
| 8 | PLATE-TIE |  |
| 9 | PLATE-EARTH |  |

## PL 4.4 L/H Cover Assembly illustration

- 1 (with 2-12)




## PL 4.4 L/H Cover Assembly

Item
Part Name
Remarks

| 1 | COVER ASSY-LH (with 2-12) |
| :---: | :--- |
| 2 | HANDLE-LH |
| 3 | ROD CRU SHUTTER |
| 4 | CHUTE LHCOV |
| 5 | -- |
| 6 | CHUTE ASSY-DUP |
| 7 | FRAME ASSY LH |
| 8 | COVER LH |
| 9 | SPRING COMP LH |
| 10 | SUPPORT-LHCOVER |
| 11 | CHUTE-EXIT |
| 12 | GUIDE HANDLE LH |

## PL 4.5 Registration illustration



## PL 4.5 Registration

Item Part Number

Remarks

| 1 | TRNS ASSY REGI (with 2-8) | PN 059K45960 |
| :---: | :---: | :---: |
| 2 | CLUTCH ASSY REGI H | PN 121K37450 |
| 3 | CHUTE-REGI |  |
| 4 | ROLLER REGI IDLER |  |
| 5 | ROLLER ASSY REGI |  |
| 6 | BEARING REGIE |  |
| 7 | SNR ASSY REGI |  |
| 8 | PLATE-EARTH FG |  |
| 9 | CHUTE-TA |  |
| 10 | CHUTE ASSY-R |  |
| 11 | BEARING |  |
| 12 | SHAFT TA |  |
| 13 | GEAR-19T |  |
| 14 | CLUTCH ASSY-TA | PN 121K32730 |
| 15 | BRACKET TA |  |
| 16 | BEARING |  |
| 17 | CHUTE-TA ASSY (with 9, 18, 19) |  |
| 18 | SENSOR |  |
| 19 | HARNESS | J150, J623 |
| 20 | PUSH TIE |  |
|  | \& Toner Dispense |  |

## PL 5.1 ROS, CRU \& Toner Dispense illustrations



## PL 5.1 ROS, CRU \& Toner Dispense

Item Part Name Remarks

| 1 | BLOCK STOPPER CRU |  |
| :--- | :--- | :--- |
| 2 | SCREW |  |
| 3 | PLATE-SW-INTLK |  |
| 4 | SWITCH ASSY XERO INTLK |  |
| 5 | SENSOR HUM \& TE |  |
| 6 | GUIDE ASSY SUB |  |
| 7 | HSG ASSY LASER C |  |
| 8 | PWBA CRUM CP1 |  |
| 9 | HARN ASSY FRONT A | J104, J150, J403, J500, P215, P610 |
| 10 | GUIDE ASSY CTG30 SUB |  |
| 11 | MOTOR ASSY-DISP 30K | PN 127K38040 |
| 12 | DUCT FUSER |  |
| 13 | FAN FUSER | PN 127K37881 |
| 14 | ROS ASSY-12 | PN 062K13615 |
| 15 | CRU |  |
| 16 | TONER CARTRIDGE |  |
| 17 | DUCT INTAKE |  |
| 18 | CRU FAN |  |

6 Fuser \& Exit 1 Unit

PL 6.1 Fuser \& Exit 1 Unit illustrations


## PL 6.1 Fuser \& Exit 1 Unit

Item
Part Name
Remarks

| 1 | SHAFT-ACTUATOR |
| :--- | :--- |
| 2 | -- |
| 3 | ACTUATOR-EXIT |
| 4 | SENSOR PHOTO |
| 5 | SPRING-ACTUATOR |
| 6 | BRKT-SENSOR,EXIT |
| 7 | FUSER ASSY |

8
TRANS ASSY EXIT (PL6.2)

## PL 6.2 Exit 1 illustration



## PL 6.2 Exit 1

| Item | Part Name | Remarks |
| :---: | :---: | :---: |
| 1 | TRANS ASSY EXIT (with 2-21, 34, 35) |  |
| 2 | HARN ASSY EXIT 1 C | J11B, J117, J613 |
| 3 | MOTOR ASSY-OFFSET |  |
| 4 | PLATE-EARTH MOTOR |  |
| 5 | SENSOR-PHOTO IN |  |
| 6 | BEARING |  |
| 7 | GEAR-19T |  |
| 8 | CAP |  |
| 9 | GEAR-EXIT |  |
| 10 | BEARING ROLL |  |
| 11 | CHUTE-OCT 1 |  |
| 12 | SPRING-PINCH EXIT |  |
| 13 | RLR-PINCH EXIT |  |
| 14 | ROLL ASSY OCT |  |
| 15 | CHUTE-LOW |  |
| 16 | BRACKET SENSOR |  |
| 17 | GEAR-OFFSET |  |
| 18 | SPRING-GATE |  |
| 19 | GATE-EXIT 1 |  |
| 20 | BEARING |  |
| 21 | PLATE-EARTH |  |
| 22 | COVER-TOP,EXIT 1 |  |
| 23 | BRKT-EXIT 2 |  |
| 24 | ELIMINATOR EXIT |  |
| 25 | GUIDE-TRAY EXIT 1 |  |
| 26 | ACTUATOR FULLSTACK |  |
| 27 | ACTUATOR |  |
| 28 | WEIGHT ASSY-PAPER |  |
| 29 | PAD EXIT A |  |
| 30 | PAD EXIT B |  |
| 31 | PAD EXIT C |  |
| 32 | ABEL EXIT 1 XC |  |
| 33 | LABEL CAUTION XC |  |
| 34 | SEAL A |  |
| 35 | SEAL B |  |

7 Drive

## PL 7.1 Drive illustration



## PL 7.1 Drive

Item Part Name Remarks
1 COLLAR

2 GEAR 21/21T MPF
3 GEAR 18T MPF
4 GEAR 28T TA
5 BELT-SYNCHRONOUS BAN PN 423W13155
6 DRIVE ASSY 242 (with 7, 8) PN 007K88598
7 MOTOR ASSY 242
8 PULLEY 25T
9 FLANGE EXIT
8 Electrical

## PL 8.1 Electrical (1/2) illustration



## PL 8.1 Electrical (1/2)

| Item | Part Name | Remarks |
| :---: | :---: | :---: |
| 1 | PSHV-Y2 | PN 105E17590 |
| 2 | SWITCH-POWER |  |
| 3 | BRACKET-SW CPR |  |
| 4 | PWBA EXIT |  |
| 5 | PWBA MCU F | PN 960K32300 |
| 6 | PWB SUPP EDGE |  |
| 7 | BRACKET MCU |  |
| 8A | POWER UNIT-C1 (100/127) | PN 105E11391 |
| 8B | POWER UNIT C1H (200/240) | PN 105E11401 |
| 9 | CHOKE COIL (220/240) |  |
| 10 | CHAS ASSY AC XC (with 11-16) |  |
| 11 | SCREW |  |
| 12 | BRACKET-CONN AC |  |
| 13 | BREAKER GFI INL | PN 908W01201 |
| 14 | HARNESS ASSY F/G,E |  |
| 15 | HARN ASSY AC US EU | J2, J11, J12, J50 |
| 16 | OUTLET MN |  |
| 17 | -- |  |
| 18 | -- |  |
| 19 | -- |  |
| 20 | COVER ASSY ESS |  |
| 21 | PANEL ASSY CONN HCF |  |
| 22 | BRKT GUIDE PRX |  |
| 23 | CHASSIS ASSY ESS PRX |  |
| 24 | BRKT-EXIT LOW |  |
| 25 | PWBA ESS | PN 101K54690 |
| 26 | PLATE ASSY LVPS |  |

## PL 8.2 Electrical (2/2) illustration



## PL 8.2 Electrical (2/2)

| Item | Part Name | Remarks |
| :---: | :---: | :---: |
| 1 | HARN ASSY FEEDER C | J409, P601, P602 |
| 2 | HARN ASSY MPF A | J411, P605 |
| 3 | HARN ASSY SIZE A | J412, J109, J110 |
| 4 | HARN ASSY ESS C | J402, J301 |
| 5 | HARN ASSY ROS C | J406, J302, J140, J160, J170, J620 |
| 6 | HARN ASSY EXIT C | J432, J433, J434, J606, P205, P613 |
| 7 | HARN ASSY PH C | J410, J106, J125, P60B, P607, P204 |
| 8 | HARN ASSY FUSER AC C | J6, J600, J607 |
| 9 | HARN ASSY LV PWR C | $\begin{aligned} & \text { J400, J401, J420, J421, J216, J300, J430, J431, } \\ & \text { J521, J525, J526 } \end{aligned}$ |
| 10 | HARN ASSY INTLK A | J120, J121, J405 |
| 11 | HARN ASSY MAIN SW C | J1, J56, J57, J68, J69 |
| 12 | HARN ASSY DRIVE A | J40B, J214 |
| 13 | WIRE HARNESS CRUM B | J419, P126, P127 |

## 1000 Sheet Feeder

## 9 Covers

PL 9.1 Covers illustration


## PL 9.1 Covers

Item
Part Number
Remarks

| 1 | TOP COVER |
| :---: | :--- |
| 2 | FOOT COVER |
| 3 | RIGHT COVER |
| 4 | LEFT COVER |
| 5 | REAR COVER |
| 6 | CASTER (STOPPER) |
| 7 | CASTER |
| 8 | FOOT ADJUSTER |
| 9 | BRACKET REAR RH 2T |
| 10 | BRACKET REAR LH 2T |

## PL 9.2 Tray (1/2) \& Feeder (1/2) illustrations



## PL 9.2 Tray (1/2) \& Feeder (1/2)

Item Part Name Remarks

1 TRAY 3/4 ASSEMBLY (PL20.3)
2 LABEL (No.3)
3 LABEL (No.4)
4 TRAY 3/4 PAPER SIZE SWITCH
5 TRAY SPACER
6 TRAY STOPPER
7 TRAY 3 FEEDER (PL20.4.1)
8 TRAY 4 FEEDER (PL20.4.1)
9 CHUTE ASSY FEEDER 2 (with 12, 13)
10 COVER SENSOR
11 COVER FDR
12 CHUTE FEED OUT
13 PAD ASSY LH LOW
14 BLOCK SLIDE LOCK

## PL 9.3 Tray (2/2) illustration



| PL 9.3 | Tray (2I2) |
| :---: | :--- |
| Item | Part Number |
|  |  |
| 1 | TRAY ASSEMBLY (with 5-26) |
| 2 | TRAY COVER |
| 3 | -- |
| 4 | LABEL (MAX) |
| 5 | BOTTOM PAD |
| 6 | FRONT SIDE GUIDE ASSY |
| 7 | -- |
| 8 | TRAY PAD |
| 9 | REAR SIDE GUIDE |
| 10 | BOTTOM PLATE |
| 11 | TRAY |
| 12 | SIDE GUIDE ACTUATOR |
| 13 | GUIDE ACTUATOR |
| 14 | SPRING |
| 15 | PINION GEAR |
| 16 | END GUIDE |
| 17 | SPRING |
| 18 | END GUIDE ACTUATOR |
| 19 | LINK |
| 20 | COUPLING GEAR (13T) |
| 21 | GEAR (13T/60T) |
| 22 | SECTOR GEAR (60T) |
| 23 | BRACKET |
| 24 | LIFT UP SHAFT |
| 25 | STOPPER |
| 26 | SEAL |
|  |  |

## PL 9.4 Feeder (2/2) illustration



| PL 9.4 Feeder (2/2) |  |  |
| :---: | :---: | :---: |
| Item | Part Name | Remarks |
| 1 | FEEDER ASSEMBLY (with 2-50) |  |
| 2 | TRAY 1/2 FEED LIFT UP MOTOR |  |
| 3 | BRACKET |  |
| 4 | SPACER |  |
| 5 | GEAR (31T) |  |
| 6 | SPRING |  |
| 7 | ONEWAY CLUTCH |  |
| 8 | ONEWAY GEAR |  |
| 9 | GEAR (13T) |  |
| 10 | BEARING |  |
| 11 | SHAFT |  |
| 12 | FRONT CHUTE |  |
| 13 | ACTUATOR |  |
| 14 | SENSOR |  |
| 15 | SENSOR |  |
| 16 | WIRE HARNESS | J101, J102, J103, J220, J661 |
| 17 | GEAR (28T/21T) |  |
| 18 | GEAR (29T) |  |
| 19 | SPRING |  |
| 20 | ROLLER ASSY | Periodical replacement parts (per 300k print) |
| 21 | ONEWAY CLUTCH |  |
| 22 | ONEWAY GEAR (22T) |  |
| 23 | SHAFT |  |
| 24 | CHUTE |  |
| 25 | SPRING |  |
| 26 | FRICTION CLUTCH |  |
| 27 | SHAFT-RETARD |  |
| 28 | -- |  |
| 29 | SPACER |  |
| 30 | GEAR (33T) |  |
| 31 | SHAFT-NUDGER |  |
| 32 | -- |  |
| 33 | GEAR (25T) |  |
| 34 | LOWER FRAME |  |
| 35 | BEARING |  |
| 36 | GEAR (27T) |  |
| 37 | LEVER |  |
| 38 | BEARING |  |
| 39 | WASHER |  |
| 40 | UPPER FRAME |  |
| 41 | -- |  |
| 42 | HOLDER HARNESS CTR |  |
| 43 | HOLDER HARNESS REAR |  |
| 44 | HOLDER HARNESS UPPER |  |

RAIL
SUPPORT RETARD

## SUPPORT NUDGER

Periodical replacement parts (per 300k print)

## PL 9.5 Transportation illustration



| Item | Part Number Remarks |
| :---: | :---: |
| 1 | CHUTE |
| 2 | COVER |
| 3 | TRAY 3 FEED OUT SENSOR |
| 4 | WIRE HARNESS J821, J841 |
| 5 | CHUTE |
| 6 | TRAY 4 FEED OUT SENSOR |
| 7 | WIRE HARNESS J825, J842 |
| 8 | TAKEAWAY ROLL ASSEMBLY |
| 9 | BEARING |
| 10 | LEFT COVER ASSEMBLY (with 11-23) |
| 11 | ROLL ASSY (with 12-16) |
| 12 | BRACKET |
| 13 | BEARING |
| 14 | BEARING |
| 15 | PINCH ROLL |
| 16 | SPRING |
| 17 | CHUTE |
| 18 | ACTUATOR |
| 19 | HOOK |
| 20 | LEFT COVER |
| 21 | SPRING |
| 22 | LATCH |
| 23 | HANDLE |
| 24 | BRACKET |
| 25 | SUPPORT |
| 26 | BRACKET ASSEMBLY |
| 27 | LEFT COVER INTERLOCK SWITCH |

## PL 9.6 Drive \& Electrical illustration




## Duplex Unit

## 10 Duplex Unit

## PL 10.1 Duplex Unit illustration



| PL 10.1 <br> Item | Duplex Unit <br> Part Name | Remarks |
| :--- | :--- | :--- |
|  |  |  |
| 1 | TRANS ASSY DUP (with 2-24) |  |
| 2 | GEAR ROLL 28 |  |
| 3 | GEAR IDLE 33 74 |  |
| 4 | GEAR IDLE 33 |  |
| 5 | GEAR IDLE 42 |  |
| 6 | LEVER LATCH RR |  |
| 7 | LEVER LATCH FR |  |
| 8 | CHUTE LOWER |  |
| 9 | SWITCH-I/L,CAB |  |
| 10 | ACTUATOR DUP |  |
| 11 | MOTOR ASSY DUP |  |
| 12 | PWBA DUPLEX |  |
| 13 | COVER DUP |  |
| 14 | SPRING LATCH |  |
| 15 | SPRING ACTUATOR DUP |  |
| 16 | BRACKET MOTOR |  |
| 17 | PLATE LATCH |  |
| 18 | SENSOR-PHOTO IN |  |
| 19 | INNER CHUTE ASSEMBLY (PL23.2) |  |
| 20 | HARN ASSY DUP SNR | J123, J124, J541 |
| 21 | HARN ASSY DUP MOT | J542, P212 |
| 22 | HARN ASSY DUP A | J417, J540 |
| 23 | FAN-DUP |  |
| 24 | DUCT-DUP |  |

## PL 10.2 Inner Chute Assembly illustration



## PL 10.2 Inner Chute Assembly

Item Part Name Remarks

| 1 | STOPPER DUP |
| :---: | :--- |
| 2 | LOCK DUP |
| 3 | BEARING DUP |
| 4 | PIN DUP |
| 5 | CHUTE OUTER |
| 6 | CHUTE INNER |
| 7 | ROLLER DUP A3L |
| 8 | ROLLER ASSY DUP |
| 9 | ROLLER PINCH DUP |
| 10 | SPRING PINCH DUP |

## Exit 2

## 11 Exit 2

PL 11.1 L/H Upper Chute Assembly illustration


| Item | Part Name Remar |
| :---: | :---: |
| 1 | TRANS ASSY EXIT2 (with 2-27, PL24.2) |
| 2 | HANDLE LATCH |
| 3 | GATE-EXIT,2 |
| 4 | SPRING-GATE 2 |
| 5 | CHUTE-UPPER,FU |
| 6 | STOPPER EXIT2 |
| 7 | COVER-GEAR |
| 8 | GEAR-52Z |
| 9 | GEAR-19Z |
| 10 | PLATE-EARTH INV |
| 11 | COVER FUP EXIT |
| 12 | PLATE-EARTH FU |
| 13 | -- |
| 14 | -- |
| 15 | -- |
| 16 | BEARING |
| 17 | BEARING |
| 18 | CHUTE LH HIGH |
| 19 | -- |
| 20 | ROLL ASSY-INV |
| 21 | BRKT ASSY TRAY |
| 22 | BRKT ASSY LINK |
| 23 | LINK-FU |
| 24 | SPRING LATCH |
| 25 | FRONT EXIT 2 COVER |
| 26 | REAR EXIT 2 COVER |
| 27 | LABEL-LH-HIGH |

## PL 11.2 Tray Guide Assembly illustration




Finisher Unit

## 12 Finisher Unit

PL 12.1 Finisher Unit illustration


## PL 12.1 Finisher Unit

Item
Part Name
Remarks

| 1 | SCREW |
| :--- | :--- |
| 2 | H-TRANSPORT ASSEMBLY (PL25.2, PL25.3) |
| 3 | STAPLE FINISHER (PL25.4-PL25.15) |
| 4 | -- |
| 5 | -- |
| 6 | LABEL |

PL 12.2 H-Transport Assembly (1/2) illustration


## PL 12.2 H-Transport Assembly (1/2)

Item
Part Name

Remarks

| 1 | COVER TOP, C |
| :--- | :--- |
| 2 | HINGE ASSEMBLY (LEFT) |
| 3 | HINGE ASSEMBLY (RIGHT) |
| 4 | BRACKET-MAGNET |
| 5 | SPRING-CHUTE |
| 6 | PINCH ROLL |
| 7 | SPRING-PINCH |
| 8 | UPPER CHUTE |
| 9 | COVER ASSY TOP (with 1-8) |

## PL 12.3 H-Transport Assembly (2/2) illustration




## PL 12.4 Finisher Cover (1/2) illustration



PL 12.4 Finisher Cover (1/2)
Item
Part Name
Remarks

| 1 | COVER TOP |
| :--- | :--- |
| 2 | GUIDE TRAY SPRING |
| 3 | TRAY ASSY SCT |
| 4 | COVER EJECT |
| 5 | TRAY ASSY STACKER |
| 6 | COVER BOTTOM |
| 7 | CASTER |
| 8 | CASTER |
| 9 | COVER REAR LOWER |
| 10 | COVER-CONNECTOR H-TRA |
| 11 | COVER REAR UPPER |
| 12 | NUT M12X1.25 |
| 13 | PLATE COVER |

PL 12.5 Finisher Cover (2/2) illustration


## PL 12.5 Finisher Cover (2/2)

| Item | Part Name |
| :---: | :--- |
|  |  |
| 1 | COVER FRONT TOP |
| 2 | INTERLOCK SWITCH |
| 3 | COVER ASSY FRONT (with 4, 5, 12) |
| 4 | BRACKET ASSY HINGE |
| 5 | COVER INNER |
| 6 | PLATE DOCKING |
| 7 | SPRING |
| 8 | COVER FRONT L/H |
| 9 | COVER LH TOP |
| 10 | PLATE ASSY DOCKING IOT |
| 11 | SCREW |
| 12 | BRACKET-COVER |



| PL 12.6 | Finisher Stack |
| :--- | :--- |
| Item | Part Name |
|  |  |
| 1 | CARRIAGE TRAY |
| 2 | CARRIAGE ASSY L (with 3-5) |
| 3 | BELT STACKER |
| 4 | CARRIAGE ASSY L |
| 5 | CLAMP BELT |
| 6 | SPRING |
| 7 | BEARING CARRIAGE |
| 8 | CARRIAGE ASSY R (with 3, 5, 11, 12) |
| 9 | -- |
| 10 | -- |
| 11 | CARRIAGE ASSY R |
| 12 | ACTUATOR |
| 13 | COVER ASSY SENSOR |
| 14 | SHAFT-ELEV |
| 15 | BEARING |
| 16 | PULLEY T18 |
| 17 | SENSOR |
| 18 | PULLEY DOC. CLUTCH |
| 19 | GEAR DOC. CLUTCH |
| 20 | SPRING DOC. |
| 21 | WASHER |
| 22 | BRACKET ASSY (with 17) |
| 23 | ENCODER |
| 24 | BRACKET ASSY STACKER (with 25, 26) |
| 25 | BELT |
| 26 | MOTOR ASSY DC |
| 27 | BEARING 10x6 |
|  |  |

PL 12.7 Finisher Punch illustration


| PL 12.7 Finisher Punch |  |
| :---: | :---: |
| Item | Part Name Remarks |
| 1 | FRAME ASSY-PUNCH ALL (with 2-18) |
| 2 | HARNESS ASSY PUNCH UNIT J8345, J8346, J8347, J8348, J8349, J8350, J8351, P8332, P8333 |
| 3 | COVER-MOTOR, PUNCH |
| 4 | BRACKET ASSY-MOTOR, PUNCH |
| 5 | HOLDER-FRAME ASSY |
| 6 | BRACKET ASSY SENSOR HOL (with 8) |
| 7 | COVER-FRONT, PUNCH |
| 8 | SENSOR |
| 9 | BRACKET ASSY-PUNCH (with 2, 6, 11-16, 22, 23) |
| 10 | COVER-LEFT, PUNCH |
| 11 | GUIDE ASSY |
| 12 | MOTOR ASSY |
| 13 | SENSOR |
| 14 | BRACKET ASSY (with 12, 13) |
| 15 | SENSOR |
| 16 | BRACKET 2\&4 (REF ONLY) |
| 17 | SENSOR |
| 18 | BRACKET ASSY-SENSOR (with 17) |
| 19 | CHUTE ASSY DUST BOX |
| 20 | DUST BOX |
| 21 | SENSOR |
| 22 | CHUTE ASSY-S REGI |
| 23 | GUIDE BOX |
| 24 | BRACKET-OPB PUNCH |
| 25 | BRACKET-OPB FRAME F |
| 26 | SENSOR |
| 27 | BRACKET |
| 28 | HARNESS ASSY PUNCH BOX SET |
| 29 | HARNESS ASSY PUNCH FULL SNRJ8353, P8355 |
| 30 | BRACKET ASSY DUST BOX J8452, 38500 |

## PL 12.8 Finisher Staple illustration



## PL 12.8 Finisher Staple

| Item | Part Name Rem | Remarks |
| :---: | :---: | :---: |
| 1 | CARTRIDGE ASSY-STAPLES |  |
| 2 | STAPLER ASSY |  |
| 3 | COVER STAPLER |  |
| 4 | HOLDER STAPLER |  |
| 5 | SENSOR |  |
| 6 | GUIDE HARNES, STAPLER |  |
| 7 | HARNESS ASSY STAPLE J8308, | J8308, J8354, J8356, J8357, J8358 |
| 8 | CARRIAGE ASSY UPPER, STAPLER |  |
| 9 | CARRIAGE ASSY LOWER, STAPLER | R PN 041K94750 |
| 10 | RAIL-UPPER |  |
| 11 | FRAME ASSY STAPLER |  |
| 12 | BASE-RAIL (REF ONLY) |  |
| 13 | STOPPER-CHUTE (REF ONLY) |  |
| 14 | STAPLER UNIT (with 1-10) (REF ONLY | NLY) |

## PL 12.9 Finisher Eject (1/3) illustration



## PL 12.9 Finisher Eject (1/3)

Item Part Name Remarks

CHUTE ASSY EJECT (with 2)
MAGNET 25N
SOLENOID ASSY
BRACKET SOLENOID
SPRING-PINCH
PADDLE-CYCLONE
SHAFT ASSY-EJECT PINCH (with 6)
SPRING SOLENOID
SHAFT ASSY PADDLE
BRACKET ASSY-EJECT CLAMP (with 11-13)
MOTOR ASSY-DC
BRACKET-EJECT CLAMP
SENSOR
LEVER ASSY
BEARING
GEAR Z23
BEARING
GEAR-CAM Z70
GEAR Z23L
GEAR Z68L/Z20L
CLAMP
BRACKET SWITCH
SENSOR ASSY
KNOB ASSY-ENT
EDGE SADDLE
CLAMP
CHUTE ASSY EJECT UNIT (with 1-7) (REF ONLY)

## PL 12.10 Finisher Eject (2/3) illustration



## PL 12.10 Finisher Eject (2/3)

| Item | Part Name | Remarks |
| :--- | :--- | :--- |
|  |  |  |
| 1 | TRAY ASSY-COMPILER (with 2-8) |  |
| 2 | SENSOR |  |
| 3 | SENSOR |  |
| 4 | ACTUATOR-PAPER |  |
| 5 | -- |  |
| 6 | MOTOR ASSY 2 |  |
| 7 | MOTOR ASSY |  |
| 8 | HARNESS ASSY COMPILER 2 J8359, J8360, J8361, J8461A, P8362, P8363 |  |
| 9 | SHAFT ASSY-EJECT ROLL (with 10) |  |
| 10 | GADDLE-SET CLAMP |  |
| 11 | BEARING |  |
| 12 | GEARING |  |
| 13 | CLEAR |  |
| 14 | ACTUATOR SET CLAMP |  |
| 15 | BRACKET ASSY-EJECT (with 18) |  |
| 16 | SENSOR |  |
| 17 | PLATE |  |
| 18 | HARNESS ASSY COMPILER 1 |  |
| 19 | J8309, J8461B |  |
| 20 |  |  |

## PL 12.11 Finisher Eject (3/3) illustration



| PL 12.11 | Finisher Eject (3/3) |
| :--- | :--- |
| Item | Part Name |
|  |  |
| 1 | BRACKET ASSY-SENSOR (with 2, 3) |
| 2 | HARNESS ASSY COMP SNR J8320, P8391 |
| 3 | SENSOR ASSY |
| 4 | ELIMINATOR |
| 5 | CHUTE-UPPER, EXIT |
| 6 | ROLL ASSY-EXIT LOW |
| 7 | CHUTE ASSY-LOWER, EXIT R (with 8-13) |
| 8 | CHUTE ASSY-LOWER, EXIT R |
| 9 | BEARING |
| 10 | ROLLER ASSY-PINCH, EXIT 1 |
| 11 | ROLLER ASSY-PINCH, EXIT 2 |
| 12 | SHAFT ASSY-PADDLE |
| 13 | BELT-SYNCRONUS Z55 |
| 14 | PULLEY T17 |
| 15 | SHAGT-DRIVE PADDLE |
| 16 | PULLEY |
| 17 | BEARING |
| 18 | PULLEY T20 |
| 19 | GEAR Z23L |
| 20 | PULLEY T20 |
| 21 | PULLEY T44/Z20 |
| 2 | GEAR Z23R |



| PL 12.12 | Finisher Transport (1/2) |
| :--- | :--- |
| Item | Part Name |
|  |  |
| 1 | CHUTE ASSY-UPPER, EXIT OPEN (with 2-5) |
| 2 | ROLLER-PINCH |
| 3 | SPRING 1.9N |
| 4 | SHAFT |
| 5 | SPRING-TORSION |
| 6 | GATE |
| 7 | GATE-BUFFER |
| 8 | MAGNET 25N |
| 9 | BEARING |
| 10 | CHUTE ASSY BUFFER TOP (with 11, 12) |
| 11 | BRACKET-SENSOR |
| 12 | SENSOR ASSY |
| 13 | ROLL ASSY-BUFFER |
| 14 | CHUTE ASSY-BUFFER BOTTOM (with 8, 15) |
| 15 | ROLLER ASSY-PINCH, EXIT |
| 16 | CHUTE ASSY-UPPER, ENT (with 17-19) |
| 17 | ROLLER ASSY-PINCH, ENT |
| 18 | BRACKET-SENSOR |
| 19 | SENSOR |
| 20 | ROLL ASSY-ENT |
| 21 | MOTOR ASSY |
| 22 | BRACKET MOTOR |
| 23 | BELT |
| 24 | PULLEY |
| 25 | SPRING-TENSION |
| 26 | BRACKET ASSY-TENSION |
| 27 | BEARING |
| 28 | GEAR Z46 |
| 29 | PULLEY T20 |
| 30 | LINK-BUFFER |
| 31 | GEAR Z23 |
| 32 | BRACKET ASSY SOL |
| 33 | LINK |
| 34 | BRACKET ASSY SOL |
| 35 | KNOB |
| 36 | BRACKET STOPPER |
|  |  |

## PL 12.13 Finisher Transport (2/2) illustration



| PL 12.13 | Finisher Transport (2/2) |  |
| :--- | :--- | :--- |
| Item | Part Name | Remarks |
|  |  |  |
| 1 | CHUTE ASSY UPPER, TOP EXIT R (with 2, 3) |  |
| 2 | SENSOR |  |
| 3 | ROLLER ASSY-PINCH, EXIT |  |
| 4 | CHUTE ASSY-LOWER, TOP EXIT R |  |
| 5 | ROLL ASSY-EXIT TOP |  |
| 6 | BRACKET ASSY-SENSOR (with 7) |  |
| 7 | SENSOR |  |
| 8 | MAGNET 25N |  |
| 9 | BEARING |  |
| 10 | CHUTE ASSY-LOWER, TOP EXIT L (with 11-13) |  |
| 11 | ROLLER-PINCH |  |
| 12 | SPRING 1.5N |  |
| 13 | SHAFT |  |
| 14 | CHUTE ASSY-UPPER, TOP EXIT L (with 15-17) |  |
| 15 | SENSOR |  |
| 16 | HARNESS ASSY-SNR |  |
| 17 | BRACKET-SENSOR |  |
| 18 | ROLL ASSY-TRANSPORT |  |
| 19 | PULLEY T53/Z23 |  |
| 20 | BEARING |  |
| 21 | PULLEY |  |
| 22 | PULLEY |  |
| 23 | BRACKET ASSY-TENSION |  |
| 24 | SPRING-TENSION |  |
| 25 | PULLEY T20/Z20 |  |
| 26 | GEAR |  |
| 27 | BELT | BELT |

## PL 12.14 Finisher Electrical illustration



| PL 12.14 <br> Item | Finisher Electrical |  |
| :---: | :--- | :--- |
|  | Part Name | Remarks |
| 1 |  |  |
| 2 | BRACKET HARNESS |  |
| 3 | BRACKET HARNESS L/H |  |
| 4 | HAR H-TRAJ8372, J8390 | PN 960K17130 |
| 5 | PWB MAIN-C |  |
| 6 | BRACKET-PWBA MAIN | PN 960K08852 |
| 7 | PLATE PWBA MAIN |  |
| 8 | HARNESS ASSY AC INLET |  |
| 9 | LVPS-C |  |
| 10 | EDGE SADDLE |  |
| 11 | CLAMP |  |
| 12 | CLAMP |  |
| 13 | CLAMP |  |
| 14 | EDGE SADDLE |  |
| 15 | -- |  |
| 16 | EDGE SADDLE |  |
| 17 | CLAMP |  |
| 18 | CLAMP |  |
| 19 | BRACKET ASSY AC FILTER |  |
| 20 | PLATE FRAME FRONT | XOG ONLY |
| 21 | BRACKET-OPB COVER L | XOG ONLY |
| 22 | BRACKET-OPB COVER R | XOG ONLY |

## PL 12.15 Finisher Harness illustration



## PL 12.15 Finisher Harness

| Item | Part Name | Remarks |
| :---: | :---: | :---: |
| 1 | HARNESS ASSY MAIN SNR | $\begin{aligned} & \text { J8302, J8303A, J8312A, J8318A, J8328, J8391A, } \\ & \text { J8393A, J8440A, J8441A, J8324, J8325, J8331 } \end{aligned}$ |
| 2 | HARNESS ASSY MAIN DRIVE | $\begin{aligned} & \text { J8304, J8334, J8335, J8336, J8339, J8340, } \\ & \text { J8341, J8342, J8394, P8338 } \end{aligned}$ |
| 3 | HARNESS ASSY I/F | J8300, CN1 |
| 4 | HARNESS ASSY X'PORT ENT SN | ,RJ8319, J8303B |
| 5 | HARNESS ASSY BUFFER SNR | J8318B, J8392 |
| 6 | HARNESS ASSY TOP EXIT SNR | J8312B, J8321 |
| 7 | HARNESS ASSY TOP SNR | J8393B, J8322 |
| 8 | HARNESS ASSY PUNCH DRIVE | PUNCH ONLY J8306, J8332, 18344 |
| 9 | HARNESS ASSY PUNCH SNR | PUNCH ONLY J8307, J8333, J8352, J8355 |
| 10 | HARNESS ASSY LVPS | J8315, J502, J505 |
| 11 | HARNESS ASSY INTERLOCK | J8314, J8364, J8365, J8388 |
| 12 | HARNESS ASSY PUNCH BOX SE | ETPUNCH ONLY J8353, P8355 |
| 13 | HARNESS ASSY M-HTRA | J8310, J8371 |
| 14 | HARNESS ASSY PUNCH FULL S | NRPUNCH ONLY J8500, J8452 |

## HCF

## 13 HCF

## PL 13.1 Cover illustration



## PL 13.1 Cover

Item Part Name Remarks

| 1 | COVER TOP LG HCF |
| :--- | :--- |
| 2 | COVER RH HCF |
| 3 | RAIL ASSY SLIDE |
| 4 | SENSOR |
| 5 | SPRING |
| 6 | LEVER LATCH |
| 7 | PLATE ASSY CASTER W |
| 8 | CASTER RACK FR |
| 9 | FOOT ADJUSTER |
| 10 | RAIL ASSY TRAY |
| 11 | COVER LH HCF |
| 12 | BRKT ASSY-SNR |
| 13 | -- |
| 14 | COVER REAR HCF |
| 15 | JOINT BRACKET |
| 16 | SCREW |
| 17 | COVER FRONT SIDE |

PL 13.2 Tray (1/2) illustration


PL 13.2 Tray (1/2)

| Item | Part Name |
| :--- | :--- |
|  | Remarks |
| 1 | COVER ASSY FRONT |
| 2 | MAGNET CATCH TRAY |
| 3 | -- |
| 4 | LEVER LATCH |
| 5 | LATCH ASSY TRAY STD |
| 6 | SPRING |
| 7 | -- |
| 8 | BRKT END FRAME |
| 9 | PLATE END |
| 10 | SPRING COMP |
| 11 | WASHR |
| 12 | PLATE END TOP |
| 13 | PIN GUIDE |
| 14 | GUIDE ASSY END (with 8-13, 15) |
| 15 | LABEL END TOP |
| 16 | WASHR WAVE |

PL 13.3 Tray (2/2) illustration


## PL 13.3 Tray (2/2)

| Item | Part Name |
| :--- | :--- |
|  | Remarks |
| 1 | GUIDE ASSY SIDE R |
| 2 | GUIDE ASSY SIDE F |
| 3 | PAD BOTTOM |
| 4 | PLATE BOTTOM |
| 5 | PLATE ASSY BOTTOM (with 3, 4) |
| 6 | CABLE |
| 7 | SCREW GUIDE TRAY |
| 8 | BRKT ASSY GEAR R PF2 |
| 9 | BEARING POWERD |
| 10 | SHAFT LIFT |
| 11 | BEARING POWERD |
| 12 | WASHER |
| 13 | PULLEY S |
| 14 | PUIDE WIRE S |
| 15 | GEAR FRONT TRAY |
| 16 | PULLEY L |
| 17 | GUIDE WIRE L |
| 18 | GEAR LIFT |
| 19 | KIT CABLE TRAY (Item 6x4Pcs.) |
| 99 |  |

## PL 13.4 Feeder (1/3) illustration

マ 1 (with 2-18, PL22.5, PL22.6)


## PL 13.4 Feeder (1/3)

Item Part Name Remarks

8 FRAME ASSY FRONT
MOTOR ASSY HCF
FRAME ASSY DRIVE
FRAME ASSY REAR (with 5)
SOLENOID ASSY
HOLDER
BLOCK

GEAR-25
BEARING
SHAFT ASSY
GEAR-25
BEARING
GEAR-19
BRACKET
GEAR-40
SPRING SPACER
SPACER
FRICTION ROLLER

FEEDER ASSY HCF (with 2-18, PL22.5, PL22.6)

Included in Maintenance kit (per 300K print)

## PL 13.5 Feeder (2/3) illustration



## PL 13.5 Feeder (2/3)

| Item | Part Name | Remarks |
| :---: | :---: | :---: |
| 1 | FEEDER ASSY UPPER (with 2-19) |  |
| 2 | LATCH |  |
| 3 | SPRING LATCH |  |
| 4 | SHAFT LATCH |  |
| 5 | LEVER |  |
| 6 | FRAME ASSY UPPER |  |
| 7 | PIN DRIVE |  |
| 8 | GEAR 25 FEED |  |
| 9 | SENSOR ASSY |  |
| 10 | CLAMP MINI-SADDLE |  |
|  | HOLDER HARNESS PS1 |  |
| 11 | GUIDE |  |
| 12 | HARN ASSY FEEDER | J560, P58, P59, P60, P61, P62 |
| 13 | CHUTE UPPER REAR |  |
| 14 | CHUTE UPPER |  |
| 15 | ACTUATOR |  |
| 16 | SENSOR-PHOTO IN |  |
| 17 | BEARING |  |
| 18 | SPACER |  |
| 19 | SHAFT ASSY FEEDER |  |
| 20 | ROLL ASSY NUD | Included in Maintenance kit (per 300K print) |
| 21 | ROLL ASSY FEED | Included in Maintenance kit (per 300K print) |

## PL 13.6 Feeder (3/3) illustration



## PL 13.6 Feeder (3/3)

| Item | Part Name | Remarks |
| :--- | :--- | :--- |
|  |  |  |
| 1 | FEEDER ASSY LOWER (with 2-17) |  |
| 2 | CHUTE LOWER |  |
| 3 | FRAME ASSY-LOWER HCF |  |
| 4 | LEVER RETARD |  |
| 5 | SPRING RET DOWN |  |
| 6 | SLIDE RETARD |  |
| 7 | SPRING RETARD |  |
| 8 | SHAFT ASSY RETARD (with 9-16) |  |
| 9 | GEAR 22 |  |
| 10 | COLLAR |  |
| 11 | CLUTCH ASSY-FRICTION |  |
| 12 | BEARING |  |
| 13 | SHAFT ASSY-RET |  |
| 14 | BEARING-6 |  |
| 15 | BRACKET-ASSY RETARD |  |
| 16 | GEAR 15 |  |

## PL 13.7 Drive \& Transportation illustration



| PL 13.7 <br> Item | Drive \& Transportation <br> Part Name |  |
| :---: | :--- | :--- |
|  |  | Remarks |
| 1 | COVER ASSY TOP S |  |
| 2 | CHUTE ASSY LOW (with 3-8) |  |
| 3 | SWITCH |  |
| 4 | BRACKET SWITCH |  |
| 5 | CHUTE LOW |  |
| 6 | SENSOR ASSY TA |  |
| 7 | BRACKET SENSOR TA |  |
| 8 | CLAMP MINI-SADDLE | ALT |
|  | HOLDER HARNESS PS1 | ALT |
| 9 | ROLLER ASSY TA P |  |
| 10 | BEARING CONDUCTIVE |  |
| 11 | BRACKET HINGE REAR NEW |  |
| 12 | MOTOR ASSY |  |
| 13 | BRACKET ASSY PIVOT |  |
| 14 | SHAFT PIVOT TOP |  |
| 15 | SPRING TOSION R |  |
| 16 | SPRING TOSION L |  |
| 17 | SWIL ASSY DOCKING |  |

## PL 13.8 Electrical illustration



| Item | Part Name | Remarks |
| :---: | :---: | :---: |
| 1 | PWB ASSY |  |
| 2 | HARNESS ASSY MAIN | J1, J2, J3, J4, J5, J6, J8, P51, P52, P53, P54, P55, P56, P57, P58, P800, FS1, FS2, FS3, FS4 |
| 3 | CLAMP WS-2N |  |
| 4 | CLAMP MINI-SADDLE | ALT |
|  | HOLDER HARNESS PS1 | ALT |
| 5 | WS-1N |  |
| 6 | -- |  |

## Tandem Tray

## 14 Tandem Tray

## PL 14.1 Cover illustration



| PL 14.1 | CoVer |
| :--- | :--- |
| Item | Part Name |
|  |  |
| 1 | TOP COVER |
| 2 | FOOT COVER |
| 3 | RIGHT COVER |
| 4 | LEFT LOWER COVER |
| 5 | REAR COVER |
| 6 | CASTER (STOPPER) |
| 7 | CASTER |
| 8 | TRAY 3 STOPPER |
| 9 | ROLL |
| 10 | SHAFT |
| 11 | BRACKET |
| 12 | -- |
| 13 | LABEL |
| 14 | TRAY 4 STOPPER (P/O ITEM 3) |
| 15 | LABEL (4) |
| 16 | TRAY 4 ASSEMBLY (PL21.3) |
| 17 | LABEL (3) |
| 18 | TRAY 3 ASSEMBLY (PL21.2) |
| 19 | FOOT ADJUSTER |
| 20 | GOVER JOINT |
| 21 |  |
| 22 |  |
| 23 |  |





| PL 14.3 | Tray $\mathbf{4}$ |  |
| :--- | :--- | :--- |
| Item | Part Name |  |
|  |  |  |
| 1 | TRAY 4 COVER |  |
| 2 | TRAY 4 TRANSPORT ASSEMBLY (PL21.4.3) |  |
| 3 | FRAME ASSEMBLY |  |
| 4 | LIFT SHAFT ASSEMBLY |  |
| 5 | PULLEY |  |
| 6 | PULLEY |  |
| 7 | CABLE GUIDE |  |
| 8 | REAR TRAY CABLE |  |
| 9 | FRONT TRAY CABLE |  |
| 10 | BOTTOM PLATE |  |
| 11 | PAD |  |
| 12 | FRONT SIDE GUIDE |  |
| 13 | KNOB |  |
| 14 | KNOB ASSEMBLY |  |
| 15 | SPRING |  |
| 16 | BRAKE BRACKET |  |
| 17 | GEAR |  |
| 18 | RACK GEAR |  |
| 19 | PINION |  |
| 20 | BRACKET |  |
| 21 | RAIL ROLL |  |
| 22 | SHAFT |  |
| 23 | STOPPER |  |
| 24 | ACTUATOR |  |
| 25 | PAD |  |
| 26 | FRAME ASSEMBLY |  |
| 27 | REAR SIDE GUIDE |  |
|  |  |  |

## PL 14.4 Feeder (1/3) illustration

$\checkmark 3$ (with 4-14)


## PL 14.4 Feeder (1/3)

| Item | Part Name Remarks |
| :---: | :---: |
| 1 | -- |
| 2 | GUIDE |
| 3 | TRAY 4 TRANSPORT ASSEMBLY (with 4-14) |
| 4 | UPPER CHUTE |
| 5 | TAKEAWAY ROLL ASSEMBLY |
| 6 | BEARING |
| 7 | COVER |
| 8 | PINCH ROLL |
| 9 | BEARING |
| 10 | SPRING |
| 11 | BEARING |
| 12 | -- |
| 13 | TRANSPORT RAIL |
| 14 | LOWER CHUTE |
| 15 | TRAY 4 FEEDER (PL21.6.1) |
| 16 | BRACKET |
| 17 | COVER |
| 18 | TRAY 4 FEED OUT SENSOR |
| 19 | UPPER CHUTE |
| 20 | F/O LOWER CHUTE |
| 21 | BRACKET |
| 22 | STAND BRACKET |
| 23 | TRAY 3/4 PAPER SIZE SWITCH |
| 24 | WIRE HARNESS J825, 3842 |

PL 14.5 Feeder (2/3) illustration


## PL 14.5 Feeder (2/3)

## Item Part Name

Remarks

| 1 | TRAY 3 FEEDER (PL21.6.1) |  |
| :--- | :--- | :--- |
| 2 | COVER |  |
| 3 | TAKEAWAY ROLL ASSEMBLY |  |
| 4 | BEARING |  |
| 5 | COVER |  |
| 6 | CHUTE |  |
| 7 | WIRE HARNESS |  |
| 8 | TRAY 3 FEED OUT SENSOR |  |
| 9 | LOWER CHUTE |  |
| 10 | CHUTE ASSY FEEDER 2 (with 11, 12) |  |
| 11 | CHUTE FEED OUT |  |
| 12 | PAD ASSY LH LOW |  |

## PL 14.6 Feeder (3/3) illustration



| PL 14.6 Feeder (3/3) |  |  |
| :---: | :---: | :---: |
| Item | Part Name | Remarks |
| 1 | FEEDER ASSEMBLY (with 2-50) |  |
| 2 | TRAY 1/2 FEED LIFT UP MOTOR |  |
| 3 | BRACKET |  |
| 4 | SPACER |  |
| 5 | GEAR (31T) |  |
| 6 | SPRING |  |
| 7 | ONEWAY CLUTCH |  |
| 8 | ONEWAY GEAR |  |
| 9 | GEAR (13T) |  |
| 10 | BEARING |  |
| 11 | SHAFT |  |
| 12 | FRONT CHUTE |  |
| 13 | ACTUATOR |  |
| 14 | SENSOR |  |
| 15 | SENSOR |  |
| 16 | WIRE HARNESS | J101, J102, J103, J220, J661 |
| 17 | GEAR (28T/21T) |  |
| 18 | GEAR (29T) |  |
| 19 | SPRING |  |
| 20 | ROLLER ASSY | Periodical replacement parts (per 300k print) |
| 21 | ONEWAY CLUTCH |  |
| 22 | ONEWAY GEAR (22T) |  |
| 23 | SHAFT |  |
| 24 | CHUTE |  |
| 25 | SPRING |  |
| 26 | FRICTION CLUTCH |  |
| 27 | SHAFT-RETARD |  |
| 28 | -- |  |
| 29 | SPACER |  |
| 30 | GEAR (33T) |  |
| 31 | SHAFT-NUDGER |  |
| 32 | -- |  |
| 33 | GEAR (25T) |  |
| 34 | LOWER FRAME |  |
| 35 | BEARING |  |
| 36 | GEAR (27T) |  |
| 37 | LEVER |  |
| 38 | BEARING |  |
| 39 | WASHER |  |
| 40 | UPPER FRAME |  |
| 41 | -- |  |
| 42 | HOLDER HARNESS CTR |  |
| 43 | HOLDER HARNESS REAR |  |
| 44 | HOLDER HARNESS UPPER |  |

HOLDER HARNESS PS1
ALT
CLAMP MINI-SADDLE ALT
RAIL
SUPPORT RETARD
48
SUPPORT NUDGER
HOLDER
SPRING

Periodical replacement parts (per 300k print)

## PL 14.7 Transportation illustration



## PL 14.7 Transportation

| Item | Part Name Rem |
| :---: | :--- |
| 1 |  |
| 2 | LEFT COVER ASSEMBLY (with 2-13) |
| 3 | LATCH |
| 4 | HOOK |
| 5 | HANDLE |
| 6 | LEFT COVER |
| 7 | CHUTE |
| 8 | ACTUATOR |
| 9 | SPRING |
| 10 | BRACKET |
| 11 | SPRING |
| 12 | BEARING |
| 13 | BEARING |
| 14 | PINCH ROLL |
| 15 | SUPPORT |
| 16 | BRFT COVER INTERLOCK SWITCH |
| 17 | BRACKET |
| 18 | ROLL ASSY (with 9-13) |



| PL 14.8 <br> Item | Drive \& Electrical <br> Part Name | Remarks |
| :---: | :--- | :--- |
|  |  |  |
| 1 | GEAR ASSEMBLY (Tray 3) |  |
| 2 | GEAR ASSEMBLY (Tray 4) |  |
| 3 | MAIN MOTOR |  |
| 4 | GEAR (22/40) |  |
| 5 | TRAY MODULE PWB |  |
| 6 | BRACKET |  |
| 7 | TAKEAWAY CLUTCH |  |
| 8 | BRACKET |  |
| 9 | BEARING |  |
| 10 | GEAR (38T) |  |
| 11 | SHAFT |  |
| 12 | GEAR (37T) |  |
| 13 | GEAR (32T) |  |
| 14 | GEAR (60T) |  |
| 15 | GEAR (60T) |  |
| 16 | BRACKET ASSEMBLY |  |
| 17 | GASKET |  |
| 18 | WIRE HARNESS |  |
|  |  |  |
| 19 | BEARING |  |
| 20 | WASHER-PLAIN,NYN |  |

## Tally Genicom Parts List

| DIAGRAM/PL \# | DESCRIPTION | PART NUMBER |
| :---: | :---: | :---: |
| Engine Parts |  |  |
| 1.1 \#6 | CONSOLE PANEL (TG UNIQUE) | 848K06630 |
| 2.1 \#7 | FEEDER ASSY | 059K26938 |
| 2.3 \#7 | Lower ONEWAY CLUTCH | $005 K 83081$ |
| 2.3 \#13 | ACTUATOR | 120E22481 |
| 2.3 \#14 | Level and No paper SENSOR | 930W00113 |
| 2.3 \#15 | Pre Feed SENSOR | 930 W 00211 |
| 2.3 \#21 | Upper ONEWAY CLUTCH | 005 K 05890 |
| 2.3 \#26 | FRICTION CLUTCH | 005 K 07010 |
| 2.3 \#99 | KIT ROLLS (with 20x3Pcs.) | 604K20530 |
| 3.2 \#15 | SOLENOID PICK UP | 121E92780 |
| 3.2 \#20 | KIT ROLLER ASSY-FEED | 604K23380 |
| 4.2 \#1 | HSG ASSY-BTR | 802K56095 |
| 4.3 \#1 | CHUTE ASSY LH (with 2-9) | 054K24054 |
| 4.3 \#3 | ROLLER ASSY-REGI-P | $059 K 32931$ |
| 4.5 \#1 | TRNS ASSY REGI (with 2-8) | 059 K 45960 |
| 4.5 \#2 | CLUTCH ASSY REGI H | 121K37450 |
| 4.5 \#14 | CLUTCH ASSY-TA | 121K32730 |
| 5.1 \#11 | MOTOR ASSY-DISP 30K | 127 K 38040 |
| 5.1 \#13 | FAN FUSER | 127 K 37881 |
| 5.1 \#14 | ROS ASSY-12 | 062 K 13615 |
| 7.1 \#5 | BELT-SYNCHRONOUS BAN | 423W13155 |
| 7.1 \#6 | DRIVE ASSY 242 (with 7, 8) | 007 K 88598 |
| 8.1 \#1 | PSHV-Y2 | 105E17590 |
| 8.1 \#5 | PWBA MCU (TG UNIQUE) | $960 K 32300$ |
| 8.1 \#8A | POWER UNIT-C1 (100/127) | 105E11391 |
| 8.1 \#8B | POWER UNIT C1H (200/240) | 105E11401 |
| 8.1 \#13 | BREAKER GFI INL | 908W01201 |
| 8.1 \#25 | PWBA, ESS, CONTROLLER (TG | 101K54690_ |
| Parts for Options |  |  |
| 10.1 \#12 | PWBA DUPLEX | 960K01426 |
| 12.8 \#9 | CARRIAGE ASSY LOWER, STAPLER | 041K94750 |
| 12.14 \#3 | PWB H-TRA | $960 K 17130$ |
| 12.14 \#5 | PWB MAIN-C | $960 K 08852$ |
| 12.14 \#9 | LVPS-C | 105K21081 |
| 13.5 \#21 | KIT, FEED ROLL (HCF) | 604K23660 |
| 13.6 \#11 | CLUTCH ASSY-FRICTION | 005K06700 |

